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2011-12-22	4.0.3	AUTOSAR Administration	• Introduced formal specification items and Constraint and Specification History • Added several clarifications, examples and constraints • Improved support for AUTOSAR Services, memory mapping and calibration • New attributes in various parts of the model
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References

[1] Generic Structure Template
AUTOSAR_FO_TPS_GenericStructureTemplate

[2] General Requirements on Basic Software Modules
AUTOSAR_CP_RS_BSWGeneral

[3] Methodology for Classic Platform
AUTOSAR_CP_TR_Methodology

[4] Glossary
AUTOSAR_FO_TR_Glossary

[5] Software Component Template
AUTOSAR_CP_TPS_SoftwareComponentTemplate

[6] System Template
AUTOSAR_CP_TPS_SystemTemplate

[7] AUTOSAR XML Schema Production Rules
AUTOSAR_FO_TPS_XMLSchemaProductionRules

[8] Standardization Template
AUTOSAR_FO_TPS_StandardizationTemplate

[9] Specification of RTE Software
AUTOSAR_CP_SWS_RTE

[10] General Specification of Basic Software Modules
AUTOSAR_CP_SWS_BSWGeneral

[11] Meta Data Exchange Format for Software Module Sharing V1.0 (MDX V1.0)
http://www.asam.net
ASAM-AE-MDX-V1_0_0.pdf

[12] Guide to BSW Distribution
AUTOSAR_CP_EXP_BSWDistributionGuide

[13] Virtual Functional Bus
AUTOSAR_CP_TR_VFB

[14] Specification of Operating System
AUTOSAR_CP_SWS_OS

[15] Specification of ECU Configuration
AUTOSAR_CP_TPS_ECUConfiguration

[16] Specification of Memory Mapping
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[17] Specification of Timing Extensions for Classic Platform
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[18] Specification of ECU Resource Template
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[19] ASAM MCD-2 MC (ASAP2 / A2L)
http://www.asam.net
ASAM_AE_MCD-2_MC_BS_V1-7-1.pdf

[20] Collection of blueprints for AUTOSAR M1 models
AUTOSAR_FO_MOD_GeneralBlueprints

[21] Specification of Function Inhibition Manager
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[22] Specification of Diagnostic Event Manager
AUTOSAR_CP_SWS_DiagnosticEventManager

[23] Specification of Watchdog Manager
AUTOSAR_CP_SWS_WatchdogManager

[24] Specification of ECU State Manager
AUTOSAR_CP_SWS_ECUStateManager

[25] Specification of Default Error Tracer
AUTOSAR_CP_SWS_DefaultErrorTracer

[26] Software Process Engineering Meta-Model Specification
http://www.omg.org/spec/SPEM/2.0/

1 General Information

1.1 Document Scope

This is the documentation of the template for the Basic Software Module Description (BSWMDT).

The BSWMD is a formal notation of all information belonging to a certain BSW artifact (BSW module or BSW cluster) in addition to the implementation of that artifact. There are several possible use cases for such a description, see 2.1 for details.

The BSWMDT - the *template* to be used for the BSWMD - is the standardized format which has to be used for this description in AUTOSAR. The template is represented in UML as part of the overall AUTOSAR meta-model and is part of the XML schema generated out of this meta-model. This document describes all the elements which belong to this template. These elements are maintained in two different packages of the AUTOSAR meta-model:

- The package `BswModuleTemplate` contains all elements which are used exclusively by the BSWMDT.
- Some elements of the BSWMDT, for example for the description of implementation aspects and resource consumption, are used also within the Software Component Template (SWCT). These elements belong to the `CommonStructure` package of the meta-model and are also described within this document.

For clarification, please note that the `GenericStructure` package of the meta-model contains some fundamental infrastructure meta-classes and common patterns that are described in [1]. These elements are also used within the `BswModuleTemplate` but for details refer to [1].

Generic Structure provides details about

- AUTOSAR top level structure
- Commonly used meta-classes and primitives
- Variant handling
- Documentation

This document addresses people who need to have a deeper understanding of the BSWMDT part of the meta-model, for example tool developers and those who maintain the meta-model. It is not intended as a guideline for the BSW developers who will have to provide the actual BSWMD, i.e. who have to “fill out” the template.

Due to the complexity of the meta-model, the text in some class-diagrams in this document is too small to be read on printed paper of normal size. It is recommended to use the electronic document and enlarge these diagrams on a computer screen if required.

1.2 Input Documents

The following input documents have been used to develop the BSWMDT:

- Generic Structure Template [1]
- General Requirements on Basic Software Modules [2]
- AUTOSAR Methodology [3]
- AUTOSAR Glossary [4]
- Software Component Template [5]
- System Template [6]
- XML Schema Production Rules [7]

1.3 Document Conventions

Technical terms are typeset in mono spaced font, e.g. `PortPrototype`. As a general rule, plural forms of technical terms are created by adding “s” to the singular form, e.g. `PortPrototype`s. By this means the document resembles terminology used in the AUTOSAR XML Schema.

This document contains constraints in textual form that are distinguished from the rest of the text by a unique numerical constraint ID, a headline, and the actual constraint text starting after the ⌈ character and terminated by the ⌋ character.

The purpose of these constraints is to literally constrain the interpretation of the AUTOSAR meta-model such that it is possible to detect violations of the standardized behavior implemented in an instance of the meta-model (i.e. on M1 level).

Makers of AUTOSAR tools are encouraged to add the numerical ID of a constraint that corresponds to an M1 modeling issue as part of the diagnostic message issued by the tool.

The attributes of the classes introduced in this document are listed in form of class tables. They have the form shown in the example of the top-level element AUTOSAR:

Please note that constraints are not supposed to be enforceable at any given time in an AUTOSAR workflow. During the development of a model, constraints may legitimately be violated because an incomplete model will obviously show inconsistencies.

However, at specific points in the workflow, constraints shall be enforced as a safeguard against misconfiguration.

The points in the workflow where constraints shall be enforced, sometimes also known as the “imposition time” of the constraint, are different for each model category, e.g. on the classic platform, the constraints defined for software-components are typically enforced prior to the generation of the RTE while the constraints against the definition

of an Ecu extract shall be applied when the Ecu configuration for the Com stack is created.

For each document, possible imposition times of constraints are defined and the imposition times are typically mentioned in the constraint themselves to give a proper orientation for implementers of AUTOSAR authoring tools.

Let AUTOSAR be an example of a typical class table. The first rows in the table have the following meaning:

Class: The name of the class as defined in the UML model.

Package: The UML package the class is defined in. This is only listed to help locating the class in the overall meta model.

Note: The comment the modeler gave for the class (class note). Stereotypes and UML tags of the class are also denoted here.

Base Classes: If applicable, the list of direct base classes.

The headers in the table have the following meaning:

Attribute: The name of an attribute of the class. Note that AUTOSAR does not distinguish between class attributes and owned association ends.

Type: The type of an attribute of the class.

Mul.: The assigned multiplicity of the attribute, i.e. how many instances of the given data type are associated with the attribute.

Kind: Specifies, whether the attribute is aggregated in the class (`aggr` aggregation), an UML attribute in the class (`attr` primitive attribute), or just referenced by it (`ref` reference). Instance references are also indicated (`iref` instance reference) in this field.

Note: The comment the modeler gave for the class attribute (role note). Stereotypes and UML tags of the class are also denoted here.

Please note that the chapters that start with a letter instead of a numerical value represent the appendix of the document. The purpose of the appendix is to support the explanation of certain aspects of the document and does not represent binding conventions of the standard.

The verbal forms for the expression of obligation specified in [TPS_STDT_00053] shall be used to indicate requirements, see [8, Standardization Template].

Please note: By intent, TPS documents (and their traceable items) do not trace up to an RS (requirement item).

2 Use Cases and Modeling Approach

2.1 Use Cases

There are several possible use cases for the BSWMDT. The following uses cases can be applied for BSW modules (ICC3 conformance class) or for BSW clusters (ICC2 conformance class) and for libraries. For convenience we often use the word “module” in this document as a synonym for all three types of artifacts.

A library can be seen as a special kind of module which provides services to be used within the basic or application software and which are accessed via direct function calls. Thus the following use cases can also be applied to a library.

The main difference between a library and a “normal” BSW module is, that library services can directly be called from application SWCs without going via the RTE. As a consequence, there will be certain restrictions on the model elements which can be used for libraries, e.g. a library should not have scheduled functions. However, these restrictions are currently not formalized.

- The BSWMDT can be used to *specify* a BSW module or cluster (or a set of those) in terms of interfaces and dependencies before it is actually implemented. Details of the internal behavior and implementation are not filled out for this use case.

  Since the BSWMDT includes variation points, several variants of a BSW module or cluster can be described by a single specification (for details see chapter 10). According to the Methodology [3], artifacts on this level are delivered as **BSW Design Bundle** as a result of the activity **Design Basic Software**.

- The BSWMDT can be used to describe an *actually implemented* BSW module or cluster delivered to the integrator of an AUTOSAR ECU. It will contain details of the internal behavior, the implementation and constraints w.r.t. the specification. Especially, there may be more than one implementation (for example for different processors) which have the same specification.

  According to the Methodology, artifacts on this level are part of a **BSW Module Delivered Bundle** as a result of the activity **Develop BSW Module** (the same delivery also contains the code, as far it is not generated during integration).

- The BSWMDT does not only serve as an “upstream” template - i.e. as a format for information provided prior to ECU configuration time - but certain parts of the BSWMD can be used by the *integrator* to add further information or adjust information which was not available at the delivery time of the module.

  In the Methodology, artifacts on this level are part of the **BSW Module Integration Bundle** and they are created or refined during the activity **Integrate Software for ECU**.

  This use case includes for example adding documentation about the actual resource consumption and adding information in response to the needs of software components and other BSW modules integrated on the ECU (see chapter 4.4).

- Similar to the last case, the BSWMDT allows to add data which are generated from the ‘upstream” descriptions in order to support measurement and calibration tools (see chapter 9).
- The source code which implements the RTE and the BSW Scheduler is typically generated completely during ECU integration. Therefore the parts of the BSWMD which documents the implementation of this code (e.g. version information, memory sections, data structures for calibration support), shall be generated or updated by the RTE generator (see [9] for mandatory parts to be generated).

Details of the work flow for the different use cases are not in the scope of this document (please refer to [3]), but the information to be provided in these various steps influences the meta-model of the BSWMDT.

There is only limited use for the BSWMDT to describe software according to ICC1 conformance class, because in this case the complete BSW (including RTE) on an ECU consists of one single cluster, so that no interfaces or dependencies within the BSW can be described by this template, which means that the relevant parts of the template will be empty.

However, even in this case the BSWMDT may be used to document implementation aspects (e.g. the required compiler, resource consumption or vendor specific configuration parameters).

2.2 Three Layer Approach

The meta-model of the BSWMDT consists of three abstraction layers similar to the SWCT. This approach allows for a better reuse of the more abstract parts of the description. An overview is shown in Figure 2.1.

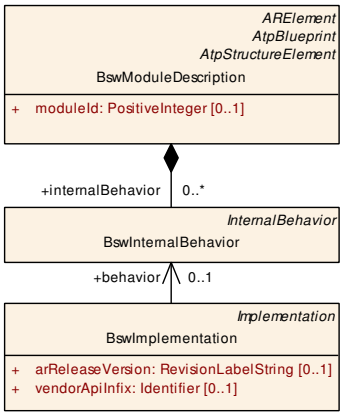

Figure 2.1: Three Layers of the BSW Module Description

The upper layer, the `BswModuleDescription`, contains the specification of all the provided and required interfaces including the dependencies to other modules.

The middle layer, the BswInternalBehavior, contains a model of some basic activity inside the module. This model defines the requirements of the module for the configuration of the OS and the BSW Scheduler.

There may be several different instances of BswInternalBehavior based on the same BswModuleDescription (even on the same CPU, for example several drivers adhering to the same BswModuleDescription).

The term “behavior” has been chosen in analogy to a similar term in the SWCT. Note that it is restricted only to the scheduling behavior here and does not describe the algorithmic behavior of the module or cluster.

The bottom layer, the BswImplementation contains information on the individual code. Again, there may be several instances of BswImplementation for the same BswInternalBehavior.

The usage of splitable aggregations resp. references between these layers instead of “ordinary” aggregations allows for more flexibility in the XML artifacts: If for example the BswInternalBehavior would aggregate BswImplementation, a concrete XML artifact of a BswInternalBehavior would have to be duplicated for every instance of BswImplementation.

By using splitable aggregations and references, the layers may be kept in separate files and also the lower layers can be modified in later project phases. This is analog to the inclusion of header files in a C-source file: Several implementation files can share the same header file which typically declares more abstract things as function prototypes and the like.

The relation from BswModuleDescription to BswInternalBehavior is a splitable aggregation instead of a reference for semantical reasons and in analogy to the SWCT.

2.3 Several Implementations of the same BSW Module or BSW Cluster

According to the three layer approach, the meta-class BswModuleDescription and an aggregated BswInternalBehavior describe a type of a BSW module or cluster, for which different implementations may exist which are represented by different BswImplementations (note that the name of the meta-class BswModuleDescription is misleading here, because this meta-class does not contain the complete description of a module or cluster).

In case the different implementations of a BSW module or cluster are compiled for different CPUs, the corresponding BSWMDs can be treated as separate artifacts which may share the BswModuleDescription and/or BswInternalBehavior.

In case the implementations are compiled for the same CPU, i.e. are integrated on the same ECU and same address space (for example CAN drivers for several CAN

channels), their BSWMDs still should share the BswModuleDescription and (in case it is equal) the BswInternalBehavior, but there has to be a mechanism to ensure, that the globally visible C symbols derived from the BswModuleDescription and BswInternalBehavior are unique. This is handled with infixes defined in the implementation part of the BSWMDT (see chapters 4.1 and 6).

2.4 Relation to SwComponentType

Some BSW modules or clusters not only have interfaces to other BSW modules or clusters, but have also more abstract interfaces accessed from Application SW-Cs via the RTE. These BSW modules or clusters can be AUTOSAR Services, part of the ECU Abstraction, or Complex Drivers.

The more abstract interfaces required here are called AUTOSAR Interfaces (see [5] and [4]).

These AUTOSAR Interfaces are described by means of the Software Component Template (SWCT), they consist of ports, port interfaces and their further detailing. The root classes of the SWCT used to describe these elements for BSW modules are ServiceSwComponentType, EcuAbstractionSwComponentType and ComplexDeviceDriverSwComponentType (see [5]) which all are derived from AtomicSwComponentType.

In addition, the function calls from the RTE into these BSW module shall be modeled as RunnableEntity-s which are also contained in the SWCT. The root class of the SWCT used to describe the RunnableEntity-s (and a few other things) is called SwcInternalBehavior.

[TPS_BSWMDT_04000] BSW modules with AUTOSAR Interfaces ⌈Thus for BSW modules or clusters which can be accessed via AUTOSAR Interfaces there shall be an XML-artifact defining an AtomicSwComponentType and an SwcInternalBehavior *in addition* to the BSWMD.⌋

These additional descriptions are required to generate the RTE. Note that in the case of AUTOSAR Services the content of these additional descriptions can vary between different ECUs (for example due to the number of ports the RTE has to create for an AUTOSAR Service) and thus have to be created per ECU. The detailed steps for creating these artifacts are described in [5].

In order to trace the dependencies between these additional SWCT descriptions and the associated BSWMD, there is a mapping between the classes SwcInternalBehavior and BswInternalBehavior, see chapter 5.11 for details.

Due to the usage of two different templates for the description of modules mentioned above (i.e. those which have ports for connection to the application software) there is a certain ambiguity how to described the scheduling: With the help of an event model defined in the BSWMDT (see chapter 5 in this document) or with an event model defined in the SwcInternalBehavior of the SWCT. The two different event models

result in different interfaces toward the RTE (the BSW-Scheduler-style C-interfaces the SWC-style C-interfaces which are both generated during RTE contract phase). For the standardized AUTOSAR Services defined up to now the SWC-style interfaces are only used for function calls directly related to communication via ports, whereas for e.g. cyclic events the BSW-Scheduler interfaces shall be used. Note, that there is no such rule for the BSW parts which are not standardized (ECU Abstraction and Complex Drivers).

Another special case arises when the BSW Scheduler or an interrupt routine triggers a cyclic function which then has to call into the RTE in order to access an SWC. In order to generate the RTE API with the means of the current SWCT, it is required to specify a `RunnableEntity` in this case even if it is not triggered by an RTE event.

3 BSW Module Description Overview

Figure 3.1 and the following class table show all the relations of the BSWMDT top layer, the BswModuleDescription.

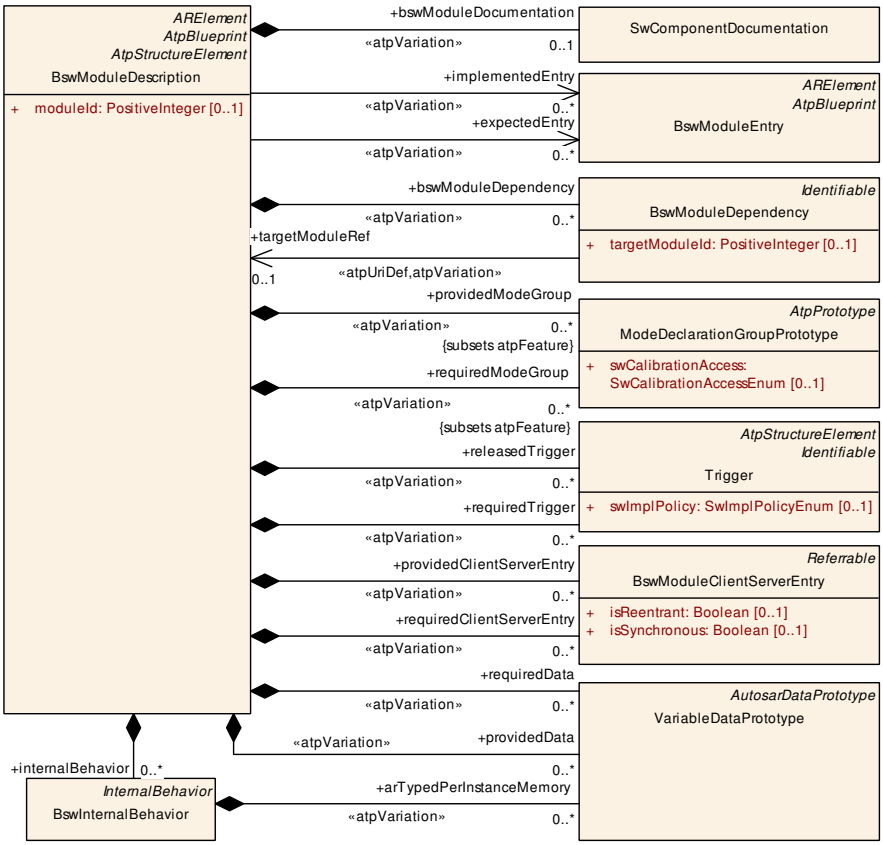

Figure 3.1: BSW Module Description Overview

[TPS_BSWMDT_04079] Usage of {reservedName} for `BswModuleDescription.shortName` ⌈For a standardized module of ICC3 conformance class the `BswModuleDescription.shortName` shall be chosen identical to the {reservedName} (resp. library abbreviation) defined in [10].⌋

In addition, the `BswModuleDescription` contains an attribute `moduleId`:

[constr_4019] BSW module identifier

Imposition time: `IT_BswMD`

⌈`BswModuleDescription.moduleId` shall refer to the identifier of the standardized AUTOSAR modules according to [10], if applicable[1]. Otherwise (e.g. for ICC2 clusters) the identifier shall either be empty or chosen differently from the ones given in [10].⌋

[1]Note that there may be more than one module in an ECU software with the same identifier, e.g. according to the standard Complex Drivers all have the same identifier.

[TPS_BSWMDT_04071] Usage of module identifier and category ⌈In any case, this identifier in the BSWMD shall be used to document the relation of an artifact to the standard and thus is a useful information for the conformance test. In addition to this, the generic `category` attribute (inherited from `Identifiable`) shall be used for a general classification of a `BswModuleDescription` as shown in the following table. This allows to check for constraints.⌋

[constr_4020] Allowed categories of `BswModuleDescription`

Imposition time: `IT_BswMD`

⌈

category	*Explanation*
BSW_MODULE	Specifies a single BSW module (ICC3 granularity).
BSW_CLUSTER	Specifies a BSW module cluster (ICC2 granularity).
LIBRARY	Specifies a Library (not restricted to be used within the BSW).

⌋

Note that other values or an empty value are not allowed for `BswModuleDescription`.

[TPS_BSWMDT_04001] Attaching `SwComponentDocumentation` to a BSWMD ⌈It is possible to attach documentation to a `BswModuleDescription` by using the meta-class `SwComponentDocumentation`. This uses the same concept as the documentation for software components and is described in detail in [5].⌋

The meta-class `BswModuleEntry` describes a single C-function prototype (see chapter 4.1) and is used here as follows:

[TPS_BSWMDT_04002] Provision of `BswModuleEntry` ⌈The interface exported by a `BswModuleDescription` is the set of `implementedEntry`-s provided for the usage by other modules (including “main”-functions called by the BSW Scheduler).⌋

[TPS_BSWMDT_04153] Usage of `BswModuleEntry` ⌈The interface required by a `BswModuleDescription` is the set of `expectedEntry`-s implemented by other modules.⌋

[TPS_BSWMDT_04130] Linkage of `BswModuleEntry` ⌈`BswModuleEntry` referenced as `implementedEntry` by one `BswModuleDescription` and a `BswModuleEntry` referenced as `expectedEntry` by another `BswModuleDescription` are matching if one of the following applies:

- The identical `BswModuleEntry` is referenced

or

- the 2 `BswModuleEntry.shortName`s are identical.

⌋

[constr_4093] Entries linked to `BswModuleEntry`s shall have compatible signature

Imposition time: `IT_BswMD`

⌈Matching `BswModuleEntry`s according to [TPS_BSWMDT_04130] are compatible if the following conditions are fulfilled:

- both or neither of them define a `returnType`
- when the `returnType`s are defined, the `SwServiceArg`s in the role `returnType` shall be compatible
- both define the same number of compatible arguments in same order

⌋

[constr_4094] compatibility of `SwServiceArg` in role `returnType`

Imposition time: `IT_BswMD`

⌈`SwServiceArg` in role `returnType` are compatible if they are identically typed⌋

[constr_4095] Compatibility of `SwServiceArg` in role `argument`

Imposition time: `IT_BswMD`

⌈`SwServiceArg` in role `returnType` are compatible if:

- they are identically typed

and

- if both do have the same `shortName`

⌋

[constr_4096] Matching `BswModuleEntry`s should have compatible attributes

Imposition time: `IT_BswMD`

⌈Matching `BswModuleEntry`s according to [TPS_BSWMDT_04130] should be defined with identical values of the attributes

- `callType`
- `executionContext`
- `isReentrant`
- `isSynchronous`
- `serviceId`
- `swServiceImplPolicy`
- `bswEntryKind`

⌋

[TPS_BSWMDT_04004] **BswModuleDescription.providedModeGroup** ⌈With the optional attribute providedModeGroup a BSW module can provide a set of modes (mode group) in order to control other BSW modules which in turn have to declare a corresponding requiredModeGroup.⌋

[TPS_BSWMDT_04005] **BswModuleDescription.releasedTrigger** ⌈With the optional attribute releasedTrigger a BSW module can declare a trigger which it releases. A trigger is used to raise events in other BSW modules which in turn have to declare a corresponding requiredTrigger.⌋

[TPS_BSWMDT_04006] **BswModuleDescription.internalBehavior** ⌈By the aggregation of class BswInternalBehavior in BswModuleDescription it is possible to add scheduling aspects to the description.⌋

[TPS_BSWMDT_04181] **BswModuleDescription with several internalBehaviors** ⌈A BswModuleDescription is allowed to aggregate more than one BswInternalBehavior in the role internalBehavior for the purpose to describe different implementation properties on BswInternalBehavior level of multi instantiated BSW Modules that are integrated on the same ECU.⌋

Please note that in case of a multi-instantiation of a BSW Module a common BswModuleDescription is shared amongst the different instances. But since the implementation of the different instances may differ, a different BswInternalBehavior may be necessary to describe the different implementation properties.

[constr_9316] Multi instantiated BSW Modules not mappable

Imposition time: IT_BswMD

⌈In case a BSW Module is multi instantiated in an ECU its BswImplementations shall not reference a SwcBswMapping in the role swcBswMapping.⌋

Note that the concepts of multi instantiation of BSW Modules and SWCs differ. It is not possible to combine them in a single module, nor to mix multi instantiated BSW Module with a single instantiated SWC or vice versa.

The declaration of function calls, dependencies, triggers and modes make up the interface of a module or cluster to be used for communication among modules on the same memory and processor core. The details are described in chapter 4.

For communication between partition and/or core boundaries, additional declarations are required, see chapter 4.6

For BswInternalBehavior see chapter 5.

Class	BswModuleDescription			
Note	Root element for the description of a single BSW module or BSW cluster. In case it describes a BSW module, the short name of this element equals the name of the BSW module. **Tags:** atp.recommendedPackage=BswModuleDescriptions This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element, *AtpClassifier*.atpFeature			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
bswModuleDependency	BswModuleDependency	*	aggr	Describes the dependency to another BSW module. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=bswModuleDependency, bswModuleDependency.shortName, bswModuleDependency.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=20
bswModuleDocumentation	SwComponentDocumentation	0..1	aggr	This adds a documentation to the BSW module. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=bswModuleDocumentation, bswModuleDocumentation.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=6
expectedEntry	BswModuleEntry	*	ref	Indicates an entry which is required by this module. Replacement of outgoingCallback / requiredEntry. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=expectedEntry, expectedEntry.bswModuleEntry, expectedEntry.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
implementedEntry	BswModuleEntry	*	ref	Specifies an entry provided by this module which can be called by other modules. This includes "main" functions, interrupt routines, and callbacks. Replacement of providedEntry / expectedCallback. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=implementedEntry, implementedEntry.bswModuleEntry, implementedEntry.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
internalBehavior	BswInternalBehavior	*	aggr	The various BswInternalBehaviors associated with a BswModuleDescription can be distributed over several physical files. Therefore the aggregation is <<atpSplitable>>. **Tags:** atp.Splitkey=internalBehavior, internalBehavior.shortName xml.sequenceOffset=65
moduleId	PositiveInteger	0..1	attr	Refers to the BSW Module Identifier defined by the AUTOSAR standard. For non-standardized modules, a proprietary identifier can be optionally chosen. **Tags:** xml.sequenceOffset=5



△

Class	**BswModuleDescription**			
providedClient ServerEntry	BswModuleClientServer Entry	*	aggr	Specifies that this module provides a client server entry which can be called from another partition or core.This entry is declared locally to this context and will be connected to the requiredClientServerEntry of another or the same module via the configuration of the BSW Scheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=providedClientServerEntry, providedClient ServerEntry.shortName, providedClientServer Entry.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=45
providedData	VariableDataPrototype	*	aggr	Specifies a data prototype provided by this module in order to be read from another partition or core.The providedData is declared locally to this context and will be connected to the requiredData of another or the same module via the configuration of the BSW Scheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=providedData, providedData.shortName, providedData.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=55
providedMode Group	ModeDeclarationGroup Prototype	*	aggr	A set of modes which is owned and provided by this module or cluster. It can be connected to the required ModeGroups of other modules or clusters via the configuration of the BswScheduler. It can also be synchronized with modes provided via ports by an associated ServiceSwComponentType, EcuAbstraction SwComponentType or ComplexDeviceDriverSw ComponentType. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=providedModeGroup, providedMode Group.shortName, providedModeGroup.variation Point.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=25
releasedTrigger	Trigger	*	aggr	A Trigger released by this module or cluster. It can be connected to the requiredTriggers of other modules or clusters via the configuration of the BswScheduler. It can also be synchronized with Triggers provided via ports by an associated ServiceSwComponentType, Ecu AbstractionSwComponentType or ComplexDeviceDriver SwComponentType. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=releasedTrigger, releasedTrigger.shortName, releasedTrigger.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=35

▽

△

Class	**BswModuleDescription**			
requiredClient ServerEntry	BswModuleClientServer Entry	*	aggr	Specifies that this module requires a client server entry which can be implemented on another partition or core.This entry is declared locally to this context and will be connected to the providedClientServerEntry of another or the same module via the configuration of the BSW Scheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=requiredClientServerEntry, requiredClient ServerEntry.shortName, requiredClientServer Entry.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=50
requiredData	VariableDataPrototype	*	aggr	Specifies a data prototype required by this module in oder to be provided from another partition or core.The required Data is declared locally to this context and will be connected to the providedData of another or the same module via the configuration of the BswScheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=requiredData, requiredData.shortName, requiredData.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=60
requiredMode Group	ModeDeclarationGroup Prototype	*	aggr	Specifies that this module or cluster depends on a certain mode group. The requiredModeGroup is local to this context and will be connected to the providedModeGroup of another module or cluster via the configuration of the BswScheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=requiredModeGroup, requiredMode Group.shortName, requiredModeGroup.variation Point.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=30
requiredTrigger	Trigger	*	aggr	Specifies that this module or cluster reacts upon an external trigger.This requiredTrigger is declared locally to this context and will be connected to the providedTrigger of another module or cluster via the configuration of the BswScheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=requiredTrigger, requiredTrigger.shortName, requiredTrigger.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=40

Table 3.1: BswModuleDescription

4 BSW Interface

This chapter describes the meta-model elements which are used to define the interface level of a BSW module: The description of `implementedEntry`-s, `expectedEntry`-s, declaration of mode groups, declaration of triggers, dependencies from other modules and the interfaces for inter-partition communication.

4.1 BSW Module Entry

[TPS_BSWMDT_04007] **`BswModuleEntry`** ⌈The meta-class `BswModuleEntry` is used to model the signature of a C-function call⌋

See figure 4.1 for more details.

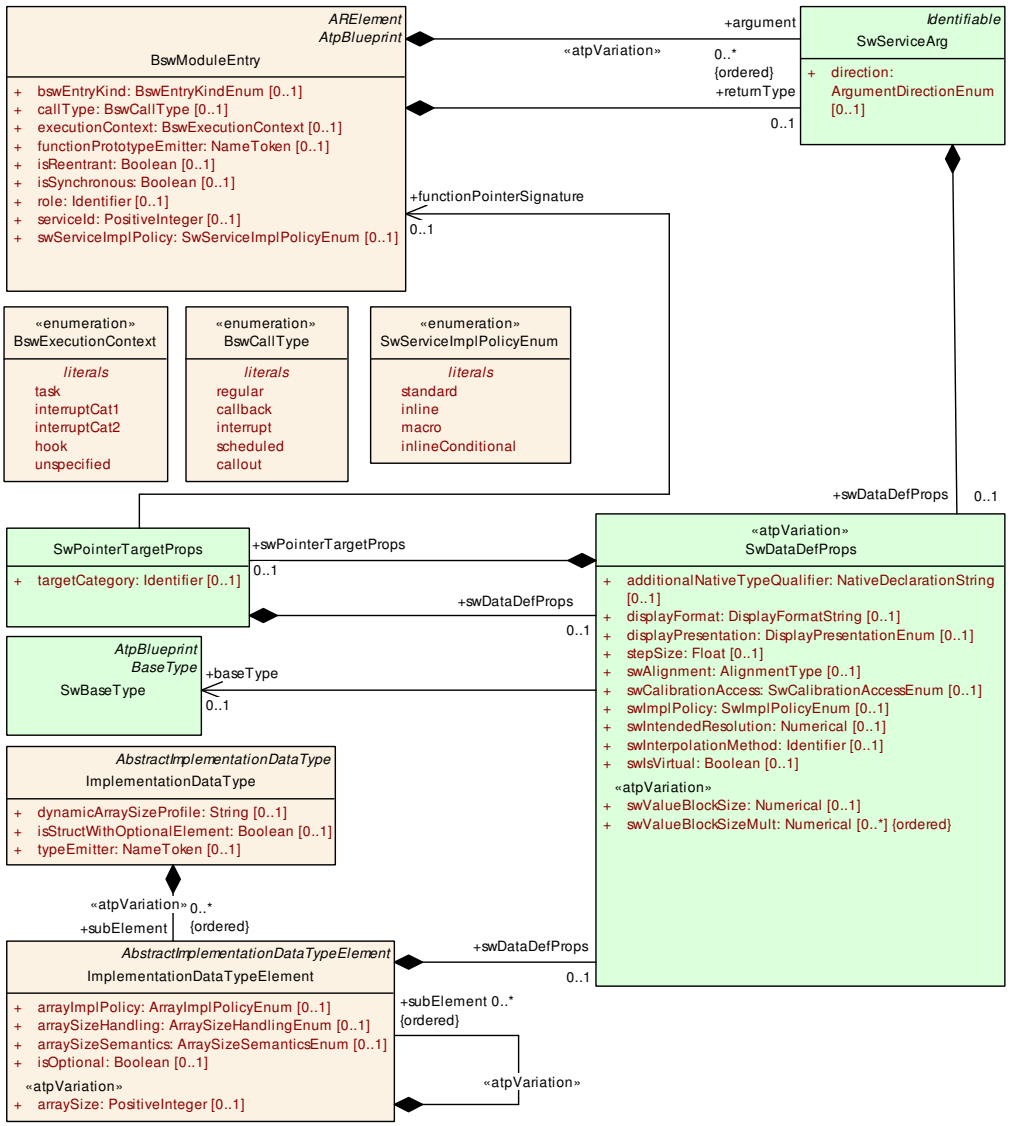

Figure 4.1: Details of meta-class BswModuleEntry

The attributes of meta-class BswModuleEntry are shown in the following table. The attribute serviceId is used to identify the C-function and thus is an important information for an AUTOSAR conformance test.

[constr_4013] BSW service identifier

Imposition time: IT_BswMD

⌈For Standardized Interfaces, this identifier is defined in the AUTOSAR Software Specification (SWS) of the module. In case the C-function prototype represented by the entry is not standardized, it still can be used optionally, but its value shall differ from the standardized ones.⌋

[TPS_BSWMDT_04156] Usage of functionPrototypeEmitter ⌈If attribute functionPrototypeEmitter is set to "RTE", the RTE shall generate the function prototypes in the Module Interlink Header File. If the attribute is set to any other value or does not exist, the BSW module shall generate and provide the prototype in its header file(s).⌋

Class	**BswModuleEntry**			
Note	This class represents a single API entry (C-function prototype) into the BSW module or cluster. The name of the C-function is equal to the short name of this element with one exception: In case of multiple instances of a module on the same CPU, special rules for "infixes" apply, see description of class BswImplementation. **Tags:** atp.recommendedPackage=BswModuleEntrys This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
argument (ordered)	SwServiceArg	*	aggr	An argument belonging to this BswModuleEntry. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=blueprintDerivationTime xml.sequenceOffset=45
bswEntryKind	BswEntryKindEnum	0..1	attr	This describes whether the entry is concrete or abstract. If the attribute is missing the entry is considered as concrete. **Tags:** xml.sequenceOffset=40
callType	BswCallType	0..1	attr	The type of call associated with this service. **Tags:** xml.sequenceOffset=25
execution Context	BswExecutionContext	0..1	attr	Specifies the execution context which is required (in case of entries into this module) or guaranteed (in case of entries called from this module) for this service. **Tags:** xml.sequenceOffset=30
function Prototype Emitter	NameToken	0..1	attr	This attribute is used to control the generation of function prototypes. If set to "RTE", the RTE generates the function prototypes in the Module Interlink Header File.

▽

△

Class	**BswModuleEntry**			
isReentrant	Boolean	0..1	attr	Reentrancy from the viewpoint of function callers: • true: Enables the service to be invoked again, before the service has finished. • false: It is prohibited to invoke the service again before is has finished. **Tags:** xml.sequenceOffset=15
isSynchronous	Boolean	0..1	attr	Synchronicity from the viewpoint of function callers: • true: This calls a synchronous service, i.e. the service is completed when the call returns. • false: The service (on semantical level) may not be complete when the call returns. **Tags:** xml.sequenceOffset=20
returnType	SwServiceArg	0..1	aggr	The return type belonging to this bswModuleEntry. **Tags:** atp.Splitkey=returnType, returnType.shortName xml.sequenceOffset=40
role	Identifier	0..1	attr	Specifies the role of the entry in the given context. It shall be equal to the standardized name of the service call, especially in cases where no ServiceIdentifier is specified, e.g. for callbacks. Note that the ShortName is not always sufficient because it maybe vendor specific (e.g. for callbacks which can have more than one instance). **Tags:** xml.sequenceOffset=10
serviceId	PositiveInteger	0..1	attr	Refers to the service identifier of the Standardized Interfaces of AUTOSAR basic software. For non-standardized interfaces, it can optionally be used for proprietary identification. **Tags:** xml.sequenceOffset=5
swServiceImpl Policy	SwServiceImplPolicy Enum	0..1	attr	Denotes the implementation policy as a standard function call, inline function or macro. This has to be specified on interface level because it determines the signature of the call. **Tags:** xml.sequenceOffset=35

Table 4.1: BswModuleEntry

[constr_10260] Existence of attribute `BswModuleEntry.callType`

Imposition time: `IT_BswMD`

⌈For each `BswModuleEntry`, the attribute `callType` shall exist.⌋

[constr_10261] Existence of attribute `BswModuleEntry.executionContext`

Imposition time: `IT_BswMD`

⌈For each `BswModuleEntry`, the attribute `executionContext` shall exist.⌋

[constr_10262] Existence of attribute `BswModuleEntry.isReentrant`

Imposition time: `IT_BswMD`

⌈For each `BswModuleEntry`, the attribute `isReentrant` shall exist.⌋

[constr_10263] Existence of attribute `BswModuleEntry.isSynchronous`

Imposition time: `IT_BswMD`

⌈For each `BswModuleEntry`, the attribute `isSynchronous` shall exist.⌋

[constr_10264] Existence of attribute `BswModuleEntry.swServiceImplPolicy`

Imposition time: `IT_BswMD`

⌈For each `BswModuleEntry`, the attribute `swServiceImplPolicy` shall exist.⌋

Enumeration	**BswEntryKindEnum**
Note	Denotes the mechanism by which the entry into the Bsw module shall be called.
Aggregated by	BswModuleEntry.bswEntryKind
Literal	***Description***
abstract	This BswModuleEntry specifies an abstract signature of C-functions. The signature needs to be implemented by concrete BswModuleEntrys **Tags:** atp.EnumerationLiteralIndex=0
concrete	This BswModuleEntry specifies a concrete C-function with its signature. **Tags:** atp.EnumerationLiteralIndex=1

Table 4.2: BswEntryKindEnum

Enumeration	**BswExecutionContext**
Note	Specifies the execution context required or guaranteed for the call associated with this service.
Aggregated by	BswModuleEntry.executionContext
Literal	***Description***
hook	Context of an OS "hook" routine always **Tags:** atp.EnumerationLiteralIndex=0
interruptCat1	CAT1 interrupt context always **Tags:** atp.EnumerationLiteralIndex=1
interruptCat2	CAT2 interrupt context always **Tags:** atp.EnumerationLiteralIndex=2
task	Task context always **Tags:** atp.EnumerationLiteralIndex=3
unspecified	The execution context is not specified by the API **Tags:** atp.EnumerationLiteralIndex=4

Table 4.3: BswExecutionContext

The RTE and *Basic Software Scheduler* do support the invocation of `triggered ExecutableEntity` via direct function call in some special cases. Nevertheless it shall be prevented that an `ExecutableEntity` from a particular execution context calls a `triggered ExecutableEntity` which requires an execution context with more permissions. [TPS_BSWMDT_04179] lists the supported combinations.

[TPS_BSWMDT_04179] Possible invocation of `ExecutableEntity`s by direct function call dependent from `BswExecutionContext` ⌈

caller's `BswExecutionContext`	callee's `BswExecutionContext`				
	task	**interruptCat2**	**interruptCat1**	**hook**	**unspecified**
task	Supported	Supported	Supported		Supported
interruptCat2		Supported	Supported		Supported
interruptCat1			Supported		Supported
hook					
unspecified	Supported				Supported

The execution context of a `RunnableEntity` is considered as `task`.

⌋

[TPS_BSWMDT_04180] invocation of `ExecutableEntity`s by direct function call dependent from `BswExecutionContext` ⌈

The invocation of an `ExecutableEntity` with an `interruptCat1` can be implemented with a direct function call if the `BswExecutionContext` of the caller `BswModuleEntry` is set to `task`, `interruptCat2` or `interruptCat1`.

This applies to the invocation of a `triggered ExecutableEntity` by the `SchM_Trigger`, `SchM_ActMain` or `Rte_Trigger` APIs, or to the invocation of an `OnEntry ExecutableEntity`, `OnTransition ExecutableEntity`, `OnExit ExecutableEntity` or `mode switch acknowledge ExecutableEntity` by the `SchM_Switch` or `Rte_Switch` APIs. For more information about the technical terms refer to [9]⌋

Enumeration	**BswCallType**
Note	Denotes the mechanism by which the entry into the Bsw module shall be called.
Aggregated by	BswModuleEntry.callType
Literal	***Description***
callback	Callback (i.e. the caller specifies the signature) **Tags:** atp.EnumerationLiteralIndex=0
callout	Callout - provide defined means to extend the functionality of an existing module. In this case caller specifies the signature. **Tags:** atp.EnumerationLiteralIndex=4
interrupt	Interrupt routine **Tags:** atp.EnumerationLiteralIndex=1
regular	Regular API call **Tags:** atp.EnumerationLiteralIndex=2
scheduled	Called by the scheduler **Tags:** atp.EnumerationLiteralIndex=3

Table 4.4: BswCallType

Enumeration	**SwServiceImplPolicyEnum**
Note	This specifies the legal values for the implementation policies for services (in AUTOSAR: BswModule Entry-s).
Aggregated by	BswModuleEntry.swServiceImplPolicy
Literal	***Description***
inline	inline service definition. **Tags:** atp.EnumerationLiteralIndex=0
inlineConditional	The service (in AUTOSAR: BswModuleEntry) is implemented in a way that it either resolves to an inline function or to a standard function depending on conditions set at a later point in time. The following two values are standardized (to be used for code sections only and exclusively to each other): • INLINE - The code section is declared with the keyword "inline". • LOCAL_INLINE - The code section is declared with the keyword "static inline". In both cases (INLINE and LOCAL_INLINE) the inline expansion depends on the compiler. Depending on this, the code section either corresponds to an actual section in memory or is put into the section of the caller. **Tags:** atp.EnumerationLiteralIndex=1
macro	macro service definition. **Tags:** atp.EnumerationLiteralIndex=2
standard	Standard service and default value, if nothing is defined. **Tags:** atp.EnumerationLiteralIndex=3

Table 4.5: SwServiceImplPolicyEnum

[constr_4014] Call type and execution context

Imposition time: IT_BswMD

⌈Within a given BswModuleEntry, the following constraint holds for its attributes:

- if attribute callType is set to value interrupt, it is not allowed that attribute executionContext is set to either of the values task or hook
- if attribute callType is set to value scheduled, it is not allowed that attribute executionContext is set to either of the values interruptCat1 or interruptCat2

⌋

Please note that all combinations of BswModuleEntry.callType and BswModuleEntry.executionContext that are not restricted by [constr_4014] are allowed.

[TPS_BSWMDT_04008] C-symbol of BswModuleEntry ⌈The shortName of a BswModuleEntry shall be equal to the name of the C-function implementing it, with one exception: In case of several instances of the same module (e.g. several CAN drivers) on a single CPU, the C-function names shall be made unique by inserting additional characters called “infixes”. Since each BSW module instance is implemented by a separate piece of code, the infixes are defined as part of each single BswImplementation of the providing module.⌋

For details see 6.

As a result, also the code of a module requiring a BswModuleEntry with infixes needs some adjustment, but this adjustment can be made only at integration time. Currently there is no standardized mechanisms for this task in AUTOSAR, but it can be solved with vendor specific configuration parameters (of the requiring modules) whose values are set at integration time according to the infixes of the actually providing modules.

[TPS_BSWMDT_04009] Usage of SwServiceArg ⌈Class SwServiceArg[1] is used to declare the properties of the function arguments as well as of the return type.⌋

[constr_4106] Restriction for the value of SwServiceArg.swImplPolicy

Imposition time: IT_BswMD

⌈The attribute SwServiceArg.swImplPolicy shall only have one of the following values:

- SwImplPolicyEnum.const
- SwImplPolicyEnum.standard

⌋

[constr_4107] swImplPolicy for SwServiceArg

Imposition time: IT_BswMD

⌈The overriding value of attribute swImplPolicy of a SwServiceArg shall be standard or const.⌋

[constr_4108] Restriction regarding the value of SwServiceArg.category

Imposition time: IT_BswMD

⌈The attribute SwServiceArg.category shall only have the following values:

- VALUE[2]
- DATA_REFERENCE
- FUNCTION_REFERENCE
- TYPE_REFERENCE
- MACRO

⌋

Please note that some regulation for the usage of SwServiceArg exist in the context of the TPS Software Component Template [5].

[1] SwServiceArg and its attributes belong to the meta-model part re-engineered from MSR-SW. This subset of MSR-SW is defined by the AUTOSAR meta-model and the XML schema published as part of an AUTOSAR release. The relevant classes are shown as green in the class diagrams. See [5] and [11] for more explanation.

[2] This option has **very few** valid use cases, e.g. for defining a function pointer in native C notation, for example: `int (*SwCluC_BManif_VoidFncPtrType)(void);`

Class	**SwServiceArg**			
Note	Specifies the properties of a data object exchanged during the call of an SwService, e.g. an argument or a return value. The SwServiceArg can also be used in the argument list of a C-macro. For this purpose the category shall be set to "MACRO". A reference to implementationDataType can optional be added if the actual argument has an implementationDataType.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswModuleEntry.argument, BswModuleEntry.returnType			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
direction	ArgumentDirectionEnum	0..1	attr	Specifies the direction of the data transfer. The direction shall indicate the direction of the actual information that is being consumed by the caller and/or the callee, not the direction of formal arguments in C. The attribute is optional for backwards compatibility reasons. For example, if a pointer is used to pass a memory address for the expected result, the direction shall be "out". If a pointer is used to pass a memory address with content to be read by the callee, its direction shall be "in". **Tags:** xml.sequenceOffset=10
swArraysize	ValueList	0..1	aggr	This turns the argument of the service to an array. **Tags:** atp.Splitkey=swArraysize xml.sequenceOffset=20
swDataDefProps	SwDataDefProps	0..1	aggr	Data properties of this SwServiceArg. **Tags:** atp.Splitkey=swDataDefProps xml.sequenceOffset=30

Table 4.6: SwServiceArg

[TPS_BSWMDT_04010] Semantics of `SwServiceArg.swDataDefProps.implementationDataType` ⌈`SwServiceArg.swDataDefProps.implementationDataType` shall be used to relate the data definition to a reusable type definition (corresponds to a C typedef). Because `ImplementationDataType` is an `ARElement` and itself contains `SwDataDefProps`, it is possible to declare the required data properties as part of an `ImplementationDataType` and reuse it as a data type by referring to it.⌋

`ImplementationDataTypeElement` within an `ImplementationDataType` allows to declare composite types (corresponding to C-structs or -arrays).

[TPS_BSWMDT_04011] Semantics of `SwServiceArg.swDataDefProps.swPointerTargetProps` ⌈`SwServiceArg.swDataDefProps.swPointerTargetProps` together with its category (see [5]) is used to declare an argument or return type as a pointer to either another data object or to a function.⌋

Class	**SwPointerTargetProps**			
Note	This element defines, that the data object (which is specified by the aggregating element) contains a reference to another data object or to a function in the CPU code. This corresponds to a pointer in the C-language. The attributes of this element describe the category and the detailed properties of the target which is either a data description or a function signature.			
Base	*ARObject*			
Aggregated by	SwDataDefProps.swPointerTargetProps			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
functionPointer Signature	BswModuleEntry	0..1	ref	The referenced BswModuleEntry serves as the signature of a function pointer definition. Primary use case: function pointer passed as argument to other function. **Tags:** atp.Splitkey=functionPointerSignature xml.sequenceOffset=40 This Attribute is only used by the AUTOSAR Classic Platform.
swDataDef Props	SwDataDefProps	0..1	aggr	The properties of the target data type. **Tags:** atp.Splitkey=swDataDefProps xml.sequenceOffset=30
targetCategory	Identifier	0..1	attr	This specifies the category of the target: • In case of a data pointer, it shall specify the category of the referenced data. • In case of a function pointer, it could be used to denote the category of the referenced BswModuleEntry. **Tags:** xml.sequenceOffset=5

Table 4.7: SwPointerTargetProps

[constr_4021] Implementation policy of function pointer target

Imposition time: IT_BswMD

⌈
A BswModuleEntry can only be used as target of a function pointer (SwPointer-TargetProps.functionPointerSignature), if its swServiceImplPolicy is 'standard'.⌋

For more information on ImplementationDataType, SwBaseType and the usage of SwServiceArg.category in relation to SwDataDefProps see [5]. This includes the usage of category VALUE for SwServiceArg.category which supports to model C-signatures using C-build in data types or function pointers to C-signatures using C-build in data types. For instance: int (*SwCluC_BManif_VoidFncPtrType)(void).

Please note that for AUTOSAR Basic Software this is seen as an exceptional case since regularly such types are abstracted via the Platform Types.

Function signatures containing the keyword **void** in C deserve special attention:

[constr_4056] `BswModuleEntry` with no `returnType`

Imposition time: IT_BswMD

⌈In case of an empty return type (“void” in C) the reference BswModuleEntry.returnType shall not be set.⌋

[constr_4057] `BswModuleEntry` with no argument

Imposition time: IT_BswMD

⌈In case of an empty argument list (“void” in C) no reference BswModuleEntry.argument shall be set.⌋

Note that nonetheless a SwBaseType exists which represents the **void** type as a pointer target.

[constr_4087] Usage of category “MACRO”

Imposition time: IT_BswMD

⌈It is only allowed to use the category “MACRO” for SwServiceArg if the owning BswModuleEntry has its swServiceImplPolicy attribute set to macro.⌋

Furthermore the usage of category ‘MACRO’ defined in chapter “Data Categories” in [5] is restricted to SwServiceArg like defined in [constr_4087].

It is still supported that BswModuleEntry being a macro describes its SwServiceArg with other categories defined in table 5.7 in [5] in order to express the assumed type of the return value and macro argument.

[TPS_BSWMDT_04012] Semantics of `SwServiceArg.direction` ⌈SwServiceArg.direction allows to declare the direction of data flow.⌋

Please note that the SwServiceArg.direction attribute was introduced in R4.0.3 and is optional for backwards compatibility reasons.

Enumeration	**ArgumentDirectionEnum**
Note	Use cases: • Arguments in ClientServerOperation can have different directions that need to be formally indicated because they have an impact on how the function signature looks like eventually. • Arguments in BswModuleEntry already determine a function signature, but the direction is used to specify the semantics, especially of pointer arguments.
Aggregated by	ArgumentDataPrototype.direction, DiagnosticSovdAccessArgument.direction, RunnableEntity Argument.direction, SwServiceArg.direction
Literal	***Description***
in	The argument value is passed to the callee. **Tags:** atp.EnumerationLiteralIndex=0

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Enumeration	ArgumentDirectionEnum
inout	The argument value is passed to the callee but also passed back from the callee to the caller. **Tags:** atp.EnumerationLiteralIndex=1
out	The argument value is passed from the callee to the caller. **Tags:** atp.EnumerationLiteralIndex=2

Table 4.8: ArgumentDirectionEnum

This value shall be chosen compatible to the role and the formal signature of the SwServiceArg instance:

[constr_4052] BswModuleEntry returnType direction

Imposition time: IT_BswMD

⌈
BswModuleEntry.returnType.direction shall not have the value **in** or **inout**.⌋

[constr_4053] BswModuleEntry argument direction

Imposition time: IT_BswMD

⌈
If BswModuleEntry.argument.direction has the value **out** or **inout**, the corresponding BswModuleEntry.argument.swDataDefProps plus eventually referred ImplementationDataType shall be such that they result in a pointer declaration.⌋

It is also possible to specify function signatures containing the keyword **enum** in C[3]:

[TPS_BSWMDT_04091] Function signature containing the keyword enum in C ⌈The respective ImplementationDataType or ImplementationDataTypeElement has to include the string "enum" in the associated SwDataDefProps.additionalNativeTypeQualifier and use an associated CompuMethod with category TEXTTABLE.

Hints: This information can be used by a code generator to create the correct signature. In case this method is applied to generate C-style enums it should be avoided to use the same CompuMethod as input to a generator (for example the RTE generator) that produces preprocessor literals instead. Otherwise, the enum-literals and the preprocessor-literals might get in conflict.⌋

4.2 BSW Mode Declaration

[TPS_BSWMDT_04013] Usage of BswModuleDescription.providedModeGroup ⌈With the optional attribute providedModeGroup a BSW module can declare one or more ModeDeclarationGroupPrototypes, each defining a set of modes (mode group) which is used to control the activity of other BSW modules. Those other

[3]Note that the usage of C-enum types is not allowed for signatures created by the RTE generator.

modules which require to be controlled by the mode group, shall declare a compatible ModeDeclarationGroupPrototype as attribute requiredModeGroup.⌋

For more information see figure 4.2.

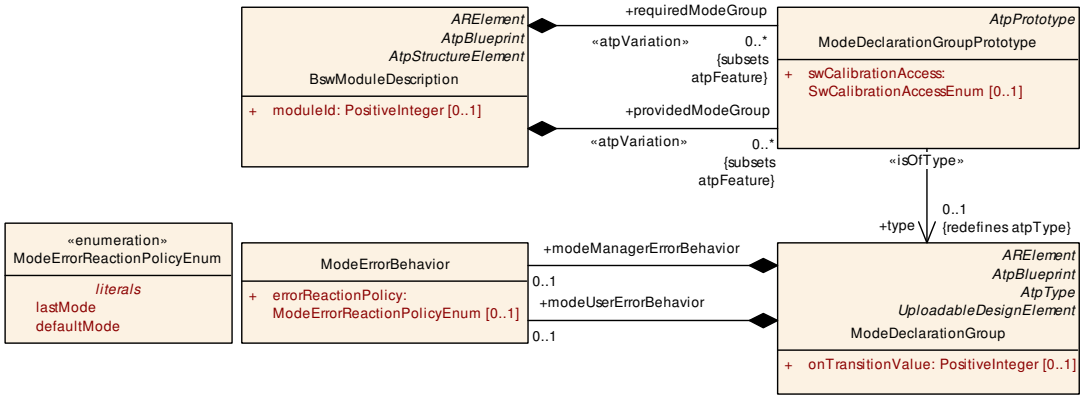

Figure 4.2: Details of BSW Interfaces for modes

For the compatibility of ModeDeclarationGroupPrototypes see [5] [constr_1074]. These declarations allow for the appropriate API generation and coordination of mode switches by the BSW Scheduler. Note that the configuration of the BSW Scheduler actually determines which provided mode group is connected to which required one. This makes the specification of the individual module independent of the overall BSW setup.

A ModeDeclarationGroupPrototype is based on a type definition by meta-class ModeDeclarationGroup. It is possible to use the same ModeDeclarationGroup within the basic software and for software components above the RTE as well, therefore ModeDeclarationGroupPrototype and ModeDeclarationGroup are part of the CommonStructure package of the meta-model. For more information on the semantics of modes see [5].

By aggregation of ModeErrorBehavior a ModeDeclarationGroup can define the behavior of mode managers and/or mode users in case of errors. This is further explained in [5] Chapter 9.4 *"Mode Error Behavior"*.

Class	**ModeDeclarationGroupPrototype**			
Note	The ModeDeclarationGroupPrototype specifies a set of Modes (ModeDeclarationGroup) which is provided or required in the given context.			
Base	*ARObject*, *AtpFeature*, *AtpPrototype*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, BswModuleDescription.providedModeGroup, BswModuleDescription.requiredModeGroup, FirewallStateSwitchInterface.firewallStateMachine, FunctionGroupSet.functionGroup, ModeSwitchInterface.modeGroup, Process.processStateMachine, StateManagementStateNotification.stateMachine			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

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△

Class	**ModeDeclarationGroupPrototype**			
swCalibration Access	SwCalibrationAccess Enum	0..1	attr	This allows for specifying whether or not the enclosing ModeDeclarationGroupPrototype can be measured at run-time. This Attribute is only used by the AUTOSAR Classic Platform.
type	ModeDeclarationGroup	0..1	tref	The "collection of ModeDeclarations" (= ModeDeclaration Group) supported by a component **Stereotypes:** isOfType **Tags:** atp.Splitkey=type

Table 4.9: ModeDeclarationGroupPrototype

Note that by aggregating `SwCalibrationAccessEnum` in the role `swCalibration-Access` `ModeDeclarationGroupPrototype` gains the ability to become measurable. For the constraint on the possible values of `swCalibrationAccess` please refer to [5].

Class	**ModeDeclarationGroup**			
Note	A collection of Mode Declarations. Also, the initial mode is explicitly identified. **Tags:** atp.recommendedPackage=ModeDeclarationGroups			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*, *UploadableDesignElement*, *Uploadable PackageElement*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
initialMode	ModeDeclaration	0..1	ref	The initial mode of the ModeDeclarationGroup. This mode is active before any mode switches occurred. **Tags:** atp.Splitkey=initialMode
mode Declaration	ModeDeclaration	*	aggr	The ModeDeclarations collected in this ModeDeclaration Group. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=modeDeclaration, modeDeclaration.short Name, modeDeclaration.variationPoint.shortLabel vh.latestBindingTime=blueprintDerivationTime
modeManager ErrorBehavior	ModeErrorBehavior	0..1	aggr	This represents the ability to define the error behavior expected by the mode manager in case of errors on the mode user side (e.g. terminated mode user). **Tags:** atp.Splitkey=modeManagerErrorBehavior This Attribute is only used by the AUTOSAR Classic Platform.
modeTransition	ModeTransition	*	aggr	This represents the avaliable ModeTransitions of the ModeDeclarationGroup **Tags:** atp.Splitkey=modeTransition, modeTransition.short Name This Attribute is only used by the AUTOSAR Classic Platform.

▽

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Class	**ModeDeclarationGroup**			
modeUserError Behavior	ModeErrorBehavior	0..1	aggr	This represents the definition of the error behavior expected by the mode user in case of errors on the mode manager side (e.g. terminated mode manager). **Tags:** atp.Splitkey=modeUserErrorBehavior This Attribute is only used by the AUTOSAR Classic Platform.
onTransition Value	PositiveInteger	0..1	attr	The value of this attribute shall be taken into account by the RTE generator for programmatically representing a value used for the transition between two statuses. This Attribute is only used by the AUTOSAR Classic Platform.

Table 4.10: ModeDeclarationGroup

Class	**ModeDeclaration**			
Note	Declaration of one Mode. The name and semantics of a specific mode is not defined in the meta-model.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, ModeDeclarationGroup.modeDeclaration			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
value	PositiveInteger	0..1	attr	The RTE shall take the value of this attribute for generating the source code representation of this Mode Declaration.

Table 4.11: ModeDeclaration

Class	**ModeTransition**			
Note	This meta-class represents the ability to describe possible ModeTransitions in the context of a Mode DeclarationGroup.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, ModeDeclarationGroup.modeTransition			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
enteredMode	ModeDeclaration	0..1	ref	This represents the entered model of the ModeTransition. **Tags:** atp.Splitkey=enteredMode
exitedMode	ModeDeclaration	0..1	ref	This represents the exited mode of the ModeTransition **Tags:** atp.Splitkey=exitedMode

Table 4.12: ModeTransition

Class	**ModeErrorBehavior**			
Note	This represents the ability to define the error behavior in the context of mode handling.			
Base	*ARObject*			
Aggregated by	ModeDeclarationGroup.modeManagerErrorBehavior, ModeDeclarationGroup.modeUserErrorBehavior			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
defaultMode	ModeDeclaration	0..1	ref	This represents the ModeDeclaration that is considered the error mode in the context of the enclosing Mode DeclarationGroup. **Tags:** atp.Splitkey=defaultMode
errorReaction Policy	ModeErrorReaction PolicyEnum	0..1	attr	This represents the ability to define the policy in terms of which default model shall apply in case an error occurs.

Table 4.13: ModeErrorBehavior

Enumeration	**ModeErrorReactionPolicyEnum**
Note	This represents the ability to specify the reaction on a mode error.
Aggregated by	ModeErrorBehavior.errorReactionPolicy
Literal	*Description*
defaultMode	This represents the ability to switch to the defaultMode in case of a mode error. **Tags:** atp.EnumerationLiteralIndex=0
lastMode	This represents the ability to keep the last mode in case of a mode error. **Tags:** atp.EnumerationLiteralIndex=1

Table 4.14: ModeErrorReactionPolicyEnum

In order to avoid conflicts in generated header files which might be included in the same C-file, the following constraint holds:

[constr_4059] Different mode groups referred by a BSWM shall have different names

Imposition time: IT_BswMD

⌈A BswModuleDescription may not refer to different ModeDeclarationGroups (via requiredModeGroup and/or providedModeGroup) having the same shortName but different elements.⌋

The attributes ModeDeclaration.value and ModeDeclarationGroup.onTransitionValue and the category of ModeDeclarationGroup allow to determine the generation of source code from the formal definition. For constraints on these attributes refer to [5].

[TPS_BSWMDT_04014] ModeRequestTypeMap in BSW ⌈Furthermore, it is required to define a ModeRequestTypeMap in order to explicitly specify by which data type a ModeDeclarationGroup is implemented:⌋

Class	**ModeRequestTypeMap**			
Note	Specifies a mapping between a ModeDeclarationGroup and an ImplementationDataType. This ImplementationDataType shall be used to implement the ModeDeclarationGroup.			
Base	*ARObject*			
Aggregated by	DataTypeMappingSet.modeRequestTypeMap			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
implementation DataType	AbstractImplementation DataType	0..1	ref	This is the corresponding AbstractImplementationDataType. It shall be modeled along the idea of an "unsigned integer-like" data type. **Tags:** atp.Splitkey=implementationDataType
modeGroup	ModeDeclarationGroup	0..1	ref	This is the corresponding ModeDeclarationGroup. **Tags:** atp.Splitkey=modeGroup

Table 4.15: ModeRequestTypeMap

[constr_4063] Restrictions of ModeRequestTypeMap in BSW

Imposition time: IT_BswMD

⌈For every ModeDeclarationGroup referenced by a ModeDeclarationGroup-Prototype used in a BswModuleDescription a ModeRequestTypeMap shall exist that points to the ModeDeclarationGroup and also to an eligible ImplementationDataType.

The ModeRequestTypeMap shall be aggregated by a DataTypeMappingSet which is referenced from the BswInternalBehavior that is aggregated by the Bsw-ModuleDescription.⌋

Refer to [5] for restrictions on the ImplementationDataType that can be used for such a mapping. Since provided and required modes are connected via ECU configuration, it is not possible to check constraints on these ImplementationDataTypes on the level of BSWMDs only.

4.3 BSW Trigger Declaration

[TPS_BSWMDT_04015] Usage of Trigger in BSW ⌈With the optional attribute releasedTrigger a BSW module can declare that it releases one or more Triggers which are used to trigger events across BSW modules. Other modules which want to react on such a trigger, shall declare a compatible Trigger as attribute requiredTrigger (for the compatibility of Triggers refer to [5] [constr_1038]). These declarations together with the associated event model allow for the appropriate API generation and coordination by the BSW Scheduler.⌋

For details see chapter 5.7.

Note that the configuration of the BSW Scheduler actually determines which released trigger is connected to which required one. This makes the specification of the individual module independent of the overall BSW setup.

Class	Trigger			
Note	A trigger which is provided (i.e. released) or required (i.e. used to activate something) in the given context.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, BswModuleDescription.releasedTrigger, BswModuleDescription.requiredTrigger, ServiceInterface.trigger, TriggerInterface.trigger			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
swImplPolicy	SwImplPolicyEnum	0..1	attr	This attribute, when set to value queued, allows for a queued processing of Triggers. This Attribute is only used by the AUTOSAR Classic Platform.
triggerPeriod	MultidimensionalTime	0..1	aggr	Optional definition of a period in case of a periodically (time or angle) driven external trigger. **Tags:** atp.Splitkey=triggerPeriod This Attribute is only used by the AUTOSAR Classic Platform.

Table 4.16: Trigger

A `Trigger` declaration can optionally set an attribute to define its queuing behavior. This is in more detail explained in [5]. The usage of the enumeration type `SwImplPolicyEnum` in `Trigger.swImplPolicy` is restricted in the following way:

[constr_4060] Allowed values of `Trigger.swImplPolicy` for BSW

Imposition time: `IT_BswMD`

⌈The **only** allowed values for the attribute `Trigger.swImplPolicy` are either `STANDARD` (in which case the `Trigger` processing does not use a queue) or `QUEUED` (in which case the processing of `Trigger`s positively uses a queue).⌋

4.4 BSW Module Dependency

4.4.1 General

Figure 4.3 and the following table show the details of class `BswModuleDependency`. This class represents the expectations of one BSW module or cluster on another BSW module or cluster.

It should be noted, that in order to define a dependency it is not required to have a complete model of the the targeted `BswModuleDescription`. This allows to maintain each BSWMD separately. Nonetheless, the target module needs to be identified by the attribute `BswModuleDependency.targetModuleId` and/or the «atpUriDef» reference `BswModuleDependency.targetModuleRef`. Of course, if both attributes are used their values shall be consistent.

Because the module identifier is not always sufficient to identify the target module (e.g. Complex Drivers all have the same module ID), the usage of `targetModuleRef` is recommended.

A module cannot state a dependency to itself:

[constr_4038] bswModuleDependency shall refer to a different module

Imposition time: IT_BswMD

⌈

- BswModuleDescription.bswModuleDependency.targetModuleId (if given) shall differ from BswModuleDescription.moduleId. This does not hold if the value is 254 (used for IO Hardware Abstraction modules) or 255 (used for Complex Driver modules).
- BswModuleDependency.targetModuleRef (if given) shall differ from the package location of the BswModuleDescription that owns the BswModuleDependency.

⌋

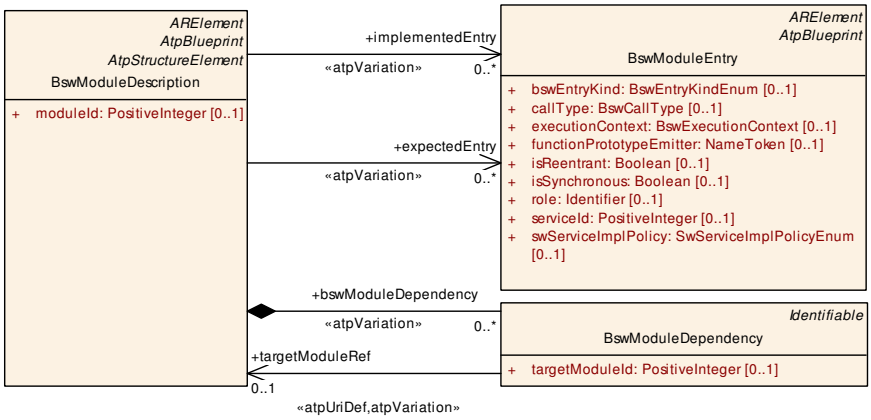

Figure 4.3: Details of class BswModuleDependency

Class	**BswModuleDependency**			
Note	This class collects the dependencies of a BSW module or cluster on a certain other BSW module. This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswModuleDescription.bswModuleDependency			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
targetModuleId	PositiveInteger	0..1	attr	AUTOSAR identifier of the target module of which the dependencies are defined. This information is optional, because the target module may also be identified by targetModuleRef. **Tags:** xml.sequenceOffset=5

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Class	**BswModuleDependency**			
targetModule Ref	BswModuleDescription	0..1	ref	Reference to the target module. It is an <<atpUriDef>> because the reference shall be used to identify the target module without actually needing the description of that target module. **Stereotypes:** atpUriDef; atpVariation **Tags:** atp.Splitkey=targetModuleRef, targetModuleRef.bswModuleDescription, targetModuleRef.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=7

Table 4.17: BswModuleDependency

The set of `expectedEntry`-s represent the interface imported from another module in terms of function calls.

4.4.2 Dependency and Packages

It is important to note that via `BswModuleDependency` the module description that owns the dependency refers to model elements which are also referred by the description of the module it depends on. This holds especially for instances of `BswModuleEntry` but also for other `ARElement`s like data types referred from there. In order to avoid inconsistencies, one should put such mutually used M1 elements under a well defined location in terms of `ARPackage`s.

Rules for the package location of standardized M1 model elements are given in [1] Chapter 3.1 *"Identifying M1 elements in packages"*. As a consequence we can state:

[TPS_BSWMDT_04016] Location of standardized `BswModuleEntry`-s ⌈Instances of standardized `BswModuleEntry`s defined for an AUTOSAR module {reservedName}[4] shall be located under a package `AUTOSAR_{reservedName}/BswModuleEntrys/`⌋

for example

`AUTOSAR_Can/BswModuleEntrys/Can_SetControllerMode`

[TPS_BSWMDT_04017] Reference to standardized `BswModuleEntry`-s ⌈If a BSWMD refers to a standardized `BswModuleEntry` via `implementedEntry` or `expectedEntry` it shall also use the path `AUTOSAR_{reservedName}/BswModuleEntrys/` thus indicating that it relies on the AUTOSAR compliant implementation of the referred API functions.⌋

[4]Here {reservedName} is the module abbreviation of the standardized ICC3 module to which the API is belongs.

It is highly recommended to follow an analog pattern (but not starting with AUTOSAR) for the package names of non-standardized ARElements too.[5] If a BSWMD refers in its dependency to a path like

```
<vendor_specific_prefix>_{reservedName}/BswModuleEntrys/
```

for example

```
VendorX_Can/BswModuleEntrys/Can_SpecialFunction
```

this would indicate that the BSWMD relies on a vendor specific function resp. callback of the referred module (for example *Can*).

In addition, the value of targetModuleRef should be set to

```
VendorX_Can/BswModuleDescriptions/Can
```

In this example, we would instead of *Can* use a non-standardized module name if the referred module is a Complex Driver. In this case, the module name would be equal to the BswModuleDescription.shortName of the BSWMD of that Complex Driver.

4.4.3 Dependency: Examples and Constraints

Note that expectedEntry-s do also include calls in interrupt context. An example could be as follows:

Consider we want to describe the callback-dependencies of an external EEPROM driver module from the (standardized) AUTOSAR SPI module. Consider the SPI driver offers an outgoing callback “EndJobNotification” always called in interrupt context. To describe the dependency we would have to create an instance BswModuleDescription.bswModuleDependency and do the following assignments:

- bswModuleDependency.targetModuleId = module identifier of the SPI driver (alternatively, we could use bswModuleDependency.targetModuleRef)

Figure 4.4 shows another example for an M1 model of a dependency between two hypothetical BSW modules. The dependency includes one regular function implemented by the lower layer module “Any” (which could stand for an MCAL module) and two callbacks implemented by the upper layer Module “MyComplexDriver”[6].

[5] The recommended name of the package that should be the immediate container of instances of a given meta-class derived from ARElement is defined as an UML-tag and can be seen in the respective class table.

[6] The AUTOSAR BSW architecture distinguishes the semantics of *callback* and *callout*: Whereas a *callback* notifies something to an upper layer module, a *callout* is used to add functionality to the calling module. Within the BSWMD, these two mechanisms can be described in the same way.

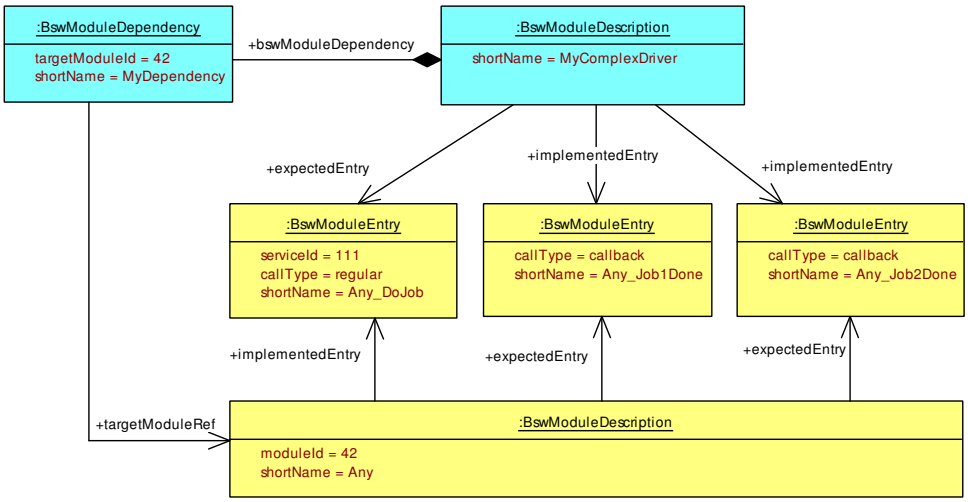

Figure 4.4: Example for an M1 model of a dependency between two modules

Note that the model of the outgoing callbacks can (in general) only be completed at configuration time, because the number and names of the BswModuleEntrys used as callbacks might be unknown at the time the BSWMD of the lower level module is delivered. However at that point in time it is still possible to describe the signature of the callback function by using an AtpBlueprint of the intended BswModuleEntry and to deliver this description together with the BSWMD of the lower level module. For more details on the blueprint concept refer to [8].

In addition to direct function calls, two BSW modules can also be connected via triggers or modes declared in their interfaces. This does not show up as a dependency, because the actual connection is created by the configuration of the BSW Scheduler.

Note that a BswModuleDependency can also contain ServiceNeeds. However, this is a deprecated relationship (only allowed for backwards compatibility) since the declaration of ServiceNeeds has been moved to the internal behavior level, see chapter 11.

4.5 BswModuleEntry Relationship Set

The BswEntryRelationshipSet describes a collection of BswEntryRelationships. A BswEntryRelationship describes a relationship between two BswModuleEntrys and the type of relationship. This is typically used to express that a concrete BswModuleEntry is derived from an abstract BswModuleEntry. In this case the bswEntryRelationshipType is set to derivedFrom, the BswEntryRelationship.from references the abstract BswModuleEntry and the BswEntryRelationship.to references the concrete BswModuleEntry.

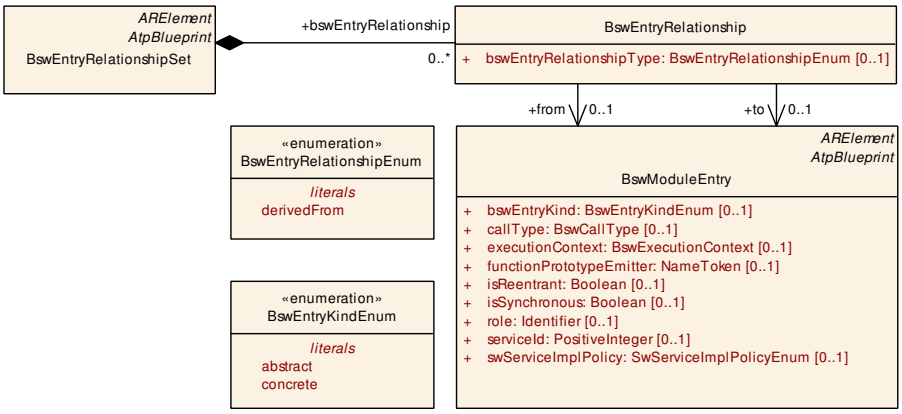

Figure 4.5: BswEntryRelationshipSet

Class	**BswEntryRelationshipSet**			
Note	Describes a set of relationships between two BswModuleEntrys. **Tags:** atp.recommendedPackage=BswEntryRelationshipSets This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bswEntry Relationship	BswEntryRelationship	*	aggr	Relationship between two BswModuleEntrys. **Tags:** atp.Splitkey=bswEntryRelationship

Table 4.18: BswEntryRelationshipSet

[constr_10265] Existence of attribute BswEntryRelationshipSet.bswEntry-Relationship

Imposition time: IT_BswMD

⌈For each BswEntryRelationshipSet, the attribute bswEntryRelationship shall exist at least once.⌋

Class	**BswEntryRelationship**			
Note	Describes a relationship between two BswModuleEntrys and the type of relationship.			
Base	*ARObject*			
Aggregated by	BswEntryRelationshipSet.bswEntryRelationship			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bswEntry Relationship Type	BswEntryRelationship Enum	0..1	attr	Denotes the type of the relationship. **Tags:** xml.sequenceOffset=5
from	BswModuleEntry	0..1	ref	Type of relationship that refers to the abstract BswModule Entry. Please notice that in this case the bswEntry RelationshipType shall be set to drivedFrom. **Tags:** atp.Splitkey=from This Attribute is only used by the AUTOSAR Classic Platform.

▽

△

Class	**BswEntryRelationship**			
to	BswModuleEntry	0..1	ref	Type of relationship that refers to the concrete Bsw ModuleEntry **Tags:** atp.Splitkey=to This Attribute is only used by the AUTOSAR Classic Platform.

Table 4.19: BswEntryRelationship

[constr_10266] Existence of attribute `BswEntryRelationship.bswEntryRelationshipType`

Imposition time: `IT_BswMD`

⌈For each `BswEntryRelationship`, the attribute `bswEntryRelationshipType` shall exist.⌋

[constr_10267] Existence of reference in the role `BswEntryRelationship.from`

Imposition time: `IT_BswMD`

⌈For each `BswEntryRelationship`, the reference in the role `from` shall exist.⌋

[constr_10268] Existence of reference in the role `BswEntryRelationship.to`

Imposition time: `IT_BswMD`

⌈For each `BswEntryRelationship`, the reference in the role `to` shall exist.⌋

Enumeration	**BswEntryRelationshipEnum**
Note	Define the type of relationship between two BswModuleEntrys.
Aggregated by	BswEntryRelationship.bswEntryRelationshipType
Literal	*Description*
derivedFrom	Describes that the BswModuleEntry referenced as "to" needs to have the same signature as the "abstract" BswModuleEntry referenced as "from". **Tags:** atp.EnumerationLiteralIndex=0

Table 4.20: BswEntryRelationshipEnum

4.6 BSW Inter-Partition Interface

4.6.1 Overview

AUTOSAR BSW has the ability to communicate across partition boundaries which includes communication across processor core boundaries.

While this is in general possible over the RTE by using Ports and Software Components (e.g. Complex Drivers) on top of the BSW modules, there exist more efficient mechanisms of doing this with the help of “glue code” provided by the BSW Scheduler part of the RTE. See [12] for a detailed guideline.

These mechanisms follow the Client-Server communication pattern or the Sender-Receiver communication pattern of the VFB - see [13] - but cannot be used for inter-ECU communication.

The required meta-model part is shown in Figure 4.6.

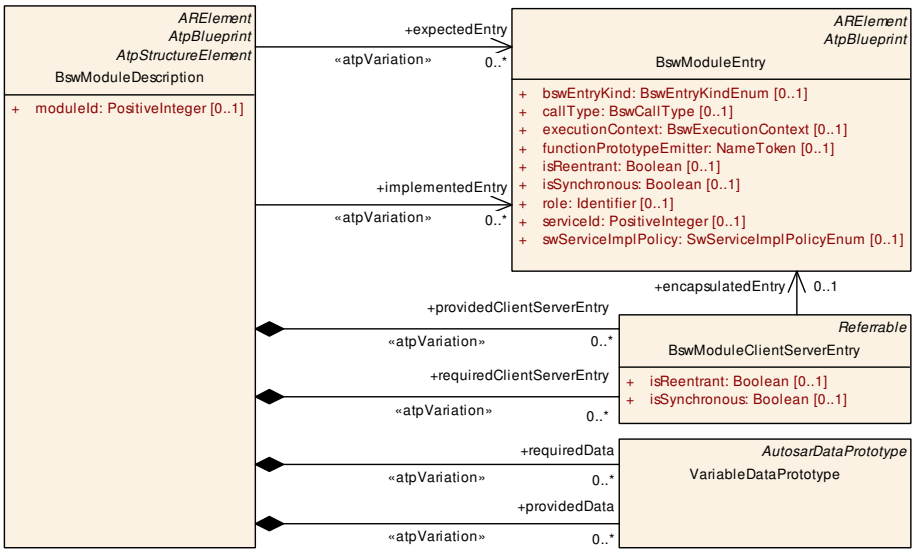

Figure 4.6: BSW Interfaces for inter-partition and multicore communication

4.6.2 Client-Server

Class	**BswModuleClientServerEntry**			
Note	This meta-class represents a single API entry into the BSW module or cluster that has the ability to be called in client-server fashion via the BSW Scheduler. In this regard it is more special than BswModuleEntry and can be seen as a wrapper around the Bsw ModuleEntry to which it refers (property encapsulatedEntry). **Tags:** atp.recommendedPackage=BswModuleEntrys			
Base	*ARObject*, *Referrable*			
Aggregated by	BswModuleDescription.providedClientServerEntry, BswModuleDescription.requiredClientServerEntry			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
encapsulated Entry	BswModuleEntry	0..1	ref	The underlying BswModuleEntry. **Tags:** atp.Splitkey=encapsulatedEntry xml.sequenceOffset=5 This Attribute is only used by the AUTOSAR Classic Platform.

△

Class	**BswModuleClientServerEntry**			
isReentrant	Boolean	0..1	attr	Reentrancy from the viewpoint of clients invoking the service via the BSW Scheduler: • true: Enables the service to be invoked again, before the service has finished. • false: It is prohibited to invoke the service again before is has finished. **Tags:** xml.sequenceOffset=10
isSynchronous	Boolean	0..1	attr	Synchronicity from the viewpoint of clients invoking the service via the BSW Scheduler: • true: This calls a synchronous service, i.e. the service is completed when the call returns. • false: The service (on semantical level) may not be complete when the call returns. **Tags:** xml.sequenceOffset=15

Table 4.21: BswModuleClientServerEntry

[constr_10269] Existence of the reference in the role `BswModuleClientServerEntry.encapsulatedEntry`

Imposition time: `IT_BswMD`

⌈For each `BswModuleClientServerEntry`, the the reference in the role `encapsulatedEntry` shall exist.⌋

[TPS_BSWMDT_04098] Declaration of `BswModuleClientServerEntry` ⌈With the optional attribute `providedClientServerEntry` a BSW module can declare that it provides a `BswModuleClientServerEntry` that can be used in the server role for client-server communication across partition boundaries.[7]. The client module (which may be a different or the same module) shall declare a compatible `BswModuleClientServerEntry` as attribute `requiredClientServerEntry`. These declarations together with the associated event model allow for the appropriate API generation and coordination by the BSW Scheduler.⌋

For details see chapter 5.7.

[constr_4074] Compatibility of `BswModuleClientServerEntry`-s

Imposition time: `IT_BswMD`

⌈Two `BswModuleClientServerEntry`-s are compatible if and only if all of the following conditions hold:

- Their synchronicity values are identical. These values are taken from the attribute `isSynchronous` or, if this is undefined, from `encapsulatedEntry.isSynchronous`.
- The two `BswModuleEntry`-s referred as `encapsulatedEntry` have `SwServiceArg`, `returnType`, `serviceId` and `swServiceImplPolicy` identical.

[7] This does not exclude configurations where client and server are executed in the same partition.

⌋

Notice that executionContext shall always follow [TPS_BSWMDT_04179].

The configuration of the BSW Scheduler determines which providedClient-ServerEntry is actually connected to which requiredClientServerEntry. This makes the specification of the individual module independent of the overall BSW setup.

[TPS_BSWMDT_04099] Semantics of BswModuleClientServerEntry attributes ⌈The optional attributes BswModuleClientServerEntry.isReentrant and BswModuleClientServerEntry.isSynchronous can have different values than the corresponding attributes of the referred BswModuleClientServer-Entry.encapsulatedEntry, because the first two attributes describe properties seen by a client calling via the BSW Scheduler wheres the latter contains the properties seen by direct callers.

If one of these attributes is undefined, its value is considered as equal to the respective attribute of the referred encapsulatedEntry.⌋

[TPS_BSWMDT_04100] Different ways of referring BswModuleEntry ⌈In a given BSWMD a BswModuleEntry, i.e. the declaration of a function signature, can be referred in two different ways:

1. as part of the “direct” module interface, namely as implementedEntry or expectedEntry
2. as part of the client-server “remote” interface via BswModuleClientServer-Entry.encapsulatedEntry

The two possibilities may be combined for one BswModuleEntry in the same BSWMD if the entry is called directly and via client-server as well. However, if the BswModule-Entry is *only* used in client-server manner it is recommended not to use the first possibility *in addition*.

Especially, it is not required to state a bswModuleDependency in this case, since the actual connection is done at configuration time and the two module environments need not to exchange header files.⌋

Client-Server communication via the BSW Scheduler implies some constraints on the nature of the function call on the server side:

[constr_4076] Constraints on BswModuleEntry used for Client-Server

Imposition time: IT_BswMD

⌈A BswModuleEntry used in the role BswModuleClientServer-Entry.encapsulatedEntry shall have attribute values as follows:

- callType shall be regular or callback.
- executionContext shall be task.

⌋

4.6.3 Sender-Receiver

[TPS_BSWMDT_04101] Declaration of `providedData` and `requiredData` ⌈With the optional attribute `providedData` a BSW module can declare that it provides a `VariableDataPrototype` that can be used in the sender role for sender-server communication across partition boundaries.[8] The receiver module (which may be a different or the same module) shall declare a compatible `VariableDataPrototype` as attribute `requiredData` (for the compatibility of `VariableDataPrototype`s refer to [5] [constr_1068]). These declarations together with the associated event model and ECU configuration allow for the appropriate API generation and coordination by the BSW Scheduler.⌋

For details see chapter 5.7.

[constr_4075] Constraints for `providedData` and `requiredData`

Imposition time: `IT_BswMD`

⌈Sender-Receiver communication in BSW is restricted to the pattern of so-called *explicit communication* (in the same way as described for software components in [5]) with queued behavior. This leads to some constraints for the `VariableDataPrototype` referred in the role `BswModuleDescription.providedData` or `BswModuleDescription.requiredData`:

- It shall not have an `initValue`.
- Its `swDataDefProps.swImplPolicy` shall be set to `queued`.
- Its `swDataDefProps.swCalibrationAccess` shall be set to `notAccessible`.

There are no further formal constraints on the attributes of the `VariableDataPrototype` to be used in these roles or on the underlying `AutosarDataPrototype`.⌋

Note that the ECU configuration of the BSW Scheduler determines which `providedData` is actually connected to which `requiredData`. This makes the specification of the individual module independent of the overall BSW setup.

[8] This does not exclude configurations where sender and receiver are executed in the same partition.

4.7 Count Value Sets

4.7.1 Background

When a high number of software components are integrated on an ECU the allocation of the RTE communication buffers (e.g. for implicit communication) or allocation of specific functions is getting a crucial performance factor. With the knowledge how often RTE API is invoked and consequential how often accesses to data are executed it is possible to optimize the implementation. For instance buffers with a high access frequency are put to a memory with low latency.

4.7.2 AccessCountSets

The meta-class `AccessCountSet` provides a collection of count values how often an implementation invokes RTE / SchM APIs provided for certain `AbstractAccessPoint` of a specific `ExecutableEntity`.

Class	**AccessCountSet**			
Note	This meta-class provides a set of count values evaluated according to the rules of a specific countProfile.			
Base	*ARObject*			
Aggregated by	ResourceConsumption.accessCountSet			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
accessCount	AccessCount	*	aggr	Count value for a AbstractAccessPoint. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=accessCount, accessCount.variation Point.shortLabel vh.latestBindingTime=preCompileTime
countProfile	NameToken	0..1	attr	This attribute defines the name of the count profile used to determine the AccessCount.value numbers.

Table 4.22: AccessCountSet

[constr_10270] Existence of attribute `AccessCountSet.countProfile`

Imposition time: `IT_BswMD`

⌈For each `AccessCountSet`, the attribute `countProfile` shall exist.⌋

Class	**AccessCount**			
Note	This meta-class provides one count value for a `AbstractAccessPoint`.			
Base	*ARObject*			
Aggregated by	AccessCountSet.accessCount			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
accessPoint	AbstractAccessPoint	0..1	ref	AbstractAccessPoint for which the count value is applicable. **Tags:** atp.Splitkey=accessPoint

▽

△

Class	AccessCount			
value	PositiveInteger	0..1	attr	This attribute represents the number of determined accesses **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime

Table 4.23: AccessCount

[constr_10271] Existence of attribute AccessCount.value

Imposition time: IT_BswMD

⌈For each AccessCount, the attribute value shall exist.⌋

Class	*AbstractAccessPoint* (abstract)			
Note	Abstract class indicating an access point from an ExecutableEntity.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	AsynchronousServerCallResultPoint, ExternalTriggeringPointIdent, InternalTriggeringPoint, ModeAccessPointIdent, ModeSwitchPoint, ParameterAccess, *ServerCallPoint*, VariableAccess			
Aggregated by	*AtpClassifier*.atpFeature			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
returnValueProvision	RteApiReturnValueProvisionEnum	0..1	attr	This attribute controls the provision of return values for RTE APIs that correspond to the enclosing access point. This Attribute is only used by the AUTOSAR Classic Platform.

Table 4.24: AbstractAccessPoint

[TPS_BSWMDT_04140] AccessCount.value describes an intrinsic property ⌈The AccessCount.values in an AccessCountSet are statements about the implementation of single ExecutableEntitys with respect to RTE/SchM API usage when the code is executed. Those values are independent from the later integration of the respective AbstractAccessPoint of a specific ExecutableEntitys.⌋

This means, that the numbers are a characteristic of a single AbstractAccessPoint of a specific ExecutableEntity and depending on the resulting call graph it might be required to calculate the consolidated numbers of accesses as the basis for the integration decisions. For instance if a server runnable is called **5** times in a loop by direct function call from a periodically scheduled runnable, the intrinsic count values for the data accesses in the server runnable needs to multiplied by **5** in order to get the consolidated effective number of access per time period.

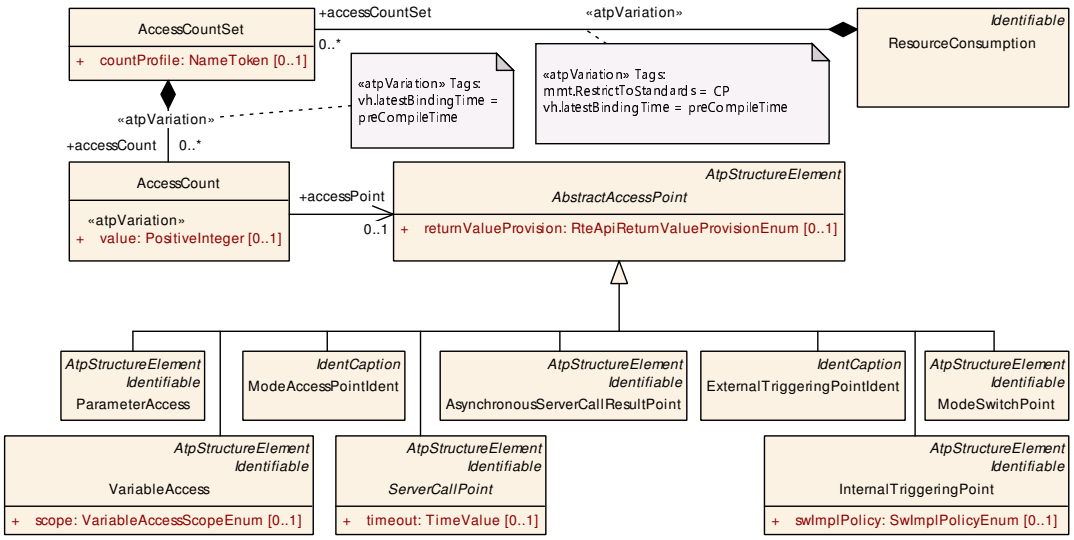

Figure 4.7: Overview AccessCountSet

In general the provider of the count values and the consumer of the count values need a common understanding how the values are determined in order to consider them appropriately for the optimization. Since the topic of optimizations may be a subject of further enhancements the `AccessCountSet` provides information about the counting strategy with the attribute `countProfile`.

[TPS_BSWMDT_04141] The attribute `countProfile` denotes the counting rules
⌈The attribute `countProfile` denotes the set of applicable counting rules used to determine the `AccessCount.value`s.⌋

[TPS_BSWMDT_04142] Standardized values of attribute `countProfile`
⌈AUTOSAR defines following standardized values of the attribute `countProfile`:

- DISTINGUISH_SINGULAR_ACCESSES

⌋

Please note that further count profiles might be defined in future.

4.7.3 Definition of countProfile: DISTINGUISH_SINGULAR_ACCESSES

The purpose of the `countProfile` DISTINGUISH_SINGULAR_ACCESSES is to determine on one hand the typical frequentness of RTE API invocation supporting the adjustment of the memory allocation. On the other hand it shall be information rich enough to provide precise information about the maximum number of access to data via implicit communication pattern which can also be used to optimize the memory allocation or even to question the existence of buffers at all. The `AccessCountSet`s provide a collection of count values how often an implementation invokes RTE / SchM APIs provided for certain `AbstractAccessPoint` of a specific `ExecutableEntity`. In case of implicit communication accesses to data the RTE API may return data ref-

erences to the location in memory where the data can be accessed. For that kind of AbstractAccessPoint the counting of the API invocations would not be sufficient but rather the number of implemented access to composite data elements via the data reference is important.

[TPS_BSWMDT_04143] countProfile DISTINGUISH_SINGULAR_ACCESSES, Explicit Communication, single access ⌈The AccessCount.value applied to a VariableAccess in role dataReceivePointByArgument, dataReceivePointByValue, dataSendPoint or a VariableAccess in role writtenLocalVariable / readLocalVariable referencing an explicitInterRunnableVariable shall be given as **1**, if the according implementation of the RunnableEntity invokes the according RTE API at most once per execution of the RunnableEntity in any condition.⌋

[TPS_BSWMDT_04144] countProfile DISTINGUISH_SINGULAR_ACCESSES, Explicit Communication, multiple accesses ⌈The AccessCount.value applied to a VariableAccess in role dataReceivePointByArgument, dataReceivePointByValue, dataSendPoint or a VariableAccess in role writtenLocalVariable / readLocalVariable referencing an explicitInterRunnableVariable shall be given greater than **1**, if the according implementation of the RunnableEntity may invoke the according RTE API multiple times per execution of the RunnableEntity. Thereby the AccessCount.value shall state the number of invocations in typically execution conditions.⌋

[TPS_BSWMDT_04145] countProfile DISTINGUISH_SINGULAR_ACCESSES, Implicit Communication and parameter accesses, single access ⌈The AccessCount.value applied to a ParameterAccess or a VariableAccess in role dataWriteAccess, dataReadAccess or a VariableAccess in role writtenLocalVariable or readLocalVariable referencing an implicitInterRunnableVariable shall be given as **1**, if the according implementation of the ExecutableEntity access at most one-time one primitive data or at most one-time one primitive composite data element per execution of the RunnableEntity in any condition.⌋

[TPS_BSWMDT_04146] countProfile DISTINGUISH_SINGULAR_ACCESSES, Implicit Communication and parameter accesses, multiple accesses ⌈The AccessCount.value applied to a ParameterAccess or a VariableAccess in role dataWriteAccess, dataReadAccess or a VariableAccess in role writtenLocalVariable or readLocalVariable referencing an implicitInterRunnableVariable shall be given greater than **1**, if the according implementation of the RunnableEntity may access primitive data multiple times or multiple primitive composite data element per execution of the RunnableEntity. Thereby the AccessCount.value shall state the number of accesses to primitive data or accesses to primitive composite data elements in typically execution conditions.⌋

For instance accessing a structure with **3** elements of type uint8, uint16 and uint64 in a loop executed **5** times counts a **15**.

For instance a RunnableEntity accesses an array of size **42** in a way, that for each execution of the RunnableEntity exactly one element of this array is read by implicit access. This counts as **1**.

[TPS_BSWMDT_04147] countProfile DISTINGUISH_SINGULAR_ACCESSES, Server calls, issued Triggers, Mode Switch Notifications, single access ⌈The AccessCount.value applied to a ServerCallPoint, AsynchronousServerCallResultPoint, InternalTriggeringPoint, ExternalTriggeringPoint, ModeSwitchPoint, ModeAccessPoint shall be given as **1**, if the according implementation of the ExecutableEntity invokes the according RTE API at most once per execution of the ExecutableEntity in any condition.⌋

[TPS_BSWMDT_04148] countProfile DISTINGUISH_SINGULAR_ACCESSES, Server calls, issued Triggers, Mode Switch Notifications, multiple accesses ⌈The AccessCount.value applied to a ServerCallPoint, AsynchronousServerCallResultPoint, InternalTriggeringPoint, ExternalTriggeringPoint, ModeSwitchPoint, ModeAccessPoint shall be given greater than **1**, if the according implementation of the ExecutableEntity invokes the according RTE API multiple times per execution of the ExecutableEntity. Thereby the AccessCount.value shall state the number of invocations in typically execution conditions.⌋

For instance if a server is invoked in a loop the AccessCount.value is set to the number of typical loop iterations.

4.7.4 Structuring of AccessCountSets

In general the detailed usage how AccessCountSets are used to structure a M1 model is not standardized. Nevertheless this section provides some hints how it might be applied for different use cases. Regardless how the AccessCountSets are substructured in detail a valid AUTOSAR model can only provide at most one value according a specific countProfile for a particular AbstractAccessPoint. Otherwise the count values would be ambiguous since multiple values would be stated for one kind of access.

[constr_4091] AccessCount.value needs to be unambiguous

Imposition time: IT_BswMD

⌈AUTOSAR model shall define at most one AccessCount.value per countProfile for a specific AbstractAccessPoint.⌋

[TPS_BSWMDT_04149] Structuring according ExecutableEntitys ⌈The meta-class AccessCountSet should be used to group the AccessCount.values for one particular ExecutableEntity.⌋

[TPS_BSWMDT_04150] Structuring according Variants ⌈The meta-class AccessCountSet should be used to group the AccessCount.values which are valid for one particular variant of the software. The grouping might be used if the Access-

Count.values are evaluated by code parsing since the parsing might be done for a specific variant of the C-implementation.⌋

[TPS_BSWMDT_04151] Structuring according different countProfile definitions ⌈The meta-class AccessCountSet should be used to group the AccessCount.values which are valid for one particular countProfile value.⌋

5 BSW Behavior

5.1 BSW Behavior Overview

Figure 5.1 and the following class table show the attributes and description of class `BswInternalBehavior`. Since several attributes on this level are the same for BSW modules and SWCs, these are aggregated by the abstract class `InternalBehavior` which is shown in the same figure and in a separate class table.

The following subsections give a more detailed explanation of the various attributes.

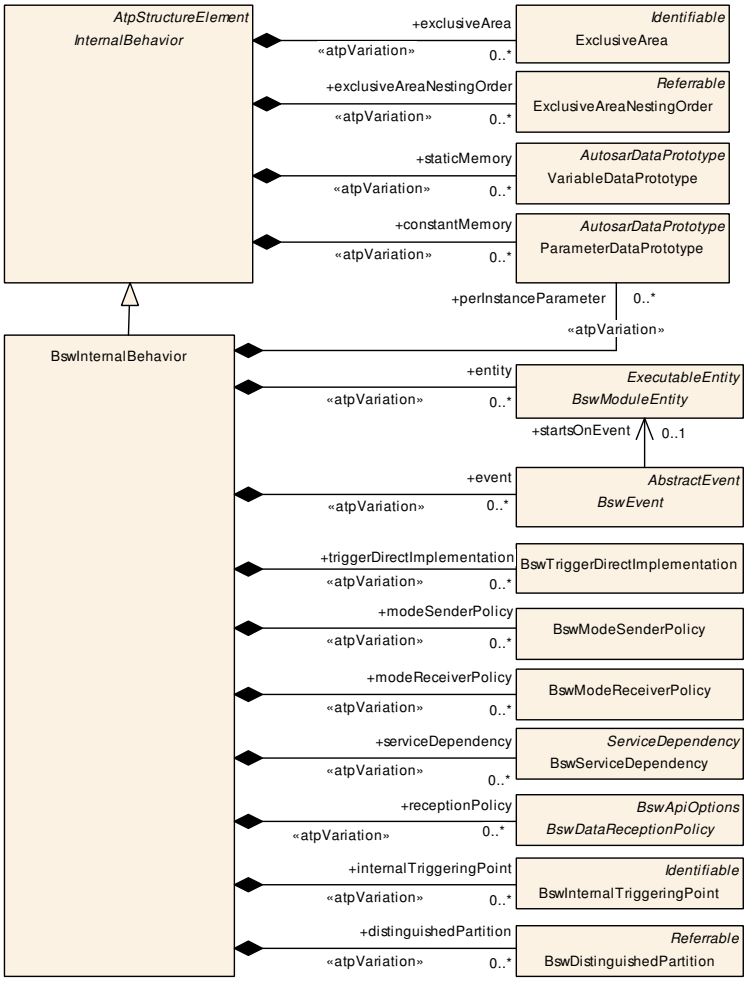

Figure 5.1: Overview of meta-class `BswInternalBehavior`

Class	***InternalBehavior*** (abstract)
Note	Common base class (abstract) for the internal behavior of both software components and basic software modules/clusters.
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*
Subclasses	BswInternalBehavior, SwcInternalBehavior

△

Class	***InternalBehavior*** (abstract)			
Aggregated by	*AtpClassifier*.atpFeature			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
constant Memory	ParameterData Prototype	*	aggr	Describes a read only memory object containing characteristic value(s) implemented by this Internal Behavior. The shortName of ParameterDataPrototype has to be equal to the ''C' identifier of the described constant. The characteristic value(s) might be shared between Sw ComponentPrototypes of the same SwComponentType. The aggregation of constantMemory is subject to variability with the purpose to support variability in the software component or module implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=constantMemory, constantMemory.short Name, constantMemory.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
constantValue Mapping	ConstantSpecification MappingSet	*	ref	Reference to the ConstantSpecificationMapping to be applied for the particular InternalBehavior **Tags:** atp.Splitkey=constantValueMapping
dataType Mapping	DataTypeMappingSet	*	ref	Reference to the DataTypeMapping to be applied for the particular InternalBehavior **Tags:** atp.Splitkey=dataTypeMapping
exclusiveArea	ExclusiveArea	*	aggr	This specifies an ExclusiveArea for this InternalBehavior. The exclusiveArea is local to the component resp. module. The aggregation of ExclusiveAreas is subject to variability. Note: the number of ExclusiveAreas might vary due to the conditional existence of RunnableEntities or BswModuleEntities. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=exclusiveArea, exclusiveArea.shortName, exclusiveArea.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
exclusiveArea NestingOrder	ExclusiveAreaNesting Order	*	aggr	This represents the set of ExclusiveAreaNestingOrder owned by the InternalBehavior. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=exclusiveAreaNestingOrder, exclusiveArea NestingOrder.shortName, exclusiveAreaNesting Order.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	***InternalBehavior*** (abstract)			
staticMemory	VariableDataPrototype	*	aggr	Describes a read and writeable static memory object representing measurerment variables implemented by this software component. The term "static" is used in the meaning of "non-temporary" and does not necessarily specify a linker encapsulation. This kind of memory is only supported if supportsMultipleInstantiation is FALSE. The shortName of the VariableDataPrototype has to be equal with the ''C' identifier of the described variable. The aggregation of staticMemory is subject to variability with the purpose to support variability in the software component's implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=staticMemory, staticMemory.shortName, staticMemory.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

Table 5.1: InternalBehavior

Class	**BswInternalBehavior**			
Note	Specifies the behavior of a BSW module or a BSW cluster w.r.t. the code entities visible by the BSW Scheduler. It is possible to have several different BswInternalBehaviors referring to the same BswModule Description.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *InternalBehavior*, *Multilanguage Referrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, BswModuleDescription.internalBehavior			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
arTypedPer Instance Memory	VariableDataPrototype	*	aggr	Defines an AUTOSAR typed memory-block that needs to be available for each instance of the Basic Software Module. The aggregation of arTypedPerInstanceMemory is subject to variability with the purpose to support variability in the Basic Software Module's implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=arTypedPerInstanceMemory, arTypedPer InstanceMemory.shortName, arTypedPerInstance Memory.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
bswPerInstance MemoryPolicy	BswPerInstance MemoryPolicy	*	aggr	Policy for a arTypedPerInstanceMemory The policy selects the options of the Schedule Manager API generation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=bswPerInstanceMemoryPolicy, bswPer InstanceMemoryPolicy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	**BswInternalBehavior**			
clientPolicy	BswClientPolicy	*	aggr	Policy for a requiredClientServerEntry. The policy selects the options of the Schedule Manager API generation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=clientPolicy, clientPolicy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
distinguished Partition	BswDistinguished Partition	*	aggr	Indicates an abstract partition context in which the enclosing BswModuleEntity can be executed. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=distinguishedPartition, distinguishedPartition.shortName, distinguishedPartition.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=60
entity	BswModuleEntity	*	aggr	A code entity for which the behavior is described **Stereotypes:** atpVariation **Tags:** atp.Splitkey=entity, entity.shortName, entity.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=5
event	BswEvent	*	aggr	An event required by this module behavior. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=event, event.shortName, event.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=10
exclusiveArea Policy	BswExclusiveArea Policy	*	aggr	Policy for an ExclusiveArea in this BswInternalBehavior. The policy selects the options of the Schedule Manager API generation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=exclusiveAreaPolicy, exclusiveAreaPolicy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
includedData TypeSet	IncludedDataTypeSet	*	aggr	The includedDataTypeSet is used by a basic software module for its implementation. **Tags:** atp.Splitkey=includedDataTypeSet
includedMode Declaration GroupSet	IncludedMode DeclarationGroupSet	*	aggr	This aggregation represents the included Mode DeclarationGroups **Tags:** atp.Splitkey=includedModeDeclarationGroupSet
internal TriggeringPoint	BswInternalTriggering Point	*	aggr	An internal triggering point. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=internalTriggeringPoint, internalTriggeringPoint.shortName, internalTriggeringPoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=2 This Attribute is only used by the AUTOSAR Classic Platform.

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Class	**BswInternalBehavior**			
internal TriggeringPoint Policy	BswInternalTriggering PointPolicy	*	aggr	Policy for an internalTriggeringPoint in this BswInternal Behavior.. The policy selects the options of the Schedule Manager API generation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=internalTriggeringPointPolicy, internal TriggeringPointPolicy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
modeReceiver Policy	BswModeReceiver Policy	*	aggr	Implementation policy for the reception of mode switches. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=modeReceiverPolicy, modeReceiver Policy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=25
modeSender Policy	BswModeSenderPolicy	*	aggr	Implementation policy for providing a mode group. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=modeSenderPolicy, modeSender Policy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=20
parameterPolicy	BswParameterPolicy	*	aggr	Policy for a perInstanceParameter in this BswInternal Behavior. The policy selects the options of the Schedule Manager API generation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=parameterPolicy, parameterPolicy.variation Point.shortLabel vh.latestBindingTime=preCompileTime
perInstance Parameter	ParameterData Prototype	*	aggr	Describes a read only memory object containing characteristic value(s) needed by this BswInternal Behavior. The role name perInstanceParameter is chosen in analogy to the similar role in the context of SwcInternal Behavior. In contrast to constantMemory, this object is not allocated locally by the module's code, but by the BSW Scheduler and it is accessed from the BSW module via the BSW Scheduler API. The main use case is the support of software emulation of calibration data. The aggregation is subject to variability with the purpose to support implementation variants. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=perInstanceParameter, perInstance Parameter.shortName, perInstanceParameter.variation Point.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=45
receptionPolicy	BswDataReception Policy	*	aggr	Data reception policy for inter-partition and/or inter-core communication. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=receptionPolicy, receptionPolicy.variation Point.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=55

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Class	**BswInternalBehavior**			
releasedTrigger Policy	BswReleasedTrigger Policy	*	aggr	Policy for a releasedTrigger. The policy selects the options of the Schedule Manager API generation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=releasedTriggerPolicy, releasedTrigger Policy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
schedulerName Prefix	BswSchedulerName Prefix	*	aggr	Optional definition of one or more prefixes to be used for the BswScheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=schedulerNamePrefix, schedulerName Prefix.shortName, schedulerNamePrefix.variation Point.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=50
sendPolicy	BswDataSendPolicy	*	aggr	Policy for a providedData. The policy selects the options of the Schedule Manager API generation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=sendPolicy, sendPolicy.variationPoint.short Label vh.latestBindingTime=preCompileTime
service Dependency	BswService Dependency	*	aggr	Defines the requirements on AUTOSAR Services for a particular item. The aggregation is subject to variability with the purpose to support the conditional existence of ServiceNeeds. The aggregation is splitable in order to support that ServiceNeeds might be provided in later development steps. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=serviceDependency, service Dependency.ident.shortName, service Dependency.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=40
triggerDirect Implementation	BswTriggerDirect Implementation	*	aggr	Specifies a trigger to be directly implemented via OS calls. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=triggerDirectImplementation, triggerDirect Implementation.variationPoint.shortLabel vh.latestBindingTime=preCompileTime xml.sequenceOffset=15
variationPoint Proxy	VariationPointProxy	*	aggr	Proxy of a variation points in the C/C++ implementation. **Tags:** atp.Splitkey=variationPointProxy, variationPoint Proxy.shortName

Table 5.2: BswInternalBehavior

Class	**BswClientPolicy**
Note	The requiredClientServerEntry for which the BSW Scheduler using this policy.
Base	*ARObject*, *BswApiOptions*
Aggregated by	BswInternalBehavior.clientPolicy

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Class	**BswClientPolicy**			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
requiredClient ServerEntry	BswModuleClientServer Entry	0..1	ref	The requiredClientServerEntry for which the BSW Scheduler using this policy. **Tags:** atp.Splitkey=requiredClientServerEntry

Table 5.3: BswClientPolicy

Class	**BswDataSendPolicy**			
Note	The data sent over the BSW Scheduler using this policy.			
Base	*ARObject*, *BswApiOptions*			
Aggregated by	BswInternalBehavior.sendPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
providedData	VariableDataPrototype	0..1	ref	The data sent over the BSW Scheduler using this policy. **Tags:** atp.Splitkey=providedData

Table 5.4: BswDataSendPolicy

Class	**BswInternalTriggeringPointPolicy**			
Note	The internal triggering point for which the BSW Scheduler using this policy.			
Base	*ARObject*, *BswApiOptions*			
Aggregated by	BswInternalBehavior.internalTriggeringPointPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bswInternal TriggeringPoint	BswInternalTriggering Point	0..1	ref	The BswInternalTriggeringPoint for which the BSW Scheduler using this policy. **Tags:** atp.Splitkey=bswInternalTriggeringPoint This Attribute is only used by the AUTOSAR Classic Platform.

Table 5.5: BswInternalTriggeringPointPolicy

Class	**BswParameterPolicy**			
Note	The perInstanceParameter for which the BSW Scheduler using this policy.			
Base	*ARObject*, *BswApiOptions*			
Aggregated by	BswInternalBehavior.parameterPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
perInstance Parameter	ParameterData Prototype	0..1	ref	The perInstanceParameter for which the BSW Scheduler using this policy. **Tags:** atp.Splitkey=perInstanceParameter

Table 5.6: BswParameterPolicy

Class	**BswPerInstanceMemoryPolicy**			
Note	The per-instance memory for which the BSW Scheduler using this policy.			
Base	*ARObject*, *BswApiOptions*			
Aggregated by	BswInternalBehavior.bswPerInstanceMemoryPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

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Class	**BswPerInstanceMemoryPolicy**			
arTypedPer Instance Memory	VariableDataPrototype	0..1	ref	The arTypedPerInstanceMemory for which the BSW Scheduler using this policy **Tags:** atp.Splitkey=arTypedPerInstanceMemory

Table 5.7: BswPerInstanceMemoryPolicy

Class	**BswReleasedTriggerPolicy**			
Note	The Trigger for which the BSW Scheduler using this policy.			
Base	*ARObject*, *BswApiOptions*			
Aggregated by	BswInternalBehavior.releasedTriggerPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
releasedTrigger	Trigger	0..1	ref	The Trigger for which the BSW Scheduler using this policy. **Tags:** atp.Splitkey=releasedTrigger

Table 5.8: BswReleasedTriggerPolicy

5.2 BSW Module Entity

5.2.1 Overview

Figure 5.2 and the next class tables shows the attributes of `BswModuleEntity`, its base class `ExecutableEntity` and its specializations for called, scheduled and interrupt entities. These attributes are mainly required to configure the BSW Scheduler.

It is important to understand the difference between `BswModuleEntity` and `BswModuleEntry`: The first one describes properties of a code fragment whereas the second one describes only the interface (i.e. the signature) used to invoke a code fragment.

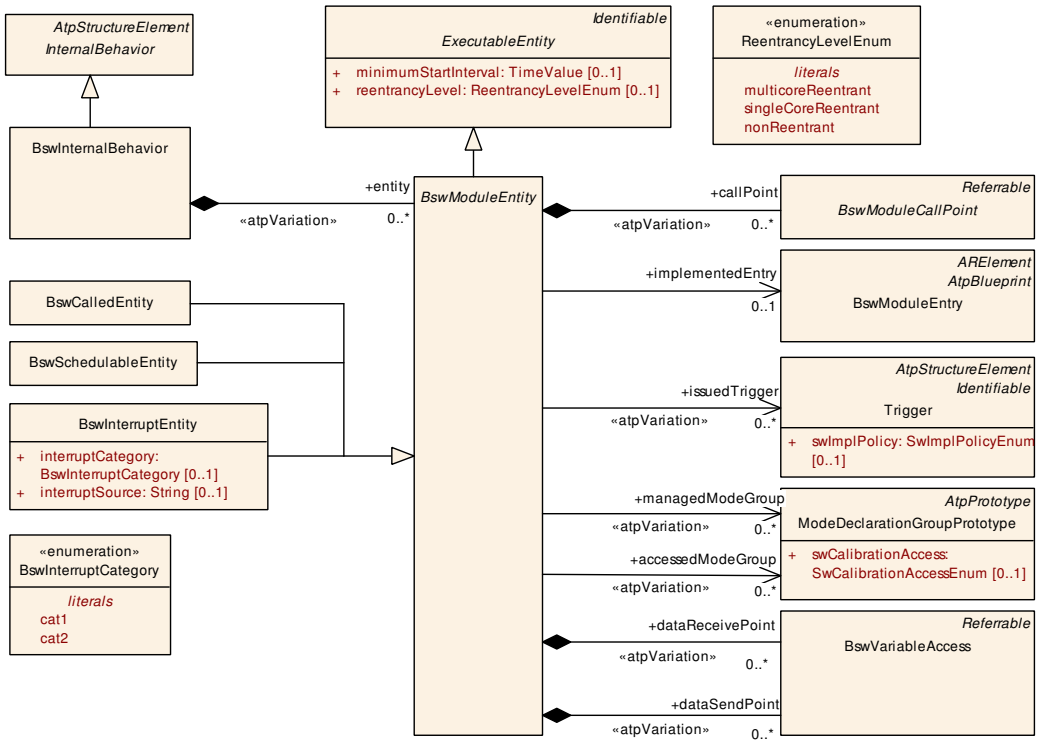

Figure 5.2: Relationships of meta-class BswModuleEntity

[TPS_BSWMDT_04072] Executable entity in BSW ⌈The abstract meta-class `ExecutableEntity` is not specific for the Basic Software, it is imported from the `CommonStructure` package of the meta-model and is defined as follows:⌋

Class	***ExecutableEntity*** (abstract)			
Note	Abstraction of executable code.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	*BswModuleEntity*, RunnableEntity			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
activation Reason	ExecutableEntity ActivationReason	*	aggr	If the `ExecutableEntity` provides at least one `activationReason` element the RTE resp. BSW Scheduler shall provide means to read the activation vector of this executable entity execution. If no `activationReason` element is provided the feature of being able to determine the activating RTEEvent is disabled for this `ExecutableEntity`. **Tags:** atp.Splitkey=activationReason, activation Reason.shortName
canEnter	ExclusiveArea	*	ref	This means that the executable entity can enter/leave the referenced exclusive area through explicit API calls. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=canEnter, canEnter.exclusiveArea, can Enter.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	***ExecutableEntity*** (abstract)			
exclusiveArea NestingOrder	ExclusiveAreaNesting Order	*	ref	This represents the set of ExclusiveAreaNestingOrders recognized by this ExecutableEntity. **Tags:** atp.Splitkey=exclusiveAreaNestingOrder
minimumStart Interval	TimeValue	0..1	attr	Specifies the time in seconds by which two consecutive starts of an ExecutableEntity are guaranteed to be separated.
reentrancyLevel	ReentrancyLevelEnum	0..1	attr	The reentrancy level of this ExecutableEntity. See the documentation of the enumeration type ReentrancyLevel Enum for details. Please note that nonReentrant interfaces can have also reentrant or multicoreReentrant implementations, and reentrant interfaces can also have multicoreReentrant implementations.
runsInside	ExclusiveArea	*	ref	The executable entity runs completely inside the referenced exclusive area. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=runsInside, runsInside.exclusiveArea, runs Inside.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
swAddrMethod	SwAddrMethod	0..1	ref	Addressing method related to this code entity. Via an association to the same SwAddrMethod, it can be specified that several code entities (even of different modules or components) shall be located in the same memory without already specifying the memory section itself. **Tags:** atp.Splitkey=swAddrMethod

Table 5.9: ExecutableEntity

Class	***BswModuleEntity*** (abstract)			
Note	Specifies the smallest code fragment which can be described for a BSW module or cluster within AUTOSAR.			
Base	*ARObject*, *ExecutableEntity*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	BswCalledEntity, BswInterruptEntity, BswSchedulableEntity			
Aggregated by	BswInternalBehavior.entity			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
accessedMode Group	ModeDeclarationGroup Prototype	*	ref	A mode group which is accessed via API call by this entity. It shall be a ModeDeclarationGroupPrototype required by this module or cluster. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=accessedModeGroup, accessedMode Group.modeDeclarationGroupPrototype, accessedMode Group.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	***BswModuleEntity*** (abstract)			
activationPoint	BswInternalTriggering Point	*	ref	Activation point used by the module entity to activate one or more internal triggers. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=activationPoint, activationPoint.bswInternal TriggeringPoint, activationPoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.
callPoint	BswModuleCallPoint	*	aggr	A call point used in the code of this entity. The variability of this association is especially targeted at debug scenarios: It is possible to have one variant calling into the AUTOSAR debug module and another one which doesn't. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=callPoint, callPoint.shortName, call Point.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
dataReceive Point	BswVariableAccess	*	aggr	The data is received via the BSW Scheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=dataReceivePoint, dataReceivePoint.short Name, dataReceivePoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
dataSendPoint	BswVariableAccess	*	aggr	The data is sent via the BSW Scheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=dataSendPoint, dataSendPoint.shortName, dataSendPoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
implemented Entry	BswModuleEntry	0..1	ref	The entry which is implemented by this module entity. **Tags:** atp.Splitkey=implementedEntry This Attribute is only used by the AUTOSAR Classic Platform.
issuedTrigger	Trigger	*	ref	A trigger issued by this entity via BSW Scheduler API call. It shall be a BswTrigger released (i.e. owned) by this module or cluster. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=issuedTrigger, issuedTrigger.trigger, issued Trigger.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
managedMode Group	ModeDeclarationGroup Prototype	*	ref	A mode group which is managed by this entity. It shall be a ModeDeclarationGroupPrototype provided by this module or cluster. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=managedModeGroup, managedMode Group.modeDeclarationGroupPrototype, managedMode Group.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	***BswModuleEntity*** (abstract)			
schedulerName Prefix	BswSchedulerName Prefix	0..1	ref	A prefix to be used in generated names for the Bsw ModuleScheduler in the context of this BswModuleEntity, for example entry point prototypes, macros for dealing with exclusive areas, header file names. Details are defined in the SWS RTE. The prefix supersedes default rules for the prefix of those names. **Tags:** atp.Splitkey=schedulerNamePrefix

Table 5.10: BswModuleEntity

[constr_10272] Existence of the reference in the role `BswModuleEntity.implementedEntry`

Imposition time: `IT_BswMD`

⌈For each `BswModuleEntity`, the reference in the role `implementedEntry` shall exist.⌋

5.2.2 BSW Module Entity Attributes

[TPS_BSWMDT_04019] `BswModuleEntity` attributes for exchange of modes and triggers ⌈The attributes `BswModuleEntity.managedModeGroup`, `BswModuleEntity.accessedModeGroup` and `BswModuleEntity.issuedTrigger` specify, that this `BswModuleEntity` initiates resp. receives mode switches or activates triggers for other modules by using the BSW Scheduler API. This is mandatory information to configure the BSW Scheduler.⌋

For an explanation of the attribute `callPoint` see chapter 5.3

For an explanation of the attributes `dataSendPoint` and `dataReceivePoint` see chapter 5.4.

[TPS_BSWMDT_04103] `BswModuleEntity` reentrancy level ⌈With the optional attribute `reentrancyLevel` a `BswModuleEntity` can state its implemented reentrancy level within the limits given by its interface (see [constr_4077]). This attribute is especially targeted at multicore scenarios.

If this attribute is omitted, reentrancy is assumed to be implemented as defined by the attribute `BswModuleEntity.implementedEntry.isReentrant`, in which case `true` means single core reentrancy.⌋

Enumeration	**ReentrancyLevelEnum**
Note	Specifies if and in which kinds of environments an entity is reentrant.
Aggregated by	*ExecutableEntity*.reentrancyLevel
Literal	***Description***
multicoreReentrant	Unlimited concurrent execution of this entity is possible, including preemption and parallel execution on multi core systems. **Tags:** atp.EnumerationLiteralIndex=0
nonReentrant	Concurrent execution of this entity is not possible. **Tags:** atp.EnumerationLiteralIndex=1
singleCore Reentrant	Pseudo-concurrent execution (i.e. preemption) of this entity is possible on single core systems. **Tags:** atp.EnumerationLiteralIndex=2

Table 5.11: ReentrancyLevelEnum

5.2.3 BSW Module Entity Constraints

The actually implemented reentrancy level can only be “better” than stated on the interface level, as the following constraint says:

[constr_4077] Constraints for `BswModuleEntity.reentrancyLevel`

Imposition time: `IT_BswMD`

⌈

- If the attribute `isReentrant` of a `BswModuleEntry` referred by an `BswModuleEntity` in the role `implementedEntry` has the value `true`, then the attribute `reentrancyLevel` of the same `BswModuleEntity` (if it exists) can only have the values `singleCoreReentrant` or `multicoreReentrant`.
- If the attribute `isReentrant` of a `BswModuleEntry` referred by an `BswModuleEntity` in the role `implementedEntry` has the values `false`, then there are no restrictions for the values of the attribute `reentrancyLevel` of the same `BswModuleEntity` (if it exists).

⌋

A `BswModuleEntity` can only implement resp. use elements which have been declared on the interface level of the respective module or cluster, in other words:

[constr_4022] `BswModuleEntity` only uses the module’s interface

Imposition time: `IT_BswMD`

⌈

- `BswModuleEntity.implementedEntry` shall refer to an element declared as `implementedEntry` of the enclosing `BswModuleDescription`
- `BswModuleEntity.callPoint.calledEntry` - where `callPoint` is instantiated from `BswDirectCallPoint` - shall refer to an element declared

as expectedEntry or implementedEntry of the enclosing BswModuleDescription.

- BswModuleEntity.callPoint.calledEntry - where callPoint is instantiated from BswSynchronousServerCallPoint or BswAsynchronousServerCallPoint - shall refer to an element declared as requiredClientServerEntry of the enclosing BswModuleDescription.
- BswModuleEntity.callPoint - where callPoint is instantiated from BswAsynchronousServerCallResultPoint - shall refer to an BswAsynchronousServerCallPoint declared in turn as callPoint of the same BswModuleEntity.
- BswModuleEntity.issuedTrigger shall refer to an element declared as releasedTrigger of the enclosing BswModuleDescription
- BswModuleEntity.managedModeGroup shall refer to an element declared as providedModeGroup of the enclosing BswModuleDescription
- BswModuleEntity.accessedModeGroup shall refer to an element declared as requiredModeGroup of the enclosing BswModuleDescription
- BswModuleEntity.dataSendPoint.accessedVariable shall refer to an element declared as providedData of the enclosing BswModuleDescription
- BswModuleEntity.dataReceivePoint.accessedVariable shall refer to an element declared as requiredData of the enclosing BswModuleDescription
- an accessedModeGroup should be allowed to refer to an element declared as providedModeGroup

⌋

5.2.4 BswCalledEntity

Class	**BswCalledEntity**			
Note	BSW module entity which is designed to be called from another BSW module or cluster.			
Base	*ARObject*, *BswModuleEntity*, *ExecutableEntity*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.entity			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 5.12: BswCalledEntity

BswCalledEntity represents an “ordinary” function call for which the following constraints apply:

[constr_4016] `BswCalledEntity` constraints

Imposition time: IT_BswMD

⌈

- BswCalledEntity.implementedEntry.callType shall be 'regular' or 'callback'
- BswCalledEntity.implementedEntry.executionContext is in general not restricted, but see [constr_4076] for constraints on the server side of a Client-Server communication.

⌋

5.2.5 BswSchedulableEntity

Class	**BswSchedulableEntity**			
Note	BSW module entity, which is designed for control by the BSW Scheduler. It may for example implement a so-called "main" function.			
Base	*ARObject*, *BswModuleEntity*, *ExecutableEntity*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.entity			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 5.13: BswSchedulableEntity

BswSchedulableEntity represents a scheduled function call for which the following constraints apply:

[constr_4017] `BswSchedulableEntity` constraints

Imposition time: IT_BswMD

⌈

- BswModuleEntity.implementedEntry.callType shall be 'scheduled'
- BswModuleEntity.implementedEntry.executionContext shall be 'task'

⌋

5.2.6 BswInterruptEntity

Class	BswInterruptEntity			
Note	BSW module entity, which is designed to be triggered by an interrupt.			
Base	*ARObject*, *BswModuleEntity*, *ExecutableEntity*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.entity			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
interrupt Category	BswInterruptCategory	0..1	attr	Category of the interrupt
interruptSource	String	0..1	attr	Allows a textual documentation of the intended interrupt source.

Table 5.14: BswInterruptEntity

[constr_10273] Existence of attribute `BswInterruptEntity.interruptCategory`

Imposition time: `IT_BswMD`

⌈For each `BswInterruptEntity`, the attribute `interruptCategory` shall exist.⌋

[constr_10274] Existence of attribute `BswInterruptEntity.interruptSource`

Imposition time: `IT_BswMD`

⌈For each `BswInterruptEntity`, the attribute `interruptSource` shall exist.⌋

Enumeration	BswInterruptCategory
Note	Category of the interrupt service
Aggregated by	BswInterruptEntity.interruptCategory
Literal	**Description**
cat1	Cat1 interrupt routines are not controlled by the OS and are only allowed to make a very limited selection of OS calls to enable and disable all interrupts. The BswInterruptEntity is implemented by the interrupt service routine, which is directly called from the interrupt vector (not via the OS). **Tags:** atp.EnumerationLiteralIndex=0
cat2	Cat2 interrupt routines are controlled by the OS and they are allowed to make OS calls. The Bsw InterruptEntity is implemented by the interrupt handler, which is called from the OS. **Tags:** atp.EnumerationLiteralIndex=1

Table 5.15: BswInterruptCategory

`BswInterruptEntity` represents an interrupt routine for which the following constraints apply:

[constr_4018] `BswInterruptEntity` constraints

Imposition time: `IT_BswMD`

⌈

- `BswInterruptEntity.implementedEntry.callType` shall be `'interrupt'`

- BswInterruptEntity.implementedEntry.executionContext shall be 'interruptCat1' if and only if BswInterruptEntity.interrupt-Category is 'Cat1'
- BswInterruptEntity.implementedEntry.executionContext shall be 'interruptCat2' if and only if BswInterruptEntity.interrupt-Category is 'Cat2'
- A BswInterruptEvent shall only trigger a BswInterruptEntity where attribute interruptCategory is set to BswInterruptCategory.cat2.

⌋

5.3 BSW Module Call Point

5.3.1 Overview

By aggregation of BswModuleCallPoints a BswModuleEntity defines how it uses BswModuleEntry-s in order to call into other (or the same) BSW module.

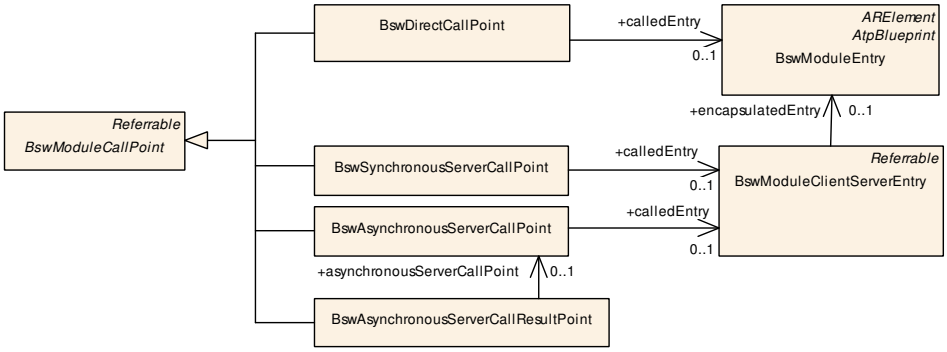

Figure 5.3: Details of BswModuleCallPoint

Class	***BswModuleCallPoint*** (abstract)			
Note	Represents a point at which a BswModuleEntity handles a procedure call into a BswModuleEntry, either directly or via the BSW Scheduler.			
Base	*ARObject*, *Referrable*			
Subclasses	BswAsynchronousServerCallPoint, BswAsynchronousServerCallResultPoint, BswDirectCallPoint, BswSynchronousServerCallPoint			
Aggregated by	*BswModuleEntity*.callPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
context Limitation	BswDistinguished Partition	*	ref	The existence of this reference indicates that the call point is used only in the context of the referred Bsw DistinguishedPartitions. **Tags:** atp.Splitkey=contextLimitation

Table 5.16: BswModuleCallPoint

5.3.2 Direct Call Points

[TPS_BSWMDT_04018] Usage of `BswDirectCallPoint` ⌈The meta-class `BswDirectCallPoint` aggregated in the role `callPoint` in a `BswModuleEntity` allows to declare which entry of another module (or the same module) is called in the code of the given `BswModuleEntity` directly, i.e. not via the BSW Scheduler.⌋

Class	**BswDirectCallPoint**			
Note	Represents a concrete point in the code from where a BswModuleEntry is called directly, i.e. not via the BSW Scheduler. This information can be used to analyze call tree and resource locking scenarios. It is not needed to configure the BSW Scheduler.			
Base	*ARObject*, *BswModuleCallPoint*, *Referrable*			
Aggregated by	*BswModuleEntity*.callPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
calledEntry	BswModuleEntry	0..1	ref	The BswModuleEntry called at this point. **Tags:** atp.Splitkey=calledEntry This Attribute is only used by the AUTOSAR Classic Platform.
calledFrom WithinExclusive Area	ExclusiveAreaNesting Order	0..1	ref	This indicates that the call point is located at the deepest level inside one or more ExclusiveAreas that are nested in the given order. **Tags:** atp.Splitkey=calledFromWithinExclusiveArea

Table 5.17: BswDirectCallPoint

[constr_10275] Existence of the reference in the role `BswDirectCallPoint.calledEntry`

Imposition time: `IT_BswMD`

⌈For each `BswDirectCallPoint`, the reference in the role `calledEntry` shall exist.⌋

Note that this is not a mandatory information in order to be able to integrate a module, but it is a very important information if an integrator wants to analyze a call chain among several modules in order to setup a proper scheduling. It is further important to note that this attribute contains additional information in comparison to `BswModuleDescription.bswModuleDependency`, because the latter only denotes the dependencies between the module interfaces whereas `calledEntry` shows from which code fragment a call is actually invoked.

In addition, a `BswDirectCallPoint` contains information about resource locking see 5.5.

Of course, the execution context (like task, interrupt, etc.) is preserved during a direct call:

[constr_4015] `calledEntry` constraints for direct calls

Imposition time: IT_BswMD

⌈The following holds if `callPoint` is aggregated as an instance of `BswDirectCallPoint`:

- `BswModuleEntity.callPoint.calledEntry.executionContext` shall be identical to `BswModuleEntity.implementedEntry.executionContext`.
- `BswModuleEntity.callPoint.calledEntry.callType` shall have the value `regular` or `callback`.

⌋

5.3.3 Client-Server Call Points

[TPS_BSWMDT_04102] Usage of `BswSynchronousServerCallPoint` ⌈The meta-class `BswSynchronousServerCallPoint` aggregated in the role `callPoint` in a `BswModuleEntity` allows to declare which entry of another module (or the same module) is called synchronously in the code of the client-side `BswModuleEntity` via the BSW Scheduler.

The intended use case is inter-partition or inter-core communication.[1] Note that it is a valid use case for a given `BswInternalBehavior` to have two different `BswModuleEntity`-s which eventually run on different partitions and/or processor cores.⌋

Class	**BswSynchronousServerCallPoint**			
Note	Represents a synchronous procedure call point via the BSW Scheduler.			
Base	*ARObject*, *BswModuleCallPoint*, *Referrable*			
Aggregated by	*BswModuleEntity*.callPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
calledEntry	BswModuleClientServerEntry	0..1	ref	The entry to be called. **Tags:** atp.Splitkey=calledEntry
calledFromWithinExclusiveArea	ExclusiveAreaNestingOrder	0..1	ref	This indicates that the call point is located at the deepest level inside one or more ExclusiveAreas that are nested in the given order. **Tags:** atp.Splitkey=calledFromWithinExclusiveArea

Table 5.18: BswSynchronousServerCallPoint

[constr_10276] Existence of the reference in the role `BswSynchronousServerCallPoint.calledEntry`

Imposition time: IT_BswMD

⌈For each `BswSynchronousServerCallPoint`, the reference in the role `calledEntry` shall exist.⌋

[1] This does not exclude configurations where client and server are executed in the same partition within the limits defined by `contextLimitation`.

In the same way as a BswDirectCallPoint also a BswSynchronousServerCallPoint contains information about resource locking see 5.5.

[TPS_BSWMDT_04104] Usage of BswAsynchronousServerCallPoint ⌈The meta-class BswAsynchronousServerCallPoint aggregated in the role callPoint in a BswModuleEntity allows to declare which entry of another module (or the same module) is called asynchronously in the code of the client-side BswModuleEntity via the BSW Scheduler.

The intended use case is inter-partition or inter-core communication. Note that it is a valid use case for a given BswInternalBehavior to have two different BswModuleEntity-s which eventually run on different partitions and/or processor cores.⌋

Class	**BswAsynchronousServerCallPoint**			
Note	Represents an asynchronous procedure call point via the BSW Scheduler.			
Base	*ARObject*, *BswModuleCallPoint*, *Referrable*			
Aggregated by	*BswModuleEntity*.callPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
calledEntry	BswModuleClientServerEntry	0..1	ref	The entry to be called. **Tags:** atp.Splitkey=calledEntry

Table 5.19: BswAsynchronousServerCallPoint

[constr_10277] Existence of the reference in the role BswAsynchronousServerCallPoint.calledEntry

Imposition time: IT_BswMD

⌈For each BswAsynchronousServerCallPoint, the reference in the role calledEntry shall exist.⌋

[TPS_BSWMDT_04105] Usage of BswAsynchronousServerCallResultPoint ⌈The meta-class BswAsynchronousServerCallResultPoint aggregated in the role callPoint in a BswModuleEntity indicates that the client-side BswModuleEntity has the possibility to retrieve the results (return value and arguments) of a former asynchronous call done via the associated BswAsynchronousServerCallPoint.⌋

Class	**BswAsynchronousServerCallResultPoint**			
Note	The callback point for an BswAsynchronousServerCallPoint i.e. the point at which the result can be retrieved from the BSW Scheduler. This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARObject*, *BswModuleCallPoint*, *Referrable*			
Aggregated by	*BswModuleEntity*.callPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
asynchronous ServerCallPoint	BswAsynchronous ServerCallPoint	0..1	ref	The call point invoking the call to which the result belongs. **Tags:** atp.Splitkey=asynchronousServerCallPoint

Table 5.20: BswAsynchronousServerCallResultPoint

[constr_10278] Existence of the reference in the role `BswAsynchronousServerCallResultPoint.asynchronousServerCallPoint`

Imposition time: IT_BswMD

⌈For each BswAsynchronousServerCallResultPoint, the reference in the role asynchronousServerCallPoint shall exist.⌋

Note that the BswModuleEntity that retrieves such a result may be scheduled in different ways: It may be started via a BswAsynchronousServerCallReturnsEvent and/or by other kind of BswEvents.

[constr_4079] `calledEntry` constraints for client-server calls

Imposition time: IT_BswMD

⌈

- The BswModuleClientServerEntry aggregated as calledEntry in a BswSynchronousServerCallPoint shall have the attribute isSynchronous = true.
- The BswModuleClientServerEntry aggregated as calledEntry in a BswAsynchronousServerCallPoint shall have the attribute isSynchronous = false.

⌋

5.4 BSW Sender-Receiver Data Access

By aggregation of meta-class BswVariableAccess a BswModuleEntity defines how it accesses data for (potential) inter-partition communication with another (or the same) BSW module.

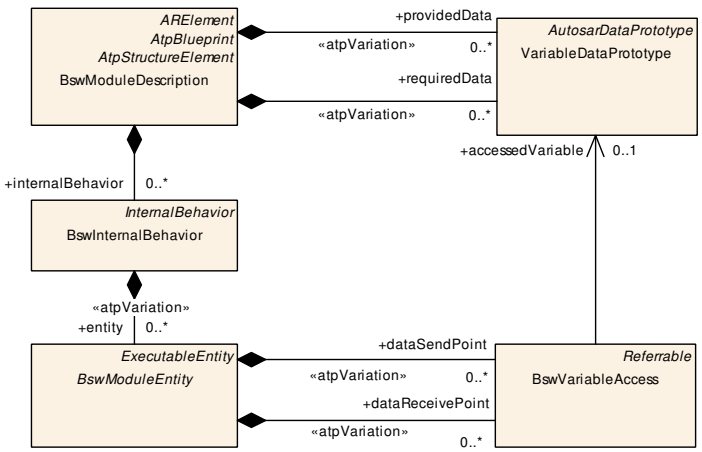

Figure 5.4: Usage of BswVariableAccess

Class	BswVariableAccess			
Note	The presence of a BswVariableAccess implies that a BswModuleEntity needs access to a VariableData Prototype via the BSW Scheduler. The kind of access is specified by the role in which the class is used.			
Base	*ARObject*, *Referrable*			
Aggregated by	*BswModuleEntity*.dataReceivePoint, *BswModuleEntity*.dataSendPoint			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
accessed Variable	VariableDataPrototype	0..1	ref	The data accessed via the BSW Scheduler. **Tags:** atp.Splitkey=accessedVariable
context Limitation	BswDistinguished Partition	*	ref	The existence of this reference indicates that the variable is received resp. sent only in the context of the referred BswDistinguishedPartitions. **Tags:** atp.Splitkey=contextLimitation

Table 5.21: BswVariableAccess

[constr_10279] Existence of the reference in the role `BswVariableAccess.accessedVariable`

Imposition time: `IT_BswMD`

⌈For each `BswVariableAccess`, the reference in the role `accessedVariable` shall exist.⌋

[TPS_BSWMDT_04106] `BswModuleEntity` attributes for sender-receiver data exchange ⌈The attributes `BswModuleEntity.dataSendPoint` and `BswModuleEntity.dataReceivePoint` specify, that this `BswModuleEntity` has access to the BSW Scheduler in order to send resp. receive the data declared in the referred `VariableDataPrototype`. This is targeted at inter-partition and/or multicore communication scenarios.[2]⌋

5.5 BSW Exclusive Areas

[TPS_BSWMDT_04073] Exclusive area in BSW ⌈The meta-class `ExclusiveArea` (including the associations from `ExecutableEntity`) is not specific for the Basic Software, is is imported from the `CommonStructure` package of the meta-model and is defined as follows:⌋

Class	ExclusiveArea			
Note	Prevents an executable entity running in the area from being preempted.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*InternalBehavior*.exclusiveArea			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table 5.22: ExclusiveArea

[2] This does not exclude configurations where sender and receiver are executed in the same partition within the limits defined by `contextLimitation`.

For certain implementations of the ExclusiveArea mechanisms it is advantageous if each BswModuleEntity uses a distinct set of enter and exit APIs. This distinct set of APIs support ExclusiveArea implementations where for the highest prior RunnableEntity(s) the lock is omitted.

This is possible when the highest prior BswModuleEntity(s) cannot get interrupted by BswModuleEntitys scheduled with lower priority in any circumstance. To support this kind of implementations the software component description has to state that it requests APIs individually for each BswModuleEntity accessing an ExclusiveArea with the canEnterExclusiveArea manner.

Class	**BswExclusiveAreaPolicy**			
Note	The ExclusiveArea for which the BSW Scheduler using this policy.			
Base	*ARObject*, *BswApiOptions*			
Aggregated by	BswInternalBehavior.exclusiveAreaPolicy			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
apiPrinciple	ApiPrincipleEnum	0..1	attr	Specifies for this ExclusiveArea if either one common set of Enter and Exit APIs for the whole BSW module is requested from the SchM or if the set of Enter and Exit APIs is expected per BswModuleEntity. The default value is "common".
exclusiveArea	ExclusiveArea	0..1	ref	The ExclusiveArea for which the BSW Scheduler using this policy. **Tags:** atp.Splitkey=exclusiveArea

Table 5.23: BswExclusiveAreaPolicy

[constr_10280] Existence of the reference in the role BswExclusiveAreaPolicy.exclusiveArea

Imposition time: IT_BswMD

⌈For each BswExclusiveAreaPolicy, the reference in the role exclusiveArea shall exist.⌋

Enumeration	**ApiPrincipleEnum**
Note	This enumeration represents the ability to control the granularity of API generation.
Aggregated by	BswExclusiveAreaPolicy.apiPrinciple, SwcExclusiveAreaPolicy.apiPrinciple
Literal	*Description*
common	The Rte or SchM API is provided for the whole software component / BSW Module **Tags:** atp.EnumerationLiteralIndex=0
perExecutable	The Rte or SchM API is provided for a specific ExecutableEntity of a software component / BSW Module **Tags:** atp.EnumerationLiteralIndex=1

Table 5.24: ApiPrincipleEnum

[TPS_BSWMDT_04154] ExclusiveArea is entered and exit by common set of API ⌈If the BswExclusiveAreaPolicy.apiPrinciple is set to common the SchM provides one sets of enter and exit APIs for the whole BSW module.⌋

In this case the same enter and exit code is executed by all affected BswModuleEntitys and there is no way to have a special treatment for the BswModuleEntitys executed in the highest prior context.

[TPS_BSWMDT_04155] ExclusiveArea is entered and exit by individual set of API ⌈If the BswExclusiveAreaPolicy.apiPrinciple is set to perExecutable the SchM provides individual sets of enter and exit APIs for each affected BswModuleEntity.⌋

In this case enter and exit code for the BswModuleEntity executed in the highest priority context can be left empty.

To avoid contradicting settings of BswExclusiveAreaPolicys for one ExclusiveArea [constr_4097] applies.

[constr_4097] Limitation on the number of BswExclusiveAreaPolicys

Imposition time: IT_BswMD

⌈An ExclusiveArea can only be referenced by at most one BswExclusiveAreaPolicy.⌋

Figure 5.5 shows the detailed meta-model of exclusive areas in BSW.

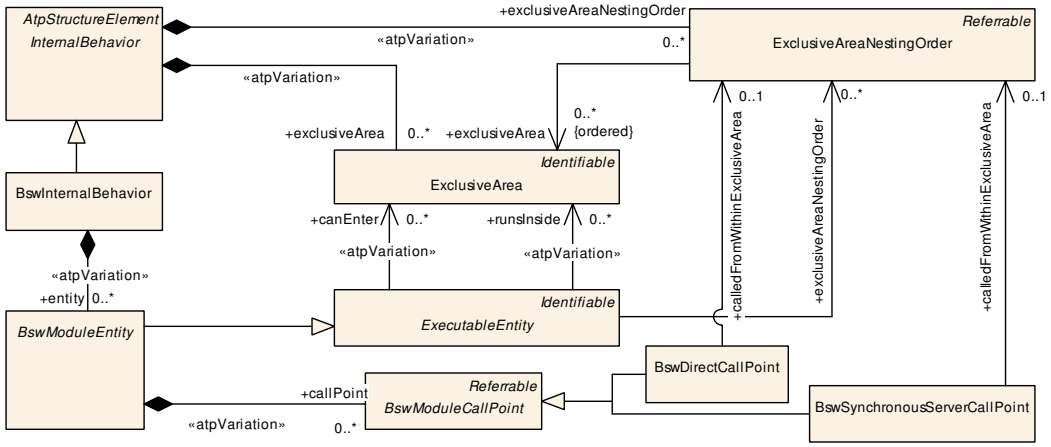

Figure 5.5: Details of defining ExclusiveAreas in BSWMDT

In addition to defining that a BswModuleEntity can enter an exclusive area or completely runs in an exclusive area, it is possible to define possible nesting orders of exclusive areas. Furthermore one can define at which level of a nesting order function calls are invoked from the BswModuleEntity. The information on nesting orders can be used to analyze the call tree with respect to resource locking scenarios.

Class	**ExclusiveAreaNestingOrder**
Note	This meta-class represents the ability to define a nesting order of ExclusiveAreas. A nesting order (that may occur in the executable code) is formally defined to be able to analyze the resource locking behavior.
Base	*ARObject*, *Referrable*

▽

△

Class	**ExclusiveAreaNestingOrder**			
Aggregated by	*InternalBehavior*.exclusiveAreaNestingOrder			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
exclusiveArea (ordered)	ExclusiveArea	*	ref	This represents a specific scenario of how Exclusive Areas can be used in terms of the nesting order.

Table 5.25: ExclusiveAreaNestingOrder

[TPS_BSWMDT_04081] **ExclusiveAreaNestingOrder** ⌈The optional ExclusiveAreaNestingOrders shall (if used at all) describe possible nesting orders (including single ExclusiveAreas) which can occur in the BswModuleEntity. Each possible locking situation requires its own ExclusiveAreaNestingOrder.⌋

[TPS_BSWMDT_04082] Indicate that the locking behavior is fully described for BswModuleEntity ⌈All ExclusiveAreas which are configured in the InternalBehavior should be referenced by an ExclusiveAreaNestingOrder to indicate that the locking behavior is fully described for the corresponding BswModuleEntity-s.⌋

[TPS_BSWMDT_04083] Locking behavior is not described for BswModuleEntity-s ⌈If ExclusiveAreas are not referenced by any ExclusiveAreaNestingOrder (this is the default scenario), this means that the locking behavior is not described for the corresponding BswModuleEntity-s and the provided information might be incomplete and cannot be used for a global offline analysis of locking behavior.⌋

[TPS_BSWMDT_04084] Relation of BswModuleCallPoint to ExclusiveAreaNestingOrder ⌈In case other BswModuleEntitys are called from within the BswModuleEntity the ExclusiveAreaNestingOrder can then be referenced by one or several BswModuleCallPoints to specify the calling environment of the invoked function with regard to ExclusiveAreas.⌋

5.6 BSW Scheduler Name Prefix

[TPS_BSWMDT_04020] Usage of BswSchedulerNamePrefix ⌈The Basic Software Scheduler API defines several generated artifacts (macro code and header file names) containing a so-called **module prefix**. This is by default derived from the attribute BswModuleDescription.shortName.

However in order to allow a more fine granular definition of these artifacts, it is possible to specify own prefixes within a BswInternalBehavior and assign them individually to each BswSchedulableEntity. Such an assignment will supersede the prefix given by BswModuleDescription.shortName. This is especially useful if the BSWMD in questions represents a cluster of several other modules.⌋

Note that this prefix cannot be used to modify any names visible in the module's interface to other modules, namely module abbreviations being part of `BswModuleEntry.shortName` cannot be superseded by it.

Figure 5.6 and the following class table show how the meta-class `BswSchedulerNamePrefix` is placed in the meta-model. Refer to [9] for the details how this information is used by the RTE generator.

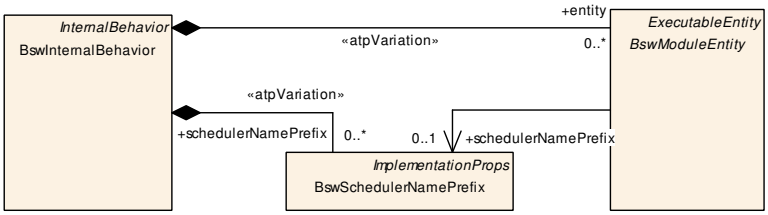

Figure 5.6: Name Prefix for BSW Scheduler artifacts

Class	**BswSchedulerNamePrefix**			
Note	A prefix to be used in names of generated code artifacts which make up the interface of a BSW module to the BswScheduler.			
Base	*ARObject*, *ImplementationProps*, *Referrable*			
Aggregated by	BswInternalBehavior.schedulerNamePrefix			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table 5.26: BswSchedulerNamePrefix

Class	***ImplementationProps*** (abstract)			
Note	Defines a symbol to be used as (depending on the concrete case) either a complete replacement or a prefix when generating code artifacts.			
Base	*ARObject*, *Referrable*			
Subclasses	BswSchedulerNamePrefix, ExecutableEntityActivationReason, SectionNamePrefix, SymbolProps, SymbolicNameProps			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
symbol	CIdentifier	0..1	attr	The symbol to be used as (depending on the concrete case) either a complete replacement or a prefix.

Table 5.27: ImplementationProps

5.7 BSW Event

5.7.1 Overview

[TPS_BSWMDT_04021] Usage of `BswEvent` ⌈The abstract class `BswEvent` is used as base class for all kinds of events which can start a `BswModuleEntity` (which means it does not include direct function calls that are not visible to the BSW Scheduler).⌋

Figure 5.7 gives an overview on these events and their association to the different kinds of `BswModuleEntity`.



Figure 5.7: Overview on `BswEvent`s

Class	***BswEvent*** (abstract)			
Note	Base class of various kinds of events which are used to trigger a BswModuleEntity of this BSW module or cluster. The event is local to the BSW module or cluster. The short name of the meta-class instance is intended as an input to configure the required API of the BSW Scheduler.			
Base	*ARObject*, *AbstractEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	BswInterruptEvent, BswOperationInvokedEvent, *BswScheduleEvent*			
Aggregated by	BswInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
context Limitation	BswDistinguished Partition	*	ref	The existence of this reference indicates that the usage of the event is limited to the context of the referred Bsw DistinguishedPartitions. **Tags:** atp.Splitkey=contextLimitation
disabledInMode	ModeDeclaration	*	iref	The modes, in which this event is disabled. **Tags:** atp.Splitkey=disabledInMode, disabledIn Mode.contextModeDeclarationGroup, disabledIn Mode.targetMode **InstanceRef implemented by:** ModeInBswModule DescriptionInstanceRef
startsOnEvent	BswModuleEntity	0..1	ref	The entity which is started by the event. **Tags:** atp.Splitkey=startsOnEvent

Table 5.28: BswEvent

[constr_10328] Existence of the reference in the role `BswEvent.startsOnEvent`

Imposition time: `IT_BswMD`

⌈For each `BswEvent`, the reference in the role `startsOnEvent` shall exist.⌋

Class	***BswScheduleEvent*** (abstract)			
Note	BswEvent that is able to start a BswSchedulabeEntity.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	BswAsynchronousServerCallReturnsEvent, BswBackgroundEvent, BswDataReceivedEvent, BswExternalTriggerOccurredEvent, BswInternalTriggerOccurredEvent, BswModeManagerErrorEvent, BswModeSwitchEvent, BswModeSwitchedAckEvent, BswOsTaskExecutionEvent, BswTimingEvent			
Aggregated by	BswInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 5.29: BswScheduleEvent

[constr_1275] Applicability of reference `startsOnEvent` for `BswScheduleEvent`

Imposition time: `IT_BswMD`

⌈The reference `BswScheduleEvent.startsOnEvent` shall only refer to a `BswSchedulableEntity`.⌋

[constr_1276] Applicability of reference `startsOnEvent` for `BswOperationInvokedEvent`

Imposition time: `IT_BswMD`

⌈The reference `BswOperationInvokedEvent.startsOnEvent` shall only refer to a `BswCalledEntity`.⌋

Class	**BswInterruptEvent**			
Note	This meta-class represents an event triggered by an interrupt.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 5.30: BswInterruptEvent

5.7.2 Timing and Background Events

[TPS_BSWMDT_04022] Timing and background events for BSW ⌈A `BswTimingEvent` and `BswBackgroundEvent` are directly driven by the Scheduler resp. OS without external sources.⌋

Class	BswTimingEvent			
Note	A recurring BswEvent driven by a time period.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
period	TimeValue	0..1	attr	Requirement for the time period (in seconds) by which this event is triggered.

Table 5.31: BswTimingEvent

[constr_10281] Existence of attribute `BswTimingEvent.period`

Imposition time: `IT_BswMD`

⌈For each `BswTimingEvent`, the attribute `period` shall exist.⌋

[constr_4043] Period of `BswTimingEvent`

Imposition time: `IT_BswMD`

⌈`BswTimingEvent.period` shall be greater than 0.⌋

Class	BswBackgroundEvent			
Note	A recurring BswEvent which is used to perform background activities. It is similar to a BswTimingEvent but has no fixed time period and is activated only with low priority.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table 5.32: BswBackgroundEvent

Class	BswOsTaskExecutionEvent			
Note	This BswEvent is supposed to execute BswSchedulableEntitys which have to react on the execution of specific OsTasks. Therefore, this event is unconditionally raised whenever the OsTask on which it is mapped is executed. The main use case for this event is scheduling of Runnables of Complex Drivers which have to react on task executions. **Tags:** atp.Status=draft			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table 5.33: BswOsTaskExecutionEvent

5.7.3 Trigger Events

Figure 5.8 and the following tables give a more detailed picture on the events driven by internal or external triggers.

Note the difference in the activation of internally triggered events and timing events:

[TPS_BSWMDT_04023] Internal trigger and timing events for BSW ⌈A `BswModuleEntity` can trigger a `BswInternalTriggerOccurredEvent` (of the same module) with the help of an API generated by the BSW Scheduler, whereas a `BswTimingEvent` is triggered by the BswScheduler via the OS timer.⌋

Further information can be found in [9].

[TPS_BSWMDT_04024] External trigger event for BSW ⌈The `BswExternalTriggerOccurredEvent` specifies the fact that the event is raised in response to a trigger issued by another BSW module. This can for example be used to communicate ECU-external events, like wakeup-events or crank-shaft-events directly between BSW modules.⌋

[constr_4023] External trigger shall belong to the interface

Imposition time: `IT_BswMD`

⌈A `BswExternalTriggerOccurredEvent` shall refer to a `Trigger` that is declared via `BswModuleDescription.requiredTrigger` for the same module.⌋

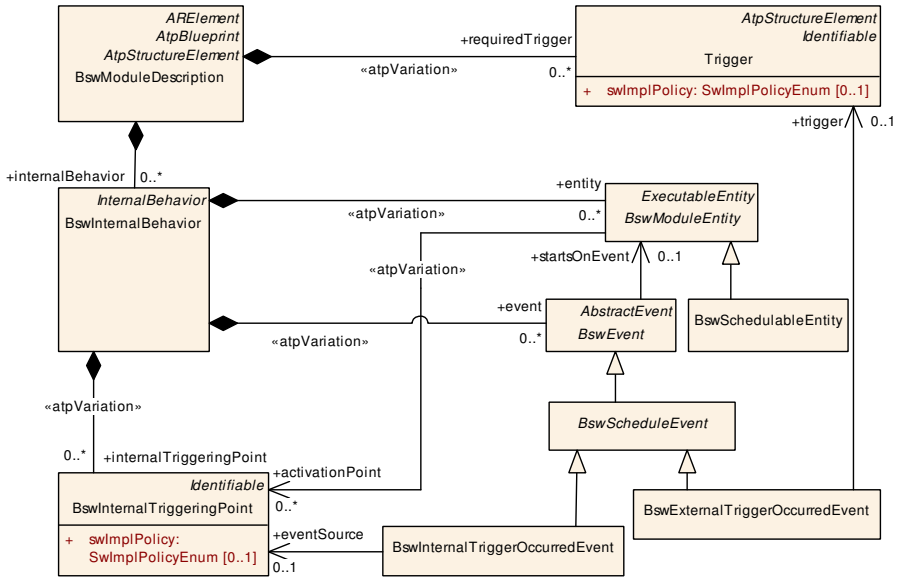

Figure 5.8: Details on BSW Trigger Events

Class	**BswInternalTriggeringPoint**			
Note	Represents the activation point for one or more BswInternalTriggerOccurredEvents. This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.internalTriggeringPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
swImplPolicy	SwImplPolicyEnum	0..1	attr	This attribute, when set to value queued, specifies a queued processing of the internal trigger event.

Table 5.34: BswInternalTriggeringPoint

In a similar way as for external triggers, the BswInternalTriggeringPoint can set an attribute to define its queuing behavior:

[constr_4065] Allowed values of BswInternalTriggeringPoint.swImplPolicy

Imposition time: IT_BswMD

⌈The **only** allowed values for the attribute BswInternalTriggeringPoint.swImplPolicy are either STANDARD (in which case the internal trigger processing does not use a queue) or QUEUED (in which case the internal trigger processing uses a queue).⌋

Class	**BswInternalTriggerOccurredEvent**			
Note	A BswEvent, which can happen sporadically. The event is activated by explicit calls from the module to the BSW Scheduler. The main purpose for such an event is to cause a context switch, e.g. from an ISR context into a task context. Activation and switching are handled within the same module or cluster only.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
eventSource	BswInternalTriggering Point	0..1	ref	The activation point is the source of this event. **Tags:** atp.Splitkey=eventSource This Attribute is only used by the AUTOSAR Classic Platform.

Table 5.35: BswInternalTriggerOccurredEvent

[constr_10282] Existence of the reference in the role BswInternalTriggerOccurredEvent.eventSource

Imposition time: IT_BswMD

⌈For each BswInternalTriggerOccurredEvent, the reference in the role eventSource shall exist.⌋

Class	**BswExternalTriggerOccurredEvent**			
Note	A BswEvent resulting from a trigger released by another module or cluster.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
trigger	Trigger	0..1	ref	The trigger associated with this event. The trigger is external to this module. **Tags:** atp.Splitkey=trigger

Table 5.36: BswExternalTriggerOccurredEvent

[constr_10283] Existence of the reference in the role `BswExternalTriggerOccurredEvent.trigger`

Imposition time: `IT_BswMD`

⌈For each `BswExternalTriggerOccurredEvent`, the reference in the role `trigger` shall exist.⌋

In addition to these mechanisms, external events can directly trigger a `BswInterruptEntity` by the means of an interrupt. This situation is not part of the event model, because it is not handled via the BSW Scheduler and is local to a BSW module.

5.7.4 Mode Events

Figure 5.9 and the following tables give a more detailed picture on the events and further classes related to mode switches.

Mode switches can influence the activation of `BswEvent`s by different mechanisms:

[TPS_BSWMDT_04025] Mode switches and events in BSW ⌈

- Via the optional attribute `disabledInMode` a `BswEvent` can specify, that it has to be suppressed in a certain mode.
- A special kind of event, the `BswModeSwitchEvent` can be used to start a `BswModuleEntity` at the entry or exit of a specific mode.
- At the sender side of a mode switch (i.e. in the module managing the mode group), a `BswModeSwitchedAckEvent` can be used to start a `BswModuleEntity` after a mode switch has been acknowledged by the BSW Scheduler.
- At the sender side of a mode switch (i.e. in the module managing the mode group), a `BswModeManagerErrorEvent` can be used to start a `BswModuleEntity` after an error has been announced. This event will be thrown by the BSW Scheduler after an error that lead to the termination of one of the partitions involved. This could be the partition in which the mode switch was managed or the partition in which it was used.

⌋

The referred `ModeDeclaration` and the enumeration `ModeActivationKind` are both imported from the `CommonStructure` package of the meta-model.

[constr_4024] Semantics of BSW mode switch event

Imposition time: `IT_BswMD`

⌈If `BswModeSwitchEvent.activation` has the value `onTransition` `BswModeSwitchEvent` shall refer to two different modes belonging to the same instance of

ModeDeclarationGroup, their order defining the direction of the transition. In all other cases, BswModeSwitchEvent shall refer to exactly one mode.⌋

[constr_4066] BswModeSwitchEvent and the definition of ModeTransition

Imposition time: IT_BswMD

⌈For each pair of ModeDeclarations referenced by a BswModeSwitchEvent with attribute activation set to onTransition a ModeTransition shall be defined in the corresponding direction (i.e. from exitedMode to enteredMode). This constraint shall only apply if the respective ModeDeclarationGroup defines at least one modeTransition.⌋

[constr_4025] Modes used by BSW mode switch event

Imposition time: IT_BswMD

⌈The ModeDeclaration used by BswModeSwitchEvent shall belong to the ModeDeclarationGroupPrototype referred as BswInternalBehavior.entity.accessedModeGroup of the enclosing BswInternalBehavior.⌋

[constr_4026] Mode group used by BSW mode switch acknowledge event

Imposition time: IT_BswMD

⌈The ModeDeclarationGroupPrototype used by BswModeSwitchedAckEvent shall be referred as BswModuleDescription.providedModeGroup by the same module.⌋

[constr_4081] Mode group used by BSW mode manager error event

Imposition time: IT_BswMD

⌈The ModeDeclarationGroupPrototype used by BswModeManagerErrorEvent shall be referred as BswModuleDescription.providedModeGroup by the same module.⌋

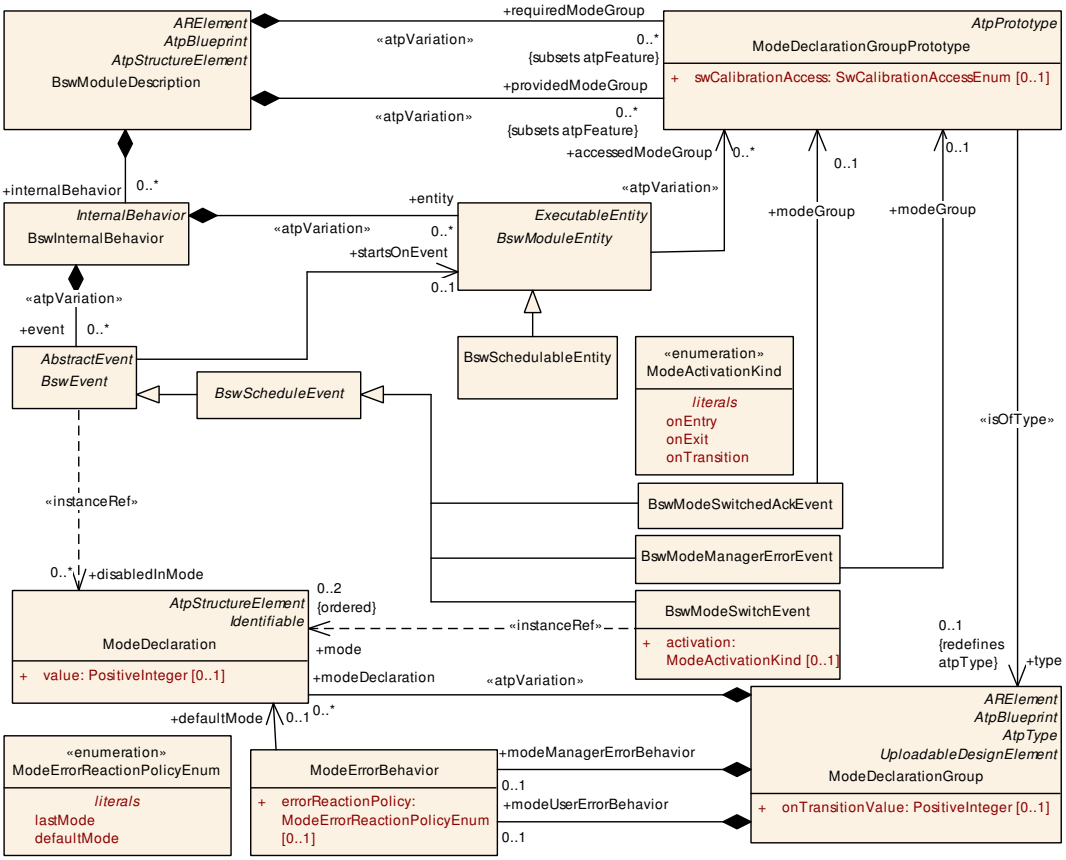

Figure 5.9: Details on BSW Events related to Mode Switches

Class	**BswModeSwitchEvent**			
Note	A BswEvent resulting from a mode switch.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
activation	ModeActivationKind	0..1	attr	Kind of activation w.r.t. to the referred mode.
mode (ordered)	ModeDeclaration	0..2	iref	Reference to one or two Modes that initiate the Mode Switch Event. **InstanceRef implemented by:** ModeInBswModule DescriptionInstanceRef

Table 5.37: BswModeSwitchEvent

[constr_10284] Existence of attribute `BswModeSwitchEvent.activation`

Imposition time: `IT_BswMD`

⌈For each `BswModeSwitchEvent`, the attribute `activation` shall exist.⌋

Class	BswModeSwitchedAckEvent			
Note	The event is raised after a switch of the referenced mode group has been acknowledged or an error occurs. The referenced mode group shall be provided by this module.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
modeGroup	ModeDeclarationGroup Prototype	0..1	ref	A mode group provided by this module. The acknowledgement of a switch of this group raises this event. **Tags:** atp.Splitkey=modeGroup

Table 5.38: BswModeSwitchedAckEvent

[constr_10285] Existence of the reference in the role BswModeSwitchedAckEvent.modeGroup

Imposition time: IT_BswMD

⌈For each BswModeSwitchedAckEvent, the reference in the role modeGroup shall exist.⌋

Class	BswModeManagerErrorEvent			
Note	This represents the ability to react on errors occurring during mode handling.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
modeGroup	ModeDeclarationGroup Prototype	0..1	ref	This represents the ModeDeclarationGroupPrototype for which the error behavior of the mode manager applies. **Tags:** atp.Splitkey=modeGroup

Table 5.39: BswModeManagerErrorEvent

[constr_10286] Existence of the reference in the role BswModeManagerErrorEvent.modeGroup

Imposition time: IT_BswMD

⌈For each BswModeManagerErrorEvent, the reference in the role modeGroup shall exist.⌋

Enumeration	ModeActivationKind
Note	Kind of mode switch condition used for activation of an event, as further described for each enumeration field.
Aggregated by	BswModeSwitchEvent.activation, SwcModeSwitchEvent.activation
Literal	**Description**
onEntry	On entering the referred mode. **Tags:** atp.EnumerationLiteralIndex=0

▽

△

Enumeration	**ModeActivationKind**
onExit	On exiting the referred mode. **Tags:** atp.EnumerationLiteralIndex=1
onTransition	On transition of the 1st referred mode to the 2nd referred mode. **Tags:** atp.EnumerationLiteralIndex=2

Table 5.40: ModeActivationKind

5.7.5 BSW Events for Client-Server Communication

Figure 5.10 and the following tables give a more detailed picture on the events driven by client-server calls. The intended use case is inter-partition and/or inter-core communication.[3]

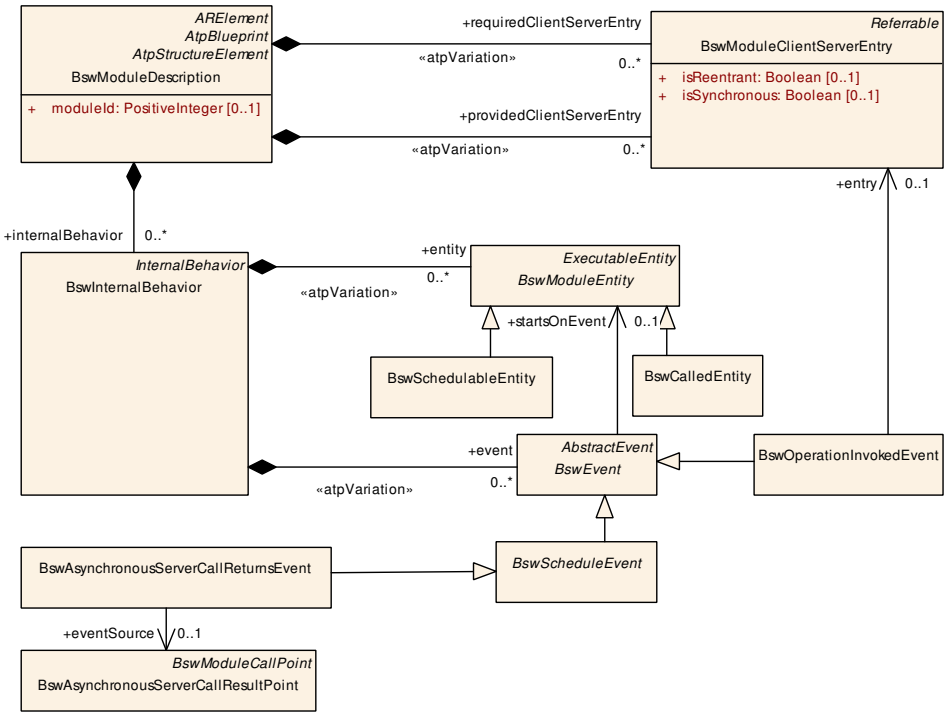

Figure 5.10: Details on BSW Events related to Client-Server Communication

[3]This does not exclude configurations where client and server are executed in the same partition.

Class	BswOperationInvokedEvent			
Note	This event is thrown on operation invocation in Client-Server-Communication via the BSW Scheduler. Its "entry" reference provides the BswClientServerEntry that is called subsequently. Note this event is not needed in case of direct function calls.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
entry	BswModuleClientServerEntry	0..1	ref	The providedClientServerEntry invoked by this event. **Tags:** atp.Splitkey=entry

Table 5.41: BswOperationInvokedEvent

[constr_10287] Existence of the reference in the role BswOperationInvokedEvent.entry

Imposition time: IT_BswMD

⌈For each BswOperationInvokedEvent, the reference in the role entry shall exist.⌋

[constr_4078] Consistent usage of BswOperationInvokedEvent

Imposition time: IT_BswMD

⌈The BswCalledEntity referred by the attribute BswOperationInvokedEvent.startsOnEvent shall refer to the same BswModuleEntry (via its attribute implementedEntry) as the BswOperationInvokedEvent (via its attribute entry.encapsulatedEntry).⌋

[constr_4098] No mode disabling for BswOperationInvokedEvent

Imposition time: IT_BswMD

⌈A BswOperationInvokedEvent shall not have a reference to a ModeDeclaration in the role disabledInMode.⌋

Class	BswAsynchronousServerCallReturnsEvent			
Note	This is the "callback" event for asynchronous Client-Server-Communication via the BSW Scheduler which is thrown after completion of the asynchronous Client-Server call. Its eventSource specifies the call point to be used for retrieving the result.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
eventSource	BswAsynchronousServerCallResultPoint	0..1	ref	The call point to be used for retrieving the result. **Tags:** atp.Splitkey=eventSource This Attribute is only used by the AUTOSAR Classic Platform.

Table 5.42: BswAsynchronousServerCallReturnsEvent

[constr_10288] Existence of the reference in the role BswAsynchronousServerCallReturnsEvent.eventSource

Imposition time: IT_BswMD

⌈For each BswAsynchronousServerCallReturnsEvent, the reference in the role eventSource shall exist.⌋

5.7.6 BSW Events for Sender-Receiver Communication

Figure 5.11 and the following table give a more detailed picture on the events driven by sender-receiver calls. The intended use case is inter-partition and/or inter-core communication.[4]

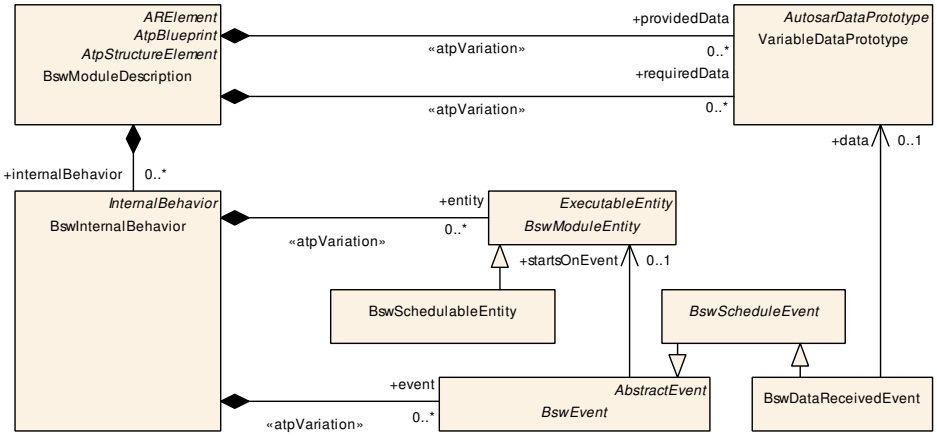

Figure 5.11: Details on BSW Events related to Sender-Receiver Communication

Class	**BswDataReceivedEvent**			
Note	This event is thrown on reception of the referenced data via Sender-Receiver-Communication over the BSW Scheduler.			
Base	*ARObject*, *AbstractEvent*, *BswEvent*, *BswScheduleEvent*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	BswInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
data	VariableDataPrototype	0..1	ref	The received data. **Tags:** atp.Splitkey=data

Table 5.43: BswDataReceivedEvent

[constr_10289] Existence of the reference in the role BswDataReceivedEvent.data

Imposition time: IT_BswMD

⌈For each BswDataReceivedEvent, the reference in the role data shall exist.⌋

[4] This does not exclude configurations where sender and receiver are executed in the same partition.

5.8 Activation Reason of a BSW Module Entity

It is feasible to activate a given BswModuleEntity by means of several BswEvents. In many cases, it is therefore necessary to retrieve the information about the activating BswEvent from within the implementation of the BswModuleEntity.

As a typical use case, consider a BswSchedulableEntity that is cyclically activated (by means of a BswTimingEvent) and in addition it shall also be executed sporadically, e.g. in response to mode switch (BswModeSwitchEvent).

By using the meta-model extract shown in Figure 5.12 (which is further explained in [5]) it is possible to generate the RTE in a way that it provides a bit vector representing the activation reason to the BswModuleEntity.

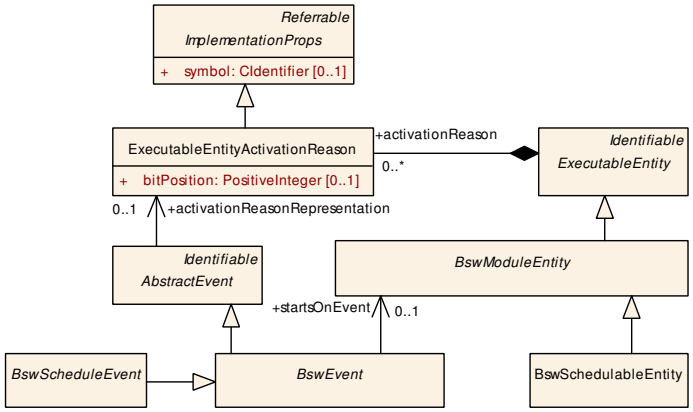

Figure 5.12: BswModuleEntity and activation reason

[TPS_BSWMDT_04089] Access to activation reason ⌈The same mechanism is available for both application software and basic software, therefore the following specification items and constraints defined in [5] also hold for the BSWMDT:

- [TPS_SWCT_01469]
- [constr_1226]
- [constr_1227]

⌋

An activation reason can only be provided to those BswModuleEntity-s that are potentially triggered by BswEvents and thus are handled by the RTE. As a further restriction, the current RTE Specification [9] does not support retrieving the activation reason for BswCalledEntitys even if they are triggered via the BSW Scheduler. This leads to the following constraint:

[constr_4070] Applicability of BswModuleEntity.activationReason

Imposition time: IT_BswMD

⌈An activationReason shall not be set

- for instances of BswInterruptEntity

- for instances of BswCalledEntity

⌋

5.9 BSW Communication Policy

The implementation of triggers, mode switches and sender-receiver-communication can follow various policies which have to be known by the generator of the RTE resp. BSW Scheduler in order to generate the correct “glue” code. The required attributes are shown in Figures 5.13 and 5.14 and are explained in the class tables below.

This kind of information is similar to what is represented by the so-called ComSpecs for VFB communication, see [5].

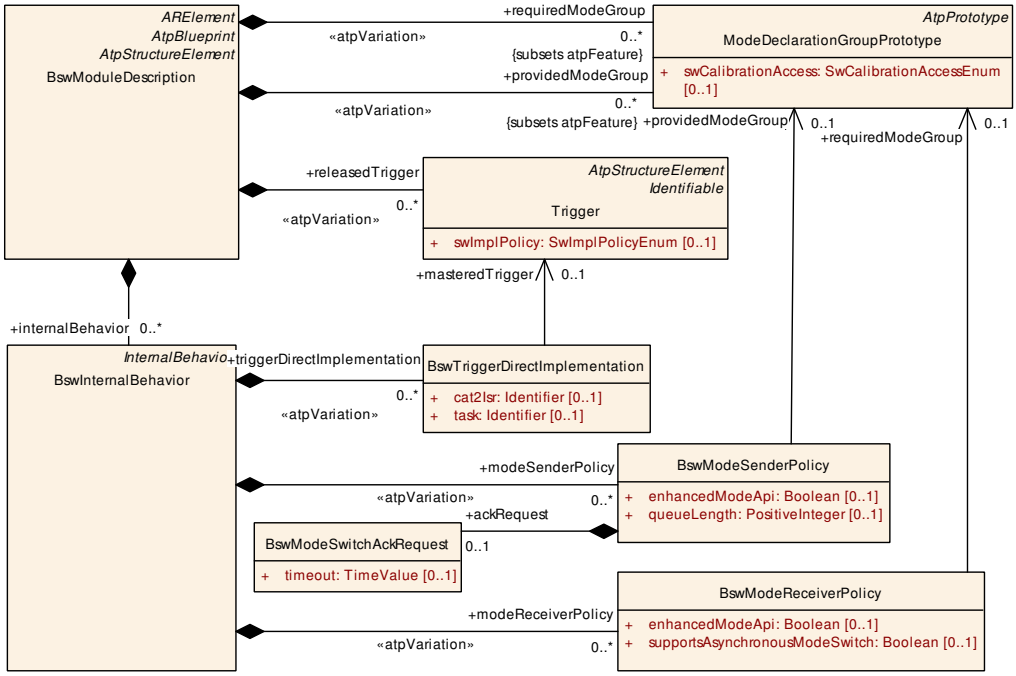

Figure 5.13: Special Implementation Policy for Modes and Triggers

Class	**BswTriggerDirectImplementation**			
Note	Specifies a released trigger to be directly implemented via OS calls, for example in a Complex Driver module.			
Base	*ARObject*			
Aggregated by	BswInternalBehavior.triggerDirectImplementation			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

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Class	**BswTriggerDirectImplementation**			
cat2Isr	Identifier	0..1	attr	The name of the OS category 2 ISR, which is controlled by the referred trigger. This means, that the module manages the category 2 ISR (e.g. according hardware initialization and enabling of ISR). Instead of calling an RTE / SchM API to raise the appropriate events in components or modules receiving the trigger, this ISR directly schedules the triggered ExecutableEntitys. The ISR name is required by the integrator to map the Bsw Events and RTEEvents to this ISR.
masteredTrigger	Trigger	0..1	ref	The trigger which is directly mastered by this module. There may be several different BswTriggerDirect Implementations mastering the same Trigger. This may be required e.g. due to memory partitioning. **Tags:** atp.Splitkey=masteredTrigger
task	Identifier	0..1	attr	The name of the OS task, which is controlled by the referred trigger. This means, that the module uses the trigger condition to directly activate an OS task instead of calling an API of the BswScheduler. The task name is required by the RTE generator resp. BswScheduler to raise the appropriate events in components or modules receiving the trigger.

Table 5.44: BswTriggerDirectImplementation

[constr_10290] Existence of the reference in the role `BswTriggerDirectImplementation.masteredTrigger`

Imposition time: `IT_BswMD`

⌈For each `BswTriggerDirectImplementation`, the reference in the role `masteredTrigger` shall exist.⌋

[constr_4105] Use of attribute `task` or `cat2Isr`

Imposition time: `IT_BswMD`

⌈Only one of the attributes is allowed to exist. Either `task` or `cat2Isr` should be configured.⌋

Class	**BswModeSenderPolicy**			
Note	Specifies the details for the sending of a mode switch for the referred mode group.			
Base	*ARObject*			
Aggregated by	BswInternalBehavior.modeSenderPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
ackRequest	BswModeSwitchAck Request	0..1	aggr	Request for acknowledgement **Tags:** atp.Splitkey=ackRequest
enhancedMode Api	Boolean	0..1	attr	This controls the creation of the enhanced mode API that returns information about the previous mode and the next mode. If set to TRUE the enhanced mode API is supposed to be generated. For more details please refer to the SWS_RTE.

▽

△

Class	BswModeSenderPolicy			
providedMode Group	ModeDeclarationGroup Prototype	0..1	ref	The provided mode group for which the policy is specified. **Tags:** atp.Splitkey=providedModeGroup
queueLength	PositiveInteger	0..1	attr	Length of call queue on the sender side. The queue is implemented by the RTE resp.BswScheduler. The value shall be greater or equal to 0. Setting the value of queue Length to 0 implies non-queued communication.

Table 5.45: BswModeSenderPolicy

[constr_10291] Existence of the reference in the role BswModeSenderPolicy.providedModeGroup

Imposition time: IT_BswMD

⌈For each BswModeSenderPolicy, the reference in the role providedModeGroup shall exist.⌋

[constr_10292] Existence of attribute BswModeSenderPolicy.queueLength

Imposition time: IT_BswMD

⌈For each BswModeSenderPolicy, the attribute queueLength shall exist.⌋

Class	BswModeSwitchAckRequest			
Note	Requests acknowledgements that a mode switch has been processed successfully			
Base	*ARObject*			
Aggregated by	BswModeSenderPolicy.ackRequest			
Attribute	Type	Mult.	Kind	Note
timeout	TimeValue	0..1	attr	Number of seconds before an error is reported.

Table 5.46: BswModeSwitchAckRequest

[constr_10293] Existence of attribute BswModeSwitchAckRequest.timeout

Imposition time: IT_BswMD

⌈For each BswModeSwitchAckRequest, the attribute timeout shall exist.⌋

Class	BswModeReceiverPolicy			
Note	Specifies the details for the reception of a mode switch for the referred mode group.			
Base	*ARObject*			
Aggregated by	BswInternalBehavior.modeReceiverPolicy			
Attribute	Type	Mult.	Kind	Note
enhancedMode Api	Boolean	0..1	attr	This controls the creation of the enhanced mode API that returns information about the previous mode and the next mode. If set to TRUE the enhanced mode API is supposed to be generated. For more details please refer to the SWS_RTE.

▽

△

Class	**BswModeReceiverPolicy**			
requiredMode Group	ModeDeclarationGroup Prototype	0..1	ref	The required mode group for which the policy is specified. **Tags:** atp.Splitkey=requiredModeGroup
supports Asynchronous ModeSwitch	Boolean	0..1	attr	Specifies whether the module can handle the reception of an asynchronous mode switch (true) or not (false).

Table 5.47: BswModeReceiverPolicy

[constr_10294] Existence of the reference in the role `BswModeReceiverPolicy.requiredModeGroup`

Imposition time: `IT_BswMD`

⌈For each `BswModeReceiverPolicy`, the reference in the role `requiredModeGroup` shall exist.⌋

[constr_10295] Existence of attribute `BswModeReceiverPolicy.supportsAsynchronousModeSwitch`

Imposition time: `IT_BswMD`

⌈For each `BswModeReceiverPolicy`, the attribute `supportsAsynchronousModeSwitch` shall exist.⌋

[TPS_BSWMDT_04107] Data reception policy ⌈By aggregating a `BswDataReceptionPolicy` a `BswInternalBehavior` specifies the detailed reception policy of the referred `VariableDataPrototype`. Note the reception policy is the same for all reception points - defined via `BswModuleEntity.dataReceivePoint` - of the respective `VariableDataPrototype` in this module.⌋

Note that due to limitations of the sender-receiver communication mechanism in BSW (in contrast to VFB communication) it is only possible to specify queued reception. Furthermore, there are no communication attributes on the sender side.

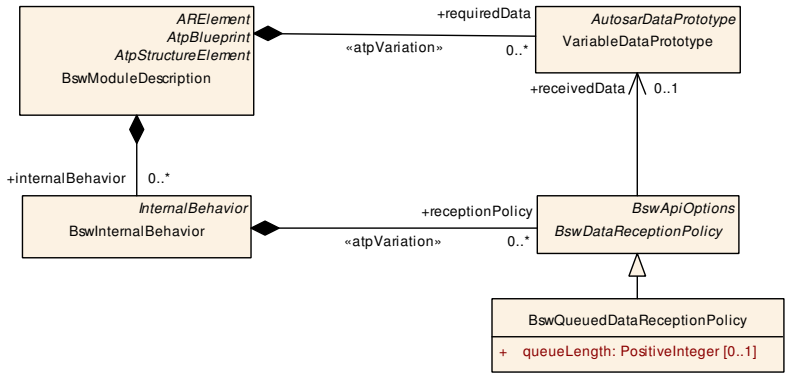

Figure 5.14: Implementation Policy for BSW Sender-Receiver Communication

Class	**BswDataReceptionPolicy** (abstract)			
Note	Specifies the reception policy for the referred data in sender-receiver communication over the BSW Scheduler. To be used for inter-partition and/or inter-core communication.			
Base	*ARObject*, *BswApiOptions*			
Subclasses	BswQueuedDataReceptionPolicy			
Aggregated by	BswInternalBehavior.receptionPolicy			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
receivedData	VariableDataPrototype	0..1	ref	The data received over the BSW Scheduler using this policy. **Tags:** atp.Splitkey=receivedData

Table 5.48: BswDataReceptionPolicy

[constr_10296] Existence of reference in the role BswDataReceptionPolicy.receivedData

Imposition time: IT_BswMD

⌈For each BswDataReceptionPolicy, the reference in the role receivedData shall exist.⌋

Class	**BswQueuedDataReceptionPolicy**			
Note	Reception policy attributes specific for queued receiving.			
Base	*ARObject*, *BswApiOptions*, *BswDataReceptionPolicy*			
Aggregated by	BswInternalBehavior.receptionPolicy			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
queueLength	PositiveInteger	0..1	attr	Length of queue for received events.

Table 5.49: BswQueuedDataReceptionPolicy

[constr_10297] Existence of attribute BswQueuedDataReceptionPolicy.queueLength

Imposition time: IT_BswMD

⌈For each BswQueuedDataReceptionPolicy, the attribute queueLength shall exist.⌋

[constr_4080] Existence of reception policy

Imposition time: IT_BswMD

⌈If a VariableDataPrototype is referred from a dataReceivePoint of any BswModuleEntity in a given BswInternalBehavior, then exactly one corresponding BswDataReceptionPolicy shall by aggregated by this BswInternalBehavior.⌋

5.10 BSW Local Data

A BSW module (or cluster) needs the ability to declare data in its BSWMD, for example

- in order to make them available for measurement and calibration tools (see chapter 9)
- in order to declare these data in relation to ServiceNeeds, e.g. as NvM blocks (see chapter 11)

[TPS_BSWMDT_04026] Local BSW data without RTE or BSW Scheduler support ⌈In many cases such data in the context of a module (or cluster) do not need any support by the RTE resp. BSW Scheduler. They are simply allocated by the module's code but they still may be accessed from outside of the module for measurement, calibration or as NvM mirrors. These data are described by the following roles:

- `BswInternalBehavior.staticMemory` for variable data
- `BswInternalBehavior.constantMemory` for constant data

⌋

[TPS_BSWMDT_04027] Local BSW data accessed via BSW Scheduler API ⌈However it is also possible to have local data allocated by the BSW Scheduler. This is especially required in the case of calibration with software emulation. These kind of data are declared by:

- `BswInternalBehavior.perInstanceParameter`

⌋

For compatibility reasons with the SWCT these various data are declared on the behavior level using the abstract class `InternalBehavior` as shown in figure 5.15. The class table for `InternalBehavior` has already been listed in chapter 5.1.

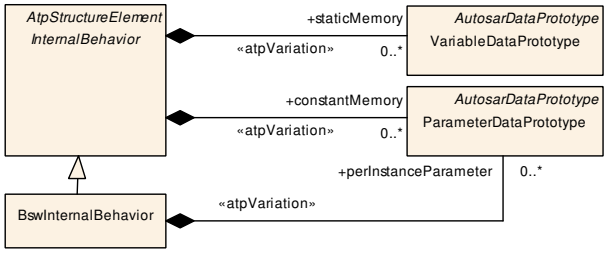

Figure 5.15: BSW Local Data

[TPS_BSWMDT_04128] BSW measurement data accessed via BSW Scheduler API ⌈BSW measurement data accessed via BSW Scheduler API It is also possible to have local data allocated by the BSW Scheduler. This kind of data is declared by

- `BswInternalBehavior.arTypedPerInstanceMemory`

⌋

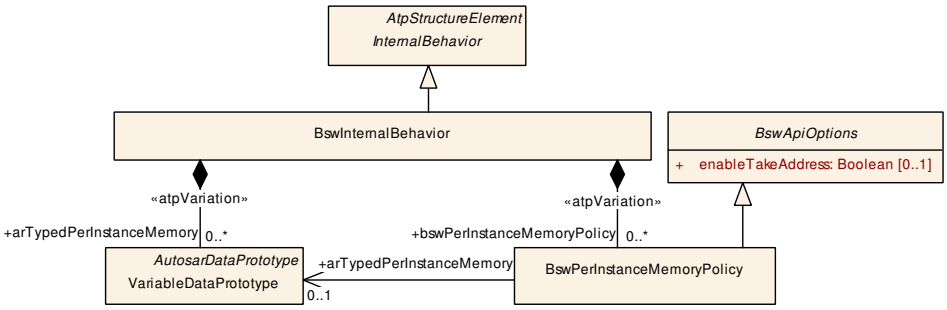

Figure 5.16: BSW Measurement Data

These data use the type system of `AutosarDataPrototype`s which is explained in more detail in [5]:

Class	**ParameterDataPrototype**			
Note	A `ParameterDataPrototype` represents a formalized generic piece of information that is typically immutable by the application software layer, but mutable by measurement and calibration tools. `ParameterDataPrototype` is used in various contexts and the specific context gives the otherwise generic `ParameterDataPrototype` a dedicated semantics.			
Base	*ARObject*, *AtpFeature*, *AtpPrototype*, *AutosarDataPrototype*, *DataPrototype*, *Identifiable*, *Multilanguage Referrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, BswInternalBehavior.perInstanceParameter, *InternalBehavior*.constantMemory, NvBlockDescriptor.romBlock, ParameterInterface.parameter, SwcInternalBehavior.perInstanceParameter, SwcInternalBehavior.sharedParameter			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
initValue	ValueSpecification	0..1	aggr	Specifies initial value(s) of the ParameterDataPrototype **Tags:** atp.Splitkey=initValue

Table 5.50: ParameterDataPrototype

Class	**VariableDataPrototype**			
Note	A `VariableDataPrototype` represents a formalized generic piece of information that is typically mutable by the application software layer. `VariableDataPrototype` is used in various contexts and the specific context gives the otherwise generic `VariableDataPrototype` a dedicated semantics.			
Base	*ARObject*, *AtpFeature*, *AtpPrototype*, *AutosarDataPrototype*, *DataPrototype*, *Identifiable*, *Multilanguage Referrable*, *Referrable*			
Aggregated by	ApplicationInterface.indication, *AtpClassifier*.atpFeature, BswInternalBehavior.arTypedPerInstanceMemory, BswModuleDescription.providedData, BswModuleDescription.requiredData, BulkNvDataDescriptor.bulkNvBlock, DiagnosticSovdAccessArgument.contentObject, *InternalBehavior*.staticMemory, NvBlockDescriptor.ramBlock, NvDataInterface.nvData, SenderReceiverInterface.dataElement, ServiceInterface.event, SwcInternalBehavior.arTypedPerInstanceMemory, SwcInternalBehavior.explicitInterRunnableVariable, SwcInternalBehavior.implicitInterRunnableVariable			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
initValue	ValueSpecification	0..1	aggr	Specifies initial value(s) of the VariableDataPrototype **Tags:** atp.Splitkey=initValue

Table 5.51: VariableDataPrototype

5.11 Synchronization with a Corresponding SWC

BSW modules which implement a `ServiceSwComponentType`, `EcuAbstractionSwComponentType` or `ComplexDeviceDriverSwComponentType` require several

mappings between their SWC description and BSWM description in order to generate the RTE resp. the BSW Scheduler.

One use case is as follows:

[TPS_BSWMDT_04074] Synchronization of mode switches or triggers ⌈A BSW module which communicates via the RTE is able to provide triggers and mode switches within the basic software and toward SWCs above the RTE as well (for example a BSW module implementing an `EcuAbstractionSwComponentType`). It may happen, that a module wants to issue a mode switch or a trigger to both BSW and to SWCs "above the RTE", i.e. a call via the BSW Scheduler API shall result in the same trigger resp. mode switch as a call via the RTE port-API (details are specified in [9]). In this case the `Trigger` resp. `ModeDeclarationGroupPrototype` provided within the BSW shall be mapped to the `Trigger` resp. `ModeDeclarationGroupPrototype` provided by the port interface. This information is an input to configure the RTE accordingly.⌋

Another use case is the specification of a `RunnableEntity` in a BSW module in order to allow calls to or from the RTE via ports:

[TPS_BSWMDT_04075] `RunnableEntity` in BSW for RTE access ⌈In this case, a `BswModuleEntity` should be specified in addition to allow for the BSW specific descriptions and the two elements have to be associated. This is e.g. required, if the RTE needs to find out whether a `RunnableEntity` runs in interrupt context.⌋

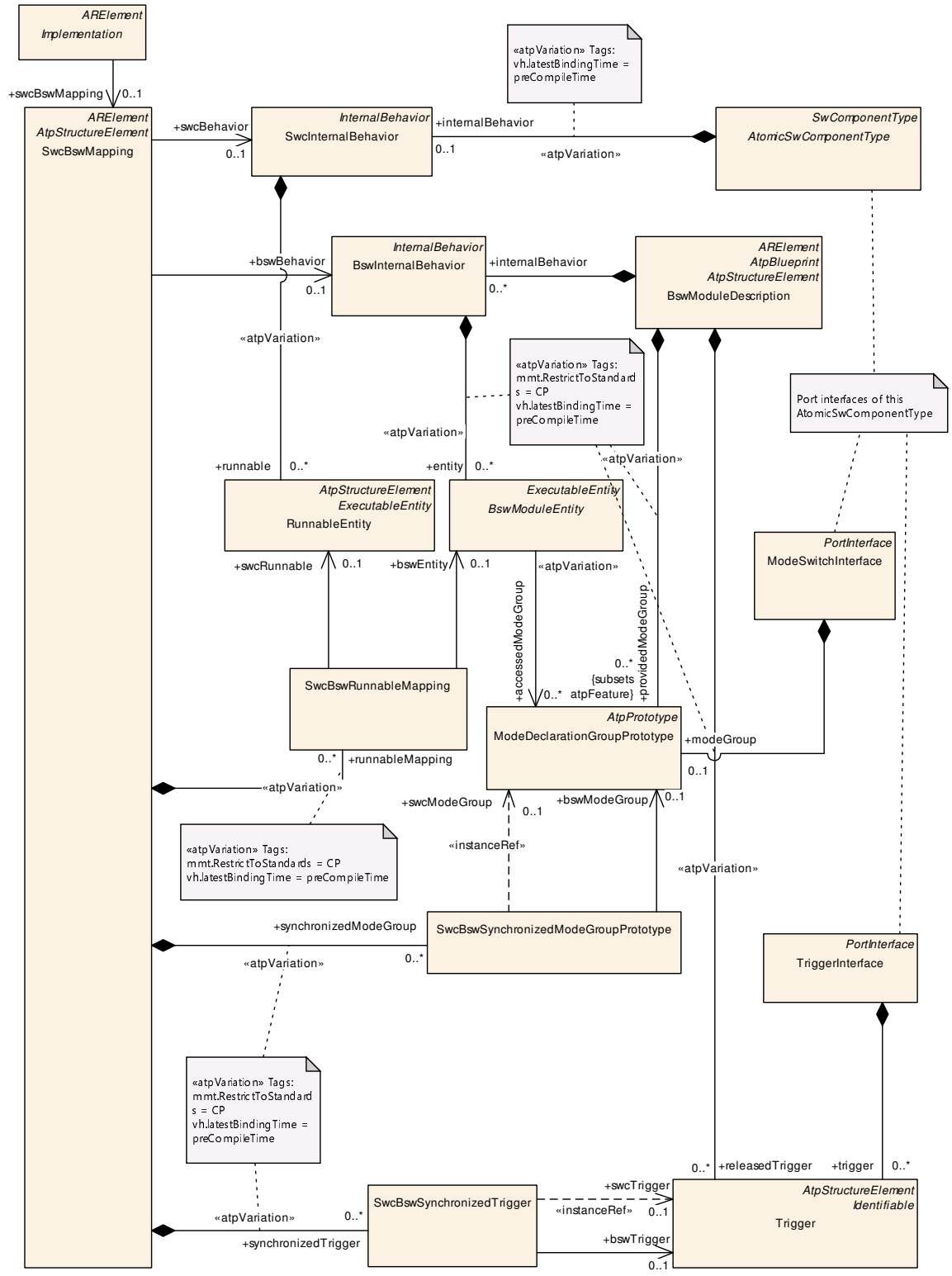

Figure 5.17: Mapping between an SWC and a BSW module.

Class	**SwcBswMapping**			
Note	Maps an SwcInternalBehavior to an BswInternalBehavior. This is required to coordinate the API generation and the scheduling for AUTOSAR Service Components, ECU Abstraction Components and Complex Driver Components by the RTE and the BSW scheduling mechanisms. **Tags:** atp.recommendedPackage=SwcBswMappings This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element, *AtpClassifier*.atpFeature			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bswBehavior	BswInternalBehavior	0..1	ref	The mapped BswInternalBehavior **Tags:** atp.Splitkey=bswBehavior
runnable Mapping	SwcBswRunnable Mapping	*	aggr	A mapping between a pair of SWC and BSW runnables. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=runnableMapping, runnable Mapping.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
swcBehavior	SwcInternalBehavior	0..1	ref	The mapped SwcInternalBehavior. **Tags:** atp.Splitkey=swcBehavior
synchronized ModeGroup	SwcBswSynchronized ModeGroupPrototype	*	aggr	A pair of SWC and BSW mode group prototypes to be synchronized by the scheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=synchronizedModeGroup, synchronized ModeGroup.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
synchronized Trigger	SwcBswSynchronized Trigger	*	aggr	A pair of SWC and BSW Triggers to be synchronized by the scheduler. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=synchronizedTrigger, synchronized Trigger.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

Table 5.52: SwcBswMapping

Class	**SwcBswRunnableMapping**			
Note	Maps a BswModuleEntity to a RunnableEntity if it is implemented as part of a BSW module (in the case of an AUTOSAR Service, a Complex Driver or an ECU Abstraction). The mapping can be used by a tool to find relevant information on the behavior, e.g. whether the bswEntity shall be running in interrupt context.			
Base	*ARObject*			
Aggregated by	SwcBswMapping.runnableMapping			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bswEntity	BswModuleEntity	0..1	ref	The mapped BswModuleEntity **Tags:** atp.Splitkey=bswEntity
swcRunnable	RunnableEntity	0..1	ref	The mapped SWC runnable. **Tags:** atp.Splitkey=swcRunnable

Table 5.53: SwcBswRunnableMapping

[constr_10298] Existence of the reference in the role SwcBswRunnableMapping.bswEntity

Imposition time: IT_BswMD

⌈For each SwcBswRunnableMapping, the reference in the role bswEntity shall exist.⌋

[constr_10299] Existence of the reference in the role SwcBswRunnableMapping.swcRunnable

Imposition time: IT_BswMD

⌈For each SwcBswRunnableMapping, the reference in the role swcRunnable shall exist.⌋

Class	**SwcBswSynchronizedModeGroupPrototype**			
Note	Synchronizes a mode group provided by a component via a port with a mode group provided by a BSW module or cluster.			
Base	*ARObject*			
Aggregated by	SwcBswMapping.synchronizedModeGroup			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bswModeGroup	ModeDeclarationGroup Prototype	0..1	ref	The BSW mode group prototype. **Tags:** atp.Splitkey=bswModeGroup
swcModeGroup	ModeDeclarationGroup Prototype	0..1	iref	The SWC mode group prototype provided by a particular port. **Tags:** atp.Splitkey=swcModeGroup, swcModeGroup.contextPPort, swcModeGroup.targetModeGroup **InstanceRef implemented by:** PModeGroupInAtomicSwcInstanceRef

Table 5.54: SwcBswSynchronizedModeGroupPrototype

[constr_10336] Existence of the reference in the role SwcBswSynchronizedModeGroupPrototype.bswModeGroup

Imposition time: IT_BswMD

⌈For each SwcBswSynchronizedModeGroupPrototype, the reference in the role bswModeGroup shall exist.⌋

[constr_10337] Existence of the instanceRef in the role SwcBswSynchronizedModeGroupPrototype.swcModeGroup

Imposition time: IT_BswMD

⌈For each SwcBswSynchronizedModeGroupPrototype, the instanceRef in the role swcModeGroup shall exist.⌋

Class	**SwcBswSynchronizedTrigger**
Note	Synchronizes a Trigger provided by a component via a port with a Trigger provided by a BSW module or cluster.
Base	*ARObject*

▽

△

Class	SwcBswSynchronizedTrigger			
Aggregated by	SwcBswMapping.synchronizedTrigger			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
bswTrigger	Trigger	0..1	ref	The BSW Trigger. **Tags:** atp.Splitkey=bswTrigger
swcTrigger	Trigger	0..1	iref	The SWC Trigger provided by a particular port. **Tags:** atp.Splitkey=swcTrigger, swcTrigger.contextPPort, swcTrigger.targetTrigger **InstanceRef implemented by:** PTriggerInAtomicSwcTypeInstanceRef

Table 5.55: SwcBswSynchronizedTrigger

[constr_10300] Existence of the reference in the role SwcBswSynchronizedTrigger.bswTrigger

Imposition time: IT_BswMD

⌈For each SwcBswSynchronizedTrigger, the reference in the role bswTrigger shall exist.⌋

[constr_10301] Existence of the instanceRef in the role SwcBswSynchronizedTrigger.swcTrigger

Imposition time: IT_BswMD

⌈For each SwcBswSynchronizedTrigger, the instanceRef in the role swcTrigger shall exist.⌋

[TPS_BSWMDT_04028] Determination of argument names for BSW functions called via ports ⌈In the case of functions calls via ports over the RTE, the RTE API generator shall determine the name of function arguments (for declaration purposes only) from the signature of the BswModuleEntry referred via the mapping.

The rule is:
The name of the function arguments shall be taken (in the given order) from
- the shortNames of the
- SwServiceArgs (according to the given order) defined in the
- BswModuleEntry referenced by the
- BswModuleEntity mapped in the
- SwcBswRunnableMapping to the
- RunnableEntity referenced by the
- OperationInvokedEvent that in turn references the
- ClientServerOperation that belongs to the
- ClientServerInterface that types the
- PortPrototype in question.

This rule applies to PortDefinedArgumentValue and “ordinary” port operation arguments as well.

If a SwcBswRunnableMapping exists, the above rule supersedes the definition of any argument identifiers by the attribute(s) RunnableEntity.argument.⌋

The meta-model elements involved in this rule are shown in the following diagram.

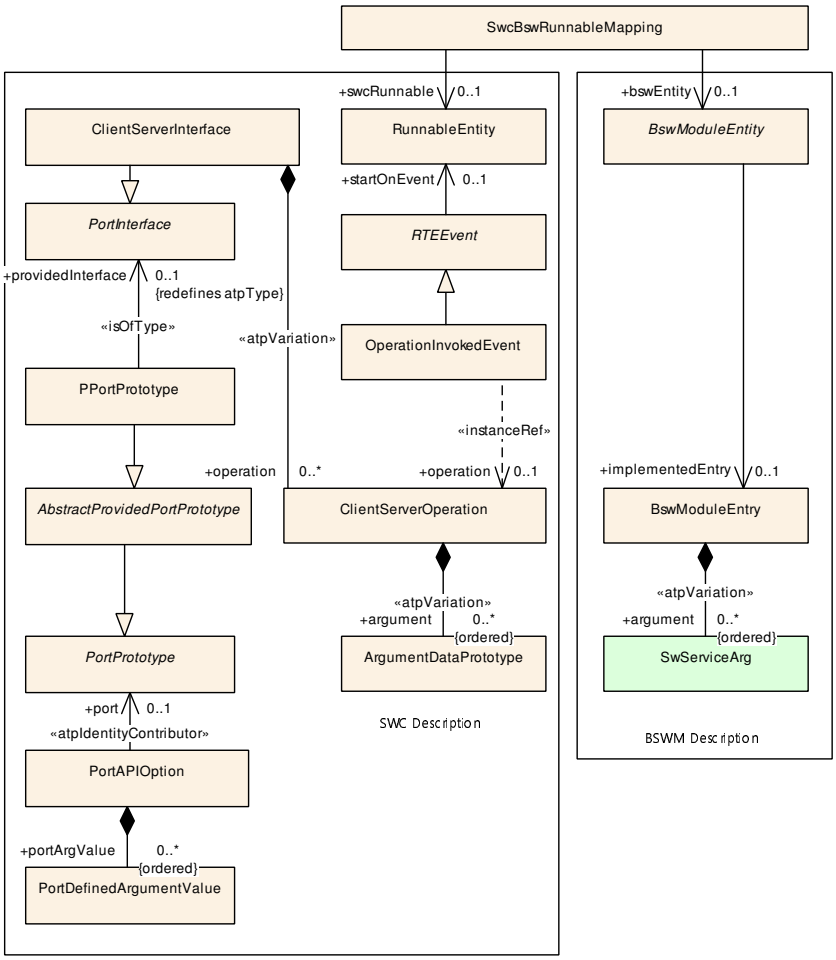

Figure 5.18: Mapping of function arguments between an SWC and a BSW module.

All mappings for one component/module are aggregated in `SwcBswMapping` which belongs to the `CommonStructure` of the meta-model. The mapping is considered as an add-on to the internal behavior (because it is mainly required to set up the RTE) but can be specified as a separate artifact which can be referred by the `Implementation` of the module. Therefore `SwcBswMapping` is derived from `ARElement`.

[TPS_BSWMDT_04138] Determination of the `BswModuleEntry` symbol ⌈The symbol of the `BswModuleEntry` is composed as following: `<bsnp>[_<vi>_<ai>]_<name>` where:

`<bsnp>` the `BswModuleDescription` shortName if no `BswSchedulerNamePrefix` is defined or the value of the symbol attribute of the `BswSchedulerNamePrefix` of the `BswModuleEntity` if a `BswSchedulerNamePrefix` is defined,

`<vi>` is the `vendorId` of the BSW module,

`<ai>` is the `vendorApiInfix` of the BSW module,

<name> is the substring after "<bsnp>_" of the BswModuleEntry shortName referred as implementedEntry.

However if <bsnp>_ is not the prefix of the related BswModuleEntry shortName then <name> is identical to BswModuleEntry.shortName.

Please note also the SWS_RTE for further details.⌋

This synchronization mechanism between software components and BSW modules is limited to the relevant parts of the basic software:

[constr_4039] Semantics of SwcBswMapping

Imposition time: IT_BswMD

⌈An SwcBswMapping is only valid, if the referred SwcInternalBehavior is aggregated by a ServiceSwComponentType, EcuAbstractionSwComponentType or ComplexDeviceDriverSwComponentType.⌋

[constr_4084] Consistency of references of InternalBehavior

Imposition time: IT_BswMD

⌈The SwcInternalBehavior referenced by SwcBswMapping.swcBehavior in the SwcBswMapping determined by SwcImplementation.swcBswMapping shall be identical to the SwcInternalBehavior referenced by SwcImplementation.behavior.⌋

[constr_4085] Consistency of references of InternalBehavior

Imposition time: IT_BswMD

⌈The BswInternalBehavior referenced by SwcBswMapping.bswBehavior in the SwcBswMapping determined by BswImplementation.swcBswMapping shall be identical to the BswInternalBehavior referenced by BswImplementation.behavior.⌋

Further constraints are:

[constr_4071] Synchronized runnables and schedulable entities shall be consistent

Imposition time: IT_BswMD

⌈A SwcBswRunnableMapping that maps a RunnableEntity to a BswCalledEntity or BswSchedulableEntity is only valid if several attributes of the mapped RunnableEntity and BswSchedulableEntity are consistent, especially all of the following constraints apply to the attributes of the given instance of SwcBswRunnableMapping:

- swcRunnable.symbol shall be identical to the symbol of bswEntity as defined in [TPS_BSWMDT_04138].
- swcRunnable.minimumStartInterval shall be identical to bswEntity.minimumStartInterval.

- swcRunnable.canBeInvokedConcurrently shall be identical to bswEntity.implementedEntry.isReentrant.
- swcRunnable.swAddrMethod shall either be empty or shall have identical attributes as the SwAddrMethod defined via bswEntity.swAddrMethod. This is required to ensure a unique configuration for the memory segment of the underlying code entity.
- swcRunnable.activationReason and bswEntity.activationReason shall have identical shortName if they define the same bitPosition and shall have identical bitPosition if they define the same shortName

⌋

[TPS_BSWMDT_04185] SwcBswRunnableMapping of a BswModuleEntity with implementedEntry in which the attribute functionPrototypeEmitter is set to RTE ⌈In case that a RunnableEntity is mapped to a BswModuleEntity by a SwcBswRunnableMapping and the BswModuleEntity refers a BswModuleEntry in the role implementedEntry in which the attribute functionPrototypeEmitter is set to RTE then the RTE Generator may emit an Entry Point Prototype for the BswModuleEntity (depending on the specified events for SWC resp. BSW).⌋

[constr_4040] Synchronized mode groups shall have same type

Imposition time: IT_BswMD

⌈SwcBswSynchronizedModeGroupPrototype can only refer to equally typed ModeDeclarationGroupPrototypes, i.e. which have identical ModeDeclarationGroups.⌋

[constr_4041] Synchronized mode groups shall have same context

Imposition time: IT_BswMD

⌈The mapping defined by SwcBswSynchronizedModeGroupPrototype implies that the component providing the one mode group prototype is also mapped to the module which provides the other mode group prototype by means of synchronizing their respective behaviors in SwcBswMapping.⌋

[constr_4042] Synchronized triggers shall have same context

Imposition time: IT_BswMD

⌈The mapping defined by SwcBswSynchronizedTrigger implies that the component providing the one trigger is also mapped to the module which provides the other trigger by means of synchronizing their respective behaviors in SwcBswMapping.⌋

[constr_4064] Synchronized triggers shall implement same policy

Imposition time: IT_BswMD

⌈The mapping defined by SwcBswSynchronizedTrigger is only valid if the attribute SwcBswSynchronizedTrigger.swcTrigger.swImplPolicy has the same value as the attribute SwcBswSynchronizedTrigger.bswTrigger.swImplPolicy.⌋

The next constraint is to avoid conflicts in generated header files for the same reason as constraint [constr_4059] does within one module (see 4.2):

[constr_4058] Different mode groups in mapped BSWM and SWC shall have different names

Imposition time: IT_BswMD

⌈If an SwcInternalBehavior is mapped to a BswInternalBehavior the corresponding SWC and BSW module descriptions may not refer to different ModeDeclarationGroups having the same shortName but different elements. This holds especially if these mode groups are not synchronized but used independently.⌋

5.12 BSW Behavior Distributed over Partitions

There a valid use cases in which parts of a given BSW module are executed on different partitions related to different processor cores within one ECU, see [12]. This includes the case, that on a given ECU different services of the same module run within different partitions and also the case, that on the same ECU the same service is available within different partitions.

In a BSWMD there is no strict information on the association of software entities to partitions or processor cores. This information is added later in the ECU configuration phase through the mapping of BswEvents to OS tasks which in turn are mapped to OsApplications which are assigned to a partition and/or processor core (see [14]). The BswModuleEntity-s that are driven by these BswEvents are then indirectly mapped to partitions and cores.

Note that under certain circumstances (e.g. no memory protection, reentrancy) it is possible to use BswModuleEntity-s and BswOperationInvokedEvents that are not mapped to tasks but still can be accessed from several partitions (see [12] for details).

Likewise, the information whether a service is potentially called across partition boundaries is added via ECU configuration of the BSW Scheduler (in case of BSW communication) or via port connectors created at ECU configuration time (in case of AUTOSAR Services).

Nonetheless the BswInternalBehavior shall be prepared for such a configuration because pieces of a module's code that potentially will run in different partitions and shall be explicitly mapped to different tasks have to be driven by separate BswEvents. In addition, it is useful to distinguish the communication behavior of a BswModuleEntity per partition, for example if it sends out data when running on one processor core and receives them when running on another core. Such information may be needed for the fine grained configuration of the RTE and IOC as well as for documentation, timing and call tree analysis.[5]

[5]The code has the possibility to retrieve information on which processor core it is running - see [12] and/or by which event it was started, see 5.8.

In particular, the following rules can be stated:

[TPS_BSWMDT_04108] `BswInternalBehavior` containing `BswModuleEntity`-s executed on different partitions ⌈If a module is designed to let the same code entities (after proper ECU configuration) run in different partitions, each code entity shall be described by only one `BswModuleEntity`. In other words, for a given code there shall be no separate `BswModuleEntity`-s per partition.

Furthermore, in case the behavior per partition shall be distinguished, the following elements shall be provided in the module's `BswInternalBehavior`:

- Each potential partition context in which some of the contained `BswModuleEntity`-s are able to run shall be modeled by an aggregation of an instance of meta-class `BswDistinguishedPartition`, see figure below. Note that this is an abstract notation and the concrete partition shall be defined later in the process as part of the configuration of the "virtual" module EcuC, see [15].
- The `BswEvent`s starting the `BswModuleEntity`s of this `BswInternalBehavior` shall be separate per potential partition and - in case there are limitations - shall indicate by the reference `BswEvent.contextLimitation` to which partition they are allowed to be mapped.
- The `BswModuleCallPoint`s of this `BswInternalBehavior` shall - in case there are limitations - indicate by the reference `BswModuleCallPoint.contextLimitation` in which partitions they are used.
- The `BswVariableAccess` elements of this `BswInternalBehavior` shall - in case there are limitations - indicate by the reference `BswVariableAccess.contextLimitation` in which partitions they are accessed.

Note that no `BswOperationInvokedEvent` and no `BswModuleClientServerEntry` are needed for a function that is provided only for callers within one partition.

Furthermore, this rule is not applicable for `BswCalledEntity`-s that shall always run in the task context of the caller.⌋

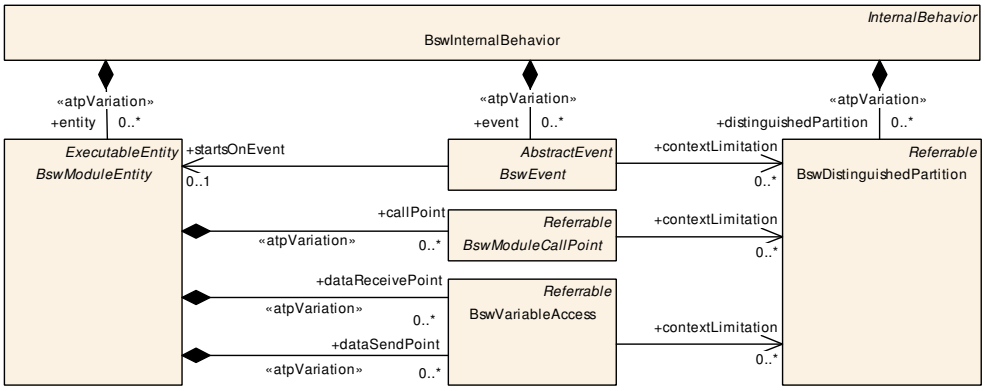

Figure 5.19: Usage of `BswDistinguishedPartition`.

[TPS_BSWMDT_04109] `BswInternalBehavior` for the same AUTOSAR Service provided on different partitions ⌈If a module is designed to implement an AUTOSAR Service - represented as a particular `ServiceSwComponentType` - which shall run (after proper ECU configuration) by the same code on several different BSW partitions in explicitly mapped tasks, then it is enough to define for each `RunnableEntity` one `SwcBswRunnableMapping` and one mapped `BswModuleEntity`. However, the necessary `RTEEvent`s shall be different for each potential partition.

This rule does not apply for those `RTEEvent`s and their corresponding `RunnableEntity`-s and `BswModuleEntity`-s which shall not be mapped to tasks.

Rule [TPS_BSWMDT_04108] applies in addition, if the behavior of the involved `BswModuleEntity`-s shall be distinguished per partition.⌋

Class	**BswDistinguishedPartition**			
Note	Each instance of this meta-class represents an abstract partition in which context the code of the enclosing BswModuleBehavior can be executed. The intended use case is to distinguish between several partitions in order to implement different behavior per partition, for example to behave either as a master or satellite in a multicore ECU with shared BSW code.			
Base	*ARObject*, *Referrable*			
Aggregated by	BswInternalBehavior.distinguishedPartition			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 5.56: BswDistinguishedPartition

[constr_4083] `BswDistinguishedPartition` shall be used only in the context of a particular `BswInternalBehavior`

Imposition time: `IT_BswMD`

⌈All instances of `BswEvent`, `BswModuleCallPoint` and `BswVariableAccess` which refer to a `BswDistinguishedPartition` shall belong to the same `BswInternalBehavior` that also aggregates the referred `BswDistinguishedPartition`.⌋

5.13 BSW API Options

The meta-class `BswApiOptions` is used as an abstract base class for the definition of concrete basic-software APIs

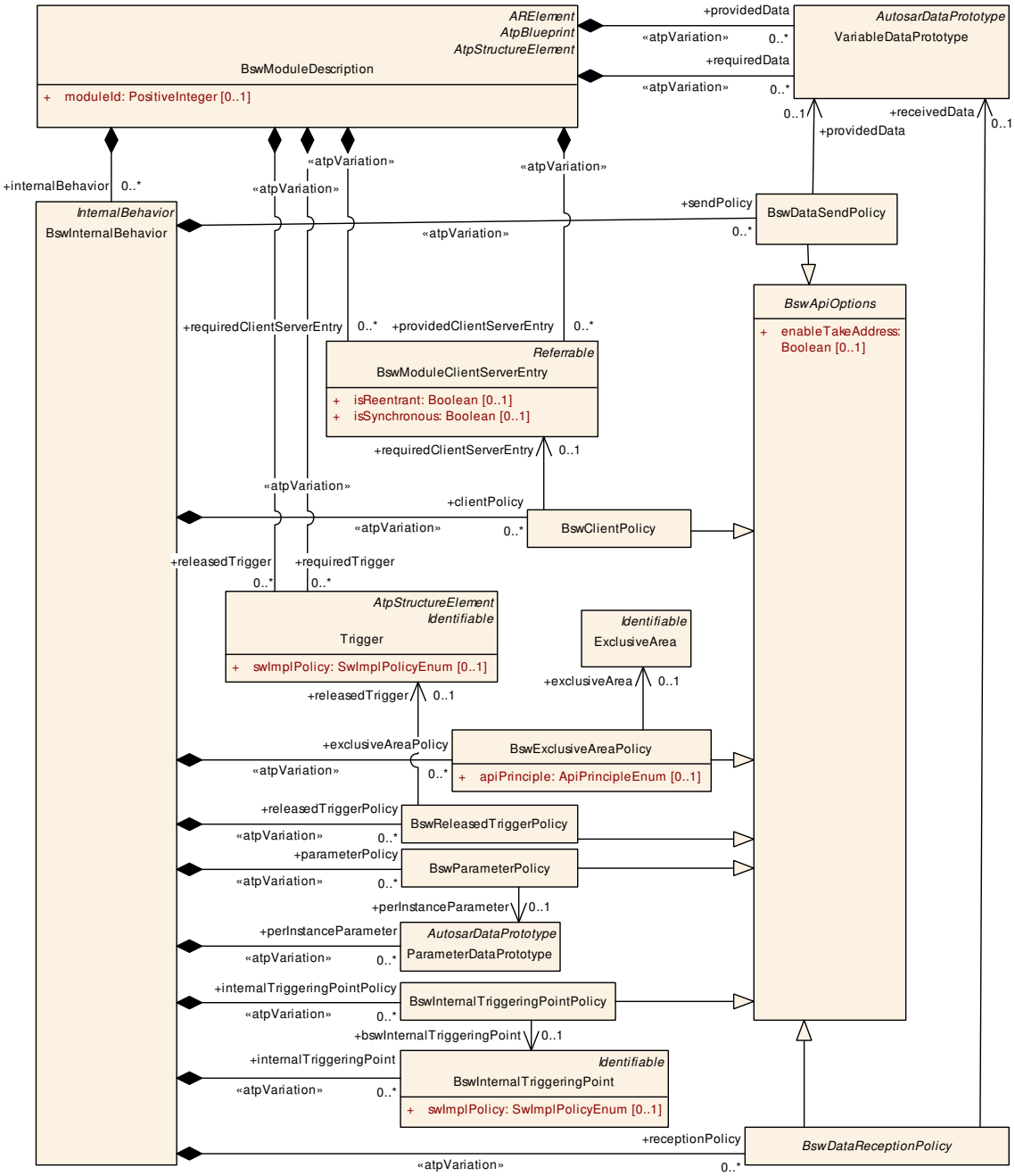

Figure 5.20: Modleing of `BswApiOptions`

Class	***BswApiOptions*** (abstract)			
Note	This meta-class represents the ability to define options for the definition of the signature of function prototypes.			
Base	*ARObject*			
Subclasses	BswClientPolicy, *BswDataReceptionPolicy*, BswDataSendPolicy, BswExclusiveAreaPolicy, BswInternal TriggeringPointPolicy, BswParameterPolicy, BswPerInstanceMemoryPolicy, BswReleasedTriggerPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
enableTake Address	Boolean	0..1	attr	If set to true, the BSW Module is able to use the API reference for deriving a pointer to an object

Table 5.57: BswApiOptions

6 BSW Implementation

6.1 Overview

The template elements to be used by the developer in order to document the actual implementation of a BSW module or cluster are very similar to what is needed for the same purpose in the case of SWCs. Therefore it is based on the `CommonStructure` part or the meta-model. This includes also the documentation of resource consumption. The generic classes of the meta-model used to document implementation and resource consumption are described in chapter 7 and chapter 8 in this document.

There are however some special features in describing the implementation of BSW. This is the purpose of the meta-class `BswImplementation` (see Figure 6.1 and the following class table).

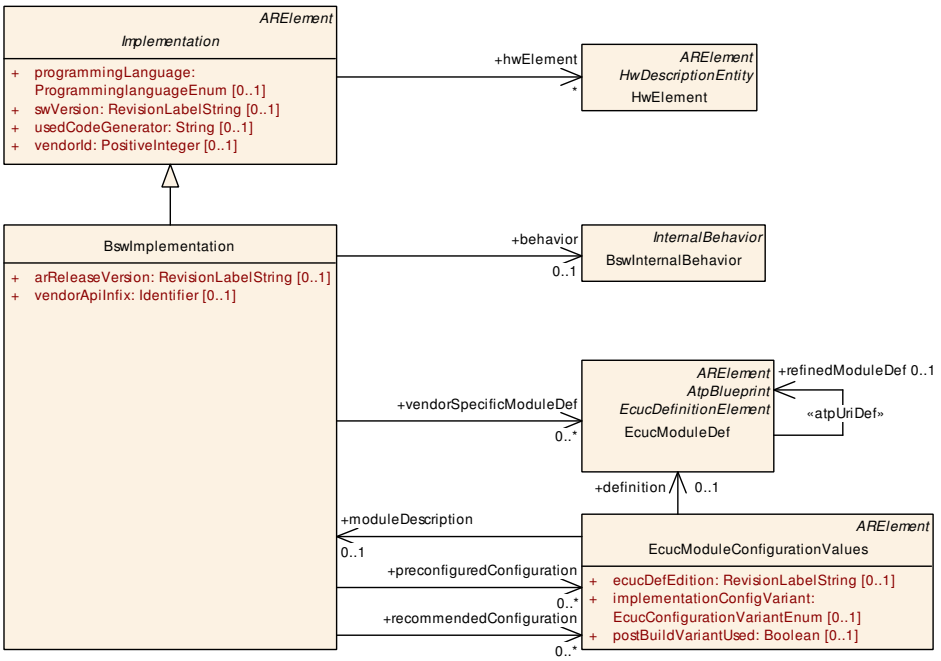

Figure 6.1: Overview of class BswImplementation

Class	**BswImplementation**			
Note	Contains the implementation specific information in addition to the generic specification (BswModule Description and BswBehavior). It is possible to have several different BswImplementations referring to the same BswBehavior. **Tags:** atp.recommendedPackage=BswImplementations This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *Implementation*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

△

Class	**BswImplementation**			
arRelease Version	RevisionLabelString	0..1	attr	Version of the AUTOSAR Release on which this implementation is based. The numbering contains three levels (major, minor, revision) which are defined by AUTOSAR.
behavior	BswInternalBehavior	0..1	ref	The behavior of this implementation. This relation is made as an association because • it follows the pattern of the SWCT • since ARElement cannot be split, but we want supply the implementation later, the BswImplementation is not aggregated in BswBehavior **Tags:** atp.Splitkey=behavior
preconfigured Configuration	EcucModule ConfigurationValues	*	ref	Reference to the set of preconfigured (i.e. fixed) configuration values for this BswImplementation. If the BswImplementation represents a cluster of several modules, more than one EcucModuleConfigurationValues element can be referred (at most one per module), otherwise at most one such element can be referred. **Tags:** atp.Splitkey=preconfiguredConfiguration xml.roleWrapperElement=true
recommended Configuration	EcucModule ConfigurationValues	*	ref	Reference to one or more sets of recommended configuration values for this module or module cluster. **Tags:** atp.Splitkey=recommendedConfiguration
vendorApiInfix	Identifier	0..1	attr	In driver modules which can be instantiated several times on a single ECU, SRS_BSW_00347 requires that the names of files, APIs, published parameters and memory allocation keywords are extended by the vendorId and a vendor specific name. This parameter is used to specify the vendor specific name. In total, the implementation specific API name is generated as follows: <Module Name>_<vendorId>_ <vendorApiInfix>_<API name from SWS>. E.g. assuming that the vendorId of the implementer is 123 and the implementer chose a vendorApiInfix of "v11r456" an API name Can_Write defined in the SWS will translate to Can_123_v11r456_Write. This attribute is mandatory for all modules with upper multiplicity > 1. It shall not be used for modules with upper multiplicity =1. See also SWS_BSW_00102.
vendorSpecific ModuleDef	EcucModuleDef	*	ref	Reference to • the vendor specific EcucModuleDef used in this Bsw Implementation if it represents a single module • several EcucModuleDefs used in this Bsw Implementation if it represents a cluster of modules • one or no EcucModuleDefs used in this Bsw Implementation if it represents a library **Tags:** atp.Splitkey=vendorSpecificModuleDef xml.roleWrapperElement=true

Table 6.1: BswImplementation

[constr_10302] Existence of attribute `BswImplementation.arReleaseVersion`

Imposition time: `IT_BswMD`

⌈For each `BswImplementation`, the attribute `arReleaseVersion` shall exist.⌋

[constr_10303] Existence of the reference in the role `BswImplementation.behavior`

Imposition time: `IT_BswMD`

⌈For each `BswImplementation`, the reference in the role `behavior` shall exist.⌋

[TPS_BSWMDT_04030] `BswImplementation.arReleaseVersion` ⌈The inclusion of the AUTOSAR version information `arReleaseVersion` is specific for AUTOSAR BSW and specified per instance of `BswImplementation`.⌋

[TPS_BSWMDT_04031] Instances of `BswImplementation` ⌈Note that in case a BSW module can potentially be used in multiple implementations on the same ECU (which means, that the code has to be there multiple times with the exception of shared libraries), for each module implementation there has to be a separate instance of `BswImplementation`. This allows to define name expansions required for global symbols via the attribute `vendorApiInfix`.⌋

[constr_4099] Support of multiple instantiation

Imposition time: `IT_BswMD`

⌈If a BSW Module supports multiple instantiation the attribute `vendorApiInfix` is mandatory.⌋

Note: If a standardized BSW Module shall support multiple instantiation is defined by AUTOSAR and described in the according STMD. For more information see [15]. It is the responsibility of a BSW Module vendor to apply unique `vendorApiInfix` values for its delivered modules.

[constr_4100] Uniqueness of module implementation prefixes

Imposition time: `IT_BswMD`

⌈Inside one ECU the Module implementation prefixes (Mip) of BSW Modules shall be unique.⌋

Note: The definition of Mip is given in [SWS_BSW_00102]

The mechanism of `vendorApiInfix`es can be seen as a special method of resolving name conflicts. This aspect is further explained in [3] [TR_METH_03010].

The notation “Wayx” in Figure 6.2 and Figure 6.3 describes that a different HW mechanism (e.g. register set) can be used to achieve the same functionality (e.g. calculation of a PWM output).

Use-case for `vendorApiInfix`es would be that the micro-controller on chip and an off chip device provide the same functionality like e.g. CanDriver capabilities. Here the abstraction shall be done via the `vendorApiInfix`es.

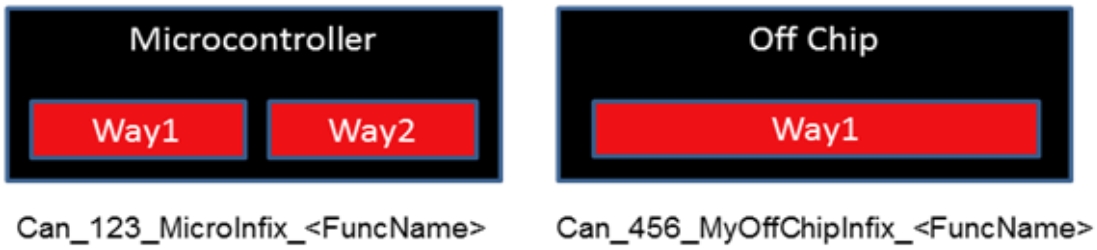

Figure 6.2: Example of a use case for `vendorApiInfix`

Non use-case for vendorApiInfixes would be that the micro-controller provides on chip for the calculation of a PWM different mechanisms for different channels. Here the abstraction shall be done via the handled ChannelNumber of the PWM.

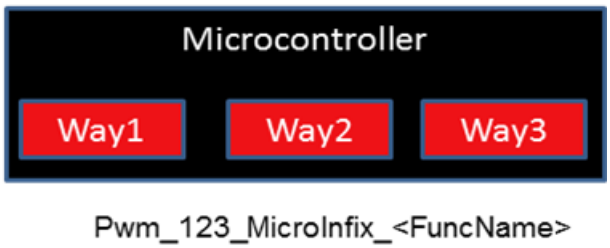

Figure 6.3: Example of a none use case for `vendorApiInfix`

[TPS_BSWMDT_04032] **`Implementation.hwElement`** ⌈The attribute `hwElement` allows to document special hardware dependencies of a BSW module or cluster in addition to what can be expressed by the generic attribute `Implementation.resourceConsumption`⌋

(see also chapter 8). The intended use case of this attribute is to document hardware dependencies of BSW modules or clusters namely in the layers MCAL, ECU Abstraction or Complex Drivers.

Finally it is possible to specify vendor specific configuration parameter definitions and predefined or recommended configuration parameter values within the scope of a BSW implementation and deliver them as part of a BSWMD. This is further explained in the next chapter.

6.2 Configuration Parameter Definitions and Values as Part of a BSWMD

[TPS_BSWMDT_04033] Reference to vendor specific configuration parameters ⌈Vendor specific configuration parameters are expressed by an association from `BswImplementation` to `EcucModuleDef`.⌋

[TPS_BSWMDT_04034] Reference to predefined or recommended configuration values ⌈Predefined or recommended configuration parameter values are expressed by associations from BswImplementation to EcucModuleConfigurationValues.⌋

The meta-classes EcucModuleDef and EcucModuleConfigurationValues are specified in the ECU Configuration Specification document [15].

Note that different implementations of the same BswModuleDescription can have different predefined or recommended parameter values and different sets of vendor specific configuration parameters. Of course it is also possible that different implementations of the same module refer to the same configuration parameter definitions resp. to the same predefined or recommended configuration parameter values.

A BswImplementation can either represent the implementation of a single module (or library) or the implementation of a cluster of modules. Therefore the following constraints hold for the multiplicities of the vendor specific configuration parameters and predefined configuration values:

[constr_4047] Multiplicity of vendor specific configuration parameters

Imposition time: IT_BswMD

⌈The association BswImplementation.vendorSpecificModuleDef shall be implemented as reference to one or more instances of EcucModuleDef if the underlying BswModuleDescription has the category BSW_CLUSTER. In all other cases, it shall refer to exactly one instance of EcucModuleDef (the one belonging to this module).⌋

[constr_4048] Multiplicity of preconfigured values

Imposition time: IT_BswMD

⌈The association BswImplementation.preconfiguredConfiguration shall be implemented as reference to zero or more different instances of EcucModuleConfigurationValues if the underlying BswModuleDescription has the category BSW_CLUSTER. In all other cases, it shall refer to at most one instance of EcucModuleConfigurationValues (the one belonging to this module).⌋

In order to specify the roles of predefined or recommended parameter values and distinguish them from the parameter value sets used finally in the ECU configuration, the following constraints hold for the enumeration attribute EcucModuleConfigurationValues.implementationConfigVariant (see [15] for definition and further usage of this attribute in the ECU configuration):

[constr_4045] implementationConfigVariant of preconfigured configuration

Imposition time: IT_BswMD

⌈An EcucModuleConfigurationValues element with the implementationConfigVariant set to the value PreconfiguredConfiguration shall only be referenced in the role preconfiguredConfiguration and no other value for implementationConfigVariant is allowed in this role.⌋

[constr_4046] `implementationConfigVariant` of recommended configuration

Imposition time: `IT_BswMD`

⌈An `EcucModuleConfigurationValues` element with the `implementationConfigVariant` set to the value `RecommendedConfiguration` shall only be referenced in the role `recommendedConfiguration` and no other value for `implementationConfigVariant` is allowed in this role.⌋

[TPS_BSWMDT_04035] Published parameter values ⌈Some AUTOSAR modules define so-called published parameters. A value of a published parameter cannot be set by the integrator, but has to be known. Thus the existence of published parameters always requires that their values have to be given as part of the `preconfiguredConfiguration`.⌋

[TPS_BSWMDT_04036] Back-reference from `EcucModuleConfigurationValues` ⌈In addition the `EcucModuleConfigurationValues` from the ECU Configuration Template can refer to the `BswImplementation` for which it defines the configuration parameters. This relation is intended to be used by the integrator or tester to indicate for which `BswImplementation` an actual ECU configuration has been set up.⌋

7 Implementation

7.1 Introduction

This chapter explains, how the implementation details of AUTOSAR Software Components and Basic Software can be described. While AUTOSAR contains various component types, only Atomic Software Components and `Basic Software Modules` possess an `Implementation`. In the meta model this means that `Implementation` can be provided for `AtomicSwComponentType` or its derived classes and `BswModuleDescription` only.

On the other hand, compositions simply structure and encapsulate their contained components in a hierarchical manner, without adding any implementation relevant behavior or functionality. So they cannot be implemented directly. Instead, the leaf components in such a composition tree which by definition are again atomic, are implemented.

7.2 Implementation Description Overview

The `Implementation` class shown in Figure 7.1 serves the following main purposes:

- provide information about the resource consumption (chapter 8)
- link to code (source code, object code) (chapter 7.5)
- specify required and generated artifacts (chapter 7.6)
- specify the compiler (chapter 7.7)
- specify the linker (chapter 7.8)
- specify data to support measurement and calibration tools (chapter 9)

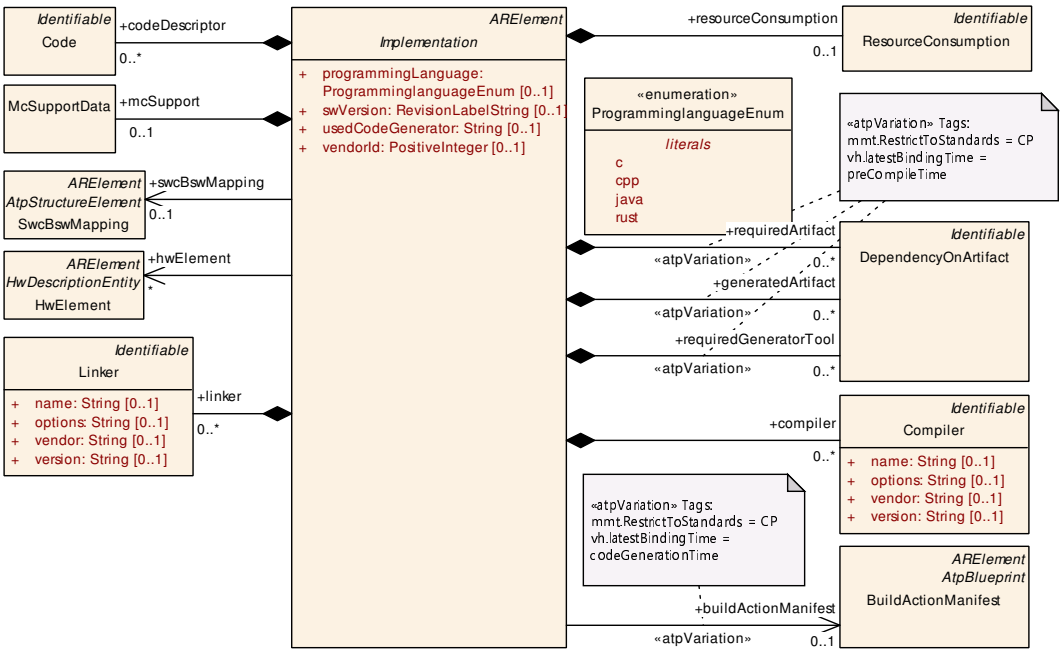

Figure 7.1: Overview of implementation description

As the figure shows, `Implementation` is derived from `ARElement`, i.e. it may be shipped as a separate engineering artifact, e.g. independent of the description of interfaces, ports and the component type.

The following table lists all attributes shown in Figure 7.1, thereby explaining the meaning of the remaining simple assertions and requirements of class `Implementation`.

Class	***Implementation*** (abstract)			
Note	Description of an implementation a single software component or module. This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Subclasses	BswImplementation, SwcImplementation			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
buildAction Manifest	BuildActionManifest	0..1	ref	A manifest specifying the intended build actions for the software delivered with this implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=buildActionManifest, buildAction Manifest.buildActionManifest, buildAction Manifest.variationPoint.shortLabel vh.latestBindingTime=codeGenerationTime
codeDescriptor	Code	*	aggr	Specifies the provided implementation code. **Tags:** atp.Splitkey=codeDescriptor, codeDescriptor.short Name
compiler	Compiler	*	aggr	Specifies the compiler for which this implementation has been released **Tags:** atp.Splitkey=compiler, compiler.shortName

△

Class	***Implementation*** (abstract)			
generated Artifact	DependencyOnArtifact	*	aggr	Relates to an artifact that will be generated during the integration of this Implementation by an associated generator tool. Note that this is an optional information since it might not always be in the scope of a single module or component to provide this information. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=generatedArtifact, generatedArtifact.shortName, generatedArtifact.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
hwElement	HwElement	*	ref	The hardware elements (e.g. the processor) required for this implementation. **Tags:** atp.Splitkey=hwElement
linker	Linker	*	aggr	Specifies the linker for which this implementation has been released. **Tags:** atp.Splitkey=linker, linker.shortName
mcSupport	McSupportData	0..1	aggr	The measurement & calibration support data belonging to this implementation. The measurement & calibration support data belonging to this implementation. **Tags:** atp.Splitkey=mcSupport
programming Language	Programminglanguage Enum	0..1	attr	Programming language the implementation was created in.
requiredArtifact	DependencyOnArtifact	*	aggr	Specifies that this Implementation depends on the existence of another artifact (e.g. a library). This aggregation of DependencyOnArtifact is subject to variability with the purpose to support variability in the implementations. Different algorithms in the implementation might cause different dependencies, e.g. the number of used libraries. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=requiredArtifact, requiredArtifact.shortName, requiredArtifact.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
required GeneratorTool	DependencyOnArtifact	*	aggr	Relates this Implementation to a generator tool in order to generate additional artifacts during integration. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=requiredGeneratorTool, requiredGeneratorTool.shortName, requiredGeneratorTool.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
resource Consumption	ResourceConsumption	0..1	aggr	All static and dynamic resources for each implementation are described within the ResourceConsumption class. **Tags:** atp.Splitkey=resourceConsumption, resourceConsumption.shortName
swcBsw Mapping	SwcBswMapping	0..1	ref	This allows a mapping between an SWC and a BSW behavior to be attached to an implementation description (for AUTOSAR Service, ECU Abstraction and Complex Driver Components). It is up to the methodology to define whether this reference has to be set for the Swc- or Bsw Implementtion or for both. **Tags:** atp.Splitkey=swcBswMapping

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Class	*Implementation* (abstract)			
swVersion	RevisionLabelString	0..1	attr	Software version of this implementation. The numbering contains three levels (like major, minor, patch), its values are vendor specific.
usedCode Generator	String	0..1	attr	Optional: code generator used.
vendorId	PositiveInteger	0..1	attr	Vendor ID of this Implementation according to the AUTOSAR vendor list

Table 7.1: Implementation

Enumeration	**ProgramminglanguageEnum**
Note	Programming language the implementation was created in.
Aggregated by	*Implementation*.programmingLanguage
Literal	***Description***
c	C language **Tags:** atp.EnumerationLiteralIndex=0
cpp	C++ language **Tags:** atp.EnumerationLiteralIndex=1
java	Java language **Tags:** atp.EnumerationLiteralIndex=2
rust	Rust language **Tags:** atp.EnumerationLiteralIndex=3

Table 7.2: ProgramminglanguageEnum

7.3 Assertions and Requirements

For some of the attributes mentioned below it is ambiguous whether they describe a requirement on the target environment or whether they are assertions made by the particular component implementation. The `Implementation` description's `compiler` attribute is an example for this: does it describe a requirement for source code to be compiled with the named compiler, or is this simply information which compiler was used in the process of creating an object file? The simple answer is: if possible, this is derived from the context. Otherwise the attribute needs to have proper documentation. For the `compiler` example just mentioned, the situation is straightforward: for source code, the attribute describes a requirement, for object code it is documented information. The same needs to be applied to all attributes in this section.

7.4 Implementation of a Software Component

[TPS_BSWMDT_04039] Association of an `Implementation` with a component or module ⌈Probably the most important information in `Implementation` is which Atomic Software Component or BSW Module is actually implemented. Implementations are actually given for a particular component behavior, specified through the

class SwcInternalBehavior respectively BswInternalBehavior. The contents of such a behavior are not of interest here, but it in turn is associated with a single AtomicSwComponentType or BswModuleDescription.⌋

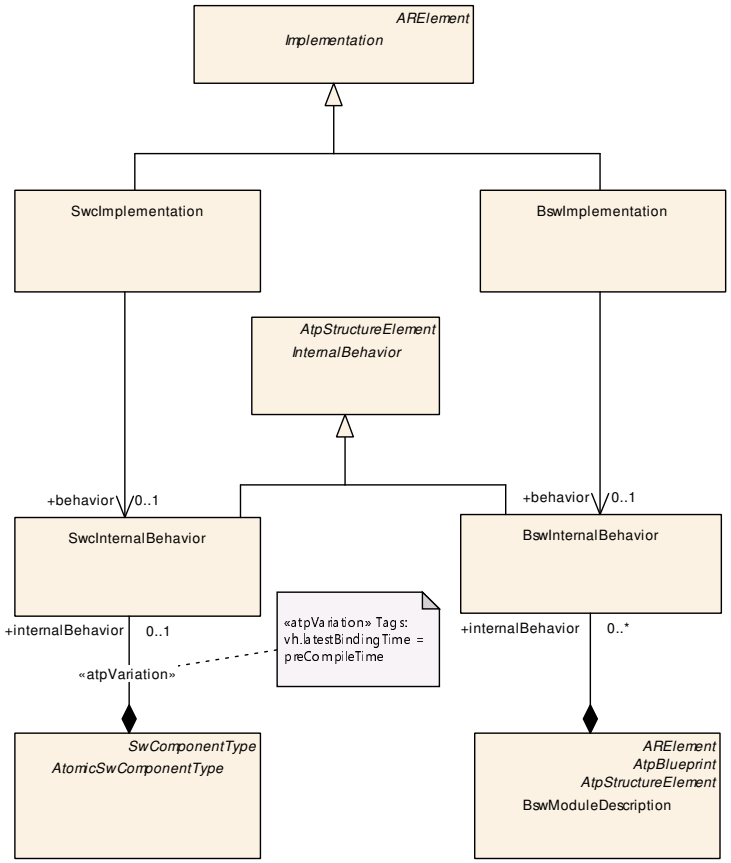

Figure 7.2: An implementation is associated with a single software component or module

7.5 Linking to Code

When a component is released the descriptions are accompanied by actual implementation code. This code can come in different ways: Source code in C, C++ or Java, object code or even executable code[1].

Figure 7.3 shows how an Implementation is linked to Code.

[TPS_BSWMDT_04040] **Implementation.codeDescriptor** ⌈For each available form of component code a Code element is used. For each codeDescriptor, all relevant artifacts are then referenced through the attribute artifactDescriptor (class AutosarEngineeringObject) which in turn references to a catalog of available files through a set of attributes as shown below. If for instance a component implementation is given as source code only, then the respective Implementation would contain

[1] Delivery of executable code is currently not supported by AUTOSAR.

exactly one codeDescriptor, whose artifactDescriptor.category attribute would denote the files to be source files.⌋

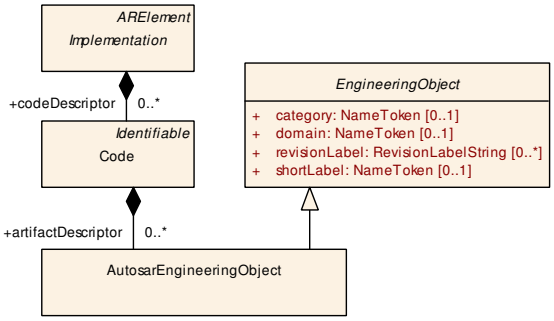

Figure 7.3: An Implementation references the code artifacts through the Code class

Class	**Code**			
Note	A generic code descriptor. The type of the code (source or object) is defined via the category attribute of the associated engineering object.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*Implementation*.codeDescriptor			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
artifact Descriptor	AutosarEngineering Object	*	aggr	Refers to the artifact belonging to this code descriptor. **Tags:** atp.Splitkey=artifactDescriptor
callbackHeader	ServiceNeeds	*	ref	The association callbackHeader describes in which header files the function declarations of callback functions are provided to a service module. With this information the service module can include the appropriate header files in its configuration files. **Tags:** atp.Splitkey=callbackHeader

Table 7.3: Code

7.6 Dependencies

An implementation can generally depend on other artifacts, e.g. files. Such files could for example be required header, configuration or library files.

[TPS_BSWMDT_04041] DependencyOnArtifact ⌈This is described by the class DependencyOnArtifact which relates to meta-information via the class Autosar-EngineeringObject.⌋

This is shown in Figure 7.4.

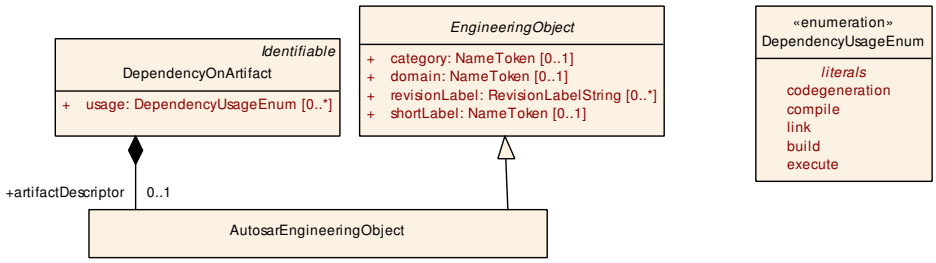

Figure 7.4: Dependencies of an `Implementation`

[TPS_BSWMDT_04042] Usage of `DependencyOnArtifact` ⌈The class `DependencyOnArtifact` can be aggregated by `Implementation` in several different roles. By this it can also be used to specify that a certain generator tool is required to integrate a module and/or that a certain artifact is generated.

For libraries, like e.g. a `math.lib`, the desired version numbers can be specified via the attribute `revisionLabel`, therefore trying to ensure compatibility. Note that the specification of version numbers and other attributes is a meta-information about certain artifacts which shall refer to a concrete catalog description.⌋

This mechanism is described in more detail in the AUTOSAR Methodology, see [3].

Class	**DependencyOnArtifact**			
Note	Dependency on the existence of another artifact, e.g. a library.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*Implementation*.generatedArtifact, *Implementation*.requiredArtifact, *Implementation*.requiredGeneratorTool			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
artifactDescriptor	AutosarEngineeringObject	0..1	aggr	The specified artifact needs to exist. **Tags:** atp.Splitkey=artifactDescriptor
usage	DependencyUsageEnum	*	attr	Specification for which process step(s) this dependency is required.

Table 7.4: DependencyOnArtifact

[constr_10304] Existence of attribute `DependencyOnArtifact.usage`

Imposition time: `IT_BswMD`

⌈For each `DependencyOnArtifact`, the attribute `usage` shall exist at least once.⌋

Enumeration	**DependencyUsageEnum**
Note	Enumeration describing the process steps a dependency is valid in.
Aggregated by	DependencyOnArtifact.usage
Literal	***Description***
build	The object referred by the dependency is required during the build process. **Tags:** atp.EnumerationLiteralIndex=0

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Enumeration	**DependencyUsageEnum**
codegeneration	The object referred by the dependency is required during code generation **Tags:** atp.EnumerationLiteralIndex=1
compile	The object referred by the dependency is required during compilation. **Tags:** atp.EnumerationLiteralIndex=2
execute	The object referred by the dependency is required at execution time. **Tags:** atp.EnumerationLiteralIndex=3
link	The object referred by the dependency is required during linking. **Tags:** atp.EnumerationLiteralIndex=4

Table 7.5: DependencyUsageEnum

Class	**AutosarEngineeringObject**			
Note	This denotes an engineering object being part of the process. It is a specialization of the abstract class EngineeringObject for usage within AUTOSAR.			
Base	*ARObject*, *EngineeringObject*			
Aggregated by	AclObjectSet.engineeringObject, *BuildActionEntity*.deliveryArtifact, Code.artifactDescriptor, Dependency OnArtifact.artifactDescriptor			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 7.6: AutosarEngineeringObject

Class	***EngineeringObject*** (abstract)			
Note	This class specifies an engineering object. Usually such an object is represented by a file artifact. The properties of engineering object are such that the artifact can be found by querying an ASAM catalog file. The engineering object is uniquely identified by domain+category+shortLabel+revisionLabel.			
Base	*ARObject*			
Subclasses	AutosarEngineeringObject, BuildEngineeringObject, Graphic			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
category	NameToken	0..1	attr	This denotes the role of the engineering object in the development cycle. Categories are such as • SWSRC for source code • SWOBJ for object code • SWHDR for a C-header file Further roles need to be defined via Methodology. **Tags:** xml.sequenceOffset=20
domain	NameToken	0..1	attr	This denotes the domain in which the engineering object is stored. This allows to indicate various segments in the repository keeping the engineering objects. The domain may segregate companies, as well as automotive domains. Details need to be defined by the Methodology. Attribute is optional to support a default domain. **Tags:** xml.sequenceOffset=40
revisionLabel	RevisionLabelString	*	attr	This is a revision label denoting a particular version of the engineering object. **Tags:** xml.sequenceOffset=30

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Class	*EngineeringObject* (abstract)			
shortLabel	NameToken	0..1	attr	This is the short name of the engineering object. Note that it is modeled as NameToken and not as Identifier since in ASAM-CC it is also a NameToken. **Tags:** xml.sequenceOffset=10

Table 7.7: EngineeringObject

7.7 Compiler

[TPS_BSWMDT_04043] `Compiler` ⌈For the specification of the used (or to be used) compiler the `Compiler` element shall be used.⌋

Class	**Compiler**			
Note	Specifies the compiler attributes. In case of source code this specifies requirements how the compiler shall be invoked. In case of object code this documents the used compiler settings.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*Implementation*.compiler			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
name	String	0..1	attr	Compiler name (like gcc).
options	String	0..1	attr	Specifies the compiler options.
vendor	String	0..1	attr	Vendor of compiler.
version	String	0..1	attr	Exact version of compiler executable.

Table 7.8: Compiler

7.8 Linker

[TPS_BSWMDT_04044] `Linker` ⌈For the specification of the to be used linker the `Linker` element shall be used.⌋

Class	**Linker**			
Note	Specifies the linker attributes used to describe how the linker shall be invoked.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*Implementation*.linker			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
name	String	0..1	attr	Linker name.
options	String	0..1	attr	Specifies the linker options.
vendor	String	0..1	attr	Vendor of linker.
version	String	0..1	attr	Exact version of linker executable.

Table 7.9: Linker

7.9 Build Action Manifest

[TPS_BSWMDT_04085] `Implementation` refers to a `BuildActionManifest` ⌈An `Implementation` can optionally be linked to a `BuildActionManifest` in order to specify the intended build actions for the software delivered with this implementation.⌋

Class	**BuildActionManifest**			
Note	This meta-class represents the ability to specify a manifest for processing artifacts. An example use case is the processing of ECUC parameter values. **Tags:** atp.recommendedPackage=BuildActionManifests xml.globalElement=false			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
buildAction	BuildAction	*	aggr	This represents a particular action in the build chain. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=buildAction, buildAction.shortName, buildAction.variationPoint.shortLabel vh.latestBindingTime=blueprintDerivationTime
buildAction Environment	BuildActionEnvironment	*	aggr	This represents a build action environment. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=buildActionEnvironment, buildAction Environment.shortName, buildAction Environment.variationPoint.shortLabel vh.latestBindingTime=blueprintDerivationTime
dynamicAction	BuildAction	*	ref	This denotes an Action which is to be executed as part of the dynamic action set. **Tags:** atp.Splitkey=dynamicAction
startAction	BuildAction	*	ref	This specifies the list of actions to be performed at the beginning of the process. **Tags:** atp.Splitkey=startAction xml.sequenceOffset=-90
tearDownAction	BuildAction	*	ref	This specifies the set of action which shall be performed after all other actions in the manifest were performed. **Tags:** atp.Splitkey=tearDownAction xml.sequenceOffset=-80

Table 7.10: BuildActionManifest

The setup of such a manifest is further explained in [1], see [TPS_GST_00294].

[TPS_BSWMDT_04086] Artifacts referred in `Implementation` and/or `BuildActionManifest` ⌈It should be noted that the `Implementation` instance as well as the `BuildActionManifest` instance can aggregate descriptive elements derived from meta-class `EngineeringObject` which eventually represent file artifacts to be used by the integrator. These two sets of artifacts may differ but are not necessarily exclusive, i.e. it shall be allowed to describe the same artifact under `Implementation` and under `BuildActionManifest` as well (of course not in contradiction).

Especially, the element Implementation.codeDescriptor is mandatory, so this element cannot be omitted even if an equivalent EngineeringObject describing the code file is part of the BuildActionManifest.⌋

8 ResourceConsumption

AUTOSAR software needs to be mapped on ECUs at some point during the development. Application Software Components can be basically mapped to any ECU available within the car. The mapping freedom is limited by the *System Constraints* [6] and the available resources on each ECU. BSW Modules are present in each ECU which provides the corresponding service. The `ResourceConsumption` element provides information about the needed resources concerning memory and execution time for each `SwcImplementation` or `BswImplementation`.

8.1 Static and Dynamic Resources

Resources can be divided into static and dynamic resources.

Static resources can only be allocated by one entity and stay with this entity. If the required amount of resources is bigger than the available resources the mapping does not fit physically. ROM is an example of a spare resource where obviously only the amount of data can be stored that is provided by the storage capacity.

Dynamic resources are shared and therefore can be allocated dynamically to different control threads over time. Processing time is a good example, where different tasks are given the processor for some time. If some runnable entity uses more processing time than originally planned, it can lead to functional failure. Also some sections of RAM can be seen as dynamic resources (e.g. stack, heap which grow and shrink dynamically).

8.2 Resource consumption overview

In Figure 8.1, the meta-model of the `ResourceConsumption` description is depicted.

[TPS_BSWMDT_04045] **`Implementation.resourceConsumption`** ⌈The `ResourceConsumption` is attached to an `Implementation`. For each `Implementation`, there is one `ResourceConsumption` description.⌋

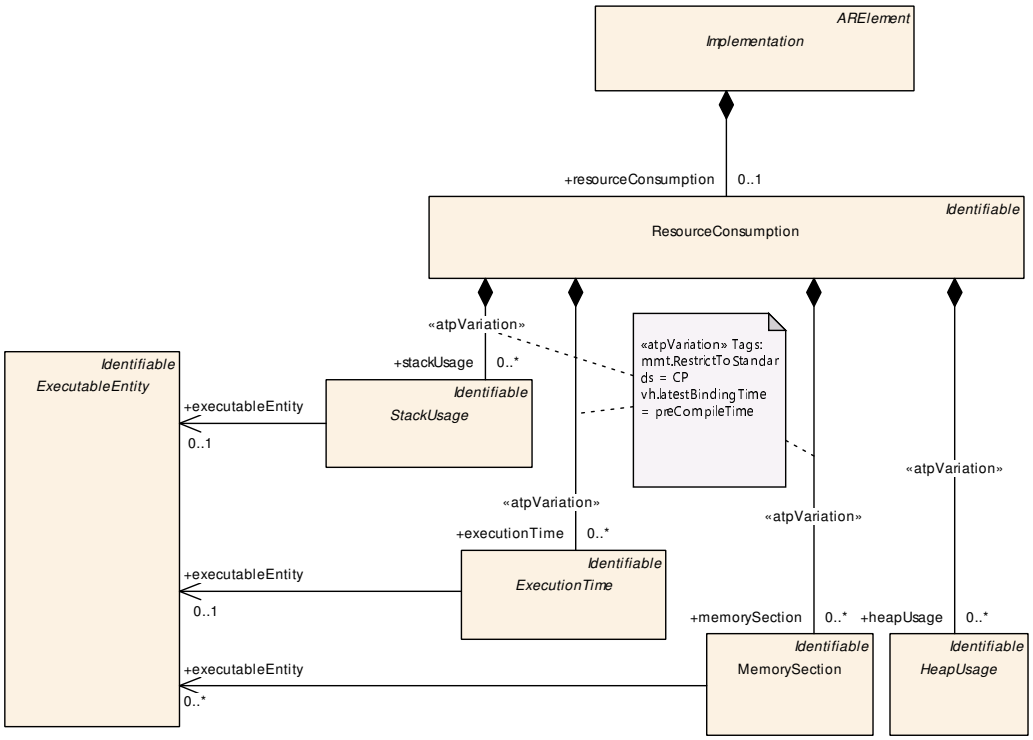

Figure 8.1: Resource consumption overview

As depicted by Figure 8.1, all resources are described within the `ResourceConsumption` meta-class.

`ExecutionTime` (chapter 8.5) and `StackUsage` (chapter 8.4.2) are used to provide information on the implementation specific resource usage of the `ExecutableEntity` defined in the `InternalBehavior` of SW-Component respectively in the `BswInternalBehavior` of BSW Module.

`MemorySection` (chapter 8.3.2) documents the resources needed to load the object file containing the implementation on the ECU.

`HeapUsage` (chapter 8.4.3) describes the dynamic memory usage of the software.

Class	**ResourceConsumption**			
Note	Description of consumed resources by one implementation of a software.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	EcuResourceEstimation.bswResourceEstimation, EcuResourceEstimation.rteResourceEstimation, *Implementation*.resourceConsumption, StateDependentStartupConfig.resourceConsumption			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

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Class	**ResourceConsumption**			
accessCount Set	AccessCountSet	*	aggr	Set of access count values **Stereotypes:** atpVariation **Tags:** atp.Splitkey=accessCountSet, accessCountSet.variation Point.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.
executionTime	ExecutionTime	*	aggr	Collection of the execution time descriptions for this implementation. The aggregation of executionTime is subject to variability with the purpose to support the conditional existence of runnable entities. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=executionTime, executionTime.shortName, executionTime.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.
heapUsage	HeapUsage	*	aggr	Collection of the heap memory allocated by this implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=heapUsage, heapUsage.shortName, heap Usage.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.
memorySection	MemorySection	*	aggr	An abstract memory section required by this Implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=memorySection, memorySection.short Name, memorySection.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.
sectionName Prefix	SectionNamePrefix	*	aggr	A prefix to be used for the memory section symbol in the code. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=sectionNamePrefix, sectionNamePrefix.short Name, sectionNamePrefix.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.

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Class	**ResourceConsumption**			
stackUsage	StackUsage	*	aggr	Collection of the stack memory usage for each runnable entity of this implementation. The aggregation of Stack Usage is subject to variability with the purpose to support the conditional existence of runnable entities. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=stackUsage, stackUsage.shortName, stack Usage.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.

Table 8.1: ResourceConsumption

8.3 Static Memory Needs

8.3.1 General

This sub-chapter describes how the static memory needs for the `Implementation` are specified. This includes all memory needs of software for code or data both at the class and at the instance level except for:

- stack space needed in the task that activates an `ExecutableEntity` of the implementation (see chapter 8.4.2)
- dynamic heap-behavior of the software (in case the software uses `malloc/free` to get/free buffers from the heap, see chapter 8.4.3[1])

8.3.2 Memory Sections

Memory will be needed to load the object-file containing an implementation of the software on an ECU. In which kind of memory the code and data of the software have to be allocated has to be defined in an abstract (i.e. platform and compiler independent) way in the source code of the software according to [16].

To support the integration and configuration of the software component or module the used (abstract) memory sections and their attributes have to be described also in XML via the `MemorySection` element from figure 8.2.

[1] This is often problematic in embedded and real-time systems: most software will only need static memory blocks and stack-size but will not require dynamic memory allocation

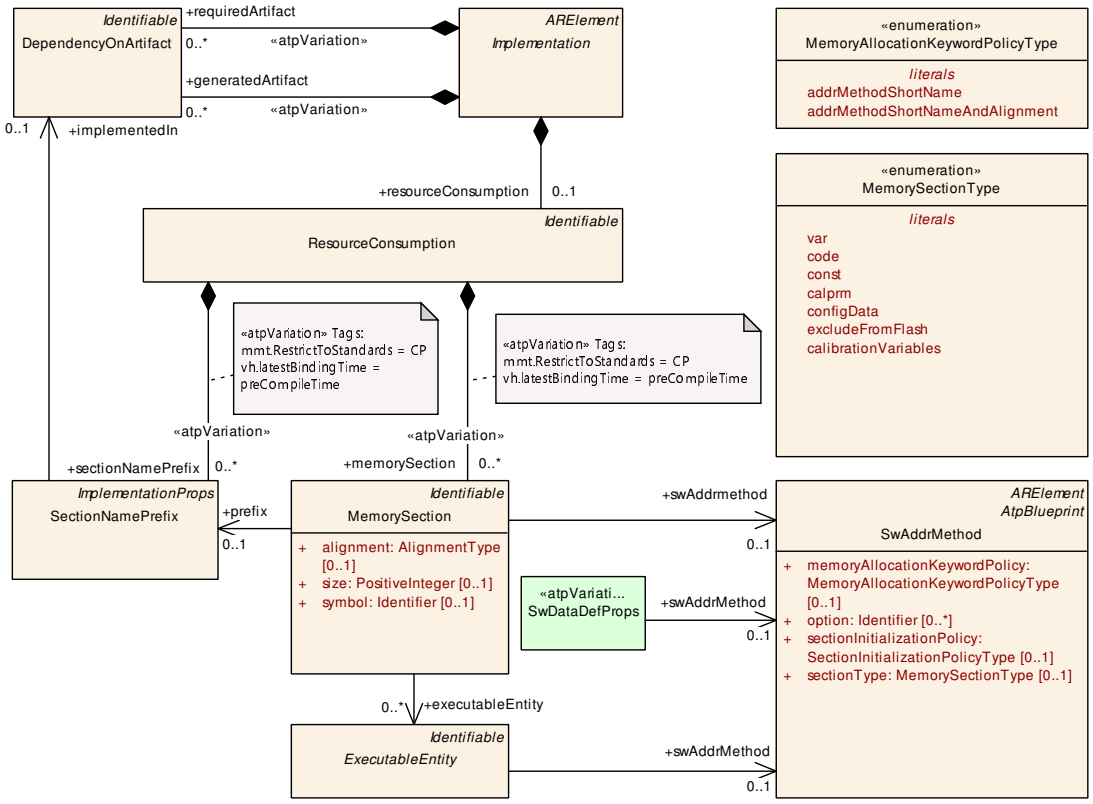

Figure 8.2: Meta-model related to the `MemorySection`

[TPS_BSWMDT_04046] Memory section name ⌈The actual section name is given by the `MemorySection.symbol`, if this attribute is missing the `MemorySection.shortName` is taken as default (this is for backwards compatibility reasons). The section name of each `MemorySection` instance shall be a part of the so-called memory allocation keyword used in preprocessor statements in the actual code.⌋

For example for a memory section entered by the macro RTE_START_SEC_VAR_FAST_8 the `MemorySection.symbol` shall be VAR_FAST_8.

The preprocessor macros contain in addition so-called prefixes which set up a kind of name space and by default are equal to the `shortName` of the enclosing `BswModuleDescription` or the `AtomicSwComponentType` (in the above example, the prefix is RTE).

[TPS_BSWMDT_04047] Memory section prefix ⌈It is possible to supersede these prefixes by more fine granular values using the meta-class `SectionNamePrefix`.⌋

There are basically two use cases to supersede the prefix of a memory allocation key word:

- A Basic Software Module Description provides the description for a ICC1 or ICC2 cluster which still has a sub granularity in its memory allocation implemented.

- A BSW module or software component is split into in allocatable memory parts. These memory parts are used to assign the sections (CODE, CONST, VAR) belonging to a certain functionality to a set of physical controller memories. For instance the interface code is put to memory which is rather fast accessibly from all interface users whereas the inner functionality is mapped to memory where the used hard ware can be accessed with less overhead.

[constr_4103] Name convention for `SectionNamePrefix.symbol`

Imposition time: `IT_BswMD`

⌈In case a BSW module is split into allocatable memory parts the existing (according to [SWS_MemMap_00041]) `SectionNamePrefix.symbol` shall be set in the <MIP>_<FEATURE> form, where:

- <MIP>: is the capitalized module implementation prefix
- <FEATURE>: is the name of the sub-feature in the BSW module denoting the allocatable memory part

⌋

[constr_4104] Referencing of `MemorySection`s to `SectionNamePrefix`

Imposition time: `IT_BswMD`

⌈In case a BSW module or Software Component is split into allocatable memory parts all `MemorySection`s belonging to the same allocatable memory part shall reference the identical `SectionNamePrefix` representing the allocatable memory part.⌋

The mapping of the allocation keywords to the compiler specific code is done via header files. It is possible to generate these header files from an ECU configuration description, which in turn is constrained by the `MemorySection`s and `SwAddrMethod`s used in the “upstream” descriptions of modules and components.

[TPS_BSWMDT_04092] Provide memory mapping header file names ⌈As a default rule, there is one memory mapping header file per BSW module or per SWC and the name of this file includes the `shortName` of the `BswModuleDescription` resp. the `AtomicSwComponentType` as a prefix.

However, for BSW modules or clusters it is possible to supersede the default rule by explicit reference to one or more files with specific names and granularity. This is specified by defining one or more `DependencyOnArtifact` elements aggregated by `BswImplementation` in the role `requiredArtifact` and with `DependencyOnArtifact.category` set to the value `MEMMAP`.

The detailed rules on how these header file names are derived are given in [16]: [SWS_MemMap_00028], [SWS_MemMap_00029], [SWS_MemMap_00032], [SWS_MemMap_00035]⌋

Note that in any case the AUTOSAR memory mapping header files are considered as implementation of an own virtual BSW module `MemMap`, therefore other modules

need to refer to these headers via the role requiredArtifact. In contrast, a BswImplementation representing the implementation of module MemMap would refer to these files via the role generatedArtifact.

[TPS_BSWMDT_04097] Assigning different header files per section prefix ⌈In case more than one memory mapping header is referred by one BswImplementation according to [TPS_BSWMDT_04092], the different header files have to be assigned to individual memory section prefixes by setting the references SectionNamePrefix.implementedIn.⌋

[constr_4072] Constraints of SectionNamePrefix.implementedIn

Imposition time: IT_BswMD

⌈

- The SectionNamePrefix and the DependencyOnArtifact connected via this link shall belong to the same BswImplementation.
- The DependencyOnArtifact referred by this link shall be aggregated by BswImplementation in the role requiredArtifact.
- The DependencyOnArtifact referred by this link shall have the category value set to MEMMAP.

⌋

For a list of standardized allocation keywords, further explanation of the memory mapping header files and their configuration parameters see [16].

[TPS_BSWMDT_04048] Scope of declared memory sections ⌈It is further important to note, that a BSW module or an SWC shall declare only those sections which are actually part of its implemented code.⌋

That means in particular, if an SWC requires some data to be allocated by the RTE, for example shared calibration parameters or buffers for communication via ports, the memory sections of these data have to be declared via an BswImplementation which is generated by the RTE and represents the implementation of the module RTE.

Several different instances of MemorySection (also across module or component boundaries) can refer to the same SwAddrMethod, indicating that these abstract sections share a common means of being handled which is further characterized by SwAddrMethod.sectionType.

The attributes of SwAddrMethod (namely sectionType, memoryAllocationKeywordPolicy,option and sectionInitializationPolicy) as well as MemorySection.alignment put constraints on the selection of appropriate allocation keywords resp. their configuration values. This is further explained in [16].

Note that the shortName of SwAddrMethod also has some relationship to the allocation keyword and thus to the section name defined by MemorySection, which is an intended redundancy.

SwAddrMethod is also referred by the “upstream” specifications of the data or executable entities belonging to these sections, so that the section type can be predefined early in the process.

The attributes of MemorySection and SwAddrMethod are shown below:

Class	**MemorySection**			
Note	Provides a description of an abstract memory section used in the Implementation for code or data. It shall be declared by the Implementation Description of the module or component, which actually allocates the memory in its code. This means in case of data prototypes which are allocated by the RTE, that the generated Implementation Description of the RTE shall contain the corresponding MemorySections. The attribute "symbol" (if symbol is missing: "shortName") defines the module or component specific section name used in the code. For details see the document "Specification of Memory Mapping". Typically the section name is build according the pattern: <SwAddrMethod shortName>[_<further specialization nominator>][_<alignment>] where • **[<SwAddrMethod shortName>]** is the shortName of the referenced SwAddrMethod • **[_<further specialization nominator>]** is an optional infix to indicate the specialization in the case that several MemorySections for different purpose of the same Implementation Description referring to the same or equally named SwAddrMethods. • **[_<alignment>]** is the alignment attributes value and is only applicable in the case that the memory AllocationKeywordPolicy value of the referenced SwAddrMethod is set to addrMethodShortNameAndAlignment MemorySection used to Implement the code of RunnableEntitys and BswSchedulableEntitys shall have a symbol (if missing: shortName) identical to the referred SwAddrMethod to conform to the generated RTE header files. In addition to the section name described above, a prefix is used in the corresponding macro code in order to define a name space. This prefix is by default given by the shortName of the BswModule Description resp. the SwComponentType. It can be superseded by the prefix attribute.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.memorySection			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
alignment	AlignmentType	0..1	attr	The attribute describes the typical alignment of objects within this memory section.
executableEntity	ExecutableEntity	*	ref	Reference to the ExecutableEntitites located in this section. This allows to locate different Executable Entitities in different sections even if the associated Sw Addrmethod is the same. This is applicable to code sections only. **Tags:** atp.Splitkey=executableEntity
prefix	SectionNamePrefix	0..1	ref	The prefix used to set the memory section’s namespace in the code. The existence of a prefix element supersedes rules for a default prefix (such as the Bsw ModuleDescription’s shortName). This allows the user to define several name spaces for memory sections within the scope of one module, cluster or SWC. **Tags:** atp.Splitkey=prefix
size	PositiveInteger	0..1	attr	The size in bytes of the section.

▽

△

Class	**MemorySection**			
swAddrmethod	SwAddrMethod	0..1	ref	This association indicates that this module specific (abstract) memory section is part of an overall SwAddr Method, referred by the upstream declarations (e.g. calibration parameters, data element prototypes, code entities) which share a common addressing strategy. This can be evaluated for the ECU configuration of the build support. This association shall always be declared by the Implementation description of the module or component, which allocates the memory in its code. This means in case of data prototypes which are allocated by the RTE, that the software components only declare the grouping of its data prototypes to SwAddrMethods, and the generated Implementation Description of the RTE actually sets up this association. **Tags:** atp.Splitkey=swAddrmethod
symbol	Identifier	0..1	attr	Defines the section name as explained in the main description. By using this attribute for code generation (instead of the shortName) it is possible to define several different MemorySections having the same name - e.g. symbol = CODE - but using different sectionName Prefixes.

Table 8.2: MemorySection

Primitive	**AlignmentType**
Note	This primitive represents the alignment of objects within a memory section. The value is in number of bits or UNKNOWN (deprecated), 8 , 16, 32, 64 UNSPECIFIED, BOOLEAN, or PTR. Typical values for numbers are 8, 16, 32, 64. **Tags:** xml.xsd.customType=ALIGNMENT-TYPE xml.xsd.pattern=[1-9][0-9]*|0[xX][0-9a-fA-F]*|0[bB][0-1]+|0[0-7]*|UNSPECIFIED|UNKNOWN|BOOLEAN|PTR xml.xsd.type=string

Table 8.3: AlignmentType

Class	**SwAddrMethod**			
Note	Used to assign a common addressing method, e.g. common memory section, to data or code objects. These objects could actually live in different modules or components. **Tags:** atp.recommendedPackage=SwAddrMethods			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
memory Allocation KeywordPolicy	MemoryAllocation KeywordPolicyType	0..1	attr	Enumeration to specify the name pattern of the Memory Allocation Keyword.

▽

△

Class	**SwAddrMethod**			
option	Identifier	*	attr	This attribute introduces the ability to specify further intended properties of the MemorySection in with the related objects shall be placed. These properties are handled as to be selected. The intended options are mentioned in the list. In the Memory Mapping configuration, this option list is used to determine an appropriate MemMapAddressing ModeSet.
section Initialization Policy	SectionInitialization PolicyType	0..1	attr	Specifies the expected initialization of the variables (inclusive those which are implementing VariableData Prototypes). Therefore this is an implementation constraint for initialization code of BSW modules (especially RTE) as well as the start-up code which initializes the memory segment to which the AutosarData Prototypes referring to the SwAddrMethod's are later on mapped. If the attribute is not defined it has the identical semantic as the attribute value "INIT"
sectionType	MemorySectionType	0..1	attr	Defines the type of memory sections which can be associated with this addressing method.

Table 8.4: SwAddrMethod

Enumeration	**MemoryAllocationKeywordPolicyType**
Note	Enumeration to specify the name pattern of the Memory Allocation Keyword.
Aggregated by	SwAddrMethod.memoryAllocationKeywordPolicy
Literal	*Description*
addrMethodShort Name	The MemorySection shortNames of referring MemorySections and therefore the belonging Memory Allocation Keywords in the code are build with the shortName of the SwAddrMethod. This is the default value if the attribute does not exist. **Tags:** atp.EnumerationLiteralIndex=0
addrMethodShort NameAndAlignment	The MemorySection shortNames of referring MemorySections and therefore the belonging Memory Allocation Keywords in the code are build with the shortName of the SwAddrMethod and a variable alignment postfix. Thereby the alignment postfix needs to be consistent with the alignment attribute of the related MemorySection. **Tags:** atp.EnumerationLiteralIndex=1

Table 8.5: MemoryAllocationKeywordPolicyType

Primitive	**SectionInitializationPolicyType**
Note	SectionInitializationPolicyType describes the intended initialization of MemorySections. The following values are standardized in AUTOSAR Methodology: • **INIT**: To be used for (explicitly or not explicitly) initialized variables. • **CLEARED**: To be used for not explicitly initialized variables. • **POWER-ON-CLEARED**: To be used for variables that are not explicitly initialized (cleared) during normal start-up. Instead these are cleared only after power on reset. Please note that the values are defined similar to the representation of enumeration types in the XML schema to ensure backward compatibility. **Tags:** xml.xsd.customType=SECTION-INITIALIZATION-POLICY-TYPE xml.xsd.type=NMTOKEN

Table 8.6: SectionInitializationPolicyType

Enumeration	**MemorySectionType**
Note	Enumeration to specify the essential nature of the data which can be allocated in a common memory class by the means of the AUTOSAR Memory Mapping.
Aggregated by	SwAddrMethod.sectionType
Literal	***Description***
calibrationVariables	This memory section is reserved for "virtual variables" that are computed by an MCD system during a measurement session but do not exist in the ECU memory. **Tags:** atp.EnumerationLiteralIndex=2
calprm	To be used for calibratable constants of ECU-functions. **Tags:** atp.EnumerationLiteralIndex=3
code	To be used for mapping code to application block, boot block, external flash etc. **Tags:** atp.EnumerationLiteralIndex=4
configData	Constants with attributes that show that they reside in one segment for module configuration. **Tags:** atp.EnumerationLiteralIndex=5
const	To be used for global or static constants. **Tags:** atp.EnumerationLiteralIndex=6
excludeFromFlash	This memory section is reserved for "virtual parameters" that are taken for computing the values of so-called dependent parameter of an MCD system. Dependent Parameters that are not at the same time "virtual parameters" are allocated in the ECU memory. Virtual parameters, on the other hand, are not allocated in the ECU memory. Virtual parameters exist in the ECU Hex file for the purpose of being considered (for computing the values of dependent parameters) during an offline-calibration session. **Tags:** atp.EnumerationLiteralIndex=7
var	To be used for global or static variables. The expected initialization is specified with the attribute sectionInitializationPolicy. **Tags:** atp.EnumerationLiteralIndex=9

Table 8.7: MemorySectionType

Class	**SectionNamePrefix**			
Note	A prefix to be used for generated code artifacts defining a memory section name in the source code of the using module or SWC.			
Base	*ARObject*, *ImplementationProps*, *Referrable*			
Aggregated by	ResourceConsumption.sectionNamePrefix			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
implementedIn	DependencyOnArtifact	0..1	ref	Optional reference that allows to Indicate the code artifact (header file) containing the preprocessor implementation of memory sections with this prefix. The usage of this link supersedes the usage of a memory mapping header with the default name (derived from the BswModuleDescription's shortName). **Tags:** atp.Splitkey=implementedIn

Table 8.8: SectionNamePrefix

[constr_4028] Semantics of memory section type

Imposition time: IT_BswMD

⌈sectionType shall be semantically compatible to the usage of the enclosing SwAddrMethod, this means especially that if SwAddrMethod is associated by ExecutableEntity-s, the sectionType shall be usable as code section, if it is associated by SwDataDefProps, sectionType shall be usable as data section.⌋

In case sectionType has the value userDefined, additional documentation is needed to support the integrator in selecting the proper memory segment from the ECU.

[constr_4054] Unambiguous links to addressing method

Imposition time: IT_BswMD

⌈MemorySection.executableEntity shall not be defined, if MemorySection.swAddrMethod represents a data section. MemorySection.executableEntity shall not refer to an ExecutableEntity which is linked to a different SwAddrMethod than MemorySection.swAddrMethod.⌋

[TPS_BSWMDT_04049] Usage of MemorySection.executableEntity ⌈It is in general not mandatory to define the relation MemorySection.executableEntity for code sections because this relationship might be sufficiently determined via the SwAddrMethod referred by both MemorySection and ExecutableEntity. However, if explicit name spaces are defined using the MemorySection.prefix attribute and if MemorySection.sectionType defines a code section, it is mandatory to assign all ExecutableEntity-s running in this section explicitly via MemorySection.executableEntity. Note that this is not a constraint that can be checked on ARXML level.⌋

8.4 Dynamic Memory Needs

8.4.1 General

The dynamic memory is mainly divided into two categories, the stack and the heap. While the stack is almost always used in embedded software, the heap is avoided as much as possible due to the complexity of its implementation, and fragmentation issues. The dynamic memory consumption of software has a much different quality than the static memory consumption. The amount of the static memory consumption can be retrieved from the compiler and is only dependent on the compiler and processor used as well as on the number of instances.

Dynamic memory consumption is heavily dependent on the actual code being executed which is dependent on the state of the software and the parameters. With the introduction of recursive concepts the uncertainty is even higher. Therefore the approach for dynamic memory consumption is far more related to the description of the execution time introduced in chapter 8.5.

8.4.2 Stack

The stack is an area in memory that is used to store temporary information like parameters and local variables of function calls. Therefore the stack usage is highly dependent on the calling hierarchy and the nesting level of function calls. The stack is organized in

a LIFO (last in first out) manner. So each time a function is called the necessary stack memory is occupied. After leaving the function also the associated memory area is freed again and can be used for the next function call. Among tasks, that do not interrupt each other, fragmentation is not a problem for a stack. Only the available amount of stack memory is relevant from the software point of view. However, there can be several stacks in a concurrent task environment. Note that it is not in the scope of a module or component to define the number of stacks, only the amount of used stack memory can be given.

Different mechanisms can be used to describe the stack memory needs of software. Needed stack size can either be *calculated*, *measured* or *estimated*. This is shown in Figure 8.3.

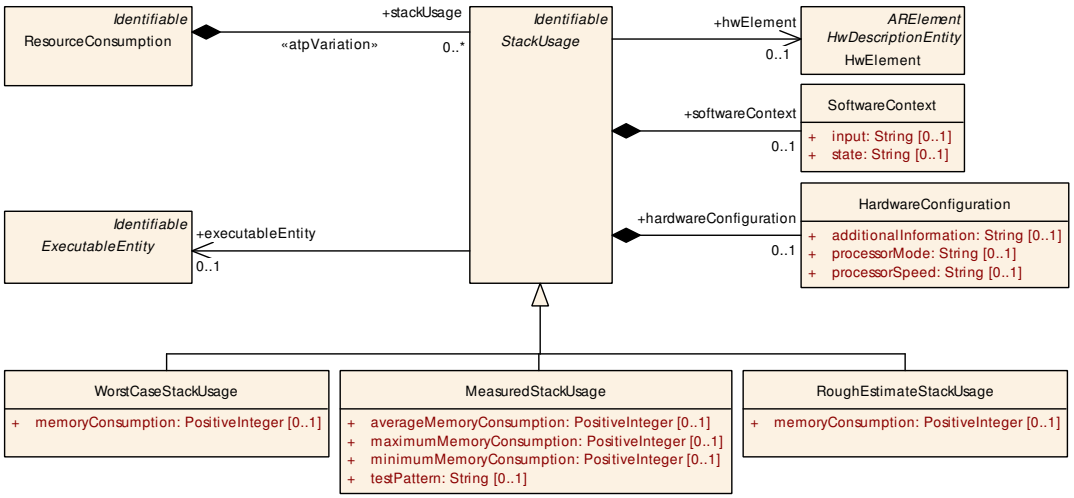

Figure 8.3: Stack Memory Consumption

The given stack memory consumption is dependent on the ECU, the software context and maybe also on the hardware configuration. The software context and the hardware configuration describe the state of the software and hardware under which the given stack usage was gathered. So for each given stack memory consumption these environmental descriptions have to be provided.

Class	***StackUsage*** (abstract)			
Note	Describes the stack memory usage of a software.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	MeasuredStackUsage, RoughEstimateStackUsage, WorstCaseStackUsage			
Aggregated by	ResourceConsumption.stackUsage			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
executableEntity	ExecutableEntity	0..1	ref	The executable entity for which this stack usage is described. **Tags:** atp.Splitkey=executableEntity
hardware Configuration	HardwareConfiguration	0..1	aggr	Contains information about the hardware context this stack usage is describing. **Tags:** atp.Splitkey=hardwareConfiguration

△

Class	***StackUsage*** (abstract)			
hwElement	HwElement	0..1	ref	Specifies for which hardware element (e.g. ECU) this stack usage is given. **Tags:** atp.Splitkey=hwElement
softwareContext	SoftwareContext	0..1	aggr	Contains details about the software context this stack usage is provided for. **Tags:** atp.Splitkey=softwareContext

Table 8.9: StackUsage

Class	**WorstCaseStackUsage**			
Note	Provides a formal worst case stack usage.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *StackUsage*			
Aggregated by	ResourceConsumption.stackUsage			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
memory Consumption	PositiveInteger	0..1	attr	Worst case stack consumption. Unit: byte.

Table 8.10: WorstCaseStackUsage

[constr_10305] Existence of attribute WorstCaseStackUsage.memoryConsumption

Imposition time: IT_BswMD

⌈For each WorstCaseStackUsage, the attribute memoryConsumption shall exist.⌋

Class	**MeasuredStackUsage**			
Note	The stack usage has been measured.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *StackUsage*			
Aggregated by	ResourceConsumption.stackUsage			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
averageMemory Consumption	PositiveInteger	0..1	attr	The average stack usage measured. Unit: byte.
maximum Memory Consumption	PositiveInteger	0..1	attr	The maximum stack usage measured. Unit: byte.
minimum Memory Consumption	PositiveInteger	0..1	attr	The minimum stack usage measured. Unit: byte.
testPattern	String	0..1	attr	Description of the test pattern used to acquire the measured values.

Table 8.11: MeasuredStackUsage

[constr_10306] Existence of attribute MeasuredStackUsage.averageMemoryConsumption

Imposition time: IT_BswMD

⌈For each MeasuredStackUsage, the attribute averageMemoryConsumption shall exist.⌋

[constr_10307] Existence of attribute `MeasuredStackUsage.maximumMemoryConsumption`

Imposition time: `IT_BswMD`

⌈For each `MeasuredStackUsage`, the attribute `maximumMemoryConsumption` shall exist.⌋

[constr_4029] Measured stack usage

Imposition time: `IT_BswMD`

⌈The attribute values of `MeasuredStackUsage` shall fulfill:
`minimumMemoryConsumption` <= `averageMemoryConsumption` <= `maximumMemoryConsumption`⌋

Class	**RoughEstimateStackUsage**			
Note	Rough estimation of the stack usage.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *StackUsage*			
Aggregated by	ResourceConsumption.stackUsage			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
memory Consumption	PositiveInteger	0..1	attr	Rough estimate of the stack usage. Unit: byte.

Table 8.12: RoughEstimateStackUsage

[constr_10308] Existence of attribute `RoughEstimateStackUsage.memoryConsumption`

Imposition time: `IT_BswMD`

⌈For each `RoughEstimateStackUsage`, the attribute `memoryConsumption` shall exist.⌋

8.4.3 Heap

Heap is the memory segment that is used to cover dynamic memory needs with explicit memory allocation and de-allocation. Since the allocation of the memory is controlled by the application program it also survives changes in the context of invocation from entering a function nesting level and leaving it again. So a memory block allocated in the subroutine can be used in the calling routine after the subroutine has returned. Also the allocated memory can be freed again in a different context.

Because of the independence of the heap consumption from processes and tasks only the whole software component or BSW Module heap consumption is provided in the description. The meta-model is shown in Figure 8.4.

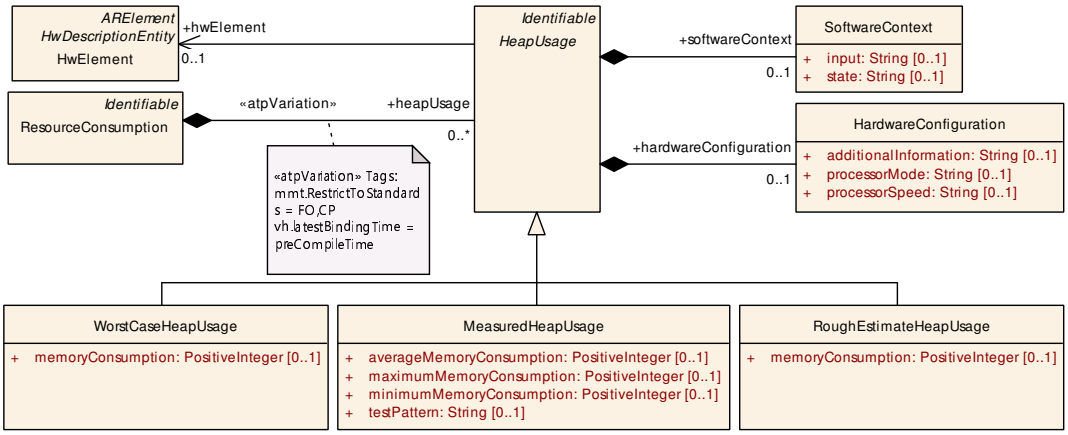

Figure 8.4: Heap Memory Consumption

The heap memory consumption also depends on the ECU, the software context and the hardware configuration.

Due to the highly dynamic nature of heap memory one problem is the fragmentation of the available memory area. So in some cases there can be not enough memory allocated, even though the total amount of free heap memory is big enough, because the available memory space is not available contiguously.

Class	***HeapUsage*** (abstract)			
Note	Describes the heap memory usage of a SW-Component.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	MeasuredHeapUsage, RoughEstimateHeapUsage, WorstCaseHeapUsage			
Aggregated by	ResourceConsumption.heapUsage			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
hardware Configuration	HardwareConfiguration	0..1	aggr	Contains information about the hardware context this heap usage is describing. **Tags:** atp.Splitkey=hardwareConfiguration This Attribute is only used by the AUTOSAR Classic Platform.
hwElement	HwElement	0..1	ref	Specifies for which hardware element (e.g. ECU) this heap usage usage is given. **Tags:** atp.Splitkey=hwElement This Attribute is only used by the AUTOSAR Classic Platform.
softwareContext	SoftwareContext	0..1	aggr	Contains details about the software context this heap usage is provided for. **Tags:** atp.Splitkey=softwareContext This Attribute is only used by the AUTOSAR Classic Platform.

Table 8.13: HeapUsage

Class	WorstCaseHeapUsage			
Note	Provides a formal worst case heap usage.			
Base	*ARObject*, *HeapUsage*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.heapUsage			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
memory Consumption	PositiveInteger	0..1	attr	Worst case heap consumption. Unit: byte.

Table 8.14: WorstCaseHeapUsage

[constr_10309] Existence of attribute WorstCaseHeapUsage.memoryConsumption

Imposition time: IT_BswMD

⌈For each WorstCaseHeapUsage, the attribute memoryConsumption shall exist.⌋

Class	MeasuredHeapUsage			
Note	The heap usage has been measured.			
Base	*ARObject*, *HeapUsage*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.heapUsage			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
averageMemory Consumption	PositiveInteger	0..1	attr	The average heap usage measured. Unit: byte.
maximum Memory Consumption	PositiveInteger	0..1	attr	The maximum heap usage measured. Unit: byte.
minimum Memory Consumption	PositiveInteger	0..1	attr	The minimum heap usage measured. Unit: byte.
testPattern	String	0..1	attr	Description of the test pattern used to acquire the measured values.

Table 8.15: MeasuredHeapUsage

[constr_10310] Existence of attribute MeasuredHeapUsage.averageMemoryConsumption

Imposition time: IT_BswMD

⌈For each MeasuredHeapUsage, the attribute averageMemoryConsumption shall exist.⌋

[constr_10311] Existence of attribute MeasuredHeapUsage.maximumMemoryConsumption

Imposition time: IT_BswMD

⌈For each MeasuredHeapUsage, the attribute maximumMemoryConsumption shall exist.⌋

[constr_4030] Measured heap usage

Imposition time: IT_BswMD

⌈The attribute values of MeasuredHeapUsage shall fulfill: minimumMemoryConsumption <= averageMemoryConsumption <= maximumMemoryConsumption⌋

Class	**RoughEstimateHeapUsage**			
Note	Rough estimation of the heap usage.			
Base	*ARObject*, *HeapUsage*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.heapUsage			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
memory Consumption	PositiveInteger	0..1	attr	Rough estimate of the heap usage. Unit: byte.

Table 8.16: RoughEstimateHeapUsage

[constr_10312] Existence of attribute RoughEstimateHeapUsage.memoryConsumption

Imposition time: IT_BswMD

⌈For each RoughEstimateHeapUsage, the attribute memoryConsumption shall exist.⌋

8.5 Execution Time

8.5.1 General

This subsection defines a model to describe the ExecutionTime of a specific ExecutableEntity of a specific Implementation.

Chapter 8.5.3 describes the goals and scope of the ExecutionTime description proposed.

Chapter 8.5.4 lists all the thoughts and observations that lead to the actual model which is described in chapter 8.5.5.

8.5.2 Preliminaries

This subsection assumes that the reader is familiar with the definition of the following terminology (please see the AUTOSAR Glossary [4] for details):

- task
- thread
- process
- executable entity

- (worst case) execution time
- (worst case) response time

8.5.3 Scope

8.5.3.1 Assertions Versus Requirements

The ExecutionTime is an ASSERTION: a statement about the duration of the execution of a piece of code in a given situation. The execution time is NOT a REQUIREMENT on the software, on the hardware or on the scheduling policy.

8.5.3.2 In Scope

This section proposes a description of the ExecutionTime of an ExecutableEntity of an Implementation. Very roughly, this description includes:

- the nominal execution time (“0.000137 s”) or a range of times
- a description of the entire context in which the execution time measurement or analysis has been made
- some indication of the quality of this measurement or estimation

The goal is to find a good compromise between flexibility and precision. The description has to be flexible enough so that the entire range between analytic results (“worst-case execution time”) and rough estimates can be described. The description should be precise enough so that it is entirely clear what the relevance or meaning of the stated execution time is. This implies that a large amount of context information needs to be provided. The following sections analyze what this context is and provide an appropriate structure for this information.

8.5.3.3 Out of Scope

It is however not in the scope of this section to specify how the execution time of a runnable entity can be or should be measured or analyzed. We will not discuss what tools or techniques can be used to find the execution time or worst-case execution time of a piece of software.

It also is not in the scope of this section to define how information about execution times is used when integrating various software onto one ECU. Similarly this section does not deal with the response time of the system to certain events. The response time does not only depend on the execution times of the involved software but also on the infrastructure overhead and on the scheduling policies which are used.

The focus also is on the description of the execution time of assembly instructions (typically generated out of compiled C or C++ code). The execution time of e.g. Java byte-code on a virtual machine has not been explicitly considered.

8.5.4 Background

This section provides some background to the proposed solution. Readers who want to skip to the result should go to chapter 8.5.5. The execution time can be described for a specific sequence of assembly instructions. It does not make sense to describe the execution time of a runnable provided as source-code unless a precise compiler (and compiler options) are also provided so that a unique set of assembly instructions can be generated out of the source-code. In addition, the execution time of such a sequence of assembly instructions depends on:

1. the hardware-platform
2. the hardware state
3. the logical (software) context
4. execution time of external pieces of code called from the software

These dependencies are discussed in detail in the following sections.

8.5.4.1 Dependency of the Execution Time on Hardware

The execution time depends both on the CPU-hardware and on certain parts of the peripheral hardware:

- The execution time depends on a complete description of the processor, including:
  - kind of processor (e.g. “PPC603”)
  - the internal Processor frequency (“100 MHz”)
  - amount of processor cache
  - configuration of CPU (e.g. power-mode)
- Aspects of the periphery that need to be described include:
  - external bus-speed
  - MMU (memory management unit)
  - configuration of the MMU (data-cache, code-cache, write-back,...)
  - external cache
  - memory (kind of RAM, RAM speed)

In addition, when other devices (I/O) are eventually accessed *as memory* by the I/O Hardware Abstraction, the speed of those devices potentially has a large influence on the execution time of software.

On top of this, the ECU might provide several ways to store the code and data that needs to be executed. This might also have a large influence on the execution time. For example:

- execution of assembly instructions stored in RAM versus execution out of ROM might have very different execution times
- when caching is present, the relative physical location of data accessed in memory might also influence the execution time

8.5.4.2 Dependency on Hardware State

In addition to the static configuration of the hardware and location of the code and data on this hardware, the dynamically changing state of the hardware might have a large influence on the execution time of a piece of code: some examples of this hardware state are:

- which parts of the code are available in the execution cache and what parts will need to be read from external RAM
- what part of the data is stored in data cache versus has to be fetched from RAM
- potentially, the state of the processor pipeline

Although this influence is not relevant on simple or deterministic processors (without cache), the influence of the cache state on modern processors can be enormous (an order of magnitude difference is not impossible). Despite the potential importance of this initial hardware-state when caching is present, it is almost impossible and definitely impractical to describe this hardware state. Therefore it is important and clear that we will not provide explicit attributes for this purpose.

8.5.4.3 Dependency on Logical Context

This logical context includes:

1. the input parameters with which the runnable is called
2. also the logical “state” of the component to which the runnable belongs (or more precisely: the contents of all the memory that is used by the runnable)

While a description of the input-parameters is relatively straight-forward to specify, it might be very hard to describe the entire logical state that the software depends on.

In addition, in certain cases, one wants to provide a specific (e.g. measured or simulated) execution time for a very specific logical context; whereas in other cases, one

wants to describe a *worst-case execution time* over all valid logical contexts or over a subset of logical contexts.

8.5.4.4 Dependency on External Code

Things get very complex when the piece of code whose execution time is described makes calls into ("jumps into") external libraries. To deal with this problem, we could take one of the following approaches:

1. Do not support this case at all: only code that does not rely on external libraries can be given an execution time
2. Support a description of the execution time for a very specific version (again at object-code level) of the libraries. The exact versions of external libraries used would be described together with the execution time. In addition, the relative location in memory of the runnable and the library, the HW-state with respect to the library (e.g. whether this code is in cache or not) and the logical state of the library might have an influence.
3. Conceptually, it might be possible to support a description of the software which explicitly describes the dependency on the execution times of the library. This description would include:
   (a) the execution time of the code provided by the software itself
   (b) a specification of which external library-calls are made (with what parameters, how often, in what order, etc.)

Option 3 is deemed unrealistic and impractical and is not supported. Option 2 however is important as many software might depend on very simple but very common external libraries (like a math-library that provides floating-point capability in software). Option 2 will therefore be supported for the case that the external library does not have an additional logical context which influences its execution time.

8.5.5 Description-Model for the Execution Time

8.5.5.1 Detailed Structure of an Execution-Time Description

Figure 8.5 shows how the `ExecutionTime` is part of the overall description of the `Implementation` and how it relates to various other model elements.

[TPS_BSWMDT_04050] **`ExecutionTime`** ⌈To each `ExecutableEntity` (of a specific `Implementation`) an arbitrary number of `ExecutionTime` descriptions can be related. Thereby this `ExecutionTime` description may also depend on code or data variant of the `Implementation`.⌋

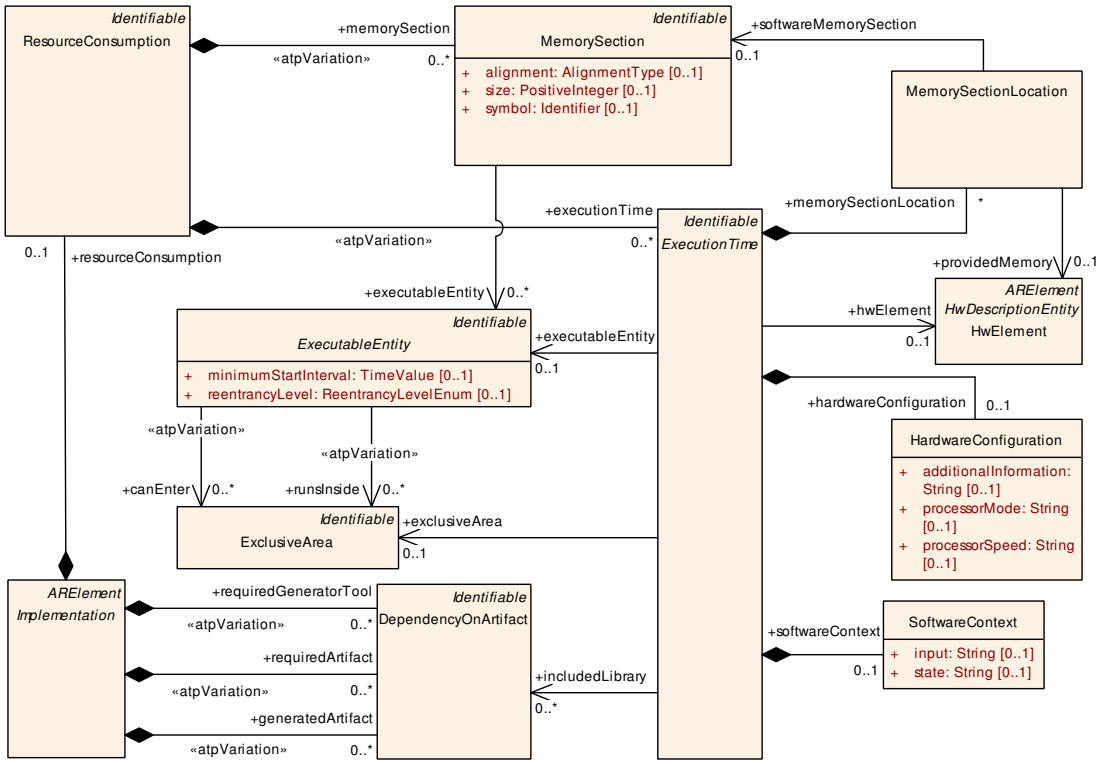

Figure 8.5: Detailed relations of an `ExecutionTime` description

It is expected that many `ExecutableEntity`-s will not have an associated `ExecutionTime` description. For `ExecutableEntity`-s that do have `ExecutionTime` descriptions, the software-implementor can provide several such descriptions with different scope: For example one per specific ECU on which the `Implementation` can run and on which the time was measured or estimated. Furthermore, even in a given ECU context it is possible to specify several different types of execution times, as will be explained below.

If an `ExecutableEntity` is defined to be running completely in an `ExclusiveArea` the related `ExecutionTime` can be considered as a constraint for configuring the data consistency mechanism in the RTE.

If an `ExecutableEntity` is defined to be able to enter an `ExclusiveArea` the `ExecutionTime` can be specified for each area. The time provided is the time consumed AFTER the call to enter the `ExclusiveArea` and BEFORE the call to leave the `ExclusiveArea`.

Figure 8.6 shows the various sub-classes of `ExecutionTime`. The following paragraphs describe the aspects of this model in more detail. For the definition of class `TimeValue` refer to the timing specification ([17]).

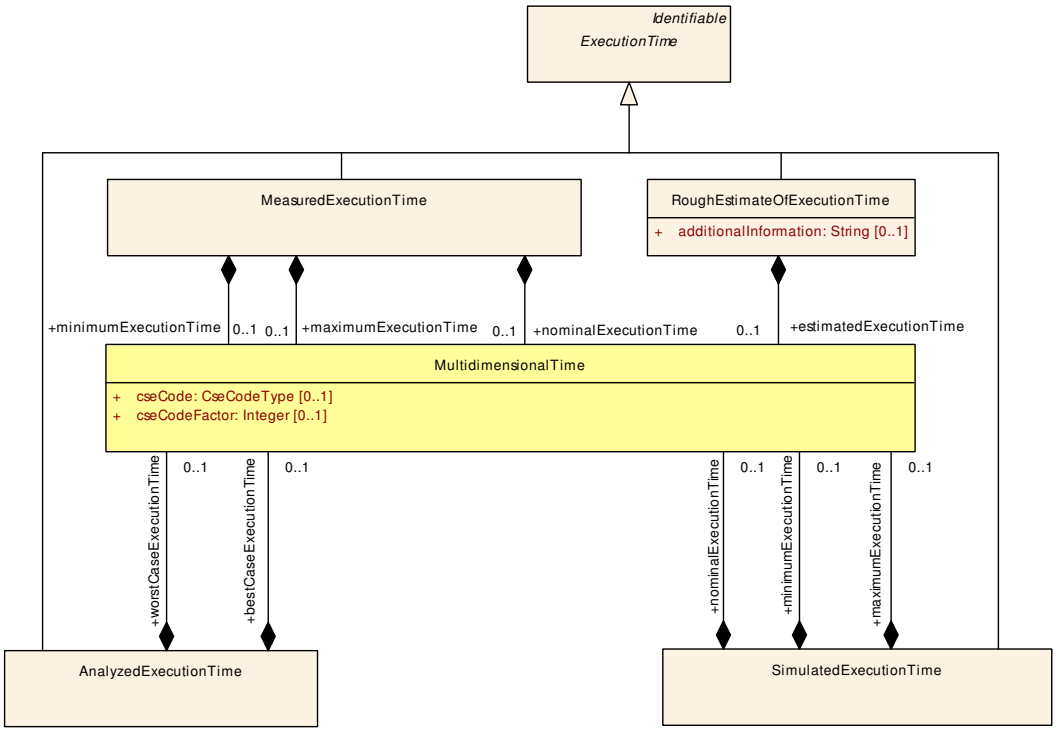

Figure 8.6: Sub-classes of `ExecutionTime` and their usage of `TimeValue`

The following shows the attributes of the `ExecutionTime` in tabular form:

Class	***ExecutionTime*** (abstract)			
Note	Base class for several means how to describe the ExecutionTime of software. The required context information is provided through this class.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	AnalyzedExecutionTime, MeasuredExecutionTime, RoughEstimateOfExecutionTime, Simulated ExecutionTime			
Aggregated by	ResourceConsumption.executionTime			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
exclusiveArea	ExclusiveArea	0..1	ref	Reference to the ExclusiveArea this execution time is provided for. **Tags:** atp.Splitkey=exclusiveArea
executableEntity	ExecutableEntity	0..1	ref	The executable entity for which this execution time is described. **Tags:** atp.Splitkey=executableEntity
hardware Configuration	HardwareConfiguration	0..1	aggr	Provides information on the HardwareConfiguration used to specify this ExecutionTime. **Tags:** atp.Splitkey=hardwareConfiguration
hwElement	HwElement	0..1	ref	The hardware element (e.g. type of ECU) for which the execution time is specified. **Tags:** atp.Splitkey=hwElement
includedLibrary	DependencyOnArtifact	*	ref	If this dependency is specified, the execution time of the library code is included in the execution time data for the runnable. **Tags:** atp.Splitkey=includedLibrary

△

Class	***ExecutionTime*** (abstract)			
memorySection Location	MemorySectionLocation	*	aggr	Provides information on the MemorySectionLocation which is involved in the ExecutionTime description. **Tags:** atp.Splitkey=memorySectionLocation
softwareContext	SoftwareContext	0..1	aggr	Provides information on the detailed SoftwareContext used to provide the ExecutionTime description. **Tags:** atp.Splitkey=softwareContext

Table 8.17: ExecutionTime

[constr_10313] Existence of attribute `ExecutionTime.hardwareConfiguration`

Imposition time: `IT_BswMD`

⌈For each `ExecutionTime`, the attribute `hardwareConfiguration` shall exist.⌋

[constr_10314] Existence of attribute `ExecutionTime.softwareContext`

Imposition time: `IT_BswMD`

⌈For each `ExecutionTime`, the attribute `softwareContext` shall exist.⌋

8.5.5.2 ExecutionTime References an "ECU"

[TPS_BSWMDT_04051] `ExecutionTime` references an ECU ⌈The `ExecutionTime` references an ECU (the concept ECU is defined by the ECU-Resource-Template [18]) via the attribute `hwElement`. This reference uniquely describes the hardware for which the `ExecutionTime` is provided.⌋

This includes: the kind of processor, the type of MMU, the type of caches, type of memory available and so on.

8.5.5.3 ExecutionTime Includes a HW-Configuration

[TPS_BSWMDT_04052] `ExecutionTime.hardwareConfiguration` ⌈The ECU described through the `hwElement` attribute can still run in several HW-modes. For example, many ECUs can run in several "speed"-modes (for example a normal fast-mode and a low-power slow mode). The goal of the `HardwareConfiguration` is to describe this. The attributes `processorSpeed` and `processorMode` should describe the specific mode of the ECU.

Because of the potential dependency on many other HW-Configuration settings (such as caching policy, MMU-settings, etc.), a generic attribute `additionalInformation` is provided. Because the exact structure of the information seems to depend so much on the specific case, all attributes are unstructured text.⌋

Class	**HardwareConfiguration**			
Note	Describes in which mode the hardware is operating while needing this resource consumption.			
Base	*ARObject*			
Aggregated by	*ExecutionTime*.hardwareConfiguration, *HeapUsage*.hardwareConfiguration, *StackUsage*.hardware Configuration			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
additional Information	String	0..1	attr	Specifies additional information on the Hardware Configuration.
processorMode	String	0..1	attr	Specifies in which mode the processor is operating.
processor Speed	String	0..1	attr	Specifies the speed the processor is operating.

Table 8.18: HardwareConfiguration

[constr_10315] Existence of attribute `HardwareConfiguration.additionalInformation`

Imposition time: `IT_BswMD`

⌈For each `HardwareConfiguration`, the attribute `additionalInformation` shall exist.⌋

[constr_10316] Existence of attribute `HardwareConfiguration.processorMode`

Imposition time: `IT_BswMD`

⌈For each `HardwareConfiguration`, the attribute `processorMode` shall exist.⌋

[constr_10317] Existence of attribute `HardwareConfiguration.processorSpeed`

Imposition time: `IT_BswMD`

⌈For each `HardwareConfiguration`, the attribute `processorSpeed` shall exist.⌋

8.5.5.4 ExecutionTime Includes a MemorySectionLocation

[TPS_BSWMDT_04053] **`ExecutionTime.memorySectionLocation`** ⌈For each `memorySection` of the `Implementation`, the `ExecutionTime` shall specify where this section was located on the physical memory of the ECU. The `memorySection`s of the software are described in the `resourceConsumption` of the `Implementation`. The available memory-regions on the hardware are described inside the description of the ECU. The `ExecutionTime` contains descriptions of the location of the memory sections `MemorySectionLocation` which link a software memory section to a hardware memory section on the ECU.⌋

Class	MemorySectionLocation			
Note	Specifies in which hardware ProvidedMemorySegment the softwareMemorySection is located.			
Base	*ARObject*			
Aggregated by	*ExecutionTime*.memorySectionLocation			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
provided Memory	HwElement	0..1	ref	Reference to the hardware ProvidedMemorySegment. **Tags:** atp.Splitkey=providedMemory
software MemorySection	MemorySection	0..1	ref	Reference to the MemorySection which is mapped on a certain hardware memory segment. **Tags:** atp.Splitkey=softwareMemorySection

Table 8.19: MemorySectionLocation

[constr_10318] Existence of reference `MemorySectionLocation.providedMemory`

Imposition time: `IT_BswMD`

⌈For each `MemorySectionLocation`, the reference in the role `providedMemory` shall exist.⌋

[constr_10319] Existence of reference `MemorySectionLocation.softwareMemorySection`

Imposition time: `IT_BswMD`

⌈For each `MemorySectionLocation`, the reference in the role `softwareMemorySection` shall exist.⌋

8.5.5.5 ExecutionTime Includes a SoftwareContext

[TPS_BSWMDT_04054] **`ExecutionTime.softwareContext`** ⌈The `SoftwareContext` is the logical context for which the `ExecutionTime` is given. This includes two aspects:

1. the values of the input-parameters to the software
2. the state the logic of the runnable depends on

In the current form, both attributes are of type `String` and can contain free-form text describing this state.⌋

For the attribute `input`, it might be appropriate to refine this into a more formal description of the values of the parameters. For the attribute `state`, it is difficult to go beyond an informal text-field, because the state is a private matter of the component and there currently is no explicit mechanism in AUTOSAR to describe the value of this state.

Further, it is possible to provide several execution times of a runnable entity, for example, in case of different values of the input-parameters. This is one of the reasons why the template supports an arbitrary number of `ExecutionTime`s.

Class	**SoftwareContext**			
Note	Specifies the context of the software for this resource consumption.			
Base	*ARObject*			
Aggregated by	*ExecutionTime*.softwareContext, *HeapUsage*.softwareContext, *StackUsage*.softwareContext			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
input	String	0..1	attr	Specifies the input vector which is used to provide the ExecutionTime.
state	String	0..1	attr	Specifies the state the software is in when the Execution Time is provided.

Table 8.20: SoftwareContext

[constr_10320] Existence of attribute `SoftwareContext.input`

Imposition time: `IT_BswMD`

⌈For each `SoftwareContext`, the attribute `input` shall exist.⌋

[constr_10321] Existence of attribute `SoftwareContext.state`

Imposition time: `IT_BswMD`

⌈For each `SoftwareContext`, the attribute `state` shall exist.⌋

8.5.5.6 Dependency on External Libraries

[TPS_BSWMDT_04055] **`ExecutionTime.includedLibrary`** ⌈The `ExecutionTime` measurements can depend on the precise version of external libraries (such as a math-emulation library) that have been used. This information can be included by adding a reference to an object of type `DependencyOnArtifact` which shall be aggregated by the corresponding `Implementation`.

If such a reference is specified, the `ExecutionTime` includes the execution time of that specific library version.

In case the `Implementation` aggregates attributes of type `DependencyOnArtifact`, to which the `ExecutionTime` does not refer, it means that the execution time of the library code is NOT included in the execution time of the `ExecutableEntity`.⌋

8.5.5.7 Several Qualities of Execution Times

8.5.5.7.1 AnalyzedExecutionTime

The `AnalyzedExecutionTime` means that an “analytic” method was used to find guaranteed boundaries. These boundaries have a lower-limit (best case) and an upper-limit (worst case).

Considering the cache processor ECU, an execution time could be computed, and it depends on cache level. A bestCaseExecutionTime and a bestCaseExecutionTime have to be filled.

Class	**AnalyzedExecutionTime**			
Note	AnalyzedExecutionTime provides an analytic method for specifying the best and worst case execution time.			
Base	*ARObject*, *ExecutionTime*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.executionTime			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bestCase ExecutionTime	MultidimensionalTime	0..1	aggr	The best case execution time (BCET) defines the minimum amount of time the related executable entity requires for its execution. **Tags:** atp.Splitkey=bestCaseExecutionTime
worstCase ExecutionTime	MultidimensionalTime	0..1	aggr	The worst case execution time (WCET) defines the maximum amount of time the related executable entity requires for its execution. **Tags:** atp.Splitkey=worstCaseExecutionTime

Table 8.21: AnalyzedExecutionTime

[constr_10323] Existence of attribute AnalyzedExecutionTime.bestCaseExecutionTime

Imposition time: IT_BswMD

⌈For each AnalyzedExecutionTime, the attribute bestCaseExecutionTime shall exist.⌋

[constr_10324] Existence of attribute AnalyzedExecutionTime.worstCaseExecutionTime

Imposition time: IT_BswMD

⌈For each AnalyzedExecutionTime, the attribute worstCaseExecutionTime shall exist.⌋

[constr_4031] Analyzed execution time

Imposition time: IT_BswMD

⌈The attribute values of AnalyzedExecutionTime shall fulfill:
bestCaseExecutionTime <= bestCaseExecutionTime⌋

Class	MultidimensionalTime			
Note	Specifies a time value based on [19] see [TPS_GST_00354].			
Base	*ARObject*			
Aggregated by	AgeConstraint.maximum, AgeConstraint.minimum, AnalyzedExecutionTime.bestCaseExecutionTime, AnalyzedExecutionTime.worstCaseExecutionTime, ArbitraryEventTriggering.maximumDistance, ArbitraryEventTriggering.minimumDistance, BurstPatternEventTriggering.minimumInterArrivalTime, BurstPatternEventTriggering.patternJitter, BurstPatternEventTriggering.patternLength, BurstPatternEventTriggering.patternPeriod, ConcretePatternEventTriggering.offset, ConcretePatternEventTriggering.patternJitter, ConcretePatternEventTriggering.patternLength, ConcretePatternEventTriggering.patternPeriod, ConfidenceInterval.lowerBound, ConfidenceInterval.upperBound, ExecutionTimeConstraint.maximum, ExecutionTimeConstraint.minimum, IoHwAbstractionServerAnnotation.age, LatencyTimingConstraint.maximum, LatencyTimingConstraint.minimum, LatencyTimingConstraint.nominal, MeasuredExecutionTime.maximumExecutionTime, MeasuredExecutionTime.minimumExecutionTime, MeasuredExecutionTime.nominalExecutionTime, OffsetTimingConstraint.maximum, OffsetTimingConstraint.minimum, PeriodicEventTriggering.jitter, PeriodicEventTriggering.minimumInterArrivalTime, PeriodicEventTriggering.period, ReceiverAnnotation.signalAge, RoughEstimateOfExecutionTime.estimatedExecutionTime, SimulatedExecutionTime.maximumExecutionTime, SimulatedExecutionTime.minimumExecutionTime, SimulatedExecutionTime.nominalExecutionTime, SporadicEventTriggering.jitter, SporadicEventTriggering.maximumInterArrivalTime, SporadicEventTriggering.minimumInterArrivalTime, SporadicEventTriggering.period, SwDataDefProps.swRefreshTiming, SynchronizationTimingConstraint.tolerance, TDLETZoneClock.accuracyExt, TDLETZoneClock.accuracyInt, TimingClockSyncAccuracy.accuracy, Trigger.triggerPeriod			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
cseCode	CseCodeType	0..1	attr	Specifies the time base by means of CSE codes.
cseCodeFactor	Integer	0..1	attr	The scaling factor for the time value based on the specified CSE code.

Table 8.22: MultidimensionalTime

[constr_10338] Existence of attribute `MultidimensionalTime.cseCode`

Imposition time: `IT_BswMD`

⌈For each `MultidimensionalTime`, the attribute `cseCode` shall exist.⌋

[constr_10339] Existence of attribute `MultidimensionalTime.cseCodeFactor`

Imposition time: `IT_BswMD`

⌈For each `MultidimensionalTime`, the attribute `cseCodeFactor` shall exist.⌋

8.5.5.7.2 MeasuredExecutionTime

The `MeasuredExecutionTime` describes the `ExecutableEntity` runtime on an ECU.

Class	MeasuredExecutionTime			
Note	Specifies the ExecutionTime which has been gathered using measurement means.			
Base	*ARObject*, *ExecutionTime*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.executionTime			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
maximum ExecutionTime	MultidimensionalTime	0..1	aggr	The maximum measured execution time. **Tags:** atp.Splitkey=maximumExecutionTime

▽

△

Class	**MeasuredExecutionTime**			
minimum ExecutionTime	MultidimensionalTime	0..1	aggr	The minimum measured execution time. **Tags:** atp.Splitkey=minimumExecutionTime
nominal ExecutionTime	MultidimensionalTime	0..1	aggr	The nominal measured execution time. **Tags:** atp.Splitkey=nominalExecutionTime

Table 8.23: MeasuredExecutionTime

[constr_10325] Existence of attribute `MeasuredExecutionTime.maximumExecutionTime`

Imposition time: `IT_BswMD`

⌈For each `MeasuredExecutionTime`, the attribute `maximumExecutionTime` shall exist.⌋

[constr_10326] Existence of attribute `MeasuredExecutionTime.minimumExecutionTime`

Imposition time: `IT_BswMD`

⌈For each `MeasuredExecutionTime`, the attribute `minimumExecutionTime` shall exist.⌋

[constr_10327] Existence of attribute `MeasuredExecutionTime.nominalExecutionTime`

Imposition time: `IT_BswMD`

⌈For each `MeasuredExecutionTime`, the attribute `nominalExecutionTime` shall exist.⌋

[constr_4032] Measured execution time

Imposition time: `IT_BswMD`

⌈The attribute values of `MeasuredExecutionTime` shall fulfill:
`minimumExecutionTime` <= `nominalExecutionTime` <= `maximumExecutionTime`⌋

8.5.5.7.3 SimulatedExecutionTime

A `SimulatedExecutionTime` describes the time information which are coming from a simulation. Simulation could be based on:

- `ExecutableEntity` model on specific hardware with time weighting to simulate processor time behavior
- `ExecutableEntity` model before generation code

Class	**SimulatedExecutionTime**			
Note	Specifies the ExecutionTime which has been gathered using simulation means.			
Base	*ARObject*, *ExecutionTime*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.executionTime			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
maximum ExecutionTime	MultidimensionalTime	0..1	aggr	The maximum simulated execution time. **Tags:** atp.Splitkey=maximumExecutionTime
minimum ExecutionTime	MultidimensionalTime	0..1	aggr	The minimum simulated execution time. **Tags:** atp.Splitkey=minimumExecutionTime
nominal ExecutionTime	MultidimensionalTime	0..1	aggr	The nominal simulated execution time. **Tags:** atp.Splitkey=nominalExecutionTime

Table 8.24: SimulatedExecutionTime

[constr_10331] Existence of attribute `SimulatedExecutionTime.maximumExecutionTime`

Imposition time: `IT_BswMD`

⌈For each `SimulatedExecutionTime`, the attribute `maximumExecutionTime` shall exist.⌋

[constr_10332] Existence of attribute `SimulatedExecutionTime.minimumExecutionTime`

Imposition time: `IT_BswMD`

⌈For each `SimulatedExecutionTime`, the attribute `minimumExecutionTime` shall exist.⌋

[constr_10333] Existence of attribute `SimulatedExecutionTime.nominalExecutionTime`

Imposition time: `IT_BswMD`

⌈For each `SimulatedExecutionTime`, the attribute `nominalExecutionTime` shall exist.⌋

[constr_4033] Simulated execution time

Imposition time: `IT_BswMD`

⌈The attribute values of `SimulatedExecutionTime` shall fulfill:
`minimumExecutionTime` <= `nominalExecutionTime` <= `maximumExecutionTime`⌋

8.5.5.7.4 RoughEstimateOfExecutionTime

A `RoughEstimateOfExecutionTime` describes the time information which are based on some estimation.

Class	**RoughEstimateOfExecutionTime**			
Note	Provides a description of a rough estimate on the ExecutionTime.			
Base	*ARObject*, *ExecutionTime*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ResourceConsumption.executionTime			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
additional Information	String	0..1	attr	Provides description on the rough estimate of the ExecutionTime.
estimated ExecutionTime	MultidimensionalTime	0..1	aggr	The estimated execution time. **Tags:** atp.Splitkey=estimatedExecutionTime

Table 8.25: RoughEstimateOfExecutionTime

[constr_10334] Existence of attribute RoughEstimateOfExecutionTime.additionalInformation

Imposition time: IT_BswMD

⌈For each RoughEstimateOfExecutionTime, the attribute additionalInformation shall exist.⌋

[constr_10335] Existence of attribute RoughEstimateOfExecutionTime.estimatedExecutionTime

Imposition time: IT_BswMD

⌈For each RoughEstimateOfExecutionTime, the attribute estimatedExecutionTime shall exist.⌋

9 Measurement and Calibration Support

9.1 Overview on McSupportData

AUTOSAR allows to declare data for measurement and calibration (MC-data) in the description of software components as a well as for basic software. Software components can declare MC-data which are handled locally, as well as MC-data for which the location and access (during normal execution) is implemented by the RTE, for example data elements in ports, data shared between instances or data requiring software emulation support.

BSW modules usually have only local data, but for software emulation support they also may declare calibration data that are handled by the RTE (see also chapter 5.10 for the various data roles).

For the final configuration of the measurement and calibration tools another representation is needed (so-called “A2L”-file) which is not part of AUTOSAR (see [19]).

For a given RTE generator and ECU configuration, the data description part of the A2L-file could in principle be generated out of the “upstream” AUTOSAR descriptions of all involved components and modules (with additional address information from the linker).

However, instead of this it has been decided for the AUTOSAR methodology to provide an additional intermediate ARXML work product, the so-called MC Support Data which is produced rather late in the ECU configuration process, out of which (with additional address information from the linker) the final A2L-file can be generated.

The reasons for this approach are:

- For the MC data coded by the RTE generator, the actual C-symbols - which are needed to find the memory addresses - depend on the RTE implementation and are not available in the “upstream” descriptions.
- The names used for the data in the BSWM- and SWC-descriptions are not necessarily unique, due to the distributed development in AUTOSAR. In order to define unique names for display in the MC system (and also for other use cases) a so-called ECU Flat Map is provided (see [3] [TR_METH_03008] and [TR_METH_02003] for the method and [6] for the meta-model). These names shall be made available to the MC tools through the MC-support-data.
- The definition of data attributes - namely `SwDataDefProps` - is subject to additions or redefinitions in several artifacts which could be produced in different process steps (for more on this see [5]).

  In many cases this finally has to be evaluated by the RTE generator, therefore it is convenient, that the RTE generator also puts these final decisions on the `SwDataDefProps` into a generated set of MC support data.

- Information on the so-called calibration method has to be provided which is currently only available in the ECU configuration of the RTE.
- By making use of a dedicated support format, an external tool is less dependent on the overall AUTOSAR meta-model.
- By making use of a dedicated support format, it is possible to restrict the information given to the operator of the final A2L generation to what is actually required in this step.

It has further been decided, that the MC support format (i.e. its part of the meta-model) reuses already existing concepts of the meta-model like categories and `SwDataDefProps`, because these concepts are close to the “upstream” descriptions and to “A2L” concepts as well.

The resulting model is shown in an overview in figure 9.1, which illustrates also the placement in the context of an ECU configuration. As the figure shows, the root element of the MC support `McSupportData` is aggregated as `splitable` in an `Implementation`.

This means, that one such element describes the calibration support for all data located in this implementation which could be a BSW module/cluster/library or an SWC as well. The `splitable`-stereotype allows, that the data can be defined as a separate artifact and at another point in time, than the `Implementation` itself.

Especially, the support data for all calibration data located in the RTE shall be generated as part of the RTE’s own `BswImplementation`.

In addition to the support for external MCD-tools, the MC-support-data produced by the RTE generator also can contain information which is needed to support the software emulation of calibration data inside the ECU. This is explained in more detail in chapter 9.3.

Furthermore, the MC-support-data produced by the RTE generator or a proprietary tool can contain information which is needed to support rapid prototyping. This is explained in chapter 9.6.

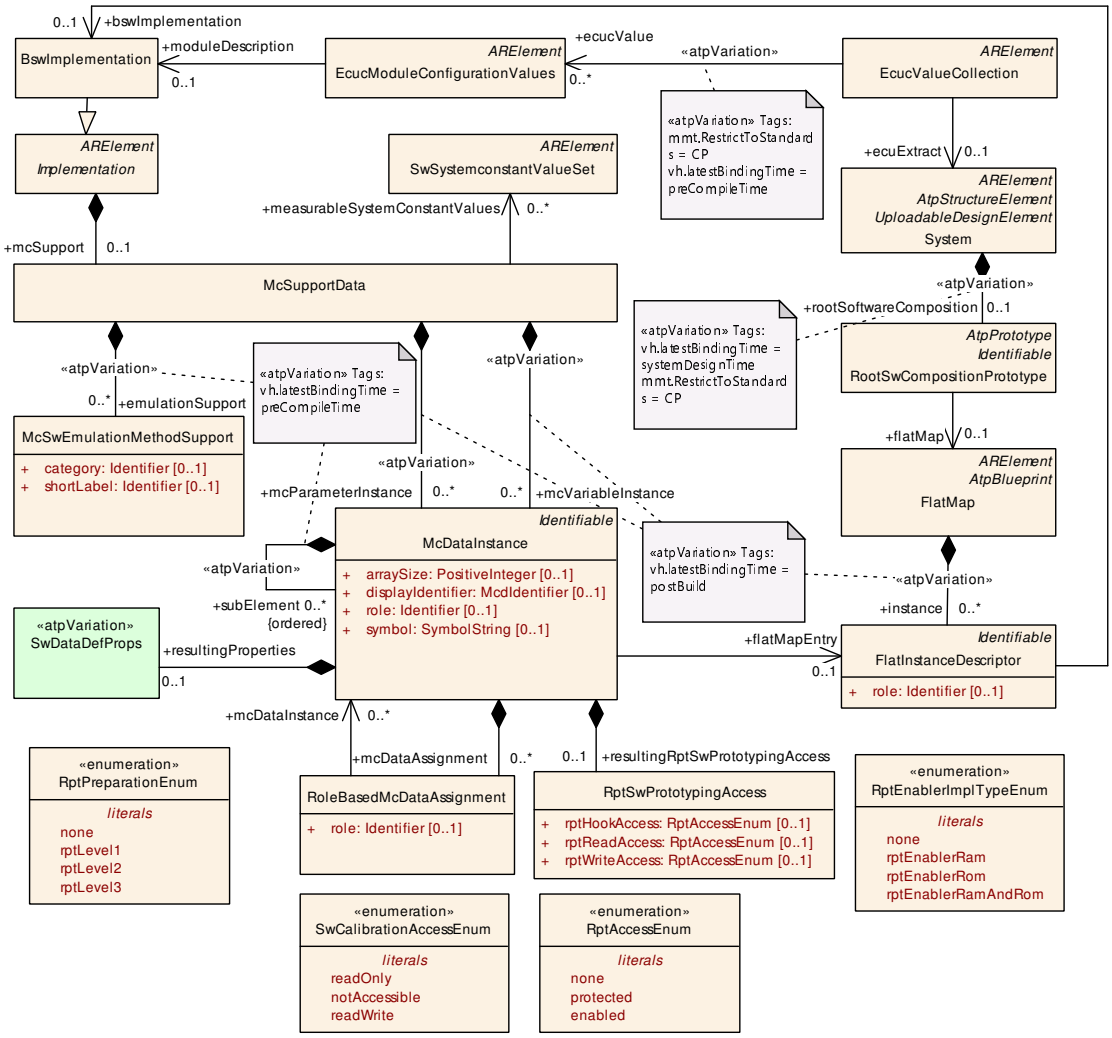

Figure 9.1: Calibration Support Data attached to Implementation

In general, MC support data shall be generated for all data with measurement or calibration access in modules or components. For the methodology, we have to distinguish two cases:

- MC support data is generated by the RTE generator for those data, which are allocated also by the RTE (resp. the BSW Scheduler). For BSW modules, this means that those data need to be declared as `BswInternalBehavior.arTypedPerInstanceMemory`. This is mandatory if calibration data need emulation support - note that for measurement data within basic software there is no use case requiring BSW data allocation by the RTE resp. the BSW Scheduler.
- MC support data are generated by any other tool if the data are allocated by the module or component itself, i.e. for `InternalBehavior.staticMemory` and `InternalBehavior.constantMemory`

Class	**McSupportData**			
Note	Root element for all measurement and calibration support data related to one Implementation artifact on an ECU. There shall be one such element related to the RTE implementation (if it owns MC data) and a separate one for each module or component, which owns private MC data.			
Base	*ARObject*			
Aggregated by	*Implementation*.mcSupport			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
emulation Support	McSwEmulationMethod Support	*	aggr	Describes the calibration method used by the RTE. This information is not needed for A2L generation, but to setup software emulation in the ECU. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=emulationSupport, emulation Support.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
mcParameter Instance	McDataInstance	*	aggr	A data instance to be used for calibration. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=mcParameterInstance, mcParameter Instance.shortName, mcParameterInstance.variation Point.shortLabel vh.latestBindingTime=postBuild
mcVariable Instance	McDataInstance	*	aggr	A data instance to be used for measurement. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=mcVariableInstance, mcVariable Instance.shortName, mcVariableInstance.variation Point.shortLabel vh.latestBindingTime=postBuild
measurable System ConstantValues	SwSystemconstant ValueSet	*	ref	Sets of system constant values to be transferred to the MCD system, because the system constants have been specified with "swCalibrationAccess" = readonly. **Tags:** atp.Splitkey=measurableSystemConstantValues
rptSupportData	RptSupportData	0..1	aggr	The rapid prototyping support data belonging to this implementation. The aggregtion is <<atpSplitable>> because in case of an already exisiting BSW Implementation model, this description will be added later in the process, namely at code generation time. **Tags:** atp.Splitkey=rptSupportData

Table 9.1: McSupportData

[TPS_BSWMDT_04057] Self-contained MC support artifact ⌈It is important to understand, that the M1 model of an `McSupportData` element shall be a self-contained tree of XML elements witch can be given to an external tool without needing all the “upstream” descriptions.

This rule cannot be expressed by the meta-model, it is part of the methodology. This means that all XML elements which are taken over from SWC and BSWM descriptions without change (e.g. data types) still have to be copied into an own artifact. Especially, the links to input variables of axis definitions shall be modified as to point to the corresponding elements within the `McSupportData`.⌋

There are several exceptions from this rule:

- **[TPS_BSWMDT_04174] Association to `FlatMap`** ⌈The association to `FlatMap` shall be handled in a way that it points to the actual ECU Flat Map, in order to provide a backward link to the actual sources of the data for documentation purposes.⌋

- **[TPS_BSWMDT_04175] Support software emulation** ⌈In order to support software emulation of calibration data, a special reference to the description of the actual data in memory is needed. However, this is not relevant for A2L generation.⌋

  For more information see chapter 9.3.

- **[TPS_BSWMDT_04176] Self-contained MC support artifact** ⌈The elements under `McSupportData` can still contain compile-time variation points. These need to be resolved in sync with the variants selected before compilation of the software, so that the generated A2L content corresponds to the actual code.

  Therefore, as long as the variants are not resolved, the variation points in the MC support artifact will depend on the system constants needed to resolve these variants.⌋

  Please refer to figure 9.1.

- **[TPS_BSWMDT_04177] Support of functional modeling** ⌈In order to support the functional modeling of measurement and calibration data, additional artifacts (based on meta-class `McFunction`) are (optionally) needed as input to the A2L generator.⌋

  For more information see chapter 9.4.

- **[TPS_BSWMDT_04178] Support of rapid prototyping** ⌈In order to support particular rapid prototyping solutions, references to the description of communication behavior of the involved software components are required.⌋

  For more information see chapter 9.6.

[TPS_BSWMDT_04058] `McSupportData.measurableSystemConstantValues` ⌈In addition to variables and parameters, also names and values of system constants may need to be transferred to an MCD tool in order to be displayed. These are modeled by the role `McSupportData.measurableSystemConstantValues`. Note that the values of system constants are also possibly subject to compile-time variation (not visible in the figure).⌋

For details on variant handling refer to [1].

The final A2L-generation is not part of AUTOSAR, but in order to get the complete picture, it should be mentioned, that in addition to the MC support data some further information is required (see also [3]):

- Output from the linker to find the actual memory addresses, as the MC support data will only contain the C-symbols. In addition, the actual (physical) memory segments shall be found from the linker output in cases where the address is not global. Note that the abstract sections defined by MemorySection do not deliver this information.
- Driver specific access information (so called IF-DATA sections) needed by the MC system as part of the A2L-file. These are described in a special non-AUTOSAR data format and shall be generated by the driver modules, e.g. XCP.
- Via the AUTOSAR meta-class AliasNameSet (see [6]) one can provide alternative names as identifiers for the A2L data which could be used by the A2L generator to supersede names given by the MC support data. One possible use case is to resolve name conflicts of system constants which may happen if SwSystemconst names are to be copied to the A2L file out of different ARPackages (this kind of name conflict cannot be resolved by a FlatMap).
- Administrative data for the A2L-File which are nor delivered by AUTOSAR.
- It is up to the A2L generator (and possibly project specific configuration) how data types are converted into A2L which are coded as C-enums.[1]

Class	**AliasNameSet**			
Note	This meta-class represents a set of AliasNames. The AliasNameSet can for example be an input to the A2L-Generator. **Tags:** atp.recommendedPackage=AliasNameSets			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
aliasName	AliasNameAssignment	*	aggr	AliasNames contained in the AliasNameSet. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=aliasName, aliasName.shortLabel, aliasName.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

Table 9.2: AliasNameSet

[constr_10362] Existence of attribute AliasNameSet.aliasName

Imposition time: IT_BswMD

⌈For each AliasNameSet, the attribute aliasName shall exist at least once.⌋

[1] This is indicated by the string “enum” as part of the McDataInstance.resultingProperties.additionalNativeTypeQualifier.

Class	**AliasNameAssignment**			
Note	This meta-class represents the ability to associate an alternative name to a flat representations or an Identifiable. The usage of this name is defined outside of AUTOSAR. For example this name can be used by MCD tools or as a name for component instances in the ECU extract. Note that flatInstance and identifiable are mutually exclusive.			
Base	*ARObject*			
Aggregated by	AliasNameSet.aliasName			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
flatInstance	FlatInstanceDescriptor	0..1	ref	Assignment of a unique name to a flat representation. **Tags:** atp.Splitkey=flatInstance xml.sequenceOffset=60 This Attribute is only used by the AUTOSAR Classic Platform.
identifiable	Identifiable	0..1	ref	Assignment of a unique name to an Identifiable. **Tags:** atp.Splitkey=identifiable xml.sequenceOffset=50
label	MultilanguageLongName	0..1	aggr	This represents an "Alias LongName". **Tags:** atp.Splitkey=label xml.sequenceOffset=20
shortLabel	String	0..1	attr	This attribute represents the alias name. It is modeled as string because the alias name is used outside of AUTOSAR and therefore no naming conventions can be applied within AUTOSAR. **Stereotypes:** atpIdentityContributor **Tags:** xml.sequenceOffset=10

Table 9.3: AliasNameAssignment

[constr_10363] Existence of attribute `AliasNameAssignment.shortLabel`

Imposition time: `IT_BswMD`

⌈For each `AliasNameAssignment`, the attribute `shortLabel` shall exist.⌋

9.2 Attributes for McSupportData

Figure 9.2 and the following class tables show the attributes which are to be attached to the `McSupportData` in order to support measurement and calibration by external tools.

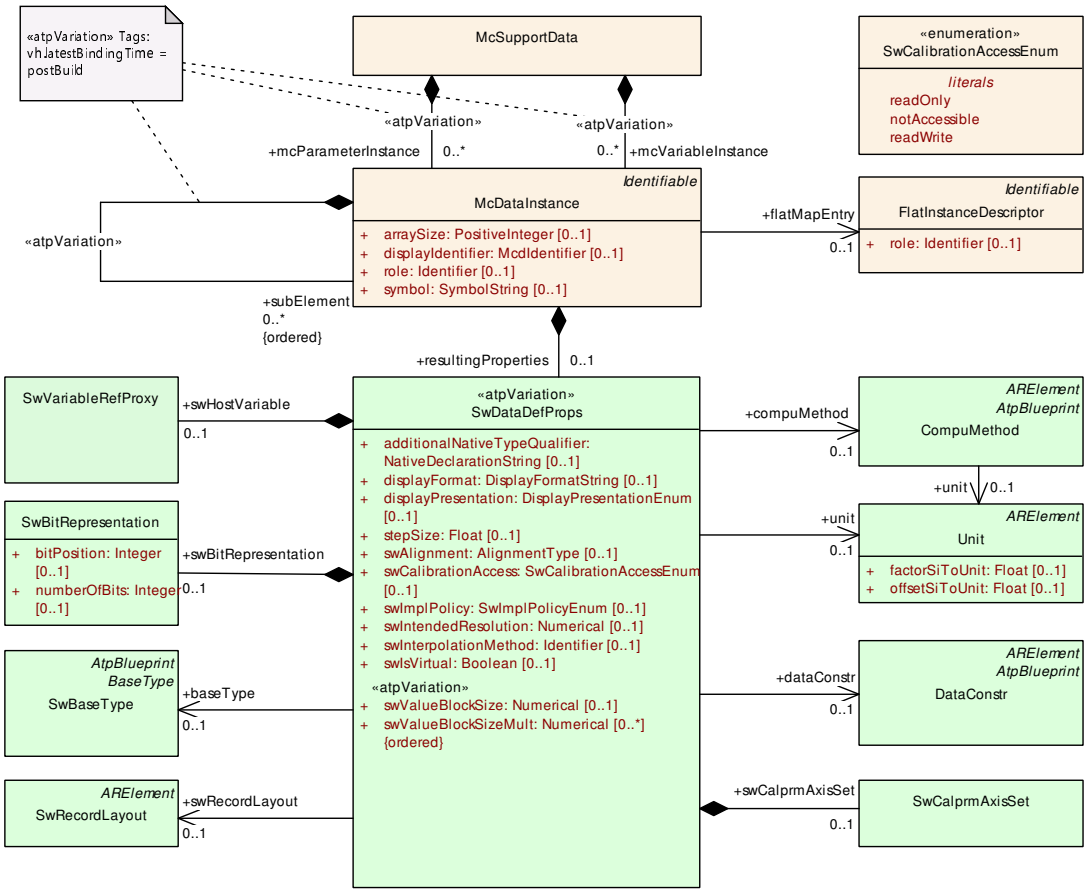

Figure 9.2: Attributes of MC Support Data

Note that `McSupportData` is a list of calibration elements (parameters) and measurement elements (variables) in which the component hierarchy has been removed. All elements of the list are described by meta-class `McDataInstance`. This meta-class allows to define arrays and structures, but is does not need a type-prototype-pattern, because it is not designed for reuse on M1:

Class	**McDataInstance**
Note	Describes the specific properties of one data instance in order to support measurement and/or calibration of this data instance. The most important attributes are: • Its shortName is copied from the ECU Flat map (if applicable) and will be used as identifier and for display by the MC system. • The category is copied from the corresponding data type (ApplicationDataType if defined, otherwise ImplementationDataType) as far as applicable. • The symbol is the one used in the programming language. It will be used to find out the actual memory address by the final generation tool with the help of linker generated information. It is assumed that in the M1 model this part and all the aggregated and referred elements (with the exception of the Flat Map and the references from ImplementationElementInParameterInstanceRef and McAccessDetails) are completely generated from "upstream" information. This means, that even if an element like e.g. a CompuMethod is only used via reference here, it will be copied into the M1 artifact which holds the complete McSupportData for a given Implementation.
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*

△

Class	**McDataInstance**			
Aggregated by	McDataInstance.subElement, McSupportData.mcParameterInstance, McSupportData.mcVariableInstance			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
arraySize	PositiveInteger	0..1	attr	The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of number of elements.
displayIdentifier	McdIdentifier	0..1	attr	An optional attribute to be used to set the ASAM ASAP2 DISPLAY_IDENTIFIER attribute.
flatMapEntry	FlatInstanceDescriptor	0..1	ref	Reference to the corresponding entry in the ECU Flat Map. This allows to trace back to the original specification of the generated data instance. This link shall be added by the RTE generator mainly for documentation purposes. The reference is optional because • The McDataInstance may represent an array or struct in which only the subElements correspond to FlatMap entries. • The McDataInstance may represent a task local buffer for rapid prototyping access which is different from the "main instance" used for measurement access. **Tags:** atp.Splitkey=flatMapEntry This Attribute is only used by the AUTOSAR Classic Platform.
instanceIn Memory	ImplementationElement InParameterInstance Ref	0..1	aggr	Reference to the corresponding data instance in the description of calibration data structures published by the RTE generator. This is used to support emulation methods inside the ECU, it is not required for A2L generation. **Tags:** atp.Splitkey=instanceInMemory, instanceIn Memory.context, instanceInMemory.target
mcDataAccess Details	McDataAccessDetails	0..1	aggr	Refers to "upstream" information on how the RTE uses this data instance. Use Case: Rapid Prototyping **Tags:** atp.Splitkey=mcDataAccessDetails
mcData Assignment	RoleBasedMcData Assignment	*	aggr	An assignment between McDataInstances. This supports the indication of related McDataElement implementing the of "RP global buffer", "RP global measurement buffer", "RP enabler flag". **Tags:** atp.Splitkey=mcDataAssignment
resulting Properties	SwDataDefProps	0..1	aggr	These are the generated properties resulting from decisions taken by the RTE generator for the actually implemented data instance. Only those properties are relevant here, which are needed for the measurement and calibration system. **Tags:** atp.Splitkey=resultingProperties
resultingRptSw Prototyping Access	RptSwPrototyping Access	0..1	aggr	Describes the implemented accessibility of data and modes by the rapid prototyping tooling. **Tags:** atp.Splitkey=resultingRptSwPrototypingAccess atp.Status=obsolete
role	Identifier	0..1	attr	An optional attribute to be used for additional information on the role of this data instance, for example in the context of rapid prototyping.

▽

△

Class	**McDataInstance**			
rptImplPolicy	RptImplPolicy	0..1	aggr	Describes the implemented code preparation for rapid prototyping at data accesses for a hook based bypassing. **Tags:** atp.Splitkey=rptImplPolicy atp.Status=obsolete
subElement (ordered)	McDataInstance	*	aggr	This relation indicates, that the target element is part of a "struct" which is given by the source element. This information will be used by the final generator to set up the correct addressing scheme. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
symbol	SymbolString	0..1	attr	This String is used to determine the memory address during final generation of the MC configuration data (e.g. "A2L" file) . It shall be the name of the element in the programming language such that it can be identified in linker generated information. In case the McDataInstance is part of composite data in the programming language, the symbol String may include parts denoting the element context, unless the context is given by the symbol attribute of an enclosing McDataInstance. This means in particular for the C language that the "." character shall be used as a separator between the name of a "struct" variable the name of one of its elements. The symbol can differ from the shortName in case of generated C data declarations. It is an optional attribute since it may be missing in case the instance represents an element (e.g. a single array element) which has no name in the linker map.

Table 9.4: McDataInstance

An McDataInstance may represent the root of a nested composite of arrays and/or structs. This is modeled by adding appropriate subElements. In this case, the attribute McDataInstance.symbol shall be set only for those elements which actually are visible in the linker map. This should be always the case for the the root element of such a composite (otherwise its address cannot be assigned via the linker map):

[constr_4062] Mandatory symbol for McDataInstance root

Imposition time: IT_BswMD

⌈McDataInstances directly aggregated in McSupportData shall have a valid McDataInstance.symbol.⌋

[constr_9357] Existence of attributes of McDataInstance depending on the category

Imposition time: IT_BswMD

⌈

Attributes of McDataInstance	Attribute Existence per McDataInstance.category													
	VALUE	VAL_BLK	STRUCTURE	UNION	ARRAY	STRING	BOOLEAN	COM_AXIS	RES_AXIS	CURVE	MAP	CUBOID	CUBE_4	CUBE_5
arraySize					1									
displayIdentifier	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1
role	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1
symbol	1	1	1	1	1	1	1	1	1	1	1	1	1	1
subElement			1..*	1..*	1..*									
flatMapEntry	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1
instanceInMemory	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1
mcDataAccessDetails	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1
mcDataAssignment	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*
resultingRptSwPrototyping-Access	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1
rptImplPolicy	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1	0..1
resultingProperties.compu-Method	0..1	0..1					0..1			0..1	0..1	0..1	0..1	0..1
resultingProperties.unit	0..1	0..1								0..1	0..1	0..1	0..1	0..1
resultingProperties.dataConstr	0..1	0..1			0..1		0..1			0..1	0..1	0..1	0..1	0..1
resultingProperties.swCalprm-AxisSet								0..1	0..1	0..1	0..1	0..1	0..1	0..1
resultingProperties.swData-Dependency	0..1						0..1			0..1	0..1	0..1	0..1	0..1
resultingProperties.swHost-Variable														
resultingProperties.swBit-Representation														
resultingProperties.baseType	0..1													
resultingProperties.swRecord-Layout	0..1	0..1				0..1		1	1	1	1	1	1	1
resultingProperties.additional-NativeTypeQualifier	0..1		0..1	0..1	0..1	0..1		0..1	0..1	0..1	0..1	0..1	0..1	0..1
resultingProperties.stepSize	0..1	0..1			0..1			0..1	0..1	0..1	0..1	0..1	0..1	0..1
resultingProperties.display-Presentation	0..1	0..1			0..1			0..1	0..1	0..1	0..1	0..1	0..1	0..1
resultingProperties.swAlign-ment														
resultingProperties.swImpl-Policy														
resultingProperties.swAddr-Method														
resultingProperties.swIntended-Resolution														
resultingProperties.swPointer-TargetProps														

▽

△

Attributes of McDataInstance	Attribute Existence per McDataInstance.category													
	VALUE	VAL_BLK	STRUCTURE	UNION	ARRAY	STRING	BOOLEAN	COM_AXIS	RES_AXIS	CURVE	MAP	CUBOID	CUBE_4	CUBE_5
resultingProperties.swInterpolation-Method								0..1	0..1	0..1	0..1	0..1	0..1	0..1
resultingProperties.swIs-Virtual														
resultingProperties.swValue-BlockSize		1												
resultingProperties.swValue-BlockSizeMult		1												
resultingProperties.annotation	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*	0..*
resultingProperties.display-Format	0..1	0..1	0..1	0..1	0..1	0..1	0..1			0..1	0..1	0..1	0..1	0..1
resultingProperties.implementation-DataType														
resultingProperties.invalid-Value	0..1		0..1		0..1	0..1								
resultingProperties.swText-Props						1								

⌋

[TPS_BSWMDT_04059] Granularity of McDataInstance.subElements ⌈Note that it is possible to e.g. define single array elements or struct elements as to be measured or calibrated (the referencing mechanism used in the FlatInstanceDescriptor is capable of stating array indexes).

In this case one needs to define one McDataInstance representing the globally visible C-array or -struct (and stating its symbol) and appropriate subElements for the nested elements to be measured and link these elements to the individual FlatInstanceDescriptors.⌋

[TPS_BSWMDT_04060] McDataInstance.resultingProperties ⌈The figure also shows the meta-classes of the typical elements which might be attached to an McDataInstance via its SwDataDefProps.

These elements (and their further detailing, which is not shown here) are used in the same way as in the SWCT (see [5]) though, as already mentioned, it is expected that the support data will contain copies of the elements found in the SWC- and BSWM-descriptions which refer to each other in a self-contained manner.⌋

[TPS_BSWMDT_04114] Using the hierarchical structuring of McDataInstance.subElements ⌈The structure of the subElements shall follow the structure of the corresponding ApplicationDataType respectively ImplementationDataType.

The value of the symbol attribute of the subElements shall exist and it shall reflect the symbol of the subElement only (as opposed to reflecting the full combined symbol starting from the root element).⌋

[TPS_BSWMDT_04115] Use of indexing for array element of subElements ⌈McDataInstances have to be created for those array elements that are accessed by MCD in separate and these have to be put as subElements under an McDataInstance representing the whole array.

The symbol of the subElement shall contain the array index in the C-notation, e.g [4].⌋

[TPS_BSWMDT_04182] No support for pointers in McDataInstance ⌈An McDataInstance does not support the definition of a pointer.⌋

Please note that this is described by [constr_1006] [5] that defines that the categories DATA_REFERENCE, FUNCTION_REFERENCE and TYPE_REFERENCE are not applicable to the McDataInstance. In addition [constr_1015] [5] forbids that swPointerTargetProps are attached as resultingProperties to an McDataInstance.

[TPS_BSWMDT_04183] McDataInstance with category STRING ⌈The amount of memory required for a McDataInstance of category STRING can be computed out of the value of attribute McDataInstance.resultingProperties.swTextProps.swMaxTextSize (this yields the number of code units) * maximum size of one code unit in bytes.⌋

9.3 Support for Software Emulation of Calibration Data

The RTE generator provides several methods to allocate calibration data in a way, that they can be emulated by software on the ECU during an online calibration procedure, see [9] for a more detailed description.

If such an emulation is configured, the calibration data changed during online calibration are “emulated” by e.g. a Complex Driver, but the access to these data by the functional software is still handled by the RTE.

In order to generate or configure the emulation code of e.g. the Complex Driver, the RTE generator has to publish a detailed description of the data structure of the calibration data and supporting elements which directly correspond to its C-code.

This information is created by the RTE generator as part the BswInternalBehavior of its own BSWMD, namely by defining local data descriptions as had been shown earlier.

HINT

These local data descriptions should not be mixed up with the input defining the calibration data from the perspective of the module or component using the data. These are, for example, given as BswInternalBehavior.arTypedPerInstanceMemory in the BSWMD of the using module, see figure 5.15.

The generated data descriptions of the RTE are an M1 model of DataPrototypes based on ImplementationDataTypes using the “normal” meta-model elements. But in addition the RTE generator has to provide an information on the so-called calibration method which it actually uses and how this relates to the generated data structures (see [9] for details).

This is expressed by the meta-class McSwEmulationMethodSupport which for convenience is attached to the McSupportData as shown in figure 9.3 and the next two class tables.

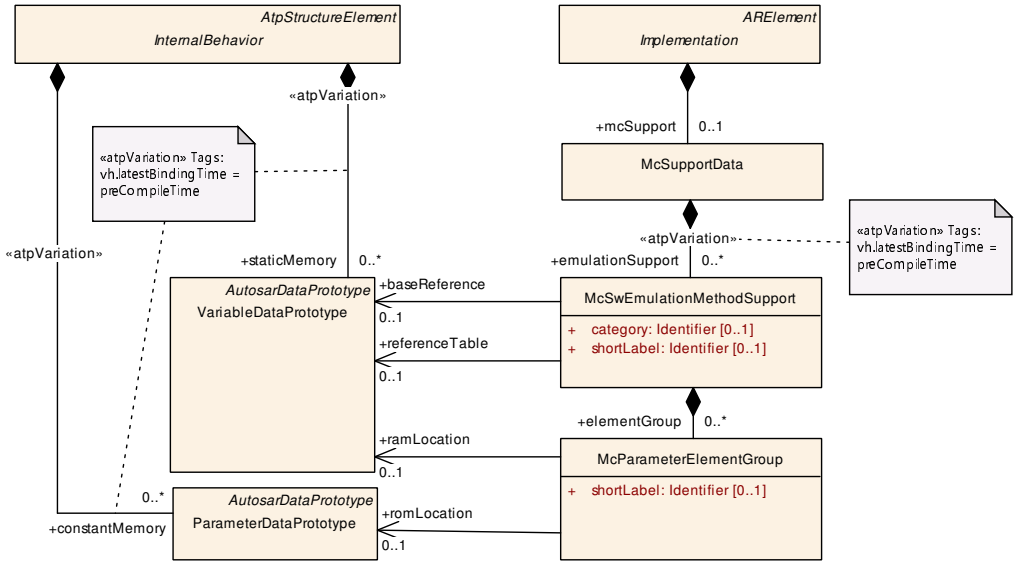

Figure 9.3: Describing the Software Emulation Method for Calibration Data

Class	**McSwEmulationMethodSupport**			
Note	This denotes the method used by the RTE to handle the calibration data. It is published by the RTE generator and can be used e.g. to generate the corresponding emulation method in a Complex Driver. According to the actual method given by the category attribute, not all attributes are always needed: • double pointered method: only baseReference is mandatory • single pointered method: only referenceTable is mandatory • initRam method: only elementGroup(s) are mandatory Note: For single/double pointered method the group locations are implicitly accessed via the reference table and their location can be found from the initial values in the M1 model of the respective pointers. Therefore, the description of elementGroups is not needed in these cases. Likewise, for double pointered method the reference table description can be accessed via the M1 model under baseReference.			
Base	*ARObject*			
Aggregated by	McSupportData.emulationSupport			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
baseReference	VariableDataPrototype	0..1	ref	Refers to the base pointer in case of the double-pointered method. **Tags:** atp.Splitkey=baseReference

△

Class	**McSwEmulationMethodSupport**			
category	Identifier	0..1	attr	Identifies the actual method. The possible names shall correspond to the symbols of the ECU configuration parameter for the calibration method of the RTE, and can include vendor specific methods. **Tags:** xml.sequenceOffset=-90
elementGroup	McParameterElement Group	*	aggr	Denotes the grouping of calibration parameters in the actual RTE code. Depending on the category, this information maybe required to set up the emulation code. **Tags:** atp.Splitkey=elementGroup
referenceTable	VariableDataPrototype	0..1	ref	Refers to the pointer table in case of the single-pointered method. **Tags:** atp.Splitkey=referenceTable
shortLabel	Identifier	0..1	attr	Assigns a name to this element. **Tags:** xml.sequenceOffset=-100

Table 9.5: McSwEmulationMethodSupport

[constr_10340] Existence of attribute McSwEmulationMethodSupport.category

Imposition time: IT_BswMD

⌈For each McSwEmulationMethodSupport, the attribute category shall exist.⌋

[constr_10341] Existence of attribute McSwEmulationMethodSupport.shortLabel

Imposition time: IT_BswMD

⌈For each McSwEmulationMethodSupport, the attribute shortLabel shall exist.⌋

Class	**McParameterElementGroup**			
Note	Denotes a group of calibration parameters which are handled by the RTE as one data structure.			
Base	*ARObject*			
Aggregated by	McSwEmulationMethodSupport.elementGroup			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
ramLocation	VariableDataPrototype	0..1	ref	Refers to the RAM location of this parameter group. To be used for the init-RAM method. **Tags:** atp.Splitkey=ramLocation
romLocation	ParameterData Prototype	0..1	ref	Refers to the ROM location of this parameter group. To be used for the init-RAM method. **Tags:** atp.Splitkey=romLocation
shortLabel	Identifier	0..1	attr	Assigns a name to this element. **Tags:** xml.sequenceOffset=-100

Table 9.6: McParameterElementGroup

[constr_10342] Existence of the reference in the role McParameterElementGroup.ramLocation

Imposition time: IT_BswMD

⌈For each McParameterElementGroup, the reference in the role ramLocation shall exist.⌋

[constr_10343] Existence of the reference in the role McParameterElementGroup.romLocation

Imposition time: IT_BswMD

⌈For each McParameterElementGroup, the reference in the role romLocation shall exist.⌋

[constr_10344] Existence of attribute McParameterElementGroup.shortLabel

Imposition time: IT_BswMD

⌈For each McParameterElementGroup, the attribute shortLabel shall exist.⌋

[TPS_BSWMDT_04061] McSwEmulationMethodSupport.category ⌈The value of McSwEmulationMethodSupport.category can either correspond to the enumeration value of the RTE configuration parameter RteCalibrationSupport (namely DOUBLE_POINTERED, SINGLE_POINTERED or INITIALIZED_RAM, see [9]), or it can be chosen differently in order to denote a vendor specific method.⌋

[constr_4044] Content of McSwEmulationMethodSupport

Imposition time: IT_BswMD

⌈The following constraints hold for the attributes of McSwEmulationMethodSupport:

- If category is DOUBLE_POINTERED, a baseReference shall exist.
- If category is SINGLE_POINTERED, a referenceTable shall exist.
- If category is INITIALIZED_RAM, one or more elementGroups shall exist.

⌋

[TPS_BSWMDT_04062] Upstream reference for emulation support ⌈For a full support of software emulation, we also need a relation between the “upstream” parameter description (represented by an entry in the ECU Flat Map) and the actually implemented code element. The required reference ImplementationElementInParameterInstanceRef is attached to McDataInstance.

This is mainly done for convenience, as McDataInstance is generated in the same step and already refers to the Flat Map.

This part of the meta-model assumes, that the RTE generator uses ImplementationDataTypes to describe the implemented data structures and that each implemented parameter element is part of a group, thus resulting in a ImplementationDataTypeElement as the target of the reference.⌋

Figure 9.4 shows the relation between the “upstream” parameter description and the actually implemented code element.

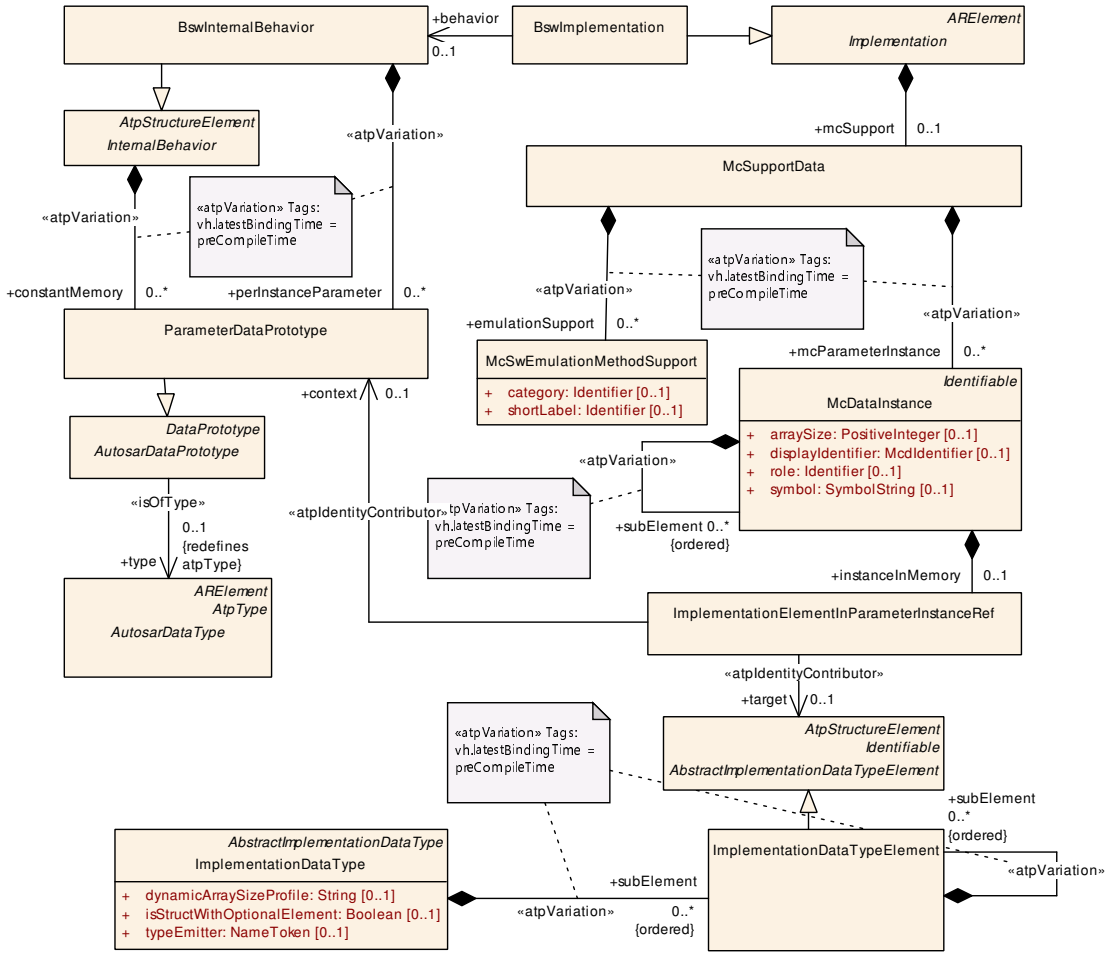

Figure 9.4: Reference to the Implemented Data needed for Emulation

Class	**ImplementationElementInParameterInstanceRef**			
Note	Describes a reference to a particular ImplementationDataTypeElement instance in the context of a given ParameterDataPrototype. Thus it refers to a particular element in the implementation description of a software data structure. Use Case: The RTE generator publishes its generated structure of calibration parameters in its BSW module description using the "constantMemory" role of ParameterDataPrototypes. Each ParameterData Prototype describes a group of single calibration parameters. In order to point to these single parameters, this "instance ref" is needed. Note that this class follows the pattern of an InstanceRef but is not implemented based on the abstract classes because the ImplementationDataType isn’t either, especially because ImplementationDataType Element isn’t derived from AtpPrototype.			
Base	*ARObject*			
Aggregated by	McDataInstance.instanceInMemory			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

△

Class	**ImplementationElementInParameterInstanceRef**			
context	ParameterData Prototype	0..1	ref	The context for the referred element. **Stereotypes:** atpIdentityContributor **Tags:** xml.sequenceOffset=20
target	AbstractImplementation DataTypeElement	0..1	ref	The referred data element. **Stereotypes:** atpIdentityContributor **Tags:** xml.sequenceOffset=30

Table 9.7: ImplementationElementInParameterInstanceRef

[constr_10345] Existence of the reference in the role ImplementationElementInParameterInstanceRef.context

Imposition time: IT_BswMD

⌈For each ImplementationElementInParameterInstanceRef, the reference in the role context shall exist.⌋

[constr_10346] Existence of the reference in the role ImplementationElementInParameterInstanceRef.target

Imposition time: IT_BswMD

⌈For each ImplementationElementInParameterInstanceRef, the reference in the role target shall exist.⌋

[constr_4034] Target and context of MC emulation reference

Imposition time: IT_BswMD

⌈Within one ImplementationElementInParameterInstanceRef, the target shall refer to a sub-element of the ParameterDataPrototype which is referred as context.⌋

If the elements to be measured or calibrated are part of arrays or structs, it is important to define the references in a consistent and complete way for all sub-elements involved in order to avoid ambiguities. Since the ImplementationElementInParameterInstanceRef allows to define only one context element, we need the following constraint:

[constr_4061] Completeness of MC emulation reference

Imposition time: IT_BswMD

⌈If an McDataInstance in the role of a subElement of another McDataInstance specifies an instanceInMemory, then the containing McDataInstance shall also specify an instanceInMemory.

The target of the latter (i.e. upper level) instanceInMemory shall be identical (including array index, if defined) to the context of the first (i.e. lower level) instanceInMemory.⌋

Without this constraint, it would be possible to define a reference to an inner element of nested arrays/structs without that the corresponding global C variable could be identified.

9.4 Support for Functional Modeling of Measurement and Calibration

The “A2L” description format for measurement and calibration data allows to associate the data with so-called *functions* in order to guide the calibration engineer in handling a large number of such data (see description of the keyword FUNCTION in [19]).

Such functions are mainly logical constructs and do not necessarily match to software objects like modules or components in the sense of AUTOSAR. However, since it is the goal of measurement and calibration support of AUTOSAR to be able to generate A2L descriptions from AUTOSAR XML descriptions, the AUTOSAR meta-model also provides the means to define such functions in the sense of A2L.

[TPS_BSWMDT_04078] Semantics of `McFunction` ⌈The meta-class `McFunction` together with associated `McFunctionDataRefSet`s can be used to define the association of measurement and/or calibration data in a software system to a logical function in various roles. In addition, it allows to structure such functions hierarchically.⌋

Note that `McFunction` is an `ARElement` so it can be used to define standalone artifacts which strictly speaking do not belong to any particular BSWMD. Nonetheless this part of the meta-model is described in this document because it belongs to the overall support for measurement and calibration.

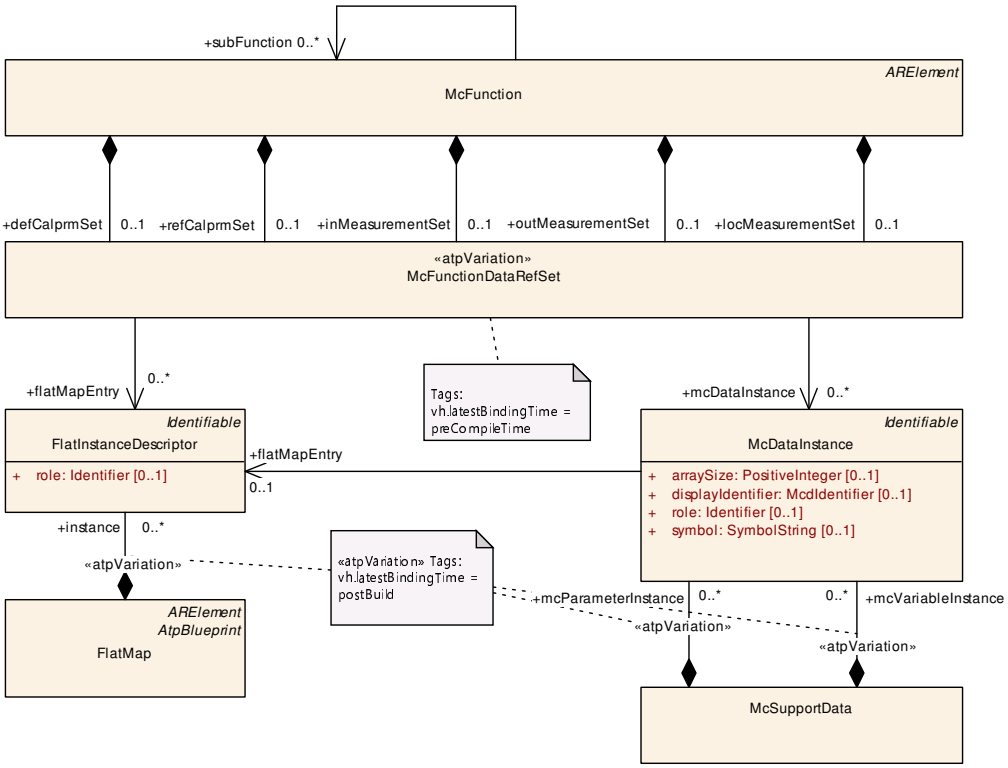

Figure 9.5: Meta-model for `McFunction`

Class	**McFunction**			
Note	Represents a functional element to be used as input to support measurement and calibration. It is used to • assign calibration parameters to a logical function • assign measurement variables to a logical function • structure functions hierarchically **Tags:** atp.recommendedPackage=McFunctions			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *Packageable Element*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
defCalprmSet	McFunctionDataRefSet	0..1	aggr	Refers to the set of adjustable data (= calibration parameters) defined in this function. **Tags:** atp.Splitkey=defCalprmSet xml.sequenceOffset=10
inMeasurement Set	McFunctionDataRefSet	0..1	aggr	Refers to the set of measurable input data for this function. **Tags:** atp.Splitkey=inMeasurementSet xml.sequenceOffset=30
loc Measurement Set	McFunctionDataRefSet	0..1	aggr	Refers to the set of measurable local data in this function. **Tags:** atp.Splitkey=locMeasurementSet xml.sequenceOffset=50

△

Class	**McFunction**			
out Measurement Set	McFunctionDataRefSet	0..1	aggr	Refers to the set of measurable output data from this function. **Tags:** atp.Splitkey=outMeasurementSet xml.sequenceOffset=60
refCalprmSet	McFunctionDataRefSet	0..1	aggr	Refers to the set of adjustable data (= calibration parameters) referred by this function. **Tags:** atp.Splitkey=refCalprmSet xml.sequenceOffset=20
subFunction	McFunction	*	ref	A sub-function that is seen as part of the enclosing function. **Tags:** atp.Splitkey=subFunction xml.sequenceOffset=70

Table 9.8: McFunction

Class	«atpVariation» **McFunctionDataRefSet**			
Note	Refers to a set of data assigned to an McFunction in a particular role. The data are given • either by entries in a FlatMap • or by data instances that are part of MC support data. These two possibilities are exclusive within a given McFunctionDataRefSet. Which one to use depends on the process and tool environment. The set is subject to variability because the same functional model may be used with various representation of the data. **Tags:** vh.latestBindingTime=preCompileTime			
Base	*ARObject*			
Aggregated by	McFunction.defCalprmSet, McFunction.inMeasurementSet, McFunction.locMeasurementSet, McFunction.outMeasurementSet, McFunction.refCalprmSet			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
flatMapEntry	FlatInstanceDescriptor	*	ref	Refers to an entry in a FlatMap that is part of the set, for example a calibration parameter or measured variable. **Tags:** atp.Splitkey=flatMapEntry xml.sequenceOffset=10 This Attribute is only used by the AUTOSAR Classic Platform.
mcDataInstance	McDataInstance	*	ref	Refers to a data instance within MC support data that is part of the set, i.e. a calibration parameter or measured variable. **Tags:** atp.Splitkey=mcDataInstance xml.sequenceOffset=20

Table 9.9: McFunctionDataRefSet

[TPS_BSWMDT_04087] Scope of `McFunctionDataRefSet`s ⌈It should be noted that `McFunctionDataRefSet`s can refer to the data either via instances of `FlatInstanceDescriptor` or `McDataInstance`:

- The first possibility, i.e. the association via a FlatMap allows to define McFunctions rather early in the project on ECU or even System level before the actual McSupport has been generated.
- The second possibility, the association to McDataInstances allows to define (or transform) McFunctions for usage in a self-contained manner together with the McSupport data for A2L generation.

⌋

[TPS_BSWMDT_04088] Usage of McFunction ⌈Since the use cases for McFunction are considered as rather project specific and the specification how to generate A2L does not belong to AUTOSAR, not all possible constraints on the attributes and association owned by McFunction are specified in this document. Especially it is not standardized, how instances of McFunctions have to be derived from an M1 model of AUTOSAR software components or modules.⌋

Still some constraints are considered as mandatory:

[constr_4068] McFunctionDataRefSet.flatMapEntry's semantic

Imposition time: IT_BswMD

⌈

- An McFunctionDataRefSet aggregated in the role of McFunction.defCalprmSet or McFunction.refCalprmSet shall only refer to FlatInstanceDescriptors that
  - either can be traced down to a ParameterDataPrototype
  - or can be traced down to a VariableDataPrototype of category COM_AXIS, RES_AXIS, CURVE, MAP, CUBOID, CUBE_4, CUBE_5 or VAL_BLK

  and which are declared for calibration access i.e. have an associated SwDataDefProps.swCalibrationAccess set to readWrite or readOnly.
- An McFunctionDataRefSet aggregated in the role of McFunction.inMeasurementSet, McFunction.outMeasurementSet or McFunction.locMeasurementSet shall only refer to FlatInstanceDescriptors that can be traced down to either a VariableDataPrototype, an ArgumentDataPrototype or a ModeDeclarationGroupPrototype and are declared as measurable i.e. have an associated SwDataDefProps.swCalibrationAccess set to readOnly.

⌋

[constr_4069] McFunctionDataRefSet.mcDataInstance's semantic

Imposition time: IT_BswMD

⌈

- An McFunctionDataRefSet aggregated in the role of McFunction.defCalprmSet or McFunction.refCalprmSet shall only refer to McDataInstances that are declared for calibration access i.e. are aggregated in the role McSupportData.mcParameterInstance or McSupportData.mcVariableInstance of category COM_AXIS, RES_AXIS, CURVE, MAP, CUBOID, CUBE_4, CUBE_5 or VAL_BLK.
- An McFunctionDataRefSet aggregated in the role of McFunction.inMeasurementSet, McFunction.outMeasurementSet or McFunction.locMeasurementSet shall only refer to McDataInstances that are declared as measurable i.e. are aggregated in the role McSupportData.mcVariableInstance.

⌋

Please note, that VariableDataPrototypes - end corresponding McDataInstances - of category of category COM_AXIS, RES_AXIS, CURVE, MAP, CUBOID, CUBE_4, CUBE_5 or VAL_BLK are describing so called adaptive characteristics. Those are modifiable during the ECU run-time and therefore described as VariableDataPrototypes but are CHARACTERISTICs in the sense of A2L.

Older versions of the meta-model didn't contain the meta-class McFunction but there was already the possibility to specify the name of a function associated with a data object by the attribute SwDataDefProps.McFunction.

This had serious limitations as is was neither possible to define input data to a function, nor to define more than one function associated with some data, nor to define sub-functions. For backward compatibility reasons this possibility still exists but the attribute has been tagged as obsolete.

9.5 Support for Structuring of Measurement and Calibration

The "A2L" description format for measurement and calibration data allows to associate the data with so-called *groups* in order to support structuring of projects involving a very large number measurement and calibration data (see description of the keyword GROUP in [19]).

Such groups are used to structure measurement and calibration data as well as functions according user specific criteria, e.g. a structuring according the C file assignment or calibration components which describe the calibration engineer's point of view.

Therefore, groups are mainly logical constructs and do not necessarily match to software objects like modules or components in the sense of AUTOSAR. However, since it is the goal of measurement and calibration support of AUTOSAR to be able to generate A2L descriptions from AUTOSAR XML descriptions, the AUTOSAR meta-model also provides the means to define such groups in the sense of A2L.

[TPS_BSWMDT_04168] Semantics of McGroup ⌈The meta-class McGroup together with associated McGroupDataRefSets can be used to define the association of measurement and/or calibration data and/or functions in a software system to a logical structure in various roles. In addition, it allows to structure such groups hierarchically.⌋

Similar as McFunction the McGroup is an ARElement so it can be used to define standalone artifacts which strictly speaking do not belong to any particular BSWMD. Nonetheless this part of the meta-model is described in this document because it belongs to the overall support for measurement and calibration.

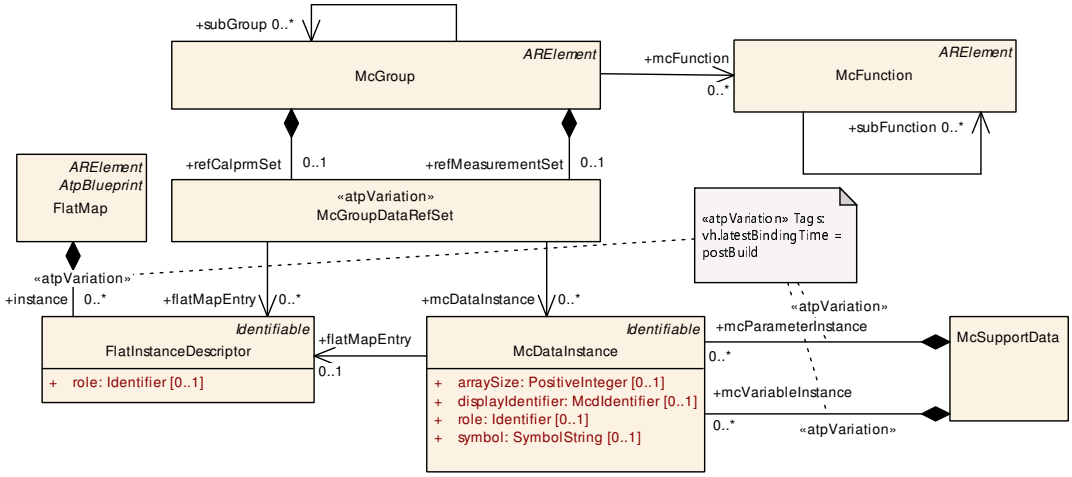

Figure 9.6: Meta-model for McGroup

Class	**McGroup**			
Note	Represents a group element to be used as input to support measurement and calibration. It is used to provide selection lists (groups) of calibration parameters, measurement variables, and functions in a hierarchical manner (subGroups). **Tags:** atp.recommendedPackage=McFunctions			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *Packageable Element*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
mcFunction	McFunction	*	ref	A McFunction that is seen as part of the enclosing group. **Tags:** atp.Splitkey=mcFunction xml.sequenceOffset=40
refCalprmSet	McGroupDataRefSet	0..1	aggr	Refers to the set of adjustable data (= calibration parameters) referred by this McGroup. **Tags:** atp.Splitkey=refCalprmSet xml.sequenceOffset=20
ref Measurement Set	McGroupDataRefSet	0..1	aggr	Refers to the set of measurable belonging to this Mc Group. **Tags:** atp.Splitkey=refMeasurementSet xml.sequenceOffset=30

△

Class	**McGroup**			
subGroup	McGroup	*	ref	A sub-group that is seen as part of the enclosing group. **Tags:** atp.Splitkey=subGroup xml.sequenceOffset=10

Table 9.10: McGroup

Class	«atpVariation» **McGroupDataRefSet**			
Note	Refers to a set of data assigned to an McGroup in a particular role. The data are given • either by entries in a FlatMap • or by data instances that are part of MC support data. These two possibilities can be mixed within a given McGroupDataRefSet. Which one to use depends on the process and tool environment. The set is subject to variability because the same functional model may be used with various representation of the data. **Tags:** vh.latestBindingTime=preCompileTime			
Base	*ARObject*			
Aggregated by	McGroup.refCalprmSet, McGroup.refMeasurementSet			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
flatMapEntry	FlatInstanceDescriptor	*	ref	Refers to an entry in a FlatMap that is part of the set, for example a calibration parameter or measured variable. **Tags:** atp.Splitkey=flatMapEntry xml.sequenceOffset=50 This Attribute is only used by the AUTOSAR Classic Platform.
mcDataInstance	McDataInstance	*	ref	Refers to a data instance within MC support data that is part of the set, i.e. a calibration parameter or measured variable. **Tags:** atp.Splitkey=mcDataInstance xml.sequenceOffset=60

Table 9.11: McGroupDataRefSet

[TPS_BSWMDT_04169] Scope of `McGroupDataRefSet`s ⌈`McGroupDataRefSet`s can refer to the data either via instances of `FlatInstanceDescriptor` or `McDataInstance`:

- The first possibility, i.e. the association via a `FlatMap` allows to define `McGroup`s rather early in the project on ECU or even System level before the actual McSupport has been generated.
- The second possibility, the association to `McDataInstance`s allows to define (or transform) `McGroup`s for usage in a self-contained manner together with the McSupport data for A2L generation.

⌋

[TPS_BSWMDT_04170] Usage of `McGroup` ⌈Since the use cases for `McGroup` are considered as rather project specific and the specification how to generate A2L does

not belong to AUTOSAR, not all possible constraints on the attributes and association owned by McGroup are specified in this document.

Especially it is not standardized, how instances of McGroups have to be derived from an M1 model of AUTOSAR software components or modules.⌋

Still some constraints are considered as mandatory:

[constr_4101] Semantics of McGroupDataRefSet.flatMapEntry

Imposition time: IT_BswMD

⌈

- An McGroupDataRefSet aggregated in the role of McGroup.refCalprmSet or McGroup.refCalprmSet shall only refer to FlatInstanceDescriptors that can either be traced down to a ParameterDataPrototype or can be traced down to a VariableDataPrototype of category COM_AXIS, RES_AXIS, CURVE, MAP, CUBOID, CUBE_4, CUBE_5 or VAL_BLK and which are declared for calibration access i.e. have an associated SwDataDefProps.swCalibrationAccess set to readWrite or readOnly.
- An McGroupDataRefSet aggregated in the role of McGroup.refMeasurementSet shall only refer to FlatInstanceDescriptors that can be traced down to either a VariableDataPrototype, an ArgumentDataPrototype or a ModeDeclarationGroupPrototype and are declared as measurable i.e. have an associated SwDataDefProps.swCalibrationAccess set to readOnly.

⌋

[constr_4102] Semantics of McGroupDataRefSet.mcDataInstance

Imposition time: IT_BswMD

⌈

- An McGroupDataRefSet aggregated in the role of McGroup.refCalprmSet shall only refer to McDataInstances that are declared for calibration access i.e. are aggregated in the role McSupportData.mcParameterInstance or McSupportData.mcParameterInstance of category VALUE, COM_AXIS, RES_AXIS, CURVE, MAP, CUBOID, CUBE_4, CUBE_5 or VAL_BLK.
- An McGroupDataRefSet aggregated in the role of McGroup.refMeasurementSet shall only refer to McDataInstances that are declared as measurable i.e. are aggregated in the role McSupportData.mcVariableInstance.

⌋

Please note, that VariableDataPrototypes - and corresponding McDataInstances - of category of category VALUE, COM_AXIS, RES_AXIS, CURVE, MAP, CUBOID, CUBE_4, CUBE_5 or VAL_BLK are describing so called adaptive characteristics. Those

are modifiable at run-time of the ECU and therefore described as VariableDataPrototypes but are CHARACTERISTICs in the sense of A2L.

[TPS_BSWMDT_04184] McDataInstance is allowed to be a member in multiple McGroups ⌈An McDataInstance is allowed to be referenced by McGroupDataRefSets that are aggregated by different McGroups.⌋

9.6 McSupportData for Rapid Prototyping

The AUTOSAR meta-model supports the description of a software system that include rapid prototyping scenarios of Application Software Components. The high level part of such a description is done with the help of the meta-class RapidPrototypingScenario, see [5] for documentation.

So far this "high level" description of rapid prototyping is not a topic for the Basic-Software Module Description Template. However some special solutions for rapid prototyping require a direct access to RTE internal data buffers that are used to hold the data for communication between software components:

- The rapid prototyping implementation (which could run on an external ECU or as a Complex Driver on the same ECU) may directly[2] access the RTE data buffers in a similar way as it is done from an MCD system (e.g. via an XCP driver)
- The rapid prototyping functionality may be embedded in the RTE itself. In this case, external data access is needed to monitor the data as well as to switch between the "prototyping" and the "original" behavior of the RTE for a particular data access point.

In order to configure a rapid prototyping system that works according to the solutions outlined above, some knowledge on the RTE internal data buffers has to be provided to external tools in a similar way as for MCD access.

Therefore the meta-classes below McSupportData are used for this purpose too. Several extensions to these meta-classes are needed for these use cases.

[2] "directly" means not via an RTE API or an RTE hook function

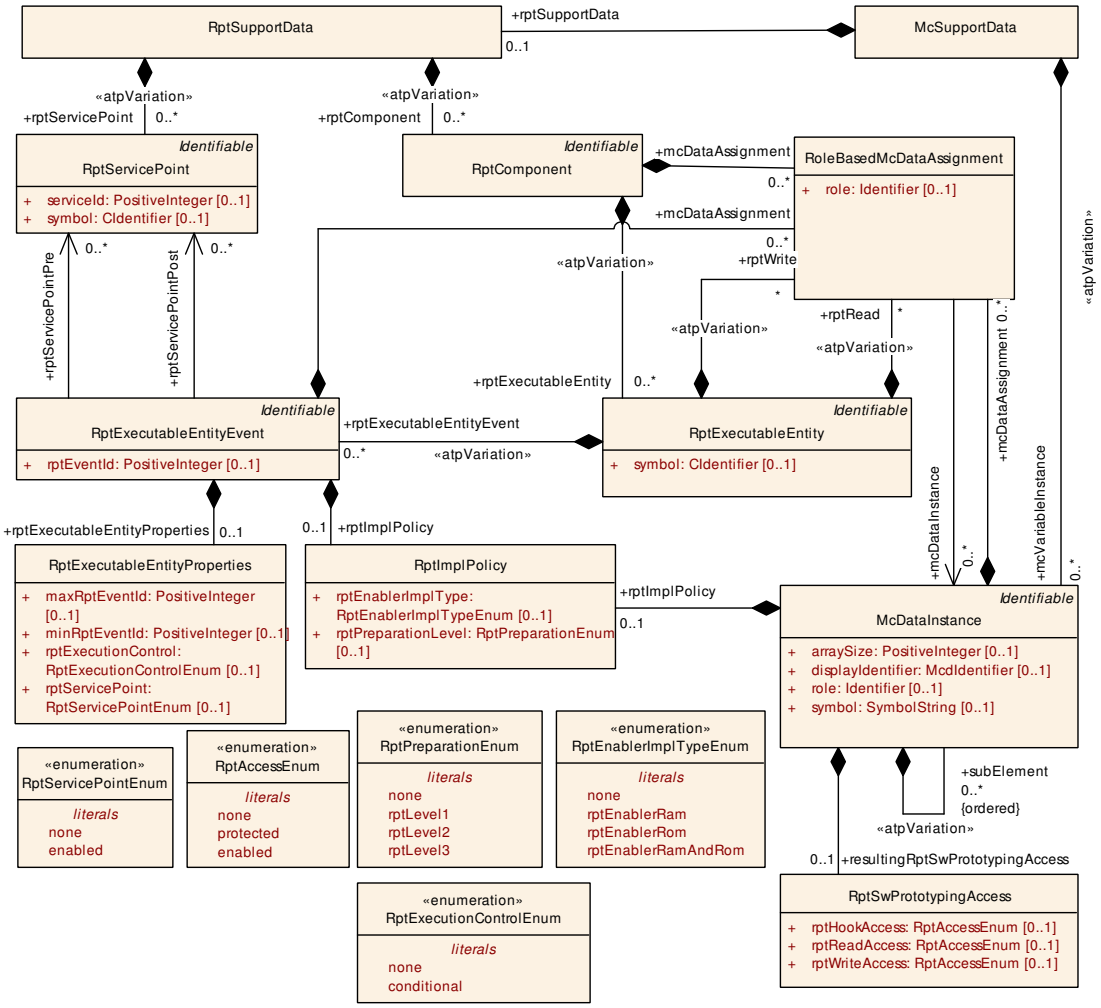

Figure 9.7: Extension of `McSupportData` for Rapid Prototyping

[TPS_BSWMDT_04094] Details of `McDataInstance` for rapid prototyping ⌈Especially for the prototyping of a `RunnableEntity` with implicit communication, typically more than one RTE internal buffer needs to be accessed and it needs to be described what kind of data access and what RTE event is associated with each buffer.

This information can be provided (for example generated) by setting the references in `McDataInstance.mcDataAccessDetails`. The base of these references shall be the ECU Extract to which also the RTE implementation belongs for which the `McSupportData` is meant (see also constraint below).

In addition to this, the attribute `McDataInstance.role` may be used to add more information on the particular role of this data instance. Note the the content of this attribute is not standardized.⌋

[constr_4073] `McDataAccessDetails` shall refer to one ECU Extract

Imposition time: `IT_BswMD`

⌈Within one given `McDataAccessDetails`, all instances of `System` referenced as the base of any `McDataAccessDetails.variableAccess` or as the base

of any McDataAccessDetails.rteEvent shall be identical and of category ECU_EXTRACT.⌋

Class	**McDataAccessDetails**			
Note	This meta-class allows to attach detailed information about the usage of a data buffer by the RTE to a corresponding McDataInstance. Use Case: Direct memory access to RTE internal buffers for rapid prototyping. In case of implicit communication, the various task local buffers need to be identified in relation to RTE events and variable access points. Note that the SwComponentPrototype, the RunnableEntity and the VariableDataPrototype are implicitly given be the referred instances of RTEEvent and VariableAccess.			
Base	*ARObject*			
Aggregated by	McDataInstance.mcDataAccessDetails			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
rteEvent	RTEEvent	*	iref	The RTE event used to receive the data via this buffer. **Tags:** atp.Splitkey=rteEvent, rteEvent.contextRoot Composition, rteEvent.contextAtomicComponent, rte Event.targetRteEvent **InstanceRef implemented by:** RteEventInEcuInstance Ref
variableAccess	VariableAccess	*	iref	The VariableAccess for which the data buffer is used. **Tags:** atp.Splitkey=variableAccess, variable Access.contextRootComposition, variableAccess.context AtomicComponent, variableAccess.targetVariableAccess **InstanceRef implemented by:** VariableAccessInEcu InstanceRef

Table 9.12: McDataAccessDetails

[constr_10347] Existence of the instanceRef in the role McDataAccessDetails.rteEvent

Imposition time: IT_BswMD

⌈For each McDataAccessDetails, the instanceRef in the role rteEvent shall exist at least once.⌋

[constr_10329] Existence of the instanceRef in the role McDataAccessDetails.variableAccess

Imposition time: IT_BswMD

⌈For each McDataAccessDetails, the instanceRef in the role variableAccess shall exist at least once.⌋

[TPS_BSWMDT_04095] Relationships between McDataInstances ⌈In the case that rapid prototyping is embedded in the RTE, several McDataInstances are needed which have relationships to each other. For example, there could be a buffer holding the “original” data, a buffer holding the “replacement” data coming from a prototype implementation and a data instance holding the “switch” for switching between normal and replacement functionality.

The meta-class RoleBasedMcDataAssignment offers the possibility to express the relationships between such associated RTE data formally and use them as input to configure external software. Note that the meta-model is rather generic at this point in

order to allow project specific use cases. Therefore the values of the attribute RoleBasedMcDataAssignment.role are not standardized except one:

- The value mainInstance of this attribute shall be used to characterize the relation to that particular McDataInstance that represent the main instance of this data buffer - i.e. the one that would be normally displayed in an MCD system.

⌋

[TPS_BSWMDT_04096] Split between different use cases of McSupportData ⌈It should be noted that the aggregation of McDataInstance by McSupportData is splitable. This allows to keep the data description for MCD use cases and rapid prototyping use cases in separate artifacts and also to generate them at a different points in time.⌋

In the case that rapid prototyping is embedded in the RTE, different kinds of McDataInstances are needed. To describe the kind of the memory to which the McDataInstance relates, the attribute role is used.

For the description of the relationships between different kinds of McDataInstances or other elements, the RoleBasedMcDataAssignment.role attribute is used. Basically the role values can be defined project specific but for the use case of rapid prototyping several role values and the according semantic are standardized.

For the use case of rapid prototyping several role values and the according semantic are standardized and described in [TPS_BSWMDT_04159].

[TPS_BSWMDT_04159] Standardized values of attribute RoleBasedMcDataAssignment.role ⌈

Role	*Explanation*
RptGlobalMeasurementBuffer	Specifies the relationship between a global buffer holding the data value used by ECU SW and the memory location which used by the MCD System to access the value for subsequent measurement purposes before replacement by the RP generated value.
RptGlobalMeasurementBufferIn	Specifies the relationship between a global buffer holding a inout argument of a ClientServerOperation and the data value used by ECU SW and the memory location which used by the RP tool or MCD System to access the originally IN value.
RptGlobalMeasurementBufferOut	Specifies the relationship between a global buffer holding a inout argument of a ClientServerOperation and the data value used by ECU SW and the memory location which used by the RP tool or MCD System to access the originally OUT value.
RptGlobalBuffer	Specifies the relationship between a rapid prototyping global buffer holding the data value written / read by the RP tool and the memory location which used by the RTE holding the value used for communication from/to other software component instances.

▽

△

RptGlobalBufferIn	Specifies the relationship between a rapid prototyping global buffer holding the data value for a inout argument of a ClientServerOperation written / read by the RP tool for the IN direction and the memory location which used by the RTE holding the value used for communication from/to other software component instances.
RptGlobalBufferOut	Specifies the relationship between a rapid prototyping global buffer holding the data value for a inout argument of a ClientServerOperation written / read by the RP tool for the OUT direction and the memory location which used by the RTE holding the value used for communication from/to other software component instances.
RptRomEnablerFlag	Specifies the relationship to the memory location implementing a rapid prototyping enabler flag in ROM. This is used for run-time enabling/disabling the bypass.
RptRomEnablerFlagIn	Specifies the relationship to the memory location implementing a rapid prototyping enabler flag in ROM for the IN direction of an inout argument of a ClientServerOperation. This is used for runtime enabling/disabling the bypass.
RptRomEnablerFlagOut	Specifies the relationship to the memory location implementing a rapid prototyping enabler flag in ROM for the OUT direction of an inout argument of a ClientServerOperation. This is used for runtime enabling/disabling the bypass.
RptRamEnablerFlag	Specifies the relationship to the memory location implementing a rapid prototyping enabler flag in RAM. This is used for run-time enabling/disabling the bypass.
RptRamEnablerFlagIn	Specifies the relationship to the memory location implementing a rapid prototyping enabler flag in RAM for the IN direction of an inout argument of a ClientServerOperation. This is used for runtime enabling/disabling the bypass.
RptRamEnablerFlagOut	Specifies the relationship to the memory location implementing a rapid prototyping enabler flag in RAM for the OUT direction of an inout argument of a ClientServerOperation. This is used for runtime enabling/disabling the bypass.
RptRunnableDisabler-Flag	Specifies the relationship to the memory location implementing a rapid prototyping enabler flag controlling the execution of ExecutableEntitys.
RptStimEnabler	Specifies the relationship to the memory location implementing the service point stimulation enabler flag. This is used for run-time enabling/disabling the stimulation by the service point.
ImplicitBuffer	Specifies the relationship from a McDataInstance describing a implicit communication buffer to the McDataInstance describing a global buffer.

⌋

9.7 Rapid Prototyping support data

9.7.1 Rapid Prototyping support for software components or basic software modules

The meta class RptSupportData provides the infrastructure to describe the implemented Rapid Prototyping support in a software component or basic software module(s).

Thereby it is possible, that the Rapid Prototyping is locally implemented in a software component or basic software module for the software entity itself or in case of RTE that the Rapid Prototyping support is implemented on the demand of the RapidPrototypingScenario for the integration of the respective software components or basic software modules.

Class	**RptSupportData**			
Note	Root element for rapid prototyping support data related to one Implementation artifact on an ECU, in particular the RTE. The rapid prototyping support data may reference to elements provided for Mc SupportData.			
Base	*ARObject*			
Aggregated by	McSupportData.rptSupportData			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
execution Context	RptExecutionContext	*	aggr	Defines an environment for the execution of Executable Entites. **Tags:** atp.Splitkey=executionContext, execution Context.shortName
rptComponent	RptComponent	*	aggr	Description of components for which rapid prototyping support is implemented. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rptComponent, rptComponent.shortName, rptComponent.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
rptServicePoint	RptServicePoint	*	aggr	This aggregation represents the collection of service points associated with the enclosing RptSuportData **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rptServicePoint, rptServicePoint.shortName, rptServicePoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

Table 9.13: RptSupportData

[constr_10349] Existence of attribute RptSupportData.executionContext

Imposition time: IT_BswMD

⌈For each RptSupportData, the attribute executionContext shall exist at least once.⌋

[constr_10350] Existence of attribute RptSupportData.rptComponent

Imposition time: IT_BswMD

⌈For each RptSupportData, the attribute rptComponent shall exist at least once.⌋

[constr_10351] Existence of attribute RptSupportData.rptServicePoint

Imposition time: IT_BswMD

⌈For each RptSupportData, the attribute rptServicePoint shall exist at least once.⌋

Class	RptSwPrototypingAccess			
Note	Describes the accessibility of data and modes by the rapid prototyping tooling. **Tags:** atp.Status=obsolete			
Base	*ARObject*			
Aggregated by	McDataInstance.resultingRptSwPrototypingAccess, RptContainer.rptSwPrototypingAccess			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
rptHookAccess	RptAccessEnum	0..1	attr	The related data element can be modified using a post-build hooking tool. An ENABLED VariableData Prototype is implicitly READABLE/WRITABLE. **Tags:** atp.Status=obsolete
rptReadAccess	RptAccessEnum	0..1	attr	The related data element can be used as input for bypass functionality by RP tool. If rptImplPolicy is not specified then RTE generation shall ensure at least suitable MC read points are created. **Tags:** atp.Status=obsolete
rptWriteAccess	RptAccessEnum	0..1	attr	The related data element can be used as output for bypass functionality by RP tool. The data element shall be prepared to rptLevel2 and related write service points are present. **Tags:** atp.Status=obsolete

Table 9.14: RptSwPrototypingAccess

Class	RptComponent			
Note	Description of component instance for which rapid prototyping support is implemented.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	RptSupportData.rptComponent			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
mcData Assignment	RoleBasedMcData Assignment	*	aggr	Reference to related McDataElement describing the implementation of "RP global buffer", "RP global measurement buffer", "RP enabler flag" and the "RP runnable disabler flag". **Tags:** atp.Splitkey=mcDataAssignment
rpImplPolicy	RptImplPolicy	0..1	aggr	Describes the implemented code preparation for rapid prototyping at data accesses. **Tags:** atp.Splitkey=rpImplPolicy atp.Status=obsolete
rptExecutable Entity	RptExecutableEntity	*	aggr	ExecutableEntity instance which can be bypassed. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rptExecutableEntity, rptExecutable Entity.shortName, rptExecutableEntity.variationPoint.short Label vh.latestBindingTime=preCompileTime

Table 9.15: RptComponent

[constr_10352] Existence of attribute `RptComponent.rptExecutableEntity`

Imposition time: `IT_BswMD`

⌈For each `RptComponent`, the attribute `rptExecutableEntity` shall exist at least once.⌋

[TPS_BSWMDT_04160] `RptComponent` represents a software component or basic software module ⌈`RptComponent` describes a software component or basic software module (e.g. a CDD) for which rapid prototyping support is implemented.⌋

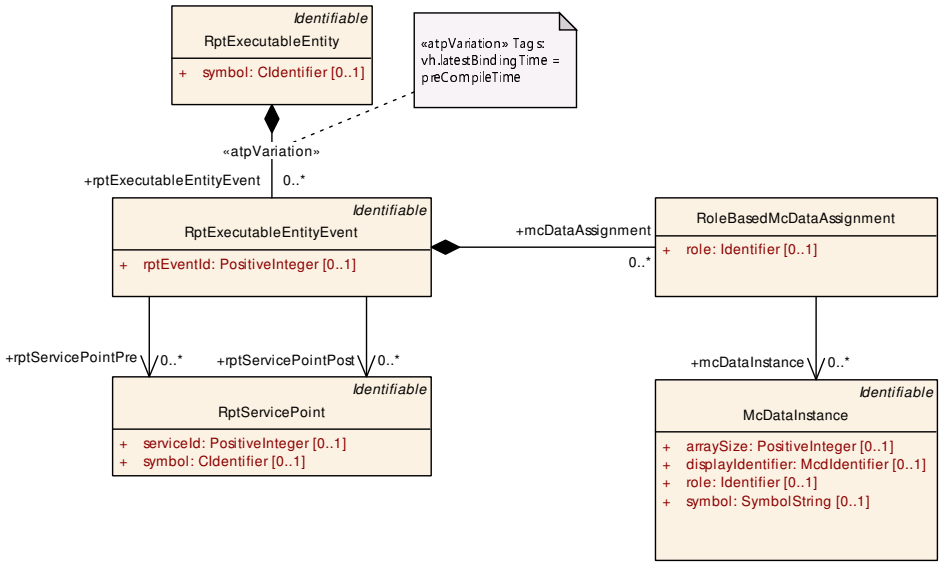

Figure 9.8: Meta-model for the usage of `RptServicePoint`

[TPS_BSWMDT_04161] `RptExecutableEntity` represents a `ExecutableEntity` with rapid prototyping support ⌈The `RptExecutableEntity` describes a `ExecutableEntity` for which rapid prototyping support is implemented.⌋

Class	**RptExecutableEntity**			
Note	This describes a ExecutableEntity instance which can be bypassed.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	RptComponent.rptExecutableEntity			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
rptExecutable EntityEvent	RptExecutableEntity Event	*	aggr	ExecutableEntity event instance activation the owning Rpt ExecutableEntity. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rptExecutableEntityEvent, rptExecutable EntityEvent.shortName, rptExecutableEntity Event.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

▽

△

Class	**RptExecutableEntity**			
rptRead	RoleBasedMcData Assignment	*	aggr	read access to a variable **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rptRead, rptRead.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
rptWrite	RoleBasedMcData Assignment	*	aggr	write access to a variable **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rptWrite, rptWrite.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
symbol	CIdentifier	0..1	attr	The symbol describing this ExecutableEntity's entry point.

Table 9.16: RptExecutableEntity

[constr_10353] Existence of attribute RptExecutableEntity.rptExecutableEntityEvent

Imposition time: IT_BswMD

⌈For each RptExecutableEntity, the attribute rptExecutableEntityEvent shall exist at least once.⌋

[constr_10354] Existence of attribute RptExecutableEntity.symbol

Imposition time: IT_BswMD

⌈For each RptExecutableEntity, the attribute symbol shall exist.⌋

[TPS_BSWMDT_04162] RptExecutableEntityEvent represents a RTEEvent or BswEvent for with rapid prototyping support ⌈The RptExecutableEntity-Event describes a instance of a RTEEvent or BswEvent for which rapid prototyping support is implemented. This means typically that Service Function calls before and after the call of the ExecutableEntity implementing the activation by the RTEEvent or BswEvent.⌋

Class	**RptExecutableEntityEvent**			
Note	This describes an ExecutableEntity event instance which can be bypassed.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	RptExecutableEntity.rptExecutableEntityEvent			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
execution Context	RptExecutionContext	*	ref	This describes the context in which the event of the executable entity is executed. **Tags:** atp.Splitkey=executionContext

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Class	**RptExecutableEntityEvent**			
mcData Assignment	RoleBasedMcData Assignment	*	aggr	Reference to related McDataElements describing the implementation of "RP runnable disabler flag" and "stimulation enabler flag" The possible roles of the RoleBasedMcData Assignment.role attribute are: • RpRunnableDisablerFlag **Tags:** atp.Splitkey=mcDataAssignment
rptEventId	PositiveInteger	0..1	attr	RPT event id used for service points call.
rptExecutable EntityProperties	RptExecutableEntity Properties	0..1	aggr	Describes the implemented code preparation for rapid prototyping at ExecutableEntity invocation. **Tags:** atp.Splitkey=rptExecutableEntityProperties atp.Status=obsolete
rptImplPolicy	RptImplPolicy	0..1	aggr	Describes the RptImplPolicy of a RptExecutableEvent for service based bypassing. **Tags:** atp.Splitkey=rptImplPolicy atp.Status=obsolete
rptServicePoint Post	RptServicePoint	*	ref	This describes the applicable Post Service Points for a RTEEvent / BswEvent of a bypassed ExecutableEntity. **Tags:** atp.Splitkey=rptServicePointPost
rptServicePoint Pre	RptServicePoint	*	ref	This describes the applicable Pre Service Points for a RTEEvent / BswEvent of a bypassed ExecutableEntity. **Tags:** atp.Splitkey=rptServicePointPre

Table 9.17: RptExecutableEntityEvent

[constr_10355] Existence of the reference in the role `RptExecutableEntityEvent.executionContext`

Imposition time: `IT_BswMD`

⌈For each `RptExecutableEntityEvent`, the reference in the role `executionContext` shall exist at least once.⌋

[constr_10356] Existence of attribute `RptExecutableEntityEvent.rptEventId`

Imposition time: `IT_BswMD`

⌈For each `RptExecutableEntityEvent`, the attribute `rptEventId` shall exist.⌋

[constr_10357] Existence of attribute `RptExecutableEntityEvent.rptExecutableEntityProperties`

Imposition time: `IT_BswMD`

⌈For each `RptExecutableEntityEvent`, the attribute `rptExecutableEntityProperties` shall exist.⌋

[constr_10358] Existence of the reference in the role RptExecutableEntityEvent.rptServicePointPost

Imposition time: IT_BswMD

⌈For each RptExecutableEntityEvent, the reference in the role rptServicePointPost shall exist at least once.⌋

[constr_10359] Existence of the reference in the role RptExecutableEntityEvent.rptServicePointPre

Imposition time: IT_BswMD

⌈For each RptExecutableEntityEvent, the reference in the role rptServicePointPre shall exist at least once.⌋

Class	**RptImplPolicy**			
Note	Describes the code preparation for rapid prototyping at data accesses. **Tags:** atp.Status=obsolete			
Base	*ARObject*			
Aggregated by	McDataInstance.rptImplPolicy, RptComponent.rpImplPolicy, RptContainer.rptImplPolicy, RptExecutableEntityEvent.rptImplPolicy			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
rptEnablerImplType	RptEnablerImplTypeEnum	0..1	attr	For Level 2 or Level3 this property determines how the RTE implements the additional "RP enabler" flag. **Tags:** atp.Status=obsolete
rptPreparationLevel	RptPreparationEnum	0..1	attr	Mandates RP preparation level for access to VariableDataPrototype within generated RTE implementation. **Tags:** atp.Status=obsolete

Table 9.18: RptImplPolicy

Enumeration	**RptEnablerImplTypeEnum**
Note	Describes the required / implemented usage of enabler flags for data access in the code. **Tags:** atp.Status=obsolete
Aggregated by	RptImplPolicy.rptEnablerImplType, RptProfile.stimEnabler
Literal	***Description***
none	No "RP enabler“ is implemented. **Tags:** atp.EnumerationLiteralIndex=0 atp.Status=obsolete
rptEnablerRam	"RP enabler“ is implemented as a RAM variable **Tags:** atp.EnumerationLiteralIndex=1 atp.Status=obsolete
rptEnablerRamAndRom	The RTE generator implements both the RAM and ROM "RP enabler“. **Tags:** atp.EnumerationLiteralIndex=3 atp.Status=obsolete

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Enumeration	**RptEnablerImplTypeEnum**
rptEnablerRom	"RP enabler“ is implemented as a calibrateable ROM variable. **Tags:** atp.EnumerationLiteralIndex=2 atp.Status=obsolete

Table 9.19: RptEnablerImplTypeEnum

Enumeration	**RptPreparationEnum**
Note	Determines the RP preparation level for access to VariableDataPrototypes within the generated RTE implementation. **Tags:** atp.Status=obsolete
Aggregated by	RptImplPolicy.rptPreparationLevel
Literal	*Description*
none	No RP preparation for VariableDataPrototype. **Tags:** atp.EnumerationLiteralIndex=0 atp.Status=obsolete
rptLevel1	The RTE implementation uses an "RP global buffer" for measurement and post-build hooking purposes. **Tags:** atp.EnumerationLiteralIndex=1 atp.Status=obsolete
rptLevel2	As rpLevel1 but the RTE implementation also uses both "RP enabler flag" to permit RP overwrite at run-time. **Tags:** atp.EnumerationLiteralIndex=2 atp.Status=obsolete
rptLevel3	As rpLevel2 but the RTE implementation also uses "RP global measurement buffer" to record the original ECU-generated value in addition to the RP value. **Tags:** atp.EnumerationLiteralIndex=3 atp.Status=obsolete

Table 9.20: RptPreparationEnum

Class	**RptExecutableEntityProperties**			
Note	Describes the code preparation for rapid prototyping at ExecutableEntity invocation. **Tags:** atp.Status=obsolete			
Base	*ARObject*			
Aggregated by	RptContainer.rptExecutableEntityProperties, RptExecutableEntityEvent.rptExecutableEntityProperties			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
maxRptEventId	PositiveInteger	0..1	attr	Highest RPT event id usable for RTE generated service points. This attribute is relevant, if dedicated id range shall be applied to the ExecutableEntitys of a software component or specific ExecutableEntitys. **Tags:** atp.Status=obsolete

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Class	**RptExecutableEntityProperties**			
minRptEventId	PositiveInteger	0..1	attr	Lowest RPT event id usable for RTE generated service points. This attribute is relevant, if dedicated id range shall be applied to the ExecutableEntitys of a software component or specific ExecutableEntitys. **Tags:** atp.Status=obsolete
rptExecution Control	RptExecutionControl Enum	0..1	attr	This attribute specifies the rapid prototyping control of the executable **Tags:** atp.Status=obsolete
rptServicePoint	RptServicePointEnum	0..1	attr	Enables generation of service points by the RTE generator. **Tags:** atp.Status=obsolete

Table 9.21: RptExecutableEntityProperties

Enumeration	**RptExecutionControlEnum**
Note	Determines rapid prototyping preparation of an ExecutableEntity. **Tags:** atp.Status=obsolete
Aggregated by	RptExecutableEntityProperties.rptExecutionControl
Literal	*Description*
conditional	The ExecutableEntity is only executed when the rapid prototyping disable flag is NOT set. **Tags:** atp.EnumerationLiteralIndex=0 atp.Status=obsolete
none	The ExecutableEntity is executed without specific rapid prototyping condition. **Tags:** atp.EnumerationLiteralIndex=1 atp.Status=obsolete

Table 9.22: RptExecutionControlEnum

Enumeration	**RptServicePointEnum**
Note	Specifies whether the invocation of ExecutableEntitys due to activation of specific RteEvents/Bsw Events requires the insertion of Service Points. **Tags:** atp.Status=obsolete
Aggregated by	RptExecutableEntityProperties.rptServicePoint
Literal	*Description*
enabled	Enables generation of service points by the RTE generator. **Tags:** atp.EnumerationLiteralIndex=0 atp.Status=obsolete
none	No Service Points are requested. **Tags:** atp.EnumerationLiteralIndex=1 atp.Status=obsolete

Table 9.23: RptServicePointEnum

9.7.2 Differentiation of execution contexts

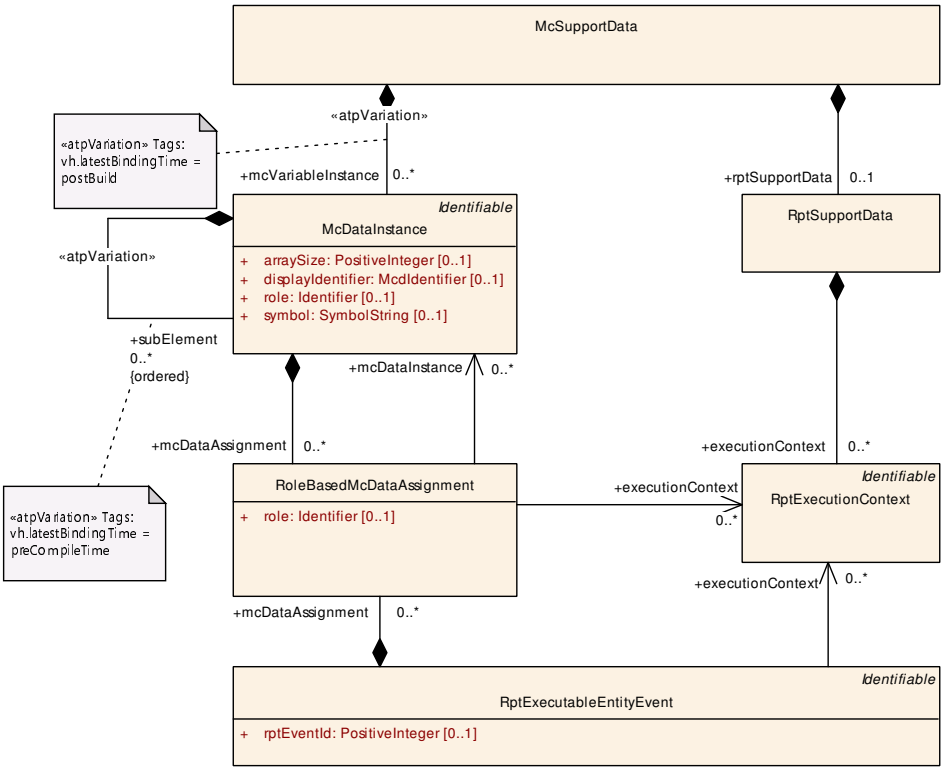

Figure 9.9: Meta-model for `RptExecutionContext`

[TPS_BSWMDT_04163] `RptExecutionContext` represents a common environment for a set of `RptExecutableEntity`s or `McDataInstance`s ⌈The `RptExecutionContext` represents a common environment for a set of `RptExecutableEntity`s or `McDataInstance`s. This common environment is qualified by the identical `OSTask` context and a identical set of implicit communication buffers.⌋

Class	**RptExecutionContext**			
Note	Defines an environment for the execution of ExecutableEntites which is qualified by • OSTask • communication buffer usage			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	RptSupportData.executionContext			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 9.24: RptExecutionContext

With the means of `RptExecutionContext`s its possible to denote the temporary validity of `McDataInstance`s describing implicit communication buffers. This is important if the identical implicit communication buffer is reused during a sequence of `RunnableEntity`s. In this case the `McDataInstance`s describing implicit communication buffers holds the value of different global buffers at different point of times.

For example the same OSTask can be split into several sub-sequences where the usage of the implicit communication buffers changes between the sub-sequences. This is the case when the content of the implicit buffer (previously used by a RunnableEntity) is written back to the global buffer and after wards fill by the value of an other global buffer in order to be used by a successor RunnableEntity.

Please note that the validity of RptExecutionContexts can even overlap (with respect to execution time) since not necessarily the whole implicit communication buffers set used for sub-sequence in a OSTask changes at such a point.

[TPS_BSWMDT_04164] Description of implicit communication buffers ⌈The McDataInstance describing a implicit communication buffers shall reference the McDataInstance describing the global buffer with a RoleBasedMcDataAssignment where the role attribute is set to ImplicitBuffer.⌋

Enumeration	**RptAccessEnum**
Note	Determines the access rights to a data object with respect to rapid prototyping. **Tags:** atp.Status=obsolete
Aggregated by	RptSwPrototypingAccess.rptHookAccess, RptSwPrototypingAccess.rptReadAccess, RptSw PrototypingAccess.rptWriteAccess
Literal	***Description***
enabled	The related data element is accessible by RP tool. **Tags:** atp.EnumerationLiteralIndex=0 atp.Status=obsolete
none	The related data element is not accessible by RP tool. **Tags:** atp.EnumerationLiteralIndex=1 atp.Status=obsolete
protected	The data element is known to the RP tool however its usage for RP can be restricted. Use case: limitation based on access rights **Tags:** atp.EnumerationLiteralIndex=2 atp.Status=obsolete

Table 9.25: RptAccessEnum

Class	**RptServicePoint**			
Note	Description of a Service Point implemented for rapid prototyping.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	RptSupportData.rptServicePoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
serviceId	PositiveInteger	0..1	attr	Unique ID (Range: 0 ... 65535) representing the service point.
symbol	CIdentifier	0..1	attr	Complete symbol of the function implementing the service point. This symbol is used for post-build hooking purposes.

Table 9.26: RptServicePoint

[constr_10360] Existence of attribute `RptServicePoint.serviceId`

Imposition time: `IT_BswMD`

⌈For each `RptServicePoint`, the attribute `serviceId` shall exist.⌋

[constr_10330] Existence of attribute `RptServicePoint.symbol`

Imposition time: `IT_BswMD`

⌈For each `RptServicePoint`, the attribute `symbol` shall exist.⌋

The following examples illustrate the usage of the `McDataInstance`s and the `RoleBasedMcDataAssignment`s with the `role` attribute values according [TPS_BSWMDT_04159] to describe the different locations in memory with their relationships and specific meaning for an rapid prototyping tooling.

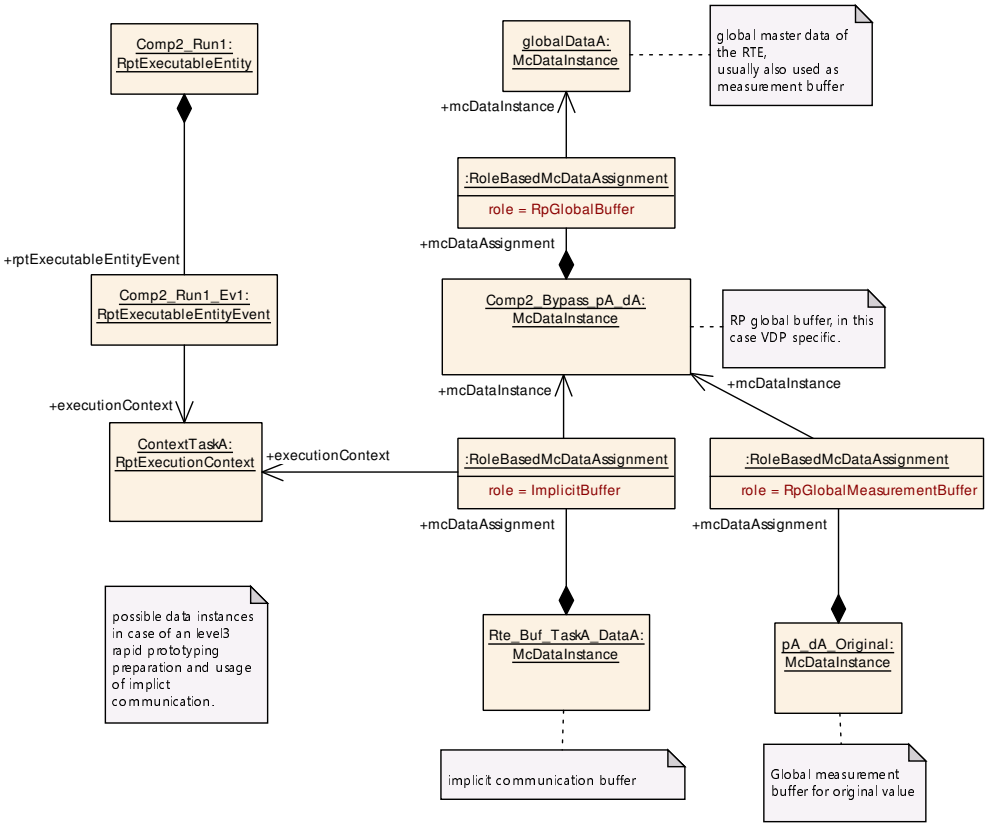

Figure 9.10: Example about Level3 RPT support implementation

Figure 9.10 shows the description of the rapid prototyping support created for the `RunnableEntity` "`Comp2_Run1`" which had original a `dataReadAccess` and a `dataWriteAccess` to `dataElement` "`dA`" in `PRPortPrototype` "`pA`".

The requested rapid prototype support was `rptLevel3`.

For the communication of the data value to other components the RTE implements the variable "`globalDataA`" and describes it as `McDataInstance`. Typically this is also the normal buffer used for measurement.

The RunnableEntity is described by RptExecutableEntity Comp2_Run1 and this references the McDataInstance "globalDataA" in the roles rptRead and rptWrite to document the dataReadAccess and dataWriteAccess of the original RunnableEntity.

The access for the rapid prototype tooling is provided by the RP global buffer "Comp2_Bypass_pA_dA" which his as well described as McDataInstance referencing the McDataInstance "globalDataA" with the RoleBasedMcDataAssignment.role = RptGlobalBuffer.

In this example the RTE uses distinct implicit communication buffers and the according buffer is described as well by an McDataInstance "Rte_Buf_TaskA_DataA" with the RoleBasedMcDataAssignment.role = ImplicitBuffer to indicate that this buffer the RP global buffer.

For the rptLevel3 support it's required that the RTE provides an additional location in memory, where the original value produced by the RunnableEntity can be accessed. This RP global measurement buffer is described by a McDataInstance pA_dA_Original and linked by RoleBasedMcDataAssignment.role = RpGlobalMeasurementBuffer to the RP global buffer.

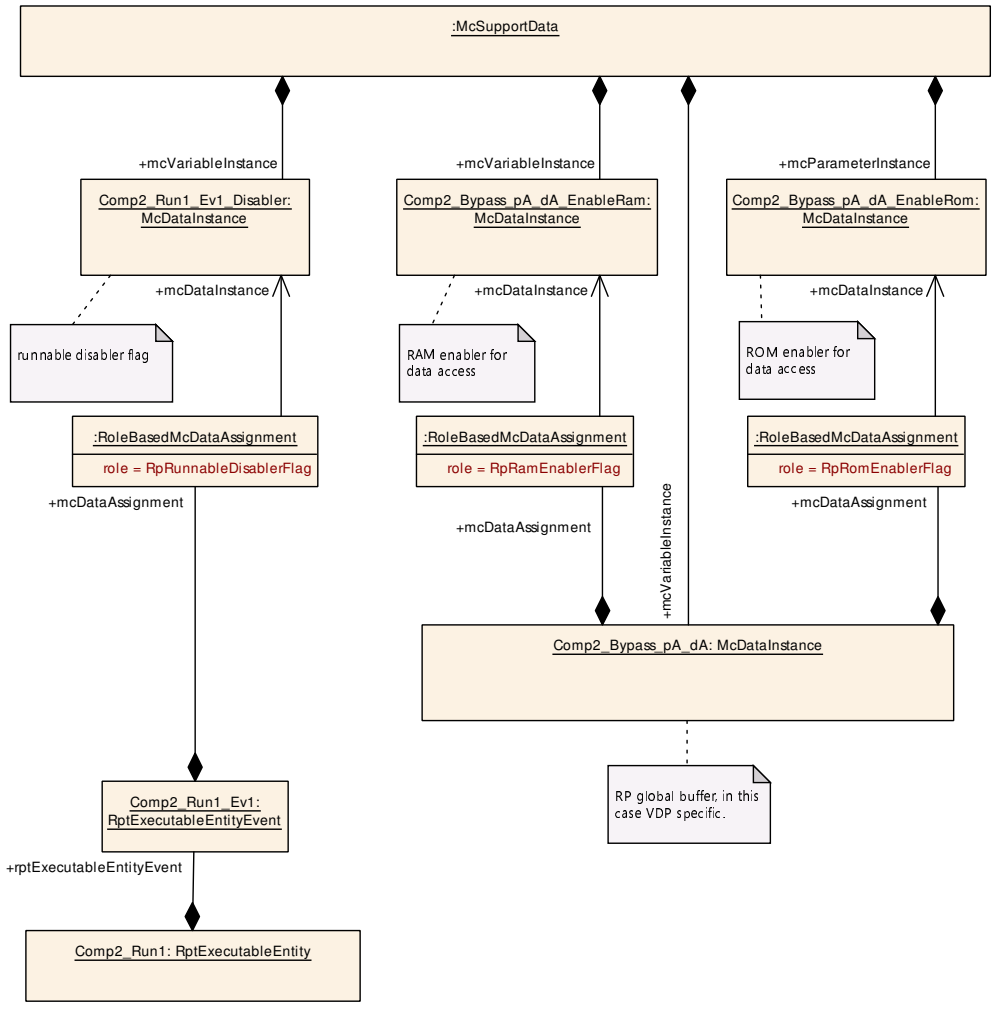

Figure 9.11: Example about Level3 enabler

Figure 9.11 shows the according enabler flags required for the `rptLevel3` rapid prototyping support.

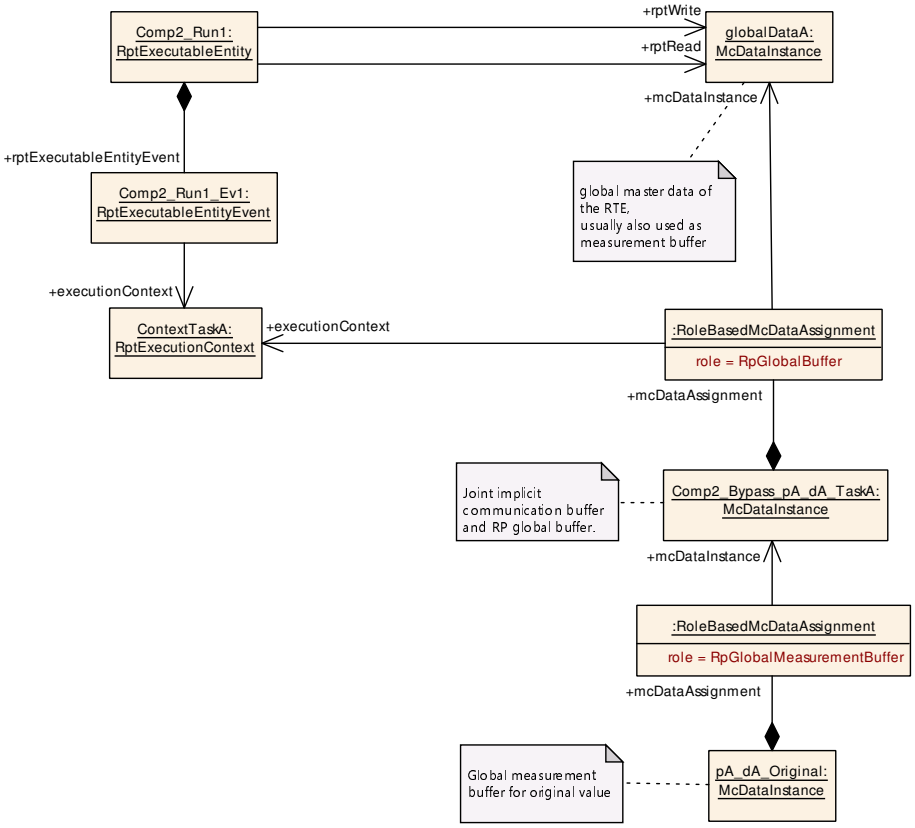

Figure 9.12: Example about optimized RPT support implementation

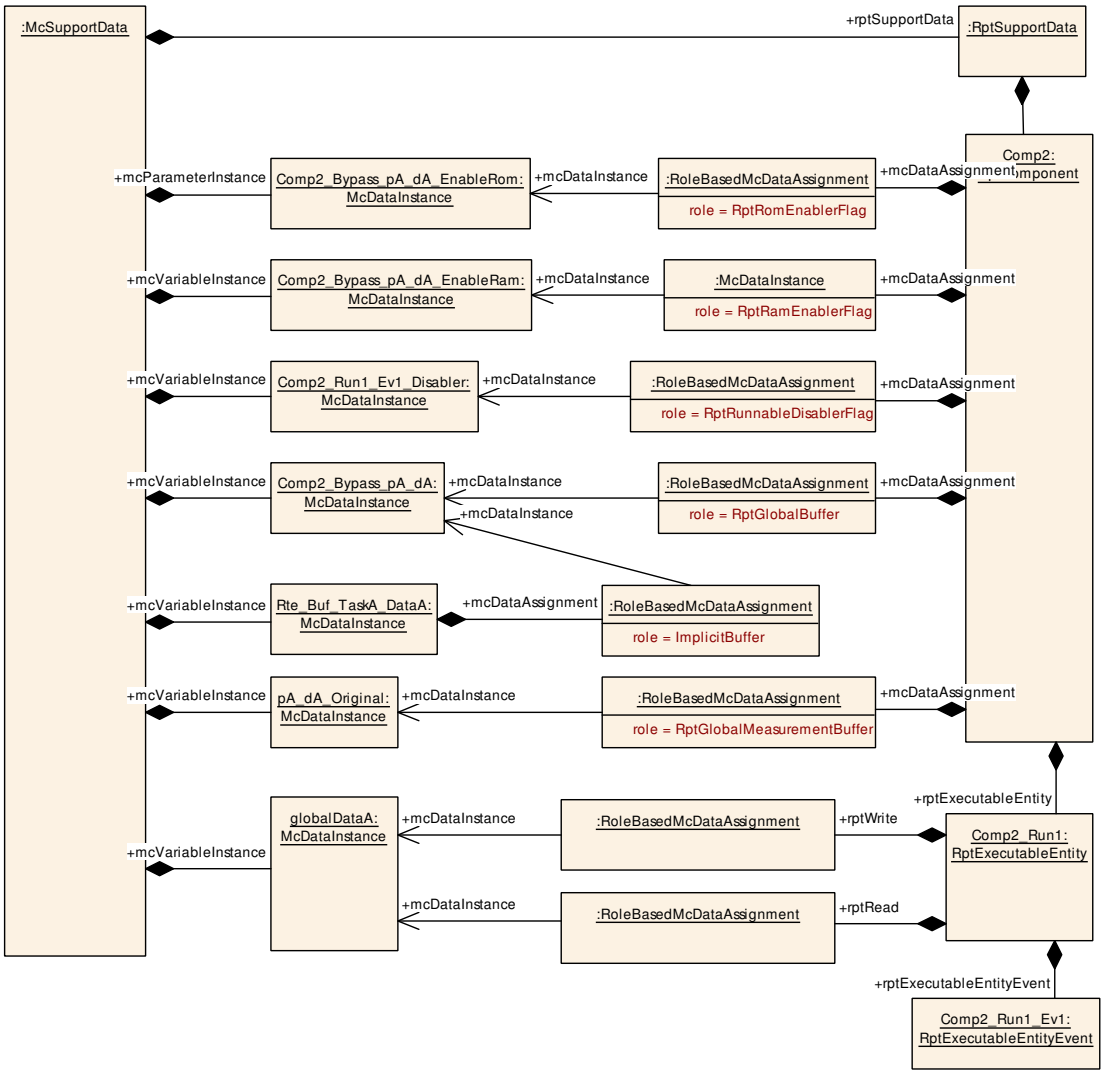

Figure 9.13: Example about RptComponent usage

10 BSW Variant Handling

The BSWMDT includes variation points which allow to describe a set of variants of a BSW module or cluster by a single XML artifact (for general information on variant handling in AUTOSAR see [1]).

Variation points are provided at all three levels of the template.

10.1 BSW Interface Variation Points

[TPS_BSWMDT_04063] BSW Interface Variation Points ⌈The variation points in the scope of `BswModuleDescription` with `latestBindingTime` = `preCompileTime` allow to declare variable sets of optional documentation, communication interfaces, dependencies, triggers and mode groups as part of one BSW module description. Further variation points in this hierarchy with can be bound at compile-time are not allowed in order to keep the meta-model and the resulting M1 models maintainable.⌋

For detail refer to figures 10.1 and 10.2.

If for example one wants to specify two variants of a module which handles a certain C-function argument either as a 16 bit or as a 32 bit type respectively and this needs to be bound at compile-time, this is possible by variation of the associations to `BswModuleEntry`, but is is not possible to declare a single `BswModuleEntry` with two compile-time variants just for a single argument.

However, at an earlier stage of development it is possible to include this kind of additional variability into `Blueprint`s of `BswModuleEntry`-s (see [8]). This is especially useful if a BSWMD is used to represent an SWS of the AUTOSAR standard, since interfaces are specified here on the level of `Blueprint`s, i.e. they still contain optional or alternative function arguments:

[TPS_BSWMDT_04090] Variation Points for `BswModuleEntry` arguments ⌈It is possible to declare a `BswModuleEntry.argument` as a variation point but its binding time shall not be later than `blueprintDerivationTime`.⌋

See figure 10.1.

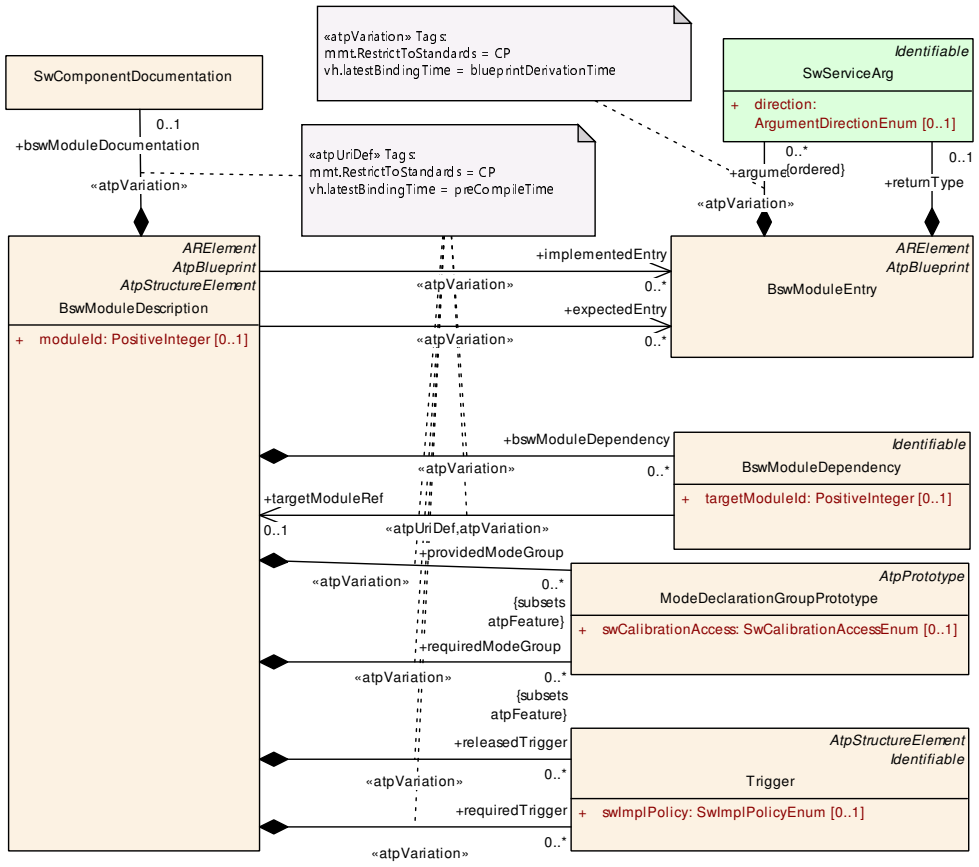

Figure 10.1: Variation points under `BswModuleDescription`, Part 1

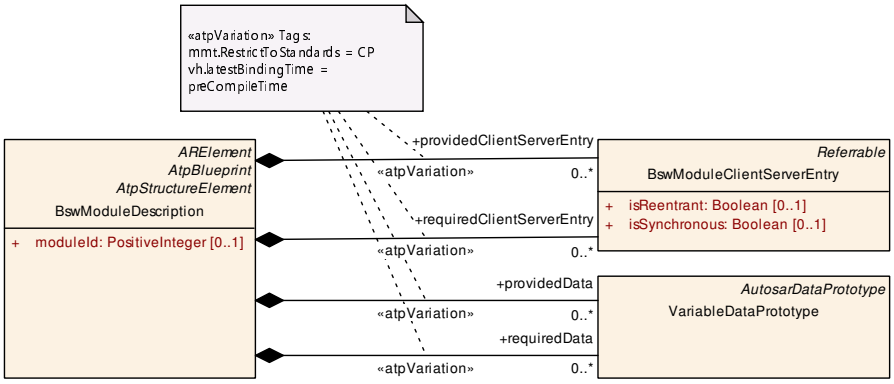

Figure 10.2: Variation points under `BswModuleDescription`, Part 2

One use case is to maintain a specification which includes optional or alternative interfaces/dependencies for a module at design time. For example, as already mentioned above, it is possible to provide one BSWMD (as an XML artifact) which describes the AUTOSAR standard for the C-interfaces of a standardized AUTOSAR module including specification of the optional parts as variants. These variants will be selected in the BSWMD of a module which is actually implemented against such a specification.

Another use case is to deliver a BSWMD still including some variation points to the integrator, which means in this case the variants will be selected by the integrator.

Since most of the variation points described in this section influence the executable code, this use case requires that the relevant parts of the code are regenerated and/or recompiled at integration time. Due to this reason, the latest possible binding time of most variation points described here is set to to `preCompileTime`.

The second use case may require that the actual selection of a variation point will constraint the ECU configuration parameter values of the module (for example, if a configuration parameter configures the existence/non-existence of a callback function this will be constrained by deselecting a variant of the attributes `expectedEntry` or `implementedEntry`). This could simply be done by delivering sets of preconfigured parameter values which obey to the same variant conditions as the corresponding elements referred/aggregated by `BswModuleDescription`. However, a more elegant solution will be to derive the parameter definition in question “automatically” (i.e. via its definition) from the condition which is implicitly defined in the M1 model with each variant selection (see [1]).

10.2 BSW Behavior Variation Points

[TPS_BSWMDT_04064] BSW Behavior Variation Points ⌈In a similar way, variation points underneath `BswInternalBehavior` allow to declare variants in the aggregation of `BswModuleEntity`-s, `BswEvent`s and further elements.

Likewise, several references and aggregations owned by `BswModuleEntity` are variation points. There is Variation point in the aggregation of local data for calibration and measurement and of `ExclusiveArea` by the base class `InternalBehavior` too.⌋

For more details on Variation Points see figure 10.4 and figure 10.3.

The use cases are similar to the ones described above (chapter 10.1). For the same reasons, the latest possible binding time for these variation points is defined as `preCompileTime`.

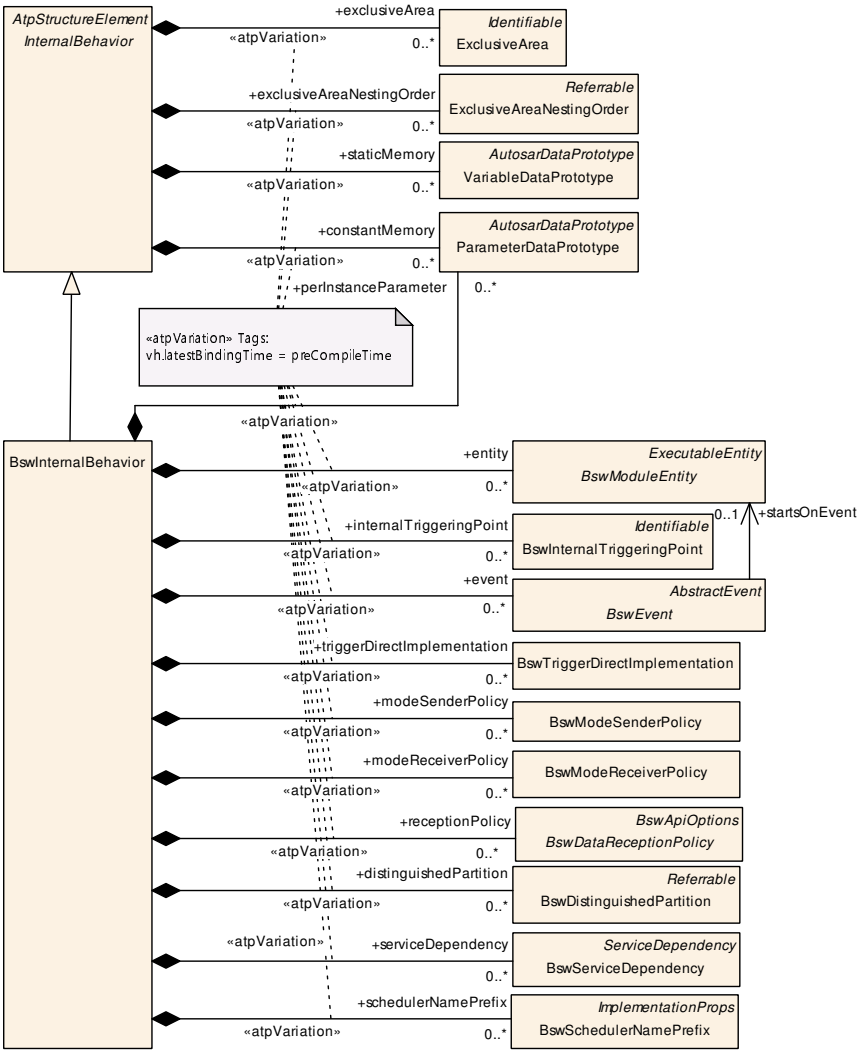

Figure 10.3: Variation points under `BswInternalBehavior`

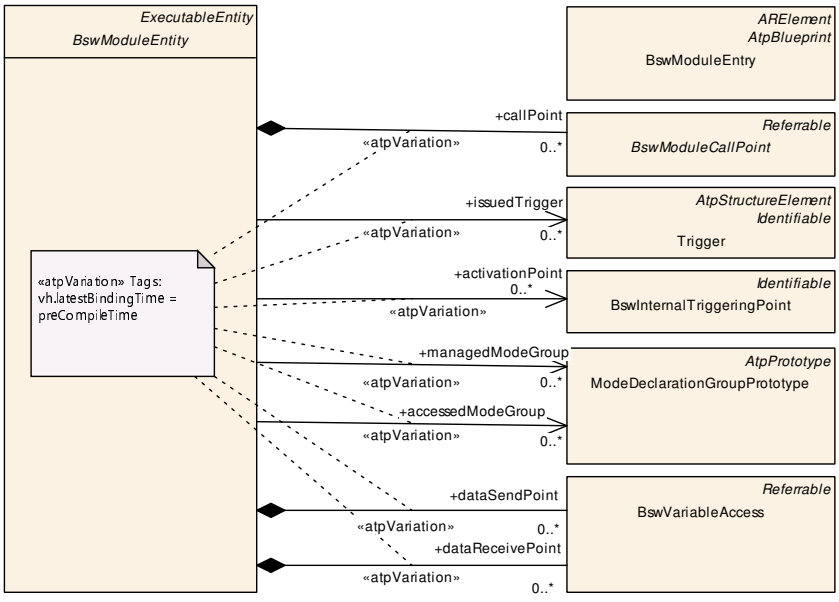

Figure 10.4: Variation points under `BswModuleEntity`

10.3 BSW Implementation Variation Points

[TPS_BSWMDT_04065] BSW Implementation Variation Points ⌈There are several variation points in the base class `Implementation` and the elements aggregated from there. They are usable for BSW and SWC descriptions as well. They all support the use case, that a module or component is delivered as source code leading to several implementation variants.

Furthermore, if an Implementation contains `McSupportData`, these can also have variation points.⌋

Variation points in the base class `Implementation` and the elements aggregated from there are visible in the respective figures of chapter 7. Figure 10.5 shows the only variation point below `BswImplementation`.
Chapter 9.1 gives an explanation for implementation containing `McSupportData`.

The associations to `vendorSpecificModuleDef` and `preconfiguredConfiguration` are not considered as variation points, since they correspond to artifacts which are supposed to be fixed at the time a module is delivered. Also `recommendedConfiguration` corresponds to a fixed set of artifacts at delivery time.

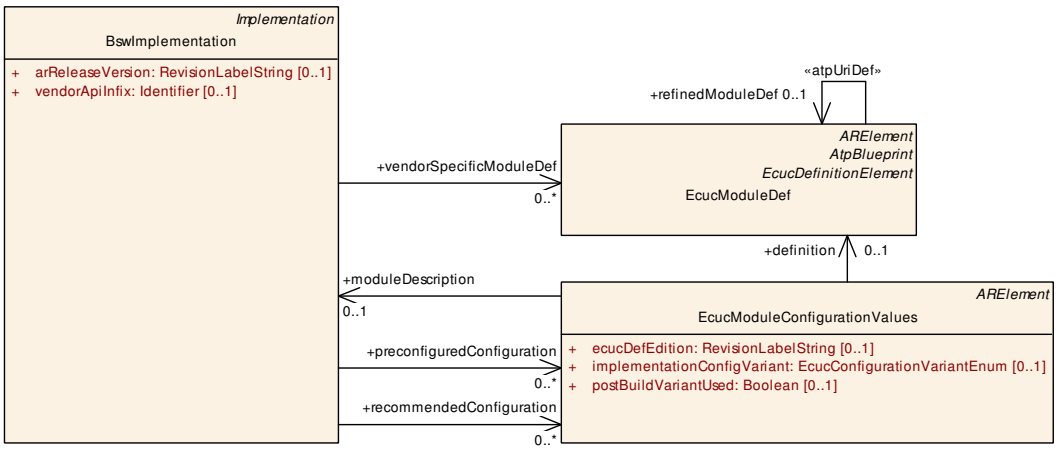

Figure 10.5: Variation points under `BswImplementation`

11 BSW Service Needs

11.1 Overview

The mechanism of so-called Service Dependencies and Service Needs is used by Software Components above the RTE to express their needs on the configuration of AUTOSAR Services. The same mechanism can be used also in the basic software in order to have a uniform approach, if an AUTOSAR Service has to be configured per ECU for the needs of both BSW and SWCs.

Figure 11.1 shows the various meta-classes which can be used on the behavior level of BSW modules and SWCs in order to express these dependencies.

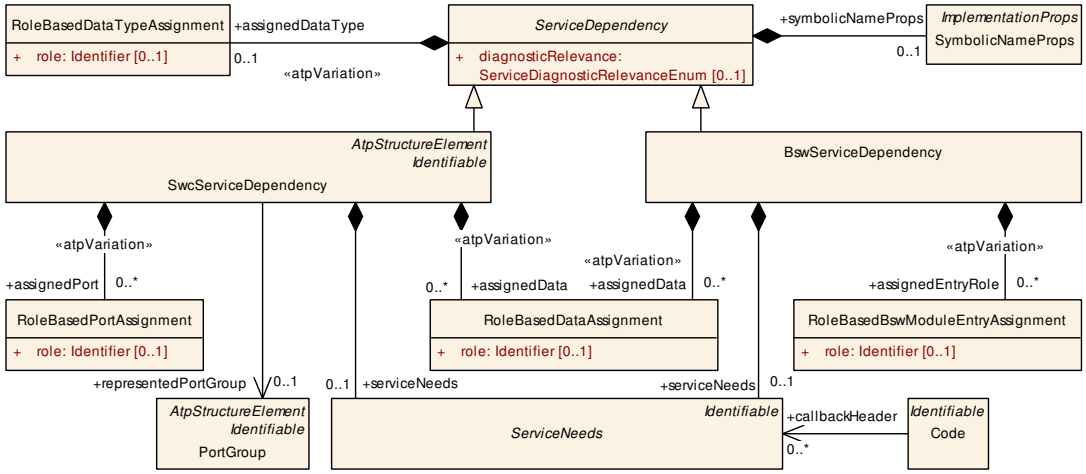

Figure 11.1: Concept of `ServiceDependency` for BSW and SWC

[TPS_BSWMDT_04029] Usage of `BswServiceDependency` ⌈There is a set of `BswServiceDependency`-s that represents the requirements of the module or cluster on the configuration of AUTOSAR Services like NVRAM Manager or Watchdog Manager. These requirements include not only the specific `ServiceNeeds` attributes, but can optionally include references to local data (for example to declare RAM mirror or ROM default data for the NVRAM Manager) or to `BswModuleEntry`-s (for example to declare which expected callbacks belong to a specific NvM block).⌋

The set of `BswServiceDependency`-s are shown in figure 11.2.

Further explanation could be found in the class tables below.

[TPS_BSWMDT_04127] Callback header declarations ⌈When a service configures callback functions the header files providing the callback function declarations needs to be identified. The reference `callbackHeader` describes in which header files the function declarations of callback functions are provided for the AUTOSAR service implementing the `ServiceNeeds`.⌋

[constr_4089] Association `callbackHeader` is only applicable for BSW modules

Imposition time: IT_BswMD

⌈The reference Code.callbackHeader is only allowed to be used if the Code is aggregated by a BswImplementation in the role codeDescriptor.⌋

[constr_4090] The `callbackHeader` reference has to be consistent with behavior reference

Imposition time: IT_BswMD

⌈The reference Code.callbackHeader is only allowed to reference ServiceNeeds in the context of the BswServiceDependency that in turn is aggregated by a BswImplementation via BswInternalBehavior that is owning the Code in the role codeDescriptor.⌋

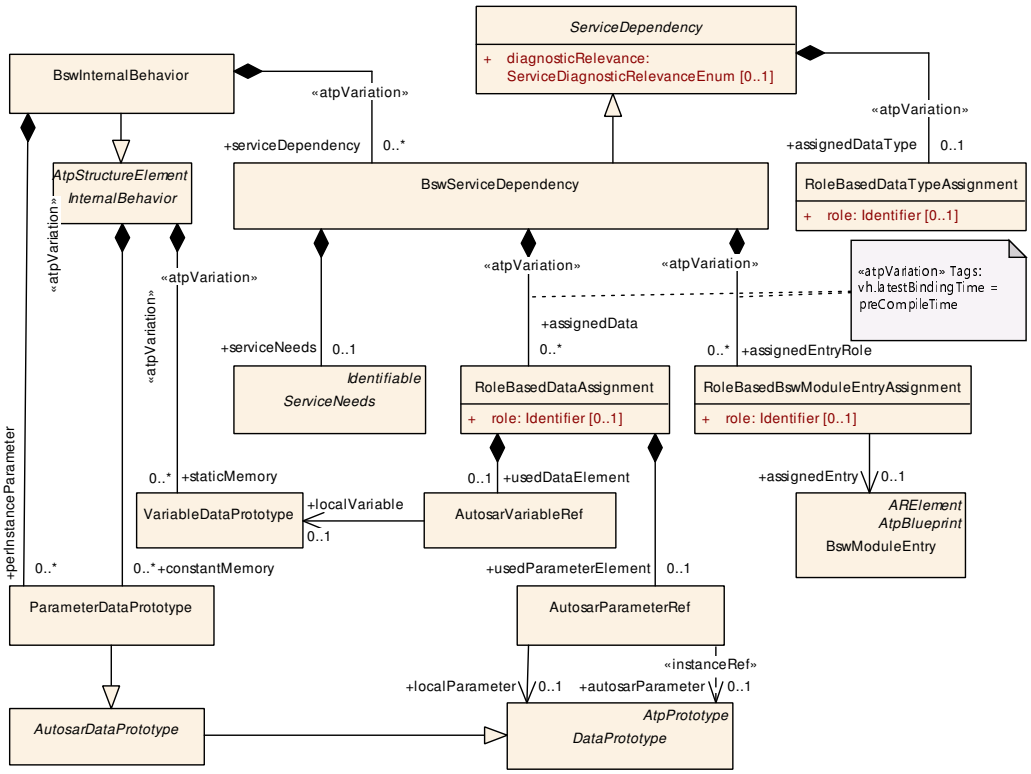

Figure 11.2: `BswServiceDependency` attached to a `BswInternalBehavior`

Class	***ServiceDependency*** (abstract)
Note	Collects all dependencies of a software module or component on an AUTOSAR Service related to a specific item (e.g. an NVRAM Block, a diagnostic event etc.). It defines the quality of service (Service Needs) of this item as well as (optionally) references to additional elements. This information is required for tools in order to generate the related basic software configuration and ServiceSwComponentTypes.
Base	*ARObject*
Subclasses	BswServiceDependency, SwcServiceDependency

△

Class	***ServiceDependency*** (abstract)			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
assignedData Type	RoleBasedDataType Assignment	0..1	aggr	This is the role of the assignment data type in the given context. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=assignedDataType, assignedData Type.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
diagnostic Relevance	ServiceDiagnostic RelevanceEnum	0..1	attr	If this attribute indicates a relevance for diagnostics then the integrator has a much easier time identifying the candidates for the configuration of the diagnostic stack. Example: identification of mode conditions (e.g. communication between application and BswM) relevant for the Dcm.
symbolicName Props	SymbolicNameProps	0..1	aggr	This attribute can be taken to contribute to the creation of symbolic name values. **Tags:** atp.Splitkey=symbolicNameProps, symbolicName Props.shortName

Table 11.1: ServiceDependency

Class	**BswServiceDependency**			
Note	Specialization of ServiceDependency in the context of an BswInternalBehavior. It allows to associate BswModuleEntries and data defined for a BSW module or cluster to a given ServiceNeeds element.			
Base	*ARObject*, *ServiceDependency*			
Aggregated by	BswInternalBehavior.serviceDependency			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
assignedData	RoleBasedData Assignment	*	aggr	Defines the role of an associated data object (owned by this module or cluster) in the context of the ServiceNeeds element. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=assignedData, assignedData.variation Point.shortLabel vh.latestBindingTime=preCompileTime
assignedEntry Role	RoleBasedBswModule EntryAssignment	*	aggr	Defines the role of an associated BswModuleEntry in the context of the ServiceNeeds element. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=assignedEntryRole, assignedEntry Role.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
ident	BswService DependencyIdent	0..1	aggr	This adds the ability to become referrable to BswService Dependency. **Stereotypes:** atpIdentityContributor **Tags:** xml.sequenceOffset=-100
serviceNeeds	ServiceNeeds	0..1	aggr	The associated ServiceNeeds. **Tags:** atp.Splitkey=serviceNeeds, serviceNeeds.short Name

Table 11.2: BswServiceDependency

[constr_10257] Existence of attribute BswServiceDependency.serviceNeeds

Imposition time: IT_BswMD

⌈For each BswServiceDependency, the attribute serviceNeeds shall exist.⌋

Class	**RoleBasedBswModuleEntryAssignment**			
Note	This class specifies an assignment of a role to a particular BswModuleEntry (usually a configurable callback). With this assignment, the role of the callback is mapped to a specific ServiceNeeds element, so that a tool is able to create appropriate configuration values for the module that implements the AUTOSAR Service.			
Base	*ARObject*			
Aggregated by	BswServiceDependency.assignedEntryRole			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
assignedEntry	BswModuleEntry	0..1	ref	The assigned entry. It should be an implementedEntry or expectedEntry of the module or cluster that requires the ServiceNeeds. **Tags:** atp.Splitkey=assignedEntry This Attribute is only used by the AUTOSAR Classic Platform.
role	Identifier	0..1	attr	This is the role of the assigned BswModuleEntry in the given context. The attribute is required (for example) because different kind of callbacks may be associated with the same ServiceNeeds (e.g. end-notification vs. error-notification). The value shall be the role name of a configurable function call (usually a callback) as standardized in the Software Specification of the related AUTOSAR Service.

Table 11.3: RoleBasedBswModuleEntryAssignment

[constr_10258] Existence of the reference in the role RoleBasedBswModuleEntryAssignment.assignedEntry

Imposition time: IT_BswMD

⌈For each RoleBasedBswModuleEntryAssignment, the reference in the role assignedEntry shall exist.⌋

[constr_10259] Existence of attribute RoleBasedBswModuleEntryAssignment.role

Imposition time: IT_BswMD

⌈For each RoleBasedBswModuleEntryAssignment, the attribute role shall exist.⌋

Class	**RoleBasedDataAssignment**			
Note	This class specifies an assignment of a role to a particular data object in either • the SwcInternalBehavior of a software component (or in the BswInternalBehavior of a BSW module or BSW cluster) in the context of an AUTOSAR Service or • an NvBlockDescriptor to sort out the assignment of event-based writing strategies to data elements in a PortPrototype. With this assignment, the role of the data can be mapped to a DataPrototype that is used in the context of the definition of a specific ServiceNeeds or NvBlockDescriptor, so that a tool is able to create the correct access or writing strategy.			
Base	*ARObject*			
Aggregated by	BswServiceDependency.assignedData, NvBlockDescriptor.writingStrategy, SwcService Dependency.assignedData			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
role	Identifier	0..1	attr	This is the role of the assigned data in the given context. Possible values need to be specified on M1 level. Additionally the TPS Software Component Template provides a list of applicable roles for various service dependencies and service use cases in chapter 13 "Service Dependencies and Service Use Cases" (e.g., ramBlock in case of the needs for a permanent RAM block).
usedData Element	AutosarVariableRef	0..1	aggr	The VariableDataPrototype used in this role, e.g. • Permanent RAM Block of an NVRAM Block which shall belong to the same SwcInternalBehavior or Bsw InternalBehavior. • In the role signalBasedDiagnostics it has to refer to a VariableDataPrototype in a SenderReceiverInterface or a NvDataInterface. **Tags:** atp.Splitkey=usedDataElement
usedParameter Element	AutosarParameterRef	0..1	aggr	The ParameterDataPrototype used in this role, e.g. • ROM Block of an NVRAM Block. It shall belong to the same SwcInternalBehavior or BswInternalbehavior. • In the role signalBasedDiagnostics it has to refer to a ParameterDataPrototype in a ParameterInterface. **Tags:** atp.Splitkey=usedParameterElement
usedPim	PerInstanceMemory	0..1	ref	The (untyped) PerInstanceMemory used in this role (e.g. as a Permanent RAM Block for an NVRAM Block). **Tags:** atp.Splitkey=usedPim

Table 11.4: RoleBasedDataAssignment

Class	**RoleBasedDataTypeAssignment**			
Note	This class specifies an assignment of a role to a particular data type of a software component (or in the BswModuleBehavior of a module or cluster) in the context of an AUTOSAR Service. With this assignment, the role of the data type can be mapped to a specific ServiceNeeds element, so that a tool is able to create the correct access.			
Base	*ARObject*			
Aggregated by	*ServiceDependency*.assignedDataType			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
role	Identifier	0..1	attr	This is the role of the associated data type in the given context.

▽

△

Class	RoleBasedDataTypeAssignment			
used Implementation DataType	ImplementationDataType	0..1	ref	This represents the associated ImplementationDataType. **Tags:** atp.Splitkey=usedImplementationDataType

Table 11.5: RoleBasedDataTypeAssignment

Class	*ServiceNeeds* (abstract)			
Note	This expresses the abstract needs that a Software Component or Basic Software Module has on the configuration of an AUTOSAR Service to which it will be connected. "Abstract needs" means that the model abstracts from the Configuration Parameters of the underlying Basic Software.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	BswMgrNeeds, ChargeManagerNeeds, ComMgrUserNeeds, CryptoKeyManagementNeeds, CryptoServiceJobNeeds, CryptoServiceNeeds, *DiagnosticCapabilityElement*, DltUserNeeds, *DoIpServiceNeeds*, EcuStateMgrUserNeeds, ErrorTracerNeeds, FunctionInhibitionAvailabilityNeeds, FunctionInhibitionNeeds, GeneralPurposeTimerServiceNeeds, GlobalSupervisionNeeds, IdsMgrCustomTimestampNeeds, IdsMgrNeeds, IndicatorStatusNeeds, J1939DcmDm19Support, J1939RmIncomingRequestServiceNeeds, J1939RmOutgoingRequestServiceNeeds, NvBlockNeeds, SecureOnBoardCommunicationNeeds, SupervisedEntityCheckpointNeeds, SupervisedEntityNeeds, SyncTimeBaseMgrUserNeeds, VendorSpecificServiceNeeds			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.6: ServiceNeeds

Note that several kinds of data assignments are restricted to be used within an SWC because they need RTE support:

RoleBasedDataTypeAssignment

This denotes the type of a temporary Ram Block and used internal data structure in case of explicit synchronization with NvMReadRamBlockFromNvM and NvMWriteRamBlockToNvM interface respectively. The type information can be used to calculate the NvBlock size and minimum Ram Mirror size.

- `temporaryRamBlock` [0..1]

[constr_4051] `RoleBasedDataAssignment` in BSW

Imposition time: `IT_BswMD`

⌈When used in the context of `BswServiceDependency`, the following restriction hold for date references described by `RoleBasedDataAssignment`:

- Within `RoleBasedDataAssignment.usedDataElement`, only the reference `AutosarVariableRef.localVariable` is applicable.
- Within `RoleBasedDataAssignment.usedParameterElement`, only the reference `AutosarParameterRef.localParameter` is applicable.
- The reference `RoleBasedDataAssignment.usedPim` shall not be set.

⌋

[TPS_BSWMDT_04113] Rule for setting RoleBasedBswModuleEntryAssignment.role ⌈The value of RoleBasedBswModuleEntryAssignment.role cannot arbitrarily set but shall to equal to the shortName of the applicable BswModuleEntry taken from the standardized AUTOSAR BswModuleEntry model (this implies that the category of the ARPackage that owns the BswModuleEntry is set to BLUEPRINT[1] and the top-most ARPackage.shortName is set to AUTOSAR, see also [20]).⌋

11.2 Specific Service Needs

The abstract meta-class ServiceNeeds and its more specific child classes are defined in the CommonStructure package of the meta-model. This class hierarchy is shown in the three figures (11.3, 11.4 and 11.5).

The subsequent tables show those specialized ServiceNeeds which are of interest for the basic software.

Note that several detailed meta-classes for diagnostic capabilities (derived from DiagnosticCapabilityElement) and for diagnostic over IP (derived from DoIpServiceNeeds) are not shown here, because they are mainly of interest for application software. For a detailed description of those refer to [5].

Note that the ServiceNeeds describes only the source data of an abstract dependency. How this is actually traced down to the configuration parameters is specified by the configuration parameters of the dependent modules itself. For a description of this mechanism see [TPS_ECUC_02047] under topic “Derived Parameter Definition” in [15]. To get the complete picture, it should be noted that also other templates can define source data for dependencies, for example the configuration of the COM stack depends on information defined via the AUTOSAR System Template.

This information as defined by AUTOSAR for standardized configuration parameters is also called “Upstream Mapping”. The Upstream Mapping relevant for BSWMDT is listed in this document in appendix F.

If a BSW module implements an AUTOSAR Service, it is possible that parts of its own ServiceNeeds are in turn influenced by the ServiceNeeds of the SWCs and BSW modules integrated on an ECU. In this case, the ServiceNeeds of that module shall be adjusted at ECU integration time before the initial ECU configuration is set up. For example, the NvBlockNeeds of the Diagnostic Event Manager will be determined in response to the number of diagnostic events on an ECU which are given by the DiagnosticEventNeeds of all integrated SWCs and BSW modules. Since parts of the XML-description of AUTOSAR Services (namely the SWC-part) are generated at integration time anyway, the adjustment of ServiceNeeds can be done in the same step.

[1] see [TPS_STDT_00033]

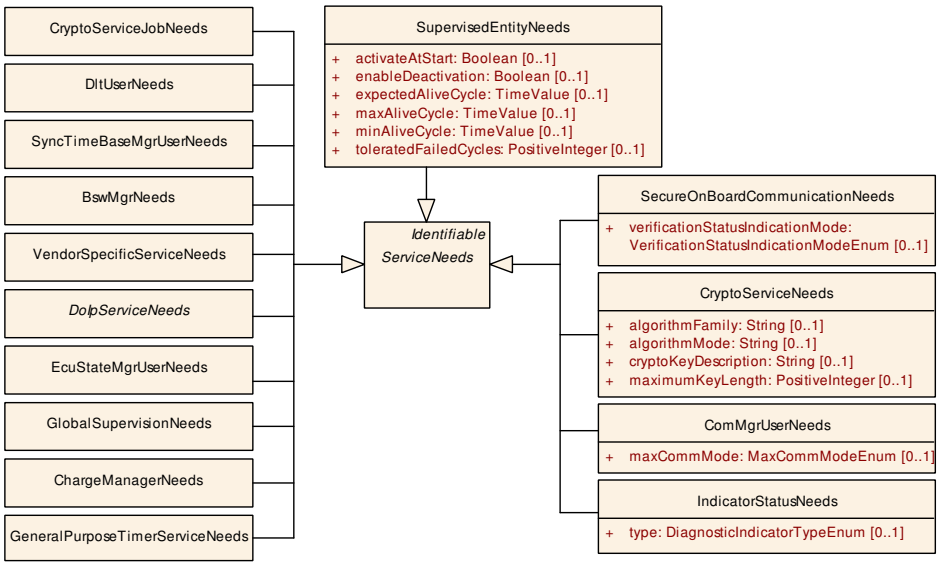

Figure 11.3: Class `ServiceNeeds` from `CommonStructure` and some derived classes

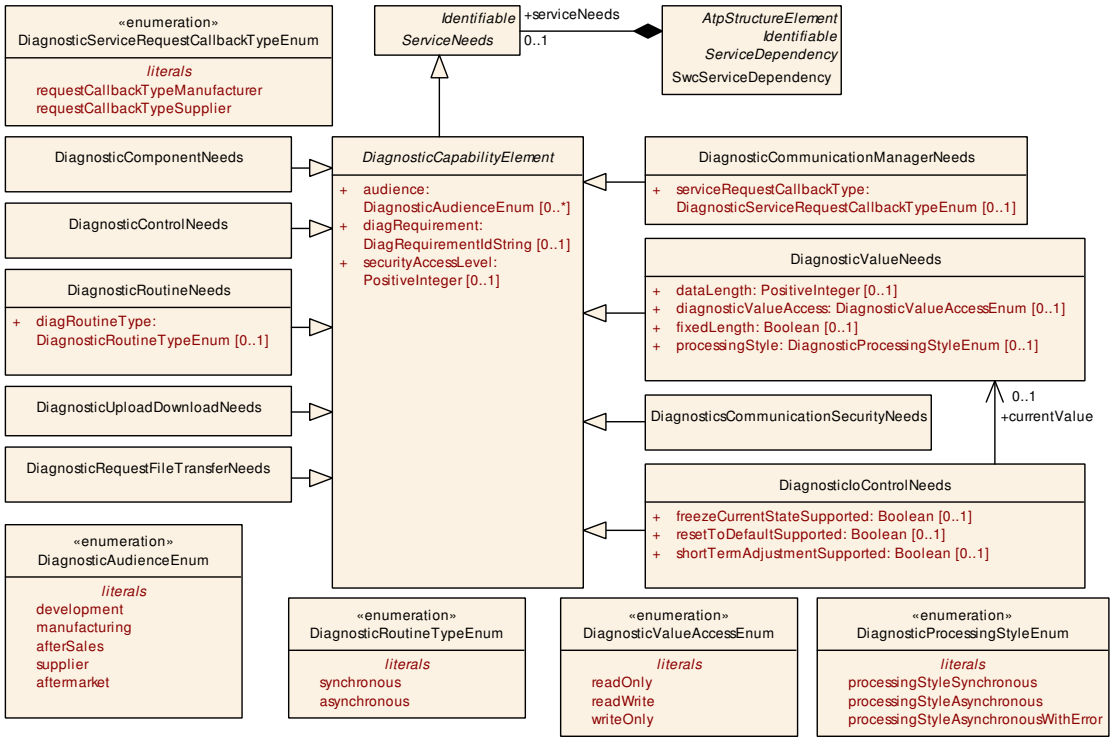

Figure 11.4: Class `ServiceNeeds` from `CommonStructure` and derived classes for diagnosis use cases

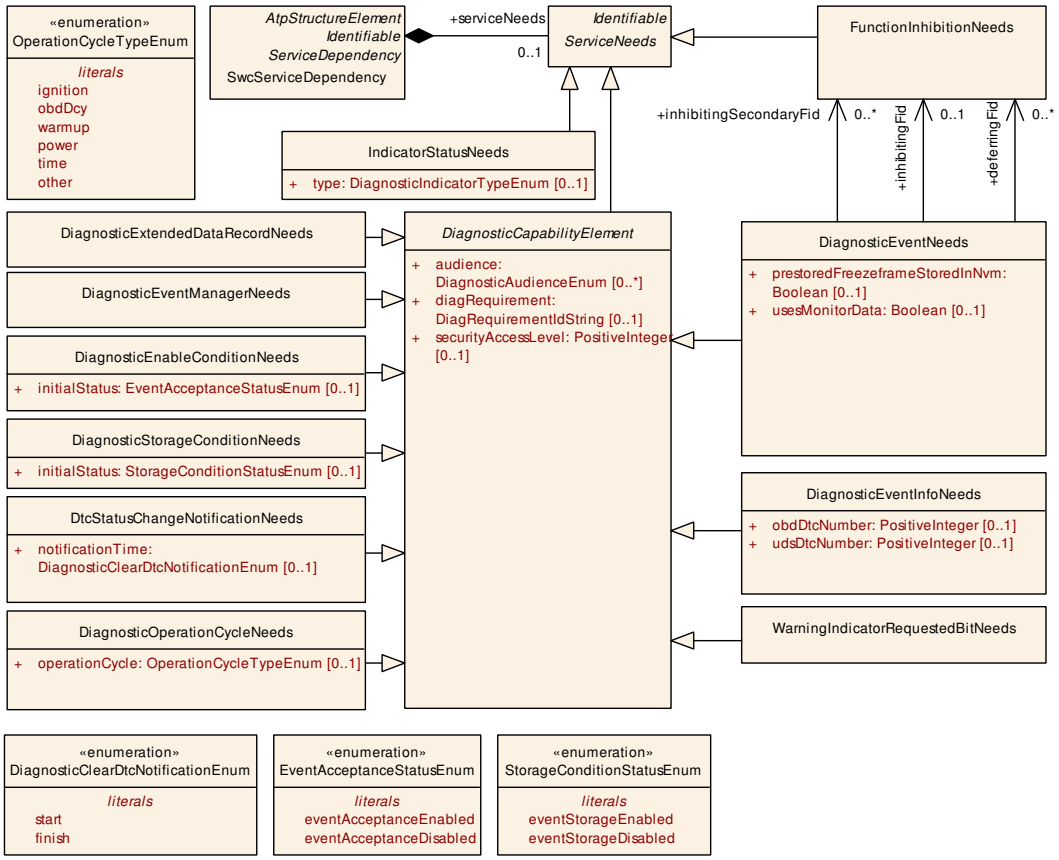

Figure 11.5: Class `ServiceNeeds` from `CommonStructure` and derived classes for diagnosis use cases

Class	**NvBlockNeeds**			
Note	Specifies the abstract needs on the configuration of a single NVRAM Block.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, NvBlockDescriptor.nvBlockNeeds, SwcService Dependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
calcRamBlock Crc	Boolean	0..1	attr	Defines if CRC (re)calculation for the permanent RAM Block is required.
checkStatic BlockId	Boolean	0..1	attr	Defines if the Static Block Id check shall be enabled.
cyclicWriting Period	TimeValue	0..1	attr	This represents the period for cyclic writing of NvData to store the associated RAM Block.
nDataSets	PositiveInteger	0..1	attr	Number of data sets to be provided by the NVRAM manager for this block. This is the total number of ROM Blocks and RAM Blocks.
nRomBlocks	PositiveInteger	0..1	attr	Number of ROM Blocks to be provided by the NVRAM manager for this block. Please note that these multiple ROM Blocks are given in a contiguous area.
ramBlockStatus Control	RamBlockStatusControl Enum	0..1	attr	This attribute defines how the management of the RAM Block status is controlled.

△

Class	**NvBlockNeeds**			
readonly	Boolean	0..1	attr	true: data of this NVRAM Block are write protected for normal operation (but protection can be disabled) false: no restriction
reliability	NvBlockNeeds ReliabilityEnum	0..1	attr	Reliability against data loss on the non-volatile medium.
resistantTo ChangedSw	Boolean	0..1	attr	Defines whether an NVRAM Block shall be treated resistant to configuration changes (true) or not (false). For details how to handle initialization in the latter case, please refer to the NVRAM specification.
restoreAtStart	Boolean	0..1	attr	Defines whether the associated RAM Block shall be implicitly restored during startup by the basic software.
selectBlockFor FirstInitAll	Boolean	0..1	attr	If this attribute is set to true the NvM shall process this block in the NvM_FirstInitAll() function.
storeAt Shutdown	Boolean	0..1	attr	Defines whether or not the associated RAM Block shall be implicitly stored during shutdown by the basic software.
storeCyclic	Boolean	0..1	attr	Defines whether or not the associated RAM Block shall be implicitly stored periodically by the basic software.
store Emergency	Boolean	0..1	attr	Defines whether or not the associated RAM Block shall be implicitly stored in case of ECU failure (e.g. loss of power) by the basic software. If the attribute store Emergency is set to true the associated RAM Block shall be configured to have immediate priority.
storeImmediate	Boolean	0..1	attr	Defines whether or not the associated RAM Block shall be implicitly stored immediately during or after execution of the according SW-C RunnableEntity by the basic software.
storeOnChange	Boolean	0..1	attr	This attribute defines whether the associated RAM Block shall be stored immediately if the written value is different to the value stored in the associated RAM Block(s) during or after execution of the according SW-C RunnableEntity.
useAuto ValidationAt ShutDown	Boolean	0..1	attr	If set to true the RAM Block shall be auto validated during shutdown phase.
useCRCComp Mechanism	Boolean	0..1	attr	If set to true the CRC of the RAM Block shall be compared during a write job with the CRC which was calculated during the last successful read or write job in order to skip unnecessary NVRAM writings.
writeOnlyOnce	Boolean	0..1	attr	Defines write protection after first write: true: This block is prevented from being changed/erased or being replaced with the default ROM data after first initialization by the software-component. false: No such restriction.
writeVerification	Boolean	0..1	attr	Defines if Write Verification shall be enabled for this NVRAM Block.
writing Frequency	PositiveInteger	0..1	attr	Provides the amount of updates to this block from the application point of view. It has to be provided in "number of write access per year".
writingPriority	NvBlockNeedsWriting PriorityEnum	0..1	attr	Requires the priority of writing this block in case of concurrent requests to write other blocks.

Table 11.7: NvBlockNeeds

Enumeration	**NvBlockNeedsReliabilityEnum**
Note	Reliability against data loss on the non-volatile medium. These requirements give only a relative indication, for example on the required degree of redundancy for storage. They do, however, not specify by which means (e.g. software or hardware) the reliability is actually achieved.
Aggregated by	NvBlockNeeds.reliability
Literal	***Description***
errorCorrection	Errors shall be corrected **Tags:** atp.EnumerationLiteralIndex=0
errorDetection	Errors shall be detected **Tags:** atp.EnumerationLiteralIndex=1
noProtection	Data need not to be handled with protection **Tags:** atp.EnumerationLiteralIndex=2

Table 11.8: NvBlockNeedsReliabilityEnum

Enumeration	**NvBlockNeedsWritingPriorityEnum**
Note	Specifies the priority of writing this block in case of concurrent requests to write other blocks.
Aggregated by	NvBlockNeeds.writingPriority
Literal	***Description***
high	Writing priority is high. **Tags:** atp.EnumerationLiteralIndex=0
low	Writing priority is low. **Tags:** atp.EnumerationLiteralIndex=1
medium	Writing priority is medium. **Tags:** atp.EnumerationLiteralIndex=2

Table 11.9: NvBlockNeedsWritingPriorityEnum

Enumeration	**RamBlockStatusControlEnum**
Note	This enumeration type defines options for how the management of the ramBlock status is controlled.
Aggregated by	NvBlockNeeds.ramBlockStatusControl
Literal	***Description***
api	The ramBlock status is controlled via service interface by usage of the SetRamBlockStatus operation. **Tags:** atp.EnumerationLiteralIndex=0
nvRamManager	The ramBlock status is controlled exclusively by the Nv Ram Manager. **Tags:** atp.EnumerationLiteralIndex=1

Table 11.10: RamBlockStatusControlEnum

Enumeration	**MaxCommModeEnum**
Note	Maximum bus communication mode required by a user of the Communication Manager Service.
Aggregated by	ComMgrUserNeeds.maxCommMode
Literal	***Description***
full	Full communication is requested. **Tags:** atp.EnumerationLiteralIndex=0

▽

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Enumeration	**MaxCommModeEnum**
none	No communication is requested. **Tags:** atp.EnumerationLiteralIndex=1
silent	Silent communication is requested: Only listening but not "talking". **Tags:** atp.EnumerationLiteralIndex=2

Table 11.11: MaxCommModeEnum

Class	**SupervisedEntityNeeds**			
Note	Specifies the abstract needs on the configuration of the Watchdog Manager for one specific Supervised Entity.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
activateAtStart	Boolean	0..1	attr	true/false: supervision activation status of Supervised Entity shall be enabled/disabled at start.
checkpoints	SupervisedEntity CheckpointNeeds	*	ref	This reference indicates the checkpoints belonging to the Supervised Entity. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=checkpoints, checkpoints.supervisedEntity CheckpointNeeds, checkpoints.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
enable Deactivation	Boolean	0..1	attr	true: software-component shall be allowed to deactivate supervision of this SupervisedEntity false: software-component shall be not allowed to deactivate supervision of this SupervisedEntity
expectedAlive Cycle	TimeValue	0..1	attr	Expected cycle time of alive trigger of this Supervised Entity (in seconds).
maxAliveCycle	TimeValue	0..1	attr	Maximum cycle time of alive trigger of this Supervised Entity (in seconds).
minAliveCycle	TimeValue	0..1	attr	Minimum cycle time of alive trigger of this Supervised Entity (in seconds).
toleratedFailed Cycles	PositiveInteger	0..1	attr	Number of consecutive failed alive cycles for this SupervisedEntity which shall be tolerated until the supervision status of the SupervisedEntity is set to WDGM_ALIVE_EXPIRED (see SWS WdgM for more details). Note that this value has to be recalculated with respect to the WdgM's own cycle time for ECU configuration.

Table 11.12: SupervisedEntityNeeds

Class	**ComMgrUserNeeds**			
Note	Specifies the abstract needs on the configuration of the Communication Manager for one "user".			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
maxComm Mode	MaxCommModeEnum	0..1	attr	Maximum communication mode requested by this ComM user.

Table 11.13: ComMgrUserNeeds

Class	**EcuStateMgrUserNeeds**			
Note	Specifies the abstract needs on the configuration of the ECU State Manager for one "user". This class currently contains no attributes. Its name can be regarded as a symbol identifying the user from the viewpoint of the component or module which owns this class.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.14: EcuStateMgrUserNeeds

Class	**CryptoServiceNeeds**			
Note	Specifies the needs on the configuration of the CryptoServiceManager for one ConfigID (see Specification AUTOSAR_SWS_CSM.doc). An instance of this class is used to find out which ports of a software-component belong to this ConfigID.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
algorithmFamily	String	0..1	attr	This attribute represents a description of the family (e.g. AES) of crypto algorithm implemented by the crypto service use case.
algorithmMode	String	0..1	attr	This meta-class has the ability to represent a crypto service use case.
cryptoKey Description	String	0..1	attr	This attribute allows for a verbal description of the applicable cryptographic key. The goal is to pass a hint for the integrator about how to treat the corresponding service use case.
maximumKey Length	PositiveInteger	0..1	attr	The maximum length of a cryptographic key, that is used by the software-component or module for this configuration. Unit: bit.

Table 11.15: CryptoServiceNeeds

Class	**DltUserNeeds**			
Note	This meta-class specifies the needs on the configuration of the Diagnostic Log and Trace module for one SessionId. This class currently contains no attributes. An instance of this class is used to find out which PortPrototypes of an AtomicSwComponentType belong to this SessionId in order to group the request and response PortPrototypes of the same SessionId. The actual SessionId value is stored in the PortDefinedArgumentValue of the respective PortPrototype specification.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.16: DltUserNeeds

Class	**SyncTimeBaseMgrUserNeeds**			
Note	Specifies the needs on the configuration of the Synchronized Time-base Manager for one time-base. This class currently contains no attributes. An instance of this class is used to find out which ports of a software-component belong to this time-base in order to group the request and response ports of the same time-base. The actual time-base value is stored in the PortDefinedArgumentValue of the respective port specification.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.17: SyncTimeBaseMgrUserNeeds

Class	***DiagnosticCapabilityElement*** (abstract)			
Note	This class identifies the capability to provide generic information about diagnostic capabilities			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Subclasses	DiagnosticCommunicationManagerNeeds, DiagnosticComponentNeeds, DiagnosticControlNeeds, DiagnosticEnableConditionNeeds, DiagnosticEventInfoNeeds, DiagnosticEventManagerNeeds, DiagnosticEventNeeds, DiagnosticExtendedDataRecordNeeds, DiagnosticIoControlNeeds, DiagnosticOperationCycleNeeds, DiagnosticRequestFileTransferNeeds, DiagnosticRoutineNeeds, DiagnosticStorageConditionNeeds, DiagnosticUploadDownloadNeeds, DiagnosticValueNeeds, DiagnosticsCommunicationSecurityNeeds, DtcStatusChangeNotificationNeeds, ObdControlServiceNeeds, ObdInfoServiceNeeds, ObdMonitorServiceNeeds, ObdPidServiceNeeds, ObdRatioDenominatorNeeds, ObdRatioServiceNeeds, WarningIndicatorRequestedBitNeeds			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
audience	DiagnosticAudienceEnum	*	attr	This specifies the intended audience for the diagnostic object. Note that this is not only for the documentation but also subsequent audience specific implementation.
diagRequirement	DiagRequirementIdString	0..1	attr	This denotes the requirement identifier to which the object can be linked to. Note that with the implementation of a generic tracing concept in AUTOSAR this attribute might become obsolete.
securityAccessLevel	PositiveInteger	0..1	attr	This attribute denotes the level of security which is touched by the diagnostic object. The higher the level the more relevance for the security exists. This level shall be mapped to the security level in the ECU.

Table 11.18: DiagnosticCapabilityElement

Class	**FunctionInhibitionNeeds**			
Note	Specifies the abstract needs on the configuration of the Function Inhibition Manager for one Function Identifier (FID). This class currently contains no attributes. Its name can be regarded as a symbol identifying the FID from the viewpoint of the component or module which owns this class.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.19: FunctionInhibitionNeeds

Class	**DoIpServiceNeeds** (abstract)			
Note	This represents an abstract base class for ServiceNeeds related to DoIP.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Subclasses	DoIpActivationLineNeeds, DoIpGidNeeds, DoIpGidSynchronizationNeeds, DoIpPowerModeStatus Needs, DoIpRoutingActivationAuthenticationNeeds, DoIpRoutingActivationConfirmationNeeds, Further ActionByteNeeds			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table 11.20: DoIpServiceNeeds

11.2.1 NvM Service Dependencies

This chapter describes the usage of the specific meta-classes derived from `ServiceNeeds` within a `Basic Software Module`. The meta-class `NvBlockNeeds` is used to define requirements to configure the NVRAM Manager Service. There are several use cases how a `Basic Software Module` can interact with the NVRAM Manager service. Each use case is discussed in a separate sub-chapter.

11.2.1.1 `Nvm` Use Case: Permanent RAM Block

Scenario: a `Basic Software Module` is using an an `NvBlock` with a `Permanent RAM Block`.

[TPS_BSWMDT_04116] Setup for `Nvm` Use Case: `Permanent RAM Block` ⌈

ServiceNeeds kind `NvBlockNeeds`

RoleBasedBswModuleEntryAssignment

For every used `BswModuleEntry` provided by the `NvM` it is necessary to create a `RoleBasedBswModuleEntryAssignment` and set the value of the attribute `role` of the `RoleBasedBswModuleEntryAssignment` to the name of the used standardized `BswModuleEntry`. The following `BswModuleEntry`s shall (i.e. lower multiplicity > 0) or can (lower multiplicity = 0) be used in this context:

- `NvM_ReadBlock` [0..1]
- `NvM_WriteBlock` [0..1]
- `NvM_RestoreBlockDefaults` [0..1]
- `NvM_EraseNvBlock` [0..1]
- `NvM_InvalidateNvBlock` [0..1]
- `NvM_ReadPRAMBlock` [0..1]
- `NvM_WritePRAMBlock` [0..1]

- NvM_RestorePRAMBlockDefaults [0..1]
- NvM_SetDataIndex [0..1]
- NvM_GetDataIndex [0..1]
- NvM_SetBlockProtection [0..1]
- NvM_GetErrorStatus [0..1]
- NvM_SetRamBlockStatus [0..1]
- NvM_SetBlockLockStatus [0..1]
- NvM_CancelJobs [0..1]
- NvM_SingleBlockCallbackFunction [0..1]
- InitBlockCallbackFunction [0..1]

RoleBasedDataAssignment

RoleBasedDataAssignment shall be created that refers to the VariableDataPrototype in the role usedDataElement. The value of the attribute role of the RoleBasedDataAssignment shall be set to ramBlock.

Optionally, it is possible to create an additional RoleBasedDataAssignment to a ParameterDataPrototype in the role usedParameterElement. The value of the ParameterDataPrototype is then taken as the initial or default value for the NvBlock. In this case the value of the attribute role of the RoleBasedDataAssignment shall be set to defaultValue.
Therefore, the following roles are applicable:

- ramBlock [1]
- defaultValue [0..1]

RoleBasedDataTypeAssignment

N/A

⌋

For more information please refer to [SWS_NvM_00734], [SWS_NvM_00735], [SWS_NvM_00736], and [SWS_NvM_00737].

11.2.1.2 Nvm Use Case: Temporary RAM Block

Scenario: a Basic Software Module is using some NV blocks with a Temporary RAM Block.

[TPS_BSWMDT_04117] Setup for Nvm Use Case: Temporary RAM Block ⌈

ServiceNeeds kind `NvBlockNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

For every used `BswModuleEntry` provided by the `NvM` it is necessary to create a `RoleBasedBswModuleEntryAssignment` and set the value of the attribute `role` of the `RoleBasedBswModuleEntryAssignment` to the name of the used standardized `BswModuleEntry`. The following `BswModuleEntry`s shall (i.e. lower multiplicity > 0) or can (lower multiplicity = 0) be used in this context:

- `NvM_ReadBlock` [0..1]
- `NvM_WriteBlock` [0..1]
- `NvM_RestoreBlockDefaults` [0..1]
- `NvM_EraseNvBlock` [0..1]
- `NvM_InvalidateNvBlock` [0..1]
- `NvM_SetDataIndex` [0..1]
- `NvM_GetDataIndex` [0..1]
- `NvM_SetBlockProtection` [0..1]
- `NvM_GetErrorStatus` [0..1]
- `NvM_SetRamBlockStatus` [0..1]
- `NvM_SetBlockLockStatus` [0..1]
- `NvM_CancelJobs` [0..1]
- `NvM_SingleBlockCallbackFunction` [0..1]
- `InitBlockCallbackFunction` [0..1]

RoleBasedDataAssignment

`RoleBasedDataAssignment` may be created that refers to a `ParameterDataPrototype` in the role `usedParameterElement`. The value of the `ParameterDataPrototype` is then taken as the initial or default value for the `NvBlock`. In this case the value of the attribute `role` of the `RoleBasedDataAssignment` shall be set to `defaultValue`.
Therefore, the following roles are applicable:

- `defaultValue` [0..1]

RoleBasedDataTypeAssignment

This denotes the type of the temporary Ram Block. The type information can be used to calculate the NVRAM block. [constr_4088] applies.

- `temporaryRamBlock` [0..1]

⌋

[constr_4088] Existence of RoleBasedDataTypeAssignment.role vs. RoleBasedDataAssignment.role

Imposition time: IT_BswMD

⌈The usage of a RoleBasedDataTypeAssignment with attribute role set to the value temporaryRamBlock is only allowed if **no** RoleBasedDataAssignment defined with attribute role set to value defaultValue exists in the owning BswServiceDependency.⌋

The rationale for [constr_4088] is that the existence of a RoleBasedDataAssignment would already provide sufficient information for the intended purpose. The parallel existence of a RoleBasedDataTypeAssignment is therefore fully redundant and could only lead to potential inconsistencies.

11.2.1.3 Nvm Use Case: RAM Block with explicit synchronization

Scenario: a Basic Software Module is using some NV blocks where the RAM Block is synchronized by means of explicit synchronization using the mirror interfaces.

[TPS_BSWMDT_04118] Setup for Nvm Use Case: RAM Block synchronized with explicit synchronization ⌈

RoleBasedBswModuleEntryAssignment valid roles:

For every used BswModuleEntry provided by the NvM it is necessary to create a RoleBasedBswModuleEntryAssignment and set the value of the attribute role of the RoleBasedBswModuleEntryAssignment to the name of the used standardized BswModuleEntry. The following BswModuleEntrys shall (i.e. lower multiplicity > 0) or can (lower multiplicity = 0) be used in this context:

- NvM_ReadBlock [0..1]
- NvM_WriteBlock [0..1]
- NvM_RestoreBlockDefaults [0..1]
- NvM_EraseNvBlock [0..1]
- NvM_InvalidateNvBlock [0..1]
- NvM_ReadPRAMBlock [0..1]
- NvM_WritePRAMBlock [0..1]
- NvM_RestorePRAMBlockDefaults [0..1]
- NvM_SetDataIndex [0..1]

- NvM_GetDataIndex [0..1]
- NvM_SetBlockProtection [0..1]
- NvM_GetErrorStatus [0..1]
- NvM_SetRamBlockStatus [0..1]
- NvM_SetBlockLockStatus [0..1]
- NvM_CancelJobs [0..1]
- NvM_SingleBlockCallbackFunction [0..1]
- InitBlockCallbackFunction [0..1]
- NvM_ReadRamBlockFromNvm [1]
- NvM_WriteRamBlockToNvm [1]

RoleBasedDataAssignment

RoleBasedDataAssignment may be created that refers to a ParameterDataPrototype in the role usedParameterElement. The value of the ParameterDataPrototype is then taken as the initial or default value for the NvBlock. In this case the value of the attribute role of the RoleBasedDataAssignment shall be set to defaultValue.
Therefore, the following roles are applicable:

- defaultValue [0..1]

RoleBasedDataTypeAssignment

This denotes the type of the internal data structure synchronized with NvMReadRamBlockFromNvM and NvMWriteRamBlockToNvM interface. The type information can be used to calculate the NVRAM block size and minimum RAM Mirror size. [constr_4088] applies.

- temporaryRamBlock [0..1]

⌋

11.2.2 Diagnostic Service Dependency

This chapter describes the usage of the specific diagnostic meta-classes derived from ServiceNeeds within a Basic Software Module.

11.2.2.1 Function Inhibition Needs

The meta-class `FunctionInhibitionNeeds` is used to define requirements in order to configure the `Function Inhibition Manager`.

A `BswInternalBehavior` may provide several `FunctionInhibitionNeeds` elements, each defines the requirements related to one function inhibition ID (for the terms related to the AUTOSAR Function Inhibition Manager, see [21]).

11.2.2.1.1 Function Inhibition Manager Service use Case: read function permission

[TPS_BSWMDT_04119] Setup for Function Inhibition Manager Service use Case: read function permission ⌈

Scenario: a `Basic Software Module` reads the function permission from FiM in order to enable or disable a functionality. In this case the following setup apply:

ServiceNeeds kind `FunctionInhibitionNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `FiM_GetFunctionPermission` [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.2.1.2 Function Inhibition Manager Service use Case: react on suppressed or unavailable events

[TPS_BSWMDT_04167] Setup for Function Inhibition Manager Service use Case: read function permission ⌈

Scenario: a `Basic Software Module` wants to react on suppressed or unavailable events and disable the permission to run for a FID. In this case, the following setup applies:

ServiceNeeds kind `FunctionInhibitionAvailabilityNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `FiM_SetFunctionAvailable` [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

Note: for variant coding `ClientServerInterface`, `ControlFunctionAvailable` is used to deactivate a certain functionality (e.g. to set the FID to not available).

For more information please refer to [SWS_Fim_00106].

11.2.2.2 Diagnostic Event Needs

The meta-classes `DiagnosticEventNeeds` is used to define requirements in order to configure the Diagnostic Event Manager Service.

An `BswInternalBehavior` may provide several `DiagnosticEventNeeds` elements that each defines the requirements related to one diagnostic monitor. (For the terms related to the AUTOSAR Diagnostic Event Manager see [22]).

11.2.2.2.1 Dem Service Use Case: diagnostic monitor, debouncing by Dem

Scenario: a `Basic Software Module` implements a Diagnostic Monitor. The debouncing of the failure condition shall be configured and processed by the Dem. In this case the following setup apply:

[TPS_BSWMDT_04120] Dem Service Use Case: `Basic Software Module` implements a Diagnostic Monitor ⌈

ServiceNeeds kind `DiagnosticEventNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `Dem_SetEventStatus` [1]
- `Dem_ResetEventDebounceStatus` [0..1]
- `Dem_GetEventStatus` [0..1]
- `Dem_GetEventFailed` [0..1]
- `Dem_GetEventTested` [0..1]
- `Dem_GetDTCOfEvent` [0..1]
- `Dem_SetEventDisabled` [0..1]
- `InitMonitorForEvent` [0..1]

- DemTriggerOnEventStatus [0..1]
- DemClearEventAllowed [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.2.2.2 Dem Service Use Case: Basic Software Module implements a Hardware Shutdown

Scenario: when a hardware component is detected as being defective, the Dem shall inform the Basic Software Module which is responsible for executing a hardware-shutdown.

[TPS_BSWMDT_04139] Dem Service Use Case: Basic Software Module implements a hardware shutdown ⌈

ServiceNeeds kind DiagnosticComponentNeeds

RoleBasedPortAssignment valid roles:

- DemTriggerOnComponentStatus [1]

RoleBasedDataAssignment
N/A

RepresentedPortGroups
N/A

⌋

11.2.2.2.3 Dem Service Use Case: Basic Software Module checks whether an event is suppressed

Scenario: a Basic Software Module needs to check for the availability of the event in order to decide whether reporting of that event is cleared by the Dem. For this purpose the Basic Software Module exposes a BswModuleEntry towards the Dem.

[TPS_BSWMDT_04173] Dem Service Use Case: Basic Software Module checks whether an event is suppressed ⌈

ServiceNeeds kind DiagnosticEventInfoNeeds

RoleBasedBswModuleEntryAssignment valid roles:

- Dem_GetEventAvailable [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

RepresentedPortGroups
N/A

⌋

11.2.2.3 Diagnostic Communication Needs

The meta-class DiagnosticValueNeeds is used to define requirements in order to configure the Diagnostic Communication Manager Service as well as the Diagnostic Event Manager Service. The DcM and Dem can access local values via callback functions.

The attribute DiagnosticValueNeeds.diagnosticValueAccess of type DiagnosticValueAccessEnum allows for distinguishing between current values to read diagnostic information (readOnly) and data elements which are additionally classified as configurable (readWrite).

Class	**DiagnosticValueNeeds**			
Note	Specifies the general needs on the configuration of the Diagnostic Communication Manager (DCM) which are not related to a particular item (e.g. a PID). The main use case is the mapping of service ports to the DCM which are not related to a particular item. In the case of using a sender receiver communicated value, the related value shall be taken via assigned Data in the role "signalBasedDiagnostics". In case of using a client/server communicated value, the related value shall be communicated via the port referenced by assignedPort. The details of this communication (e.g. appropriate naming conventions) are specified in the related software specifications (SWS).			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
dataLength	PositiveInteger	0..1	attr	This attribute is applicable only if the DiagnosticValue Needs is aggregated within a BswModuleDependency. This attribute represents the length of data (in bytes) provided for this particular PID signal. This Attribute is only used by the AUTOSAR Classic Platform.
diagnosticValue Access	DiagnosticValueAccess Enum	0..1	attr	This attribute is applicable only if the DiagnosticValue Needs is aggregated within a BswModuleDependency. This attribute controls whether the data can be read and written or whether it is to be handled read-only.

▽

△

Class	**DiagnosticValueNeeds**			
fixedLength	Boolean	0..1	attr	This attribute is applicable only if the DiagnosticValue Needs is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed.
processingStyle	DiagnosticProcessing StyleEnum	0..1	attr	This attribute controls whether interaction requires the software-component to react synchronously on a request or whether it processes the request in background but still the DCM has to issue the call again to eventually obtain the result of the request.

Table 11.21: DiagnosticValueNeeds

Enumeration	**DiagnosticValueAccessEnum**
Note	Defines the access of the configured diagnostic current values which will be used by the Dem or Dcm module.
Aggregated by	DiagnosticValueNeeds.diagnosticValueAccess
Literal	***Description***
readOnly	The access to the data element is limited to read-only. This is typically used to read-out diagnostic information (e.g. current values). **Tags:** atp.EnumerationLiteralIndex=0
readWrite	The value of the diagnostic data element is classified as configurable (read and write access is possible). **Tags:** atp.EnumerationLiteralIndex=1
writeOnly	The access to the data element is limited to write-only. This supports the use case where the Dcm just writes data to the application software without the intention to read it back, **Tags:** atp.EnumerationLiteralIndex=2

Table 11.22: DiagnosticValueAccessEnum

Enumeration	**DiagnosticProcessingStyleEnum**
Note	This meta-class represents the ability to define the processing style of diagnostic requests.
Aggregated by	DiagnosticValueNeeds.processingStyle
Literal	***Description***
processingStyle Asynchronous	The software-component processes the request in background but still the Dcm has to issue the call again to eventually obtain the result of the request. **Tags:** atp.EnumerationLiteralIndex=0
processingStyle AsynchronousWith Error	The software-component processes the request in background but still the Dcm has to issue the call again to eventually obtain the result of the request or handle error code. **Tags:** atp.EnumerationLiteralIndex=1
processingStyle Synchronous	The software-component is supposed to react synchronously on the request. **Tags:** atp.EnumerationLiteralIndex=2

Table 11.23: DiagnosticProcessingStyleEnum

The meta-class `DiagnosticRoutineNeeds` is used to define requirements to configure the Diagnostic Communication Manager Service. A `Basic Software Module` may provide `BswModuleEntry`s (for example, “start”, “stop”, and “RequestResults”). The `BswModuleEntry`s correspond to the diagnostic service RoutineControl

for one routine identifier. The enumeration parameter DiagnosticRoutineType-Enum is used to define whether the diagnostic server or client is responsible for stopping the routine.

Class	**DiagnosticRoutineNeeds**			
Note	Specifies the general needs on the configuration of the Diagnostic Communication Manager (Dcm) which are not related to a particular item (e.g. a PID). The main use case is the mapping of service ports to the Dcm which are not related to a particular item.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
diagRoutine Type	DiagnosticRoutineType Enum	0..1	attr	This denotes the type of diagnostic routine which is implemented by the referenced server port.

Table 11.24: DiagnosticRoutineNeeds

Enumeration	**DiagnosticRoutineTypeEnum**
Note	This enumerator specifies the different types of diagnostic routines.
Aggregated by	DiagnosticRoutineNeeds.diagRoutineType
Literal	***Description***
asynchronous	This indicates that the diagnostic server is not blocked while the diagnostic routine is running. **Tags:** atp.EnumerationLiteralIndex=0
synchronous	This indicates that the diagnostic routine blocks the diagnostic server in the ECU while the routine is running. **Tags:** atp.EnumerationLiteralIndex=1

Table 11.25: DiagnosticRoutineTypeEnum

The meta-class DiagnosticIoControlNeeds is used to define requirements to configure the Diagnostic Communication Manager Service.

Class	**DiagnosticIoControlNeeds**			
Note	Specifies the general needs on the configuration of the Diagnostic Communication Manager (DCM) which are not related to a particular item (e.g. a PID). The main use case is the mapping of service ports to the Dcm which are not related to a particular item.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
currentValue	DiagnosticValueNeeds	0..1	ref	Reference to the DiagnosticValueNeeds indicating the access to the current value via signalBasedDiagnostics. **Tags:** atp.Splitkey=currentValue
freezeCurrent StateSupported	Boolean	0..1	attr	This attribute determines, if the referenced port supports temporary freezing of I/O value.
resetToDefault Supported	Boolean	0..1	attr	This represents a flag for the existence of the ResetTo Default operation in the service interface.
shortTerm Adjustment Supported	Boolean	0..1	attr	This attribute determines, if the referenced port supports temporarily setting of I/O value to a specific value provided by the diagnostic tester.

Table 11.26: DiagnosticIoControlNeeds

Class	**DiagnosticsCommunicationSecurityNeeds**			
Note	This meta-class represents the needs of a software-component to verify the access to security level via diagnostic services.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.27: DiagnosticsCommunicationSecurityNeeds

Class	**DiagnosticCommunicationManagerNeeds**			
Note	Specifies the general needs on the configuration of the Diagnostic Communication Manager (Dcm) which are not related to a particular item (e.g. a PID or DiagnosticRoutineNeeds). The main use case is the mapping of service ports to the Dcm which are not related to a particular item.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
serviceRequest CallbackType	DiagnosticService RequestCallbackType Enum	0..1	attr	This represents the ability to define whether the usage of PortInterface ServiceRequestNotification has the characteristics of being initiated by a manufacturer or by a supplier.

Table 11.28: DiagnosticCommunicationManagerNeeds

11.2.2.3.1 Dcm Service Use Case: read/write current values by `BswModuleEntry`s

Scenario: a `Basic Software Module` offers a `BswModuleEntry`s to read/write current value via diagnostic services.

[TPS_BSWMDT_04121] `Basic Software Module` offers `BswModuleEntry`s to read/write current value via diagnostic services ⌈

ServiceNeeds kind `DiagnosticValueNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `Xxx_ReadData` [0..1] (1 in case read is supported)
- `Xxx_WriteData` [0..1] (1 in case write is supported)
- `Xxx_ReadDataLength` [0..1] (1 in case of variable length)
- `Xxx_ConditionCheckRead` [0..1] (1 in case the read condition is provided by the BSW module)

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.2.3.2 Dcm Service Use Case: start/stop or request routine results

Scenario: a `Basic Software Module` offers a `BswModuleEntry`s to start/stop or request routines via diagnostic services.

[TPS_BSWMDT_04122] `Basic Software Module` offers `BswModuleEntry`s to start/stop or request routines via diagnostic services ⌈

ServiceNeeds kind `DiagnosticRoutineNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `Xxx_Start` [1]
- `Xxx_Stop` [0..1]
- `Xxx_RequestResults` [0..1]
- `Xxx_StartConfirmation` [0..1]
- `Xxx_StopConfirmation` [0..1]
- `Xxx_RequestResultsConfirmation` [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.2.3.3 Dcm Service Use Case: IO control

Scenario: a `Basic Software Module` offers a `BswModuleEntry`s BswModuleEntrys to adjust the IO signal via diagnostic services.

[TPS_BSWMDT_04123] `Basic Software Module` offers `BswModuleEntry`s to adjust the IO signal via diagnostic services ⌈

ServiceNeeds kind `DiagnosticIoControlNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `Xxx_ReadData` [1]
- `Xxx_ReturnControlToECU` [0..1]
- `Xxx_ResetToDefault` [0..1]

- Xxx_FreezeCurrentState [0..1]
- Xxx_ShortTermAdjustment [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.2.3.4 Dcm Service Use Case: Access to protocol, session and security Information

Scenario: a Basic Software Module offers a BswModuleEntrys to access protocol, session and security information.

[TPS_BSWMDT_04124] Basic Software Module offers BswModuleEntrys to access protocol, session and security information ⌈

ServiceNeeds kind DiagnosticCommunicationManagerNeeds

RoleBasedBswModuleEntryAssignment valid roles:

- Dcm_ResetToDefaultSession [0..1]
- Dcm_GetSecurityLevel [0..1]
- Dcm_GetSesCtrlTypel [0..1]
- Dcm_GetActiveProtocol [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.2.3.5 Dcm Service Use Case: Seed / Key handling for security level access and the optional security attempt counter handling

Scenario: a Basic Software Module offers BswModuleEntrys for the Seed and Key handling for security level access and the optional security attempt counter handling.

[TPS_BSWMDT_04125] **`Basic Software Module`** **offers** **`BswModuleEntry`****s for the Seed adn Key handling for security level access and the optional security attempt counter handling** ⌈

ServiceNeeds kind `DiagnosticsCommunicationSecurityNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `Xxx_CompareKey` [1]
- `Xxx_GetSeed` [1]
- `Xxx_GetSecurityAttemptCounter` [0..1]
- `Xxx_SetSecurityAttemptCounter` [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.2.3.6 Dcm Service Use Case: Upload and download of data

Scenario: a `Basic Software Module` implements the ability to accept data for upload and/or provide data for download. For this purpose the `Basic Software Module` provides a `BswModuleEntry` that connects to the Dcm service component.

[TPS_BSWMDT_04172] **`Basic Software Module`** **implements the ability to accept data for upload and/or provide data for download. For this purpose the** **`Basic Software Module`** **provides a** **`BswModuleEntry`** **that connects to the Dcm service component.** ⌈

ServiceNeeds kind `DiagnosticUploadDownloadNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `UploadDownloadServices` [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

Class	**DiagnosticUploadDownloadNeeds**			
Note	This meta-class represents the ability to specify needs regarding upload and download by means of diagnostic services.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.29: DiagnosticUploadDownloadNeeds

11.2.2.4 OBD Service Needs

The meta-class `ObdPidServiceNeeds` is used to define requirements to configure OBD Services in relation to a particular PID (parameter identifier).

11.2.2.4.1 OBD Service Use Case: Read value via OBD services

Scenario: a `Basic Software Module` offers a `BswModuleEntry`s BswModuleEntrys to read value via OBD services.

[TPS_BSWMDT_04165] `Basic Software Module` offers `BswModuleEntry`s to read value via OBD services ⌈

ServiceNeeds kind `ObdPidServiceNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `Xxx_ReadData` [1] (1 in case read is supported)

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

The meta-class `ObdInfoServiceNeeds` is used to define requirements to configure OBD Services in relation to a given InfoType (OBD Service 09).

11.2.2.4.2 OBD Service Use Case: Read vehicle information via OBD services

Scenario: a `Basic Software Module` offers a `BswModuleEntry`s BswModuleEntrys to read vehicle information via OBD services.

[TPS_BSWMDT_04166] `Basic Software Module` offers `BswModuleEntry`s to read vehicle information via OBD services ⌈

ServiceNeeds kind ObdInfoServiceNeeds

RoleBasedBswModuleEntryAssignment valid roles:

- Xxx_GetInfoTypeValueData [1] (1 in case read is supported)

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.3 Watchdog Service Dependencies

The meta-class SupervisedEntityNeeds is used to define requirements to configure the Watchdog Service. For the terms related to the AUTOSAR Watchdog Manager see [23].

11.2.4 Watchdog Service use Case: Local Supervision

The service interaction with the *Watchdog Manager* consists of two aspects:

- supervised entity
- checkpoint

For each of the two aspects a separated ServiceNeeds is defined. However, the BswServiceDependencys that own these ServiceNeeds are semantically bound and cannot be used independently of each other.

In other words, the usage of two kinds of BswServiceDependency in concert creates a higher-level semantics. Of course, in order to express this higher-level semantics a reference between the BswServiceDependencys has to be available.

However, since the BswServiceDependency represents a generic concept the actual reference needs to be implemented on the level of specific subclass of ServiceNeeds, in this case the SupervisedEntityNeeds and the SupervisedEntityCheckpointNeeds.

The former refers to the latter in order to express the relation of a supervised entity to its checkpoints.

Class	**SupervisedEntityCheckpointNeeds**			
Note	Specifies the abstract needs on the configuration of the Watchdog Manager to support a Checkpoint for a Supervised Entity.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
–	–	–	–	–

Table 11.30: SupervisedEntityCheckpointNeeds

[TPS_BSWMDT_04129] Definition a Supervised Entity in a `Basic Software Module` ⌈

ServiceNeeds kind : `SupervisedEntityNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `WdgM_GetLocalStatus` [0..1]
- `WdgM_LocalMode` [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

For more information please refer to [SWS_WdgM_00333], and [SWS_WdgM_00335].

Please note that an `BswInternalBehavior` may provide several `SupervisedEntityNeeds` elements where each defines the requirements in relation to one supervised entity.

[TPS_BSWMDT_04157] Definition of Checkpoints for a Supervised Entity in a `Basic Software Module` ⌈

ServiceNeeds kind : `SupervisedEntityCheckpointNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `WdgM_CheckpointReached` [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

For more information please refer to [SWS_WdgM_00333], and [SWS_WdgM_00335].

Please note that an BswInternalBehavior may provide several SupervisedEntityCheckpointNeeds elements where each defines the relation to one SupervisedEntityNeeds.

11.2.5 Watchdog Service use Case: Control global supervision or get global supervision status

Scenario: a Basic Software Module either controls the global operation of the watchdog manager or gets information about the current operations status requiring at least one of the following use cases:

- Sets the current mode of Watchdog Manager
- Gets the current mode of the Watchdog Manager
- Gets the global supervision status of the Watchdog Manager
- Identifier of the supervised entity that first reached the expired state
- Instructs the Watchdog Manager to cause a watchdog reset

For instance the Basic Software Module sets the current mode of the Watchdog Manager according the operational state of the ECU or polls the global supervision status.

In this case the following setup applies:

[TPS_BSWMDT_04158] Setup for a Basic Software Module which sets or gets Global Supervision Status ⌈

ServiceNeeds kind : GlobalSupervisionNeeds

RoleBasedPortAssignment valid roles:

- WdgM_GetFirstExpiredSEID [0..1]
- WdgM_GetGlobalStatus [0..1]
- WdgM_GetLocalStatus [0..1]
- WdgM_GetMode [0..1]
- WdgM_PerformReset [0..1]
- WdgM_SetMode [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.6 ECU State Manager Service Needs

The meta-class `EcuStateMgrUserNeeds` is used to define the requirements to configure the ECU State Manager Service. There are actually two variants of AUTOSAR ECU management: flexible and fixed. An `BswInternalBehavior` may provide several `EcuStateMgrUserNeeds` elements where each defines the requirements from one "user" of the EcuM Service (for the terms related to the AUTOSAR ECU State Manager see [24]).

11.2.6.1 EcuM Flex Use Case: select Shutdown Target

Scenario: a `Basic Software Module` wants to select a shutdown target. This corresponds to the "select shutdown target" use case of the fix EcuM.

In this case the following rules apply:

[TPS_BSWMDT_04135] `Basic Software Module` wants to select a shutdown target (flexible variant) ⌈

RoleBasedBswModuleEntryAssignment valid roles:

- `EcuM_GetShutdownTarget` [1]
- `EcuM_SelectShutdownTarget` [1]
- `EcuM_GetLastShutdownTarget` [1]
- `EcuM_GetShutdownCause` [1]
- `EcuM_SelectShutdownCause` [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.6.2 EcuM Flex Use Case: select Boot Target

Scenario: a `Basic Software Module` wants to select a boot target.

In this case the following rules apply:

[TPS_BSWMDT_04136] `Basic Software Module` wants to select a boot target (flexible variant) ⌈

RoleBasedBswModuleEntryAssignment valid roles:

- `EcuM_GetBootTarget` [1]
- `EcuM_SelectBootTarget` [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.2.6.3 EcuM Flex Use Case: use Alarm Clock

Scenario: a `Basic Software Module` wants to use an alarm clock.

In this case the following rules apply:

[TPS_BSWMDT_04137] `Basic Software Module` wants to use an alarm clock (flexible variant) ⌈

RoleBasedBswModuleEntryAssignment valid roles:

- `EcuM_SetRelWakeupAlarm` [1]
- `EcuM_SetAbsWakeupAlarm` [1]
- `EcuM_AbortWakeupAlarm` [1]
- `EcuM_SetClock` [1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

11.3 Basic Software Production Errors

The meta-class `DiagnosticEventNeeds` is used to specify production errors in a BSWMD.

Class	DiagnosticEventNeeds			
Note	Specifies the abstract needs on the configuration of the Diagnostic Event Manager for one diagnostic event. Its shortName can be regarded as a symbol identifying the diagnostic event from the viewpoint of the component or module which owns this element. In case the diagnostic event specifies a production error, the shortName shall be the name of the production error.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
deferringFid	FunctionInhibitionNeeds	*	ref	This reference contains the link to a function identifier within the FiM which is used by the monitor before delivering a result. **Tags:** atp.Splitkey=deferringFid
diagEvent Debounce Algorithm	DiagEventDebounce Algorithm	0..1	aggr	Specifies the abstract need on the Debounce Algorithm applied by the Diagnostic Event Manager. **Tags:** atp.Splitkey=diagEventDebounceAlgorithm, diag EventDebounceAlgorithm.shortName
inhibitingFid	FunctionInhibitionNeeds	0..1	ref	This represents the primary Function Inhibition Identifier used for inhibition of the diagnostic monitor. The FID might either inhibit the monitoring of a symptom or the reporting of detected faults. **Tags:** atp.Splitkey=inhibitingFid
inhibiting SecondaryFid	FunctionInhibitionNeeds	*	ref	This represents the secondary Function Inhibition Identifier used for inhibition of the diagnostic monitor. Any of the FID inhibitions leads to an inhibition of the monitoring of a symptom or the reporting of detected faults. **Tags:** atp.Splitkey=inhibitingSecondaryFid
prestored Freezeframe StoredInNvm	Boolean	0..1	attr	If the Event uses a prestored freeze-frame (using the operations PrestoreFreezeFrame and ClearPrestored FreezeFrame of the service interface DiagnosticMonitor) this attribute indicates if the Event requires the data to be stored in non-volatile memory. TRUE = Dem shall store the prestored data in non-volatile memory, FALSE = Data can be lost at shutdown (not stored in Nvm).
usesMonitor Data	Boolean	0..1	attr	This attribute defines whether additional monitor data shall be added to the reporting of events.

Table 11.31: DiagnosticEventNeeds

Class	***DiagEventDebounceAlgorithm*** (abstract)			
Note	This class represents the ability to specify the pre-debounce algorithm which is selected and/or required by the particular monitor. This class inherits from Identifiable in order to allow further documentation of the expected or implemented debouncing and to use the category for the identification of the expected / implemented debouncing.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	DiagEventDebounceCounterBased, DiagEventDebounceMonitorInternal, DiagEventDebounceTime Based			
Aggregated by	DiagnosticDebounceAlgorithmProps.debounceAlgorithm, DiagnosticEventNeeds.diagEventDebounce Algorithm			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table 11.32: DiagEventDebounceAlgorithm

Class	**DiagEventDebounceCounterBased**			
Note	This meta-class represents the ability to indicate that the counter-based debounce algorithm shall be used by the DEM for this diagnostic monitor. This is related to set the ECUC choice container DemDebounceAlgorithmClass to DemDebounce CounterBased.			
Base	*ARObject*, *DiagEventDebounceAlgorithm*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	DiagnosticDebounceAlgorithmProps.debounceAlgorithm, DiagnosticEventNeeds.diagEventDebounce Algorithm			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
counterBased FdcThreshold StorageValue	Integer	0..1	attr	Threshold to allocate an event memory entry and to capture the Freeze Frame.
counter DecrementStep Size	Integer	0..1	attr	This value shall be taken to decrement the internal debounce counter. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
counterFailed Threshold	Integer	0..1	attr	This value defines the event-specific limit that indicates the "failed" counter status. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
counter IncrementStep Size	Integer	0..1	attr	This value shall be taken to increment the internal debounce counter. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
counterJump Down	Boolean	0..1	attr	This value activates or deactivates the counter jump-down behavior. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
counterJump DownValue	Integer	0..1	attr	This value represents the initial value of the internal debounce counter if the counting direction changes from incrementing to decrementing. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
counterJumpUp	Boolean	0..1	attr	This value activates or deactivates the counter jump-up behavior. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
counterJumpUp Value	Integer	0..1	attr	This value represents the initial value of the internal debounce counter if the counting direction changes from decrementing to incrementing. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
counterPassed Threshold	Integer	0..1	attr	This value defines the event-specific limit that indicates the "passed" counter status. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime

Table 11.33: DiagEventDebounceCounterBased

Class	**DiagEventDebounceTimeBased**
Note	This meta-class represents the ability to indicate that the time-based pre-debounce algorithm shall be used by the Dem for this diagnostic monitor. This is related to set the EcuC choice container DemDebounceAlgorithmClass to DemDebounceTime Base.

△

Class	**DiagEventDebounceTimeBased**			
Base	*ARObject*, *DiagEventDebounceAlgorithm*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	DiagnosticDebounceAlgorithmProps.debounceAlgorithm, DiagnosticEventNeeds.diagEventDebounceAlgorithm			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
timeBasedFdcThresholdStorageValue	TimeValue	0..1	attr	Threshold to allocate an event memory entry and to capture the Freeze Frame. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
timeFailedThreshold	TimeValue	0..1	attr	This value represents the event-specific delay indicating the "failed" status. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
timePassedThreshold	TimeValue	0..1	attr	This value represents the event-specific delay indicating the "passed" status. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime

Table 11.34: DiagEventDebounceTimeBased

Class	**DiagEventDebounceMonitorInternal**			
Note	This meta-class represents the ability to indicate that no Dem pre-debounce algorithm shall be used for this diagnostic monitor. The SWC might implement an internal debouncing algorithm and report qualified (debounced) results to the Dem/DM.			
Base	*ARObject*, *DiagEventDebounceAlgorithm*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	DiagnosticDebounceAlgorithmProps.debounceAlgorithm, DiagnosticEventNeeds.diagEventDebounceAlgorithm			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.35: DiagEventDebounceMonitorInternal

[TPS_BSWMDT_04110] Declaration of production errors ⌈If a BSW module reports diagnostic events to the module DEM (= Diagnostic Event Manager, see [22]), its `BswInternalBehavior` shall contain for each kind of diagnostic event one `ServiceDependency` element in the role `serviceDependency`.

This diagnostic event is further characterized by the element `ServiceDependency.serviceNeeds` which shall be an instance of meta-class `DiagnosticEventNeeds`. If the diagnostic event describes a production error, its `DiagnosticEventNeeds.category` attribute shall have one of the following values:

- **PRODUCTION_ERROR** if it represents a production error.
- **EXTENDED_PRODUCTION_ERROR** if it represents an extended production error.

Its `DiagnosticEventNeeds.shortName` shall be equal to the error symbol defined in the AUTOSAR SWS of the respective module if the production error is standardized.⌋

For further information on production error reporting refer to [10].

Production errors and extended production errors are reported to the DEM via the C-function Dem_SetEventStatus(). This scenario shall be specified in the following way:

[TPS_BSWMDT_04111] BswServiceDependency refers to Dem_SetEventStatus() ⌈A BswModuleEntry representing the signature of the C-function Dem_SetEventStatus() shall be specified. According to the rules [TPS_BSWMDT_04008] and [TPS_BSWMDT_04016] defined earlier in this document, its shortName shall have the value Dem_SetEventStatus and the package location in XML shall be:

AUTOSAR_Dem/BswModuleEntrys/

Each BswServiceDependency representing a production error in a BSWMD shall refer to this BswModuleEntry via an aggregated assignedEntryRole which has its role attribute set to the value ReportErrorStatus.⌋

Note that in order to model the complete picture, the module in question should also have a BswModuleDescription.bswModuleDependency.expectedEntry[2] referring to

AUTOSAR_Dem/BswModuleEntrys/Dem_SetEventStatus

and one more BswModuleCallPoints representing the calls into Dem_SetEventStatus(). This additional information is not mandatory to configure the DEM, but it can be used for documentation and call tree or timing analysis.

If the diagnostic event is associated with a callback routine to be called by the DEM and implemented by the module in question, this shall also be modeled by a BswModuleEntry which is referred as BswServiceDependency.assignedEntryRole. This holds namely for the standardized callback InitMonitorForEvent specified in [SWS_Dem_00256]:

[TPS_BSWMDT_04112] BswServiceDependency refers to InitMonitorForEvent ⌈If a module implements the callback InitMonitorForEvent, a BswModuleEntry shall be defined with

- shortName = Service name as defined in [SWS_Dem_00256]

The BswServiceDependency representing this diagnostic event shall refer to this BswModuleEntry via its assignedEntry and its assignedEntryRole shall have the value InitMonitorForEvent.⌋

Note that in order to model the complete picture for such a callback, the module in question should also have a BswModuleDescription.bswModuleDependency.implementedEntry[3] referring to the BswModuleEntry that describes

[2] This shall be modeled differently, if the call crosses partition boundaries, see 4.6.2
[3] This shall be modeled differently, if the call crosses partition boundaries, see 4.6.2

the callback signature and a BswModuleEntity representing the implementation of the callback. This additional information is not mandatory to configure the DEM, but it can be used for documentation and call tree or timing analysis.

11.4 Error Tracer Needs

The meta-class ErrorTracerNeeds is used to define requirements in order to configure the Default Error Tracer.

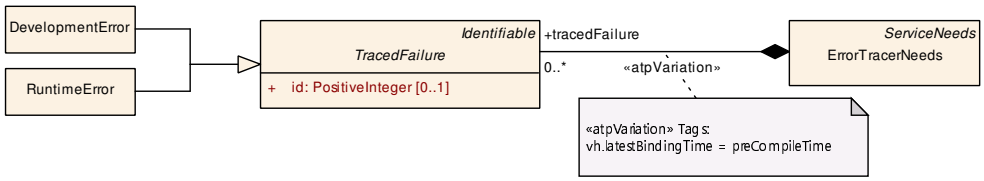

Figure 11.6: Modeling of ErrorTracerNeeds

[constr_4092] Number of ErrorTracerNeeds in BswInternalBehavior

Imposition time: IT_BswMD

⌈A BswInternalBehavior shall provide at most one ErrorTracerNeeds element.⌋

This ErrorTracerNeeds element provides the exhaustive list of all tracedFailures implemented in the BSW module. Each tracedFailure relates to one ID. For more suggestion see Specification of Default Error Tracer [25].

Class	**ErrorTracerNeeds**			
Note	Specifies the need to report failures to the error tracer.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
tracedFailure	TracedFailure	*	aggr	list of traced failures **Stereotypes:** atpVariation **Tags:** atp.Splitkey=tracedFailure, tracedFailure.shortName, tracedFailure.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

Table 11.36: ErrorTracerNeeds

Class	***TracedFailure*** (abstract)			
Note	Specifies the ability to report a specific failure to the error tracer. The short name specifies the literal applicable for the Default Error Tracer.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	DevelopmentError, RuntimeError			
Aggregated by	ErrorTracerNeeds.tracedFailure			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
id	PositiveInteger	0..1	attr	ID of detected failure used in reporting API as error or fault id.

Table 11.37: TracedFailure

Class	**DevelopmentError**			
Note	The reported failure is classified as development error.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *TracedFailure*			
Aggregated by	ErrorTracerNeeds.tracedFailure			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.38: DevelopmentError

Class	**RuntimeError**			
Note	The reported failure is classified as runtime error.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *TracedFailure*			
Aggregated by	ErrorTracerNeeds.tracedFailure			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table 11.39: RuntimeError

11.4.1 Default Error Tracer Service use Case: report failure

[TPS_BSWMDT_04152] Setup for Default Error Tracer Service use Case: report failure: ⌈Scenario: a `Basic Software Module` reports a failure to the Default Error Tracer. In this case the following setup apply:

ServiceNeeds kind `ErrorTracerNeeds`

RoleBasedBswModuleEntryAssignment valid roles:

- `Det_ReportError` [0..1]
- `Det_ReportRuntimeError` [0..1]

RoleBasedDataAssignment
N/A

RoleBasedDataTypeAssignment
N/A

⌋

A Reference Material

A.1 Abbreviations

The content of this appendix chapter is *informative* in nature and shall **not** be considered as *normative* content.

The following table contains a list of abbreviations used in the scope of this document along with the spelled-out meaning of each of the abbreviations.

Abbreviation	*Meaning*
BSWMDT	Basic Software Module Description Template
ECUC	ECU Configuration
ICC1, ICC2, ICC3	AUTOSAR Implementation Conformance Class 1...3
ICS	Implementation Conformance Statement
IOC	Inter OS-Application Communication
MC	Measurement and Calibration
MSR	Manufacturer Supplier Relationship
NvM	Non Volatile Memory

Table A.1: Abbreviations used in the scope of this Document

A.2 Imposition Times of Constraints

The constraints formulated in this document have different actual imposition times which denote the steps in the workflow when the respective constraint has to be imposed.

The imposition times that are considered applicable in the scope of this document *(other imposition times may be defined in the context of other AUTOSAR standard documents)* are listed here.

The imposition times are intentionally rendered as technical terms such that it is possible to link back from each constraint to the definition of the affected imposition time in the table here.

Imposition Time	**Description**	**Motivation**
IT_BswMD	Configuration of the BSW module is finished	This imposition time is applicable at the time when the BSW module description is complete.

Table A.2: Imposition Times of constraints in this document

B Glossary

The content of this appendix chapter is *informative* in nature and shall **not** be considered as *normative* content.

Artifact This is a Work Product Definition that provides a description and definition for tangible work product types. Artifacts may be composed of other artifacts ([26]).

At a high level, an artifact is represented as a single conceptual file.

AUTOSAR Tool This is a software tool which supports one or more tasks defined as AUTOSAR tasks in the methodology. Depending on the supported tasks, an AUTOSAR tool can act as an authoring tool, a converter tool, a processor tool or as a combination of those (see separate definitions).

AUTOSAR Authoring Tool An AUTOSAR Tool used to create and modify AUTOSAR XML Descriptions. Example: System Description Editor.

AUTOSAR Converter Tool An AUTOSAR Tool used to create AUTOSAR XML files by converting information from other AUTOSAR XML files. Example: ECU Flattener

AUTOSAR Definition This is the definition of parameters which can have values. One could say that the parameter values are Instances of the definitions. But in the meta model hierarchy of AUTOSAR, definitions are also instances of the meta model and therefore considered as a description. Examples for AUTOSAR definitions are: `PortPrototype`, `PostBuildVariantCriterion`, `SwSystemconst`.

AUTOSAR XML Description In AUTOSAR this means “filled Template”. In fact an AUTOSAR XML description is the XML representation of an AUTOSAR model.

The AUTOSAR XML description can consist of several files. Each individual file represents an AUTOSAR partial model and shall validate successfully against the AUTOSAR XML schema.

AUTOSAR Meta-Model This is an UML2.0 model that defines the language for describing AUTOSAR systems. The AUTOSAR meta-model is an UML representation of the AUTOSAR templates. UML2.0 class diagrams are used to describe the attributes and their interrelationships. Stereotypes, UML tags and OCL expressions (object constraint language) are used for defining specific semantics and constraints.

AUTOSAR Meta-Model Tool The AUTOSAR Meta-Model Tool is the tool that generates different views (class tables, list of constraints, diagrams, XML Schema etc.) on the AUTOSAR meta-model.

AUTOSAR Model This is a representation of an AUTOSAR product. The AUTOSAR model represents aspects suitable to the intended use according to the AUTOSAR methodology.

Strictly speaking, this is an instance of the AUTOSAR meta-model. The information contained in the AUTOSAR model can be anything that is representable according to the AUTOSAR meta-model.

AUTOSAR Partial Model In AUTOSAR, the possible partitioning of models is marked in the meta-model by ≪atpSplitable≫. One partial model is represented in an AUTOSAR XML description by one file. The partial model does not need to fulfill all semantic constraints applicable to an AUTOSAR model.

AUTOSAR Processor Tool An AUTOSAR Tool used to create non-AUTOSAR files by processing information from AUTOSAR XML files. Example: RTE Generator

AUTOSAR Specification Element An AUTOSAR Specification Element is a named element that is part of an AUTOSAR specification. Examples: requirement, constraint, specification item, class or attribute in the meta model, methodology, deliverable, methodology activity, model element, bsw module etc.

AUTOSAR Template The term "Template" is used in AUTOSAR to describe the format different kinds of descriptions. The term template comes from the idea, that AUTOSAR defines a kind of form which shall be filled out in order to describe a model. The filled form is then called the description.

In fact the AUTOSAR templates are now defined as a meta-model.

AUTOSAR Validation Tool A specialized AUTOSAR Tool which is able to check an AUTOSAR model against the rules defined by a profile.

AUTOSAR XML Schema This is a W3C XML schema that defines the language for exchanging AUTOSAR models. This Schema is derived from the AUTOSAR meta-model. The AUTOSAR XML Schema defines the AUTOSAR data exchange format.

Blueprint This is a model from which other models can be derived by copy and refinement. Note that in contrast to meta model resp. types, this process is *not* an instantiation.

Instance Generally this is a particular exemplar of a model or of a type.

Life Cycle Life Cycle is the course of development/evolutionary stages of a model element during its life time.

Meta-Model This defines the building blocks of a model. In that sense, a Meta-Model represents the language for building models.

Meta-Data This includes pertinent information about data, including information about the authorship, versioning, access-rights, timestamps etc.

Model A Model is an simplified representation of reality. The model represents the aspects suitable for an intended purpose.

Partial Model This is a part of a model which is intended to be persisted in one particular artifact.

Pattern in GST This is an approach to simplify the definition of the meta model by applying a model transformation. This transformation creates an enhanced model out of an annotated model.

Property A property is a structural feature of an object. As an example a “connector” has the properties “receive port” and “send port”.

Properties are made variant by the ≪atpVariation≫.

Prototype This is the implementation of a role of a type within the definition of another type. In other words a type may contain Prototypes that in turn are typed by “Types”. Each one of these prototypes becomes an instance when this type is instantiated.

Type A type provides features that can appear in various roles of this type.

Value This is a particular value assigned to a “Definition”.

Variability Variability of a system is its quality to describe a set of variants. These variants are characterized by variant specific property settings and / or selections. As an example, such a system property selection manifests itself in a particular “receive port” for a connection.

This is implemented using the ≪atpVariation≫.

Variant A system variant is a concrete realization of a system, so that all its properties have been set respectively selected. The software system has no variability anymore with respect to the binding time.

This is implemented using EvaluatedVariantSet.

Variation Binding A variant is the result of a variation binding process that resolves the variability of the system by assigning particular values/selections to all the system’s properties.

This is implemented by VariationPoint.

Variation Binding Time The variation binding time determines the step in the methodology at which the variability given by a set of variable properties is resolved.

This is implemented by vh.latestBindingTime at the related properties.

Variation Definition Time The variation definition time determines the step in the methodology at which the variation points are defined.

Variation Point A variation point indicates that a property is subject to variation. Furthermore, it is associated with a condition and a binding time which define the system context for the selection / setting of a concrete variant.

This is implemented by VariationPoint.

C Constraint and Specification History

The content of this appendix chapter is *informative* in nature and shall **not** be considered as *normative* content.

C.1 Constraint History of this Document according to AUTOSAR R4.0.1

C.1.1 Changed Constraints in R4.0.1

N/A

C.1.2 Added Constraints in R4.0.1

Number	Heading
[constr_4013]	BSW service identifier
[constr_4014]	Call type and execution context
[constr_4015]	`calledEntry` constraints
[constr_4016]	`BswCalledEntity` constraints
[constr_4017]	`BswSchedulableEntity` constraints
[constr_4018]	`BswInterruptEntity` constraints
[constr_4019]	BSW module identifier
[constr_4020]	Categories of `BswModuleDescription`
[constr_4021]	Implementation policy of function pointer target[1]
[constr_4022]	`BswModuleEntry` only uses the module's interface
[constr_4023]	External trigger shall belong to the interface
[constr_4024]	Semantics of BSW mode switch event
[constr_4025]	Modes used by BSW mode switch event
[constr_4026]	Mode group used by BSW mode switch acknowledge event
[constr_4028]	Semantics of memory section type
[constr_4029]	Measured stack usage
[constr_4030]	Measured heap usage
[constr_4031]	Analyzed execution time
[constr_4032]	Measured execution time
[constr_4033]	Simulated execution time
[constr_4034]	Target and context of MC emulation reference
[constr_4036]	Entries linked to `BswModuleDescription`
[constr_4037]	Entries linked to `BswModuleDependency`
[constr_4038]	`bswModuleDependency` shall refer to a different module
[constr_4039]	Semantics of `SwcBswMapping`
[constr_4040]	Synchronized mode groups shall have same type
[constr_4041]	Synchronized mode groups shall have same context
[constr_4042]	Synchronized triggers shall have same context
[constr_4043]	Period of `BswTimingEvent`
[constr_4044]	Content of `McSwEmulationMethodSupport`
[constr_4045]	`implementationConfigVariant` of preconfigured configuration

[1] this constraint was by mistake named **Bsw service identifier** in R4.0.1 and R4.0.2

[constr_4046]	implementationConfigVariant of recommended configuration

Table C.1: Added Constraints in R4.0.1

C.1.3 Deleted Constraints

N/A

C.2 Constraint History of this Document according to AUTOSAR R4.0.2

C.2.1 Changed Constraints in R4.0.2

N/A

C.2.2 Added Constraints in R4.0.2

Number	Heading
[constr_4047]	Multiplicity of vendor specific configuration parameters
[constr_4048]	Multiplicity of preconfigured values

Table C.2: Added Constraints in R4.0.2

C.2.3 Deleted Constraints in R4.0.2

N/A

C.3 Constraint History of this Document according to AUTOSAR R4.0.3

C.3.1 Changed Constraints in R4.0.3

N/A

C.3.2 Added Specification Items in R4.0.3

Number	Heading
[TPS_BSWMDT_04000]	BSW modules with AUTOSAR Interfaces
[TPS_BSWMDT_04001]	Attaching SwComponentDocumentation to a BSWMD
[TPS_BSWMDT_04002]	Usage of BswModuleEntry

[TPS_BSWMDT_04003]	BswModuleDependency
[TPS_BSWMDT_04004]	BswModuleDescription.providedModeGroup
[TPS_BSWMDT_04005]	BswModuleDescription.releasedTrigger
[TPS_BSWMDT_04006]	BswModuleDescription.internalBehavior
[TPS_BSWMDT_04007]	BswModuleEntry
[TPS_BSWMDT_04008]	C-symbol of BswModuleEntry
[TPS_BSWMDT_04009]	Usage of SwServiceArg
[TPS_BSWMDT_04010]	SwServiceArg.swDataDefProps.implementationDataType
[TPS_BSWMDT_04011]	SwServiceArg.swDataDefProps.swPointerTargetProps
[TPS_BSWMDT_04012]	SwServiceArg.direction
[TPS_BSWMDT_04014]	ModeRequestTypeMap in BSW
[TPS_BSWMDT_04015]	Usage of Trigger in BSW
[TPS_BSWMDT_04016]	Location of standardized BswModuleEntrys
[TPS_BSWMDT_04017]	Reference to standardized BswModuleEntry-s
[TPS_BSWMDT_04018]	BswDirectCallPoint.calledEntry
[TPS_BSWMDT_04019]	BswModuleEntity attributes
[TPS_BSWMDT_04020]	Usage of BswSchedulerNamePrefix
[TPS_BSWMDT_04021]	Usage of BswEvent
[TPS_BSWMDT_04022]	Timing and background events for BSW
[TPS_BSWMDT_04023]	Internal trigger and timing events for BSW
[TPS_BSWMDT_04024]	External trigger event for BSW
[TPS_BSWMDT_04025]	Mode switches and events in BSW
[TPS_BSWMDT_04026]	Local BSW data without RTE or BSW Scheduler support
[TPS_BSWMDT_04027]	Local BSW data accessed via BSW Scheduler API
[TPS_BSWMDT_04028]	Determination of argument names for BSW functions called via ports
[TPS_BSWMDT_04029]	Usage of BswServiceDependency
[TPS_BSWMDT_04030]	BswImplementation.arReleaseVersion
[TPS_BSWMDT_04031]	Instances of BswImplementation
[TPS_BSWMDT_04032]	Implementation.hwElement
[TPS_BSWMDT_04033]	Reference to vendor specific configuration parameters
[TPS_BSWMDT_04034]	Reference to predefined or recommended configuration values
[TPS_BSWMDT_04035]	Published parameter values
[TPS_BSWMDT_04036]	Back-reference from EcucModuleConfigurationValues
[TPS_BSWMDT_04039]	Association of an Implementation with a component or module
[TPS_BSWMDT_04040]	Implementation.codeDescriptor
[TPS_BSWMDT_04041]	DependencyOnArtifact
[TPS_BSWMDT_04042]	Usage of DependencyOnArtifact
[TPS_BSWMDT_04043]	Compiler
[TPS_BSWMDT_04044]	Linker
[TPS_BSWMDT_04045]	Implementation.resourceConsumption
[TPS_BSWMDT_04046]	Memory section name
[TPS_BSWMDT_04047]	Memory section prefix
[TPS_BSWMDT_04048]	Scope of declared memory sections
[TPS_BSWMDT_04049]	Usage of MemorySection.executableEntity
[TPS_BSWMDT_04050]	ExecutionTime
[TPS_BSWMDT_04051]	ExecutionTime references an ECU
[TPS_BSWMDT_04052]	ExecutionTime.hardwareConfiguration
[TPS_BSWMDT_04053]	ExecutionTime.memorySectionLocation
[TPS_BSWMDT_04054]	ExecutionTime.softwareContext
[TPS_BSWMDT_04055]	ExecutionTime.includedLibrary
[TPS_BSWMDT_04056]	Multiplicity of McSupportData
[TPS_BSWMDT_04057]	Self-contained MC support artifact
[TPS_BSWMDT_04058]	McSupportData.measurableSystemConstantValues

[TPS_BSWMDT_04059]	Granularity of McDataInstance.subElements
[TPS_BSWMDT_04060]	McDataInstance.resultingProperties
[TPS_BSWMDT_04061]	McSwEmulationMethodSupport.category
[TPS_BSWMDT_04062]	Upstream reference for emulation support
[TPS_BSWMDT_04063]	BSW Interface Variation Points
[TPS_BSWMDT_04064]	BSW Behavior Variation Points
[TPS_BSWMDT_04065]	BSW Implementation Variation Points
[TPS_BSWMDT_04066]	Relevant elements for ICS on Interface level
[TPS_BSWMDT_04067]	No relevant elements for ICS on Internal Behavior level
[TPS_BSWMDT_04068]	Relevant elements for ICS on Implementation level
[TPS_BSWMDT_04069]	Configuration in ICS
[TPS_BSWMDT_04070]	No variants in ICS

Table C.3: Added Specification Items in 4.0.3

C.3.3 Added Constraints in R4.0.3

Number	Heading
[constr_4051]	RoleBasedDataAssignment in BSW
[constr_4052]	BswModuleEntry returnType direction
[constr_4053]	BswModuleEntry argument direction
[constr_4054]	Unambiguous links to addressing method
[constr_4056]	BswModuleEntry with no returnType
[constr_4057]	BswModuleEntry with no argument
[constr_4058]	Different mode groups in mapped BSWM and SWC shall have different names
[constr_4059]	Different mode groups referred by a BSWM shall have different names
[constr_4060]	Allowed values of Trigger.swImplPolicy for BSW
[constr_4061]	Completeness of MC emulation reference
[constr_4062]	Mandatory symbol for McDataInstance root
[constr_4063]	Restrictions of ModeRequestTypeMap in BSW
[constr_4064]	Synchronized triggers shall implement same policy
[constr_4065]	Allowed values of BswInternalTriggeringPoint.swImplPolicy

Table C.4: Added Constraints in R4.0.3

C.3.4 Deleted Constraints in R4.0.3

N/A

C.4 Constraint History of this Document according to AUTOSAR R4.1.1

C.4.1 Changed Specification Items in R4.1.1

Number	Heading
[TPS_BSWMDT_04021]	Usage of BswEvent
[TPS_BSWMDT_04025]	Mode switches and events in BSW

[TPS_BSWMDT_04057]	Self-contained MC support artifact
[TPS_BSWMDT_04063]	BSW Interface Variation Points
[TPS_BSWMDT_04064]	BSW Behavior Variation Points

Table C.5: Changed Specification Items in 4.1.1

C.4.2 Changed Constraints in R4.1.1

Number	Heading
[constr_4015]	`calledEntry` constraints for direct calls
[constr_4022]	`BswModuleEntry` only uses the module's interface

Table C.6: Changed Constraints in R4.1.1

C.4.3 Added Specification Items in R4.1.1

Number	Heading
[TPS_BSWMDT_04071]	Usage of module identifier and category
[TPS_BSWMDT_04072]	Executable entity in BSW
[TPS_BSWMDT_04073]	Exclusive area in BSW
[TPS_BSWMDT_04074]	Synchronization of mode switches or triggers
[TPS_BSWMDT_04075]	`RunnableEntity` in BSW for RTE access
[TPS_BSWMDT_04126]	General meta-model methodology
[TPS_BSWMDT_04076]	ECUC features
[TPS_BSWMDT_04077]	Timing requirements and guarantees
[TPS_BSWMDT_04078]	Semantics of `McFunction`
[TPS_BSWMDT_04079]	Usage of module `shortName`
[TPS_BSWMDT_04080]	Options for inline code sections
[TPS_BSWMDT_04081]	`ExclusiveAreaNestingOrder`
[TPS_BSWMDT_04082]	Indicate that the locking behavior is fully described for `BswModuleEntity`
[TPS_BSWMDT_04083]	Locking behavior is not described for `BswModuleEntity`-s
[TPS_BSWMDT_04084]	Relation of `BswModuleCallPoint` to `ExclusiveAreaNestingOrder`
[TPS_BSWMDT_04085]	`Implementation` refers to a `BuildActionManifest`
[TPS_BSWMDT_04086]	Artifacts referred in `Implementation` and/or `BuildActionManifest`
[TPS_BSWMDT_04087]	Scope of `McFunctionDataRefSet`s
[TPS_BSWMDT_04088]	Usage of `McFunction`
[TPS_BSWMDT_04089]	Access to activation reason
[TPS_BSWMDT_04090]	Variation Points for `BswModuleEntry` arguments
[TPS_BSWMDT_04091]	Function signature containing the keyword **enum** in C
[TPS_BSWMDT_04092]	Provide memory mapping header file names
[TPS_BSWMDT_04093]	Memory classes for compiler abstraction
[TPS_BSWMDT_04094]	Details of `McDataInstance` for rapid prototyping
[TPS_BSWMDT_04095]	Relationships between `McDataInstance`s
[TPS_BSWMDT_04096]	Split between different use cases of `McSupportData`
[TPS_BSWMDT_04097]	Assigning different header files per section prefix
[TPS_BSWMDT_04098]	Declaration of `BswModuleClientServerEntry`

[TPS_BSWMDT_04099]	Semantics of BswModuleClientServerEntry attributes
[TPS_BSWMDT_04100]	Different ways of referring BswModuleEntry
[TPS_BSWMDT_04101]	Declaration of providedData and requiredData
[TPS_BSWMDT_04102]	Usage of BswSynchronousServerCallPoint
[TPS_BSWMDT_04103]	BswModuleEntity reentrancy level
[TPS_BSWMDT_04104]	Usage of BswAsynchronousServerCallPoint
[TPS_BSWMDT_04105]	Usage of BswAsynchronousServerCallResultPoint
[TPS_BSWMDT_04106]	BswModuleEntity attributes for sender-receiver data exchange
[TPS_BSWMDT_04107]	Data reception policy
[TPS_BSWMDT_04108]	BswInternalBehavior containing BswModuleEntity-s executed on different partitions
[TPS_BSWMDT_04109]	BswInternalBehavior for the same AUTOSAR Service provided on different partitions
[TPS_BSWMDT_04110]	Declaration of production errors
[TPS_BSWMDT_04111]	BswServiceDependency refers to Dem_SetEventStatus()
[TPS_BSWMDT_04112]	BswServiceDependency refers to InitMonitorForEvent
[TPS_BSWMDT_04113]	Rule for setting RoleBasedPortAssignment.role
[TPS_BSWMDT_04114]	Use the hierarchical structuring of McDataInstance.subElements
[TPS_BSWMDT_04115]	Use of indexing for array element of subElements

Table C.7: Added Specification Items in 4.1.1

C.4.4 Added Constraints in R4.1.1

Number	Heading
[constr_1275]	Applicability of reference startsOnEvent for BswScheduleEvent
[constr_1276]	Applicability of reference startsOnEvent for BswOperationInvokedEvent
[constr_4066]	BswModeSwitchEvent and the definition of ModeTransition
[constr_4067]	Exclusive usage of data references in McFunctionDataRefSet
[constr_4068]	Semantics of McFunctionDataRefSet.flatMapEntry
[constr_4069]	Semantics of McFunctionDataRefSet.mcDataInstance
[constr_4070]	Applicability of BswModuleEntity.activationReason
[constr_4071]	Synchronized runnables and schedulable entities shall be consistent
[constr_4072]	Constraints of SectionNamePrefix.implementedIn
[constr_4073]	McDataAccessDetails shall refer to one ECU Extract
[constr_4074]	Compatibility of BswModuleClientServerEntry-s
[constr_4075]	Constraints for providedData and requiredData
[constr_4076]	Constraints on BswModuleEntry used for Client-Server
[constr_4077]	Constraints for BswModuleEntity.reentrancyLevel
[constr_4078]	Consistent usage of BswOperationInvokedEvent
[constr_4079]	calledEntry constraints for client-server calls
[constr_4080]	Existence of reception policy
[constr_4081]	Mode group used by BSW mode manager error event
[constr_4083]	BswDistinguishedPartition shall be used only in the context of a particular BswInternalBehavior
[constr_4084]	Consistency of references of InternalBehavior
[constr_4085]	Consistency of references of InternalBehavior

Table C.8: Added Constraints in R4.1.1

C.4.5 Deleted Specification Items in R4.1.1

N/A

C.4.6 Deleted Constraints in R4.1.1

N/A

C.5 Constraint History of this Document according to AUTOSAR R4.2.1

C.5.1 Changed Constraints in R4.2.1

N/A

C.5.2 Added Constraints in R4.2.1

Number	Heading
[constr_4086]	invocation of ExecutableEntitys by direct function call dependent from BswExecutionContext
[constr_4087]	Usage of category "MACRO"
[constr_4088]	Existence of RoleBasedDataTypeAssignment.role vs. RoleBasedDataAssignment.role

Table C.9: Added Constraints in R4.2.1

C.5.3 Deleted Constraints in R4.2.1

N/A

C.5.4 Changed Specification Items in R4.2.1

Number	Heading
[TPS_BSWMDT_04113]	Rule for setting RoleBasedBswModuleEntryAssignment.role

Table C.10: Changed Specification Items in 4.2.1

C.5.5 Added Specification Items in R4.2.1

Number	Heading
[TPS_BSWMDT_04116]	Setup for Nvm Use Case: Permanent RAM Block

[TPS_BSWMDT_04117]	Setup for Nvm Use Case: Temporary RAM Block
[TPS_BSWMDT_04118]	Setup for Nvm Use Case: RAM Block synchronised with explicit synchronisation
[TPS_BSWMDT_04119]	Setup for Function Inhibition Manager Service use Case: read function permission
[TPS_BSWMDT_04120]	Basic Software Module implements a Diagnostic Monitor
[TPS_BSWMDT_04121]	Basic Software Module offers BswModuleEntrys to read/write current value via diagnostic services
[TPS_BSWMDT_04122]	Basic Software Module offers BswModuleEntrys to start/stop or request routines via diagnostic services
[TPS_BSWMDT_04123]	Basic Software Module offers BswModuleEntrys BswModuleEntrys to adjust the IO signal via diagnostic services
[TPS_BSWMDT_04124]	Basic Software Module offers BswModuleEntrys to access protocol, session and security information
[TPS_BSWMDT_04125]	Basic Software Module offers BswModuleEntrys for the Seed adn Key handling for security level access

Table C.11: Added Specification Items in 4.2.1

C.5.6 Deleted Specification Items in R4.2.1

N/A

C.6 Constraint History of this Document according to AUTOSAR R4.2.2

C.6.1 Added Specification Items in 4.2.2

Id	Heading
[TPS_BSWMDT_04076]	ECUC features
[TPS_BSWMDT_04077]	Timing requirements and guarantees
[TPS_BSWMDT_04116]	Setup for Nvm Use Case: Permanent RAM Block
[TPS_BSWMDT_04117]	Setup for Nvm Use Case: Temporary RAM Block
[TPS_BSWMDT_04118]	Setup for Nvm Use Case: RAM Block synchronised with explicit synchronization
[TPS_BSWMDT_04126]	General meta-model methodology
[TPS_BSWMDT_04127]	Callback header declarations
[TPS_BSWMDT_04128]	BSW measurement data accessed via BSW Scheduler API

Table C.12: Added Traceables in 4.2.2

C.6.2 Changed Specification Items in 4.2.2

Id	Heading
[TPS_BSWMDT_04027]	Local BSW data accessed via BSW Scheduler API

Table C.13: Changed Traceables in 4.2.2

C.6.3 Deleted Specification Items in 4.2.2

Id	Heading
[TPS_BSWMDT_04116]	Setup for Nvm Use Case: Permanent RAM Block
[TPS_BSWMDT_04117]	Setup for Nvm Use Case: Temporary RAM Block
[TPS_BSWMDT_04118]	Setup for Nvm Use Case: RAM Block synchronised with explicit synchronization
[TPS_BSWMDT_GEN]	General meta-model methodology
[TPS_BSWMDT_GEN_04076]	ECUC features
[TPS_BSWMDT_GEN_04077]	Timing requirements and guarantees

Table C.14: Deleted Traceables in 4.2.2

C.6.4 Added Constraints in 4.2.2

Id	Heading
[constr_4089]	Association callbackHeader is only applicable for BSW modules
[constr_4090]	The callbackHeader reference has to be consistent with behavior reference

Table C.15: Added Constraints in 4.2.2

C.6.5 Changed Constraints in 4.2.2

none

C.6.6 Deleted Constraints in 4.2.2

none

C.7 Constraint History of this Document according to AUTOSAR R4.3.0

C.7.1 Added Specification Items in 4.3.0

Id	Heading
[TPS_BSWMDT_04129]	Definition a Supervised Entity in a Basic Software Module
[TPS_BSWMDT_04130]	Linkage of BswModuleEntry
[TPS_BSWMDT_04131]	Basic Software Module reads the current ECU mode (fixed variant)
[TPS_BSWMDT_04132]	Basic Software Module shall keep the ECU alive (fixed variant)
[TPS_BSWMDT_04133]	Basic Software Module wants to select a shutdown target (fixed variant)

[TPS_BSWMDT_04134]	`Basic Software Module` wants to select a boot target (fixed variant)
[TPS_BSWMDT_04135]	`Basic Software Module` wants to select a shutdown target (flexible variant)
[TPS_BSWMDT_04136]	`Basic Software Module` wants to select a boot target (flexible variant)
[TPS_BSWMDT_04137]	`Basic Software Module` wants to use an alarm clock (flexible variant)
[TPS_BSWMDT_04138]	Determination of the `BswModuleEntry` symbol
[TPS_BSWMDT_04139]	Dem Use Case: Bsw Module implements a hardware shutdown
[TPS_BSWMDT_04140]	`AccessCount.value` describes an intrinsic property
[TPS_BSWMDT_04141]	The attribute `countProfile` denotes the counting rules
[TPS_BSWMDT_04142]	Standardized values of attribute `countProfile`
[TPS_BSWMDT_04143]	`countProfile` DISTINGUISH_SINGULAR_ACCESSES, Explicit Communication, single access
[TPS_BSWMDT_04144]	`countProfile` DISTINGUISH_SINGULAR_ACCESSES, Explicit Communication, multiple accesses
[TPS_BSWMDT_04145]	`countProfile` DISTINGUISH_SINGULAR_ACCESSES, Implicit Communication and parameter accesses, single access
[TPS_BSWMDT_04146]	`countProfile` DISTINGUISH_SINGULAR_ACCESSES, Implicit Communication and parameter accesses, multiple accesses
[TPS_BSWMDT_04147]	`countProfile` DISTINGUISH_SINGULAR_ACCESSES, Server calls, issued Triggers, Mode Switch Notifications, single access
[TPS_BSWMDT_04148]	`countProfile` DISTINGUISH_SINGULAR_ACCESSES, Server calls, issued Triggers, Mode Switch Notifications, multiple accesses
[TPS_BSWMDT_04149]	Structuring according `ExecutableEntity`s
[TPS_BSWMDT_04150]	Structuring according Variants
[TPS_BSWMDT_04151]	Structuring according different `countProfile` definitions
[TPS_BSWMDT_04152]	Setup for Default Error Tracer Service use Case: report failure:
[TPS_BSWMDT_04153]	Usage of `BswModuleEntry`
[TPS_BSWMDT_04154]	`ExclusiveArea` is entered and exit by common set of API
[TPS_BSWMDT_04155]	`ExclusiveArea` is entered and exit by individual set of API
[TPS_BSWMDT_04156]	Usage of `functionPrototypeEmitter`
[TPS_BSWMDT_04157]	Definition of Checkpoints for a Supervised Entity in a `Basic Software Module`
[TPS_BSWMDT_04158]	Setup for a `Basic Software Module` which sets or gets Global Supervision Status
[TPS_BSWMDT_04159]	Standardized values of attribute `RoleBasedMcDataAssignment.role`
[TPS_BSWMDT_04160]	`RptComponent` represents a software component or basic software module
[TPS_BSWMDT_04161]	`RptExecutableEntity` represents a `ExecutableEntity` with rapid prototyping support
[TPS_BSWMDT_04162]	`RptExecutableEntityEvent` represents a `RTEEvent` or `BswEvent` for with rapid prototyping support
[TPS_BSWMDT_04163]	`RptExecutionContext` represents a common environment for a set of `RptExecutableEntity`s or `McDataInstance`s
[TPS_BSWMDT_04164]	Description of implicit communication buffers

Table C.16: Added Traceables in 4.3.0

C.7.2 Changed Specification Items in 4.3.0

Id	Heading
[TPS_BSWMDT_04002]	Provision of BswModuleEntry
[TPS_BSWMDT_04010]	SwServiceArg.swDataDefProps.implementationDataType
[TPS_BSWMDT_04011]	SwServiceArg.swDataDefProps.swPointerTargetProps
[TPS_BSWMDT_04016]	Location of standardized BswModuleEntry-s
[TPS_BSWMDT_04017]	Reference to standardized BswModuleEntry-s
[TPS_BSWMDT_04025]	Mode switches and events in BSW
[TPS_BSWMDT_04026]	Local BSW data without RTE or BSW Scheduler support
[TPS_BSWMDT_04066]	Relevant elements for ICS on Interface level
[TPS_BSWMDT_04087]	Scope of McFunctionDataRefSets
[TPS_BSWMDT_04100]	Different ways of referring BswModuleEntry
[TPS_BSWMDT_04111]	BswServiceDependency refers to Dem_SetEventStatus()
[TPS_BSWMDT_04120]	Basic Software Module implements a Diagnostic Monitor
[TPS_BSWMDT_04122]	Basic Software Module offers BswModuleEntrys to start/stop or request routines via diagnostic services
[TPS_BSWMDT_04128]	BSW measurement data accessed via BSW Scheduler API

Table C.17: Changed Traceables in 4.3.0

C.7.3 Deleted Specification Items in 4.3.0

Id	Heading
[TPS_BSWMDT_04003]	BswModuleDependency
[TPS_BSWMDT_04037]	BswDebugInfo
[TPS_BSWMDT_04038]	Data types for debug data

Table C.18: Deleted Traceables in 4.3.0

C.7.4 Added Constraints in 4.3.0

Id	Heading
[constr_4091]	AccessCount.value needs to be unambiguous
[constr_4092]	Number of ErrorTracerNeeds in BswInternalBehavior
[constr_4093]	Entries linked to BswModuleEntrys shall have compatible signature
[constr_4094]	compatibility of SwServiceArg in role returnType
[constr_4095]	Compatibility of SwServiceArg in role argument
[constr_4096]	Matching BswModuleEntrys should have compatible attributes
[constr_4097]	Limitation on the number of BswExclusiveAreaPolicys

Table C.19: Added Constraints in 4.3.0

C.7.5 Changed Constraints in 4.3.0

Id	Heading
[constr_4015]	calledEntry constraints for direct calls
[constr_4020]	Categories of BswModuleDescription
[constr_4021]	Implementation policy of function pointer target
[constr_4022]	BswModuleEntity only uses the module's interface

[constr_4071]	Synchronized runnables and schedulable entities must be consistent
[constr_4077]	Constraints for BswModuleEntity.reentrancyLevel
[constr_4079]	calledEntry constraints for client-server calls
[constr_4086]	invocation of ExecutableEntitys by direct function call dependent from BswExecutionContext

Table C.20: Changed Constraints in 4.3.0

C.7.6 Deleted Constraints in 4.3.0

Id	Heading
[constr_4036]	Entries linked to BswModuleDescription
[constr_4037]	Entries linked to BswModuleDependency

Table C.21: Deleted Constraints in 4.3.0

C.8 Constraint History of this Document according to AUTOSAR R4.3.1

C.8.1 Added Specification Items in 4.3.1

Number	Heading
[TPS_BSWMDT_04165]	Basic Software Module offers BswModuleEntrys to read value via OBD services
[TPS_BSWMDT_04166]	Basic Software Module offers BswModuleEntrys to read vehicle information via OBD services
[TPS_BSWMDT_04167]	Setup for Function Inhibition Manager Service use Case: read function permission

Table C.22: Added Specification Items in 4.3.1

C.8.2 Changed Specification Items in 4.3.1

Number	Heading
[TPS_BSWMDT_04125]	Basic Software Module offers BswModuleEntrys for the Seed adn Key handling for security level access and the optional security attempt counter handling

Table C.23: Changed Specification Items in 4.3.1

C.8.3 Deleted Specification Items in 4.3.1

none

C.8.4 Added Constraints in 4.3.1

Number	Heading
[constr_4098]	No mode disabling for `BswOperationInvokedEvent`

Table C.24: Added Constraints in 4.3.1

C.8.5 Changed Constraints in 4.3.1

none

C.8.6 Deleted Constraints in 4.3.1

none

C.9 Constraint History of this Document according to AUTOSAR R4.4.0

C.9.1 Added Specification Items in 4.4.0

Number	Heading
[TPS_BSWMDT_04168]	Semantics of `McGroup`
[TPS_BSWMDT_04169]	Scope of `McGroupDataRefSet`s
[TPS_BSWMDT_04170]	Usage of `McGroup`
[TPS_BSWMDT_04171]	HtssM Service Use Case: Query results of hardware tests
[TPS_BSWMDT_04172]	`Basic Software Module` implements the ability to accept data for upload and/or provide data for download. For this purpose the `Basic Software Module` provides a `BswModuleEntry` that connects to the Dcm service component.

Table C.25: Added Specification Items in 4.4.0

C.9.2 Changed Specification Items in 4.4.0

Number	Heading
[TPS_BSWMDT_04032]	`Implementation.hwElement`

Table C.26: Changed Specification Items in 4.4.0

C.9.3 Deleted Specification Items in 4.4.0

Number	Heading
[TPS_BSWMDT_04131]	`Basic Software Module` reads the current ECU mode (fixed variant)
[TPS_BSWMDT_04132]	`Basic Software Module` shall keep the ECU alive (fixed variant)
[TPS_BSWMDT_04133]	`Basic Software Module` wants to select a shutdown target (fixed variant)
[TPS_BSWMDT_04134]	`Basic Software Module` wants to select a boot target (fixed variant)

Table C.27: Deleted Specification Items in 4.4.0

C.9.4 Added Constraints in 4.4.0

Number	Heading
[constr_4099]	Support of multiple instantiation
[constr_4100]	Uniqueness of module implementation prefixes
[constr_4101]	Semantics of `McGroupDataRefSet.flatMapEntry`
[constr_4102]	Semantics of `McGroupDataRefSet.mcDataInstance`
[constr_4103]	Name convention for `SectionNamePrefix`
[constr_4104]	Referencing of `MemorySection`s to `SectionNamePrefix`

Table C.28: Added Constraints in 4.4.0

C.9.5 Changed Constraints in 4.4.0

Number	Heading
[constr_4068]	`McFunctionDataRefSet.flatMapEntry`'s semantic
[constr_4069]	`McFunctionDataRefSet.mcDataInstance`'s semantic
[constr_4071]	Synchronized runnables and schedulable entities must be consistent

Table C.29: Changed Constraints in 4.4.0

C.9.6 Deleted Constraints in 4.4.0

Number	Heading
[constr_4067]	Exclusive usage of data references in `McFunctionDataRefSet`

Table C.30: Deleted Constraints in 4.4.0

C.10 Constraint History of this Document according to AUTOSAR R19-11

C.10.1 Added Specification Items in 19-11

none

C.10.2 Changed Specification Items in 19-11

Number	Heading
[TPS_BSWMDT_04000]	BSW modules with AUTOSAR Interfaces
[TPS_BSWMDT_04013]	Usage of `BswModuleDescription.providedModeGroup`
[TPS_BSWMDT_04021]	Usage of `BswEvent`
[TPS_BSWMDT_04057]	Self-contained MC support artifact
[TPS_BSWMDT_04074]	Synchronization of mode switches or triggers
[TPS_BSWMDT_04098]	Declaration of `BswModuleClientServerEntry`
[TPS_BSWMDT_04101]	Declaration of `providedData` and `requiredData`
[TPS_BSWMDT_04108]	`BswInternalBehavior` containing `BswModuleEntity`-s executed on different partitions
[TPS_BSWMDT_04109]	`BswInternalBehavior` for the same AUTOSAR Service provided on different partitions
[TPS_BSWMDT_04120]	Dem Service Use Case: `Basic Software Module` implements a Diagnostic Monitor
[TPS_BSWMDT_04139]	Dem Service Use Case: `Basic Software Module` implements a hardware shutdown
[TPS_BSWMDT_04163]	`RptExecutionContext` represents a common environment for a set of `RptExecutableEntity`s or `McDataInstance`s
[TPS_BSWMDT_04169]	Scope of `McGroupDataRefSet`s

Table C.31: Changed Specification Items in 19-11

C.10.3 Deleted Specification Items in 19-11

none

C.10.4 Added Constraints in 19-11

Number	Heading
[constr_4105]	Use of attribute `task` or `cat2Isr`

Table C.32: Added Constraints in 19-11

C.10.5 Changed Constraints in 19-11

Number	Heading
[constr_4013]	BSW service identifier
[constr_4015]	`calledEntry` constraints for direct calls
[constr_4016]	`BswCalledEntity` constraints
[constr_4017]	`BswSchedulableEntity` constraints
[constr_4018]	`BswInterruptEntity` constraints
[constr_4019]	BSW module identifier
[constr_4022]	`BswModuleEntity` only uses the module's interface
[constr_4023]	External trigger shall belong to the interface
[constr_4025]	Modes used by BSW mode switch event
[constr_4026]	Mode group used by BSW mode switch acknowledge event
[constr_4028]	Semantics of memory section type
[constr_4029]	Measured stack usage
[constr_4030]	Measured heap usage
[constr_4031]	Analyzed execution time
[constr_4032]	Measured execution time
[constr_4033]	Simulated execution time
[constr_4034]	Target and context of MC emulation reference
[constr_4038]	`bswModuleDependency` shall refer to a different module
[constr_4040]	Synchronized mode groups shall have same type
[constr_4041]	Synchronized mode groups shall have same context
[constr_4042]	Synchronized triggers shall have same context
[constr_4044]	Content of `McSwEmulationMethodSupport`
[constr_4052]	`BswModuleEntry` returnType direction
[constr_4053]	`BswModuleEntry` argument direction
[constr_4054]	Unambiguous links to addressing method
[constr_4058]	Different mode groups in mapped BSWM and SWC shall have different names
[constr_4059]	Different mode groups referred by a BSWM shall have different names
[constr_4061]	Completeness of MC emulation reference
[constr_4062]	Mandatory symbol for `McDataInstance` root
[constr_4064]	Synchronized triggers shall implement same policy
[constr_4071]	Synchronized runnables and schedulable entities shall be consistent
[constr_4072]	Constraints of `SectionNamePrefix.implementedIn`
[constr_4073]	`McDataAccessDetails` shall refer to one ECU Extract
[constr_4076]	Constraints on `BswModuleEntry` used for Client-Server
[constr_4079]	`calledEntry` constraints for client-server calls
[constr_4080]	Existence of reception policy

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Number	Heading
[constr_4081]	Mode group used by BSW mode manager error event

Table C.33: Changed Constraints in 19-11

C.10.6 Deleted Constraints in 19-11

none

C.11 Constraint History of this Document according to AUTOSAR R20-11

C.11.1 Added Specification Items in R20-11

Number	Heading
[TPS_BSWMDT_04173]	Dem Service Use Case: `Basic Software Module` checks whether an event is suppressed
[TPS_BSWMDT_04174]	Association to `FlatMap`
[TPS_BSWMDT_04175]	Support software emulation
[TPS_BSWMDT_04176]	Self-contained MC support artifact
[TPS_BSWMDT_04177]	Support of functional modeling
[TPS_BSWMDT_04178]	Support of rapid prototyping

Table C.34: Added Specification Items in R20-11

C.11.2 Changed Specification Items in R20-11

Number	Heading
[TPS_BSWMDT_04057]	Self-contained MC support artifact

Table C.35: Changed Specification Items in R20-11

C.11.3 Deleted Specification Items in R20-11

none

C.11.4 Added Constraints in R20-11

none

C.11.5 Changed Constraints in R20-11

Number	Heading
[constr_4071]	Synchronized runnables and schedulable entities shall be consistent

Table C.36: Changed Constraints in R20-11

C.11.6 Deleted Constraints in R20-11

none

C.12 Constraint History of this Document according to AUTOSAR R21-11

C.12.1 Added Specification Items in R21-11

none

C.12.2 Changed Specification Items in R21-11

Number	Heading
[TPS_BSWMDT_04027]	Local BSW data accessed via BSW Scheduler API
[TPS_BSWMDT_04028]	Determination of argument names for BSW functions called via ports
[TPS_BSWMDT_04049]	Usage of `MemorySection.executableEntity`
[TPS_BSWMDT_04092]	Provide memory mapping header file names
[TPS_BSWMDT_04103]	`BswModuleEntity` reentrancy level
[TPS_BSWMDT_04110]	Declaration of production errors
[TPS_BSWMDT_04111]	BswServiceDependency refers to `Dem_SetEventStatus()`

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Number	Heading
[TPS_BSWMDT_04112]	BswServiceDependency refers to `InitMonitorForEvent`
[TPS_BSWMDT_04128]	BSW measurement data accessed via BSW Scheduler API
[TPS_BSWMDT_04173]	Dem Service Use Case: `Basic Software Module` checks whether an event is suppressed

Table C.37: Changed Specification Items in R21-11

C.12.3 Deleted Specification Items in R21-11

Number	Heading
[TPS_BSWMDT_04093]	Memory classes for compiler abstraction

Table C.38: Deleted Specification Items in R21-11

C.12.4 Added Constraints in R21-11

none

C.12.5 Changed Constraints in R21-11

Number	Heading
[constr_4014]	Call type and execution context
[constr_4015]	`calledEntry` constraints for direct calls
[constr_4022]	`BswModuleEntity` only uses the module's interface
[constr_4028]	Semantics of memory section type
[constr_4051]	`RoleBasedDataAssignment` in BSW
[constr_4054]	Unambiguous links to addressing method
[constr_4066]	`BswModeSwitchEvent` and the definition of `ModeTransition`
[constr_4068]	`McFunctionDataRefSet.flatMapEntry`'s semantic
[constr_4073]	`McDataAccessDetails` shall refer to one ECU Extract
[constr_4074]	Compatibility of `BswModuleClientServerEntry`-s
[constr_4075]	Constraints for `providedData` and `requiredData`
[constr_4076]	Constraints on `BswModuleEntry` used for Client-Server
[constr_4077]	Constraints for `BswModuleEntity.reentrancyLevel`

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Number	Heading
[constr_4078]	Consistent usage of BswOperationInvokedEvent
[constr_4079]	calledEntry constraints for client-server calls
[constr_4084]	Consistency of references of InternalBehavior
[constr_4086]	invocation of ExecutableEntitys by direct function call dependent from BswExecutionContext
[constr_4101]	Semantics of McGroupDataRefSet.flatMapEntry
[constr_4105]	Use of attribute task or cat2Isr

Table C.39: Changed Constraints in R21-11

C.12.6 Deleted Constraints in R21-11

none

C.13 Constraint History of this Document according to AUTOSAR R22-11

C.13.1 Added Specification Items in R22-11

none

C.13.2 Changed Specification Items in R22-11

none

C.13.3 Deleted Specification Items in R22-11

none

C.13.4 Added Constraints in R22-11

Number	Heading
[constr_4106]	Restriction for the value of SwServiceArg.swImplPolicy
[constr_4107]	swImplPolicy for SwServiceArg
[constr_4108]	Restriction regarding the value of SwServiceArg.category
[constr_10257]	Existence of attribute BswServiceDependency.serviceNeeds

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Number	Heading
[constr_10258]	Existence of the reference in the role RoleBasedBswModuleEntryAssignment.assignedEntry
[constr_10259]	Existence of attribute RoleBasedBswModuleEntryAssignment.role
[constr_10260]	Existence of attribute BswModuleEntry.callType
[constr_10261]	Existence of attribute BswModuleEntry.executionContext
[constr_10262]	Existence of attribute BswModuleEntry.isReentrant
[constr_10263]	Existence of attribute BswModuleEntry.isSynchronous
[constr_10264]	Existence of attribute BswModuleEntry.swServiceImplPolicy
[constr_10265]	Existence of attribute BswEntryRelationshipSet.bswEntryRelationship
[constr_10266]	Existence of attribute BswEntryRelationship.bswEntryRelationshipType
[constr_10267]	Existence of reference in the role BswEntryRelationship.from
[constr_10268]	Existence of reference in the role BswEntryRelationship.to
[constr_10269]	Existence of the reference in the role BswModuleClientServerEntry.encapsulatedEntry
[constr_10270]	Existence of attribute AccessCountSet.countProfile
[constr_10271]	Existence of attribute AccessCount.value
[constr_10272]	Existence of the reference in the role BswModuleEntity.implementedEntry
[constr_10273]	Existence of attribute BswInterruptEntity.interruptCategory
[constr_10274]	Existence of attribute BswInterruptEntity.interruptSource
[constr_10275]	Existence of the reference in the role BswDirectCallPoint.calledEntry
[constr_10276]	Existence of the reference in the role BswSynchronousServerCallPoint.calledEntry
[constr_10277]	Existence of the reference in the role BswAsynchronousServerCallPoint.calledEntry
[constr_10278]	Existence of the reference in the role BswAsynchronousServerCallResultPoint.asynchronousServerCallPoint
[constr_10279]	Existence of the reference in the role BswVariableAccess.accessedVariable
[constr_10280]	Existence of the reference in the role BswExclusiveAreaPolicy.exclusiveArea
[constr_10281]	Existence of attribute BswTimingEvent.period
[constr_10282]	Existence of the reference in the role BswInternalTriggerOccurredEvent.eventSource
[constr_10283]	Existence of the reference in the role BswExternalTriggerOccurredEvent.trigger
[constr_10284]	Existence of attribute BswModeSwitchEvent.activation
[constr_10285]	Existence of the reference in the role BswModeSwitchedAckEvent.modeGroup
[constr_10286]	Existence of the reference in the role BswModeManagerErrorEvent.modeGroup
[constr_10287]	Existence of the reference in the role BswOperationInvokedEvent.entry
[constr_10288]	Existence of the reference in the role BswAsynchronousServerCallReturnsEvent.eventSource
[constr_10289]	Existence of the reference in the role BswDataReceivedEvent.data

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Number	Heading
[constr_10290]	Existence of the reference in the role BswTriggerDirectImplementation.masteredTrigger
[constr_10291]	Existence of the reference in the role BswModeSenderPolicy.providedModeGroup
[constr_10292]	Existence of attribute BswModeSenderPolicy.queueLength
[constr_10293]	Existence of attribute BswModeSwitchAckRequest.timeout
[constr_10294]	Existence of the reference in the role BswModeReceiverPolicy.requiredModeGroup
[constr_10295]	Existence of attribute BswModeReceiverPolicy.supportsAsynchronousModeSwitch
[constr_10296]	Existence of reference in the role BswDataReceptionPolicy.receivedData
[constr_10297]	Existence of attribute BswQueuedDataReceptionPolicy.queueLength
[constr_10298]	Existence of the reference in the role SwcBswRunnableMapping.bswEntity
[constr_10299]	Existence of the reference in the role SwcBswRunnableMapping.swcRunnable
[constr_10300]	Existence of the reference in the role SwcBswSynchronizedTrigger.bswTrigger
[constr_10301]	Existence of the instanceRef in the role SwcBswSynchronizedTrigger.swcTrigger
[constr_10302]	Existence of attribute BswImplementation.arReleaseVersion
[constr_10303]	Existence of the reference in the role BswImplementation.behavior
[constr_10304]	Existence of attribute DependencyOnArtifact.usage
[constr_10305]	Existence of attribute WorstCaseStackUsage.memoryConsumption
[constr_10306]	Existence of attribute MeasuredStackUsage.averageMemoryConsumption
[constr_10307]	Existence of attribute MeasuredStackUsage.maximumMemoryConsumption
[constr_10308]	Existence of attribute RoughEstimateStackUsage.memoryConsumption
[constr_10309]	Existence of attribute WorstCaseHeapUsage.memoryConsumption
[constr_10310]	Existence of attribute MeasuredHeapUsage.averageMemoryConsumption
[constr_10311]	Existence of attribute MeasuredHeapUsage.maximumMemoryConsumption
[constr_10312]	Existence of attribute RoughEstimateHeapUsage.memoryConsumption
[constr_10313]	Existence of attribute ExecutionTime.hardwareConfiguration
[constr_10314]	Existence of attribute ExecutionTime.softwareContext
[constr_10315]	Existence of attribute HardwareConfiguration.additionalInformation
[constr_10316]	Existence of attribute HardwareConfiguration.processorMode
[constr_10317]	Existence of attribute HardwareConfiguration.processorSpeed
[constr_10318]	Existence of reference MemorySectionLocation.providedMemory
[constr_10319]	Existence of reference MemorySectionLocation.softwareMemorySection
[constr_10320]	Existence of attribute SoftwareContext.input
[constr_10321]	Existence of attribute SoftwareContext.state
[constr_10323]	Existence of attribute AnalyzedExecutionTime.bestCaseExecutionTime
[constr_10324]	Existence of attribute AnalyzedExecutionTime.worstCaseExecutionTime

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Number	Heading
[constr_10325]	Existence of attribute MeasuredExecutionTime.maximumExecutionTime
[constr_10326]	Existence of attribute MeasuredExecutionTime.minimumExecutionTime
[constr_10327]	Existence of attribute MeasuredExecutionTime.nominalExecutionTime
[constr_10328]	Existence of the reference in the role BswEvent.startsOnEvent
[constr_10329]	Existence of the instanceRef in the role McDataAccessDetails.variableAccess
[constr_10330]	Existence of attribute RptServicePoint.symbol
[constr_10331]	Existence of attribute SimulatedExecutionTime.maximumExecutionTime
[constr_10332]	Existence of attribute SimulatedExecutionTime.minimumExecutionTime
[constr_10333]	Existence of attribute SimulatedExecutionTime.nominalExecutionTime
[constr_10334]	Existence of attribute RoughEstimateOfExecutionTime.additionalInformation
[constr_10335]	Existence of attribute RoughEstimateOfExecutionTime.estimatedExecutionTime
[constr_10336]	Existence of the reference in the role SwcBswSynchronizedModeGroupPrototype.bswModeGroup
[constr_10337]	Existence of the instanceRef in the role SwcBswSynchronizedModeGroupPrototype.swcModeGroup
[constr_10338]	Existence of attribute MultidimensionalTime.cseCode
[constr_10339]	Existence of attribute MultidimensionalTime.cseCodeFactor
[constr_10340]	Existence of attribute McSwEmulationMethodSupport.category
[constr_10341]	Existence of attribute McSwEmulationMethodSupport.shortLabel
[constr_10342]	Existence of the reference in the role McParameterElementGroup.ramLocation
[constr_10343]	Existence of the reference in the role McParameterElementGroup.romLocation
[constr_10344]	Existence of attribute McParameterElementGroup.shortLabel
[constr_10345]	Existence of the reference in the role ImplementationElementInParameterInstanceRef.context
[constr_10346]	Existence of the reference in the role ImplementationElementInParameterInstanceRef.target
[constr_10347]	Existence of the instanceRef in the role McDataAccessDetails.rteEvent
[constr_10349]	Existence of attribute RptSupportData.executionContext
[constr_10350]	Existence of attribute RptSupportData.rptComponent
[constr_10351]	Existence of attribute RptSupportData.rptServicePoint
[constr_10352]	Existence of attribute RptComponent.rptExecutableEntity
[constr_10353]	Existence of attribute RptExecutableEntity.rptExecutableEntityEvent
[constr_10354]	Existence of attribute RptExecutableEntity.symbol
[constr_10355]	Existence of the reference in the role RptExecutableEntityEvent.executionContext
[constr_10356]	Existence of attribute RptExecutableEntityEvent.rptEventId

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Number	Heading
[constr_10357]	Existence of attribute RptExecutableEntityEvent.rptExecutableEntityProperties
[constr_10358]	Existence of the reference in the role RptExecutableEntityEvent.rptServicePointPost
[constr_10359]	Existence of the reference in the role RptExecutableEntityEvent.rptServicePointPre
[constr_10360]	Existence of attribute RptServicePoint.serviceId
[constr_10362]	Existence of attribute AliasNameSet.aliasName
[constr_10363]	Existence of attribute AliasNameAssignment.shortLabel

Table C.40: Added Constraints in R22-11

C.13.5 Changed Constraints in R22-11

Number	Heading
[constr_4020]	Allowed categories of BswModuleDescription
[constr_4068]	McFunctionDataRefSet.flatMapEntry's semantic
[constr_4069]	McFunctionDataRefSet.mcDataInstance's semantic
[constr_4074]	Compatibility of BswModuleClientServerEntry-s
[constr_4086]	invocation of ExecutableEntitys by direct function call dependent from BswExecutionContext
[constr_4101]	Semantics of McGroupDataRefSet.flatMapEntry
[constr_4102]	Semantics of McGroupDataRefSet.mcDataInstance
[constr_4103]	Name convention for SectionNamePrefix.symbol

Table C.41: Changed Constraints in R22-11

C.13.6 Deleted Constraints in R22-11

none

C.14 Constraint History of this Document according to AUTOSAR R23-11

C.14.1 Added Specification Items in R23-11

Number	Heading
[TPS_BSWMDT_04179]	Possible invocation of ExecutableEntitys by direct function call dependent from BswExecutionContext

Table C.42: Added Specification Items in R23-11

C.14.2 Changed Specification Items in R23-11

Number	Heading
[TPS_BSWMDT_04159]	Standardized values of attribute RoleBasedMcDataAssignment.role

Table C.43: Changed Specification Items in R23-11

C.14.3 Deleted Specification Items in R23-11

none

C.14.4 Added Constraints in R23-11

none

C.14.5 Changed Constraints in R23-11

Number	Heading
[constr_4016]	BswCalledEntity constraints

Table C.44: Changed Constraints in R23-11

C.14.6 Deleted Constraints in R23-11

none

C.15 Spec Item and Constraint History of this Document according to AUTOSAR R24-11

C.15.1 Added Specification Items in R24-11

Number	Heading
[TPS_BSWMDT_04180]	invocation of ExecutableEntitys by direct function call dependent from BswExecutionContext
[TPS_BSWMDT_04181]	BswModuleDescription with several internalBehaviors
[TPS_BSWMDT_04182]	No support for pointers in McDataInstance
[TPS_BSWMDT_04183]	McDataInstance with category STRING
[TPS_BSWMDT_04184]	McDataInstance is allowed to be a member in multiple McGroups
[TPS_BSWMDT_04185]	SwcBswRunnableMapping of a BswModuleEntity with implementedEntry in which the attribute functionPrototypeEmitter is set to RTE

Table C.45: Added Specification Items in R24-11

C.15.2 Changed Specification Items in R24-11

Number	Heading
[TPS_BSWMDT_04152]	Setup for Default Error Tracer Service use Case: report failure:

Table C.46: Changed Specification Items in R24-11

C.15.3 Deleted Specification Items in R24-11

Number	Heading
[TPS_BSWMDT_04056]	Multiplicity of McSupportData

Table C.47: Deleted Specification Items in R24-11

C.15.4 Added Constraints in R24-11

Number	Heading
[constr_9316]	Multi instantiated BSW Modules not mappable

Table C.48: Added Constraints in R24-11

C.15.5 Changed Constraints in R24-11

Number	Heading
[constr_4014]	Call type and execution context
[constr_4016]	`BswCalledEntity` constraints
[constr_4018]	`BswInterruptEntity` constraints
[constr_4071]	Synchronized runnables and schedulable entities shall be consistent
[constr_4089]	Association `callbackHeader` is only applicable for BSW modules
[constr_4090]	The `callbackHeader` reference has to be consistent with behavior reference
[constr_4102]	Semantics of `McGroupDataRefSet.mcDataInstance`

Table C.49: Changed Constraints in R24-11

C.15.6 Deleted Constraints in R24-11

Number	Heading
[constr_4086]	invocation of `ExecutableEntity`s by direct function call dependent from `BswExecutionContext`

Table C.50: Deleted Constraints in R24-11

C.16 Spec Item and Constraint History of this Document according to AUTOSAR R25-11

C.16.1 Added Specification Items in R25-11

none

C.16.2 Changed Specification Items in R25-11

Number	Heading
[TPS_BSWMDT_04016]	Location of standardized `BswModuleEntry`-s
[TPS_BSWMDT_04017]	Reference to standardized `BswModuleEntry`-s
[TPS_BSWMDT_04079]	Usage of {reservedName} for `BswModuleDescription.shortName`

Table C.51: Changed Specification Items in R25-11

C.16.3 Deleted Specification Items in R25-11

Number	Heading
[TPS_BSWMDT_04066]	Relevant elements for ICS on Interface level
[TPS_BSWMDT_04067]	No relevant elements for ICS on Internal Behavior level
[TPS_BSWMDT_04068]	Relevant elements for ICS on Implementation level
[TPS_BSWMDT_04069]	Configuration in ICS
[TPS_BSWMDT_04070]	No variants in ICS
[TPS_BSWMDT_04076]	ECUC features
[TPS_BSWMDT_04077]	Timing requirements and guarantees
[TPS_BSWMDT_04080]	Options for inline code sections
[TPS_BSWMDT_04126]	General meta-model methodology
[TPS_BSWMDT_04171]	HtssM Service Use Case: Query results of hardware tests

Table C.52: Deleted Specification Items in R25-11

C.16.4 Added Constraints in R25-11

Number	Heading
[constr_9357]	Existence of attributes of `McDataInstance` depending on the category

Table C.53: Added Constraints in R25-11

C.16.5 Changed Constraints in R25-11

none

C.16.6 Deleted Constraints in R25-11

none

C.17 Spec Item and Constraint History of this Document according to AUTOSAR R26-11

C.17.1 Added Specification Items in R26-11

none

C.17.2 Changed Specification Items in R26-11

none

C.17.3 Deleted Specification Items in R26-11

none

C.17.4 Added Constraints in R26-11

none

C.17.5 Changed Constraints in R26-11

Number	Heading
[constr_9357]	Existence of attributes of `McDataInstance` depending on the category

Table C.54: Changed Constraints in R26-11

C.17.6 Deleted Constraints in R26-11

none

D Mentioned Class Tables

For the sake of completeness, this chapter contains a set of class tables representing meta-classes mentioned in the context of this document but which are not contained directly in the scope of describing specific meta-model semantics.

Class	***ARElement*** (abstract)			
Note	An element that can be defined stand-alone, i.e. without being part of another element (except for packages of course).			
Base	*ARObject*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Subclasses	*AbstractMessageToSecureChannelMapping*, AclObjectSet, AclOperation, AclPermission, AclRole, AliasNameSet, ApplicabilityInfoSet, ApplicationPartition, *AutosarDataType*, *BaseType*, BlueprintMappingSet, BswEntryRelationshipSet, BswModuleDescription, BswModuleEntry, BuildActionManifest, Calibration ParameterValueSet, ClientIdDefinitionSet, Collection, CompuMethod, ConsistencyNeedsBlueprintSet, ConstantSpecification, ConstantSpecificationMappingSet, CpSoftwareCluster, CpSoftwareClusterBinary ManifestDescriptor, CpSoftwareClusterMappingSet, CpSoftwareClusterResourcePool, CryptoElliptic CurveProps, CryptoServiceCertificate, CryptoServiceKey, CryptoServicePrimitive, CryptoServiceQueue, CryptoSignatureScheme, DataConstr, DataTransformationSet, DataTypeMappingSet, DdsCpConfig, *DiagnosticCommonElement*, DiagnosticConnection, DiagnosticContributionSet, DltArgumentPropsSet, DltContext, DltEcu, Documentation, E2EProfileCompatibilityProps, EcucDefinitionCollection, Ecuc DestinationUriDefSet, EcucModuleConfigurationValues, EcucModuleDef, EcucValueCollection, EthIp Props, EthTcpIpIcmpProps, EthTcpIpProps, EvaluatedVariantSet, FMFeature, FMFeatureMap, FMFeatureModel, FMFeatureSelectionSet, FirewallRule, FlatMap, GeneralPurposeConnection, Hw Category, HwElement, HwType, *IEEE1722TpConnection*, IPSecConfigProps, IPv6ExtHeaderFilterSet, *IdsCommonElement*, IdsDesign, *Implementation*, ImpositionTimeDefinitionGroup, InterpolationRoutine MappingSet, J1939ControllerApplication, KeywordSet, LifeCycleInfoSet, LifeCycleStateDefinitionGroup, LogAndTraceMessageCollectionSet, MacSecGlobalKayProps, MacSecParticipantSet, McFunction, Mc Group, ModeDeclarationGroup, ModeDeclarationMappingSet, OsTaskProxy, PhysicalDimension, PhysicalDimensionMappingSet, *PortInterface*, PortInterfaceMappingSet, PortPrototypeBlueprint, Post BuildVariantCriterion, PostBuildVariantCriterionValueSet, PredefinedVariant, RapidPrototypingScenario, SdgDef, *SecureComProps*, *SecurityConnectivityAssociation*, SignalServiceTranslationPropsSet, Someip SdClientEventGroupTimingConfig, SomeipSdClientServiceInstanceConfig, SomeipSdServerEventGroup TimingConfig, SomeipSdServerServiceInstanceConfig, SwAddrMethod, SwAxisType, SwComponent MappingConstraints, *SwComponentType*, SwRecordLayout, SwSystemconst, SwSystemconstantValue Set, SwcBswMapping, System, SystemComSpecDefinitionSet, SystemSignal, SystemSignalGroup, TDCpSoftwareClusterMappingSet, TcpOptionFilterSet, *TimingExtension*, TlsConnectionGroup, TlvData IdDefinitionSet, TransformationPropsSet, Unit, UnitGroup, *UploadablePackageElement*, ViewMapSet			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table D.1: ARElement

Class	**ARPackage**			
Note	AUTOSAR package, allowing to create top level packages to structure the contained ARElements. ARPackages are open sets. This means that in a file based description system multiple files can be used to partially describe the contents of a package. This is an extended version of MSR's SW-SYSTEM.			
Base	*ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ARPackage.arPackage, AUTOSAR.arPackage			
Attribute	***Type***	***Mult.***	***Kind***	***Note***



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Class	**ARPackage**			
arPackage	ARPackage	*	aggr	This represents a sub package within an ARPackage, thus allowing for an unlimited package hierarchy. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=arPackage, arPackage.shortName, ar Package.variationPoint.shortLabel vh.latestBindingTime=blueprintDerivationTime xml.sequenceOffset=30
element	PackageableElement	*	aggr	Elements that are part of this package **Stereotypes:** atpVariation **Tags:** atp.Splitkey=element, element.shortName, element.variationPoint.shortLabel vh.latestBindingTime=systemDesignTime xml.sequenceOffset=20
referenceBase	ReferenceBase	*	aggr	This denotes the reference bases for the package. This is the basis for all relative references within the package. The base needs to be selected according to the base attribute within the references. **Tags:** atp.Splitkey=referenceBase, referenceBase.shortLabel xml.sequenceOffset=10

Table D.2: ARPackage

Class	**AUTOSAR**			
Note	Root element of an AUTOSAR description, also the root element in corresponding XML documents. **Tags:** xml.globalElement=true			
Base	*ARObject*			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
adminData	AdminData	0..1	aggr	This represents the administrative data of an Autosar file. **Tags:** atp.Splitkey=adminData xml.sequenceOffset=10
arPackage	ARPackage	*	aggr	This is the top level package in an AUTOSAR model. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=arPackage, arPackage.shortName, ar Package.variationPoint.shortLabel vh.latestBindingTime=blueprintDerivationTime xml.sequenceOffset=30
fileInfo Comment	FileInfoComment	0..1	aggr	This represents a possibility to provide a structured comment in an AUTOSAR file. **Stereotypes:** atpStructuredComment **Tags:** atp.Splitkey=fileInfoComment xml.roleElement=true xml.sequenceOffset=-10 xml.typeElement=false

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Class	AUTOSAR			
introduction	DocumentationBlock	0..1	aggr	This represents an introduction on the Autosar file. It is intended for example to represent disclaimers and legal notes. **Tags:** atp.Splitkey=introduction xml.sequenceOffset=20

Table D.3: AUTOSAR

Class	*ApplicationDataType* (abstract)			
Note	`ApplicationDataType` defines a data type from the application point of view. Especially it should be used whenever something "physical" is at stake. An `ApplicationDataType` represents a set of values as seen in the application model, such as measurement units. It does not consider implementation details such as bit-size, endianess, etc. It should be possible to model the application level aspects of a VFB system by using `ApplicationDataType`s only.			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *AutosarDataType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Subclasses	*ApplicationCompositeDataType*, ApplicationPrimitiveDataType			
Aggregated by	ARPackage.element			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table D.4: ApplicationDataType

Class	ArgumentDataPrototype			
Note	An argument of an operation, carries direction and implementation information.			
Base	*ARObject*, *AtpFeature*, *AtpPrototype*, *AutosarDataPrototype*, *DataPrototype*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, ClientServerOperation.argument			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
direction	ArgumentDirectionEnum	0..1	attr	This attribute specifies the direction of the argument.
serverArgumentImplPolicy	ServerArgumentImplPolicyEnum	0..1	attr	This defines how the argument type of the servers `RunnableEntity` is implemented. If the attribute is not defined this has the same semantics as if the attribute is set to the value `useArgumentType` for primitive arguments and structures.

Table D.5: ArgumentDataPrototype

Class	AsynchronousServerCallResultPoint
Note	If a `RunnableEntity` owns an `AsynchronousServerCallResultPoint` it is entitled to get the result of the referenced `AsynchronousServerCallPoint`. If it is associated with an `AsynchronousServerCallReturnsEvent`, this `RTEEvent` notifies the completion of the required `ClientServerOperation` or a timeout. The occurrence of this event can either unblock a `WaitPoint` or can lead to the invocation of a `RunnableEntity`. This Class is only used by the AUTOSAR Classic Platform.
Base	*ARObject*, *AbstractAccessPoint*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*

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Class	**AsynchronousServerCallResultPoint**			
Aggregated by	*AtpClassifier*.atpFeature, RunnableEntity.asynchronousServerCallResultPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
asynchronous ServerCallPoint	AsynchronousServer CallPoint	0..1	ref	The referenced Asynchronous Server Call Point defines the asynchronous server call from which the results are returned. **Tags:** atp.Splitkey=asynchronousServerCallPoint

Table D.6: AsynchronousServerCallResultPoint

Class	***AtomicSwComponentType*** (abstract)			
Note	An atomic software component is atomic in the sense that it cannot be further decomposed and distributed across multiple ECUs.			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*, *SwComponentType*			
Subclasses	ApplicationSwComponentType, ComplexDeviceDriverSwComponentType, EcuAbstractionSwComponent Type, NvBlockSwComponentType, SensorActuatorSwComponentType, ServiceProxySwComponent Type, ServiceSwComponentType			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
internalBehavior	SwcInternalBehavior	0..1	aggr	The `SwcInternalBehavior`s owned by an `AtomicSwComponentType` can be located in a different physical file. Therefore the aggregation is <<atp Splitable>>. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=internalBehavior, internalBehavior.short Name, internalBehavior.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
symbolProps	SymbolProps	0..1	aggr	This represents the `SymbolProps` for the `AtomicSwComponentType`. **Tags:** atp.Splitkey=symbolProps, symbolProps.short Name

Table D.7: AtomicSwComponentType

Class	***AtpBlueprint*** (abstract)			
Note	This meta-class represents the ability to act as a Blueprint. As this class is an abstract one, particular blueprint meta-classes inherit from this one.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	ARPackage, *AbstractImplementationDataType*, AclObjectSet, AclOperation, AclPermission, AclRole, AliasNameSet, *ApplicationDataType*, BswEntryRelationshipSet, BswModuleDescription, BswModule Entry, *BuildActionEntity*, BuildActionEnvironment, BuildActionManifest, CompuMethod, Consistency Needs, DataConstr, DataTypeMappingSet, EcucDefinitionCollection, EcucDestinationUriDefSet, Ecuc ModuleDef, FlatMap, ImpositionTime, ImpositionTimeDefinitionGroup, KeywordSet, LifeCycleState, Life CycleStateDefinitionGroup, ModeDeclarationGroup, *PortInterface*, *PortInterfaceMapping*, PortInterface MappingSet, PortPrototypeBlueprint, SecurityEventContextDataElement, SwAddrMethod, SwBaseType, *SwComponentType*, VfbTiming			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
blueprintPolicy	BlueprintPolicy	*	aggr	This role indicates whether the blueprintable element will be modifiable or not modifiable. **Tags:** atp.Splitkey=blueprintPolicy, blueprint Policy.attributeName

Table D.8: AtpBlueprint

Class	***AtpInstanceRef*** (abstract)			
Note	An M0 instance of a classifier may be represented as a tree rooted at that instance, where under each node come the sub-trees representing the instances which act as features under that node. An instance ref specifies a navigation path from any M0 tree-instance of the base (which is a classifier) to a leaf (which is an instance of the target).			
Base	*ARObject*			
Subclasses	AnyInstanceRef, ApplicationCompositeElementInPortInterfaceInstanceRef, ComponentInComposition InstanceRef, ComponentInSystemInstanceRef, *DataPrototypeInPortInterfaceInstanceRef*, Data PrototypeInSystemInstanceRef, InnerDataPrototypeGroupInCompositionInstanceRef, InnerPortGroupIn CompositionInstanceRef, InnerRunnableEntityGroupInCompositionInstanceRef, InstanceEventIn CompositionInstanceRef, ModeDeclarationGroupPrototypeInSystemInstanceRef, *ModeGroupInAtomic SwcInstanceRef*, ModeInBswInstanceRef, ModeInBswModuleDescriptionInstanceRef, ModeInSwc InstanceRef, OperationArgumentInComponentInstanceRef, *OperationInAtomicSwcInstanceRef*, OperationInSystemInstanceRef, PModeInSystemInstanceRef, ParameterDataPrototypeInSystem InstanceRef, ParameterInAtomicSWCTypeInstanceRef, PortGroupInSystemInstanceRef, *PortIn CompositionTypeInstanceRef*, RModeInAtomicSwcInstanceRef, RteEventInCompositionInstanceRef, RteEventInEcuInstanceRef, RteEventInSystemInstanceRef, RunnableEntityInCompositionInstanceRef, SwcServiceDependencyInSystemInstanceRef, *TriggerInAtomicSwcInstanceRef*, TriggerInSystem InstanceRef, VariableAccessInEcuInstanceRef, VariableDataPrototypeInCompositionInstanceRef, VariableDataPrototypeInSystemInstanceRef, VariableInAtomicSWCTypeInstanceRef, *VariableInAtomic SwcInstanceRef*, VariableInComponentInstanceRef			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
atpBase	AtpClassifier	0..1	ref	This is the base from which the navigaion path starts. **Stereotypes:** atpAbstract; atpDerived
atpContext Element (ordered)	AtpPrototype	*	ref	This is one particular step in the navigation path. **Stereotypes:** atpAbstract
atpTarget	AtpFeature	0..1	ref	This is the target of the instance ref. In other words it is the terminal of the navigation path. **Stereotypes:** atpAbstract

Table D.9: AtpInstanceRef

Class	***AutosarDataPrototype*** (abstract)			
Note	Base class for prototypical roles of an `AutosarDataType`.			
Base	*ARObject*, *AtpFeature*, *AtpPrototype*, *DataPrototype*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	ArgumentDataPrototype, ParameterDataPrototype, VariableDataPrototype			
Aggregated by	*AtpClassifier*.atpFeature			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
type	AutosarDataType	0..1	tref	This represents the corresponding data type. **Stereotypes:** isOfType **Tags:** atp.Splitkey=type

Table D.10: AutosarDataPrototype

Class	***AutosarDataType*** (abstract)			
Note	Abstract base class for user defined AUTOSAR data types for software.			
Base	*ARElement*, *ARObject*, *AtpClassifier*, *AtpType*, *CollectableElement*, *Identifiable*, *Multilanguage Referrable*, *PackageableElement*, *Referrable*			
Subclasses	*AbstractImplementationDataType*, *ApplicationDataType*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
swDataDef Props	SwDataDefProps	0..1	aggr	The properties of this AutosarDataType. **Tags:** atp.Splitkey=swDataDefProps

Table D.11: AutosarDataType

Class	**AutosarParameterRef**			
Note	This class represents a reference to a parameter within AUTOSAR which can be one of the following use cases: localParameter: • localParameter which is used as whole (e.g. sharedAxis for curve) autosarVariable: • a parameter provided via `PortPrototype` which is used as whole (e.g. parameterAccess) • an element inside of a composite local parameter typed by `ApplicationDataType` (e.g. sharedAxis for a curve) • an element inside of a composite parameter provided via Port and typed by `ApplicationDataType` (e.g. sharedAxis for a curve) autosarParameterInImplDatatype: • an element inside of a composite local parameter typed by ImplementationDatatype • an element inside of a composite parameter provided via PortPrototype and typed by Implementation Datatype			
Base	*ARObject*			
Aggregated by	InstantiationDataDefProps.parameterInstance, ParameterAccess.accessedParameter, RoleBasedData Assignment.usedParameterElement, SwCalprmRefProxy.arParameter			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
autosar Parameter	DataPrototype	0..1	iref	This instance reference is used if the calibration parameter is either imported via a port or is part of a composite data structure. **Tags:** atp.Splitkey=autosarParameter, autosar Parameter.portPrototype, autosarParameter.root ParameterDataPrototype, autosarParameter.contextData Prototype, autosarParameter.targetDataPrototype **InstanceRef implemented by:** ParameterInAtomic SWCTypeInstanceRef
localParameter	DataPrototype	0..1	ref	In the majority of cases this reference goes to Parameter DataPrototypes rather than VariableDataPrototypes. Pointing the reference to a VariableDataPrototype is limited to special use cases, e.g. if the AutosarParameter Ref is used in the context of an SwAxisGrouped. This reference is used if the arParameter is local to the current component. Of course, it would technically also be feasible to use an InstanceRef for this case. However, the InstanceRef would not have a contextElement (because the current instance is the context). Hence, the local instance is a special case which may provide further optimization. Therefore an explicit reference is provided for this case. **Tags:** atp.Splitkey=localParameter

Table D.12: AutosarParameterRef

Class	**AutosarVariableRef**			
Note	This class represents a reference to a variable within AUTOSAR which can be one of the following use cases: localVariable: • localVariable which is used as whole (e.g. InterRunnableVariable, inputValue for curve) autosarVariable: • a variable provided via Port which is used as whole (e.g. dataAccessPoints) • an element inside of a composite local variable typed by `ApplicationDataType` (e.g. inputValue for a curve) • an element inside of a composite variable provided via `PortPrototype` and typed by `ApplicationDataType` (e.g. inputValue for a curve) autosarVariableInImplDatatype: • an element inside of a composite local variable typed by `ImplementationDataType` (e.g. nvram Data mapping) • an element inside of a composite variable provided via Port and typed by `ImplementationDataType` (e.g. inputValue for a curve)			
Base	*ARObject*			
Aggregated by	InstantiationDataDefProps.variableInstance, NvBlockDataMapping.nvRamBlockElement, NvBlockDataMapping.readNvData, NvBlockDataMapping.writtenNvData, NvBlockDataMapping.writtenReadNvData, RoleBasedDataAssignment.usedDataElement, SwVariableRefProxy.autosarVariable, VariableAccess.accessedVariable			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
autosarVariable	DataPrototype	0..1	iref	This references a variable which is provided by a port and/or which is part of a CompositeDataType. **Tags:** atp.Splitkey=autosarVariable, autosarVariable.portPrototype, autosarVariable.rootVariableDataPrototype, autosarVariable.contextDataPrototype, autosarVariable.targetDataPrototype **InstanceRef implemented by:** VariableInAtomicSWCTypeInstanceRef
autosarVariableInImplDatatype	ArVariableInImplementationDataInstanceRef	0..1	aggr	This is used if the target variable is inside of variableDataPrototype typed by an ImplementationDataType. **Tags:** atp.Splitkey=autosarVariableInImplDatatype, autosarVariableInImplDatatype.portPrototype, autosarVariableInImplDatatype.rootVariableDataPrototype, autosarVariableInImplDatatype.contextDataPrototype, autosarVariableInImplDatatype.targetDataPrototype
localVariable	VariableDataPrototype	0..1	ref	This reference is used if the variable is local to the current component. It would also be possible to use the instance refence here. Such an instance ref would not have a contextElement, since the current instance is the context. But the local instance is a special case which may provide further optimization. Therefore an explicit reference is provided for this case. **Tags:** atp.Splitkey=localVariable

Table D.13: AutosarVariableRef

Enumeration	**BindingTimeEnum**
Note	This enumerator specifies the applicable binding times for the pre build variation points.
Aggregated by	ConditionByFormula.bindingTime, FMFeature.maximumIntendedBindingTime, FMFeature.minimumIntendedBindingTime, FMFeatureSelection.maximumSelectedBindingTime, FMFeatureSelection.minimumSelectedBindingTime
Literal	***Description***

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Enumeration	**BindingTimeEnum**
codeGeneration Time	• Coding by hand, based on requirements document. • Tool based code generation, e.g. from a model. • The model may contain variants. • Only code for the selected variant(s) is actually generated. **Tags:** atp.EnumerationLiteralIndex=0
linkTime	Configure what is included in object code, and what is omitted Based on which variant(s) are selected E.g. for modules that are delivered as object code (as opposed to those that are delivered as source code) **Tags:** atp.EnumerationLiteralIndex=1
preCompileTime	This is typically the C-Preprocessor. Exclude parts of the code from the compilation process, e.g., because they are not required for the selected variant, because they are incompatible with the selected variant, because they require resources that are not present in the selected variant. Object code is only generated for the selected variant(s). The code that is excluded at this stage code will not be available at later stages. **Tags:** atp.EnumerationLiteralIndex=2
systemDesignTime	• Designing the VFB. • Software Component types (PortInterfaces). • SWC Prototypes and the Connections between SWCprototypes. • Designing the Topology • ECUs and interconnecting Networks • Designing the Communication Matrix and Data Mapping **Tags:** atp.EnumerationLiteralIndex=3

Table D.14: BindingTimeEnum

Class	**ClientServerInterface**			
Note	A client/server interface declares a number of operations that can be invoked on a server by a client. **Tags:** atp.recommendedPackage=PortInterfaces			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *PortInterface*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
operation	ClientServerOperation	*	aggr	`ClientServerOperation`(s) of this `ClientServerInterface`. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=operation, operation.shortName, operation.variationPoint.shortLabel vh.latestBindingTime=blueprintDerivationTime This Attribute is only used by the AUTOSAR Classic Platform.
possibleError	ApplicationError	*	aggr	Application errors that are defined as part of this interface. **Tags:** atp.Splitkey=possibleError, possibleError.short Name

Table D.15: ClientServerInterface

Class	**ClientServerOperation**			
Note	An operation declared within the scope of a client/server interface.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	ApplicationInterface.command, *AtpClassifier*.atpFeature, ClientServerInterface.operation, DiagnosticDataElementInterface.read, DiagnosticDataIdentifierInterface.read, DiagnosticDataIdentifierInterface.write, DiagnosticExtendedDataRecordInterface.provide, DiagnosticRoutineInterface.requestResult, DiagnosticRoutineInterface.start, DiagnosticRoutineInterface.stop, ServiceInterface.method			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
argument (ordered)	ArgumentDataPrototype	*	aggr	An argument of this `ClientServerOperation`. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=blueprintDerivationTime
diagArgIntegrity	Boolean	0..1	attr	This attribute shall only be used in the implementation of diagnostic routines to support the case where input and output arguments are allocated in a shared buffer and might unintentionally overwrite input arguments by tentative write operations to output arguments. This situation can happen during sliced execution or while output parameters are arrays (call by reference). The value true means that the `ClientServerOperation` is aware of the usage of a shared buffer and takes precautions to avoid unintentional overwrite of input arguments. If the attribute does not exist or is set to false the `ClientServerOperation` does not have to consider the usage of a shared buffer. This Attribute is only used by the AUTOSAR Classic Platform.
possibleError	ApplicationError	*	ref	Possible errors that may by raised by the referring operation. **Tags:** atp.Splitkey=possibleError This Attribute is only used by the AUTOSAR Classic Platform.

Table D.16: ClientServerOperation

Class	**ComplexDeviceDriverSwComponentType**			
Note	The ComplexDeviceDriverSwComponentType is a special AtomicSwComponentType that has direct access to hardware on an ECU and which is therefore linked to a specific ECU or specific hardware. The ComplexDeviceDriverSwComponentType introduces the possibility to link from the software representation to its hardware description provided by the ECU Resource Template. **Tags:** atp.recommendedPackage=SwComponentTypes			
Base	*ARElement*, *ARObject*, *AtomicSwComponentType*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*, *SwComponentType*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
hardware Element	HwDescriptionEntity	*	ref	Reference from the ComplexDeviceDriverSwComponent Type to the description of the used HwElements. **Tags:** atp.Splitkey=hardwareElement

Table D.17: ComplexDeviceDriverSwComponentType

Class	CompuMethod			
Note	This meta-class represents the ability to express the relationship between a physical value and the mathematical representation. Note that this is still independent of the technical implementation in data types. It only specifies the formula how the internal value corresponds to its physical pendant. **Tags:** atp.recommendedPackage=CompuMethods			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
compuInternalToPhys	Compu	0..1	aggr	This specifies the computation from internal values to physical values. **Tags:** atp.Splitkey=compuInternalToPhys xml.sequenceOffset=80
compuPhysToInternal	Compu	0..1	aggr	This represents the computation from physical values to the internal values. **Tags:** atp.Splitkey=compuPhysToInternal xml.sequenceOffset=90
displayFormat	DisplayFormatString	0..1	attr	This property specifies, how the physical value shall be displayed e.g. in documents or measurement and calibration tools. **Tags:** xml.sequenceOffset=20
unit	Unit	0..1	ref	This is the physical unit of the Physical values for which the CompuMethod applies. **Tags:** atp.Splitkey=unit xml.sequenceOffset=30

Table D.18: CompuMethod

Class	*DataPrototype* (abstract)			
Note	Base class for prototypical roles of any data type.			
Base	*ARObject*, *AtpFeature*, *AtpPrototype*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	*ApplicationCompositeElementDataPrototype*, *AutosarDataPrototype*			
Aggregated by	*AtpClassifier*.atpFeature			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
swDataDefProps	SwDataDefProps	0..1	aggr	This property allows to specify data definition properties which apply on data prototype level. **Tags:** atp.Splitkey=swDataDefProps

Table D.19: DataPrototype

Class	DataTypeMappingSet
Note	This class represents a list of mappings between `ApplicationDataType`s and `ImplementationDataType`s. In addition, it can contain mappings between `ImplementationDataType`s and `ModeDeclarationGroup`s. **Tags:** atp.recommendedPackage=DataTypeMappingSets
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*
Aggregated by	ARPackage.element



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Class	**DataTypeMappingSet**			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
dataTypeMap	DataTypeMap	*	aggr	This is one particular association between an `ApplicationDataType` and its `AbstractImplementationDataType`. **Tags:** atp.Splitkey=dataTypeMap
modeRequest TypeMap	ModeRequestTypeMap	*	aggr	This is one particular association between an `ModeDeclarationGroup` and its `AbstractImplementationDataType`. **Tags:** atp.Splitkey=modeRequestTypeMap

Table D.20: DataTypeMappingSet

Class	**DiagnosticComponentNeeds**			
Note	This meta-class represents the ability to specify the service needs for the configuration of component events.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table D.21: DiagnosticComponentNeeds

Class	**DiagnosticEventInfoNeeds**			
Note	This meta-class represents the needs of a software-component interested to get information regarding specific DTCs.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
obdDtcNumber	PositiveInteger	0..1	attr	This represents a reasonable Diagnostic Trouble Code. This allows to predefine the Diagnostic Trouble Code, e.g. if the function developer has received a particular requirement from the OEM or from a standardization body. This attribute applies for the OBD diagnostics use case.
udsDtcNumber	PositiveInteger	0..1	attr	This represents a reasonable Diagnostic Trouble Code. This allows to predefine the Diagnostic Trouble Code, e.g. if the function developer has received a particular requirement from the OEM or from a standardization body. This attribute applies for the UDS diagnostics use case.

Table D.22: DiagnosticEventInfoNeeds

Class	EcuAbstractionSwComponentType			
Note	The ECUAbstraction is a special AtomicSwComponentType that resides between a software-component that wants to access ECU periphery and the Microcontroller Abstraction. The EcuAbstractionSw ComponentType introduces the possibility to link from the software representation to its hardware description provided by the ECU Resource Template. **Tags:** atp.recommendedPackage=SwComponentTypes			
Base	*ARElement*, *ARObject*, *AtomicSwComponentType*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *Collectable Element*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*, *SwComponentType*			
Aggregated by	ARPackage.element			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
hardware Element	HwDescriptionEntity	*	ref	Reference from the EcuAbstractionComponentType to the description of the used HwElements. **Tags:** atp.Splitkey=hardwareElement

Table D.23: EcuAbstractionSwComponentType

Class	EcucModuleConfigurationValues			
Note	Head of the configuration of one Module. A Module can be a BSW module as well as the RTE and ECU Infrastructure. As part of the BSW module description, the EcucModuleConfigurationValues element has two different roles: The recommendedConfiguration contains parameter values recommended by the BSW module vendor. The preconfiguredConfiguration contains values for those parameters which are fixed by the implementation and cannot be changed. These two EcucModuleConfigurationValues are used when the base EcucModuleConfigurationValues (as part of the base ECU configuration) is created to fill parameters with initial values. **Tags:** atp.recommendedPackage=EcucModuleConfigurationValuess This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *Packageable Element*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
container	EcucContainerValue	*	aggr	Aggregates all containers that belong to this module configuration. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=container, container.shortName, container.variationPoint.shortLabel vh.latestBindingTime=postBuild xml.sequenceOffset=10
definition	EcucModuleDef	0..1	ref	Reference to the definition of this EcucModule ConfigurationValues element. Typically, this is a vendor specific module configuration. **Tags:** atp.Splitkey=definition xml.sequenceOffset=-10
ecucDefEdition	RevisionLabelString	0..1	attr	This is the version info of the ModuleDef ECUC Parameter definition to which this values conform to / are based on. For the Definition of ModuleDef ECUC Parameters the AdminData shall be used to express the semantic changes. The compatibility rules between the definition and value revision labels is up to the module's vendor.

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Class	**EcucModuleConfigurationValues**			
implementation ConfigVariant	EcucConfiguration VariantEnum	0..1	attr	Specifies the kind of deliverable this EcucModule ConfigurationValues element provides. If this element is not used in a particular role (e.g. preconfigured Configuration or recommendedConfiguration) then the value shall be one of VariantPreCompile, VariantLink Time, VariantPostBuild. **Tags:** atp.Status=obsolete
module Description	BswImplementation	0..1	ref	Referencing the BSW module description, which this EcucModuleConfigurationValues element is configuring. This is optional because the EcucModuleConfiguration Values element is also used to configure the ECU infrastructure (memory map) or Application SW-Cs. However in case the EcucModuleConfigurationValues are used to configure the module, the reference is mandatory in order to fetch module specific "common" published information. **Tags:** atp.Splitkey=moduleDescription
postBuildVariant Used	Boolean	0..1	attr	Indicates whether a module implementation has or plans to have (i.e., introduced at link or post-build time) new post-build variation points. TRUE means yes, FALSE means no. If the attribute is not defined, FALSE semantics shall be assumed.

Table D.24: EcucModuleConfigurationValues

Class	**EcucModuleDef**			
Note	Used as the top-level element for configuration definition for Software Modules, including BSW and RTE as well as ECU Infrastructure. **Tags:** atp.recommendedPackage=EcucDefs This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *AtpDefinition*, *CollectableElement*, *EcucDefinitionElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
apiServicePrefix	CIdentifier	0..1	attr	For modules where several instances of the VSMD can be defined the apiServicePrefix defines the API namespace of the derived instances, e.g. Cdd, Xfrm (ComXf, SomeIpXf, E2EXf).
container	EcucContainerDef	*	aggr	Aggregates the top-level container definitions of this specific module definition. **Tags:** atp.Splitkey=container, container.shortName xml.sequenceOffset=11
postBuild Loadable Support	Boolean	0..1	attr	Indicates if the module supports changing the configuration by loading a new configuration binary at postBuild time. TRUE means yes, FALSE means no.
postBuildVariant Support	Boolean	0..1	attr	Indicates if a module supports different post-build variants (previously known as post-build selectable configuration sets). TRUE means yes, FALSE means no.

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Class	**EcucModuleDef**			
refinedModule Def	EcucModuleDef	0..1	ref	Optional reference from the Vendor Specific Module Definition to the Standardized Module Definition it refines. In case this EcucModuleDef has the category STANDARDIZED_MODULE_DEFINITION this reference shall not be provided. In case this EcucModuleDef has the category VENDOR_SPECIFIC_MODULE_ DEFINITION this reference is mandatory. **Stereotypes:** atpUriDef **Tags:** atp.Splitkey=refinedModuleDef
supported ConfigVariant	EcucConfiguration VariantEnum	*	attr	Specifies which ConfigurationVariants are supported by this software module. This attribute is optional if the Ecuc ModuleDef has the category STANDARDIZED_ MODULE_DEFINITION. If the category attribute of the EcucModuleDef is set to VENDOR_SPECIFIC_ MODULE_DEFINITION then this attribute is mandatory. **Tags:** atp.Status=obsolete

Table D.25: EcucModuleDef

Class	**EvaluatedVariantSet**			
Note	This meta class represents the ability to express if a set of ARElements is able to support one or more particular variants. In other words, for a given set of evaluatedElements this meta class represents a table of evaluated variants, where each PredefinedVariant represents one column. In this column each descendant sw SystemconstantValue resp. postbuildVariantCriterionValue represents one entry. In a graphical representation each swSystemconstantValueSet / postBuildVariantCriterionValueSet could be used as an intermediate headline in the table column. If the approvalStatus is "APPROVED" it expresses that the collection of CollectableElements is known be valid for the given evaluatedVariants. Note that the EvaluatedVariantSet is a CollectableElement. This allows to establish a hierarchy of EvaluatedVariantSets. **Tags:** atp.recommendedPackage=EvaluatedVariantSets			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *Packageable Element*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
approvalStatus	NameToken	0..1	attr	Defines the approval status of a predefined variant. Two values are predefined: "APPROVED" and "REJECTED": • Approved variants are known to work. • Rejected variants are known NOT to work. Further values can be approved on a per-company basis; within AUTOSAR only "APPROVED" and "REJECTED" should be recognized.
evaluated Element	CollectableElement	*	ref	This represents a particular element which is evaluated in context of the EvaluatedVariants. The approvalStatus applies to this element (and all of its descendants). In other words, the referenced elements are those that were considered when the predefined variant was evaluated. **Tags:** atp.Splitkey=evaluatedElement
evaluated Variant	PredefinedVariant	*	ref	This metaclass represents one particular variant which was evaluated. LowerMultiplicity is set to 0 to support a stepwise approach. **Tags:** atp.Splitkey=evaluatedVariant

Table D.26: EvaluatedVariantSet

Class	**ExecutableEntityActivationReason**			
Note	This meta-class represents the ability to define the reason for the activation of the enclosing `ExecutableEntity`.			
Base	*ARObject*, *ImplementationProps*, *Referrable*			
Aggregated by	*ExecutableEntity*.activationReason			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bitPosition	PositiveInteger	0..1	attr	This attribute allows for defining the position of the enclosing ExecutableEntityActivationReason in the activation vector.

Table D.27: ExecutableEntityActivationReason

Class	**ExternalTriggeringPoint**			
Note	If a RunnableEntity owns an ExternalTriggeringPoint it is entitled to raise an ExternalTriggerOccurred Event.			
Base	*ARObject*			
Aggregated by	RunnableEntity.externalTriggeringPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
ident	ExternalTriggeringPoint Ident	0..1	aggr	The aggregation in the role ident provides the ability to make the ExternalTriggeringPoint identifiable. From the semantical point of view, the ExternalTriggering Point is considered a first-class Identifiable and therefore the aggregation in the role ident shall always exist (until it may be possible to let ModeAccessPoint directly inherit from Identifiable). **Stereotypes:** atpIdentityContributor **Tags:** xml.sequenceOffset=-100
trigger	Trigger	0..1	iref	The trigger taken for the ExternalTriggeringPoint. **Tags:** atp.Splitkey=trigger, trigger.contextPPort, trigger.target Trigger xml.namePlural=TRIGGER-IREF xml.roleElement=false xml.roleWrapperElement=true xml.typeElement=true xml.typeWrapperElement=false **InstanceRef implemented by:** PTriggerInAtomicSwc TypeInstanceRef

Table D.28: ExternalTriggeringPoint

Class	**FlatInstanceDescriptor**
Note	Represents exactly one node (e.g. a component instance or data element) of the instance tree of a software system. The purpose of this element is to map the various nested representations of this instance to a flat representation and assign a unique name (shortName) to it. Use cases: • Specify unique names of measurable data to be used by MCD tools • Specify unique names of calibration data to be used by MCD tool • Specify a unique name for an instance of a component prototype in the ECU extract of the system description Note that in addition it is possible to assign alias names via AliasNameAssignment. This Class is only used by the AUTOSAR Classic Platform.
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*
Aggregated by	FlatMap.instance



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Class	**FlatInstanceDescriptor**			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
bsw Implementation	BswImplementation	0..1	ref	Reference to BswImplementation that defines the context for the AutosarDataPrototype that is referenced by Flat InstanceDescriptor.dataPrototype. **Tags:** atp.Splitkey=bswImplementation
dataPrototype	AutosarDataPrototype	0..1	ref	Reference to a DataPrototype that is defined in the Bsw InternalBehavior in the context of a BswImplementation that is defined by the FlatInstanceDescriptor.bsw Implementation reference. **Tags:** atp.Splitkey=dataPrototype
ecuExtract Reference	AtpFeature	0..1	iref	Refers to the instance in the ECU extract. This is valid only, if the FlatMap is used in the context of an ECU extract. The reference shall be such that it uniquely defines the object instance. For example, if a data prototype is declared as a role within an SwcInternalBehavior, it is not enough to state the SwcInternalBehavior as context and the aggregated data prototype as target. In addition, the reference shall also include the complete path identifying instance of the component prototype and the Atomic SoftwareComponentType, which is refered by the particular SwcInternalBehavior. **Tags:** atp.Splitkey=ecuExtractReference, ecuExtract Reference.contextElement, ecuExtractReference.target xml.sequenceOffset=40 **InstanceRef implemented by:** AnyInstanceRef
role	Identifier	0..1	attr	The role denotes the particular role of the downstream memory location described by this FlatInstanceDescriptor. It applies to use case where one upstream object results in multiple downstream objects, e.g. ModeDeclaration GroupPrototypes which are measurable. In this case the RTE will provide locations for current mode, previous mode and next mode.
rtePluginProps	RtePluginProps	0..1	aggr	The properties of a communication graph with respect to the utilization of RTE Implementation Plug-in. **Tags:** atp.Splitkey=rtePluginProps
swDataDef Props	SwDataDefProps	0..1	aggr	The properties of this FlatInstanceDescriptor. **Tags:** atp.Splitkey=swDataDefProps
upstream Reference	AtpFeature	0..1	iref	Refers to the instance in the context of an "upstream" description, which could be: the SYSTEM_ DESCRIPTION, or SYSTEM_EXTRACT, or ECU_ SYSTEM_DESCRIPTION, or SW_CLUSTER_SYSTEM_ DESCRIPTION, or the basic software module description (in this case only the target reference of the AnyInstance Ref is needed), or (if a flat map is used in preliminary context) a description of an atomic component or composition. This reference is optional in case the flat map is used in ECU context. The reference shall be such that it uniquely defines the object instance in the given context. For example, if a data prototype is declared as a role within an SwcInternal Behavior, it is not enough to state the Swc Internal Behavior as context and the aggregated data prototype as target. In addition, the reference shall also include the complete path identifying the instance of the ▽

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Class	FlatInstanceDescriptor			
				△ component prototype that contains the particular instance of Swc InternalBehavior. **Tags:** atp.Splitkey=upstreamReference, upstream Reference.contextElement, upstreamReference.target xml.sequenceOffset=20 **InstanceRef implemented by:** AnyInstanceRef

Table D.29: FlatInstanceDescriptor

Class	FlatMap			
Note	Contains a flat list of references to software objects. This list is used to identify instances and to resolve name conflicts. The scope is given by the RootSwCompositionPrototype for which it is used, i.e. it can be applied to a system, system extract or ECU-extract. An instance of FlatMap may also be used in a preliminary context, e.g. in the scope of a software component before integration into a system. In this case it is not referred by a RootSwComposition Prototype. **Tags:** atp.recommendedPackage=FlatMaps This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
instance	FlatInstanceDescriptor	*	aggr	A descriptor instance aggregated in the flat map. The variation point accounts for the fact, that the system in scope can be subject to variability, and thus the existence of some instances is variable. The aggregation has been made splitable because the content might be contributed by different stakeholders at different times in the workflow. Plus, the overall size might be so big that eventually it becomes more manageable if it is distributed over several files. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=instance, instance.shortName, instance.variationPoint.shortLabel vh.latestBindingTime=postBuild

Table D.30: FlatMap

Enumeration	FullBindingTimeEnum
Note	This enumeration specifies the BindingTimes that can be used in AUTOSAR models.
Aggregated by	*AbstractVariationRestriction*.validBindingTime, *AttributeValueVariationPoint*.bindingTime
Literal	**Description**
blueprintDerivation Time	The point in time when an object is created from a blueprint. **Tags:** atp.EnumerationLiteralIndex=0

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Enumeration	**FullBindingTimeEnum**
codeGeneration Time	• Coding by hand, based on requirements document. • Tool based code generation, e.g. from a model. • The model may contain variants. • Only code for the selected variant(s) is actually generated. **Tags:** atp.EnumerationLiteralIndex=2
linkTime	Configure what is included in object code, and what is omitted Based on which variant(s) are selected E.g. for modules that are delivered as object code (as opposed to those that are delivered as source code) **Tags:** atp.EnumerationLiteralIndex=4
postBuild	PostBuild is the binding time which is bound latest at startup of the ECU. In other words this is everything between creation of the executable program and startup of the ECU. **Tags:** atp.EnumerationLiteralIndex=5
preCompileTime	This is typically the C-Preprocessor. Exclude parts of the code from the compilation process, e.g., because they are not required for the selected variant, because they are incompatible with the selected variant, because they require resources that are not present in the selected variant. Object code is only generated for the selected variant(s). The code that is excluded at this stage code will not be available at later stages. **Tags:** atp.EnumerationLiteralIndex=3
systemDesignTime	• Designing the VFB. • Software Component types (PortInterfaces). • SWC Prototypes and the Connections between SWCprototypes. • Designing the Topology • ECUs and interconnecting Networks • Designing the Communication Matrix and Data Mapping **Tags:** atp.EnumerationLiteralIndex=1

Table D.31: FullBindingTimeEnum

Class	**FunctionInhibitionAvailabilityNeeds**			
Note	Specifies the abstract needs on the configuration of the Function Inhibition Manager to provide the control function for one Function Identifier (FID).			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
controlledFid	FunctionInhibitionNeeds	0..1	ref	This reference represents the controlled FID **Tags:** atp.Splitkey=controlledFid

Table D.32: FunctionInhibitionAvailabilityNeeds

Class	**GlobalSupervisionNeeds**			
Note	Specifies the abstract needs on the configuration of the Watchdog Manager to get access on the Global Supervision control and status interface.			
Base	*ARObject*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
–	–	–	–	–

Table D.33: GlobalSupervisionNeeds

Class	***Identifiable*** (abstract)			
Note	Instances of this class can be referred to by their identifier (within the namespace borders). In addition to this, Identifiables are objects which contribute significantly to the overall structure of an AUTOSAR description. In particular, Identifiables might contain Identifiables.			
Base	*ARObject*, *MultilanguageReferrable*, *Referrable*			
Subclasses	ARPackage, *AbstractDoIpLogicAddressProps*, *AbstractEvent*, *AbstractImplementationDataTypeElement*, *AbstractSecurityEventFilter*, *AbstractSecurityIdsmInstanceFilter*, *AbstractServiceInstance*, AppOsTask ProxyToEcuTaskProxyMapping, ApplicationEndpoint, ApplicationError, ApplicationPartitionToEcuPartition Mapping, AppliedStandard, AsynchronousServerCallResultPoint, *AtpBlueprint*, *AtpClassifier*, *Atp Feature*, AutosarOperationArgumentInstance, AutosarVariableInstance, *BinaryManifestAddressable Object*, BinaryManifestItemDefinition, *BinaryManifestResource*, BinaryManifestResourceDefinition, Block State, BswInternalTriggeringPoint, BswModuleDependency, *BuildActionEntity*, BuildActionEnvironment, CanSecSecureChannel, CanTpAddress, CanTpChannel, CanTpNode, Chapter, ClientIdDefinition, Client ServerOperation, Code, *CollectableElement*, ComManagementMapping, *CommConnectorPort*, *CommunicationConnector*, *CommunicationController*, Compiler, ConsistencyNeeds, ConsumedEvent Group, *CouplingElementAbstractDetails*, CouplingPort, *CouplingPortAbstractShaper*, *CouplingPort StructuralElement*, *CpSoftwareClusterResource*, CpSoftwareClusterResourceToApplicationPartition Mapping, CpSoftwareClusterToApplicationPartitionMapping, CpSoftwareClusterToEcuInstanceMapping, CpSoftwareClusterToResourceMapping, *CryptoServiceMapping*, CyclicHandlingComDataToOsTask ProxyMapping, DataPrototypeGroup, DataPrototypeTransformationPropsIdent, DataTransformation, *Dds AbstractServiceInstanceElementCp*, DdsCpDomain, DdsCpPartition, DdsCpQosProfile, DdsCpTopic, DependencyOnArtifact, *DiagEventDebounceAlgorithm*, DiagnosticAuthTransmitCertificateEvaluation, DiagnosticConnectedIndicator, DiagnosticDataElement, DiagnosticDebounceAlgorithmProps, Diagnostic ExtendedDataRecordElement, DiagnosticFunctionInhibitSource, DiagnosticParameterElement, *DiagnosticRoutineSubfunction*, DltApplication, DltArgument, DltArgumentProps, DltLogChannel, Dlt Message, DoIpInterface, DoIpLogicAddress, DoIpRoutingActivation, ECUMapping, *EOCExecutableEntity RefAbstract*, EcuPartition, EcuPartitionToCoreMapping, EcucContainerValue, *EcucDefinitionElement*, EcucDestinationUriDef, EcucEnumerationLiteralDef, EcucQuery, EcucValidationCondition, Ethernet WakeupSleepOnDatalineConfig, EventHandler, ExclusiveArea, *ExecutableEntity*, *ExecutionTime*, FMAttributeDef, FMFeatureMapAssertion, FMFeatureMapCondition, FMFeatureMapElement, FMFeature Relation, FMFeatureRestriction, FMFeatureSelection, FlatInstanceDescriptor, FlexrayTpConnection Control, FlexrayTpNode, FlexrayTpPduPool, *FrameTriggering*, GlobalTimeGateway, *GlobalTimeMaster*, *GlobalTimeSlave*, *HeapUsage*, HwAttributeDef, HwAttributeLiteralDef, HwPin, HwPinGroup, *IEEE1722 TpAcfBus*, *IEEE1722TpAcfBusPart*, IPSecRule, IPv6ExtHeaderFilterList, ISignalToIPduMapping, ISignal Triggering, *IdentCaption*, ImpositionTime, InternalTriggeringPoint, J1939Node, J1939SharedAddress Cluster, J1939TpNode, Keyword, LifeCycleState, LinScheduleTable, LinTpNode, Linker, MacAddress VlanMembership, MacMulticastGroup, MacSecKayParticipant, McDataInstance, MemorySection, Mode Declaration, ModeDeclarationMapping, ModeSwitchPoint, ModeSwitchSenderComSpecProps, Network Endpoint, *NmCluster*, NmEcu, *NmNode*, NvBlockDescriptor, *PackageableElement*, ParameterAccess, PduActivationRoutingGroup, PduToFrameMapping, PduTriggering, PerInstanceMemory, *Physical Channel*, PortElementToCommunicationResourceMapping, PortGroup, *PortInterfaceMapping*, Queued ReceiverComSpecProps, ResourceConsumption, RootSwCompositionPrototype, RptComponent, Rpt Container, RptExecutableEntity, RptExecutableEntityEvent, RptExecutionContext, RptProfile, RptService Point, RteEventInCompositionSeparation, RteEventInCompositionToOsTaskProxyMapping, RteEventIn SystemSeparation, RteEventInSystemToOsTaskProxyMapping, RunnableEntityGroup, *SdgAttribute*, Sdg Class, SecOcJobRequirement, SecureCommunicationAuthenticationProps, SecureCommunication FreshnessProps, SecurityEventContextDataElement, SecurityEventContextProps, *ServerCallPoint*, ServerComSpecProps, *ServiceNeeds*, SignalServiceTranslationElementProps, SignalServiceTranslation EventProps, SignalServiceTranslationProps, SocketAddress, SomeipTpChannel, *StackUsage*, Static SocketConnection, StructuredReq, SwGenericAxisParamType, SwServiceArg, SwcServiceDependency, SwcToApplicationPartitionMapping, SwcToEcuMapping, SwcToImplMapping, SwitchAsynchronousTraffic ShaperGroupEntry, SwitchAtsInstanceEntry, SwitchFlowMeteringEntry, SwitchStreamFilterActionDest PortModification, SwitchStreamFilterEntry, SwitchStreamFilterRule, SwitchStreamGateEntry, Switch StreamIdentification, SystemMapping, SystemSignalGroupToCommunicationResourceMapping, System SignalToCommunicationResourceMapping, TDCpSoftwareClusterMapping, TDCpSoftwareCluster ResourceMapping, TcpOptionFilterList, *TimingClock*, TimingClockSyncAccuracy, TimingCondition, *TimingConstraint*, *TimingDescription*, TimingExtensionResource, TimingModeInstance, TlsCryptoCipher Suite, TlsCryptoCipherSuiteProps, Topic1, TpAddress, TraceableTable, TraceableText, *TracedFailure*, TransformationISignalPropsIdent, *TransformationProps*, TransformationTechnology, Trigger, Variable Access, VariationPointProxy, ViewMap, VlanConfig, WaitPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

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Class	***Identifiable*** (abstract)			
adminData	AdminData	0..1	aggr	This represents the administrative data for the identifiable object. **Tags:** atp.Splitkey=adminData xml.sequenceOffset=-40
annotation	Annotation	*	aggr	Possibility to provide additional notes while defining a model element (e.g. the ECU Configuration Parameter Values). These are not intended as documentation but are mere design notes. **Tags:** atp.Splitkey=annotation xml.sequenceOffset=-25
category	CategoryString	0..1	attr	The category is a keyword that specializes the semantics of the Identifiable. It affects the expected existence of attributes and the applicability of constraints. **Tags:** xml.sequenceOffset=-50
desc	MultiLanguageOverview Paragraph	0..1	aggr	This represents a general but brief (one paragraph) description what the object in question is about. It is only one paragraph! Desc is intended to be collected into overview tables. This property helps a human reader to identify the object in question. More elaborate documentation, (in particular how the object is built or used) should go to "introduction". **Tags:** atp.Splitkey=desc xml.sequenceOffset=-60
introduction	DocumentationBlock	0..1	aggr	This represents more information about how the object in question is built or is used. Therefore it is a DocumentationBlock. **Tags:** atp.Splitkey=introduction xml.sequenceOffset=-30
uuid	String	0..1	attr	The purpose of this attribute is to provide a globally unique identifier for an instance of a meta-class. The values of this attribute should be globally unique strings prefixed by the type of identifier. For example, to include a DCE UUID as defined by The Open Group, the UUID would be preceded by "DCE:". The values of this attribute may be used to support merging of different AUTOSAR models. The form of the UUID (Universally Unique Identifier) is taken from a standard defined by the Open Group (was Open Software Foundation). This standard is widely used, including by Microsoft for COM (GUIDs) and by many companies for DCE, which is based on CORBA. The method for generating these 128-bit IDs is published in the standard and the effectiveness and uniqueness of the IDs is not in practice disputed. If the id namespace is omitted, DCE is assumed. An example is "DCE:2fac1234-31f8-11b4-a222-08002b34c003". The uuid attribute has no semantic meaning for an AUTOSAR model and there is no requirement for AUTOSAR tools to manage the timestamp. **Tags:** xml.attribute=true

Table D.34: Identifiable

Class	ImplementationDataType			
Note	Describes a reusable data type on the implementation level. This will typically correspond to a typedef in C-code. **Tags:** atp.recommendedPackage=ImplementationDataTypes			
Base	*ARElement*, *ARObject*, *AbstractImplementationDataType*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *Autosar DataType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
dynamicArray SizeProfile	String	0..1	attr	Specifies the profile which the array will follow in case this data type is a variable size array.
isStructWith Optional Element	Boolean	0..1	attr	This attribute is only valid if the attribute category is set to STRUCTURE. If set to true, this attribute indicates that the ImplementationDataType has been created with the intention to define at least one element of the structure as optional.
subElement (ordered)	ImplementationData TypeElement	*	aggr	Specifies an element of an array, struct, or union data type. The aggregation of `ImplementationDataTypeElement` is subject to variability with the purpose to support the conditional existence of elements inside a `ImplementationDataType` representing a structure. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
symbolProps	SymbolProps	0..1	aggr	This represents the SymbolProps for the Implementation DataType. **Tags:** atp.Splitkey=symbolProps, symbolProps.short Name
typeEmitter	NameToken	0..1	attr	This attribute is used to control which part of the AUTOSAR toolchain is supposed to trigger data type definitions.

Table D.35: ImplementationDataType

Class	ImplementationDataTypeElement			
Note	Declares a data object which is locally aggregated. Such an element can only be used within the scope where it is aggregated. This element either consists of further `subElement`s or it is further defined via its `swDataDefProps`. There are several use cases within the system of `ImplementationDataType`s for such a local declaration: • It can represent the elements of an array, defining the element type and array size • It can represent an element of a struct, defining its type • It can be the local declaration of a debug element.			
Base	*ARObject*, *AbstractImplementationDataTypeElement*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, ImplementationDataType.subElement, ImplementationDataTypeElement.sub Element			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
arrayImplPolicy	ArrayImplPolicyEnum	0..1	attr	This attribute controls the implementation of the payload of an array. It shall only be used if the enclosing `ImplementationDataType` constitutes an array.



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Class	**ImplementationDataTypeElement**			
arraySize	PositiveInteger	0..1	attr	The existence of this attributes (if bigger than 0) defines the size of an array and declares that this `ImplementationDataTypeElement` represents the type of each single array element. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
arraySize Handling	ArraySizeHandling Enum	0..1	attr	The way how the size of the array is handled in case of a variable size array.
arraySize Semantics	ArraySizeSemantics Enum	0..1	attr	This attribute controls the meaning of the value of the array size.
isOptional	Boolean	0..1	attr	This attribute represents the ability to declare the enclosing `ImplementationDataTypeElement` as optional. This means that, at runtime, the `ImplementationDataTypeElement` may or may not have a valid value and shall therefore be ignored. The underlying runtime software provides means to set the `CppImplementationDataTypeElement` as not valid at the sending end of a communication and determine its validity at the receiving end.
subElement (ordered)	ImplementationData TypeElement	*	aggr	Element of an array, struct, or union in case of a nested declaration (i.e. without using "typedefs"). The aggregation of `ImplementationDataTypeElement` is subject to variability with the purpose to support the conditional existence of elements inside a `ImplementationDataType` representing a structure. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
swDataDef Props	SwDataDefProps	0..1	aggr	The properties of this ImplementationDataTypeElement. **Tags:** atp.Splitkey=swDataDefProps

Table D.36: ImplementationDataTypeElement

Class	**InternalTriggeringPoint**			
Note	If a `RunnableEntity` owns an `InternalTriggeringPoint` it is entitled to trigger the execution of `RunnableEntity`s of the corresponding software-component.			
Base	*ARObject*, *AbstractAccessPoint*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, RunnableEntity.internalTriggeringPoint			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
swImplPolicy	SwImplPolicyEnum	0..1	attr	This attribute, when set to value queued, allows for a queued processing of Triggers.

Table D.37: InternalTriggeringPoint

Class	**ModeAccessPoint**			
Note	A ModeAccessPoint is required by a RunnableEntity owned by a Mode Manager or Mode User. Its semantics implies the ability to access the current mode (provided by the RTE) of a ModeDeclaration GroupPrototype's ModeDeclarationGroup.			
Base	*ARObject*			
Aggregated by	RunnableEntity.modeAccessPoint			
Attribute	*Type*	*Mult.*	*Kind*	*Note*

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Class	**ModeAccessPoint**			
ident	ModeAccessPointIdent	0..1	aggr	The aggregation in the role ident provides the ability to make the ModeAccessPoint identifiable. From the semantical point of view, the ModeAccessPoint is considered a first-class Identifiable and therefore the aggregation in the role ident shall always exist (until it may be possible to let ModeAccessPoint directly inherit from Identifiable). **Stereotypes:** atpIdentityContributor **Tags:** xml.sequenceOffset=-100
modeGroup	ModeDeclarationGroup Prototype	0..1	iref	The mode declaration group that is accessed by this runnable. **Tags:** atp.Splitkey=modeGroup, modeGroup.contextPPort, modeGroup.contextRPort, modeGroup.targetModeGroup xml.typeElement=true **InstanceRef implemented by:** ModeGroupInAtomicSwc InstanceRef

Table D.38: ModeAccessPoint

Class	**ModeSwitchPoint**			
Note	A `ModeSwitchPoint` is required by a `RunnableEntity` owned a Mode Manager. Its semantics implies the ability to initiate a mode switch.			
Base	*ARObject*, *AbstractAccessPoint*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, RunnableEntity.modeSwitchPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
modeGroup	ModeDeclarationGroup Prototype	0..1	iref	The mode declaration group that is switched by this runnable. **Tags:** atp.Splitkey=modeGroup, modeGroup.context PPort, modeGroup.targetModeGroup **InstanceRef implemented by:** PModeGroupInAtomic SwcInstanceRef

Table D.39: ModeSwitchPoint

Class	**ObdInfoServiceNeeds**			
Note	Specifies the abstract needs of a component or module on the configuration of OBD Services in relation to a given InfoType (OBD Service 09) which is supported by this component or module.			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *Service Needs*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table D.40: ObdInfoServiceNeeds

Class	**ObdPidServiceNeeds**
Note	Specifies the abstract needs of a component or module on the configuration of OBD Services in relation to a particular PID (parameter identifier) which is supported by this component or module. In case of using a client/server communicated value, the related value shall be communicated via the port referenced by assignedPort. The details of this communication (e.g. appropriate naming conventions) are specified in the related software specifications (SWS).

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Class	ObdPidServiceNeeds			
Base	*ARObject*, *DiagnosticCapabilityElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*, *ServiceNeeds*			
Aggregated by	BswServiceDependency.serviceNeeds, SwcServiceDependency.serviceNeeds			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
–	–	–	–	–

Table D.41: ObdPidServiceNeeds

Class	OperationInvokedEvent			
Note	This event is raised when the `ClientServerOperation` referenced in `OperationInvokedEvent.operation` shall be invoked.			
Base	*ARObject*, *AbstractEvent*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *RTEEvent*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, SwcInternalBehavior.event			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
operation	ClientServerOperation	0..1	iref	This represents the ClientServerOperation which shall be invoked. **Tags:** atp.Splitkey=operation, operation.contextPPort, operation.targetProvidedOperation **InstanceRef implemented by:** POperationInAtomicSwcInstanceRef

Table D.42: OperationInvokedEvent

Class	PRPortPrototype			
Note	This kind of PortPrototype can take the role of both a required and a provided PortPrototype.			
Base	*ARObject*, *AbstractProvidedPortPrototype*, *AbstractRequiredPortPrototype*, *AtpFeature*, *AtpPrototype*, *Identifiable*, *MultilanguageReferrable*, *PortPrototype*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, *SwComponentType*.port			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
providedRequiredInterface	PortInterface	0..1	tref	This represents the `PortInterface` used to type the `PRPortPrototype`. **Stereotypes:** isOfType **Tags:** atp.Splitkey=providedRequiredInterface

Table D.43: PRPortPrototype

Class	ParameterAccess			
Note	The presence of a `ParameterAccess` implies that a `RunnableEntity` needs access to a `ParameterDataPrototype`.			
Base	*ARObject*, *AbstractAccessPoint*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, RunnableEntity.parameterAccess			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
accessedParameter	AutosarParameterRef	0..1	aggr	Reference to the accessed calibration parameter. **Tags:** atp.Splitkey=accessedParameter
swDataDefProps	SwDataDefProps	0..1	aggr	This allows denote instance and access specific properties, mainly input values and common axis. **Tags:** atp.Splitkey=swDataDefProps

Table D.44: ParameterAccess

Class	PortDefinedArgumentValue			
Note	A PortDefinedArgumentValue is passed to a RunnableEntity dealing with the ClientServerOperations provided by a given PortPrototype. Note that this is restricted to PPortPrototypes of a ClientServer Interface.			
Base	*ARObject*			
Aggregated by	PortAPIOption.portArgValue			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
value	ValueSpecification	0..1	aggr	Specifies the actual value.
valueType	ImplementationDataType	0..1	tref	The implementation type of this argument value. It should not be composite type or a pointer. **Stereotypes:** isOfType

Table D.45: PortDefinedArgumentValue

Class	***PortPrototype*** (abstract)			
Note	Base class for the ports of an AUTOSAR software component. The aggregation of PortPrototypes is subject to variability with the purpose to support the conditional existence of ports.			
Base	*ARObject*, *AtpFeature*, *AtpPrototype*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	*AbstractProvidedPortPrototype*, *AbstractRequiredPortPrototype*			
Aggregated by	*AtpClassifier*.atpFeature, *SwComponentType*.port			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
clientServer Annotation	ClientServerAnnotation	*	aggr	Annotation of this `PortPrototype` with respect to client/server communication. **Tags:** atp.Splitkey=clientServerAnnotation
delegatedPort Annotation	DelegatedPort Annotation	0..1	aggr	Annotations on this delegated port. **Tags:** atp.Splitkey=delegatedPortAnnotation
ioHwAbstraction Server Annotation	IoHwAbstractionServer Annotation	*	aggr	Annotations on this IO Hardware Abstraction port. **Tags:** atp.Splitkey=ioHwAbstractionServerAnnotation
modePort Annotation	ModePortAnnotation	*	aggr	Annotations on this mode port. **Tags:** atp.Splitkey=modePortAnnotation
nvDataPort Annotation	NvDataPortAnnotation	*	aggr	Annotations on this non voilatile data port. **Tags:** atp.Splitkey=nvDataPortAnnotation
parameterPort Annotation	ParameterPort Annotation	*	aggr	Annotations on this parameter port. **Tags:** atp.Splitkey=parameterPortAnnotation
senderReceiver Annotation	SenderReceiver Annotation	*	aggr	Collection of annotations of this ports sender/receiver communication. **Tags:** atp.Splitkey=senderReceiverAnnotation
triggerPort Annotation	TriggerPortAnnotation	*	aggr	Annotations on this trigger port. **Tags:** atp.Splitkey=triggerPortAnnotation

Table D.46: PortPrototype

Class	PostBuildVariantCriterion
Note	This class specifies one particular PostBuildVariantSelector. **Tags:** atp.recommendedPackage=PostBuildVariantCriterions
Base	*ARElement*, *ARObject*, *AtpDefinition*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*

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Class	**PostBuildVariantCriterion**			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
compuMethod	CompuMethod	0..1	ref	The compuMethod specifies the possible values for the variant criterion serving as an enumerator. **Tags:** atp.Splitkey=compuMethod

Table D.47: PostBuildVariantCriterion

Class	***RTEEvent*** (abstract)			
Note	Abstract base class for all RTE-related events			
Base	*ARObject*, *AbstractEvent*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	AsynchronousServerCallReturnsEvent, BackgroundEvent, DataReceiveErrorEvent, DataReceivedEvent, DataSendCompletedEvent, DataWriteCompletedEvent, ExternalTriggerOccurredEvent, InitEvent, InternalTriggerOccurredEvent, ModeSwitchedAckEvent, OperationInvokedEvent, OsTaskExecutionEvent, SwcModeManagerErrorEvent, SwcModeSwitchEvent, TimingEvent, TransformerHardErrorEvent			
Aggregated by	*AtpClassifier*.atpFeature, SwcInternalBehavior.event			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
disabledMode	ModeDeclaration	*	iref	Reference to the Modes that disable the Event. **Tags:** atp.Splitkey=disabledMode, disabledMode.contextPort, disabledMode.contextModeDeclarationGroupPrototype, disabledMode.targetModeDeclaration **InstanceRef implemented by:** RModeInAtomicSwcInstanceRef
startOnEvent	RunnableEntity	0..1	ref	The referenced `RunnableEntity` starts when the corresponding `RTEEvent` is raised. **Tags:** atp.Splitkey=startOnEvent

Table D.48: RTEEvent

Class	**RapidPrototypingScenario**			
Note	This meta-class provides the ability to describe a Rapid Prototyping Scenario. Such a Rapid Prototyping Scenario consist out of two main aspects, the description of the byPassPoints and the relation to an rpt Hook. **Tags:** atp.recommendedPackage=RapidPrototypingScenarios			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
hostSystem	System	0..1	ref	System which describes the software components of the host ECU. **Tags:** atp.Splitkey=hostSystem
rptContainer	RptContainer	*	aggr	Top-level rptContainer definitions of this specific rapid prototyping scenario. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rptContainer, rptContainer.shortName, rptContainer.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	RapidPrototypingScenario			
rptProfile	RptProfile	*	aggr	Defiens the applicable Rapid Prototyping profils which are especially defining the smbol of the service functions and the valid id range. The order of the RptProfiles determines the order of the service function invocation by RTE. **Tags:** atp.Splitkey=rptProfile, rptProfile.shortName atp.Status=obsolete
rptSystem	System	0..1	ref	System which describes the rapid prototyping algorithm in the format of AUTOSAR Software Components. **Tags:** atp.Splitkey=rptSystem

Table D.49: RapidPrototypingScenario

Class	*Referrable* (abstract)			
Note	Instances of this class can be referred to by their identifier (while adhering to namespace borders).			
Base	*ARObject*			
Subclasses	*AtpDefinition*, BswDistinguishedPartition, *BswModuleCallPoint*, BswModuleClientServerEntry, BswVariableAccess, CouplingPortTrafficClassAssignment, *DiagnosticEnvModeElement*, EthernetPriorityRegeneration, ExclusiveAreaNestingOrder, *HwDescriptionEntity*, *ImplementationProps*, LinSlaveConfigIdent, ModeTransition, *MultilanguageReferrable*, PncMappingIdent, *SingleLanguageReferrable*, SoConIPduIdentifier, TpConnectionIdent			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
shortName	Identifier	1	attr	This specifies an identifying shortName for the object. It needs to be unique within its context and is intended for humans but even more for technical reference. **Stereotypes:** atpIdentityContributor **Tags:** xml.enforceMinMultiplicity=true xml.sequenceOffset=-100
shortName Fragment	ShortNameFragment	*	aggr	This specifies how the Referrable.shortName is composed of several shortNameFragments. **Tags:** atp.Splitkey=shortNameFragment xml.sequenceOffset=-90

Table D.50: Referrable

Class	RoleBasedMcDataAssignment			
Note	This meta-class allows to define links that specify logical relationships between single McDataInstances. The details on the existence and semantics of such links are not standardized. Possible Use Case: Rapid Prototyping solutions in which additional communication buffers and switches are implemented in the RTE that allow to switch between the usage of the original and the bypass buffers. The different buffers and the switch can be represented by McDataInstances (in order to be accessed by MC tools) which have relationships to each other.			
Base	*ARObject*			
Aggregated by	McDataInstance.mcDataAssignment, RptComponent.mcDataAssignment, RptExecutableEntity.rptRead, RptExecutableEntity.rptWrite, RptExecutableEntityEvent.mcDataAssignment			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
execution Context	RptExecutionContext	*	ref	Determines the executionContext in which the McData Instance describing a local (e.g Task-Local) buffer of a global buffer is valid. **Tags:** atp.Splitkey=executionContext

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Class	**RoleBasedMcDataAssignment**			
mcDataInstance	McDataInstance	*	ref	The target of the assignment. **Tags:** atp.Splitkey=mcDataInstance
role	Identifier	0..1	attr	Shall be used to specify the role of the assigned data instance in relation to the instance that owns the assignment. The standardized roles of the RoleBasedMcData Assignment.role attribute are: • GlobalMeasurementBuffer • RpEnablerFlag • RpRunnableDisablerFlag • BufferOf

Table D.51: RoleBasedMcDataAssignment

Class	**RoleBasedPortAssignment**			
Note	This class specifies an assignment of a role to a particular service port (RPortPrototype or PPort Prototype) of an AtomicSwComponentType. With this assignment, the role of the service port can be mapped to a specific ServiceNeeds element, so that a tool is able to create the correct connector.			
Base	*ARObject*			
Aggregated by	NvBlockDescriptor.clientServerPort, SwcServiceDependency.assignedPort			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
portPrototype	PortPrototype	0..1	ref	Service PortPrototype used in the assigned role. This PortPrototype shall either belong to the same AtomicSw ComponentType as the SwcInternalBehavior which owns the ServiceDependency or to the same NvBlockSw ComponentType as the NvBlockDescriptor. **Tags:** atp.Splitkey=portPrototype
role	Identifier	0..1	attr	This is the role of the assigned Port in the given context. The value shall be a shortName of the Blueprint of a Port Interface as standardized in the Software Specification of the related AUTOSAR Service.

Table D.52: RoleBasedPortAssignment

Class	**RunnableEntity**			
Note	A `RunnableEntity` represents the smallest code-fragment that is provided by an `AtomicSwComponentType` and are executed under control of the RTE. `RunnableEntity`s are for instance set up to respond to data reception or operation invocation on a server.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *ExecutableEntity*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, SwcInternalBehavior.runnable			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
argument (ordered)	RunnableEntity Argument	*	aggr	This represents the formal definition of an argument to a RunnableEntity.

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Class	**RunnableEntity**			
asynchronous ServerCall ResultPoint	AsynchronousServer CallResultPoint	*	aggr	The server call result point admits a runnable to fetch the result of an asynchronous server call. The aggregation of AsynchronousServerCallResultPoint is subject to variability with the purpose to support the conditional existence of client server PortPrototypes and the variant existence of server call result points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=asynchronousServerCallResultPoint, asynchronousServerCallResultPoint.shortName, asynchronousServerCallResultPoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.
canBeInvoked Concurrently	Boolean	0..1	attr	If the value of this attribute is set to "true" the enclosing `RunnableEntity` can be invoked concurrently (even for one instance of the corresponding `AtomicSwComponentType`). This implies that it is the responsibility of the implementation of the `RunnableEntity` to take care of this form of concurrency.
dataRead Access	VariableAccess	*	aggr	RunnableEntity has implicit read access to dataElement of a sender-receiver PortPrototype or nv data of a nv data PortPrototype. The aggregation of dataReadAccess is subject to variability with the purpose to support the conditional existence of sender receiver ports or the variant existence of dataReadAccess in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=dataReadAccess, dataReadAccess.shortName, dataReadAccess.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
dataReceive PointBy Argument	VariableAccess	*	aggr	RunnableEntity has explicit read access to dataElement of a sender-receiver PortPrototype or nv data of a nv data PortPrototype. The result is passed back to the application by means of an argument in the function signature. The aggregation of dataReceivePointByArgument is subject to variability with the purpose to support the conditional existence of sender receiver PortPrototype or the variant existence of data receive points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=dataReceivePointByArgument, dataReceivePointByArgument.shortName, dataReceivePointByArgument.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	**RunnableEntity**			
dataReceive PointByValue	VariableAccess	*	aggr	RunnableEntity has explicit read access to dataElement of a sender-receiver PortPrototype or nv data of a nv data PortPrototype. The result is passed back to the application by means of the return value. The aggregation of dataReceivePointBy Value is subject to variability with the purpose to support the conditional existence of sender receiver ports or the variant existence of data receive points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=dataReceivePointByValue, dataReceivePoint ByValue.shortName, dataReceivePointByValue.variation Point.shortLabel vh.latestBindingTime=preCompileTime
dataSendPoint	VariableAccess	*	aggr	RunnableEntity has explicit write access to dataElement of a sender-receiver PortPrototype or nv data of a nv data PortPrototype. The aggregation of dataSendPoint is subject to variability with the purpose to support the conditional existence of sender receiver PortPrototype or the variant existence of data send points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=dataSendPoint, dataSendPoint.shortName, dataSendPoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
dataWrite Access	VariableAccess	*	aggr	RunnableEntity has implicit write access to dataElement of a sender-receiver PortPrototype or nv data of a nv data PortPrototype. The aggregation of dataWriteAccess is subject to variability with the purpose to support the conditional existence of sender receiver ports or the variant existence of dataWriteAccess in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=dataWriteAccess, dataWriteAccess.short Name, dataWriteAccess.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
external TriggeringPoint	ExternalTriggeringPoint	*	aggr	The aggregation of ExternalTriggeringPoint is subject to variability with the purpose to support the conditional existence of trigger ports or the variant existence of external triggering points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=externalTriggeringPoint, externalTriggering Point.ident.shortName, externalTriggeringPoint.variation Point.shortLabel vh.latestBindingTime=preCompileTime

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Class	**RunnableEntity**			
internal TriggeringPoint	InternalTriggeringPoint	*	aggr	The aggregation of InternalTriggeringPoint is subject to variability with the purpose to support the variant existence of internal triggering points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=internalTriggeringPoint, internalTriggering Point.shortName, internalTriggeringPoint.variation Point.shortLabel vh.latestBindingTime=preCompileTime
modeAccess Point	ModeAccessPoint	*	aggr	The runnable has a mode access point. The aggregation of ModeAccessPoint is subject to variability with the purpose to support the conditional existence of mode ports or the variant existence of mode access points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=modeAccessPoint, modeAccess Point.ident.shortName, modeAccessPoint.variation Point.shortLabel vh.latestBindingTime=preCompileTime
modeSwitch Point	ModeSwitchPoint	*	aggr	The runnable has a mode switch point. The aggregation of ModeSwitchPoint is subject to variability with the purpose to support the conditional existence of mode ports or the variant existence of mode switch points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=modeSwitchPoint, modeSwitchPoint.short Name, modeSwitchPoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
parameter Access	ParameterAccess	*	aggr	The presence of a ParameterAccess implies that a RunnableEntity needs read only access to a Parameter DataPrototype which may either be local or within a Port Prototype. The aggregation of ParameterAccess is subject to variability with the purpose to support the conditional existence of parameter ports and component local parameters as well as the variant existence of Parameter Access (points) in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=parameterAccess, parameterAccess.short Name, parameterAccess.variationPoint.shortLabel vh.latestBindingTime=preCompileTime

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Class	**RunnableEntity**			
readLocal Variable	VariableAccess	*	aggr	The presence of a readLocalVariable implies that a RunnableEntity needs read access to a VariableData Prototype in the role of implicitInterRunnableVariable or explicitInterRunnableVariable. The aggregation of readLocalVariable is subject to variability with the purpose to support the conditional existence of implicitInterRunnableVariable and explicit InterRunnableVariable or the variant existence of read LocalVariable (points) in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=readLocalVariable, readLocalVariable.short Name, readLocalVariable.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
serverCallPoint	ServerCallPoint	*	aggr	The RunnableEntity has a ServerCallPoint. The aggregation of ServerCallPoint is subject to variability with the purpose to support the conditional existence of client server PortPrototypes or the variant existence of server call points in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=serverCallPoint, serverCallPoint.shortName, serverCallPoint.variationPoint.shortLabel vh.latestBindingTime=preCompileTime This Attribute is only used by the AUTOSAR Classic Platform.
symbol	CIdentifier	0..1	attr	The symbol describing this `RunnableEntity`'s entry point. This is considered the API of the `RunnableEntity` and is required during the RTE contract phase.
waitPoint	WaitPoint	*	aggr	The `WaitPoint` associated with the `RunnableEntity`. **Tags:** atp.Splitkey=waitPoint, waitPoint.shortName
writtenLocal Variable	VariableAccess	*	aggr	The presence of a writtenLocalVariable implies that a RunnableEntity needs write access to a VariableData Prototype in the role of implicitInterRunnableVariable or explicitInterRunnableVariable. The aggregation of writtenLocalVariable is subject to variability with the purpose to support the conditional existence of implicitInterRunnableVariable and explicit InterRunnableVariable or the variant existence of written LocalVariable (points) in the implementation. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=writtenLocalVariable, writtenLocal Variable.shortName, writtenLocalVariable.variation Point.shortLabel vh.latestBindingTime=preCompileTime

Table D.53: RunnableEntity

Class	**SenderReceiverInterface**
Note	A sender/receiver interface declares a number of data elements to be sent and received. **Tags:** atp.recommendedPackage=PortInterfaces
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *CollectableElement*, *DataInterface*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *PortInterface*, *Referrable*
Aggregated by	ARPackage.element

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Class	**SenderReceiverInterface**			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
dataElement	VariableDataPrototype	*	aggr	The data elements of this `SenderReceiverInterface`. **Tags:** atp.Splitkey=dataElement, dataElement.shortName
invalidationPolicy	InvalidationPolicy	*	aggr	InvalidationPolicy for a particular dataElement **Tags:** atp.Splitkey=invalidationPolicy
metaDataItemSet	MetaDataItemSet	*	aggr	This aggregation defines fixed sets of meta-data items associated with `dataElement`s of the enclosing `SenderReceiverInterface` **Tags:** atp.Splitkey=metaDataItemSet

Table D.54: SenderReceiverInterface

Class	***ServerCallPoint*** (abstract)			
Note	If a RunnableEntity owns a `ServerCallPoint` it is entitled to invoke a particular `ClientServerOperation` of a specific `RPortPrototype` of the corresponding `AtomicSwComponentType`. This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARObject*, *AbstractAccessPoint*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Subclasses	AsynchronousServerCallPoint, SynchronousServerCallPoint			
Aggregated by	*AtpClassifier*.atpFeature, RunnableEntity.serverCallPoint			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
operation	ClientServerOperation	0..1	iref	The operation that is called by this runnable. **Tags:** atp.Splitkey=operation, operation.contextRPort, operation.targetRequiredOperation **InstanceRef implemented by:** ROperationInAtomicSwcInstanceRef
timeout	TimeValue	0..1	attr	Time in seconds before the server call times out and returns with an error message. It depends on the call type (synchronous or asynchronous) how this is reported.

Table D.55: ServerCallPoint

Class	**ServiceSwComponentType**			
Note	ServiceSwComponentType is used for configuring services for a given ECU. Instances of this class are only to be created in ECU Configuration phase for the specific purpose of the service configuration. **Tags:** atp.recommendedPackage=SwComponentTypes			
Base	*ARElement*, *ARObject*, *AtomicSwComponentType*, *AtpBlueprint*, *AtpClassifier*, *AtpType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*, *SwComponentType*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table D.56: ServiceSwComponentType

Primitive	**String**
Note	This represents a String in which white-space shall be normalized before processing. For example: in order to compare two Strings: • leading and trailing white-space needs to be removed • consecutive white-space (blank, cr, lf, tab) needs to be replaced by one blank. **Tags:** xml.xsd.customType=STRING xml.xsd.type=string

Table D.57: String

Class	**SwBaseType**			
Note	This meta-class represents a base type used within ECU software. **Tags:** atp.recommendedPackage=BaseTypes			
Base	*ARElement*, *ARObject*, *AtpBlueprint*, *BaseType*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
–	–	–	–	–

Table D.58: SwBaseType

Enumeration	**SwCalibrationAccessEnum**
Note	Determines the access rights to a data object w.r.t. measurement and calibration.
Aggregated by	ModeDeclarationGroupPrototype.swCalibrationAccess, SwCalprmAxis.swCalibrationAccess, SwDataDefProps.swCalibrationAccess
Literal	***Description***
notAccessible	The element will not be accessible via MCD tools, i.e. will not appear in the ASAP file. **Tags:** atp.EnumerationLiteralIndex=0
readOnly	The element will only appear as read-only in an ASAP file. **Tags:** atp.EnumerationLiteralIndex=1
readWrite	The element will appear in the ASAP file with both read and write access. **Tags:** atp.EnumerationLiteralIndex=2

Table D.59: SwCalibrationAccessEnum

Class	**SwComponentDocumentation**			
Note	This class specifies the ability to write dedicated documentation to a component type according to ASAM FSX.			
Base	*ARObject*			
Aggregated by	BswModuleDescription.bswModuleDocumentation, *SwComponentType*.swComponentDocumentation			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

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Class	**SwComponentDocumentation**			
chapter	Chapter	*	aggr	These chapters provide additional information about the software component that do not fit in the other chapters. Note that this is subject to variation because Chapter aggregations in the role chapter are variant within the documentation in general. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=chapter, chapter.shortName, chapter.variationPoint.shortLabel vh.latestBindingTime=postBuild xml.roleElement=true xml.roleWrapperElement=false xml.sequenceOffset=100 xml.typeElement=false
swCalibration Notes	Chapter	0..1	aggr	This element contains calibration instructions and hints for a calibration engineer. **Tags:** atp.Splitkey=swCalibrationNotes, swCalibration Notes.shortName xml.roleElement=true xml.sequenceOffset=60 xml.typeElement=false
swCarbDoc	Chapter	0..1	aggr	This element records the documentation requested by CARB. **Tags:** atp.Splitkey=swCarbDoc, swCarbDoc.shortName xml.roleElement=true xml.sequenceOffset=80 xml.typeElement=false
swDiagnostics Notes	Chapter	0..1	aggr	This element contains general information about diagnostics issues within the component. **Tags:** atp.Splitkey=swDiagnosticsNotes, swDiagnostics Notes.shortName xml.roleElement=true xml.sequenceOffset=75 xml.typeElement=false
swFeatureDef	Chapter	0..1	aggr	This element contains the definition of the physical functionality of this software component. This definition is more or less formal and is intended to be delivered from modeling tools. **Tags:** atp.Splitkey=swFeatureDef, swFeatureDef.shortName xml.roleElement=true xml.sequenceOffset=20 xml.typeElement=false
swFeatureDesc	Chapter	0..1	aggr	This element contains the textual description of the software functionality of this software component. Expert should write this description. **Tags:** atp.Splitkey=swFeatureDesc, swFeatureDesc.shortName xml.roleElement=true xml.sequenceOffset=30 xml.typeElement=false

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Class	**SwComponentDocumentation**			
swMaintenance Notes	Chapter	0..1	aggr	This element contains information regarding the software maintenance of the component. **Tags:** atp.Splitkey=swMaintenanceNotes, swMaintenance Notes.shortName xml.roleElement=true xml.sequenceOffset=70 xml.typeElement=false
swTestDesc	Chapter	0..1	aggr	This element contains suggestions and hints for the test of the software functionality of this software component. **Tags:** atp.Splitkey=swTestDesc, swTestDesc.shortName xml.roleElement=true xml.sequenceOffset=50 xml.typeElement=false

Table D.60: SwComponentDocumentation

Class	«atpVariation» **SwDataDefProps**			
Note	This class is a collection of properties relevant for data objects under various aspects. One could consider this class as a "pattern of inheritance by aggregation". The properties can be applied to all objects of all classes in which SwDataDefProps is aggregated. Note that not all of the attributes or associated elements are useful all of the time. Hence, the process definition (e.g. expressed with an OCL or a Document Control Instance MSR-DCI) has the task of implementing limitations. SwDataDefProps covers various aspects: • Structure of the data element for calibration use cases: is it a single value, a curve, or a map, but also the recordLayouts which specify how such elements are mapped/converted to the DataTypes in the programming language (or in AUTOSAR). This is mainly expressed by properties like swRecordLayout and swCalprmAxisSet • Implementation aspects, mainly expressed by swImplPolicy, swAddrMethod, baseType, implementationDataType and additionalNativeTypeQualifier • Access policy for the MCD system, mainly expressed by swCalibrationAccess • Semantics of the data element, mainly expressed by compuMethod and/or unit, dataConstr, invalid Value • Code generation policy provided by swRecordLayout **Tags:** vh.latestBindingTime=codeGenerationTime			
Base	*ARObject*			
Aggregated by	*AutosarDataType*.swDataDefProps, CompositeNetworkRepresentation.networkRepresentation, Cpp ImplementationDataTypeElement.swDataDefProps, *DataPrototype*.swDataDefProps, DataPrototype TransformationProps.networkRepresentationProps, DiagnosticDataElement.swDataDefProps, Diagnostic EnvDataElementCondition.swDataDefProps, DiagnosticExtendedDataRecordElement.swDataDefProps, DiagnosticSovdPrimitiveContentElement.swDataDefProps, DltArgumentProps.networkRep, FlatInstance Descriptor.swDataDefProps, ImplementationDataTypeElement.swDataDefProps, InstantiationDataDef Props.swDataDefProps, ISignal.networkRepresentationProps, McDataInstance.resultingProperties, ParameterAccess.swDataDefProps, PerInstanceMemory.swDataDefProps, *ReceiverComSpec*.network Representation, SecurityEventContextDataElement.networkRepresentation, *SenderComSpec*.network Representation, SomeipDataPrototypeTransformationProps.networkRepresentation, SwPointerTarget Props.swDataDefProps, SwServiceArg.swDataDefProps, SwSystemconst.swDataDefProps, System Signal.physicalProps			
Attribute	***Type***	***Mult.***	***Kind***	***Note***

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Class	«atpVariation» **SwDataDefProps**			
additionalNative TypeQualifier	NativeDeclarationString	0..1	attr	This attribute is used to declare native qualifiers of the programming language which can neither be deduced from the baseType (e.g. because the data object describes a pointer) nor from other more abstract attributes. Examples are qualifiers like "volatile", "strict" or "enum" of the C-language. All such declarations have to be put into one string. **Tags:** xml.sequenceOffset=235
annotation	Annotation	*	aggr	This aggregation allows to add annotations (yellow pads ...) related to the current data object. **Tags:** atp.Splitkey=annotation xml.roleElement=true xml.roleWrapperElement=true xml.sequenceOffset=20 xml.typeElement=false xml.typeWrapperElement=false
baseType	SwBaseType	0..1	ref	Base type associated with the containing data object. **Tags:** atp.Splitkey=baseType xml.sequenceOffset=50
compuMethod	CompuMethod	0..1	ref	Computation method associated with the semantics of this data object. **Tags:** atp.Splitkey=compuMethod xml.sequenceOffset=180
dataConstr	DataConstr	0..1	ref	Data constraint for this data object. **Tags:** atp.Splitkey=dataConstr xml.sequenceOffset=190
displayFormat	DisplayFormatString	0..1	attr	This property describes how a number is to be rendered e.g. in documents or in a measurement and calibration system. **Tags:** xml.sequenceOffset=210
display Presentation	DisplayPresentation Enum	0..1	attr	This attribute controls the presentation of the related data for measurement and calibration tools.
implementation DataType	AbstractImplementation DataType	0..1	ref	This association denotes the ImplementationDataType of a data declaration via its aggregated SwDataDefProps. It is used whenever a data declaration is not directly referring to a base type. Especially • redefinition of an ImplementationDataType via a "typedef" to another ImplementationDatatype • the target type of a pointer (see SwPointerTarget Props), if it does not refer to a base type directly • the data type of an array or record element within an ImplementationDataType, if it does not refer to a base type directly • the data type of an SwServiceArg, if it does not refer to a base type directly **Tags:** atp.Splitkey=implementationDataType xml.sequenceOffset=215

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Class	«atpVariation» **SwDataDefProps**			
invalidValue	ValueSpecification	0..1	aggr	Optional value to express invalidity of the actual data element. **Tags:** atp.Splitkey=invalidValue xml.sequenceOffset=255
stepSize	Float	0..1	attr	This attribute can be used to define a value which is added to or subtracted from the value of a DataPrototype when using up/down keys while calibrating.
swAddrMethod	SwAddrMethod	0..1	ref	Addressing method related to this data object. Via an association to the same SwAddrMethod it can be specified that several DataPrototypes shall be located in the same memory without already specifying the memory section itself. **Tags:** atp.Splitkey=swAddrMethod xml.sequenceOffset=30
swAlignment	AlignmentType	0..1	attr	The attribute describes the intended typical alignment of the DataPrototype. If the attribute is not defined the alignment is determined by the swBaseType size and the memoryAllocationKeywordPolicy of the referenced Sw AddrMethod. **Tags:** xml.sequenceOffset=33
swBit Representation	SwBitRepresentation	0..1	aggr	Description of the binary representation in case of a bit variable. **Tags:** atp.Splitkey=swBitRepresentation xml.sequenceOffset=60
swCalibration Access	SwCalibrationAccess Enum	0..1	attr	Specifies the read or write access by MCD tools for this data object. **Tags:** xml.sequenceOffset=70
swCalprmAxis Set	SwCalprmAxisSet	0..1	aggr	This specifies the properties of the axes in case of a curve or map etc. This is mainly applicable to calibration parameters. **Tags:** atp.Splitkey=swCalprmAxisSet xml.sequenceOffset=90
swComparison Variable	SwVariableRefProxy	*	aggr	Variables used for comparison in an MCD process. **Tags:** atp.Splitkey=swComparisonVariable xml.sequenceOffset=170 xml.typeElement=false
swData Dependency	SwDataDependency	0..1	aggr	Describes how the value of the data object has to be calculated from the value of another data object (by the MCD system). **Tags:** atp.Splitkey=swDataDependency xml.sequenceOffset=200
swHostVariable	SwVariableRefProxy	0..1	aggr	Contains a reference to a variable which serves as a host-variable for a bit variable. Only applicable to bit objects. **Tags:** atp.Splitkey=swHostVariable xml.sequenceOffset=220 xml.typeElement=false

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Class	«atpVariation» **SwDataDefProps**			
swImplPolicy	SwImplPolicyEnum	0..1	attr	Implementation policy for this data object. **Tags:** xml.sequenceOffset=230
swIntended Resolution	Numerical	0..1	attr	The purpose of this element is to describe the requested quantization of data objects early on in the design process. The resolution ultimately occurs via the conversion formula present (compuMethod), which specifies the transition from the physical world to the standardized world (and vice-versa) (here, "the slope per bit" is present implicitly in the conversion formula). In the case of a development phase without a fixed conversion formula, a pre-specification can occur through swIntendedResolution. The resolution is specified in the physical domain according to the property "unit". **Tags:** xml.sequenceOffset=240
swInterpolation Method	Identifier	0..1	attr	This is a keyword identifying the mathematical method to be applied for interpolation. The keyword needs to be related to the interpolation routine which needs to be invoked. **Tags:** xml.sequenceOffset=250
swIsVirtual	Boolean	0..1	attr	This element distinguishes virtual objects. Virtual objects do not appear in the memory, their derivation is much more dependent on other objects and hence they shall have a swDataDependency . **Tags:** xml.sequenceOffset=260
swPointerTarget Props	SwPointerTargetProps	0..1	aggr	Specifies that the containing data object is a pointer to another data object. **Tags:** atp.Splitkey=swPointerTargetProps xml.sequenceOffset=280
swRecord Layout	SwRecordLayout	0..1	ref	Record layout for this data object. **Tags:** atp.Splitkey=swRecordLayout xml.sequenceOffset=290
swRefresh Timing	MultidimensionalTime	0..1	aggr	This element specifies the frequency in which the object involved shall be or is called or calculated. This timing can be collected from the task in which write access processes to the variable run. But this cannot be done by the MCD system. So this attribute can be used in an early phase to express the desired refresh timing and later on to specify the real refresh timing. **Tags:** atp.Splitkey=swRefreshTiming xml.sequenceOffset=300
swTextProps	SwTextProps	0..1	aggr	the specific properties if the data object is a text object. **Tags:** atp.Splitkey=swTextProps xml.sequenceOffset=120

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Class	«atpVariation» **SwDataDefProps**			
swValueBlock Size	Numerical	0..1	attr	This represents the size of a Value Block **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime xml.sequenceOffset=80
swValueBlock SizeMult (ordered)	Numerical	*	attr	This attribute is used to specify the dimensions of a value block (VAL_BLK) for the case that that value block has more than one dimension. The dimensions given in this attribute are ordered such that the first entry represents the first dimension, the second entry represents the second dimension, and so on. For one-dimensional value blocks the attribute swValue BlockSize shall be used and this attribute shall not exist. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime
unit	Unit	0..1	ref	Physical unit associated with the semantics of this data object. This attribute applies if no compuMethod is specified. If both units (this as well as via compuMethod) are specified the units shall be compatible. **Tags:** atp.Splitkey=unit xml.sequenceOffset=350
valueAxisData Type	ApplicationPrimitive DataType	0..1	ref	The referenced ApplicationPrimitiveDataType represents the primitive data type of the value axis within a compound primitive (e.g. curve, map). It supersedes CompuMethod, Unit, and BaseType. **Tags:** atp.Splitkey=valueAxisDataType xml.sequenceOffset=355

Table D.61: SwDataDefProps

Enumeration	**SwImplPolicyEnum**
Note	Specifies the implementation strategy with respect to consistency mechanisms of variables.
Aggregated by	BswInternalTriggeringPoint.swImplPolicy, InternalTriggeringPoint.swImplPolicy, SwDataDefProps.swImplPolicy, Trigger.swImplPolicy
Literal	*Description*
const	forced implementation such that the running software within the ECU shall not modify it. For example implemented with the "const" modifier in C. This can be applied for parameters (not for those in NVRAM) as well as argument data prototypes. **Tags:** atp.EnumerationLiteralIndex=0
fixed	This data element is fixed. In particular this indicates, that it might also be implemented e.g. as in place data, (#DEFINE). **Tags:** atp.EnumerationLiteralIndex=1
measurementPoint	The data element is created for measurement purposes only. The data element is never read directly within the ECU software. In contrast to a "standard" data element in an unconnected provide port is, this unconnection is guaranteed for measurementPoint data elements. **Tags:** atp.EnumerationLiteralIndex=2

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Enumeration	**SwImplPolicyEnum**
queued	The content of the data element is queued and the data element has 'event' semantics, i.e. data elements are stored in a queue and all data elements are processed in 'first in first out' order. The queuing is intended to be implemented by RTE Generator. This value is not applicable for parameters. **Tags:** atp.EnumerationLiteralIndex=3
standard	This is applicable for all kinds of data elements. For variable data prototypes the 'last is best' semantics applies. For parameter there is no specific implementation directive. **Tags:** atp.EnumerationLiteralIndex=4

Table D.62: SwImplPolicyEnum

Class	**SwSystemconst**			
Note	This element defines a system constant which serves an input to select a particular variation point. In particular a system constant serves as an operand of the binding function (swSyscond) in a Variation point. Note that the binding process can only happen if a value was assigned to to the referenced system constants. **Tags:** atp.recommendedPackage=SwSystemconsts			
Base	*ARElement*, *ARObject*, *AtpDefinition*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
swDataDef Props	SwDataDefProps	0..1	aggr	This denotes the data definition properties of the system constant. This supports to express the limits and optionally a conversion within the internal to physical values by a compu method. **Tags:** atp.Splitkey=swDataDefProps xml.sequenceOffset=40

Table D.63: SwSystemconst

Class	**SwTextProps**			
Note	This meta-class expresses particular properties applicable to strings in variables or calibration parameters.			
Base	*ARObject*			
Aggregated by	SwDataDefProps.swTextProps			
Attribute	*Type*	*Mult.*	*Kind*	*Note*
arraySize Semantics	ArraySizeSemantics Enum	0..1	attr	This attribute controls the semantics of the arraysize for the array representing the string in an `ImplementationDataType`. It is there to support a safe conversion between `ApplicationDataType` and `ImplementationDataType`, even for variable length strings as required e.g. for Support of SAE J1939.
baseType	SwBaseType	0..1	ref	This is the base type of one character in the string. In particular this baseType denotes the intended encoding of the characters in the string on level of `ApplicationDataType`. **Tags:** atp.Splitkey=baseType xml.sequenceOffset=30

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Class	**SwTextProps**			
swFillCharacter	Integer	0..1	attr	Filler character for text parameter to pad up to the maximum length `swMaxTextSize`. The value will be interpreted according to the encoding specified in the associated base type of the data object, e.g. 0x30 (hex) represents the ASCII character zero as filler character and 0 (dec) represents an end of string as filler character. The usage of the fill character depends on the `arraySizeSemantics`. **Tags:** xml.sequenceOffset=40
swMaxTextSize	Integer	0..1	attr	Specifies the maximum text size in characters. Note the size in bytes depends on the encoding in the corresponding `baseType`. **Stereotypes:** atpVariation **Tags:** vh.latestBindingTime=preCompileTime xml.sequenceOffset=20

Table D.64: SwTextProps

Class	**SwcImplementation**			
Note	This meta-class represents a specialization of the general Implementation meta-class with respect to the usage in application software. **Tags:** atp.recommendedPackage=SwcImplementations This Class is only used by the AUTOSAR Classic Platform.			
Base	*ARElement*, *ARObject*, *CollectableElement*, *Identifiable*, *Implementation*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*			
Aggregated by	ARPackage.element			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
behavior	SwcInternalBehavior	0..1	ref	The internal behavior implemented by this Implementation. **Tags:** atp.Splitkey=behavior
perInstance MemorySize	PerInstanceMemory Size	*	aggr	Allows a definition of the size of the per-instance memory for this implementation. The aggregation of PerInstance MemorySize is subject to variability with the purpose to support variability in the software components implementations. Typically different algorithms in the implementation are requiring different number of memory objects, in this case PerInstanceMemory. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=perInstanceMemorySize, perInstance MemorySize.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
required RTEVendor	String	0..1	attr	Identify a specific RTE vendor. This information is potentially important at the time of integrating (in particular: linking) the application code with the RTE. The semantics is that (if the association exists) the corresponding code has been created to fit to the vendor-mode RTE provided by this specific vendor. Attempting to integrate the code with another RTE generated in vendor mode is in general not possible.

Table D.65: SwcImplementation

Class	SwcInternalBehavior			
Note	The SwcInternalBehavior of an AtomicSwComponentType describes the relevant aspects of the software-component with respect to the RTE, i.e. the RunnableEntitys and the RTEEvents they respond to.			
Base	*ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *InternalBehavior*, *Multilanguage Referrable*, *Referrable*			
Aggregated by	*AtomicSwComponentType*.internalBehavior, *AtpClassifier*.atpFeature			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
arTypedPer Instance Memory	VariableDataPrototype	*	aggr	Defines an AUTOSAR typed memory-block that needs to be available for each instance of the SW-component. This is typically only useful if supportsMultipleInstantiation is set to "true" or if the component defines NVRAM access via permanent blocks. The aggregation of arTypedPerInstanceMemory is subject to variability with the purpose to support variability in the software component's implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=arTypedPerInstanceMemory, arTypedPer InstanceMemory.shortName, arTypedPerInstance Memory.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
event	RTEEvent	*	aggr	This is a RTEEvent specified for the particular SwcInternalBehavior. The aggregation of RTEEvent is subject to variability with the purpose to support the conditional existence of RTEEvents. Note: the number of RTEEvents might vary due to the conditional existence of PortPrototypes using DataReceivedEvents or due to different scheduling needs of algorithms. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=event, event.shortName, event.variation Point.shortLabel vh.latestBindingTime=preCompileTime
exclusiveArea Policy	SwcExclusiveArea Policy	*	aggr	Options how to generate the ExclusiveArea related APIs. When no SwcExclusiveAreaPolicy is specified for an ExclusiveArea the default values apply. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=exclusiveAreaPolicy, exclusiveArea Policy.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
explicitInter RunnableVariable	VariableDataPrototype	*	aggr	Implement state message semantics for establishing communication among runnables of the same component. The aggregation of explicitInterRunnable Variable is subject to variability with the purpose to support variability in the software components implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=explicitInterRunnableVariable, explicitInter RunnableVariable.shortName, explicitInterRunnable Variable.variationPoint.shortLabel vh.latestBindingTime=preCompileTime



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Class	**SwcInternalBehavior**			
implicitInter Runnable Variable	VariableDataPrototype	*	aggr	Implement state message semantics for establishing communication among runnables of the same component. The aggregation of implicitInterRunnable Variable is subject to variability with the purpose to support variability in the software components implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=implicitInterRunnableVariable, implicitInter RunnableVariable.shortName, implicitInterRunnable Variable.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
includedData TypeSet	IncludedDataTypeSet	*	aggr	The `includedDataTypeSet` is used by a software component for its implementation. **Tags:** atp.Splitkey=includedDataTypeSet
includedMode Declaration GroupSet	IncludedMode DeclarationGroupSet	*	aggr	This aggregation represents the included Mode DeclarationGroups **Tags:** atp.Splitkey=includedModeDeclarationGroupSet
instantiation DataDefProps	InstantiationDataDef Props	*	aggr	The purpose of this is that within the context of a given SwComponentType some data def properties of individual instantiations can be modified. The aggregation of InstantiationDataDefProps is subject to variability with the purpose to support the conditional existence of Port Prototypes and component local memories like "per InstanceParameter" or "arTypedPerInstanceMemory". **Stereotypes:** atpVariation **Tags:** atp.Splitkey=instantiationDataDefProps, instantiationData DefProps.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
perInstance Memory	PerInstanceMemory	*	aggr	Defines a per-instance memory object needed by this software component. The aggregation of PerInstance Memory is subject to variability with the purpose to support variability in the software components implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=perInstanceMemory, perInstance Memory.shortName, perInstanceMemory.variation Point.shortLabel vh.latestBindingTime=preCompileTime

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Class	**SwcInternalBehavior**			
perInstance Parameter	ParameterData Prototype	*	aggr	Defines parameter(s) or characteristic value(s) that needs to be available for each instance of the software-component. This is typically only useful if supportsMultipleInstantiation is set to "true". The aggregation of perInstanceParameter is subject to variability with the purpose to support variability in the software components implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=perInstanceParameter, perInstance Parameter.shortName, perInstanceParameter.variation Point.shortLabel vh.latestBindingTime=preCompileTime
portAPIOption	PortAPIOption	*	aggr	Options for generating the signature of port-related calls from a runnable to the RTE and vice versa. The aggregation of PortPrototypes is subject to variability with the purpose to support the conditional existence of ports. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=portAPIOption, portAPIOption.port, port APIOption.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
runnable	RunnableEntity	*	aggr	This is a `RunnableEntity` specified for the particular `SwcInternalBehavior`. The aggregation of `RunnableEntity` is subject to variability with the purpose to support the conditional existence of `RunnableEntity`s. Note: the number of `RunnableEntity`s might vary due to the conditional existence of `PortPrototype`s using `DataReceivedEvent`s or due to different scheduling needs of algorithms. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=runnable, runnable.shortName, runnable.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
service Dependency	SwcService Dependency	*	aggr	Defines the requirements on AUTOSAR Services for a particular item. The aggregation of SwcServiceDependency is subject to variability with the purpose to support the conditional existence of ports as well as the conditional existence of ServiceNeeds. The SwcServiceDependency owned by an SwcInternal Behavior can be located in a different physical file in order to support that SwcServiceDependency might be provided in later development steps or even by different expert domain (e.g OBD expert for Obd related Service Needs) tools. Therefore the aggregation is <<atp Splitable>>. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=serviceDependency, service Dependency.shortName, serviceDependency.variation Point.shortLabel vh.latestBindingTime=preCompileTime

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Class	**SwcInternalBehavior**			
shared Parameter	ParameterData Prototype	*	aggr	Defines parameter(s) or characteristic value(s) shared between SwComponentPrototypes of the same Sw ComponentType The aggregation of sharedParameter is subject to variability with the purpose to support variability in the software components implementations. Typically different algorithms in the implementation are requiring different number of memory objects. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=sharedParameter, sharedParameter.short Name, sharedParameter.variationPoint.shortLabel vh.latestBindingTime=preCompileTime
supports Multiple Instantiation	Boolean	0..1	attr	Indicate whether the corresponding software-component can be multiply instantiated on one ECU. In this case the attribute will result in an appropriate component API on programming language level (with or without instance handle).
variationPoint Proxy	VariationPointProxy	*	aggr	Proxy of a variation points in the C/C++ implementation. **Tags:** atp.Splitkey=variationPointProxy, variationPoint Proxy.shortName

Table D.66: SwcInternalBehavior

Class	**System**			
Note	The top level element of the System Description. The System description defines five major elements: Topology, Software, Communication, Mapping and Mapping Constraints. The System element directly aggregates the elements describing the Software, Mapping and Mapping Constraints; it contains a reference to an ASAM FIBEX description specifying Communication and Topology. **Tags:** atp.recommendedPackage=Systems			
Base	*ARElement*, *ARObject*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *CollectableElement*, *Identifiable*, *MultilanguageReferrable*, *PackageableElement*, *Referrable*, *UploadableDesignElement*, *UploadablePackageElement*			
Aggregated by	ARPackage.element, *AtpClassifier*.atpFeature			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
clientId DefinitionSet	ClientIdDefinitionSet	*	ref	Set of Client Identifiers that are used for inter-ECU client-server communication in the System. **Tags:** atp.Splitkey=clientIdDefinitionSet This Attribute is only used by the AUTOSAR Classic Platform.
containerIPdu HeaderByte Order	ByteOrderEnum	0..1	attr	Defines the byteOrder of the header in ContainerIPdus. This Attribute is only used by the AUTOSAR Classic Platform.
ecuExtract Version	RevisionLabelString	0..1	attr	Version number of the Ecu Extract. This Attribute is only used by the AUTOSAR Classic Platform.

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Class	**System**			
fibexElement	FibexElement	*	ref	Reference to ASAM FIBEX elements specifying Communication and Topology. All Fibex Elements used within a System Description shall be referenced from the System Element. atpVariation: In order to describe a product-line, all Fibex Elements can be optional. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=fibexElement, fibexElement.fibexElement, fibexElement.variationPoint.shortLabel vh.latestBindingTime=postBuild
interpolation Routine MappingSet	InterpolationRoutine MappingSet	*	ref	This reference identifies the InterpolationRoutineMapping Sets that are relevant in the context of the enclosing System. **Tags:** atp.Splitkey=interpolationRoutineMappingSet This Attribute is only used by the AUTOSAR Classic Platform.
j1939Shared AddressCluster	J1939SharedAddress Cluster	*	aggr	Collection of J1939Clusters that share a common address space for the routing of messages. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=j1939SharedAddressCluster, j1939Shared AddressCluster.shortName, j1939SharedAddress Cluster.variationPoint.shortLabel vh.latestBindingTime=postBuild This Attribute is only used by the AUTOSAR Classic Platform.
mapping	SystemMapping	*	aggr	Aggregation of all mapping aspects (mapping of SW components to ECUs, mapping of data elements to signals, and mapping constraints). In order to support OEM / Tier 1 interaction and shared development for one common System this aggregation is atpSplitable and atpVariation. The content of System Mapping can be provided by several parties using different names for the SystemMapping. This element is not required when the System description is used for a network-only use-case. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=mapping, mapping.shortName, mapping.variationPoint.shortLabel vh.latestBindingTime=postBuild
pncVector Length	PositiveInteger	0..1	attr	Length of the partial networking request release information vector (in bytes).
pncVectorOffset	PositiveInteger	0..1	attr	Absolute offset (with respect to the NM-PDU) of the partial networking request release information vector that is defined in bytes as an index starting with 0.

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Class	**System**			
rootSoftware Composition	RootSwComposition Prototype	0..1	aggr	Aggregation of the root software composition, containing all software components in the System in a hierarchical structure. This element is not required when the System description is used for a network-only use-case. atpVariation: The RootSwCompositionPrototype can vary. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=rootSoftwareComposition, rootSoftware Composition.shortName, rootSoftware Composition.variationPoint.shortLabel vh.latestBindingTime=systemDesignTime This Attribute is only used by the AUTOSAR Classic Platform.
swCluster	CpSoftwareCluster	*	ref	CP Software Clusters of this System **Stereotypes:** atpVariation **Tags:** atp.Splitkey=swCluster, swCluster.cpSoftwareCluster, sw Cluster.variationPoint.shortLabel vh.latestBindingTime=systemDesignTime This Attribute is only used by the AUTOSAR Classic Platform.
systemCom SpecDefinition	SystemComSpec DefinitionSet	*	ref	Reference to the set of ComSpec definitions that are used for inter-ECU communication in the System. **Tags:** atp.Splitkey=systemComSpecDefinition
system Documentation	Chapter	*	aggr	Possibility to provide additional documentation while defining the System. The System documentation can be composed of several chapters. **Stereotypes:** atpVariation **Tags:** atp.Splitkey=systemDocumentation, system Documentation.shortName, system Documentation.variationPoint.shortLabel vh.latestBindingTime=systemDesignTime xml.sequenceOffset=-10 This Attribute is only used by the AUTOSAR Classic Platform.
systemVersion	RevisionLabelString	0..1	attr	Version number of the System Description.

Table D.67: System

Primitive	**TimeValue**
Note	This primitive type is taken for expressing time values. The numerical value is supposed to be interpreted in the physical unit second. **Tags:** xml.xsd.customType=TIME-VALUE xml.xsd.type=double

Table D.68: TimeValue

Class	**VariableAccess**
Note	The presence of a `VariableAccess` implies that a `RunnableEntity` needs access to a `VariableDataPrototype`. The kind of access is specified by the role in which the class is used.

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Class	VariableAccess			
Base	*ARObject*, *AbstractAccessPoint*, *AtpClassifier*, *AtpFeature*, *AtpStructureElement*, *Identifiable*, *MultilanguageReferrable*, *Referrable*			
Aggregated by	*AtpClassifier*.atpFeature, *ReceiverComSpec*.replaceWith, RunnableEntity.dataReadAccess, RunnableEntity.dataReceivePointByArgument, RunnableEntity.dataReceivePointByValue, RunnableEntity.dataSendPoint, RunnableEntity.dataWriteAccess, RunnableEntity.readLocalVariable, RunnableEntity.writtenLocalVariable			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
accessedVariable	AutosarVariableRef	0..1	aggr	This denotes the accessed variable. **Tags:** atp.Splitkey=accessedVariable
scope	VariableAccessScopeEnum	0..1	attr	This attribute allows for constraining the scope of the corresponding communication. For example, it possible to express whether the communication is intended to cross the boundary of an ECU or whether it is intended not to cross the boundary of a single partition.

Table D.69: VariableAccess

Class	VariationPoint			
Note	This meta-class represents the ability to express a "structural variation point". The container of the variation point is part of the selected variant if swSyscond evaluates to true and each postBuildVariantCriterion is fulfilled.			
Base	*ARObject*			
Attribute	**Type**	**Mult.**	**Kind**	**Note**
blueprintCondition	DocumentationBlock	0..1	aggr	This represents a description that documents how the variation point shall be resolved when deriving objects from the blueprint. Note that variationPoints are not allowed within a blueprintCondition. **Tags:** xml.sequenceOffset=28
desc	MultiLanguageOverviewParagraph	0..1	aggr	This allows to describe shortly the purpose of the variation point. **Tags:** xml.sequenceOffset=20
formalBlueprintGenerator	BlueprintGenerator	0..1	aggr	This represents a description that documents how the variation point shall be resolved when deriving objects from the blueprint by using ARMQL. Note that variationPoints are not allowed within a formal BlueprintGenerator. **Tags:** atp.Status=draft xml.sequenceOffset=30
postBuildVariantCondition	PostBuildVariantCondition	*	aggr	This is the set of post build variant conditions which all shall be fulfilled in order to (postbuild) bind the variation point. **Tags:** xml.sequenceOffset=40
sdg	Sdg	0..1	aggr	An optional special data group is attached to every variation point. These data can be used by external software systems to attach application specific data. For example, a variant management system might add an identifier, an URL or a specific classifier. **Tags:** xml.sequenceOffset=50

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Class	**VariationPoint**			
shortLabel	Identifier	0..1	attr	This provides a name to the particular variation point to support the RTE generator. It is necessary for supporting splitable aggregations and if binding time is later than codeGenerationTime, as well as some RTE conditions. It needs to be unique with in the enclosing Identifiables with the same ShortName. **Stereotypes:** atpIdentityContributor **Tags:** xml.sequenceOffset=10
swSyscond	ConditionByFormula	0..1	aggr	This condition acts as Binding Function for the Variation Point. Note that the multiplicity is 0..1 in order to support pure postBuild variants. **Tags:** xml.sequenceOffset=30

Table D.70: VariationPoint

E Modeling of InstanceRef

E.1 Introduction

The existence of so-called InstanceRefs is a direct consequence of the usage of the type-prototype pattern for modeling within AUTOSAR. When referencing a prototype, it is also necessary to include a reference to the prototypes typed by their corresponding types that in turn aggregate further prototypes to set up the context.

In other words, InstanceRefs are representing **structured references** that, on the one hand, consist of references to context prototypes (indicated by a subsetting or redefinition of atpContextElement) and finally a reference to the applicable target prototype (indicated by a redefinition of atpTarget).

Note that it is not uncommon to have more than a single context in the modeling of particular InstanceRefs.

For the reader of specifications, the modeling of InstanceRefs manifests as a UML dependency stereotyped ≪instanceRef≫ drawn from one meta-class to another. This is a simplified indication that the source of the dependency implements an InstanceRef to the meta-class at the target of the dependency.

Again, in most cases this is everything a reader needs to understand in order to figure out the modeling. The formal modeling of InstanceRefs is done by creating subclasses of the abstract meta-class AtpInstanceRef.

Wherever a more detailed understanding of the modeling is advised in the context of the specific chapter of this document, the modeling of a specific subclass of AtpInstanceRef is explained directly in the context of the corresponding chapter.

In all other cases, a deeper understanding of the modeling of particular subclasses of AtpInstanceRefs can be obtained from reading this chapter.

Class tables included in this chapter are not fully filled out in the sense that most of the notes inside the class tables are missing. The **primary** purpose of these class tables is to **provide information about the intended order in which InstanceRefs are serialized in M1 AUTOSAR models**.

In particular, the information about the order in serialized M1 models can be obtained from the value of the tag xml.sequenceOffset of each attribute of an InstanceRef meta-class.

For more information about the general concept of modeling AtpInstanceRef (e.g. the conceptual background of redefining or subsetting an association from a subclass of AtpInstanceRef to other meta-classes) please refer to the [1, AUTOSAR TPS Generic Structure Template].

E.2 Modeling

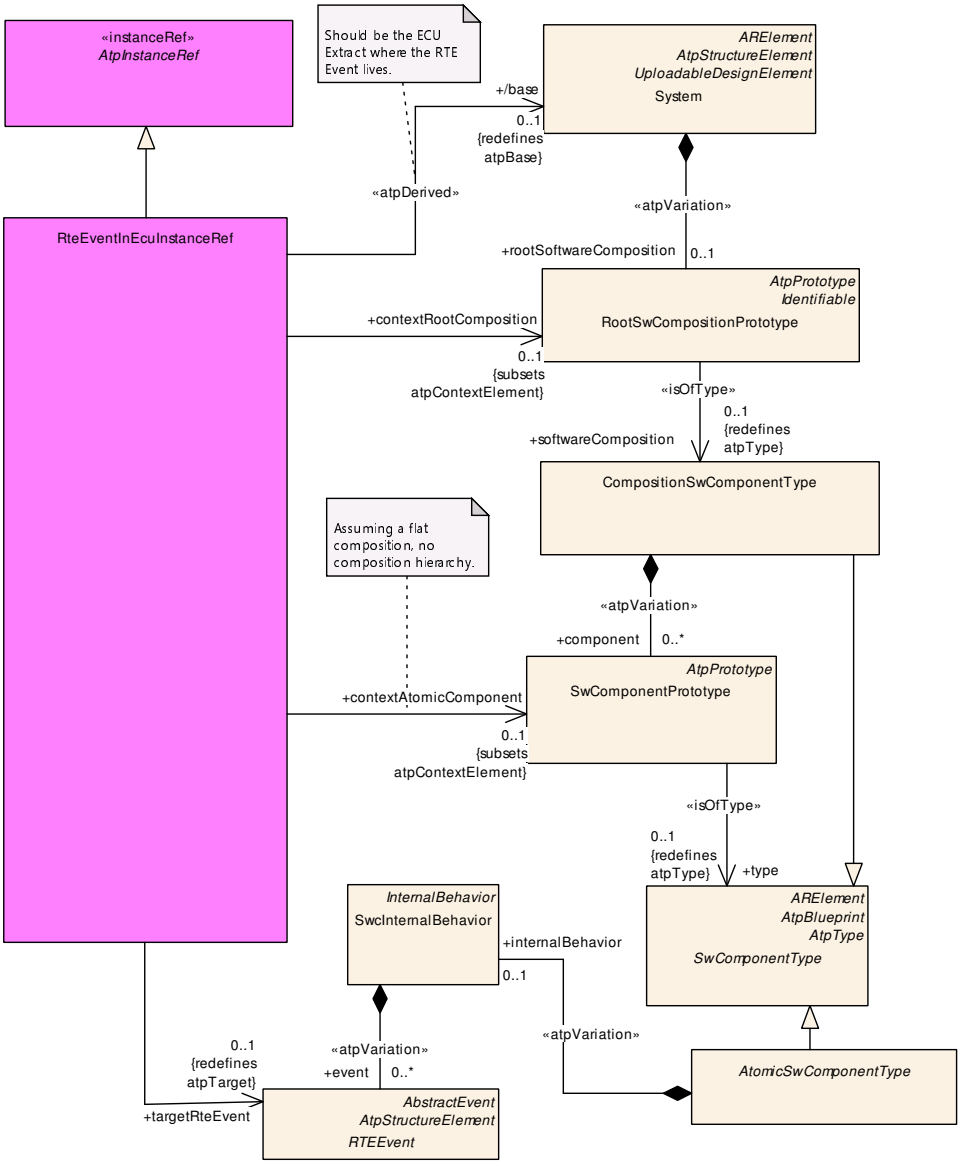

Figure E.1: RTE event in ECU

Class	**RteEventInEcuInstanceRef**			
Note				
Base	*ARObject*, *AtpInstanceRef*			
Aggregated by	McDataAccessDetails.rteEvent			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
base	System	0..1	ref	**Stereotypes:** atpDerived **Tags:** xml.sequenceOffset=10
contextAtomic Component	SwComponent Prototype	0..1	ref	**Tags:** xml.sequenceOffset=30
contextRoot Composition	RootSwComposition Prototype	0..1	ref	**Tags:** xml.sequenceOffset=20
targetRteEvent	RTEEvent	0..1	ref	**Tags:** xml.sequenceOffset=40

Table E.1: RteEventInEcuInstanceRef

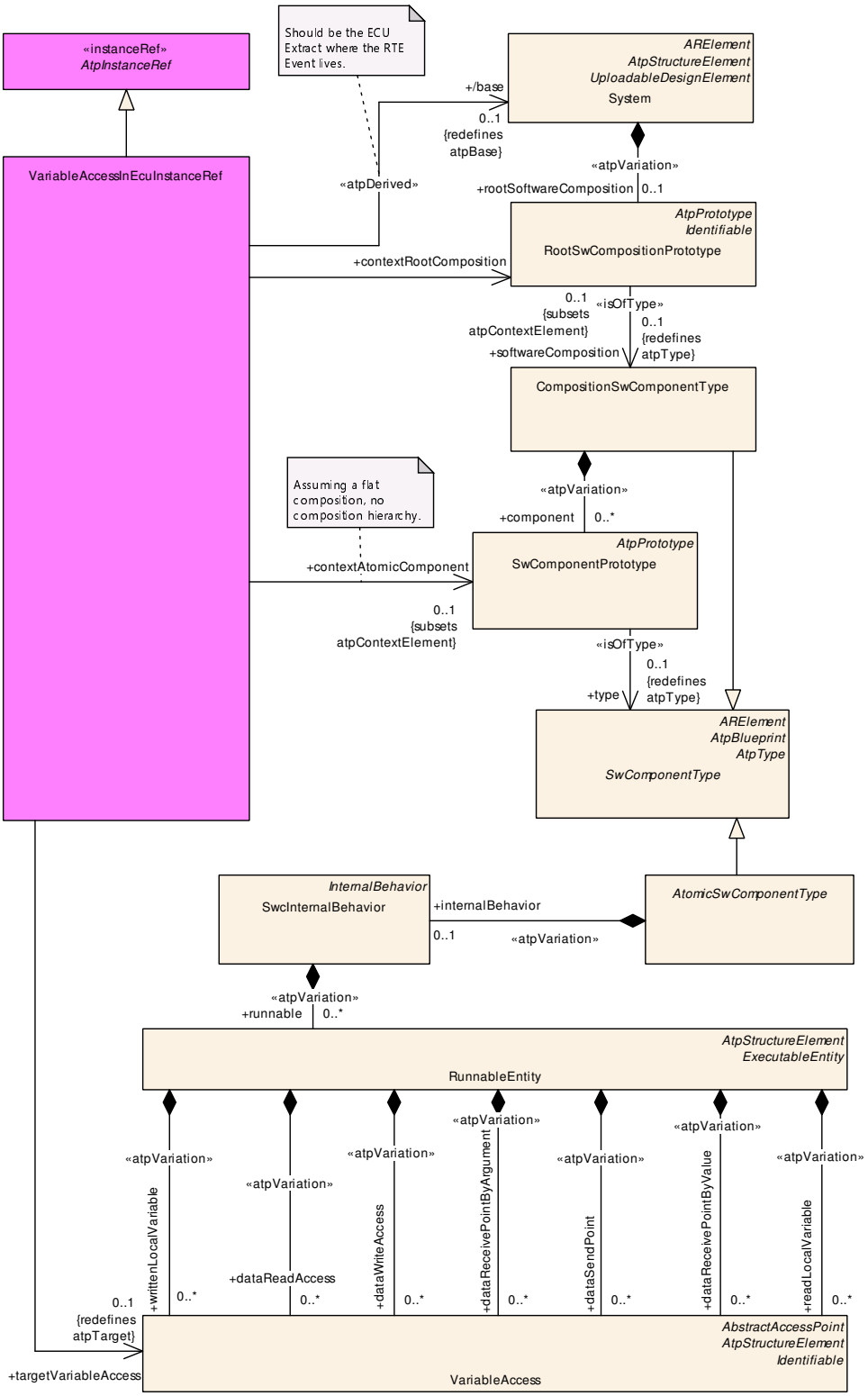

Figure E.2: Variable in ECU

Class	**VariableAccessInEcuInstanceRef**			
Note				
Base	*ARObject*, *AtpInstanceRef*			
Aggregated by	McDataAccessDetails.variableAccess			
Attribute	***Type***	***Mult.***	***Kind***	***Note***
base	System	0..1	ref	**Stereotypes:** atpDerived **Tags:** xml.sequenceOffset=10
contextAtomic Component	SwComponent Prototype	0..1	ref	**Tags:** xml.sequenceOffset=30
contextRoot Composition	RootSwComposition Prototype	0..1	ref	**Tags:** xml.sequenceOffset=20
targetVariable Access	VariableAccess	0..1	ref	**Tags:** xml.sequenceOffset=40

Table E.2: VariableAccessInEcuInstanceRef

F Upstream Mapping

The content of this appendix chapter is *informative* in nature and shall **not** be considered as *normative* content.

F.1 Introduction

This chapter describes the mapping of the ECU Configuration parameters (M1 model) onto the meta-classes and attributes of the BSWMDT.

The relationships between BSWMDT and ECU Configuration are described in order to answer typical questions like:

- How shall a supplier use the information in a System Description in order to fulfill the needs defined by the systems engineer?
- How is a tool vendor supposed to generate an ECU Configuration Description out of an ECU Extract of System Description and BSWMDs delivered for an ECU?

Please note that the tables contain the following columns:

BSW Module: Name of BSW module

BSW Context: Reference to parameter container

BSW Parameter: Name of the BSW parameter

BSW Type: Type of parameter

BSW Description: Description from the configuration document

M2 Template: The upstream templates

M2 Description: Description from the upstream template definition

M2 Parameter: Name of the upstream template parameter

Mapping Rule: Textual description on how to transform between M2 and BSW domains

Mapping Type:
- local: no mapping needed since parameter local to BSW
- partial: some data can be automatically mapped but not all
- full: all data can be automatically mapped

F.2 ComM

BSW Module	BSW Context	
ComM	ComM/ComMConfigSet	
BSW Parameter		**BSW Type**
ComMUser		ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description		
This container contains a list of identifiers that are needed to refer to a user in the system which is designated to request Communication modes.		
Template Description		
Specifies the abstract needs on the configuration of the Communication Manager for one "user".		
M2 Parameter		
ComMgrUserNeeds		
Mapping Rule		**Mapping Type**
In case the owner of the ComMgrUserNeeds is a BSW module then the ComMUser.shortName = {capitalizedMip}_{ServiceDependency.symbolicNameProps.symbol}.		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_ComM_00653]

F.3 Dcm

BSW Module	BSW Context	
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData	
BSW Parameter		**BSW Type**
DcmDspDataFreezeCurrentStateFnc		ECUC-FUNCTION-NAME-DEF
BSW Description		
Function name to request to application to freeze the current state of an IOControl. (FreezeCurrentState-function). This parameter is related to the interface Xxx_FreezeCurrentState.		
Template Description		
DiagnosticIoControlNeeds.freezeCurrentStateSupported: This attribute determines, if the referenced port supports temporary freezing of I/O value. **DiagnosticServiceSwMapping.mappedBswServiceDependency:** This is supposed to represent a reference to a BswServiceDependency. the latter is not derived from Referrable and therefore this detour needs to be implemented to still let BswServiceDependency become the target of a reference.		
M2 Parameter		
DiagnosticIoControlNeeds.freezeCurrentStateSupported, DiagnosticServiceSwMapping.mappedBswServiceDependency		
Mapping Rule		**Mapping Type**
It could be possible to get the FNC name via BswServiceDependency		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Dcm_00674]

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData
BSW Parameter	**BSW Type**
DcmDspDataResetToDefaultFnc	ECUC-FUNCTION-NAME-DEF
BSW Description	
Function name to request to application to reset an IOControl to default value. (ResetToDefault-function). This parameter is related to the interface Xxx_ResetToDefault.	
Template Description	
DiagnosticIoControlNeeds.resetToDefaultSupported: This represents a flag for the existence of the ResetToDefault operation in the service interface. **DiagnosticServiceSwMapping.mappedBswServiceDependency:** This is supposed to represent a reference to a BswServiceDependency. the latter is not derived from Referrable and therefore this detour needs to be implemented to still let BswServiceDependency become the target of a reference.	
M2 Parameter	
DiagnosticIoControlNeeds.resetToDefaultSupported, DiagnosticServiceSwMapping.mappedBswServiceDependency	
Mapping Rule	**Mapping Type**
It could be possible to get the FNC name via BswServiceDependency	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Dcm_00673]

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData
BSW Parameter	**BSW Type**
DcmDspDataShortTermAdjustmentFnc	ECUC-FUNCTION-NAME-DEF
BSW Description	
Function name to request to application to adjust the IO signal. (ShortTermAdjustment-function). This parameter is related to the interface Xxx_ShortTermAdjustment.	
Template Description	
DiagnosticIoControlNeeds.shortTermAdjustmentSupported: This attribute determines, if the referenced port supports temporarily setting of I/O value to a specific value provided by the diagnostic tester. **DiagnosticServiceSwMapping.mappedBswServiceDependency:** This is supposed to represent a reference to a BswServiceDependency. the latter is not derived from Referrable and therefore this detour needs to be implemented to still let BswServiceDependency become the target of a reference.	
M2 Parameter	
DiagnosticIoControlNeeds.shortTermAdjustmentSupported, DiagnosticServiceSwMapping.mappedBswServiceDependency	
Mapping Rule	**Mapping Type**
It could be possible to get the FNC name via BswServiceDependency.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Dcm_00675]

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	

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Type of the data is float array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size.	
M2 Parameter	
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticDataElement.arraySizeSemantics`	
Mapping Rule	**Mapping Type**
• `baseTypeEncoding` = IEEE754 • `baseTypeSize` = 32 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
SINT16_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint16 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeSize: Describes the length of the data type specified in the container in bits. **BaseTypeDirectDefinition.baseTypeEncoding:** This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed.	
M2 Parameter	

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BaseTypeDirectDefinition.baseTypeSize, BaseTypeDirectDefinition.baseTypeEncoding, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.maxNumberOfElements, DiagnosticDataElement.arraySizeSemantics	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = 2C • baseTypeSize = 16 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001)* arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
SINT32_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint32 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeSize: Describes the length of the data type specified in the container in bits. **BaseTypeDirectDefinition.baseTypeEncoding:** This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed.	
M2 Parameter	
BaseTypeDirectDefinition.baseTypeSize, BaseTypeDirectDefinition.baseTypeEncoding, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = 2C • baseTypeSize = 32 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint64 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.	
M2 Parameter	
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`	
Mapping Rule	**Mapping Type**
• `baseTypeEncoding` = 2C • `baseTypeSize` = 64 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
SINT8_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint8 array.	
Template Description	

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BaseTypeDirectDefinition.baseTypeSize:
Describes the length of the data type specified in the container in bits.

BaseTypeDirectDefinition.baseTypeEncoding:
This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence.

DiagnosticDataElement.arraySizeSemantics:
This attribute controls the meaning of the value of the array size.

DiagnosticDataElement.maxNumberOfElements:
The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.

DiagnosticValueNeeds.fixedLength:
This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency.

This attribute controls whether the data length of the data is fixed.

M2 Parameter

`BaseTypeDirectDefinition.baseTypeSize`, `BaseTypeDirectDefinition.baseTypeEncoding`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`

Mapping Rule	Mapping Type
• `baseTypeEncoding` = 2C • `baseTypeSize` = 8 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001)* `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
UINT16_N	ECUC-ENUMERATION-LITERAL-DEF

BSW Description

Type of the data is uint16 array.

Template Description

BaseTypeDirectDefinition.baseTypeEncoding:
This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence.

BaseTypeDirectDefinition.baseTypeSize:
Describes the length of the data type specified in the container in bits.

DiagnosticDataElement.arraySizeSemantics:
This attribute controls the meaning of the value of the array size.

DiagnosticDataElement.maxNumberOfElements:
The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.

DiagnosticValueNeeds.fixedLength:
This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency.

This attribute controls whether the data length of the data is fixed.

M2 Parameter

`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticDataElement.arraySizeSemantics`

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Mapping Rule	Mapping Type
• baseTypeEncoding = NONE,UTF-16 • baseTypeSize = 16 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
UINT32_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is uint32 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed.	
M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	

Mapping Rule	Mapping Type
• baseTypeEncoding = NONE,UTF-32 • baseTypeSize = 8 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
UINT8_DYN	ECUC-ENUMERATION-LITERAL-DEF

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BSW Description	
Type of the data is uint8 array with dynamic length.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed.	
M2 Parameter	
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`	
Mapping Rule	**Mapping Type**
• `baseTypeEncoding` = NONE,WINDOWS-1252,UTF-8 • `baseTypeSize` = 8 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `variableSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =0 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataType
BSW Parameter	**BSW Type**
UINT8_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is uint8 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed.	
M2 Parameter	

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BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = NONE • baseTypeSize = 8 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataUsePort
BSW Parameter	**BSW Type**
USE_DATA_ASYNCH_FNC	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
The DCM will access the Data using the functions that are defined in parameters of type EcucFunctionNameDef (but without DcmDspDataReadDataLengthFnc) in the DcmDspData container. DCM_E_PENDING return is allowed. OpStatus is existing as IN parameter.	
Template Description	
The software-component processes the request in background but still the Dcm has to issue the call again to eventually obtain the result of the request.	
M2 Parameter	
DiagnosticProcessingStyleEnum.processingStyleAsynchronous	
Mapping Rule	**Mapping Type**
DiagnosticServiceSwMapping is having a BswServiceDependency and ServiceNeeds::DiagnosticProcessingStyleEnum is equal to processingStyleAsynchronous	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataUsePort
BSW Parameter	**BSW Type**
USE_DATA_ASYNCH_FNC_ERROR	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
The DCM will access the Data using the functions that are defined in parameters of type EcucFunctionNameDef (but without DcmDspDataReadDataLengthFnc) in the DcmDspData container. DCM_E_PENDING return is allowed. OpStatus is existing as IN parameter. The parameter ErrorCode can be returned to allow the application to trigger a negative response during the operation.	
Template Description	
The software-component processes the request in background but still the Dcm has to issue the call again to eventually obtain the result of the request or handle error code.	
M2 Parameter	
DiagnosticProcessingStyleEnum.processingStyleAsynchronousWithError	
Mapping Rule	**Mapping Type**

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DiagnosticServiceSwMapping is having a BswServiceDependency and ServiceNeeds::DiagnosticProcessingStyleEnum is equal to processingStyleAsynchronousWithError	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspData/DcmDspDataUsePort
BSW Parameter	**BSW Type**
USE_DATA_SYNCH_FNC	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
The DCM will access the Data using the functions that are defined in parameters of type EcucFunctionNameDef (but without DcmDspDataReadDataLengthFnc) in the DcmDspData container. DCM_E_PENDING return value is not allowed and Op Status parameter is not existing in the prototype.	
Template Description	
The software-component is supposed to react synchronously on the request.	
M2 Parameter	
DiagnosticProcessingStyleEnum.processingStyleSynchronous	
Mapping Rule	**Mapping Type**
DiagnosticServiceSwMapping is having a BswServiceDependency and ServiceNeeds::DiagnosticProcessingStyleEnum is equal to processingStyleSynchronous	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspPid/DcmDspPidData/DcmDspPidService01/DcmDspPid DataType
BSW Parameter	**BSW Type**
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint64 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.	
M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	
Mapping Rule	**Mapping Type**

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• baseTypeEncoding = 2C • baseTypeSize = 64 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspRequestRoutineResults/DcmDspRequestRoutineResultsOut/DcmDspRequestRoutineResultsOutSignal/DcmDspRoutineSignalType
BSW Parameter	**BSW Type**
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is float array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size.	
M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.maxNumberOfElements, DiagnosticDataElement.arraySizeSemantics	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = IEEE754 • baseTypeSize = 32 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspRequestRoutineResults/DcmDspRequestRoutineResultsOut/DcmDspRequestRoutineResultsOutSignal/DcmDspRoutineSignalType
BSW Parameter	**BSW Type**
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF

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BSW Description
Type of the data is sint64 array.
Template Description
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.
M2 Parameter
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`

Mapping Rule	Mapping Type
• `baseTypeEncoding` = 2C • `baseTypeSize` = 64 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspRequestRoutineResults/DcmDspRequestRoutineResultsOut/DcmDspRequestRoutineResultsOutSignalCompositePool/DcmDspRequestRoutineResultsOutSignal/DcmDspRoutineSignalType

BSW Parameter	BSW Type
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is float array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size.	

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M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.maxNumberOfElements, DiagnosticDataElement.arraySizeSemantics	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = IEEE754 • baseTypeSize = 32 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspRequestRoutineResults/DcmDspRequestRoutineResultsOut/DcmDspRequestRoutineResultsOutSignalCompositePool/DcmDspRequestRoutineResultsOutSignal/DcmDspRoutineSignalType

BSW Parameter	BSW Type
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF

BSW Description

Type of the data is sint64 array.

Template Description

BaseTypeDirectDefinition.baseTypeEncoding:
This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence.

BaseTypeDirectDefinition.baseTypeSize:
Describes the length of the data type specified in the container in bits.

DiagnosticValueNeeds.fixedLength:
This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency.

This attribute controls whether the data length of the data is fixed.

DiagnosticDataElement.arraySizeSemantics:
This attribute controls the meaning of the value of the array size.

DiagnosticDataElement.maxNumberOfElements:
The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.

M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = 2C • baseTypeSize = 64 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineIn/DcmDspStartRoutineInSignal/DcmDspRoutineSignalType

BSW Parameter	BSW Type
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF

BSW Description

Type of the data is float array.

Template Description

BaseTypeDirectDefinition.baseTypeEncoding:
This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence.

BaseTypeDirectDefinition.baseTypeSize:
Describes the length of the data type specified in the container in bits.

DiagnosticValueNeeds.fixedLength:
This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency.

This attribute controls whether the data length of the data is fixed.

DiagnosticDataElement.maxNumberOfElements:
The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.

DiagnosticDataElement.arraySizeSemantics:
This attribute controls the meaning of the value of the array size.

M2 Parameter

`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticDataElement.arraySizeSemantics`

Mapping Rule	Mapping Type
• `baseTypeEncoding` = IEEE754 • `baseTypeSize` = 32 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full

Mapping Status	ECUC Parameter ID
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineIn/DcmDspStartRoutineInSignal/DcmDspRoutineSignalType

BSW Parameter	BSW Type
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF

BSW Description

Type of the data is sint64 array.

Template Description

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BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.
M2 Parameter
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`

Mapping Rule	**Mapping Type**
• `baseTypeEncoding` = 2C • `baseTypeSize` = 64 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineIn/DcmDspStartRoutineInSignalCompositePool/DcmDspStartRoutineInSignal/DcmDspRoutineSignalType

BSW Parameter	**BSW Type**
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is float array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size.	
M2 Parameter	
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticDataElement.arraySizeSemantics`	

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Mapping Rule	Mapping Type
• baseTypeEncoding = IEEE754 • baseTypeSize = 32 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineIn/DcmDspStartRoutineInSignalCompositePool/DcmDspStartRoutineInSignal/DcmDspRoutineSignalType
BSW Parameter	**BSW Type**
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint64 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.	
M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = 2C • baseTypeSize = 64 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineOut/DcmDspStartRoutineOutSignal/DcmDspRoutineSignalType
BSW Parameter	**BSW Type**

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FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is float array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size.	
M2 Parameter	
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticDataElement.arraySizeSemantics`	
Mapping Rule	**Mapping Type**
• `baseTypeEncoding` = IEEE754 • `baseTypeSize` = 32 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineOut/DcmDspStartRoutineOutSignal/DcmDspRoutineSignalType
BSW Parameter	**BSW Type**
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint64 array.	
Template Description	

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BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.
M2 Parameter
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`

Mapping Rule	**Mapping Type**
• `baseTypeEncoding` = 2C • `baseTypeSize` = 64 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineOut/DcmDspStartRoutineOutSignalCompositePool/DcmDspStartRoutineOutSignal/DcmDspRoutineSignalType

BSW Parameter	**BSW Type**
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is float array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size.	
M2 Parameter	

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BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.maxNumberOfElements, DiagnosticDataElement.arraySizeSemantics	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = IEEE754 • baseTypeSize = 32 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStartRoutine/DcmDspStartRoutineOut/DcmDspStartRoutineOutSignalCompositePool/DcmDspStartRoutineOutSignal/DcmDspRoutineSignalType
BSW Parameter	**BSW Type**
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint64 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.	
M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = 2C • baseTypeSize = 64 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStopRoutine/DcmDspStopRoutineOut/DcmDspStopRoutineOutSignal/DcmDspRoutineSignalType

BSW Parameter	BSW Type
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF

BSW Description

Type of the data is float array.

Template Description

BaseTypeDirectDefinition.baseTypeEncoding:
This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence.

BaseTypeDirectDefinition.baseTypeSize:
Describes the length of the data type specified in the container in bits.

DiagnosticValueNeeds.fixedLength:
This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency.

This attribute controls whether the data length of the data is fixed.

DiagnosticDataElement.maxNumberOfElements:
The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.

DiagnosticDataElement.arraySizeSemantics:
This attribute controls the meaning of the value of the array size.

M2 Parameter

`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.maxNumberOfElements`, `DiagnosticDataElement.arraySizeSemantics`

Mapping Rule	Mapping Type
• `baseTypeEncoding` = IEEE754 • `baseTypeSize` = 32 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full

Mapping Status	ECUC Parameter ID
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStopRoutine/DcmDspStopRoutineOut/DcmDspStopRoutineOutSignal/DcmDspRoutineSignalType

BSW Parameter	BSW Type
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF

BSW Description

Type of the data is sint64 array.

Template Description

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BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.
M2 Parameter
`BaseTypeDirectDefinition.baseTypeEncoding`, `BaseTypeDirectDefinition.baseTypeSize`, `DiagnosticValueNeeds.fixedLength`, `DiagnosticDataElement.arraySizeSemantics`, `DiagnosticDataElement.maxNumberOfElements`

Mapping Rule	Mapping Type
• `baseTypeEncoding` = 2C • `baseTypeSize` = 64 • `maxNumberOfElements` exists and value is greater than 0 (cf. TPS_DEXT_01001) • `arraySizeSemantics` either does not exist or exists and is set to `fixedSize` (cf. TPS_DEXT_01001) Derivation from `fixedLength` =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	BSW Context
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStopRoutine/DcmDspStopRoutineOut/DcmDspStopRoutineOutSignalCompositePool/DcmDspStopRoutineOutSignal/DcmDspRoutineSignalType

BSW Parameter	BSW Type
FLOAT_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is float array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size.	
M2 Parameter	

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BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.maxNumberOfElements, DiagnosticDataElement.arraySizeSemantics	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = IEEE754 • baseTypeSize = 32 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

BSW Module	**BSW Context**
Dcm	Dcm/DcmConfigSet/DcmDsp/DcmDspRoutine/DcmDspStopRoutine/DcmDspStopRoutineOut/DcmDspStopRoutineOutSignalCompositePool/DcmDspStopRoutineOutSignal/DcmDspRoutineSignalType
BSW Parameter	**BSW Type**
SINT64_N	ECUC-ENUMERATION-LITERAL-DEF
BSW Description	
Type of the data is sint64 array.	
Template Description	
BaseTypeDirectDefinition.baseTypeEncoding: This specifies, how an object of the current BaseType is encoded, e.g. in an ECU within a message sequence. **BaseTypeDirectDefinition.baseTypeSize:** Describes the length of the data type specified in the container in bits. **DiagnosticValueNeeds.fixedLength:** This attribute is applicable only if the DiagnosticValueNeeds is aggregated within a BswModuleDependency. This attribute controls whether the data length of the data is fixed. **DiagnosticDataElement.arraySizeSemantics:** This attribute controls the meaning of the value of the array size. **DiagnosticDataElement.maxNumberOfElements:** The existence of this attribute turns the data instance into an array of data. The attribute determines the size of the array in terms of how many elements the array can take.	
M2 Parameter	
BaseTypeDirectDefinition.baseTypeEncoding, BaseTypeDirectDefinition.baseTypeSize, DiagnosticValueNeeds.fixedLength, DiagnosticDataElement.arraySizeSemantics, DiagnosticDataElement.maxNumberOfElements	
Mapping Rule	**Mapping Type**
• baseTypeEncoding = 2C • baseTypeSize = 64 • maxNumberOfElements exists and value is greater than 0 (cf. TPS_DEXT_01001) • arraySizeSemantics either does not exist or exists and is set to fixedSize (cf. TPS_DEXT_01001) Derivation from fixedLength =1 possible.	full
Mapping Status	**ECUC Parameter ID**
valid	

F.4 Dem

BSW Module	BSW Context	
Dem	Dem/DemConfigSet	
BSW Parameter		**BSW Type**
DemEventParameter		ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description		
This container contains the configuration (parameters) for events.		
Template Description		
DiagnosticEventNeeds: Specifies the abstract needs on the configuration of the Diagnostic Event Manager for one diagnostic event. Its shortName can be regarded as a symbol identifying the diagnostic event from the viewpoint of the component or module which owns this element. In case the diagnostic event specifies a production error, the shortName shall be the name of the production error. **DiagnosticEvent:** This element is used to configure DiagnosticEvents.		
M2 Parameter		
DiagnosticEventNeeds, DiagnosticEvent		
Mapping Rule		**Mapping Type**
In case the owner of the DiagnosticEventNeeds is a BSW module then the DemEvent Parameter.shortName = {capitalizedMip}_{ServiceDependency.symbolicNameProps.symbol}. For DiagnosticEvent: 1:1		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Dem_00661]

BSW Module	BSW Context	
Dem	Dem/DemGeneral	
BSW Parameter		**BSW Type**
DemRatio		ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description		
This container contains the OBD-specific in-use-monitor performance ratio configuration. It is related to a specific event, a FID, and an IUMPR group.		
Template Description		
ObdRatioServiceNeeds: Specifies the abstract needs of a component or module on the configuration of OBD Services in relation to a particular "ratio monitoring" which is supported by this component or module. **DiagnosticIumprGroup:** This meta-class represents the ability to model a IUMPR groups.		
M2 Parameter		
ObdRatioServiceNeeds, DiagnosticIumprGroup		
Mapping Rule		**Mapping Type**
In case the owner of the ObdRatioServiceNeeds is a BSW module then the DemRatio.shortName = {capitalizedMip}_{ServiceDependency.symbolicNameProps.symbol}. For the DiagnosticIumprGroup the mapping rule is 1:1		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Dem_00734]

F.5 EcuC

BSW Module	BSW Context
EcuC	EcuC/EcucPartitionCollection/EcucPartition
BSW Parameter	**BSW Type**
EcucPartitionBswModuleDistinguishedPartition	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
This maps the abstract partition of the Bsw Module to a concrete Partition existing in the ECU.	
Template Description	
Each instance of this meta-class represents an abstract partition in which context the code of the enclosing BswModule Behavior can be executed. The intended use case is to distinguish between several partitions in order to implement different behavior per partition, for example to behave either as a master or satellite in a multicore ECU with shared BSW code.	
M2 Parameter	
BswDistinguishedPartition	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_EcuC_00068]

BSW Module	BSW Context
EcuC	EcuC/EcucUnitGroupAssignment
BSW Parameter	**BSW Type**
EcucUnitGroupRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Optional reference to the UnitGroup to support the generation of ASAM MCD file. These UnitGroups are selecting a set of units for a specific country.	
Template Description	
This meta-class represents the ability to specify a logical grouping of units.The category denotes the unit system that the referenced units are associated to. In this way, e.g. country-specific unit systems (CATEGORY="COUNTRY") can be defined as well as specific unit systems for certain application domains. In the same way a group of equivalent units, can be defined which are used in different countries, by setting CATEGORY="EQUIV_UNITS". KmPerHour and MilesPerHour could such be combined to one group named "vehicle_speed". The unit MeterPerSec would not belong to this group because it is normally not used for vehicle speed. But all of the mentioned units could be combined to one group named "speed". Note that the UnitGroup does not ensure the physical compliance of the units. This is maintained by the physical dimension.	
M2 Parameter	
UnitGroup	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_EcuC_00062]

F.6 FiM

BSW Module	BSW Context
FiM	FiM/FiMConfigSet
BSW Parameter	**BSW Type**
FiMFID	ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description	
This container includes symbolic names of all FIDs.	
Template Description	
FunctionInhibitionNeeds: Specifies the abstract needs on the configuration of the Function Inhibition Manager for one Function Identifier (FID). This class currently contains no attributes. Its name can be regarded as a symbol identifying the FID from the viewpoint of the component or module which owns this class. **DiagnosticFunctionIdentifier:** This meta-class represents a diagnostic function identifier (a.k.a. FID).	
M2 Parameter	
FunctionInhibitionNeeds, DiagnosticFunctionIdentifier	
Mapping Rule	**Mapping Type**
In case the owner of the FunctionInhibitionNeeds is a BSW module then the FiMFID.shortName= {capitalizedMip}_{ServiceDependency.symbolicNameProps.symbol}.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_FiM_00039]

F.7 NvM

BSW Module	BSW Context
NvM	NvM
BSW Parameter	**BSW Type**
NvMBlockDescriptor	ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description	
Container for a management structure to configure the composition of a given NVRAM Block Management Type. Its multiplicity describes the number of configured NVRAM blocks, one block is required to be configured. The NVRAM block descriptors are condensed in the NVRAM block descriptor table.	
Template Description	
Specifies the abstract needs on the configuration of a single NVRAM Block.	
M2 Parameter	
NvBlockNeeds	
Mapping Rule	**Mapping Type**
In case the owner of the NvBlockNeeds is a BSW module then the NvMBlockDescriptor.short Name = {capitalizedMip}_{ServiceDependency.symbolicNameProps.symbol}.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00061]

BSW Module	BSW Context
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**

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NvMBlockJobPriority	ECUC-INTEGER-PARAM-DEF
BSW Description	
Defines the job priority for a NVRAM block (0 = Immediate priority).	
Template Description	
NvBlockNeeds.writingPriority: Requires the priority of writing this block in case of concurrent requests to write other blocks. **NvBlockNeeds.storeEmergency:** Defines whether or not the associated RAM Block shall be implicitly stored in case of ECU failure (e.g. loss of power) by the basic software. If the attribute storeEmergency is set to true the associated RAM Block shall be configured to have immediate priority.	
M2 Parameter	
NvBlockNeeds.writingPriority, NvBlockNeeds.storeEmergency	
Mapping Rule	**Mapping Type**
It is the integrators job to secure the value-monotonic assignment of writingPriority to NvMBlock JobPriority. This means that the lowest assigned value of writingPriority=MEDIUM shall be greater than highest assigned value of writingPriority=HIGH etc.If NvBlockNeeds.storeEmergency is set to true, then NvMBlockJobPriority shall be 0 (Immediate priority). If NvBlockNeeds.storeEmergency is set to false, then the value of NvMBlockJobPriority depends on the value of NvBlock Needs.writingPriority.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00477]

BSW Module	**BSW Context**
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMBlockManagementType	ECUC-ENUMERATION-PARAM-DEF
BSW Description	
Defines the block management type for the NVRAM block.[SWS_NvM_00137]	
Template Description	
Reliability against data loss on the non-volatile medium.	
M2 Parameter	
NvBlockNeeds.reliability	
Mapping Rule	**Mapping Type**
if (reliability == errorDetection | noProtection) && nDataSets==0 then NvmBlockManagementType = NVM_BLOCK_NATIVE. if reliability == errorCorrection then NvmBlockManagementType = NVM_BLOCK_REDUNDANT. [constr_1095] applies.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00062]

BSW Module	**BSW Context**
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMBlockUseAutoValidation	ECUC-BOOLEAN-PARAM-DEF
BSW Description	
Defines whether the RAM Block shall be auto validated during shutdown phase. true: if auto validation mechanism is used, false: otherwise	
Template Description	
If set to true the RAM Block shall be auto validated during shutdown phase.	

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M2 Parameter	
NvBlockNeeds.useAutoValidationAtShutDown	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00557]

BSW Module	BSW Context
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMBlockUseCRCCompMechanism	ECUC-BOOLEAN-PARAM-DEF
BSW Description	
Defines whether the CRC of the RAM Block shall be compared during a write job with the CRC which was calculated during the last successful read or write job. true: if compare mechanism is used, false: otherwise	
Template Description	
If set to true the CRC of the RAM Block shall be compared during a write job with the CRC which was calculated during the last successful read or write job in order to skip unnecessary NVRAM writings.	
M2 Parameter	
NvBlockNeeds.useCRCCompMechanism	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00556]

BSW Module	BSW Context
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMBlockUseCrc	ECUC-BOOLEAN-PARAM-DEF
BSW Description	
Defines CRC usage for the NVRAM block, i.e. memory space for CRC is reserved in RAM and NV memory. true: CRC will be used for this NVRAM block. false: CRC will not be used for this NVRAM block. Note: Configuring CRC for a block with immediate priority is not recommended, since the CRC calculation may extend over more than one NvM main function and this could increase the time of writing the immediate data significantly, thus defeating the purpose of immediate priority.	
Template Description	
Reliability against data loss on the non-volatile medium.	
M2 Parameter	
NvBlockNeeds.reliability	
Mapping Rule	**Mapping Type**
reliability == errorCorrection | errorDetection means that NvmBlockUseCrc shall bet set to true, else NvmBlockUseCrc = false	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00036]

BSW Module	BSW Context	
NvM	NvM/NvMBlockDescriptor	
BSW Parameter		**BSW Type**
NvMBlockUseSetRamBlockStatus		ECUC-BOOLEAN-PARAM-DEF
BSW Description		
Defines if NvMSetRamBlockStatusApi shall be used for this block or not. Note: If NvMSetRamBlockStatusApi is disabled this configuration parameter shall be ignored. true: calling of NvMSetRamBlockStatus for this RAM block shall set the status of the RAM block. false: calling of NvMSetRamBlockStatus for this RAM block shall be ignored.		
Template Description		
This attribute defines how the management of the RAM Block status is controlled.		
M2 Parameter		
NvBlockNeeds.ramBlockStatusControl		
Mapping Rule		**Mapping Type**
If the value of NvBlockNeeds.ramBlockStatusControl is set to RamBlockStatusControlEnum.api the parameter shall be set to true. If the value of NvBlockNeeds.ramBlockStatusControl is set to RamBlockStatusControlEnum.nvRamManager it shall be set to false.		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_NvM_00552]

BSW Module	BSW Context	
NvM	NvM/NvMBlockDescriptor	
BSW Parameter		**BSW Type**
NvMBlockWriteProt		ECUC-BOOLEAN-PARAM-DEF
BSW Description		
Defines an initial write protection of the NV block true: Initial block write protection is enabled. false: Initial block write protection is disabled.		
Template Description		
true: data of this NVRAM Block are write protected for normal operation (but protection can be disabled) false: no restriction		
M2 Parameter		
NvBlockNeeds.readonly		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_NvM_00033]

BSW Module	BSW Context	
NvM	NvM/NvMBlockDescriptor	
BSW Parameter		**BSW Type**
NvMCalcRamBlockCrc		ECUC-BOOLEAN-PARAM-DEF
BSW Description		
Defines CRC (re)calculation for the permanent RAM block or NVRAM blocks which are configured to use explicit synchronization mechanism. true: CRC will be (re)calculated for this permanent RAM block. false: CRC will not be (re)calculated for this permanent RAM block.		

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Template Description	
Defines if CRC (re)calculation for the permanent RAM Block is required.	
M2 Parameter	
NvBlockNeeds.calcRamBlockCrc	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00119]

BSW Module	BSW Context
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMNvBlockNum	ECUC-INTEGER-PARAM-DEF
BSW Description	
Defines the number of multiple NV blocks in a contiguous area according to the given block management type. 1-255 For NVRAM blocks to be configured of block management type NVM_BLOCK_DATASET. The actual range is limited according to SWS_NvM_00444. 1 For NVRAM blocks to be configured of block management type NVM_BLOCK_NATIVE 2 For NVRAM blocks to be configured of block management type NVM_BLOCK_REDUNDANT	
Template Description	
NvBlockNeeds.nDataSets: Number of data sets to be provided by the NVRAM manager for this block. This is the total number of ROM Blocks and RAM Blocks. **NvBlockNeeds.reliability:** Reliability against data loss on the non-volatile medium.	
M2 Parameter	
NvBlockNeeds.nDataSets, NvBlockNeeds.reliability	
Mapping Rule	**Mapping Type**
if (nDataSets == 0 && reliability ==noProtection | errorDetection) then NvMNvBlockNum = 1. if (n DataSets >0 && reliability ==noProtection | errorDetection) then NvMNvBlockNum = nDataSets.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00480]

BSW Module	BSW Context
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMResistantToChangedSw	ECUC-BOOLEAN-PARAM-DEF
BSW Description	
Defines whether a NVRAM block shall be treated resistant to configuration changes or not. If there is no default data available at configuration time then the application shall be responsible for providing the default initialization data. In this case the application has to use NvM_GetErrorStatus()to be able to distinguish between first initialization and corrupted data. true: NVRAM block is resistant to changed software. false: NVRAM block is not resistant to changed software.	
Template Description	
Defines whether an NVRAM Block shall be treated resistant to configuration changes (true) or not (false). For details how to handle initialization in the latter case, please refer to the NVRAM specification.	
M2 Parameter	
NvBlockNeeds.resistantToChangedSw	

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Mapping Rule	Mapping Type
1:1 Mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00483]

BSW Module	BSW Context
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMRomBlockNum	ECUC-INTEGER-PARAM-DEF
BSW Description	
Defines the number of multiple ROM blocks in a contiguous area according to the given block management type. 0-254 For NVRAM blocks to be configured of block management type NVM_BLOCK_DATASET. The actual range is limited according to SWS_NvM_00444. 0-1 For NVRAM blocks to be configured of block management type NVM_BLOCK_NATIVE 0-1 For NVRAM blocks to be configured of block management type NVM_BLOCK_REDUNDANT	
Template Description	
Number of ROM Blocks to be provided by the NVRAM manager for this block. Please note that these multiple ROM Blocks are given in a contiguous area.	
M2 Parameter	
NvBlockNeeds.nRomBlocks	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00485]

BSW Module	BSW Context
NvM	NvM/NvMBlockDescriptor
BSW Parameter	**BSW Type**
NvMSelectBlockForReadAll	ECUC-BOOLEAN-PARAM-DEF
BSW Description	
Defines whether a NVRAM block shall be processed during NvM_ReadAll or not. This configuration parameter has only influence on those NVRAM blocks which are configured to have a permanent RAM block or which are configured to use explicit synchronization mechanism. true: NVRAM block shall be processed by NvM_ReadAll false: NVRAM block shall not be processed by NvM_ReadAll	
Template Description	
Defines whether the associated RAM Block shall be implicitly restored during startup by the basic software.	
M2 Parameter	
NvBlockNeeds.restoreAtStart	
Mapping Rule	**Mapping Type**
1:1 Mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00117]

BSW Module	BSW Context	
NvM	NvM/NvMBlockDescriptor	
BSW Parameter		**BSW Type**
NvMSelectBlockForWriteAll		ECUC-BOOLEAN-PARAM-DEF
BSW Description		
Defines whether a NVRAM block shall be processed during NvM_WriteAll or not. This configuration parameter has only influence on those NVRAM blocks which are configured to have a permanent RAM block or which are configured to use explicit synchronization mechanism. true: NVRAM block shall be processed by NvM_WriteAll false: NVRAM block shall not be processed by NvM_WriteAll		
Template Description		
Defines whether or not the associated RAM Block shall be implicitly stored during shutdown by the basic software.		
M2 Parameter		
NvBlockNeeds.storeAtShutdown		
Mapping Rule		**Mapping Type**
1:1 Mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_NvM_00549]

BSW Module	BSW Context	
NvM	NvM/NvMBlockDescriptor	
BSW Parameter		**BSW Type**
NvMStaticBlockIDCheck		ECUC-BOOLEAN-PARAM-DEF
BSW Description		
Defines if the Static Block ID check is enabled. false: Static Block ID check is disabled. true: Static Block ID check is enabled.		
Template Description		
Defines if the Static Block Id check shall be enabled.		
M2 Parameter		
NvBlockNeeds.checkStaticBlockId		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_NvM_00532]

BSW Module	BSW Context	
NvM	NvM/NvMBlockDescriptor	
BSW Parameter		**BSW Type**
NvMWriteBlockOnce		ECUC-BOOLEAN-PARAM-DEF
BSW Description		
Defines write protection after first write. The NVRAM manager sets the write protection bit either after the NV block was written the first time or if the block was already written and it is detected as valid and consistent during a read for it. true: Defines write protection after first write is enabled. false: Defines write protection after first write is disabled.		
Template Description		

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Defines write protection after first write: true: This block is prevented from being changed/erased or being replaced with the default ROM data after first initialization by the software-component. false: No such restriction.	
M2 Parameter	
NvBlockNeeds.writeOnlyOnce	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_NvM_00072]

BSW Module	**BSW Context**	
NvM	NvM/NvMBlockDescriptor	
BSW Parameter		**BSW Type**
NvMWriteVerification		ECUC-BOOLEAN-PARAM-DEF
BSW Description		
Defines if Write Verification is enabled. false: Write verification is disabled. true: Write Verification is enabled.		
Template Description		
Defines if Write Verification shall be enabled for this NVRAM Block.		
M2 Parameter		
NvBlockNeeds.writeVerification		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_NvM_00534]

F.8 Rte

BSW Module	**BSW Context**	
Rte	Rte/RteBswModuleInstance/RteBswEventToIsrMapping	
BSW Parameter		**BSW Type**
RteBswIsrEventRef		ECUC-FOREIGN-REFERENCE-DEF
BSW Description		
Reference to the BswEvent.		
Template Description		
Base class of various kinds of events which are used to trigger a BswModuleEntity of this BSW module or cluster. The event is local to the BSW module or cluster. The short name of the meta-class instance is intended as an input to configure the required API of the BSW Scheduler.		
M2 Parameter		
BswEvent		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**

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valid	[ECUC_Rte_09159]

BSW Module	BSW Context	
Rte	Rte/RteBswModuleInstance/RteBswEventToTaskMapping	
BSW Parameter		**BSW Type**
RteBswEventRef		ECUC-FOREIGN-REFERENCE-DEF
BSW Description		
Reference to the BswEvent.		
Template Description		
Base class of various kinds of events which are used to trigger a BswModuleEntity of this BSW module or cluster. The event is local to the BSW module or cluster. The short name of the meta-class instance is intended as an input to configure the required API of the BSW Scheduler.		
M2 Parameter		
BswEvent		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Rte_09064]

BSW Module	BSW Context	
Rte	Rte/RteBswModuleInstance/RteBswExclusiveAreaImpl	
BSW Parameter		**BSW Type**
RteBswExclusiveAreaRef		ECUC-FOREIGN-REFERENCE-DEF
BSW Description		
Reference to the ExclusiveArea for which the implementation mechanism shall be specified.		
Template Description		
Prevents an executable entity running in the area from being preempted.		
M2 Parameter		
ExclusiveArea		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Rte_09074]

BSW Module	BSW Context	
Rte	Rte/RteBswModuleInstance/RteBswExternalTriggerConfig	
BSW Parameter		**BSW Type**
RteBswTriggerSourceRef		ECUC-FOREIGN-REFERENCE-DEF
BSW Description		
Reference to a Trigger instance in the role releasedTrigger of the related BSW Module instance. The referenced Trigger has to belong to the same BSW Module instance as the RteBswModuleInstance owning this parameter configures.		
Template Description		
A trigger which is provided (i.e. released) or required (i.e. used to activate something) in the given context.		
M2 Parameter		

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Trigger	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09100]

BSW Module	**BSW Context**	
Rte	Rte/RteBswModuleInstance	
BSW Parameter		**BSW Type**
RteBswImplementationRef		ECUC-FOREIGN-REFERENCE-DEF
BSW Description		
Reference to the BswImplementation for which the Rte /SchM is configured.		
Template Description		
Contains the implementation specific information in addition to the generic specification (BswModuleDescription and Bsw Behavior). It is possible to have several different BswImplementations referring to the same BswBehavior.		
M2 Parameter		
BswImplementation		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Rte_09066]

BSW Module	**BSW Context**	
Rte	Rte/RteBswModuleInstance/RteBswInternalTriggerConfig	
BSW Parameter		**BSW Type**
RteBswTriggerSourceRef		ECUC-FOREIGN-REFERENCE-DEF
BSW Description		
Reference to a BswInternalTriggeringPoint of the related BSW Module instance. The referenced BswInternalTriggeringPoint has to belong to the same BSW Module instance as the RteBswModuleInstance owning this parameter configures.		
Template Description		
Represents the activation point for one or more BswInternalTriggerOccurredEvents.		
M2 Parameter		
BswInternalTriggeringPoint		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Rte_09103]

BSW Module	**BSW Context**	
Rte	Rte/RteBswModuleInstance/RteBswModeMachineInstanceConfig	
BSW Parameter		**BSW Type**
RteBswModeManagerRef		ECUC-FOREIGN-REFERENCE-DEF
BSW Description		

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Reference to a ModeDeclarationGroupPrototype of the related BSW Module instance. The referenced ModeDeclarationGroupPrototype has to belong to the same BSW Module instance as the RteBswModule Instance owning this parameter configures.	
Template Description	
Represents the activation point for one or more BswInternalTriggerOccurredEvents.	
M2 Parameter	
BswInternalTriggeringPoint	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09149]

BSW Module	**BSW Context**
Rte	Rte/RteBswModuleInstance/RteBswRequiredClientServerConnection
BSW Parameter	**BSW Type**
RteBswProvidedClientServerEntryRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference the providedClientServerEntry for this connection.	
Template Description	
This meta-class represents a single API entry into the BSW module or cluster that has the ability to be called in client-server fashion via the BSW Scheduler. In this regard it is more special than BswModuleEntry and can be seen as a wrapper around the BswModuleEntry to which it refers (property encapsulatedEntry).	
M2 Parameter	
BswModuleClientServerEntry	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09119]

BSW Module	**BSW Context**
Rte	Rte/RteBswModuleInstance/RteBswRequiredClientServerConnection
BSW Parameter	**BSW Type**
RteBswRequiredClientServerEntryRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference the requiredClientServerEntry for this connection.	
Template Description	
This meta-class represents a single API entry into the BSW module or cluster that has the ability to be called in client-server fashion via the BSW Scheduler. In this regard it is more special than BswModuleEntry and can be seen as a wrapper around the BswModuleEntry to which it refers (property encapsulatedEntry).	
M2 Parameter	
BswModuleClientServerEntry	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09118]

BSW Module	BSW Context	
Rte	Rte/RteBswModuleInstance/RteBswRequiredModeGroupConnection	
BSW Parameter	**BSW Type**	
RteBswProvidedModeGroupRef	ECUC-FOREIGN-REFERENCE-DEF	
BSW Description		
References the providedModeGroupPrototype to which this requiredModeGroup shall be connected.		
Template Description		
The ModeDeclarationGroupPrototype specifies a set of Modes (ModeDeclarationGroup) which is provided or required in the given context.		
M2 Parameter		
ModeDeclarationGroupPrototype		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Rte_09079]

BSW Module	BSW Context	
Rte	Rte/RteBswModuleInstance/RteBswRequiredModeGroupConnection	
BSW Parameter	**BSW Type**	
RteBswRequiredModeGroupRef	ECUC-FOREIGN-REFERENCE-DEF	
BSW Description		
References requiredModeGroupPrototype which shall be connected to the providedModeGroupPrototype.		
Template Description		
The ModeDeclarationGroupPrototype specifies a set of Modes (ModeDeclarationGroup) which is provided or required in the given context.		
M2 Parameter		
ModeDeclarationGroupPrototype		
Mapping Rule		**Mapping Type**
1:1 mapping		full
Mapping Status		**ECUC Parameter ID**
valid		[ECUC_Rte_09082]

BSW Module	BSW Context	
Rte	Rte/RteBswModuleInstance/RteBswRequiredModeGroupConnection	
BSW Parameter	**BSW Type**	
RteModeDeclarationMappingSetRef	ECUC-FOREIGN-REFERENCE-DEF	
BSW Description		
This defines the effective ModeDeclarationMappingSet in the case that the provided ModeDeclarationGroupPrototype and the required ModeDeclarationGroupPrototype are not compatible.		
Template Description		
This meta-class implements a container for ModeDeclarationMappings		
M2 Parameter		
ModeDeclarationMappingSet		
Mapping Rule		**Mapping Type**
1:1 mapping		full

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Mapping Status	ECUC Parameter ID
valid	[ECUC_Rte_09125]

BSW Module	BSW Context
Rte	Rte/RteBswModuleInstance/RteBswRequiredSenderReceiverConnection
BSW Parameter	**BSW Type**
RteBswProvidedVariableDataPrototypeRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference the providedData for this connection.	
Template Description	
A `VariableDataPrototype` represents a formalized generic piece of information that is typically mutable by the application software layer. `VariableDataPrototype` is used in various contexts and the specific context gives the otherwise generic `VariableDataPrototype` a dedicated semantics.	
M2 Parameter	
`VariableDataPrototype`	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09122]

BSW Module	BSW Context
Rte	Rte/RteBswModuleInstance/RteBswRequiredSenderReceiverConnection
BSW Parameter	**BSW Type**
RteBswRequiredVariableDataPrototypeRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference the requiredData for this connection.	
Template Description	
A `VariableDataPrototype` represents a formalized generic piece of information that is typically mutable by the application software layer. `VariableDataPrototype` is used in various contexts and the specific context gives the otherwise generic `VariableDataPrototype` a dedicated semantics.	
M2 Parameter	
`VariableDataPrototype`	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09121]

BSW Module	BSW Context
Rte	Rte/RteBswModuleInstance/RteBswRequiredTriggerConnection
BSW Parameter	**BSW Type**
RteBswReleasedTriggerRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
References the releasedTrigger to which this requiredTrigger shall be connected.	
Template Description	
A trigger which is provided (i.e. released) or required (i.e. used to activate something) in the given context.	

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M2 Parameter	
Trigger	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09076]

BSW Module	BSW Context
Rte	Rte/RteBswModuleInstance/RteBswRequiredTriggerConnection
BSW Parameter	**BSW Type**
RteBswRequiredTriggerRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
References one requiredTrigger which shall be connected to the releasedTrigger.	
Template Description	
A trigger which is provided (i.e. released) or required (i.e. used to activate something) in the given context.	
M2 Parameter	
Trigger	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09078]

BSW Module	BSW Context
Rte	Rte/RteOsInteraction/RteModeToScheduleTableMapping/RteModeSchtblMapBsw
BSW Parameter	**BSW Type**
RteModeSchtblMapBswProvidedModeGroupRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference to an instance of a ModeDeclarationGroupPrototype of a Bsw-Module.	
Template Description	
The ModeDeclarationGroupPrototype specifies a set of Modes (ModeDeclarationGroup) which is provided or required in the given context.	
M2 Parameter	
ModeDeclarationGroupPrototype	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09053]

BSW Module	BSW Context
Rte	Rte/RteOsInteraction/RteModeToScheduleTableMapping
BSW Parameter	**BSW Type**
RteModeSchtblMapModeDeclarationRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference to the ModeDeclarations.	

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Template Description	
Declaration of one Mode. The name and semantics of a specific mode is not defined in the meta-model.	
M2 Parameter	
ModeDeclaration	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09054]

BSW Module	BSW Context
Rte	Rte/RteOsInteraction/RteModeToScheduleTableMapping/RteModeSchtblMapSwc
BSW Parameter	**BSW Type**
RteModeSchtblMapSwcPortRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference to the PPortPrototype of a SwComponentPrototype.	
Template Description	
Component port providing a certain port interface.	
M2 Parameter	
PPortPrototype	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Rte_09057]

F.9 StbM

BSW Module	BSW Context
StbM	StbM
BSW Parameter	**BSW Type**
StbMSynchronizedTimeBase	ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description	
Synchronized time.base collects the information about a specific time-base provider within the system.	
Template Description	
This represents the ability to define a global time domain.	
M2 Parameter	
GlobalTimeDomain	
Mapping Rule	**Mapping Type**
For each GlobalTimeDomain where - the configured Ecu is connected to as slave or - the configured Ecu is connected to as master if the Ecu is not in the role of a GlobalTimeGateway for this GlobalTimeDomain an instance of StbMSynchronizedTimeBase shall be created.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_StbM_00003]

F.10 WdgM

BSW Module	BSW Context
WdgM	WdgM/WdgMConfigSet/WdgMMode/WdgMLocalStatusParams
BSW Parameter	**BSW Type**
WdgMFailedAliveSupervisionRefCycleTol	ECUC-INTEGER-PARAM-DEF
BSW Description	
This parameter shall contain the acceptable amount of reference cycles with incorrect/failed alive supervisions for this Supervised Entity.	
Template Description	
Number of consecutive failed alive cycles for this SupervisedEntity which shall be tolerated until the supervision status of the SupervisedEntity is set to WDGM_ALIVE_EXPIRED (see SWS WdgM for more details). Note that this value has to be recalculated with respect to the WdgM's own cycle time for ECU configuration.	
M2 Parameter	
SupervisedEntityNeeds.toleratedFailedCycles	
Mapping Rule	**Mapping Type**
1:1	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_WdgM_00327]

BSW Module	BSW Context
WdgM	WdgM/WdgMGeneral
BSW Parameter	**BSW Type**
WdgMSupervisedEntity	ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description	
This container collects all common (mode-independent) parameters of a Supervised Entity to be supervised by the Watchdog Manager.	
Template Description	
Specifies the abstract needs on the configuration of the Watchdog Manager for one specific Supervised Entity.	
M2 Parameter	
SupervisedEntityNeeds	
Mapping Rule	**Mapping Type**
In case the owner of the SupervisedEntityNeeds is a BSW module then the WdgMSupervised Entity.shortName = {capitalizedMip}_{ServiceDependency.symbolicNameProps.symbol}.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_WdgM_00303]

BSW Module	BSW Context
WdgM	WdgM/WdgMGeneral/WdgMSupervisedEntity
BSW Parameter	**BSW Type**
WdgMCheckpoint	ECUC-PARAM-CONF-CONTAINER-DEF
BSW Description	
This container collects all Checkpoints of this Supervised Entity. Each Supervised Entity has at least one Checkpoint.	
Template Description	
Specifies the abstract needs on the configuration of the Watchdog Manager to support a Checkpoint for a Supervised Entity.	

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M2 Parameter	
SupervisedEntityCheckpointNeeds	
Mapping Rule	**Mapping Type**
In case the owner of the SupervisedEntityCheckpointNeeds is a BSW module then the Wdg MCheckpoint.shortName = {capitalizedMip}_{ServiceDependency.symbolicNameProps.symbol}.	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_WdgM_ 00305]

F.11 Xfrm

BSW Module	BSW Context
Xfrm	Xfrm/XfrmImplementationMapping
BSW Parameter	**BSW Type**
XfrmInvTransformerBswModuleEntryRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference to the BswModuleEntry which implements the referenced inverse transformer on the receiving/called side.	
Template Description	
This class represents a single API entry (C-function prototype) into the BSW module or cluster. The name of the C-function is equal to the short name of this element with one exception: In case of multiple instances of a module on the same CPU, special rules for "infixes" apply, see description of class BswImplementation.	
M2 Parameter	
BswModuleEntry	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Xfrm_00005]

BSW Module	BSW Context
Xfrm	Xfrm/XfrmImplementationMapping
BSW Parameter	**BSW Type**
XfrmTransformerBswModuleEntryRef	ECUC-FOREIGN-REFERENCE-DEF
BSW Description	
Reference to the BswModuleEntry which implements the referenced transformer on the sending/calling side.	
Template Description	
This class represents a single API entry (C-function prototype) into the BSW module or cluster. The name of the C-function is equal to the short name of this element with one exception: In case of multiple instances of a module on the same CPU, special rules for "infixes" apply, see description of class BswImplementation.	
M2 Parameter	
BswModuleEntry	
Mapping Rule	**Mapping Type**
1:1 mapping	full
Mapping Status	**ECUC Parameter ID**
valid	[ECUC_Xfrm_00018]

G Non-Splitable Elements in this Template

This chapter contains a table of all model elements which are **not splitable** in the scope of this document.

Note for R26-11:

The life cycle of the stereotype ≪atpSplitable≫ will end with the AUTOSAR Release R26-11. Any remaining references to the stereotype ≪atpSplitable≫ in this document will be removed in release R27-05.

Name of non splitable element
AnyInstanceRef.base
AnyInstanceRef.contextElement
AnyInstanceRef.target
ApplicationRuleBasedValueSpecification.swAxisCont
ApplicationValueSpecification.swAxisCont
ArrayValueSpecification.element
AtpClassifier.atpFeature
AtpInstanceRef.atpBase
AtpInstanceRef.atpContextElement
AtpInstanceRef.atpTarget
AtpPrototype.atpType
BswModeSwitchEvent.mode
BswModuleEntry.argument
BswServiceDependency.ident
CompositeRuleBasedValueSpecification.argument
CompositeRuleBasedValueSpecification.compoundPrimitiveArgument
ExclusiveAreaNestingOrder.exclusiveArea
FormulaExpression.atpReference
FormulaExpression.atpStringReference
ImplementationDataType.subElement
ImplementationDataTypeElement.subElement
ImplementationElementInParameterInstanceRef.context
ImplementationElementInParameterInstanceRef.target
McDataInstance.subElement
ModeInBswModuleDescriptionInstanceRef.base
ModeInBswModuleDescriptionInstanceRef.contextModeDeclarationGroup
ModeInBswModuleDescriptionInstanceRef.targetMode
RecordValueSpecification.field
RteEventInEcuInstanceRef.base
RteEventInEcuInstanceRef.contextAtomicComponent
RteEventInEcuInstanceRef.contextRootComposition
RteEventInEcuInstanceRef.targetRteEvent
RuleArguments.vtf
RuleBasedAxisCont.ruleBasedValues

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Name of non splitable element
RuleBasedAxisCont.swArraysize
RuleBasedAxisCont.unit
SdgClass.attribute
SwCalprmAxis.swCalprmAxisTypeProps
SwCalprmRefProxy.arParameter
SwCalprmRefProxy.mcDataInstance
SwDataDependencyArgs.swCalprmRef
SwDataDependencyArgs.swVariable
SwRecordLayoutGroup.swRecordLayoutGroupContentType
SwRecordLayoutGroupContent.swRecordLayout
SwRecordLayoutGroupContent.swRecordLayoutGroup
SwRecordLayoutGroupContent.swRecordLayoutV
SwRecordLayoutV.baseType
SwRecordLayoutV.desc
SwRecordLayoutV.swGenericAxisParamType
VariableAccessInEcuInstanceRef.base
VariableAccessInEcuInstanceRef.contextAtomicComponent
VariableAccessInEcuInstanceRef.contextRootComposition
VariableAccessInEcuInstanceRef.targetVariableAccess

Table G.1: Usage of non splitable elements

H Variation Points in the Scope of this Document

This chapter contains a table of all model elements stereotyped ≪atpVariation≫ in the scope of this document.

Each entry in the table consists of the identification of the model element itself and the applicable value of the tagged value vh.latestBindingTime.

For more information about the concept of variation points and how model elements that contain variation points shall be treated please refer to [1].

Variation Point	*Latest Binding Time*
AccessCount.value	preCompileTime
AccessCountSet.accessCount	preCompileTime
ARPackage.arPackage	blueprintDerivationTime
ARPackage.element	systemDesignTime
ArrayValueSpecification.element	preCompileTime
BswInternalBehavior.arTypedPerInstanceMemory	preCompileTime
BswInternalBehavior.bswPerInstanceMemoryPolicy	preCompileTime
BswInternalBehavior.clientPolicy	preCompileTime
BswInternalBehavior.distinguishedPartition	preCompileTime
BswInternalBehavior.entity	preCompileTime
BswInternalBehavior.event	preCompileTime
BswInternalBehavior.exclusiveAreaPolicy	preCompileTime
BswInternalBehavior.internalTriggeringPoint	preCompileTime
BswInternalBehavior.internalTriggeringPointPolicy	preCompileTime
BswInternalBehavior.modeReceiverPolicy	preCompileTime
BswInternalBehavior.modeSenderPolicy	preCompileTime
BswInternalBehavior.parameterPolicy	preCompileTime
BswInternalBehavior.perInstanceParameter	preCompileTime
BswInternalBehavior.receptionPolicy	preCompileTime
BswInternalBehavior.releasedTriggerPolicy	preCompileTime
BswInternalBehavior.schedulerNamePrefix	preCompileTime
BswInternalBehavior.sendPolicy	preCompileTime
BswInternalBehavior.serviceDependency	preCompileTime
BswInternalBehavior.triggerDirectImplementation	preCompileTime
BswModuleDependency.targetModuleRef	preCompileTime
BswModuleDescription.bswModuleDependency	preCompileTime
BswModuleDescription.bswModuleDocumentation	preCompileTime
BswModuleDescription.expectedEntry	preCompileTime
BswModuleDescription.implementedEntry	preCompileTime
BswModuleDescription.providedClientServerEntry	preCompileTime
BswModuleDescription.providedData	preCompileTime
BswModuleDescription.providedModeGroup	preCompileTime
BswModuleDescription.releasedTrigger	preCompileTime
BswModuleDescription.requiredClientServerEntry	preCompileTime

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Variation Point	*Latest Binding Time*
BswModuleDescription.requiredData	preCompileTime
BswModuleDescription.requiredModeGroup	preCompileTime
BswModuleDescription.requiredTrigger	preCompileTime
BswModuleEntity.accessedModeGroup	preCompileTime
BswModuleEntity.activationPoint	preCompileTime
BswModuleEntity.callPoint	preCompileTime
BswModuleEntity.dataReceivePoint	preCompileTime
BswModuleEntity.dataSendPoint	preCompileTime
BswModuleEntity.issuedTrigger	preCompileTime
BswModuleEntity.managedModeGroup	preCompileTime
BswModuleEntry.argument	blueprintDerivationTime
BswServiceDependency.assignedData	preCompileTime
BswServiceDependency.assignedEntryRole	preCompileTime
DiagEventDebounceCounterBased.counterDecrementStepSize	preCompileTime
DiagEventDebounceCounterBased.counterFailedThreshold	preCompileTime
DiagEventDebounceCounterBased.counterIncrementStepSize	preCompileTime
DiagEventDebounceCounterBased.counterJumpDown	preCompileTime
DiagEventDebounceCounterBased.counterJumpDownValue	preCompileTime
DiagEventDebounceCounterBased.counterJumpUp	preCompileTime
DiagEventDebounceCounterBased.counterJumpUpValue	preCompileTime
DiagEventDebounceCounterBased.counterPassedThreshold	preCompileTime
DiagEventDebounceTimeBased.timeBasedFdcThresholdStorageValue	preCompileTime
DiagEventDebounceTimeBased.timeFailedThreshold	preCompileTime
DiagEventDebounceTimeBased.timePassedThreshold	preCompileTime
ErrorTracerNeeds.tracedFailure	preCompileTime
ExecutableEntity.canEnter	preCompileTime
ExecutableEntity.runsInside	preCompileTime
Implementation.buildActionManifest	codeGenerationTime
Implementation.generatedArtifact	preCompileTime
Implementation.requiredArtifact	preCompileTime
Implementation.requiredGeneratorTool	preCompileTime
ImplementationDataType.subElement	preCompileTime
ImplementationDataTypeElement.arraySize	preCompileTime
ImplementationDataTypeElement.subElement	preCompileTime
InternalBehavior.constantMemory	preCompileTime
InternalBehavior.exclusiveArea	preCompileTime
InternalBehavior.exclusiveAreaNestingOrder	preCompileTime
InternalBehavior.staticMemory	preCompileTime
McDataInstance.subElement	preCompileTime
McFunctionDataRefSet	preCompileTime
McSupportData.emulationSupport	preCompileTime
McSupportData.mcParameterInstance	postBuild
McSupportData.mcVariableInstance	postBuild

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Variation Point	*Latest Binding Time*
ModeDeclarationGroup.modeDeclaration	blueprintDerivationTime
NumericalOrText.vf	preCompileTime
NumericalValueSpecification.value	preCompileTime
RecordValueSpecification.field	preCompileTime
ResourceConsumption.accessCountSet	preCompileTime
ResourceConsumption.executionTime	preCompileTime
ResourceConsumption.heapUsage	preCompileTime
ResourceConsumption.memorySection	preCompileTime
ResourceConsumption.sectionNamePrefix	preCompileTime
ResourceConsumption.stackUsage	preCompileTime
RptComponent.rptExecutableEntity	preCompileTime
RptExecutableEntity.rptExecutableEntityEvent	preCompileTime
RptExecutableEntity.rptRead	preCompileTime
RptExecutableEntity.rptWrite	preCompileTime
RptSupportData.rptComponent	preCompileTime
RptSupportData.rptServicePoint	preCompileTime
RuleArguments.vf	preCompileTime
RuleArguments.vtf	preCompileTime
RuleBasedValueSpecification.arguments	preCompileTime
ServiceDependency.assignedDataType	preCompileTime
SupervisedEntityNeeds.checkpoints	preCompileTime
SwcBswMapping.runnableMapping	preCompileTime
SwcBswMapping.synchronizedModeGroup	preCompileTime
SwcBswMapping.synchronizedTrigger	preCompileTime
SwDataDefProps	codeGenerationTime
SwDataDefProps.swValueBlockSize	preCompileTime
SwDataDefProps.swValueBlockSizeMult	preCompileTime
SwTextProps.swMaxTextSize	preCompileTime
ValueList.vf	preCompileTime

Table H.1: Usage of variation points