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2013-10-31	4.1.2	AUTOSAR Release Management	<ul style="list-style-type: none"> <li>• Introduction of Eth_GeneralTypes.h</li> <li>• Support of API deviation for asynchronous implementation</li> <li>• Changes in API of EthIf_ProvideTxBuffer and EthIf_SetPhysAddr</li> <li>• Editorial changes</li> <li>• Removed chapter(s) on change documentation</li> </ul>
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2011-12-22	4.0.3	AUTOSAR Administration	<ul style="list-style-type: none"> <li>• Description of payload data in EthIf_Cbk_RxIndication adapted</li> </ul>
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2010-02-02	3.1.4	AUTOSAR Administration	<ul style="list-style-type: none"> <li>• Initial Release</li> </ul>

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## Known Limitations

Currently, chapter [5](#) Dependencies to other modules does not describe the versions of dependent modules. Thus, a version check will extend the chapter.

# 1 Introduction and functional overview

This specification specifies the functionality, API and the configuration of the AUTOSAR Basic Software module Ethernet Interface.

In the AUTOSAR Layered Software Architecture [1], the Ethernet Interface belongs to the ECU Abstraction Layer, or more precisely, to the Communication Hardware Abstraction.

This indicates the main task of the Ethernet Interface:

Provide to upper layers a hardware independent interface to the Ethernet Communication System comprising multiple different wired or wireless Ethernet controllers and transceivers. This interface shall be uniform for all Ethernet controllers and transceivers, as well as Cellular V2X controllers. Thus, the upper layers (TCP/IP [2], EthSM [3], CDD, V2x modules) may access the underlying bus system in a uniform manner.

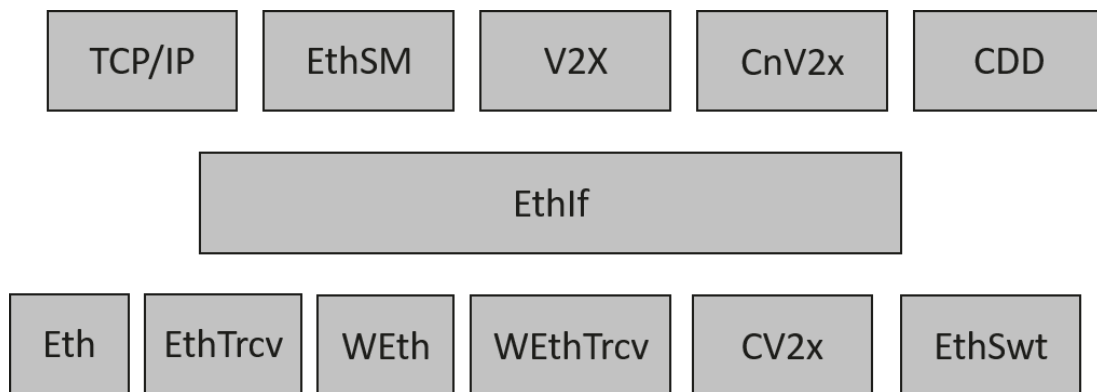
The Ethernet Interface does not directly access the Ethernet hardware (Ethernet Communication Controller and Ethernet Transceiver) but by means of one or more hardware-specific driver modules.

**[SWS\_EthIf\_00111]** [In order to access the Ethernet controller(s), the Ethernet Interface shall use one or multiple Ethernet Driver modules, which abstract the specific features and interfaces of the respective Ethernet controller(s).]()

**[SWS\_EthIf\_00123]** [In order to access the Ethernet transceiver(s), the Ethernet Interface shall use one or multiple Ethernet Transceiver Driver modules, which abstract the specific features and interfaces of the respective Ethernet transceiver(s).]()

**[SWS\_EthIf\_00228]** [In order to access the Ethernet switch(es), the Ethernet Interface shall use one or multiple Ethernet Switch Driver modules, which abstract the specific features and interfaces of the respective Ethernet switch(es).]()

**[SWS\_EthIf\_00112]** [Therefore, the Ethernet Interface executable code (however, not the configuration used during runtime) shall be completely independent of the Ethernet Communication Controller(s).]()



**Figure 1.1: Ethernet stack module overview**

Note: The Ethernet Interface is specified in a way that allows for object code delivery of the code module, following the "one-fits-all" principle, i.e. the entire configuration of the Ethernet Interface can be carried out without modifying any source code. Thus, the configuration of the Ethernet Interface can be carried out largely without detailed knowledge of the underlying hardware.

## 2 Acronyms and Abbreviations

The glossary below includes acronyms and abbreviations relevant to the Ethernet Interface module that are not included in the [4, AUTOSAR glossary].

Abbreviation / Acronym:	Description:
CBR	Channel Busy Ratio
CIT	Channel Idle Time
CV2x	Cellular Vehicle to X driver
Eth	Ethernet Controller Driver (AUTOSAR BSW module)
EthIf	Ethernet Interface (AUTOSAR BSW module)
EthSM	Ethernet State Manager (AUTOSAR BSW module)
EthTrcv	Ethernet Transceiver Driver (AUTOSAR BSW module)
IP	Internet Protocol
MCG	Module Configuration Generator
MII	Media Independent Interface (standardized Interface provided by Ethernet controllers to access Ethernet transceivers)
RSSI	Received Signal Strength Indicator
TCP	Transmission Control Protocol
TCP/IP Stack	Ethernet communication stack
VLAN	Virtual Local Area Network
WEth	Wireless Ethernet Driver
WEthTrcv	Wireless Ethernet Transceiver Driver
OA TC10	Open Alliance TC10 Specification [5]

## 3 Related documentation

### 3.1 Input documents & related standards and norms

- [1] Layered Software Architecture  
AUTOSAR\_EXP\_LayeredSoftwareArchitecture
- [2] Specification of TCP/IP Stack  
AUTOSAR\_SWS\_Tcplp
- [3] Specification of Ethernet State Manager  
AUTOSAR\_SWS\_EthernetStateManager
- [4] Glossary  
AUTOSAR\_TR\_Glossary
- [5] OPEN Sleep/Wake-up Specification for Automotive Ethernet  
<http://www.opensig.org/Automotive-Ethernet-Specifications/>
- [6] General Specification of Basic Software Modules  
AUTOSAR\_SWS\_BSWGeneral
- [7] Specification of Vehicle-2-X Geo Networking  
AUTOSAR\_SWS\_V2XGeoNetworking
- [8] Specification of Chinese Vehicle-2-X Network  
AUTOSAR\_SWS\_ChineseV2XNetwork
- [9] Specification of Chinese Vehicle-2-X Management  
AUTOSAR\_SWS\_ChineseV2XManagement
- [10] Specification of Ethernet Driver  
AUTOSAR\_SWS\_EthernetDriver
- [11] Specification of Ethernet Transceiver Driver  
AUTOSAR\_SWS\_EthernetTransceiverDriver
- [12] General Requirements on Basic Software Modules  
AUTOSAR\_SRS\_BSWGeneral
- [13] Requirements on Ethernet Support in AUTOSAR  
AUTOSAR\_SRS\_Ethernet
- [14] Specification of Default Error Tracer  
AUTOSAR\_SWS\_DefaultErrorTracer
- [15] Specification of Time Synchronization over Ethernet  
AUTOSAR\_SWS\_TimeSyncOverEthernet
- [16] Specification of Wireless Ethernet Driver  
AUTOSAR\_SWS\_WirelessEthernetDriver
- [17] Specification of Ethernet Switch Driver

AUTOSAR\_SWS\_EthernetSwitchDriver

[18] Specification of Wireless Ethernet Transceiver Driver  
AUTOSAR\_SWS\_WirelessEthernetTransceiverDriver

[19] Specification of Cellular Vehicle-2-X Driver  
AUTOSAR\_SWS\_CellularV2XDriver

[20] IEEE Standard for Local and metropolitan area networks-Media Access Control (MAC) Security  
<https://ieeexplore.ieee.org/document/8585421>

### **3.2 Related specification**

AUTOSAR provides a General Specification on Basic Software modules [6, SWS BSW General], which is also valid for Ethernet Interface.

Thus, the specification SWS BSW General shall be considered as additional and required specification for Ethernet Interface.

## **4 Constraints and assumptions**

### **4.1 Limitations**

The Ethernet Interface is conceptually able to access one or more Ethernet Driver and one or more Ethernet Transceiver Driver.

It is not possible to transmit data which exceeds the available buffer size of the used Ethernet controller. Longer data has to be transmitted using the Internet Protocol (IP) or Transmission Control Protocol (TCP).

### **4.2 Applicability to car domains**

The Ethernet BSW stack is intended to be used wherever high data rates are required but no hard real-time is required. Of course, it can also be used for less-demanding use cases, i.e. for low data rates.



## 5 Dependencies to other modules

This chapter lists the modules interacting with the Ethernet Interface module.

Modules that use Ethernet Interface module:

- Ethernet Communication Stack (TCP/IP Stack [2])
- Ethernet State Manager (EthSM) [3]
- V2xGn [7]
- CnV2xNet [8]
- CnV2xM [9]

Dependencies to other Modules:

- The Ethernet Interface module doesn't take care of configuring Ethernet Driver [10] but requires its preceding initialization and configuration.
- The Ethernet Interface module doesn't take care of configuring Ethernet Transceiver Driver [11] but requires its preceding initialization and configuration.

## 6 Requirements Tracing

The following tables reference the requirements specified in [12, SRS BSWGeneral] and [13, SRS Ethernet] and links to the fulfillment of these. Please note that if column “Satisfied by” is empty for a specific requirement this means that this requirement is not fulfilled by this document.

Requirement	Description	Satisfied by
[FO_RS_MACsec_ - 00001]	MACsec Protocol support	[SWS_EthIf_00560]
[FO_RS_MACsec_ - 00002]	MACsec Key Agreement Protocol support	[SWS_EthIf_00581] [SWS_EthIf_00582]
[FO_RS_MACsec_ - 00004]	Configure which Ethernet ports use MACsec	[SWS_EthIf_00561] [SWS_EthIf_00562]
[FO_RS_MACsec_ - 00007]	Configuration of unprotected traffic (for Software-based MACsec)	[SWS_EthIf_00563]
[FO_RS_MACsec_ - 00009]	MACsec Security Events	[SWS_EthIf_00564]
[FO_RS_MACsec_ - 00010]	Support of integrity and confidentiality	[SWS_EthIf_00565]
[FO_RS_MACsec_ - 00011]	MAC Security TAG	[SWS_EthIf_00566] [SWS_EthIf_00568] [SWS_EthIf_00569] [SWS_EthIf_00570] [SWS_EthIf_00571]
[FO_RS_MACsec_ - 00012]	MACsec EtherType	[SWS_EthIf_00567]
[FO_RS_MACsec_ - 00017]	Support of Extended Packet Number (XPN)	[SWS_EthIf_00572]
[FO_RS_MACsec_ - 00018]	Secure Channel Identifier (SCI)	[SWS_EthIf_00573]
[FO_RS_MACsec_ - 00019]	Secure Data	[SWS_EthIf_00574]
[FO_RS_MACsec_ - 00020]	Integrity Check Value (ICV)	[SWS_EthIf_00575]
[FO_RS_MACsec_ - 00021]	Protect function in software solution	[SWS_EthIf_00576]
[FO_RS_MACsec_ - 00022]	Validation function in software solution	[SWS_EthIf_00577]
[FO_RS_MACsec_ - 00023]	Support of MKA Packets	[SWS_EthIf_00583]
[FO_RS_MACsec_ - 00032]	List of minimal supported cipher suites	[SWS_EthIf_00578]
[FO_RS_MACsec_ - 00033]	Validation function for ICVs	[SWS_EthIf_00579]
[FO_RS_MACsec_ - 00034]	Generation function for ICVs	[SWS_EthIf_00580]
[RS_Ids_00810]	Basic SW security events	[SWS_EthIf_00502] [SWS_EthIf_00503]
[SRS_BSW_00101]	The Basic Software Module shall be able to initialize variables and hardware in a separate initialization function	[SWS_EthIf_00304] [SWS_EthIf_00306]
[SRS_BSW_00170]	The AUTOSAR SW Components shall provide information about their dependency from faults, signal qualities, driver demands	[SWS_EthIf_00999]





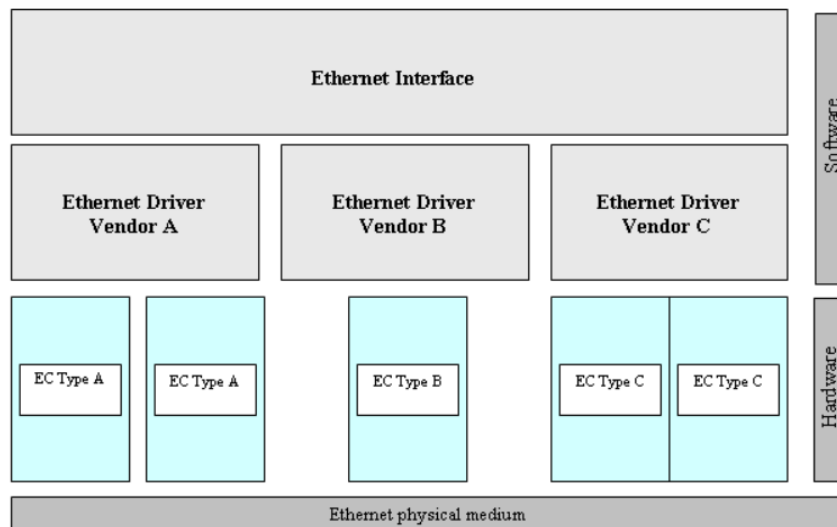
Requirement	Description	Satisfied by
[SRS_BSW_00369]	All AUTOSAR Basic Software Modules shall not return specific development error codes via the API	[SWS_EthIf_00304] [SWS_EthIf_00306]
[SRS_Eth_00106]	The Ethernet Transceiver Driver shall switch on/off wake up functionality at pre compile time.	[SWS_EthIf_00245] [SWS_EthIf_00500]
[SRS_Eth_00107]	The Ethernet Transceiver Driver shall support access to the wake up reason.	[SWS_EthIf_00486] [SWS_EthIf_00490] [SWS_EthIf_91004]
[SRS_Eth_00117]	The Ethernet Transceiver Driver shall provide access to standardized hardware features	[SWS_EthIf_00474] [SWS_EthIf_91014] [SWS_EthIf_91016] [SWS_EthIf_91018] [SWS_EthIf_91020] [SWS_EthIf_91021] [SWS_EthIf_91061]
[SRS_Eth_00125]	The Ethernet Switch Driver shall support switch frame management	[SWS_EthIf_91003] [SWS_EthIf_91007]
[SRS_Eth_00156]	The Ethernet Interface shall provide indication for a received sleep request.	[SWS_EthIf_00497] [SWS_EthIf_00499] [SWS_EthIf_91006]
[SRS_Eth_00157]	The Ethernet Interface shall trigger requested modes for Ethernet hardware with wake-up capability even if the requested mode has already been reached.	[SWS_EthIf_00264] [SWS_EthIf_00266] [SWS_EthIf_00478] [SWS_EthIf_00479] [SWS_EthIf_00480] [SWS_EthIf_00481] [SWS_EthIf_00482] [SWS_EthIf_00483] [SWS_EthIf_00504]

**Table 6.1: RequirementsTracing**

## 7 Functional specification

### 7.1 Ethernet BSW stack

As part of the AUTOSAR Layered Software Architecture [1], the Ethernet BSW modules also form a layered software stack. Figure 7.1 depicts the basic structure of this Ethernet BSW stack. The Ethernet Interface module accesses several Ethernet controllers using the Ethernet Driver layer, which can be made up of several Ethernet Drivers modules.

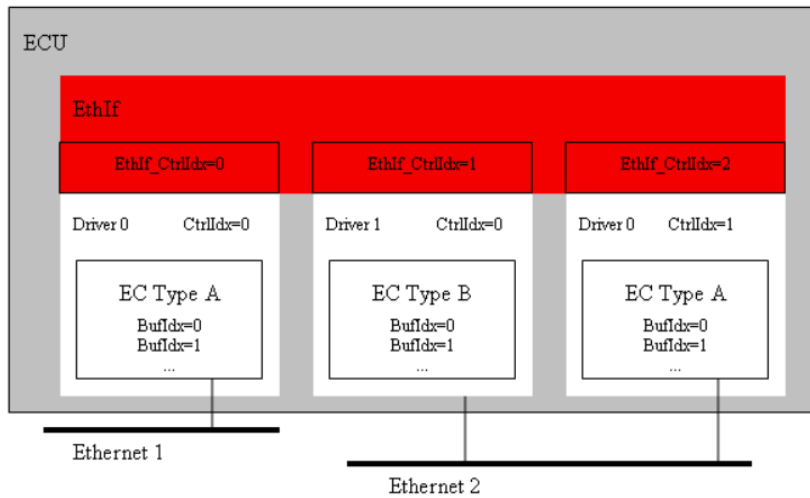


**Figure 7.1: Basic Structure of the Ethernet BSW Stack**

#### 7.1.1 Indexing scheme for Ethernet controller

In case CAN XL is used as physical medium, the configuration will contain an `EthIfEth-CanXLCtrlRef` instead of an `EthIfEthCtrlRef` and an `EthIfCanXLTrcvRef` instead of an `EthIfEthTrcvRef`. In this case, APIs denoted as `<EthDrv>_Xxx` will be called as `CanXL_Xxx`, otherwise as `Eth_Xxx`, and likewise APIs denoted as `<EthTrcv>_Yyy` will be called as `CanXLTrcv_Yyy`, otherwise `EthTrcv_Yyy`.

Users of the Ethernet Interface identify Ethernet controller resources using an indexing scheme as depicted in Figure 7.2.



**Figure 7.2: Ethernet Interface controller indexing scheme**

**[SWS\_EthIf\_00003]** [The Ethernet Interface is using an index (EthIfCtrlIdx) to abstract the access to VLANs from the underlying communication system comprised of Ethernet Controller and Ethernet Transceiver.

Therefore the Ethernet Interface shall implement a mapping from Ethernet Interface controllers (EthIfCtrlIdx) to respective hardware resource controllers (EthCtrlId + EthTrcvId).] ()

### 7.1.2 Indexing scheme for Ethernet switches

Since the EthIf is not concerned with the individual EthSwtPorts which belong to the individual EthSwtes there is no indexing scheme for EthSwtPorts required in the EthIf. Any BSW module which interacts with EthSwtPorts can directly refer to the ECU configuration of the EthSwtPort for the indexing.

**[SWS\_EthIf\_00224]** [The EthIf shall dispatch all accesses by the EthIfSwitchIdx index to the respective EthSwt driver module with the EthSwtIdx value] ()

### 7.1.3 Ethernet Interface main function

**[SWS\_EthIf\_00004]** [The Ethernet Interface shall implement main functions to be used for frame transmission confirmation and frame reception in polling mode with a calling period configurable at system configuration time.] ()

### 7.1.4 Requirements

This chapter lists requirements that shall be fulfilled by Ethernet Interface module implementations.

The Ethernet Interface module environment comprises all modules which are calling interfaces of the Ethernet Interface module.

**[SWS\_EthIf\_00005]** [The Ethernet Interface module shall support pre-compile time, link time and post-build time configuration.]()

**[SWS\_EthIf\_00006]** [The header file EthIf.h shall include a software and specification version number.]()

**[SWS\_EthIf\_00007]** [The Ethernet Interface module shall perform a consistency check between code files and header files based on pre-process-checking the version numbers of related code files and header files.]()

**[SWS\_EthIf\_00008]** [In case development error detection is enabled for the Ethernet Interface module: The Ethernet Interface module shall check API parameters for validity and report detected errors to the DET.]()

DET API functions are specified in [14, Specification of Default Error Tracer].

**[SWS\_EthIf\_00010]** [The Ethernet Interface module shall implement the API functions specified by the Ethernet Interface SWS as real C-code functions and shall not implement the API as macros for object code deliveries.]()

**[SWS\_EthIf\_00011]** [None of the Ethernet Interface module header files shall define global variables.]()

### 7.1.5 Configuration description

**[SWS\_EthIf\_00012]** [The Ethernet Interface module shall provide an XML file that contains the data, which is required for the SW identification (it shall contain the vendor identification, module ID and software version information), configuration and integration process. This file should describe vendor specific configuration parameters as well as it should contain recommended configuration parameter values.]()

**[SWS\_EthIf\_00117]** [The MCG shall read the ECU configuration description of the Ethernet Driver and the Ethernet Interface module(s). While cluster related configuration parameters are contained in the Ethernet Interface module configuration description, Ethernet Driver related configuration data is contained in the Ethernet Driver module configuration description. The Ethernet Interface module specific configuration tool shall read both ECU module descriptions to derive the configuration data for all Ethernet Drivers mapped to the Ethernet Interface module.]()

**[SWS\_EthIf\_00118]** [The MCG shall ensure the consistency of the generated configuration data.]()

**[SWS\_EthIf\_00013]** [The configuration of the Ethernet Interface module shall be configured at ECU configuration time. None of the communication parameters shall be configured at runtime.]()

**[SWS\_EthIf\_00014]** [The start address of post-build time configuration data shall be passed during module initialization.] ()

An assignment of those configuration classes to configuration parameters can be found in chapter 10.

A detailed description of all Ethernet Interface related configuration parameters can be found in chapter 10 of this document. Additionally, the configuration description of the Ethernet Driver (see chapter 10 of [10, Specification of Ethernet Driver]) shall be evaluated for Ethernet Interface module configuration.

### 7.1.6 VLAN support

**[SWS\_EthIf\_00128]** [The Ethernet Interface shall support Virtual Local Area Networks (VLAN).] ()

**[SWS\_EthIf\_00129]** [The Ethernet Interface shall encapsulate Virtual Local Area Networks (VLAN) into virtual controllers (Ethernet Interface controller) representing a dedicated VLAN.

All BSW modules above the Ethernet Interface shall interact based on those virtual controllers.

The Ethernet Driver and Transceiver deal only with real controllers and are not aware of the existence of virtual controllers.

Caveat: the virtual controller represents the untagged VLAN if no VLAN ID is set.] ()

**[SWS\_EthIf\_00130]** [The Ethernet Interface shall use the buffers provided by the Ethernet Driver for VLAN support. If Can XL is used the Ethernet Interface shall use the buffers provided by the Can XL Driver.] ()

### 7.1.7 Wake up support

The Ethernet Interface supports wake up depending on the parameter EthIfWakeUp-Support.

Note: Enabling wake-up support in EthIf makes only sense if the underlying EthTrcv supports also wake up.

### 7.1.8 Ethernet Switch Management support

Ethernet switch management enables the possibility to control an Ethernet frame regarding an Ethernet switch port specific ingress and egress handling as well as providing a Ethernet switch port specific timestamp. This functionality is essential for other

BSW modules, in particular for EthTSyn, which requires Port specific information associated to a time synchronization [15] or path-delay measurement frame.

For an introduction of the basic HW architecture and interaction, please refer to [10, Specification of Ethernet Driver].

For more details regarding functional sequences, please refer to [16, Specification of Wireless Ethernet Driver].

Note: Ethernet switch management API's supporting the <Upper Layer> to gather / modify Ethernet switch port specific communication attributes.

### 7.1.9 Handling of maintained Ethernet hardware

The Ethernet Interface handle the maintained Ethernet hardware due to its configuration:

- EthIfPhysController (representing physical Ethernet controller)
- EthIfController (representing virtual Ethernet controller to support VLANs)
- EthIfTransceiver (representing PHYs)
- EthIfSwitch (representation of an Ethernet switch)
- EthIfSwitchPortGroups (representing groups of EthSwtPorts)

At least one EthIfPhysController should be present in the configuration to interact with the Ethernet driver. EthIfController represent the connection between the physical Ethernet controller and used Ethernet hardware to communicate on and Ethernet network. This could be either an EthIfTransceiver or an EthIfSwitch or an EthIfSwitchPortGroup. If an upper layer wants to control the communication on a particular Ethernet network, it calls the corresponding EthIfController via [EthIf\\_SetControllerMode](#). The Ethernet Interface handle a communication request, such that it takes care to forward the request to the corresponding Ethernet hardware:

- EthIfTransceiver
- EthIfSwitch
- EthIfSwitchPortGroup with reference of type "control"

For EthIfController with reference of type "link-information" to an EthIfSwitchPortGroup, the Ethernet Interface supervise the link state of all EthSwtPorts within a EthIfSwitchPortGroup and signal the accumulated link state to the corresponding upper layer (EthSM [3]). Those EthIfSwitchPortGroups are controlled via a call of [EthIf\\_SwitchPortGroupRequestMode](#). This is used if EthIfSwitchPortGroups are controlled according to partial network requests. Partial network requests are forwarded to BswM and a particular rule in the BswM lead to an action to control the corresponding EthIfSwitchPortGroup. Thus the upper layer of the Ethernet Interface to control the communication is EthSM and the BswM, if EthIfSwitchPortGroup switching



is used. Independent if an EthIfController or an EthIfSwitchPortGroup are addressed for a communication request, the upper layer request the Ethernet Connection to be ACTIVE (ETH\_MODE\_ACTIVE or ETH\_MODE\_WITH\_WAKEUP\_REQUEST) or DOWN (ETH\_MODE\_DOWN). The Ethernet Interface requests the corresponding lower layer to switch on the corresponding Ethernet hardware for an ACTIVE-request or switch off the corresponding Ethernet Hardware for a DOWN-request.

### 7.1.9.1 EthIfSwitchPortGroup

The Ethernet Interface supports the grouping of Ethernet switch ports (EthIfSwitchPortGroup). The request (either ACTIVE or DOWN) will be handled and rated by the Ethernet Interface. The Ethernet Interface has to decide either to put the EthIfSwitchPortGroup to DOWN or ACTIVE state. ACTIVE-request for EthIfSwitchPortGroup will always overrule DOWN-request for EthIfSwitchPortGroups. If a DOWN-request for an EthIfSwitchPortGroup is ready for execution, the EthIf will check the EthSwtPorts which are referenced by the EthIfSwitchPortGroup and decide if the EthSwtPort can be set to DOWN state. If this is valid, the EthSwtPort is set to DOWN state after the configured switch off delay timer has expired.

Note: Further requirements for switching of EthIfSwitchPortGroups are available in chapter 7.1.9.2 and 8.3.21.

#### 7.1.9.1.1 Link state accumulation of EthIfSwitchPortGroup

The Ethernet Interface need to know the actual link state of the EthIfSwitchPortGroups. The link state for an EthIfSwitchPortGroup is computed over all link states of the EthSwtPorts which are referenced by the EthIfSwitchPortGroup. The execution of the computation is called "link state accumulation" and the result is called "accumulated link state". The accumulated link state of the EthIfSwitchPortGroup is the actual state of the EthIfSwitchPortGroup. The actual state of the EthIfSwitchPortGroup. The actual state of EthIfSwitchPortGroups referenced by an EthIfController is reported to the EthSM by calling EthSM\_TrvcLinkStateChg. The actual state of EthIfSwitchPortGroups which are not referenced by any EthIfController is reported to the BswM by calling BswM\_EthIf\_PortGroupLinkStateChg.

**[SWS\_EthIf\_00259]** [The link state for an EthIfSwitchPortGroup is computed over all link states of the EthSwtPorts which are referenced by the EthIfSwitchPortGroup. Its status is ETHTRCV\_LINK\_STATE\_DOWN (link down) if one of the following conditions is met:

- Referenced EthSwtPort with the role "host port" or the role "up link port" has link down state
- All referenced EthSwtPort without a role have link down state

Otherwise its accumulated link state is ETHTRCV\_LINK\_STATE\_ACTIVE (link up).] ()

**[SWS\_EthIf\_00260]** [If the EthIfCtrl references a EthIfSwitch but no port group is configured, the EthIf shall indicate the link state of the host port to the EthSM by calling `EthSM_TrcvLinkStateChg` for the EthIfController when the link state changes.]()

**[SWS\_EthIf\_00261]** [In case a EthIfSwitchPortGroup is not connected to any EthIfController, the EthIf shall indicate the accumulated link state of the EthIfSwitchPortGroup to the BswM by calling `BswM_EthIf_PortGroupLinkStateChg` for the EthIfSwitchPortGroup when the link state changes (refer to [SWS\_EthIf\_00259] for link state accumulation).]()

**[SWS\_EthIf\_00262]** [In case a EthIfSwitchPortGroup is connected to a EthIfController, the EthIf shall indicate the accumulated link state of the EthIfSwitchPortGroup to the EthSM by calling `EthSM_TrcvLinkStateChg` for the EthIfController when the link state changes (refer to [SWS\_EthIf\_00259] for link state accumulation).]()

### 7.1.9.2 Switching of EthIfController and the corresponding Ethernet hardware

Switching of an EthIfController is triggered via a call of `EthIf_SetControllerMode`. Switching of an EthIfController implicitly include the switching of the corresponding Ethernet hardware (PHY, Ethernet switch, Ethernet switch port). The Ethernet Interface interact with the lower layer via asynchronous callback notification (e.g. `EthIf_TrcvModeIndication`). The chapter describe the interaction of the APIs used to switch the EthIfController and the corresponding Ethernet hardware.

Note:

1. A call of the `EthIf_SetControllerMode` causes an asynchronous indication by calling `EthIf_CtrlModeIndication`, if the mode of the referenced EthIfPhysController has changed.
2. The requirements assume that Ethernet Controller (`EthIfPhysControllerIdx`) and the referenced Ethernet hardware (e.g. PHY, Ethernet Switch) are controlled independent from each other. For example, if `ETH_MODE_ACTIVE` or `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` has been requested and Ethernet Controller Driver of the affected Ethernet Controller (`EthIfPhysControllerIdx`) has NOT indicated `ETH_MODE_ACTIVE` yet, then those requests can be forwarded directly to the corresponding lower layers of the referenced Ethernet hardware. An implementation has to consider the following points:
  - `ETH_MODE_ACTIVE` and `ETH_MODE_DOWN` are activating and de-activating the communication capability of an Ethernet Controller, but not the control capability of connected Ethernet hardware (e.g. MDIO).
  - The implementation has to ensure, that the control capabilities via an Ethernet controller are always available, if needed by the driver modules (e.g. Ethernet switch driver)
3. EthIf has to ensure that a request with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` is not overwritten by another call of `EthIf_SetControllerMode` with

ETH\_MODE\_ACTIVE, if the request is deferred due to the EthIfPhysController has not already indicated ETH\_MODE\_ACTIVE.

**[SWS\_EthIf\_00035]** [The function `EthIf_SetControllerMode` shall forward the call to function `<EthDrv>_SetControllerMode` of the corresponding Ethernet Controller Driver (`EthIfPhysControllerIdx`) with `ETH_MODE_ACTIVE`, if mode `ETH_MODE_ACTIVE` or `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` has been requested and the corresponding Ethernet Controller Driver (`EthIfPhysControllerIdx`) has NOT already indicated `ETH_MODE_ACTIVE`.]()

**[SWS\_EthIf\_00266]** [If `EthIf_SetControllerMode` has been called for an EthIfController with `ETH_MODE_ACTIVE` and this EthIfController has a reference to an EthIfTransceiver, then EthIf shall forward the call to the following functions in the given order, if the current mode of the EthIfTransceiver is `ETH_MODE_DOWN`:

1. `<EthTrcv>_SetTransceiverMode` with `ETH_MODE_ACTIVE`
2. `<EthTrcv>_TransceiverLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`

]([SRS\\_Eth\\_00157](#))

**[SWS\_EthIf\_00478]** [If `EthIf_SetControllerMode` has been called for an EthIfController with `ETH_MODE_ACTIVE` and this EthIfController has a reference to an EthIfSwitch, then EthIf shall forward the call to the following functions in the given order for all EthSwtPorts of the referenced switch if mode `ETH_MODE_ACTIVE` has been requested and the current EthSwtPort mode is `ETH_MODE_DOWN`:

1. `EthSwt_SetSwitchPortMode` with `ETH_MODE_ACTIVE`
2. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`

]([SRS\\_Eth\\_00157](#))

**[SWS\_EthIf\_00264]** [If `EthIf_SetControllerMode` has been called for an EthIfController with `ETH_MODE_ACTIVE` and this EthIfController has a reference to an EthIfSwitchPortGroup of type "control", then EthIf shall forward the call to the following functions in the given order for all EthSwtPorts of the respective EthIfSwitchPortGroup if the mode `ETH_MODE_ACTIVE` has been requested for the first EthIfSwitchPortGroup referencing the EthSwtPort and the current EthSwtPort mode is `ETH_MODE_DOWN`:

1. `EthSwt_SetSwitchPortMode` with `ETH_MODE_ACTIVE`
2. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`

]([SRS\\_Eth\\_00157](#))

Note: EthIfController that reference EthIfSwitchPortGroups and the reference is of type "link-information" (see [ECUC\\_EthIf\\_00048](#)), then those EthIfSwitchPortGroups could be switched according to PNC states via a dedicated rules in the BswM. The BswM rule can be configured via the `BswMEthIfSwitchPortGroupRequestMode` action. The BswM

call the API `EthIf_SwitchPortGroupRequestMode` to switch the corresponding `EthIfSwitchPortGroup`.

**[SWS\_EthIf\_00272]** [If `EthIf_SwitchPortGroupRequestMode` has been called with `ETH_MODE_ACTIVE`, `EthIf` shall forward the call to the following functions in the given order for all `EthSwtPorts` of the respective `EthIfSwitchPortGroup`:

1. Call `EthSwt_SetSwitchPortMode` with `ETH_MODE_ACTIVE`, if the current mode is `ETH_MODE_DOWN`.
2. Call `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`, if the current link state is `ETHTRCV_LINK_STATE_DOWN`

)]()

**[SWS\_EthIf\_00479]** [Everytime `EthIf_SetControllerMode` has been called for an `EthIfController` with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` and this `EthIfController` has a reference to an `EthIfTransceiver`, then `EthIf` shall forward the call to the following functions in the given order, independent of the current mode:

1. `<EthTrcv>_SetTransceiverMode` with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`
2. `<EthTrcv>_TransceiverLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`, only if the current state is `ETHTRCV_LINK_STATE_DOWN`

)]([SRS\\_Eth\\_00157](#))

**[SWS\_EthIf\_00480]** [Everytime `EthIf_SetControllerMode` has been called for an `EthIfController` with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` and this `EthIfController` has a reference to an `EthIfSwitch`, then `EthIf` shall forward the call to the following functions in the given order for all `EthSwtPorts` of the respective `EthIfSwitchPortGroup`, independent of the current mode:

1. `EthSwt_SetSwitchPortMode` with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`
2. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`, if the current mode is `ETHTRCV_LINK_STATE_DOWN`

)]([SRS\\_Eth\\_00157](#))

**[SWS\_EthIf\_00481]** [Everytime `EthIf_SetControllerMode` has been called for an `EthIfController` with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` and this `EthIfController` has a reference to an `EthIfSwitchPortGroup` of type "control", then `EthIf` shall forward the call to the following functions in the given order for all `EthSwtPorts` of the respective `EthIfSwitchPortGroup`, independent of the current mode:

1. `EthSwt_SetSwitchPortMode` with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`
2. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`, if the current mode is `ETHTRCV_LINK_STATE_DOWN`

](SRS\_Eth\_00157)

**[SWS\_EthIf\_00482]** [Everytime `EthIf_SwitchPortGroupRequestMode` has been called with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`, `EthIf` shall forward the call for all `EthSwtPorts` of the respective `EthIfSwitchPortGroup` to the following functions in the given order independent of the current `EthSwtPort` mode:

1. `EthSwt_SetSwitchPortMode` with `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`
2. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`, only if current link state is `ETHTRCV_LINK_STATE_DOWN`

](SRS\_Eth\_00157)

Rational for [\[SWS\\_EthIf\\_00479\]](#), [\[SWS\\_EthIf\\_00480\]](#), [\[SWS\\_EthIf\\_00481\]](#) and [\[SWS\\_EthIf\\_00482\]](#): A wake-up request has always to be forwarded to the lower layer independent of the current mode to ensure that a wake-up is triggered on the network. This could be used for e.g. communication channels where the Ethernet hardware is compliant to OA TC10 (see [\[5, OPEN Sleep/Wake-up Specification for Automotive Ethernet\]](#))

**[SWS\_EthIf\_00483]** [If `EthIf_SwitchPortGroupRequestMode` is called with `ETH_MODE_ACTIVE` or `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`, then a running timer to delay the switch off all ports of the respective `EthIfSwitchPortGroup` (`PortGroupIdx`) shall be canceled.](SRS\_Eth\_00157)

**[SWS\_EthIf\_00263]** [`EthIf` shall call the function `<EthDrv>_SetControllerMode` of the corresponding Ethernet Controller Driver (`EthIfPhysControllerIdx`) with `ETH_MODE_DOWN`, if `EthIf_SetControllerMode` has been called with mode `ETH_MODE_DOWN` for all Ethernet Interface Controller referencing the Ethernet Controller.]  
( )

Note:

- In case of VLAN support, `EthIf` has to store internally the state of each `EthIfController` in order to filter out the requests from upper layers and disable the callouts to upper layers when the `EthIfController` is disabled.

**[SWS\_EthIf\_00484]** [If `EthIf_SetControllerMode` is called for an `EthIfController` with `ETH_MODE_DOWN` and this `EthIfController` has a reference to an `EthIfTransceiver`, then `EthIf` shall forward the call to the following functions in the given order, if the current mode of the `EthIfTransceiver` is `ETH_MODE_ACTIVE`:

1. `<EthTrcv>_SetTransceiverMode` with `ETH_MODE_DOWN`
2. `<EthTrcv>_TransceiverLinkStateRequest` with `ETHTRCV_LINK_STATE_DOWN`

]()

**[SWS\_EthIf\_00485]** [If [EthIf\\_SetControllerMode](#) is called for an EthIfController with `ETH_MODE_DOWN` and this EthIfController has a reference to an EthIfSwitch, then EthIf shall forward the call to the following functions in the given order for all EthSwtPorts, where the current mode of the EthSwtPort is `ETH_MODE_ACTIVE`:

1. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_DOWN`
2. `EthSwt_SetSwitchPortMode` with `ETH_MODE_DOWN`

]()

**[SWS\_EthIf\_00265]** [If [EthIf\\_SetControllerMode](#) is called for an EthIfController with `ETH_MODE_DOWN` and this EthIfController has a reference to an EthIfSwitchPortGroup of type "control", then EthIf shall forward the call to the following functions in the given order for all EthSwtPorts of the respective EthIf\_SwitchPortGroup, but only for those EthSwtPorts where all referencing EthIfSwitchPortGroups has been requested with `ETH_MODE_DOWN` and the current mode of the EthSwtPort is `ETH_MODE_ACTIVE`:

1. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_DOWN`
2. `EthSwt_SetSwitchPortMode` with `ETH_MODE_DOWN`

]()

Rationale: In case the respective EthIfController has no reference to an EthIf\_SwitchPortGroup or the reference is of type "link information" the requested modes are not forwarded. This EthIf\_SwitchPortGroups will be requested by an upper layer (e.g. BswM) with API [EthIf\\_SwitchPortGroupRequestMode](#).

### 7.1.9.3 Additional Ethernet switch port handling

The following additional Ethernet switch port handling has been introduced to support a use case for a passive wake up of an ECU where all Ethernet switch ports of the corresponding Ethernet switches shall be switched on immediately. E.g. after a wakeup occurred. Afterwards it is checked if a PN request is received via NM frames within `EthIfPortStartupActiveTime`. If a PN request is received, then the corresponding EthIfSwitchPortGroups are requested with `ETH_MODE_ACTIVE` and corresponding Ethernet switch ports stay active. All Ethernet switch ports where the corresponding EthIfSwitchPortGroups are not requested (due to no according PN request received within `EthIfPortStartupActiveTime`) are switched off.

**[SWS\_EthIf\_00275]** [If [EthIf\\_StartAllPorts](#) has been called, then EthIf shall forward the call to the following functions in the given order to all EthSwtPorts of all configured EthIfSwitches:

1. Call `EthSwt_SetSwitchPortMode` with `ETH_MODE_ACTIVE`, if the current mode is `ETH_MODE_DOWN`.
2. Call `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_ACTIVE`, if the current link state is `ETHTRCV_LINK_STATE_DOWN`

and start a timer with `EthIfPortStartupActiveTime` for all these ports. ]()

**[SWS\_EthIf\_00276]** [After `EthIf_StartAllPorts` has been called, `EthIf` shall deactivate all those ports activated due to `EthIf_StartAllPorts` (see [\[SWS\\_EthIf\\_00275\]](#)) which are not requested with `ETH_MODE_ACTIVE` within `EthIfPortStartupActiveTime` by calling the following functions in the given order:

1. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_DOWN`
2. `EthSwt_SetSwitchPortMode` with `ETH_MODE_DOWN`

]()

Rational: Delaying with `EthIfPortStartTime` is needed to ensure that NM messages with PNC information are received and the requested PNCs are activated.

Note:

1. `EthIf_StartAllPorts` could be called in context of `BswM_EcuM_Current-Wakeup`. After a wakeup occurred on the wakeup line, all `EthIfSwitchPortgroups` shall be activated to enable communication stack to receive NM messages (PNC information). With this it is possible to start the `EthIfSwitchPortGroups` without starting a PNC.
2. Further requirements for switching of `EthSwtPorts`, if an `EthIfController` referencing an `EthIfSwitch` are available in chapter [7.1.9.2](#).

### 7.1.10 Communication control

The Ethernet Interface has to provide a kind of communication control to support the so-called "silent communication". Silent communication is used for mode management to support a communication mode where the transmission path for a particular `EthIfController` is disabled, while the reception path is still enabled (see `COMM_SILENT_COMMUNICATION`). Disabling of the transmission path is exclusively introduced in the Ethernet Interface and has no impact on the used Ethernet hardware.

**[SWS\_EthIf\_00504]** [If `EthIf_SetControllerMode` is called for an `EthIfController` with `ETH_MODE_ACTIVE_TX_OFFLINE` and the latest accepted controller mode for this `EthIfController` is `ETH_MODE_ACTIVE` or `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`, then `ETH_MODE_TX_OFFLINE` shall be stored as current controller mode. Otherwise the requested controller mode shall be rejected and function shall return with `E_NOT_OK`.] ([SRS\\_Eth\\_00157](#))

Note: The transmission related APIs (see [\[SWS\\_EthIf\\_00075\]](#) and [\[SWS\\_EthIf\\_00067\]](#)) will only forward transmission requests, if the stored communication mode is `ETH_MODE_ACTIVE` or `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST`.

### 7.1.11 Global Time support

For more details regarding time measurement with Switches, please refer to [17, Specification of Ethernet Switch Driver].

### 7.1.12 Wireless Ethernet Support

**[SWS\_EthIf\_00340]** [The Ethernet Interface shall support Wireless Ethernet specific functionality, depending on the parameter EthIfEnableWEthApi.] ()

The Wireless functions are divided in controller and transceiver specific functionality. Mainly, transmission and reception parameters are being exchanged with the EthIf upper module and the controller/transceiver.

The controller is being called only for buffer specific transmission and reception parameters by the APIs:

- [EthIf\\_GetBufWRxParams](#)
- [EthIf\\_GetBufWTxParams](#)
- [EthIf\\_SetBufWTxParams](#)

The Transceiver is being called for general configuration of the wireless radio and the wireless radio's channel by:

- [EthIf\\_SetRadioParams](#)
- [EthIf\\_SetChanRxParams](#)
- [EthIf\\_SetChanTxParams](#)
- [EthIf\\_GetChanRxParams](#)

The parameter values are requested or transmitted by unique parameter identifiers. They are defined within the controller and transceiver specification [16] [18].

### 7.1.13 Cellular V2X Support

**[SWS\_EthIf\_00520]{DRAFT}** [The Ethernet Interface shall support Cellular V2X specific functionality, depending on the parameter EthIfEnableCV2xApi.] ()

Transmission and reception parameters are being exchanged with the EthIf upper module and the controller. The controller is being called only for buffer specific transmission and reception parameters by the APIs:

- [EthIf\\_GetBufCV2xPC5RxParams](#)
- [EthIf\\_GetBufCV2xPC5TxParams](#)
- [EthIf\\_SetBufCV2xPC5TxParams](#)



The controller is being called for general configuration of the Cellular V2X radio and the Cellular V2X radio's channel by:

- [EthIf\\_GetChanCV2xPC5TxParams](#)

The parameter values are requested or transmitted by unique parameter identifiers. They are defined within the controller specification [19].

#### 7.1.14 MACsec support

**[SWS\_EthIf\_00560]{DRAFT}** [The Ethernet Interface shall support MACsec as a SW implementation as specified in [20].] ([FO\\_RS\\_MACsec\\_00001](#))

**[SWS\_EthIf\_00561]{DRAFT}** [The Ethernet Interface shall support configuring which Ethernet Interface Controllers are MACsec protected.] ([FO\\_RS\\_MACsec\\_00004](#))

**[SWS\_EthIf\_00562]{DRAFT}** [The Ethernet Interface shall support configuring per Ethernet Interface Controller the MACsec Entity to use (per SW or HW i.e., offloaded).] ([FO\\_RS\\_MACsec\\_00004](#))

**Note:** This is included per configuration with the parameter [EthIfMacSecSupport](#).

**[SWS\_EthIf\_00563]{DRAFT}** [The MACsec Entity per SW of the Ethernet Interface shall provide a mechanism to configure rules to bypass MACsec for incoming and outgoing traffic based on EtherType and/or VLAN-ID. All traffic not configured as bypassed traffic shall be processed by the MACsec entity or dropped. This configuration shall be supported at initial configuration time of the Ports.] ([FO\\_RS\\_MACsec\\_00007](#))

**[SWS\_EthIf\_00564]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support status counters for the following information, which may be attached to IDSM functionality:

- Dropped frames because of incorrect ICV per port.
- Unsuccessful MKA sequence per peer.
- Additionally, all the port statistics required by [20].

] ([FO\\_RS\\_MACsec\\_00009](#))

**[SWS\_EthIf\_00565]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support "Integrity only" as well as "Integrity with Confidentiality" for all supported ciphers.] ([FO\\_RS\\_MACsec\\_00010](#))

**[SWS\_EthIf\_00566]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support MAC Security TAG (SecTAG) as defined in [20]. The SecTAG shall convey:

- TAG Control Information (TCI)
- Association Number (AN)

- Short Length (SL)
- Packet Number (PN)
- Secure Channel Identifier (SCI) - Optional

]([FO\\_RS\\_MACsec\\_00011](#))

**[SWS\_EthIf\_00567]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support MACsec EtherType as defined in [20].]([FO\\_RS\\_MACsec\\_00012](#))

**[SWS\_EthIf\_00568]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support TAG Control Information (TCI) as defined in [20]. The TCI shall be encoded in the SecTAG.]([FO\\_RS\\_MACsec\\_00011](#))

**[SWS\_EthIf\_00569]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support Association Number (AN) as defined in [20]. The AN shall be encoded in the SecTAG.]([FO\\_RS\\_MACsec\\_00011](#))

**[SWS\_EthIf\_00570]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support Short Length (SL) as defined in [20]. The SL shall be encoded in the SecTAG.]([FO\\_RS\\_MACsec\\_00011](#))

**[SWS\_EthIf\_00571]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support Packet Number (PN) with 32 least significant bits, as defined in [20]. The PN shall be encoded in the SecTAG.]([FO\\_RS\\_MACsec\\_00011](#))

**[SWS\_EthIf\_00572]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support Extended Packet Number (XPN) as defined in [20]. The XPN extends the PN to 64 bits.]([FO\\_RS\\_MACsec\\_00017](#))

**[SWS\_EthIf\_00573]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support Secure Channel Identifier (SCI), as defined in [20]. The SCI may be encoded in the SecTAG if SCI is required to be sent.]([FO\\_RS\\_MACsec\\_00018](#))

**[SWS\_EthIf\_00574]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support Secure Data as defined in [20].]([FO\\_RS\\_MACsec\\_00019](#))

**[SWS\_EthIf\_00575]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support Integrity check value (ICV) as defined in [20]. The ICV length depends on the used cipher suite but is not less than 8 octets and not more than 16 octets. The transmitted ICV is always 16 octets.]([FO\\_RS\\_MACsec\\_00020](#))

**[SWS\_EthIf\_00576]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support a protect function as specified in [20].]([FO\\_RS\\_MACsec\\_00021](#))

**[SWS\_EthIf\_00577]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support a validation function as specified in [20].]([FO\\_RS\\_MACsec\\_00022](#))

**[SWS\_EthIf\_00578]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support the following ciphers suites:

- GCM-AES-128

- GCM-AES-256
- GCM-AES-XPB-128
- GCM-AES-XPB-256

]([FO\\_RS\\_MACsec\\_00032](#))

**[SWS\_EthIf\_00579]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support a validation function for MACsec ICV.]([FO\\_RS\\_MACsec\\_00033](#))

**[SWS\_EthIf\_00580]{DRAFT}** [The MACsec entity per SW of the Ethernet Interface shall support a generation function for MACsec ICV.]([FO\\_RS\\_MACsec\\_00034](#))

**[SWS\_EthIf\_00581]{DRAFT}** [The Ethernet Interface Module shall share the MACsec Operational status between Ethernet Interface Controllers sharing a physical or virtual controlled port. An Ethernet Interface controller shall trigger the MKA Module to start the MKA sequence in a port with MKA\_LinkStateChange after receiving the "Mode Indication" from the Switch or Transceiver with the corresponding function [EthIf\\_SwitchPortModeIndication](#) or [EthIf\\_TrcevModeIndication](#).]([FO\\_RS\\_MACsec\\_00002](#))

**[SWS\_EthIf\_00582]{DRAFT}** [Once the physical or virtual port can generate and validate MACsec traffic (signaled by [EthIf\\_MacSecOperational](#)), all Controllers using the virtual or physical port shall immediately communicate the MacSecOperational status to the upper layers with [EthSM\\_TrcevLinkStateChg](#).]([FO\\_RS\\_MACsec\\_00002](#))

**[SWS\_EthIf\_00583]{DRAFT}** [The Ethernet Interface module shall support the MKA related EtherTypes as defined in [20].]([FO\\_RS\\_MACsec\\_00023](#))

**[SWS\_EthIf\_00584]{DRAFT}** [The Ethernet Interface module shall allow forwarding the received Ethernet frames of a specific EtherType to multiple frame owners if configured.](/)

## 7.2 Security Events

**[SWS\_EthIf\_00502]{DRAFT}** [If security event reporting has been enabled for the EthIf module ( [EthIfEnableSecurityEventReporting](#) = true) the respective security events shall be reported to the IdsM via the interfaces defined in AUTOSAR\_SWS\_BSWGeneral [6].]([RS\\_Ids\\_00810](#))

The following table lists the security events which are standardized for the EthIf together with their trigger conditions:

**[SWS\_EthIf\_00503] Security events for EthIf [**

<i>Name</i>	<i>Description</i>	<i>ID</i>
ETHIF_SEV_DROP_UNKNOWN_ETHERTYPE	An ethernet datagram was dropped due the Ethertype in not known.	15
ETHIF_SEV_DROP_VLAN_DOUBLE_TAG	An ethernet datagram was dropped due to double VLAN tag.	16
ETHIF_SEV_DROP_INV_VLAN	An ethernet datagram was dropped due to an invalid CtrlIdx/VLAN.	17
ETHIF_SEV_DROP_ETH_MAC_COLLISION	Ethernet datagram was dropped because local MAC was same as source MAC in an incoming frame.	18

]([RS\\_Ids\\_00810](#))

Context data is not provided by the EthIf for the security events.

## 7.3 Error Classification

Section "Error Handling" of the document [6] "General Specification of Basic Software Modules" describes the error handling of the Basic Software in detail. Above all, it constitutes a classification scheme consisting of five error types which may occur in BSW modules.

Based on this foundation, the following section specifies particular errors arranged in the respective subsections below.

### 7.3.1 Development Errors

**[SWS\_EthIf\_00017] [**

<i>Type of error</i>	<i>Related error code</i>	<i>Error value</i>
API service called with invalid controller index	ETHIF_E_INV_CTRL_IDX	0x01
API service called with invalid transceiver index	ETHIF_E_INV_TRCV_IDX	0x02
API service called with invalid switch index	ETHIF_E_INV_SWT_IDX	0x03
API service called with invalid port group index	ETHIF_E_INV_PORT_GROUP_IDX	0x04
API service called when EthIf module was not initialized	ETHIF_E_UNINIT	0x05
API service called with invalid pointer in parameter list	ETHIF_E_PARAM_POINTER	0x06
API service called with invalid parameter	ETHIF_E_INV_PARAM	0x07
EthIf_Init called with an invalid configuration pointer	ETHIF_E_INIT_FAILED	0x08
Invalid port index	ETHIF_E_INV_PORT_IDX	0x09

](0)

### **7.3.2 Runtime Errors**

There are no runtime errors.

### **7.3.3 Transient Faults**

There are no transient faults.

### **7.3.4 Production Errors**

There are no production errors.

### **7.3.5 Extended Production Errors**

There are no extended production errors.

## 8 API specification

### 8.1 Imported types

This chapter lists all types included from the following module:

[SWS\_EthIf\_00023] [

<i>Module</i>	<i>Header File</i>	<i>Imported Type</i>
ComStack_Types	ComStack_Types.h	BufReq_ReturnType
CV2x	CV2x_GeneralTypes.h	CV2x_BufCV2xPC5RxParamIdType (draft)
	CV2x_GeneralTypes.h	CV2x_BufCV2xPC5TxParamIdType (draft)
	CV2x_GeneralTypes.h	CV2x_GetChanTxParamIdType (draft)
EcuM	EcuM.h	EcuM_WakeupSourceType
Eth	Eth.h	Eth_SpiStatusType (draft)
	Eth_GeneralTypes.h	Eth_BufIdxType
	Eth_GeneralTypes.h	Eth_CounterType
	Eth_GeneralTypes.h	Eth_DataType
	Eth_GeneralTypes.h	Eth_FilterActionType
	Eth_GeneralTypes.h	Eth_FrameType
	Eth_GeneralTypes.h	Eth_MacVlanType
	Eth_GeneralTypes.h	Eth_ModeType
	Eth_GeneralTypes.h	Eth_RxStatsType
	Eth_GeneralTypes.h	Eth_RxStatusType
	Eth_GeneralTypes.h	Eth_TimeStampQualType
	Eth_GeneralTypes.h	Eth_TimeStampType
	Eth_GeneralTypes.h	Eth_TxErrorCounterValuesType
	Eth_GeneralTypes.h	Eth_TxStatsType
EthSwt	Eth_GeneralTypes.h	EthSwt_MacLearningType
	Eth_GeneralTypes.h	EthSwt_MgmtInfoType
	Eth_GeneralTypes.h	EthSwt_MgmtObjectType
	Eth_GeneralTypes.h	EthSwt_MgmtObjectValidType
	Eth_GeneralTypes.h	EthSwt_MgmtOwner
	Eth_GeneralTypes.h	EthSwt_PortMirrorCfgType
EthTrcv	Eth_GeneralTypes.h	EthTrcv_BaudRateType
	Eth_GeneralTypes.h	EthTrcv_CableDiagResultType
	Eth_GeneralTypes.h	EthTrcv_DuplexModeType
	Eth_GeneralTypes.h	EthTrcv_LinkStateType
	Eth_GeneralTypes.h	EthTrcv_MacMethodType (draft)
	Eth_GeneralTypes.h	EthTrcv_PhyLoopbackModeType
	Eth_GeneralTypes.h	EthTrcv_PhyTestModeType
	Eth_GeneralTypes.h	EthTrcv_PhyTxModeType
Eth_GeneralTypes.h	EthTrcv_WakeupReasonType	





<b>Module</b>	<b>Header File</b>	<b>Imported Type</b>
IdsM	IdsM_Types.h	IdsM_SecurityEventIdType
Mka	Mka.h	Mka_ConfidentialityOffsetType (DRAFT)
	Mka.h	Mka_MacSecConfigType (DRAFT)
	Mka.h	Mka_SakKeyPtrType (DRAFT)
	Mka.h	Mka_Stats_Rx_ScType (DRAFT)
	Mka.h	Mka_Stats_Rx_SecYType (DRAFT)
	Mka.h	Mka_Stats_SecYType (DRAFT)
	Mka.h	Mka_Stats_Tx_ScType (DRAFT)
	Mka.h	Mka_Stats_Tx_SecYType (DRAFT)
	Mka.h	Mka_ValidateFramesType (DRAFT)
Std	Std_Types.h	Std_ReturnType
	Std_Types.h	Std_VersionInfoType
WEth	WEth_GeneralTypes.h	WEth_BufWRxParamIdType
	WEth_GeneralTypes.h	WEth_BufWTxParamIdType
WEthTrcv	WEth_GeneralTypes.h	WEthTrcv_GetChanRxParamIdType
	WEth_GeneralTypes.h	WEthTrcv_SetChanRxParamIdType
	WEth_GeneralTypes.h	WEthTrcv_SetChanTxParamIdType
	WEth_GeneralTypes.h	WEthTrcv_SetRadioParamIdType

]()

## 8.2 Type definitions

### 8.2.1 Ethlf\_ConfigType

[SWS\_Ethlf\_00149] [

<b>Name</b>	Ethlf_ConfigType
<b>Kind</b>	Structure
<b>Description</b>	Implementation specific structure of the post build configuration
<b>Available via</b>	Ethlf.h

]()

## 8.2.2 EthIf\_SwitchPortGroupIdxType

[SWS\_EthIf\_91101] [

<b>Name</b>	EthIf_SwitchPortGroupIdxType		
<b>Kind</b>	Type		
<b>Derived from</b>	uint8		
<b>Range</b>	0..255	–	–
<b>Description</b>	Data Type that represents the Ethernet interface switch port group index. The index is zero based and unique for every configured switch port group.		
<b>Available via</b>	EthIf.h		

]()

## 8.2.3 EthIf\_MeasurementIdxType

[SWS\_EthIf\_91010] [

<b>Name</b>	EthIf_MeasurementIdxType		
<b>Kind</b>	Type		
<b>Derived from</b>	uint8		
<b>Range</b>	ETHIF_MEAS_DROP_CRTLIDX	0x01	Measurement index of dropped datagrams caused by invalid CtrlIdx/VLAN
	ETHIF_MEAS_RESERVED_1	0x02-0x7F	reserved by AUTOSAR
	ETHIF_MEAS_RESERVED_2	0x80-0xEF	Vendor specific range
	ETHIF_MEAS_RESERVED_3	0xF0-0xFE	reserved by AUTOSAR (future use)
	ETHIF_MEAS_ALL	0xFF	represents all measurement indexes
<b>Description</b>	Index to select specific measurement data		
<b>Available via</b>	EthIf.h		

]()

## 8.2.4 EthIf\_SignalQualityResultType

[SWS\_EthIf\_91057] [

<b>Name</b>	EthIf_SignalQualityResultType	
<b>Kind</b>	Structure	
<b>Elements</b>	HighestSignalQuality	
	<b>Type</b>	uint32
	<b>Comment</b>	the highest signal quality of a link since last clear





△

	LowestSignalQuality	
	<b>Type</b>	uint32
	<b>Comment</b>	the lowest link signal quality of a link since last clear
	ActualSignalQuality	
	<b>Type</b>	uint32
	<b>Comment</b>	the actual signal quality
<b>Description</b>	-	
<b>Available via</b>	Ethlf.h	

]()

## 8.3 Function definitions

This is a list of functions provided for upper layer modules.

Note: All functions in this chapter requires previous initialization ([EthIf\\_Init](#)), except the following ones: [EthIf\\_Init](#), [EthIf\\_GetVersionInfo](#)

### 8.3.1 Ethlf\_Init

[SWS\_Ethlf\_00024] [

<b>Service Name</b>	Ethlf_Init	
<b>Syntax</b>	<pre>void Ethlf_Init (     const Ethlf_ConfigType* CfgPtr )</pre>	
<b>Service ID [hex]</b>	0x01	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CfgPtr	Points to the implementation specific structure
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Initializes the Ethernet Interface	
<b>Available via</b>	Ethlf.h	

]()

[SWS\_Ethlf\_00025] [The function shall store the access to the configuration structure for subsequent API calls.]()

[SWS\_Ethlf\_00114] [The function shall change the state of the component from uninitialized to initialized.]()

[SWS\_Ethlf\_00116] [If development error detection is enabled: the function shall check the parameter [CfgPtr](#) for containing a valid configuration. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INIT\\_FAILED](#).]()

### 8.3.2 EthIf\_SetControllerMode

[SWS\_EthIf\_00034] [

<b>Service Name</b>	EthIf_SetControllerMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetControllerMode (     uint8 CtrlIdx,     Eth_ModeType CtrlMode )</pre>	
<b>Service ID [hex]</b>	0x03	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	CtrlMode	ETH_MODE_DOWN: disable the controller ETH_MODE_ACTIVE: enable the controller ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST: enable the controller and request a wake-up on the network. ETH_MODE_TX_OFFLINE: disable transmission handling in Eth If. Please note, the according Ethernet controller is not affected
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: controller mode could not be changed
<b>Description</b>	Enables / disables the indexed controller	
<b>Available via</b>	EthIf.h	

]()

Note: Further requirements regarding the call of [EthIf\\_SetControllerMode](#) are described in chapter [7.1.9.2](#) and [7.1.10](#).

[SWS\_EthIf\_00036] [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

[SWS\_EthIf\_00037] [If development error detection is enabled: the function shall check the parameter [CtrlIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_CTRL\\_IDX](#).]()

### 8.3.3 EthIf\_GetControllerMode

[SWS\_EthIf\_00039] [

<b>Service Name</b>	EthIf_GetControllerMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetControllerMode (     uint8 CtrlIdx,     Eth_ModeType* CtrlModePtr )</pre>	





<b>Service ID [hex]</b>	0x04	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	CtrlModePtr	ETH_MODE_DOWN: the controller is disabled ETH_MODE_ACTIVE: the controller is enabled
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: controller could not be initialized
<b>Description</b>	Obtains the state of the indexed controller	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00040]** [The function `EthIf_GetControllerMode` shall forward the call to function `<EthDrv>_GetControllerMode` of the corresponding Ethernet Controller Driver (`EthIfPhysControllerIdx`).]()

**[SWS\_EthIf\_00041]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00042]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00043]** [If development error detection is enabled: the function shall check the parameter `CtrlModePtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.4 EthIf\_CheckWakeup

**[SWS\_EthIf\_00244]** [

<b>Service Name</b>	EthIf_CheckWakeup	
<b>Syntax</b>	Std_ReturnType EthIf_CheckWakeup ( EcuM_WakeupSourceType WakeupSource )	
<b>Service ID [hex]</b>	0x30	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	WakeupSource	Source device which initiated the wake up event. The source device could either be a Ethernet switch or a Ethernet transceiver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	





<b>Return value</b>	Std_ReturnType	E_OK when the request to check for a wake-up of the affected Ethernet hardware (e.g. PHY) has been accepted. E_NOT_OK when the request to check for a wake-up of the affected Ethernet hardware is rejected.
<b>Description</b>	This API request the affected Ethernet hardware to check for a signaled wake-up. The used Ethernet hardware could be an Ethernet switch or Ethernet transceiver (PHY). This is used e.g. for Ethernet hardware which is compliant to the specification of Open Alliance TC10. This API is called by the integration code. The function could be called in context of the interrupt or on task level.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00245]** [For all affected Ethernet transceiver (either referenced by EthIfTransceiver or by EthIfSwitchPortGroups) the function `EthIf_CheckWakeup` shall forward the call to function `<EthTrcv>_CheckWakeup` of the respective Ethernet Transceiver Driver.] ([SRS\\_Eth\\_00106](#))

**[SWS\_EthIf\_00500]** [For all affected Ethernet switches (referenced by EthIfSwitch) the function `EthIf_CheckWakeup` shall forward the call to function `EthSwT_SwitchCheckWakeup` of the respective Ethernet Switch Driver.] ([SRS\\_Eth\\_00106](#))

**[SWS\_EthIf\_00246]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00247]** [If development error detection is enabled: the function shall check the parameter `WakeupSource` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

### 8.3.5 EthIf\_GetPhyWakeupReason

**[SWS\_EthIf\_91004]** [

<b>Service Name</b>	EthIf_GetPhyWakeupReason	
<b>Syntax</b>	Std_ReturnType EthIf_GetPhyWakeupReason ( uint8 TrcvIdx, EthTrcv_WakeupReasonType* WakeupReasonPtr )	
<b>Service ID [hex]</b>	0x69	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	WakeupReasonPtr	Pointer to structure of least recent wakeup event, which was detected by the Ethernet PHY





<b>Return value</b>	Std_ReturnType	E_OK: PHY wake up reason request has been accepted. E_NOT_OK: PHY wake up reason request has not been accepted.
<b>Description</b>	This function obtains the wake up reasons of the indexed Ethernet Transceiver (PHY) by calling EthTrcv_GetBusWuReason(...)	
<b>Available via</b>	EthIf.h	

](SRS\_Eth\_00107)

**[SWS\_EthIf\_00486]** [The function `EthIf_GetPhyWakeupReason` shall forward the call to function `EthTrcv_GetBusWuReason` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).](SRS\_Eth\_00107)

**[SWS\_EthIf\_00487]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00488]** [If development error detection is enabled: the function shall check the parameter `TrcvIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

**[SWS\_EthIf\_00489]** [If development error detection is enabled: the function shall check the parameter `WakeupReasonPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.6 EthIf\_GetSwitchPortWakeupReason

**[SWS\_EthIf\_91005]** [

<b>Service Name</b>	EthIf_GetSwitchPortWakeupReason	
<b>Syntax</b>	Std_ReturnType EthIf_GetSwitchPortWakeupReason ( uint8 SwitchIdx, uint8 SwitchPortIdx, EthTrcv_WakeupReasonType* WakeupReasonPtr )	
<b>Service ID [hex]</b>	0x67	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the Ethernet switch within the context of the Ethernet Interface
	SwitchPortIdx	Index of the Ethernet switch port index in the context of the Ethernet switch driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	WakeupReasonPtr	Pointer to structure of least recent wakeup event, which was detected by the Ethernet switch port





<b>Return value</b>	Std_ReturnType	E_OK: Ethernet switch port wake up reason request has been accepted. E_NOT_OK: Ethernet switch port wake up reason request has not been accepted.
<b>Description</b>	This function obtains the wake up reasons of the indexed Ethernet switch port by calling EthSwt_GetSwitchPortWakeUpReason().	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00490]** [The function `EthIf_GetSwitchPortWakeUpReason` shall forward the call to function `EthSwt_GetSwitchPortWakeUpReason` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).] ([SRS\\_Eth\\_00107](#))

**[SWS\_EthIf\_00491]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT` otherwise (if DET is disabled) return `E_NOT_OK`.]()

**[SWS\_EthIf\_00492]** [If development error detection is enabled: the function shall check the parameter `SwitchIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_SWT_IDX` otherwise (if DET is disabled) return `E_NOT_OK`.]()

**[SWS\_EthIf\_00493]** [If development error detection is enabled: the function shall check the parameter `SwitchPortIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PORT_IDX` otherwise (if DET is disabled) return `E_NOT_OK`.]()

**[SWS\_EthIf\_00494]** [If development error detection is enabled: the function shall check the parameter `WakeUpReasonPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.7 EthIf\_GetPhysAddr

**[SWS\_EthIf\_00061]** [

<b>Service Name</b>	EthIf_GetPhysAddr	
<b>Syntax</b>	<pre>void EthIf_GetPhysAddr (     uint8 CtrlIdx,     uint8* PhysAddrPtr )</pre>	
<b>Service ID [hex]</b>	0x08	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	





<b>Parameters (out)</b>	PhysAddrPtr	Physical source address (MAC address) in network byte order.
<b>Return value</b>	None	
<b>Description</b>	Obtains the physical source address used by the indexed controller	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00062]** [The function `EthIf_GetPhysAddr` shall forward the call to the respective Ethernet Controller Driver.]()

**[SWS\_EthIf\_00063]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00064]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00065]** [If development error detection is enabled: the function shall check the parameter `PhysAddrPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.8 EthIf\_SetPhysAddr

**[SWS\_EthIf\_00132]** [

<b>Service Name</b>	EthIf_SetPhysAddr	
<b>Syntax</b>	<pre>void EthIf_SetPhysAddr (     uint8 CtrlIdx,     const uint8* PhysAddrPtr )</pre>	
<b>Service ID [hex]</b>	0x0d	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant for the same CtrlIdx, reentrant for different	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Driver.
	PhysAddrPtr	Pointer to memory containing the physical source address (MAC address) in network byte order.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Sets the physical source address used by the indexed controller.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00134]** [The function `EthIf_SetPhysAddr` shall forward the call to the respective Ethernet Controller Driver.]()

**[SWS\_EthIf\_00135]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00136]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00137]** [If development error detection is enabled: the function shall check the parameter `PhysAddrPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.9 EthIf\_UpdatePhysAddrFilter

**[SWS\_EthIf\_00139]** [

<b>Service Name</b>	EthIf_UpdatePhysAddrFilter	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_UpdatePhysAddrFilter (     uint8 CtrlIdx,     const uint8* PhysAddrPtr,     Eth_FilterActionType Action )</pre>	
<b>Service ID [hex]</b>	0x0c	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant for the same CtrlIdx, reentrant for different	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Driver.
	PhysAddrPtr	Pointer to memory containing the physical destination address (MAC address) in network byte order. This is the multicast destination address of the layer 2 Ethernet packet.
	Action	Add or remove the address from the Ethernet controllers filter.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: filter was successfully changed E_NOT_OK: filter could not be changed
<b>Description</b>	Update the physical source address to/from the indexed controller filter. If the Ethernet Controller is not capable to do the filtering, the software has to do this.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00140]** [The function `EthIf_SetPhysAddrFilter` shall forward the call to the respective Ethernet Controller Driver.]()

**[SWS\_EthIf\_00141]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00142]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()



**[SWS\_EthIf\_00143]** [If development error detection is enabled: the function shall check the parameter `PhysAddrPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.10 EthIf\_GetPortMacAddr

**[SWS\_EthIf\_00190]** [

<b>Service Name</b>	EthIf_GetPortMacAddr	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetPortMacAddr (     const uint8* MacAddrPtr,     uint8* SwitchIdxPtr,     uint8* PortIdxPtr )</pre>	
<b>Service ID [hex]</b>	0x28	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	MacAddrPtr	MAC-address for which a switch port is searched over which the node with this MAC-address can be reached.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	SwitchIdxPtr	Pointer to the switch index
	PortIdxPtr	Pointer to the port index
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: an error occurred, e.g. multiple ports were found
<b>Description</b>	Obtains the port over which this MAC-address can be reached	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00191]** [The function `EthIf_GetPortMacAddr` shall return the switch and port index over which the given MAC-address is reachable. If multiple or no ports are possible, this API call will return `E_NOT_OK`. `EthSwt_GetPortMacAddr` will be called for all Ethernet Switch drivers.]()

**[SWS\_EthIf\_00192]** [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfGetPortMacAddrApi`.]()

**[SWS\_EthIf\_00193]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00194]** [If development error detection is enabled: the function shall check the parameter `MacAddrPtr`, `SwitchIdxPtr` and `PortIdxPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.11 EthIf\_GetArITable

[SWS\_EthIf\_00196] [

<b>Service Name</b>	EthIf_GetArITable	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetArITable (     uint8 switchIdx,     uint16* numberOfElements,     Eth_MacVlanType* arITableListPointer )</pre>	
<b>Service ID [hex]</b>	0x29	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	switchIdx	Index of the switch within the context of the Ethernet Switch Driver
<b>Parameters (inout)</b>	numberOfElements	In: Maximum number of elements which can be written into the arITable Out: Number of elements which are currently available in the EthSwitch module.
<b>Parameters (out)</b>	arITableListPointer	Returns a pointer to the memory where the ARL table of the switch consisting of a list of structs with MAC-address, VLAN-ID and port shall be stored.
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: requested switchIdx is not valid or inactive
<b>Description</b>	Obtains the address resolution table of a switch and copies the list into a user provided buffer. The function will copy all or numberOfElements into the output list. If input value of numberOfElements is 0 the function will not copy any data but only return the number of valid entries in the cache. arITableListPointer may be NULL_PTR in this case.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00197] [The function `EthIf_GetArITable` shall return a list of structs with MAC-address, VLAN-ID and port for the indexed switch.]()

[SWS\_EthIf\_00254] [The function `EthIf_GetArITable` shall forward the call to function `EthSwt_GetArITable` of the respective Ethernet Switch Driver.]()

[SWS\_EthIf\_00198] [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfGetArITable`.]()

[SWS\_EthIf\_00199] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00200] [If development error detection is enabled: the function shall check the parameter `arITableListPointer` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.12 EthIf\_GetCtrlIdxList

[SWS\_EthIf\_91053] [

<b>Service Name</b>	EthIf_GetCtrlIdxList	
<b>Syntax</b>	Std_ReturnType EthIf_GetCtrlIdxList ( uint8* NumberOfCtrlIdx, uint8* CtrlIdxListPtr )	
<b>Service ID [hex]</b>	0x44	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	None	
<b>Parameters (inout)</b>	NumberOfCtrlIdx	in: maximum number of controllers in CtrlIdxListPtr, 0 to return the number of controllers but without filling CtrlIdxListPtr. out: number of active controllers.
<b>Parameters (out)</b>	CtrlIdxListPtr	List of active controller indexes
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failure
<b>Description</b>	Returns the number and index of all active Ethernet controllers.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00298] [The optional `EthIf_GetCtrlIdxList` API shall return only the `NumberOfCtrlIdx` which are active.]()

[SWS\_EthIf\_00299] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00300] [If development error detection is enabled: the function shall check the OUT parameter `CtrlIdxListPtr` for being valid only if the the OUT parameter `NumberOfCtrlIdx` is greater 0x00. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.13 EthIf\_GetVlanId

[SWS\_EthIf\_91052] [

<b>Service Name</b>	EthIf_GetVlanId	
<b>Syntax</b>	Std_ReturnType EthIf_GetVlanId ( uint8 CtrlIdx, uint16* VlanIdPtr )	
<b>Service ID [hex]</b>	0x43	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	



△

<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	VlanIdPtr	Pointer to store the VLAN identifier (VID) of the Ethernet controller. 0 if the the Ethernet controller represents no virtual network (VLAN).
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failure
<b>Description</b>	Returns the VLAN identifier of the requested Ethernet controller.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00301]** [The optional `EthIf_GetVlanId` API shall return the `VlanId` of the requested `CtrlIdx`.]()

**[SWS\_EthIf\_00302]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00303]** [If development error detection is enabled: the function shall check the parameter `VlanIdPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.14 EthIf\_GetAndResetMeasurementData

**[SWS\_EthIf\_91011]** [

<b>Service Name</b>	EthIf_GetAndResetMeasurementData	
<b>Syntax</b>	Std_ReturnType EthIf_GetAndResetMeasurementData ( EthIf_MeasurementIdxType MeasurementIdx, boolean MeasurementResetNeeded, uint32* MeasurementDataPtr )	
<b>Service ID [hex]</b>	0x45	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	MeasurementIdx	Data index of measurement data
	MeasurementReset Needed	Flag to trigger a reset of the measurement data
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	MeasurementDataPtr	Reference to data buffer, where to copy measurement data
<b>Return value</b>	Std_ReturnType	E_OK: successful E_NOT_OK: failed
<b>Description</b>	Allows to read and reset detailed measurement data for diagnostic purposes. Get all <code>MeasurementIdx</code> 's at once is not supported. <code>ETHIF_MEAS_ALL</code> shall only be used to reset all <code>MeasurementIdx</code> 's at once. A <code>NULL_PTR</code> shall be provided for <code>MeasurementDataPtr</code> in this case.	
<b>Available via</b>	EthIf.h	

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[SWS\_EthIf\_00308] [EthIf\_GetAndResetMeasurementData shall return measurement data for selected measurement index.]()

[SWS\_EthIf\_00309] [For measurement index ETHIF\_MEAS\_DROP\_CRTLIDX the function shall return the number of all dropped datagrams, caused by invalid CrtlIdx/VLAN. If the VLAN is not enabled, all received VLAN tagged datagrams are invalid and shall be counted also.]()

[SWS\_EthIf\_00310] [The function shall return E\_NOT\_OK if the requested measurement index is not supported.]()

[SWS\_EthIf\_00312] [The function shall reset all existing measurement data to 0, if MeasurementResetNeeded is true and measurement index is set to ETHIF\_MEAS\_ALL.]()

[SWS\_EthIf\_00313] [All measurement data which counts data shall not overrun.]()

[SWS\_EthIf\_00314] [The function shall accept NULL\_PTR. In this case the measurement data shall not be copied.]()

[SWS\_EthIf\_00316] [The function shall be pre compile time configurable On/Off by the configuration parameter: EthIfGetAndResetMeasurementDataApi.]()

[SWS\_EthIf\_00317] [If the VLAN is not active the Ethernet Interface shall increment the corresponding measurement data and filter the message.]()

[SWS\_EthIf\_00319] [If development error detection is enabled: The function shall check that the service EthIf\_Init was previously called. If the check fails, the function shall raise the development error ETHIF\_E\_NOTINIT.]()

### 8.3.15 EthIf\_StoreConfiguration

[SWS\_EthIf\_00214] [

<b>Service Name</b>	EthIf_StoreConfiguration	
<b>Syntax</b>	Std_ReturnType EthIf_StoreConfiguration ( uint8 SwitchIdx )	
<b>Service ID [hex]</b>	0x2c	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: Storage/Reset request accepted E_NOT_OK: Storage/Reset request not accepted
<b>Description</b>	Trigger the storage/reset of the configuration of the learned MAC/Port tables of a switch in a persistent manner and will be used by e.g. CDD.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00215] [The function `EthIf_StoreConfiguration` shall trigger to store the learned MAC/Port tables of a Ethernet switch.]()

[SWS\_EthIf\_00216] [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfStoreConfigurationApi`.]()

[SWS\_EthIf\_00217] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

### 8.3.16 EthIf\_ResetConfiguration

[SWS\_EthIf\_00219] [

<b>Service Name</b>	EthIf_ResetConfiguration	
<b>Syntax</b>	Std_ReturnType EthIf_ResetConfiguration ( uint8 SwitchIdx )	
<b>Service ID [hex]</b>	0x2d	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: Request to persistently reset the MAC/Port table was accepted E_NOT_OK: Request to persistently reset the MAC/Port table was not accepted
<b>Description</b>	The function shall request to reset the configuration of the learned MAC/Port tables of a Ethernet switch in a persistent manner. This could be used by e.g. a CDD. The statically configured entries shall still remain.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00220] [The function `EthIf_ResetConfiguration` shall trigger to re-set the learned MAC/Port tables of a Ethernet switch.]()

[SWS\_EthIf\_00221] [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfResetConfigurationApi`.]()

[SWS\_EthIf\_00222] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

### 8.3.17 EthIf\_GetCurrentTime

[SWS\_EthIf\_00154] [

<b>Service Name</b>	EthIf_GetCurrentTime	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetCurrentTime (     uint8 CtrlIdx,     Eth_TimeStampQualType* timeQualPtr,     Eth_TimeStampType* timeStampPtr )</pre>	
<b>Service ID [hex]</b>	0x22	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the addresses ETH controller.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	timeQualPtr	quality of HW time stamp, e.g. based on current drift
	timeStampPtr	current time stamp
<b>Return value</b>	Std_ReturnType	E_OK: successful E_NOT_OK: failed
<b>Description</b>	<p>Returns a time value out of the HW registers according to the capability of the HW. Is the HW resolution is lower than the Eth_TimeStampType resolution resp. range, the remaining bits will be filled with 0.</p> <p>Important Note: EthIf_GetCurrentTime may be called within an exclusive area.</p>	
<b>Available via</b>	EthIf.h	

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[SWS\_EthIf\_00155] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00156] [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00157] [If development error detection is enabled: the function shall check the parameter `timeQualPtr` and `timeStampPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

[SWS\_EthIf\_00158] [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfGlobalTimeSupport`.]()

[SWS\_EthIf\_00473] [The EthIf module shall apply appropriate mechanisms to allow calls of `EthIf_GetCurrentTime` API from other partitions than its main function, e.g. by providing an EthIf satellite.]()

### 8.3.18 EthIf\_EnableEgressTimeStamp

[SWS\_EthIf\_00160] [

<b>Service Name</b>	EthIf_EnableEgressTimeStamp	
<b>Syntax</b>	<pre>void EthIf_EnableEgressTimeStamp (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx )</pre>	
<b>Service ID [hex]</b>	0x23	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the addresses ETH controller.
	BufIdx	Index of the message buffer, where Application expects egress time stamping
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Activates egress time stamping on a dedicated message object. Some HW does store once the egress time stamp marker and some HW needs it always before transmission. There will be no "disable" functionality, due to the fact, that the message type is always "time stamped" by network design.	
<b>Available via</b>	EthIf.h	

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[SWS\_EthIf\_00161] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00162] [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00164] [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfGlobalTimeSupport`.]()

### 8.3.19 EthIf\_GetEgressTimeStamp

[SWS\_EthIf\_00166] [

<b>Service Name</b>	EthIf_GetEgressTimeStamp	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetEgressTimeStamp (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx,     Eth_TimeStampQualType* timeQualPtr,     Eth_TimeStampType* timeStampPtr )</pre>	
<b>Service ID [hex]</b>	0x24	
<b>Sync/Async</b>	Synchronous	







<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the address ETH controller.
	BuflIdx	Index of the message buffer, where the Upper Layer expects egress time stamping
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	timeQualPtr	quality of HW time stamp, e.g. based on current drift
	timeStampPtr	current time stamp
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed to read time stamp.
<b>Description</b>	Reads back the egress time stamp on a dedicated message object. It must be called within the TxConfirmation() function.	
<b>Available via</b>	EthIf.h	

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**[SWS\_EthIf\_00167]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00168]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00169]** [If development error detection is enabled: the function shall check the parameter `timeQualPtr` and `timeStampPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00170]** [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfGlobalTimeSupport`.]()

### 8.3.20 EthIf\_GetIngressTimeStamp

**[SWS\_EthIf\_00172]** [

<b>Service Name</b>	EthIf_GetIngressTimeStamp	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetIngressTimeStamp (     uint8 CtrlIdx,     const Eth_DataType* DataPtr,     Eth_TimeStampQualType* timeQualPtr,     Eth_TimeStampType* timeStampPtr )</pre>	
<b>Service ID [hex]</b>	0x25	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the addresses ETH controller.
	DataPtr	Pointer to the message buffer, where Application expects ingress time stamping
<b>Parameters (inout)</b>	None	





<b>Parameters (out)</b>	timeQualPtr	quality of HW time stamp, e.g. based on current drift
	timeStampPtr	current time stamp
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed to read time stamp.
<b>Description</b>	Reads back the ingress time stamp on a dedicated message object. It must be called within the RxIndication() function.	
<b>Available via</b>	EthIf.h	

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**[SWS\_EthIf\_00173]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00174]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00175]** [If development error detection is enabled: the function shall check the parameter `DataPtr`, `timeQualPtr` and `timeStampPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00176]** [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfGlobalTimeSupport`.]()

### 8.3.21 EthIf\_SwitchPortGroupRequestMode

**[SWS\_EthIf\_91102]** [

<b>Service Name</b>	EthIf_SwitchPortGroupRequestMode	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchPortGroupRequestMode ( EthIf_SwitchPortGroupIdxType PortGroupIdx, Eth_ModeType PortMode )	
<b>Service ID [hex]</b>	0x06	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	PortGroupIdx	Index of the port group within the context of the Ethernet Interface
	PortMode	ETH_MODE_DOWN: disable the Ethernet switch port group ETH_MODE_ACTIVE: enable the Ethernet switch port group ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST: enable the port group and request for a wake-up on the network
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: port group mode could not be changed





<b>Description</b>	Request a mode for the EthIfSwtPortGroup. The call shall be forwarded to EthSwt by calling EthSwt_SetSwitchPortMode for all EthSwtPorts referenced by the port group.
<b>Available via</b>	EthIf.h

]()

**[SWS\_EthIf\_00270]** [If `EthIf_SwitchPortGroupRequestMode` is called with `ETH_MODE_DOWN` EthIf shall start a timer with `EthIfSwitchOffPortTimedelay` for all ports of the respective `EthIf_SwitchPortGroup` if the mode `ETH_MODE_DOWN` has been requested for all `EthIfSwitchPortGroups` referencing the port and the current mode is `ETH_MODE_ACTIVE`.]()

**[SWS\_EthIf\_00271]** [If the timer to switch off ports (see [\[SWS\\_EthIf\\_00270\]](#)) elapses for a port, EthIf shall call the following functions in the given order for the corresponding `EthSwtPort`:

1. `EthSwt_PortLinkStateRequest` with `ETHTRCV_LINK_STATE_DOWN`
2. `EthSwt_SetSwitchPortMode` with `ETH_MODE_DOWN`

]()

Note: The implementation has to ensure that `EthSwtPorts` within `EthIfSwitchPortGroups` are only disabled if all prior activation request have been withdrawn. This could be realized e.g. by a counter mechanism.

Rationale: Delaying to switch off `EthSwtPorts` by `EthIfSwitchOffPortTimedelay` is needed to ensure a simultaneous switch-off of the Ethernet switch port and the Ethernet hardware (PHY or another Ethernet switch) of the connected communication partner:

1. If the Ethernet hardware of the connected communication partner is an PHY, then the `EthIfSwitchOffPortTimedelay` cover the time which is needed until the PHY of the connected communication partner will be switched off, due to the NM handling.
2. If the Ethernet hardware of the connected communication partner is an Ethernet switch, then both `EthSwtPorts` should be switched off in the same point in time to avoid link down recognition.

**[SWS\_EthIf\_00273]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00274]** [If development error detection is enabled: the function shall check that the provided parameter `PortGroupId` addresses a port group not referenced by any `EthIfController`. If the check fails, the function shall raise the development error `ETHIF_E_INV_PORT_GROUP_IDX`.]()

Rationale: Avoid that a `EthIfSwitchPortGroup` which shall be controlled by `EthIfController` is incidentally called by `BswM`

### 8.3.22 EthIf\_StartAllPorts

[SWS\_EthIf\_91103] [

<b>Service Name</b>	EthIf_StartAllPorts	
<b>Syntax</b>	Std_ReturnType EthIf_StartAllPorts ( void )	
<b>Service ID [hex]</b>	0x07	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	None	
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: Request was accepted E_NOT_OK: Request was rejected
<b>Description</b>	Request to set all configured and affected EthSwTPorts to ETH_MODE_ACTIVE	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00277] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

### 8.3.23 EthIf\_SetSwitchMgmtInfo

[SWS\_EthIf\_91003] [

<b>Service Name</b>	EthIf_SetSwitchMgmtInfo	
<b>Syntax</b>	Std_ReturnType EthIf_SetSwitchMgmtInfo ( uint8 CtrlIdx, Eth_BufIdxType BufIdx, EthSwT_MgmtInfoType* MgmtInfoPtr )	
<b>Service ID [hex]</b>	0x38	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of an Ethernet Interface controller
	BufIdx	Ethernet Tx Buffer index
	MgmtInfoPtr	Pointer to the management information
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: Management infos successfully set E_NOT_OK: Setting of management infos failed
<b>Description</b>	Provides additional management information along to an Ethernet frame that requires special treatment within the Switch. It has to be called between <code>EthIf_ProvideTxBuffer()</code> and <code>EthIf_Transmit()</code> of the related frame.	
<b>Available via</b>	EthIf.h	

] ([SRS\\_Eth\\_00125](#))

**[SWS\_EthIf\_00279]** [The function shall be pre compile time configurable ON/OFF by the configuration parameter: `EthIfSwitchManagementSupport`.]()

**[SWS\_EthIf\_00280]** [If development error detection is enabled: the function shall check that the service `EthIf_Init()` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00281]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00282]** [If development error detection is enabled: the function shall check the parameter `BufIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

**[SWS\_EthIf\_00283]** [If development error detection is enabled: the function shall check the parameter `MgmtInfoPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.24 EthIf\_GetRxMgmtObject

**[SWS\_EthIf\_91105]** [

<b>Service Name</b>	EthIf_GetRxMgmtObject	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetRxMgmtObject (     uint8 CtrlIdx,     Eth_DataType* DataPtr,     EthSwt_MgmtObjectType **MgmtObjectPtr )</pre>	
<b>Service ID [hex]</b>	0x47	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of an Ethernet Interface controller
	DataPtr	Ethernet data pointer
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	**MgmtObjectPtr	MgmtObjectPtr Pointer to the management object
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: management object could not be obtained
<b>Description</b>	Request the MgmtObject of the (in this context) unique DataPtr.	
<b>Available via</b>	EthIf.h	

]()

### 8.3.25 EthIf\_GetTxMgmtObject

[SWS\_EthIf\_91106] [

<b>Service Name</b>	EthIf_GetTxMgmtObject	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetTxMgmtObject (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx,     EthSwt_MgmtObjectType **MgmtObjectPtr )</pre>	
<b>Service ID [hex]</b>	0x48	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of an Ethernet Interface controller
	BufIdx	Ethernet Rx Buffer index
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	**MgmtObjectPtr	Pointer to the management object
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: management object could not be obtained
<b>Description</b>	Request the MgmtObject of the (in this context) unique BufIdx.	
<b>Available via</b>	EthIf.h	

]()

### 8.3.26 EthIf\_SwitchEnableTimeStamping

[SWS\_EthIf\_91007] [

<b>Service Name</b>	EthIf_SwitchEnableTimeStamping	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchEnableTimeStamping (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx,     EthSwt_MgmtInfoType* MgmtInfo )</pre>	
<b>Service ID [hex]</b>	0x39	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	BufIdx	Index of the message buffer, where Application expects egress time stamping
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	MgmtInfo	Management information
<b>Return value</b>	Std_ReturnType	E_OK: Time stamping on egress successfully enabled E_NOT_OK: Enabling of time stamping on egress has been failed
<b>Description</b>	Activates egress time stamping on a dedicated message object, addressed by CtrlIdx and BufIdx.	
<b>Available via</b>	EthIf.h	

] ([SRS\\_Eth\\_00125](#))

**[SWS\_EthIf\_00387]** [If `EthIf_SwitchEnableTimeStamping` is called, the `EthIf` shall call `EthSwt_PortEnableTimeStamp` for every port in the group.]()

**[SWS\_EthIf\_00285]** [The function shall be pre compile time configurable ON/OFF by the configuration parameter: `EthIfGlobalTimeSupport`.]()

**[SWS\_EthIf\_00286]** [If development error detection is enabled: the function shall check that the service `Eth_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00287]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00288]** [If development error detection is enabled: the function shall check the parameter `BufIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

**[SWS\_EthIf\_00289]** [If development error detection is enabled: the function shall check the parameter `BufIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

**[SWS\_EthIf\_00290]** [If development error detection is enabled: the function shall check the parameter `BufIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

### 8.3.27 EthIf\_VerifyConfig

**[SWS\_EthIf\_91012]** [

<b>Service Name</b>	EthIf_VerifyConfig	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_VerifyConfig (     uint8 SwitchIdx,     boolean* Result )</pre>	
<b>Service ID [hex]</b>	0x40	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	Result	Result of verification, TRUE: configuration verified ok, FALSE: configuration values found corrupted
<b>Return value</b>	Std_ReturnType	E_OK: Configuration verification succeeded, E_NOT_OK: Configuration verification not succeeded.
<b>Description</b>	Forwarded to <code>EthSwt_VerifyConfig</code> . <code>EthSwt_VerifyConfig</code> verifies the Switch Configuration depending on the HW-Architecture, HW-capability and the intended accuracy of this verification.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00304]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT.`]([SRS\\_BSW\\_00101](#), [SRS\\_BSW\\_00369](#))

**[SWS\_EthIf\_00305]** [The function shall be compile time configurable On/Off by the configuration parameter: `EthIfVerifyConfigApi.`](`()`)

### 8.3.28 EthIf\_SetForwardingMode

**[SWS\_EthIf\_91013]** [

<b>Service Name</b>	EthIf_SetForwardingMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetForwardingMode (     uint8 SwitchIdx,     boolean mode )</pre>	
<b>Service ID [hex]</b>	0x41	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	mode	True Forwarding enabled, False Forwarding disabled
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: stopping of frame forwarding succeeded, E_NOT_OK: stopping of frame forwarding not succeeded.
<b>Description</b>	Verifies the Switch Configuration. If Configuration is not valid, Switch is reconfigured.	
<b>Available via</b>	EthIf.h	

](`()`)

**[SWS\_EthIf\_00306]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT.`]([SRS\\_BSW\\_00101](#), [SRS\\_BSW\\_00369](#))

**[SWS\_EthIf\_00307]** [The function shall be compile time configurable On/Off by the configuration parameter: `EthIfSetForwardingModeApi.`](`()`)



### 8.3.29 EthIf\_GetTrcvSignalQuality

[SWS\_EthIf\_91056] [

<b>Service Name</b>	EthIf_GetTrcvSignalQuality	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetTrcvSignalQuality (     uint8 TrcvIdx,     EthIf_SignalQualityResultType* ResultPtr )</pre>	
<b>Service ID [hex]</b>	0x18	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different TrcvIdx. Non reentrant for the same TrcvIdx.	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ResultPtr	Pointer to the memory where the signal quality in percent shall be stored.
<b>Return value</b>	Std_ReturnType	E_OK: The signal quality retrieved successfully E_NOT_OK: The signal quality not retrieved successfully
<b>Description</b>	Retrieves the signal quality of the link of the given Ethernet transceiver	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00391] [The function `EthIf_GetTrcvSignalQuality` shall forward the call to function `EthTrcv_GetPhySignalQuality` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

[SWS\_EthIf\_00392] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00393] [If development error detection is enabled: the function shall check the parameter `TrcvIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

[SWS\_EthIf\_00394] [If development error detection is enabled: the function shall check the parameter `ResultPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.30 EthIf\_GetSwitchPortSignalQuality

[SWS\_EthIf\_91058] [

<b>Service Name</b>	EthIf_GetSwitchPortSignalQuality	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetSwitchPortSignalQuality (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     EthIf_SignalQualityResultType* ResultPtr )</pre>	
<b>Service ID [hex]</b>	0x1a	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different Ethernet switch indexes and Ethernet Switch port indexes. Non reentrant for the same SwitchPortIdx.	
<b>Parameters (in)</b>	SwitchIdx	Index of the Ethernet switch within the context of the Ethernet Interface
	SwitchPortIdx	Index of the Ethernet switch port within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ResultPtr	Pointer to the memory where the signal quality in percent shall be stored.
<b>Return value</b>	Std_ReturnType	E_OK: The signal quality retrieved successfully E_NOT_OK: The signal quality not retrieved successfully
<b>Description</b>	Retrieves the signal quality of the link of the given Ethernet switch port	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00395] [The function `EthIf_GetSwitchPortSignalQuality` shall forward the call to function `EthSwt_GetPortSignalQuality` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

[SWS\_EthIf\_00396] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00397] [If development error detection is enabled: the function shall check the parameter `SwitchIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_SWT_IDX`.]()

[SWS\_EthIf\_00495] [If development error detection is enabled: the function shall check the parameter `SwitchPortIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PORT_IDX` otherwise (if DET is disabled) return `E_NOT_OK`.]()

[SWS\_EthIf\_00399] [If development error detection is enabled: the function shall check the parameter `ResultPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.31 EthIf\_ClearTrcvSignalQuality

[SWS\_EthIf\_91059] [

<b>Service Name</b>	EthIf_ClearTrcvSignalQuality	
<b>Syntax</b>	Std_ReturnType EthIf_ClearTrcvSignalQuality ( uint8 TrcvIdx )	
<b>Service ID [hex]</b>	0x19	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different TrcvIdx. Non reentrant for the same TrcvIdx.	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The signal quality cleared successfully E_NOT_OK: The signal quality cleared not successfully
<b>Description</b>	Clear the stored signal quality of the link of the given Ethernet transceiver	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00400] [The function [EthIf\\_ClearTrcvSignalQuality](#) shall clear the stored signal quality values (see [EthIf\\_SignalQualityResultType](#)) of the EthIfTransceiver given by [TrcvIdx](#).]()

[SWS\_EthIf\_00401] [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

[SWS\_EthIf\_00402] [If development error detection is enabled: the function shall check the parameter [TrcvIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_TRCV\\_IDX](#).]()

### 8.3.32 EthIf\_ClearSwitchPortSignalQuality

[SWS\_EthIf\_91060] [

<b>Service Name</b>	EthIf_ClearSwitchPortSignalQuality	
<b>Syntax</b>	Std_ReturnType EthIf_ClearSwitchPortSignalQuality ( uint8 SwitchIdx, uint8 SwitchPortIdx )	
<b>Service ID [hex]</b>	0x1b	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different Ethernet switch indexes and Ethernet Switch port indexes. Non reentrant for the same SwitchPortIdx.	
<b>Parameters (in)</b>	SwitchIdx	Index of the Ethernet switch within the context of the Ethernet Interface





	SwitchPortIdx	Index of the Ethernet switch port within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The signal quality cleared successfully E_NOT_OK: The signal quality cleared not successfully
<b>Description</b>	Clear the stored signal quality of the link of the given Ethernet switch port	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00404]** [The function `EthIf_ClearSwitchPortSignalQuality` shall clear the stored signal quality values (see `EthIf_SignalQualityResultType`) of the `EthSwtPort` given by `SwitchIdx` and `SwitchPortIdx`.]()

**[SWS\_EthIf\_00405]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00406]** [If development error detection is enabled: the function shall check the parameter `SwitchIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_SWT_IDX`.]()

**[SWS\_EthIf\_00496]** [If development error detection is enabled: the function shall check the parameter `SwitchPortIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PORT_IDX` otherwise (if DET is disabled) return `E_NOT_OK`.]()

### 8.3.33 EthIf\_SetPhyTestMode

**[SWS\_EthIf\_91016]** [

<b>Service Name</b>	EthIf_SetPhyTestMode	
<b>Syntax</b>	Std_ReturnType EthIf_SetPhyTestMode ( uint8 TrcvIdx, EthTrcv_PhyTestModeType Mode )	
<b>Service ID [hex]</b>	0x17	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different TrcvIdx. Non reentrant for the same TrcvIdx.	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Interface
	Mode	Test mode to be activated
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted.



△

<b>Description</b>	Activates a given test mode.
<b>Available via</b>	EthIf.h

](SRS\_Eth\_00117)

**[SWS\_EthIf\_00324]** [The function `EthIf_SetPhyTestMode` shall forward the call to function `EthTrcv_SetPhyTestMode` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

**[SWS\_EthIf\_00325]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00326]** [If development error detection is enabled: the function shall check the parameter `TrcvIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

### 8.3.34 EthIf\_SetPhyLoopbackMode

**[SWS\_EthIf\_91018]** [

<b>Service Name</b>	EthIf_SetPhyLoopbackMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetPhyLoopbackMode (     uint8 TrcvIdx,     EthTrcv_PhyLoopbackModeType Mode )</pre>	
<b>Service ID [hex]</b>	0x12	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different <code>TrcvIdx</code> . Non reentrant for the same <code>TrcvIdx</code> .	
<b>Parameters (in)</b>	<code>TrcvIdx</code>	Index of the transceiver within the context of the Ethernet Interface
	<code>Mode</code>	Loopback mode to be activated
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	<code>Std_ReturnType</code>	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted.
<b>Description</b>	Activates a given loopback mode.	
<b>Available via</b>	EthIf.h	

](SRS\_Eth\_00117)

**[SWS\_EthIf\_00327]** [The function `EthIf_SetPhyLoopbackMode` shall forward the call to function `EthTrcv_SetPhyLoopbackMode` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

**[SWS\_EthIf\_00328]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00329]** [If development error detection is enabled: the function shall check the parameter `TrcvIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

### 8.3.35 EthIf\_SetPhyTxMode

**[SWS\_EthIf\_91061]** [

<b>Service Name</b>	EthIf_SetPhyTxMode	
<b>Syntax</b>	Std_ReturnType EthIf_SetPhyTxMode ( uint8 TrcvIdx, EthTrcv_PhyTxModeType Mode )	
<b>Service ID [hex]</b>	0x13	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different TrcvIdx. Non reentrant for the same TrcvIdx.	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Interface
	Mode	Transmission mode to be activated
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Activates a given transmission mode.	
<b>Available via</b>	EthIf.h	

] ([SRS\\_Eth\\_00117](#))

**[SWS\_EthIf\_00388]** [The function `EthIf_SetPhyTxMode` shall forward the call to function `EthTrcv_SetPhyTxMode` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

**[SWS\_EthIf\_00389]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00390]** [If development error detection is enabled: the function shall check the parameter `TrcvIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

### 8.3.36 EthIf\_GetCableDiagnosticsResult

[SWS\_EthIf\_91014] [

<b>Service Name</b>	EthIf_GetCableDiagnosticsResult	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetCableDiagnosticsResult (     uint8 TrcvIdx,     EthTrcv_CableDiagResultType* ResultPtr )</pre>	
<b>Service ID [hex]</b>	0x14	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different TrcvIdx. Non reentrant for the same TrcvIdx.	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ResultPtr	Pointer to the location where the cable diagnostics result shall be stored
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Retrieves the cable diagnostics result of a given transceiver.	
<b>Available via</b>	EthIf.h	

](SRS\_Eth\_00117)

[SWS\_EthIf\_00330] [The function `EthIf_GetCableDiagnosticsResult` shall forward the call to function `EthTrcv_GetCableDiagnosticsResult` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

[SWS\_EthIf\_00331] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00332] [If development error detection is enabled: the function shall check the parameter `TrcvIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

[SWS\_EthIf\_00333] [If development error detection is enabled: the function shall check the parameter `ResultPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.37 EthIf\_GetPhyIdentifier

[SWS\_EthIf\_91020] [

<b>Service Name</b>	EthIf_GetPhyIdentifier	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetPhyIdentifier (     uint8 TrcvIdx,     uint32* OrgUniqueIdPtr,     uint8* ModelNrPtr,     uint8* RevisionNrPtr )</pre>	
<b>Service ID [hex]</b>	0x15	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different TrcvIdx. Non reentrant for the same TrcvIdx.	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	OrgUniqueIdPtr	Pointer to the memory where the Organizationally Unique Identifier shall be stored.
	ModelNrPtr	Pointer to the memory where the Manufacturer's Model Number shall be stored.
	RevisionNrPtr	Pointer to the memory where the Revision Number shall be stored.
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Obtains the PHY identifier of the Ethernet Interface according to IEEE 802.3-2015 chapter 22.2.4.3.1 PHY Identifier.	
<b>Available via</b>	EthIf.h	

](SRS\_Eth\_00117)

[SWS\_EthIf\_00334] [The function [EthIf\\_GetPhyIdentifier](#) shall forward the call to function [EthTrcv\\_GetPhyIdentifier](#) of the corresponding Ethernet Transceiver Driver (EthIfTransceiverIdx).]()

[SWS\_EthIf\_00335] [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

[SWS\_EthIf\_00336] [If development error detection is enabled: the function shall check the parameter [TrcvIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_TRCV\\_IDX](#).]()

[SWS\_EthIf\_00337] [If development error detection is enabled: the function shall check the parameter [OrgUniqueIdPtr](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

[SWS\_EthIf\_00338] [If development error detection is enabled: the function shall check the parameter [ModelNrPtr](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

[SWS\_EthIf\_00339] [If development error detection is enabled: the function shall check the parameter [RevisionNrPtr](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()



### 8.3.38 EthIf\_GetBufWRxParams

[SWS\_EthIf\_91002] [

<b>Service Name</b>	EthIf_GetBufWRxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetBufWRxParams (     uint8 CtrlIdx,     const WEth_BufWRxParamIdType* RxParamIds,     uint32* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x32	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	RxParamIds	IDs of the Parameters to read
	NumParams	Number of Parameters
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ParamValues	Values of the Parameters requested
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed reading parameters
<b>Description</b>	Read out values related to the receive direction of the transceiver for a received packet. For example, this could be RSSI or Channel belonging to one single packet.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00341]** [The function [EthIf\\_GetBufWRxParams](#) shall forward the call to function [WEth\\_GetBufWRxParams](#) of the respective Wireless Ethernet Controller Driver.]()

**[SWS\_EthIf\_00342]** [The function shall be pre compile time configurable On/Off by the configuration parameter: [EthIfEnableWEthApi](#).]()

**[SWS\_EthIf\_00343]** [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

**[SWS\_EthIf\_00344]** [If development error detection is enabled: the function shall check the parameter [CtrlIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_CTRL\\_IDX](#).]()

**[SWS\_EthIf\_00345]** [If development error detection is enabled: the function shall check the parameter [RxParamIds](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

**[SWS\_EthIf\_00346]** [If development error detection is enabled: the function shall check the parameter [ParamValues](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

Note: The function requires previous reception ([EthIf\\_RxIndication](#)).

### 8.3.39 EthIf\_GetBufWTxParams

[SWS\_EthIf\_91054] [

<b>Service Name</b>	EthIf_GetBufWTxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetBufWTxParams (     uint8 CtrlIdx,     const WEth_BufWTxParamIdType* TxParamIds,     uint32* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x31	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	TxParamIds	IDs of the Parameter that are requested
	NumParams	Number of Parameters that are requested
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ParamValues	Values of the Parameters requested
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed reading parameters
<b>Description</b>	Read out values related to the transmit direction of the transceiver for a transmitted packet. For example, this could be transaction ID belonging to one single packet.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00347] [The function [EthIf\\_GetBufWTxParams](#) shall forward the call to function `WEth_GetBufWTxParams` of the respective Wireless Ethernet Controller Driver.]()

[SWS\_EthIf\_00348] [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableWEthApi`.]()

[SWS\_EthIf\_00349] [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00350] [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00351] [If development error detection is enabled: the function shall check the parameter `TxParamIds` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

[SWS\_EthIf\_00352] [If development error detection is enabled: the function shall check the parameter `ParamValues` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

Note: The function requires previous transmission ([EthIf\\_Transmit](#)).

### 8.3.40 EthIf\_SetBufWTxParams

[SWS\_EthIf\_91017] [

<b>Service Name</b>	EthIf_SetBufWTxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetBufWTxParams (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx,     const WEth_BufWTxParamIdType* TxParamIds,     const uint32* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x33	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	BufIdx	Index of the buffer resource
	TxParamIds	IDs of the Parameter that are provided to the transmit radio
	ParamValues	Values of the Parameters that are provided to the transmit radio
	NumParams	Number of Parameters that are provided to the transmit radio
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed setting parameter
<b>Description</b>	Set values related to the transmit direction of the transceiver for a specific buffer (packet to be sent). For example, this can be the desired transmit power or the channel belonging to one single packet.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00353] [The function [EthIf\\_SetBufWTxParams](#) shall forward the call to function `WEth_SetBufWTxParams` of the respective Wireless Ethernet Controller Driver.]()

[SWS\_EthIf\_00354] [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableWEthApi`.]()

[SWS\_EthIf\_00355] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00356] [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00357] [If development error detection is enabled: the function shall check the parameter `BufIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

[SWS\_EthIf\_00358] [If development error detection is enabled: the function shall check the parameter `TxParamIds` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00359]** [If development error detection is enabled: the function shall check the parameter `ParamValues` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

Note: The function requires previous buffer request (`EthIf_ProvideTxBuffer`).

### 8.3.41 EthIf\_SetRadioParams

**[SWS\_EthIf\_91026]** [

<b>Service Name</b>	EthIf_SetRadioParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetRadioParams (     uint8 TrcvId,     const WEthTrcv_SetRadioParamIdType* ParamIds,     const uint32* ParamValue,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x34	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvId	Index of the transceiver
	ParamIds	IDs of the Parameters to set
	ParamValue	Values of the Parameters to set
	NumParams	Number of Parameters to set
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed writing parameters
<b>Description</b>	Set values related to a transceiver's wireless radio. For example, this could be the selection of the radio settings (channel, ...).	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00360]** [The function `EthIf_SetRadioParams` shall forward the call to function `WEthTrcv_SetRadioParams` of the respective Wireless Ethernet Transceiver Driver.]()

**[SWS\_EthIf\_00361]** [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableWEthApi`.]()

**[SWS\_EthIf\_00362]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00363]** [If development error detection is enabled: the function shall check the parameter `TrcvId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

**[SWS\_EthIf\_00364]** [If development error detection is enabled: the function shall check the parameter `ParamIds` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00365]** [If development error detection is enabled: the function shall check the parameter `ParamValue` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.42 EthIf\_SetChanRxParams

**[SWS\_EthIf\_91034]** [

<b>Service Name</b>	EthIf_SetChanRxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetChanRxParams (     uint8 TrcvId,     uint8 RadioId,     const WEthTrcv_SetChanRxParamIdType* ParamIds,     const uint32* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x35	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvId	Index of the transceiver
	RadioId	Index of the Transceiver's Radio (including channel)
	ParamIds	IDs of the Parameters to set
	ParamValues	Values of the Parameters to set
	NumParams	Number of Parameters to set
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed writing parameters
<b>Description</b>	Set values related to the receive direction of a transceiver's wireless channel. For example, this could be a channel parameter like the frequency.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00366]** [The function `EthIf_SetChanRxParams` shall forward the call to function `WEthTrcv_SetChanRxParams` of the respective Wireless Ethernet Transceiver Driver.]()

**[SWS\_EthIf\_00367]** [The function `EthIf_SetChanRxParams` shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableWEthApi`.]()

**[SWS\_EthIf\_00368]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00369]** [If development error detection is enabled: the function shall check the parameter `TrcvId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

**[SWS\_EthIf\_00370]** [If development error detection is enabled: the function shall check the parameter `RadioId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

**[SWS\_EthIf\_00371]** [If development error detection is enabled: the function shall check the parameter `ParamIds` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00372]** [If development error detection is enabled: the function shall check the parameter `ParamValues` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.43 EthIf\_SetChanTxParams

**[SWS\_EthIf\_91042]** [

<b>Service Name</b>	EthIf_SetChanTxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetChanTxParams (     uint8 TrcvId,     uint8 RadioId,     const WEthTrcv_SetChanTxParamIdType* TxParamIds,     const uint32* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x36	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvId	Index of the transceiver
	RadioId	Index of the Transceiver's Radio (including channel)
	TxParamIds	IDs of the Parameters to set
	ParamValues	Values of the Parameters to set
	NumParams	Number of Parameters to set
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed writing parameters
<b>Description</b>	Set values related to the transmit direction of a transceiver's wireless channel. For example, this could be the bitrate of a channel.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00373]** [The function `EthIf_SetChanTxParams` shall forward the call to function `WEthTrcv_SetChanTxParams` of the respective Wireless Ethernet Transceiver Driver.]()

**[SWS\_EthIf\_00374]** [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableWEthApi`.]()

**[SWS\_EthIf\_00375]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00376]** [If development error detection is enabled: the function shall check the parameter `TrcvId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

**[SWS\_EthIf\_00377]** [If development error detection is enabled: the function shall check the parameter `RadioId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

**[SWS\_EthIf\_00378]** [If development error detection is enabled: the function shall check the parameter `TxParamIds` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00379]** [If development error detection is enabled: the function shall check the parameter `ParamValues` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.44 EthIf\_GetChanRxParams

**[SWS\_EthIf\_91050]** [

<b>Service Name</b>	EthIf_GetChanRxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetChanRxParams (     uint8 TrcvId,     uint8 RadioId,     const WEthTrcv_GetChanRxParamIdType* ParamIds,     uint32* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x37	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvId	Index of the transceiver
	RadioId	Index of the Transceiver's Radio ( including channel)
	ParamIds	IDs of the Parameters to read
	NumParams	Number of Parameters to read
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ParamValues	Values of the requested Parameters
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed reading parameters
<b>Description</b>	Read values related to the receive direction of the transceiver. For example, this could be a Channel Busy Ratio (CBR) or the average Channel Idle Time (CIT).	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00380]** [The function `EthIf_GetChanRxParams` shall forward the call to function `WEthTrcv_GetChanRxParams` of the respective Wireless Ethernet Transceiver Driver.]()

**[SWS\_EthIf\_00381]** [The function shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableWEthApi`.]()

**[SWS\_EthIf\_00382]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00383]** [If development error detection is enabled: the function shall check the parameter `TrcvId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_TRCV_IDX`.]()

**[SWS\_EthIf\_00384]** [If development error detection is enabled: the function shall check the parameter `RadioId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

**[SWS\_EthIf\_00385]** [If development error detection is enabled: the function shall check the parameter `ParamIds` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00386]** [If development error detection is enabled: the function shall check the parameter `ParamValues` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.45 EthIf\_ProvideTxBuffer

**[SWS\_EthIf\_00067]** [

<b>Service Name</b>	EthIf_ProvideTxBuffer	
<b>Syntax</b>	<pre>BufReq_ReturnType EthIf_ProvideTxBuffer (     uint8 CtrlIdx,     Eth_FrameType FrameType,     uint8 Priority,     Eth_BufIdxType* BufIdxPtr,     uint8** BufPtr,     uint16* LenBytePtr )</pre>	
<b>Service ID [hex]</b>	0x09	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	FrameType	Ethernet Frame Type (EtherType)
	Priority	Priority value which shall be used for the 3-bit PCP field of the VLAN tag
<b>Parameters (inout)</b>	LenBytePtr	in: desired length in bytes, out: granted length in bytes
<b>Parameters (out)</b>	BufIdxPtr	Index to the granted buffer resource. To be used for subsequent requests
	BufPtr	Pointer to the granted buffer
<b>Return value</b>	BufReq_ReturnType	BUFREQ_OK: success BUFREQ_E_NOT_OK: development error detected BUFREQ_E_BUSY: all buffers in use BUFREQ_E_OVFL: requested buffer too large
<b>Description</b>	Provides access to a transmit buffer of the specified Ethernet controller.	
<b>Available via</b>	EthIf.h	



]()

**[SWS\_EthIf\_00146]** [If `CtrlIdx` refers to an `EthIfCtrl` where no `EthIfVlanID` is configured, the parameters `FrameType` and `Priority` are not used.]()

**[SWS\_EthIf\_00147]** [If VLAN is used

- EthIf shall increment the input desired length by 4 bytes before calling the Ethernet Driver module
- EthIf shall store the PCP (`Priority` parameter), CFI (always 0), VID (configured VLAN ID) and value of the `FrameType` parameter at the beginning of the buffer received from `<EthDrv>_ProvideTxBuffer`.
- EthIf shall increment the `BufPtr` by 4 bytes when returning the granted buffer
- EthIf shall decrement the output granted length by 4 bytes

]()

**[SWS\_EthIf\_00068]** [If the latest accepted controller mode is equal to `ETH_MODE_ACTIVE` or `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` for the given `EthIfController`, then the function `EthIf_ProvideTxBuffer` shall forward the call to the respective Ethernet Controller Driver or CanXL Controller Driver. Otherwise the function shall reject the request for a transmission buffer and return with `E_NOT_OK`.]()

**[SWS\_EthIf\_00069]** [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

**[SWS\_EthIf\_00070]** [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

**[SWS\_EthIf\_00071]** [If development error detection is enabled: the function shall check the parameter `BufIdxPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00072]** [If development error detection is enabled: the function shall check the parameter `BufPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

**[SWS\_EthIf\_00073]** [If development error detection is enabled: the function shall check the parameter `LenBytePtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.46 EthIf\_Transmit

[SWS\_EthIf\_00075] [

<b>Service Name</b>	EthIf_Transmit	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_Transmit (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx,     Eth_FrameType FrameType,     boolean TxConfirmation,     uint16 LenByte,     const uint8* PhysAddrPtr )</pre>	
<b>Service ID [hex]</b>	0x0a	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different buffer indexes and Ctrl indexes	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	BufIdx	Index of the buffer resource
	FrameType	Ethernet frame type
	TxConfirmation	Activates transmission confirmation
	LenByte	Data length in byte
	PhysAddrPtr	Physical target address (MAC address) in network byte order
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: transmission failed
<b>Description</b>	Triggers transmission of a previously filled transmit buffer	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00250] [If `CtrlIdx` refers to an `EthIfCtrl` where an `EthIfVlanID` is configured, the parameters `FrameType` is not used, and `0x8100` is provided to `<EthDrv>_Transmit` instead.]()

[SWS\_EthIf\_00076] [If the latest accepted controller mode is equal to `ETH_MODE_ACTIVE` or `ETH_MODE_ACTIVE_WITH_WAKEUP_REQUEST` for the given `EthIfController`, then the function `EthIf_Transmit` shall forward the call to the respective Ethernet Controller Driver. Otherwise the function shall reject the request for a transmission and return with `E_NOT_OK`.]()

[SWS\_EthIf\_00077] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00078] [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00079] [If development error detection is enabled: the function shall check the parameter `BufIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM`.]()

**[SWS\_EthIf\_00080]** [If development error detection is enabled: the function shall check the parameter `PhysAddrPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.47 EthIf\_GetVersionInfo

**[SWS\_EthIf\_00082]** [

<b>Service Name</b>	EthIf_GetVersionInfo	
<b>Syntax</b>	<pre>void EthIf_GetVersionInfo (     Std_VersionInfoType* VersionInfoPtr )</pre>	
<b>Service ID [hex]</b>	0x0b	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	None	
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	VersionInfoPtr	Version information of this module
<b>Return value</b>	None	
<b>Description</b>	Returns the version information of this module	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00127]** [If development error detection is enabled: the function shall check the parameter `VersionInfoPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.48 EthIf\_GetSwitchPortMode

**[SWS\_EthIf\_91107]** [

<b>Service Name</b>	EthIf_GetSwitchPortMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetSwitchPortMode (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     Eth_ModeType* PortModePtr )</pre>	
<b>Service ID [hex]</b>	0x49	
<b>Sync/Async</b>	Synchronous /Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	





<b>Parameters (out)</b>	PortModePtr	ETH_MODE_DOWN: The Ethernet switch port of the given Ethernet switch is disabled ETH_MODE_ACTIVE: The Ethernet switch port of the given Ethernet switch is enabled
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: The mode of the indexed switch port could not be obtained, or the function is called in state ETHSWT_STATE_UNINIT or ETHSWT_STATE_INIT.
<b>Description</b>	Obtains the mode of the indexed switch port	
<b>Available via</b>	Ethlf.h	

]()

**[SWS\_EthIf\_00415]** [The function [EthIf\\_GetSwitchPortMode](#) shall forward the call to function `EthSwt_GetSwitchPortMode` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.49 EthIf\_GetTransceiverMode

**[SWS\_EthIf\_91108]** [

<b>Service Name</b>	EthIf_GetTransceiverMode	
<b>Syntax</b>	Std_ReturnType EthIf_GetTransceiverMode ( uint8 TrcvIdx, Eth_ModeType* TrcvModePtr )	
<b>Service ID [hex]</b>	0x4a	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Transceiver Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	TrcvModePtr	ETH_MODE_DOWN: the transceiver is disabled ETH_MODE_ACTIVE: the transceiver is enable
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: transceiver could not be initialized
<b>Description</b>	Obtains the state of the indexed transceiver	
<b>Available via</b>	Ethlf.h	

]()

**[SWS\_EthIf\_00417]** [The function [EthIf\\_GetTransceiverMode](#) shall forward the call to function `<EthTrcv>_GetTransceiverMode` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

### 8.3.50 EthIf\_SwitchPortGetLinkState

[SWS\_EthIf\_91109] [

<b>Service Name</b>	EthIf_SwitchPortGetLinkState	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetLinkState (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     EthTrcv_LinkStateType* LinkStatePtr )</pre>	
<b>Service ID [hex]</b>	0x4b	
<b>Sync/Async</b>	Synchronous /Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	LinkStatePtr	ETHTRCV_LINK_STATE_DOWN: Switch port is disconnected ETHTRCV_LINK_STATE_ACTIVE: Switch port is connected
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: Link state of the indexed switch port could not be obtained, or the function is called in state ETHSWT_STATE_UNINIT or ETHSWT_STATE_INIT.
<b>Description</b>	Obtains the link state of the indexed switch port	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00419] [The function `EthIf_SwitchPortGetLinkState` shall forward the call to function `EthSwt_GetLinkState` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.51 EthIf\_TransceiverGetLinkState

[SWS\_EthIf\_91110] [

<b>Service Name</b>	EthIf_TransceiverGetLinkState	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_TransceiverGetLinkState (     uint8 TrcvIdx,     EthTrcv_LinkStateType* LinkStatePtr )</pre>	
<b>Service ID [hex]</b>	0x4c	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Transceiver Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	LinkStatePtr	ETHTRCV_LINK_STATE_DOWN: transceiver is disconnected ETHTRCV_LINK_STATE_ACTIVE: transceiver is connected
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: transceiver could not be initialized





<b>Description</b>	Obtains the link state of the indexed transceiver
<b>Available via</b>	EthIf.h

]()

**[SWS\_EthIf\_00421]** [The function `EthIf_TransceiverGetLinkState` shall forward the call to function `<EthTrcv>_GetLinkState` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

### 8.3.52 EthIf\_SwitchPortGetBaudRate

**[SWS\_EthIf\_91111]** [

<b>Service Name</b>	EthIf_SwitchPortGetBaudRate	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetBaudRate (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     EthTrcv_BaudRateType* BaudRatePtr )</pre>	
<b>Service ID [hex]</b>	0x4d	
<b>Sync/Async</b>	Synchronous /Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	BaudRatePtr	ETHTRCV_BAUD_RATE_10MBIT: 10MBit connection ETHTRCV_BAUD_RATE_100MBIT: 100MBit connection ETHTRCV_BAUD_RATE_1000MBIT: 1000MBit connection ETHTRCV_BAUD_RATE_2500MBIT: 2500MBit connection
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: Baud rate of the indexed switch port could not be obtained, or the function is called in state ETHSWT_STATE_UNINIT or ETHSWT_STATE_INIT.
<b>Description</b>	Obtains the baud rate of the indexed switch port	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00423]** [The function `EthIf_SwitchPortGetBaudRate` shall forward the call to function `EthSwt_GetBaudRate` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.53 EthIf\_TransceiverGetBaudRate

[SWS\_EthIf\_91112] [

<b>Service Name</b>	EthIf_TransceiverGetBaudRate	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_TransceiverGetBaudRate (     uint8 TrcvIdx,     EthTrcv_BaudRateType* BaudRatePtr )</pre>	
<b>Service ID [hex]</b>	0x4e	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Transceiver Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	BaudRatePtr	ETHTRCV_BAUD_RATE_10MBIT: 10MBit connection ETHTRCV_BAUD_RATE_100MBIT: 100MBit connection ETHTRCV_BAUD_RATE_1000MBIT: 1000MBit connection ETHTRCV_BAUD_RATE_2500MBIT: 2500MBit connection
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: transceiver could not be initialized
<b>Description</b>	Obtains the baud rate of the indexed transceiver	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00426] [The function [EthIf\\_TransceiverGetBaudRate](#) shall forward the call to function `EthTrcv_GetBaudRate` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()

### 8.3.54 EthIf\_SwitchPortGetDuplexMode

[SWS\_EthIf\_91113] [

<b>Service Name</b>	EthIf_SwitchPortGetDuplexMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetDuplexMode (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     EthTrcv_DuplexModeType* DuplexModePtr )</pre>	
<b>Service ID [hex]</b>	0x4f	
<b>Sync/Async</b>	Synchronous /Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	DuplexModePtr	ETHTRCV_DUPLEX_MODE_HALF: half duplex connections ETHTRCV_DUPLEXMODE_FULL: full duplex connection





<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: duplex mode of the indexed switch port could not be obtained, or the function is called in state ETHSWT_STATE_UNINIT or ETHSWT_STATE_INIT.
<b>Description</b>	Obtains the duplex mode of the indexed switch port	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00428]** [The function [EthIf\\_SwitchPortGetDuplexMode](#) shall forward the call to function `EthSwt_GetDuplexMode` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.55 EthIf\_TransceiverGetDuplexMode

**[SWS\_EthIf\_91114]** [

<b>Service Name</b>	EthIf_TransceiverGetDuplexMode	
<b>Syntax</b>	Std_ReturnType EthIf_TransceiverGetDuplexMode ( uint8 TrcvIdx, EthTrcv_DuplexModeType* DuplexModePtr )	
<b>Service ID [hex]</b>	0x50	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Transceiver Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	DuplexModePtr	ETHTRCV_DUPLEX_MODE_HALF: half duplex connections ETHTRCV_DUPLEX_MODE_FULL: full duplex connection
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: transceiver could not be initialized
<b>Description</b>	Obtains the duplex mode of the indexed transceiver	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00430]** [The function [EthIf\\_TransceiverGetDuplexMode](#) shall forward the call to function `EthTrcv_GetDuplexMode` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).]()



### 8.3.56 EthIf\_SwitchPortGetCounterValues

[SWS\_EthIf\_91115] [

<b>Service Name</b>	EthIf_SwitchPortGetCounterValues	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetCounterValues (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     Eth_CounterType* CounterPtr )</pre>	
<b>Service ID [hex]</b>	0x51	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	CounterPtr	counter values according to IETF RFC 1757, RFC 1643 and RFC 2233.
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: counter values read failure
<b>Description</b>	Reads a list with drop counter values of the corresponding port of the switch. The meaning of these values is described at Eth_CounterType.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00432] [The function [EthIf\\_SwitchPortGetCounterValues](#) shall forward the call to function `EthSwt_GetCounterValues` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.57 EthIf\_SwitchPortGetRxStats

[SWS\_EthIf\_91116] [

<b>Service Name</b>	EthIf_SwitchPortGetRxStats	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetRxStats (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     Eth_RxStatsType* RxStatsPtr )</pre>	
<b>Service ID [hex]</b>	0x52	
<b>Sync/Async</b>	Synchronous /Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	RxStatsPtr	List of values according to IETF RFC 2819 (Remote Network Monitoring Management Information Base)
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: drop counter could not be obtained





<b>Description</b>	Returns a list of statistic counters defined with Eth_RxTatsType. The majority of these Counters are derived from the IETF RFC2819.
<b>Available via</b>	EthIf.h

]()

**[SWS\_EthIf\_00434]** [The function `EthIf_SwitchPortGetRxStats` shall forward the call to function `EthSwt_GetRxStats` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.58 EthIf\_SwitchPortGetTxStats

**[SWS\_EthIf\_91117]** [

<b>Service Name</b>	EthIf_SwitchPortGetTxStats	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetTxStats (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     Eth_TxStatsType* TxStatsPtr )</pre>	
<b>Service ID [hex]</b>	0x53	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	–
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	TxStatsPtr	List of values to read statistic values for transmission.
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOTOK: Tx-statistics could not be obtained
<b>Description</b>	List of values to read statistic values for transmission.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00436]** [The function `EthIf_SwitchPortGetTxStats` shall forward the call to function `EthSwt_GetTxStats` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.59 EthIf\_SwitchPortGetTxErrorCounterValues

[SWS\_EthIf\_91118] [

<b>Service Name</b>	EthIf_SwitchPortGetTxErrorCounterValues	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetTxErrorCounterValues (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     Eth_TxErrorCounterValuesType* TxStatsPtr )</pre>	
<b>Service ID [hex]</b>	0x54	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Drive
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	TxStatsPtr	List of values to read statistic error counter values for transmission.
<b>Return value</b>	Std_ReturnType	E_OK: success, E_NOTOK: Tx-statistics could not be obtained
<b>Description</b>	List of values to read statistic error counter values for transmission from.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00438] [The function [EthIf\\_SwitchPortGetTxErrorCounterValues](#) shall forward the call to function [EthSwt\\_GetTxErrorCounterValues](#) of the corresponding Ethernet Switch Driver (EthIfSwitchIdx).]()

### 8.3.60 EthIf\_SwitchPortGetMacLearningMode

[SWS\_EthIf\_91119] [

<b>Service Name</b>	EthIf_SwitchPortGetMacLearningMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchPortGetMacLearningMode (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     EthSwt_MacLearningType* MacLearningModePtr )</pre>	
<b>Service ID [hex]</b>	0x55	
<b>Sync/Async</b>	Synchronous /Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	MacLearningModePtr	Defines whether MAC addresses shall be learned and if they shall be learned in software or hardware.
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: configuration could be persistently reset



△

<b>Description</b>	Returns the MAC learning mode, i.e. 1.) HW learning enabled, 2.) Hardware learning disabled, 3.) Software learning enabled. Note: This feature is hardware dependent, i.e. the switch hardware needs to support the different learning modes
<b>Available via</b>	EthIf.h

]()

**[SWS\_EthIf\_00440]** [The function `EthIf_SwitchPortGetMacLearningMode` shall forward the call to function `EthSwt_GetMacLearningMode` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.61 EthIf\_GetSwitchPortIdentifier

**[SWS\_EthIf\_91120]** [

<b>Service Name</b>	EthIf_GetSwitchPortIdentifier	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetSwitchPortIdentifier (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     uint32* OrgUniqueIdPtr,     uint8* ModelNrPtr,     uint8* RevisionNrPtr )</pre>	
<b>Service ID [hex]</b>	0x56	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	OrgUniqueIdPtr	Pointer to the memory where the Organizationally Unique Identifier (OUI) shall be stored.
	ModelNrPtr	Pointer to the memory where the Manufacturer's Model Number shall be stored.
	RevisionNrPtr	Pointer to the memory where the Revision Number shall be stored.
<b>Return value</b>	Std_ReturnType	E_OK: organizationally unique identifier of the Ethernet transceiver could be read. E_NOT_OK: organizationally unique identifier of the Ethernet transceiver could not be obtained (i.e. OUI is not available).
<b>Description</b>	This function retrieves the OUI (24 bit) of the indexed Ethernet switch port.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00442]** [The function `EthIf_GetSwitchPortIdentifier` shall forward the call to function `EthSwt_GetPortIdentifier` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.62 EthIf\_GetSwitchIdentifier

[SWS\_EthIf\_91121] [

<b>Service Name</b>	EthIf_GetSwitchIdentifier	
<b>Syntax</b>	Std_ReturnType EthIf_GetSwitchIdentifier ( uint8 SwitchIdx, uint32* OrgUniqueIdPtr )	
<b>Service ID [hex]</b>	0x57	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	OrgUniqueIdPtr	Pointer to the memory where the Organizationally Unique Identifier shall be stored.
<b>Return value</b>	Std_ReturnType	E_OK: organizationally unique identifier of the Ethernet switch could be read. E_NOT_OK: organizationally unique identifier of the Ethernet switch could not be read (i.e. no OUI is available for this Ethernet switch)
<b>Description</b>	Obtain the Organizationally Unique Identifier that is given by the IEEE of the indexed Ethernet switch. This function shall provide the OUI of Ethernet switch. The OUI has a size of 24 bit. If a ethernet switch can provide the OUI the 8 most significant bits of the OUI shall be set to 0x00xxxxx. If a Ethernet switch can not provide the OUI the 8 most significant bits of the OUI shall be set to 0xFFxxxxx.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00444] [The function [EthIf\\_GetSwitchIdentifier](#) shall forward the call to function [EthSwt\\_GetSwitchIdentifier](#) of the corresponding Ethernet Switch Driver (EthIfSwitchIdx).]()

### 8.3.63 EthIf\_WritePortMirrorConfiguration

[SWS\_EthIf\_91122] [

<b>Service Name</b>	EthIf_WritePortMirrorConfiguration	
<b>Syntax</b>	Std_ReturnType EthIf_WritePortMirrorConfiguration ( uint8 MirroredSwitchIdx, const EthSwt_PortMirrorCfgType* PortMirrorConfigurationPtr )	
<b>Service ID [hex]</b>	0x58	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	MirroredSwitchIdx	Index of the switch within the context of the Ethernet Switch Driver, where the Ethernet switch port is located, that has to be mirrored
	PortMirrorConfigurationPtr	-
<b>Parameters (inout)</b>	None	





<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: the port mirror configuration for the indexed Ethernet switch port was written. E_NOT_OK: the port mirror configuration for the indexed Ethernet switch port was not written. (i.e. indexed ethernet switch is not available) ETHSWT_PORT_MIRRORING_CONFIGURATION_NOT_SUPPORTED: port mirroring configuration is not supported by Ethernet switch driver or by the Ethernet switch hardware
<b>Description</b>	Store the given port mirror configuration in a shadow buffer in the Ethernet switch driver for the given MirroredSwitchIdx.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00446]** [The function [EthIf\\_WritePortMirrorConfiguration](#) shall forward the call to function `EthSwt_WritePortMirrorConfiguration` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.64 EthIf\_ReadPortMirrorConfiguration

**[SWS\_EthIf\_91123]** [

<b>Service Name</b>	EthIf_ReadPortMirrorConfiguration	
<b>Syntax</b>	Std_ReturnType EthIf_ReadPortMirrorConfiguration ( uint8 MirroredSwitchIdx, EthSwt_PortMirrorCfgType* PortMirrorConfigurationPtr )	
<b>Service ID [hex]</b>	0x59	
<b>Sync/Async</b>	Asynchronous Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	MirroredSwitchIdx	Index of the Ethernet switch within the context of the Ethernet Switch Driver, where the Ethernet switch ports are located, that have to be mirrored
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	PortMirrorConfigurationPtr	Pointer to the memory where the port configuration shall be stored.
<b>Return value</b>	Std_ReturnType	E_OK: the port mirror configuration for the indexed Ethernet switch port was red successfully. E_NOT_OK: the port mirror configuration for the indexed Ethernet switch was not red successfully. (i.e. indexed Ethernet switch is not available)
<b>Description</b>	Obtain the port mirror configuration of the given Ethernet switch.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00448]** [The function [EthIf\\_ReadPortMirrorConfiguration](#) shall forward the call to function `EthSwt_ReadPortMirrorConfiguration` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.65 EthIf\_DeletePortMirrorConfiguration

[SWS\_EthIf\_91124] [

<b>Service Name</b>	EthIf_DeletePortMirrorConfiguration	
<b>Syntax</b>	Std_ReturnType EthIf_DeletePortMirrorConfiguration ( uint8 MirroredSwitchIdx )	
<b>Service ID [hex]</b>	0x5a	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant Reentrant for different MirroredSwitchIdx. Non reentrant for the same SwitchIdx.	
<b>Parameters (in)</b>	MirroredSwitchIdx	Index of the switch within the context of the Ethernet Switch Driver.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: Port mirror configuration was deleted successfully E_NOT_OK: Port mirror configuration was not deleted successfully. (e.g. the port mirroring is enabled)
<b>Description</b>	Delete the stored port mirror configuration of the given MirroredSwitchIdx. If no port mirror configuration was found for the given MirroredSwitchIdx, the return value shall be E_OK.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00450] [The function [EthIf\\_DeletePortMirrorConfiguration](#) shall forward the call to function [EthSwt\\_DeletePortMirrorConfiguration](#) of the corresponding Ethernet Switch Driver (EthIfSwitchIdx).]()

### 8.3.66 EthIf\_GetPortMirrorState

[SWS\_EthIf\_91125] [

<b>Service Name</b>	EthIf_GetPortMirrorState	
<b>Syntax</b>	Std_ReturnType EthIf_GetPortMirrorState ( uint8 SwitchIdx, uint8 PortIdx, EthSwt_PortMirrorStateType* PortMirrorStatePtr )	
<b>Service ID [hex]</b>	0x5b	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	PortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	PortMirrorStatePtr	Pointer to the memory where the port mirroring state (either PORT_MIRRORING_ENABLED or PORT_MIRRORING_DISABLED)of the given Ethernet switch port shall be stored.





<b>Return value</b>	Std_ReturnType	E_OK: the port mirroring state for the indexed Ethernet switch port returned successfully. E_NOT_OK: the port mirror configuration for the indexed Ethernet switch returned not successfully. (i.e. indexed ethernet switch port is not available)
<b>Description</b>	Obtain the current status of the port mirroring for the indexed Ethernet switch port	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00452]** [The function `EthIf_GetPortMirrorState` shall forward the call to function `EthSwt_GetPortMirrorState` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.67 EthIf\_SetPortMirrorState

**[SWS\_EthIf\_91126]** [

<b>Service Name</b>	EthIf_SetPortMirrorState	
<b>Syntax</b>	Std_ReturnType EthIf_SetPortMirrorState ( uint8 MirroredSwitchIdx, uint8 PortIdx, EthSwt_PortMirrorStateType PortMirrorState )	
<b>Service ID [hex]</b>	0x5c	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	MirroredSwitchIdx	Index of the Ethernet switch within the context of the Ethernet Switch Driver, where the port mirroring configuration is located that has to be enabled and disabled, respectively.
	PortIdx	Index of the port at the addressed switch
	PortMirrorState	Contain the requested port mirroring state either PORT_MIRRORING_ENABLED or PORT_MIRRORING_DISABLED
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	Std_ReturnType E_OK: the requested port mirroring state for the indexed Ethernet switch port was set successfully. E_NOT_OK: the requested port mirroring state for the indexed Ethernet switch was not set successfully. (i.e. indexed Ethernet switch is not available, no port mirror configuration is available)
<b>Description</b>	Request to set the given port mirroring state of the port mirror configuration for the given Ethernet switch.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00454]** [The function `EthIf_SetPortMirrorState` shall forward the call to function `EthSwt_SetPortMirrorState` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()



### 8.3.68 EthIf\_SetPortTestMode

[SWS\_EthIf\_91127] [

<b>Service Name</b>	EthIf_SetPortTestMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetPortTestMode (     uint8 SwitchIdx,     uint8 PortIdx,     EthTrcv_PhyTestModeType Mode )</pre>	
<b>Service ID [hex]</b>	0x5d	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	PortIdx	Index of the port at the addressed switch
	Mode	Test mode to be activated
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: the port test mode for the indexed Ethernet switch port was set successfully. E_NOT_OK: the port test mode for the indexed Ethernet switch was not set successfully. (i.e. indexed Ethernet switch port is not available)
<b>Description</b>	Activates a given test mode of the indexed Ethernet switch port.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00456] [The function `EthIf_SetPortTestMode` shall forward the call to function `EthSwt_SetPortTestMode` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.69 EthIf\_SetPortLoopbackMode

[SWS\_EthIf\_91128] [

<b>Service Name</b>	EthIf_SetPortLoopbackMode	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetPortLoopbackMode (     uint8 SwitchIdx,     uint8 PortIdx,     EthTrcv_PhyLoopbackModeType Mode )</pre>	
<b>Service ID [hex]</b>	0x5e	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	PortIdx	Index of the port at the addressed switch
	Mode	Loop-back mode to be activated
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	





<b>Return value</b>	Std_ReturnType	E_OK: the port mirroring loop-back mode for the indexed Ethernet switch port was activated successfully. E_NOT_OK: the port mirroring loop-back mode for the indexed Ethernet switch port was not activated successfully. (i.e. indexed Ethernet switch port is not available)
<b>Description</b>	Activates a given test loop-back mode of the indexed Ethernet switch port.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00458]** [The function [EthIf\\_SetPortLoopbackMode](#) shall forward the call to function `EthSwt_SetPortLoopbackMode` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.70 EthIf\_SetPortTxMode

**[SWS\_EthIf\_91129]** [

<b>Service Name</b>	EthIf_SetPortTxMode	
<b>Syntax</b>	Std_ReturnType EthIf_SetPortTxMode ( uint8 SwitchIdx, uint8 PortIdx, EthTrcv_PhyTxModeType Mode )	
<b>Service ID [hex]</b>	0x5f	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	PortIdx	Index of the port at the addressed switch
	Mode	Transmission mode to be activated
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: the port Tx mode for the indexed Ethernet switch port was activated successfully. E_NOT_OK: the port Tx mode for the indexed Ethernet switch port was not activated successfully. (i.e. indexed Ethernet switch port is not available)
<b>Description</b>	Activates a given transmission mode of the indexed Ethernet switch port.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00460]** [The function [EthIf\\_SetPortTxMode](#) shall forward the call to function `EthSwt_SetPortTxMode` of the corresponding Ethernet Switch Driver (`EthIf-SwitchIdx`).]()

### 8.3.71 EthIf\_GetPortCableDiagnosticsResult

[SWS\_EthIf\_91130] [

<b>Service Name</b>	EthIf_GetPortCableDiagnosticsResult	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetPortCableDiagnosticsResult (     uint8 SwitchIdx,     uint8 PortIdx,     EthTrcv_CableDiagResultType* ResultPtr )</pre>	
<b>Service ID [hex]</b>	0x60	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	PortIdx	Index of the port at the addressed switch
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ResultPtr	Pointer to the location where the cable diagnostics result shall be stored
<b>Return value</b>	Std_ReturnType	E_OK: the port cable diagnostic result for the indexed Ethernet switch port was obtained successfully. E_NOT_OK: the port cable diagnostic result for the indexed Ethernet switch port was not obtained successfully. (i.e. indexed Ethernet switch port is not available)
<b>Description</b>	Retrieves the cable diagnostics result of the indexed Ethernet switch port respectively the referenced Ethernet Transceiver Driver.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00462] [The function `EthIf_GetPortCableDiagnosticsResult` shall forward the call to function `EthSwt_GetPortCableDiagnosticsResult` of the corresponding Ethernet Switch Driver (`EthIfSwitchIdx`).]()

### 8.3.72 EthIf\_RunPortCableDiagnostic

[SWS\_EthIf\_91131] [

<b>Service Name</b>	EthIf_RunPortCableDiagnostic	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_RunPortCableDiagnostic (     uint8 SwitchIdx,     uint8 PortIdx )</pre>	
<b>Service ID [hex]</b>	0x61	
<b>Sync/Async</b>	Asynchronous Asynchronous	
<b>Reentrancy</b>	Reentrant Reentrant for different SwitchIdx and PortIdx. Non reentrant for the same SwitchIdx and PortIdx.	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver.
	PortIdx	Index of the port at the addressed switch.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	



△

<b>Return value</b>	Std_ReturnType	E_OK: The trigger to run the cable diagnostic has been accepted E_NOT_OK: The trigger to run the cable diagnostic has not been accepted
<b>Description</b>	Trigger the cable diagnostics of the given Ethernet Switch port (PortIdx) by calling EthTrcv_RunCableDiagnostic of the referenced Ethernet transceiver.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00464]** [If the function `EthIf_RunPortCableDiagnostic` is called, EthIf shall ensure that the corresponding EthIfController is in mode `ETH_MODE_ACTIVE` and forward the call to function `EthSwt_RunPortCableDiagnostic` of the corresponding Ethernet Switch Driver (EthIfSwitchIdx).]()

### 8.3.73 EthIf\_RunCableDiagnostic

**[SWS\_EthIf\_91132]** [

<b>Service Name</b>	EthIf_RunCableDiagnostic	
<b>Syntax</b>	Std_ReturnType EthIf_RunCableDiagnostic ( uint8 TrcvIdx )	
<b>Service ID [hex]</b>	0x62	
<b>Sync/Async</b>	Asynchronous Asynchronous	
<b>Reentrancy</b>	Reentrant Reentrant for different TrcvIdx. Non reentrant for the same TrcvIdx.	
<b>Parameters (in)</b>	TrcvIdx	Index of the Ethernet transceiver within the context of the Ethernet Transceiver Driver.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The trigger has been accepted. E_NOT_OK: The trigger has not been accepted.
<b>Description</b>	Trigger the cable diagnostics for the given Ethernet transceiver.	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00466]** [If the function `EthIf_RunCableDiagnostic` is called, EthIf shall ensure that the corresponding EthIfController is in mode `ETH_MODE_ACTIVE` and forward the call to function `EthTrcv_RunCableDiagnostic` of the corresponding Ethernet Transceiver Driver (EthIfTransceiverIdx).]()

### 8.3.74 EthIf\_SwitchGetCfgDataRaw

[SWS\_EthIf\_91133] [

<b>Service Name</b>	EthIf_SwitchGetCfgDataRaw	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchGetCfgDataRaw (     uint8 SwitchIdx,     uint32 Offset,     uint16 Length,     uint8* BufferPtr )</pre>	
<b>Service ID [hex]</b>	0x63	
<b>Sync/Async</b>	Asynchronous Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the Ethernet switch within the context of the Ethernet Switch Driver
	Offset	Offset of the Ethernet switch memory from where the reading starts
	Length	Length of data in bytes that shall be copied
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	BufferPtr	Pointer to the location where the data shall be copied
<b>Return value</b>	Std_ReturnType	E_OK: the data read was triggered successfully E_NOT_OK: the data read was not triggered successfully (i.e. indexed Ethernet switch is not available)
<b>Description</b>	Retrieves the data in memory of the indexed Ethernet switch in variable length	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00468] [The function [EthIf\\_SwitchGetCfgDataRaw](#) shall forward the call to function [EthSwt\\_GetCfgDataRaw](#) of the corresponding Ethernet Switch Driver (EthIfSwitchIdx).]()

### 8.3.75 EthIf\_SwitchGetCfgDataInfo

[SWS\_EthIf\_91134] [

<b>Service Name</b>	EthIf_SwitchGetCfgDataInfo	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchGetCfgDataInfo (     uint8 SwitchIdx,     uint32* DataSizePtr,     uint32* DataAdressPtr )</pre>	
<b>Service ID [hex]</b>	0x64	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the Ethernet switch within the context of the Ethernet Switch Driver
<b>Parameters (inout)</b>	None	





<b>Parameters (out)</b>	DataSizePtr	Pointer to the location where the total size of the configuration data shall be copied
	DataAdressPtr	Pointer to the location where the start address of the configuration registers shall be copied
<b>Return value</b>	Std_ReturnType	E_OK: the data was obtained successfully E_NOT_OK: the data was not obtained successfully. (i.e. indexed Ethernet switch is not available)
<b>Description</b>	Retrieves the total size of data and the memory start address of the indexed Ethernet Switch.	
<b>Available via</b>	Ethlf.h	

]()

**[SWS\_EthIf\_00470]** [The function [EthIf\\_SwitchGetCfgDataInfo](#) shall forward the call to function [EthSwt\\_GetCfgDataInfo](#) of the corresponding Ethernet Switch Driver (EthIfSwitchIdx).]()

### 8.3.76 EthIf\_SwitchPortGetMaxFIFOBufferFillLevel

**[SWS\_EthIf\_91135]** [

<b>Service Name</b>	EthIf_SwitchPortGetMaxFIFOBufferFillLevel	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchPortGetMaxFIFOBufferFillLevel ( uint8 SwitchPortIdx, uint8 PortIdx, uint8 SwitchPortEgressFifoIdx, uint32* SwitchPortEgressFifoBufferLevelPtr )	
<b>Service ID [hex]</b>	0x65	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant Reentrant for different SwitchIdx and PortIdx. Non reentrant for the same SwitchIdx and PortIdx.	
<b>Parameters (in)</b>	SwitchPortIdx	Index of the Ethernet switch within the context of the Ethernet Switch Driver.
	PortIdx	Index of the Ethernet switch egress port at the addressed Ethernet switch.
	SwitchPortEgressFifoIdx	Index of the egress FIFO of the addressed Ethernet switch port
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	SwitchPortEgressFifoBufferLevelPtr	Pointer to a memory location, where the maximum amount of allocated FIFO buffer (in bytes) since the last read out shall be stored
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: The maximal FIFO buffer level could not be obtained
<b>Description</b>	The function retrieves the maximum amount of allocated FIFO buffer of the indexed Ethernet switch egress port. If the Ethernet switch hardware does not support Ethernet switch port based maximal FIFO buffer level, the content of SwitchPortEgressFifoBufferLevelPtr shall be set to 0xFFFFFFFF. This API may be called by e.g. a CDD.	
<b>Available via</b>	Ethlf.h	

]()

**[SWS\_EthIf\_00472]** [The function [EthIf\\_SwitchPortGetMaxFIFOBufferFillLevel](#) shall forward the call to function [EthSwt\\_GetMaxFIFOBufferFillLevel](#) of the corresponding Ethernet Switch Driver (EthIfSwitchIdx).]()

### 8.3.77 EthIf\_TransceiverGetMacMethod

[SWS\_EthIf\_91021] [

<b>Service Name</b>	EthIf_TransceiverGetMacMethod	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_TransceiverGetMacMethod (     uint8* TrcvIdx,     EthTrcv_MacMethodType* MacModePtr )</pre>	
<b>Service ID [hex]</b>	0x66	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	TrcvIdx	Index of the transceiver within the context of the Ethernet Transceiver Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	MacModePtr	ETHTRCV_MAC_TYPE_CSMA_CD: Carrier-sense multiple access with collision detection. ETHTRCV_MAC_TYPE_PLCA: Physical layer collision avoidance.
<b>Return value</b>	Std_ReturnType	E_OK: success. E_NOT_OK: transceiver request has not been accepted.
<b>Description</b>	Obtains the media access mode of the transceiver.	
<b>Available via</b>	EthIf.h	

](SRS\_Eth\_00117)

[SWS\_EthIf\_00474] [The function `EthIf_TransceiverGetMacMethod` shall forward the call to function `EthTrcv_GetMacMethod` of the corresponding Ethernet Transceiver Driver (`EthIfTransceiverIdx`).](SRS\_Eth\_00117)

[SWS\_EthIf\_00475] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00476] [If development error detection is enabled: the function shall check the parameter `TrcvIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00477] [If development error detection is enabled: the function shall check the parameter `MacModePtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

### 8.3.78 EthIf\_EthGetSpiStatus

[SWS\_EthIf\_91022]{DRAFT} [

<b>Service Name</b>	EthIf_EthGetSpiStatus (draft)	
<b>Syntax</b>	Std_ReturnType EthIf_EthGetSpiStatus ( uint8* CtrlIdx, Eth_SpiStatusType* SpiStatusPtr )	
<b>Service ID [hex]</b>	0x6a	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the controller within the context of the Ethernet controller Driver
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	SpiStatusPtr	Status of the SPI interface
<b>Return value</b>	Std_ReturnType	E_OK: success. E_NOT_OK: Controller request has not been accepted.
<b>Description</b>	When MACPHY controller are used, obtains the SPI interface status. <b>Tags:</b> atp.Status=draft	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00505]{DRAFT} [The function `EthIf_EthGetSpiStatus` shall forward the call to function `Eth_GetSpiStatus` of the corresponding Ethernet Driver (`CtrlIdx`).]()

[SWS\_EthIf\_00506]{DRAFT} [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00507]{DRAFT} [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00508]{DRAFT} [If development error detection is enabled: the function shall check the parameter `SpiStatusPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()



### 8.3.79 EthIf\_GetBufCV2xPC5RxParams

[SWS\_EthIf\_91201] [

<b>Service Name</b>	EthIf_GetBufCV2xPC5RxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetBufCV2xPC5RxParams (     uint8 CtrlId,     const CV2x_BufCV2xPC5RxParamIdType* RxParamIds,     uint16* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x60	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlId	Index of the Ethernet controller within the context of the Ethernet Interface
	RxParamIds	IDs of the Parameters to read
	NumParams	Number of Parameters
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ParamValues	Values of the Parameters requested
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed reading parameter
<b>Description</b>	Read out values related to the receive direction of the Cellular V2X for a received packet. For example, this could be CBR belonging to one single packet.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00521]{DRAFT} [The function [EthIf\\_GetBufCV2xPC5RxParams](#) shall forward the call to function [CV2x\\_GetBufCV2xPC5RxParams](#) of the respective Cellular V2X Driver.]()

[SWS\_EthIf\_00522]{DRAFT} [The function [EthIf\\_GetBufCV2xPC5RxParams](#) shall be pre compile time configurable On/Off by the configuration parameter: [EthIfEnabledCV2xApi](#).]()

[SWS\_EthIf\_00523]{DRAFT} [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

[SWS\_EthIf\_00524]{DRAFT} [If development error detection is enabled: the function shall check the parameter [CtrlIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_CTRL\\_IDX](#).]()

[SWS\_EthIf\_00525]{DRAFT} [If development error detection is enabled: the function shall check the parameter [RxParamIds](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

[SWS\_EthIf\_00526]{DRAFT} [If development error detection is enabled: the function shall check the parameter [ParamValues](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]() Note: The function requires previous transmission ([EthIf\\_RxIndication](#)).

### 8.3.80 EthIf\_GetBufCV2xPC5TxParams

[SWS\_EthIf\_91202] [

<b>Service Name</b>	EthIf_GetBufCV2xPC5TxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetBufCV2xPC5TxParams (     uint8 CtrlId,     const CV2x_BufCV2xPC5TxParamIdType* TxParamIds,     uint16* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x61	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlId	Index of the Ethernet controller within the context of the Ethernet Interface
	TxParamIds	IDs of the Parameter to get
	NumParams	Number of Parameters
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ParamValues	Values of the Parameters requested
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed reading parameter
<b>Description</b>	Read out values related to the transmit direction of the Cellular V2X for a transmitted packet. For example, this could be transaction ID belonging to one single packet.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00531]{DRAFT} [The function [EthIf\\_GetBufCV2xPC5TxParams](#) shall forward the call to function [CV2x\\_GetBufCV2xPC5TxParams](#) of the respective Cellular V2X Driver.]()

[SWS\_EthIf\_00532]{DRAFT} [The function [EthIf\\_GetBufCV2xPC5TxParams](#) shall be pre compile time configurable On/Off by the configuration parameter: [EthIfEnabledCV2xApi](#).]()

[SWS\_EthIf\_00533]{DRAFT} [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

[SWS\_EthIf\_00534]{DRAFT} [If development error detection is enabled: the function shall check the parameter [CtrlIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_CTRL\\_IDX](#).]()

[SWS\_EthIf\_00535]{DRAFT} [If development error detection is enabled: the function shall check the parameter [TxParamIds](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

[SWS\_EthIf\_00536]{DRAFT} [If development error detection is enabled: the function shall check the parameter [ParamValues](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]() Note: The function requires previous transmission ([EthIf\\_Transmit](#)).

### 8.3.81 EthIf\_SetBufCV2xPC5TxParams

[SWS\_EthIf\_91203] [

<b>Service Name</b>	EthIf_SetBufCV2xPC5TxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SetBufCV2xPC5TxParams (     uint8 CtrlId,     uint8 BufIdx,     const CV2x_BufCV2xPC5TxParamIdType* TxParamIds,     const uint16* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x62	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlId	Index of the Ethernet controller within the context of the Ethernet Interface
	BufIdx	Index of the buffer resource
	TxParamIds	IDs of the Parameter to set
	ParamValues	Value of the Parameter to set
	NumParams	Number of Parameters
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed setting parameter
<b>Description</b>	Set values related to the transmit direction of the Cellular V2X for a specific buffer (packet to be sent). For example, this can be the desired ProSe per-packet priority belonging to one single packet.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00541]{DRAFT} [The function [EthIf\\_SetBufCV2xPC5TxParams](#) shall forward the call to function [CV2x\\_SetBufCV2xPC5TxParams](#) of the respective Cellular V2X Driver.]()

[SWS\_EthIf\_00542]{DRAFT} [The function [EthIf\\_SetBufCV2xPC5TxParams](#) shall be pre compile time configurable On/Off by the configuration parameter: [EthIfEnableCV2xApi](#).]()

[SWS\_EthIf\_00543]{DRAFT} [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

[SWS\_EthIf\_00544]{DRAFT} [If development error detection is enabled: the function shall check the parameter [CtrlIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_CTRL\\_IDX](#).]()

[SWS\_EthIf\_00545]{DRAFT} [If development error detection is enabled: the function shall check the parameter [BufIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

[SWS\_EthIf\_00546]{DRAFT} [If development error detection is enabled: the function shall check the parameter [TxParamIds](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_PARAM\\_POINTER](#).]()

[SWS\_EthIf\_00547]{DRAFT} [If development error detection is enabled: the function shall check the parameter `ParamValues` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

Note: The function requires previous transmission (`EthIf_ProvideTxBuffer`).

### 8.3.82 EthIf\_GetChanCV2xPC5TxParams

[SWS\_EthIf\_91204] [

<b>Service Name</b>	EthIf_GetChanCV2xPC5TxParams	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_GetChanCV2xPC5TxParams (     uint8 CtrlId,     uint8 ChannelId,     const CV2x_GetChanTxParamIdType* ParamIds,     uint32* ParamValues,     uint8 NumParams )</pre>	
<b>Service ID [hex]</b>	0x63	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlId	Index of the controller within the context of the Cellular V2X Driver (Transceiver Id)
	ChannelId	Index of Transceiver's Radio Channel
	ParamIds	IDs of the Parameters to read
	NumParams	Number of parameters to read
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	ParamValues	Value of the requested Parameters
<b>Return value</b>	Std_ReturnType	E_OK: success E_NOT_OK: failed setting parameter
<b>Description</b>	Read values related to the receive direction of the channel. For example, this could be a Channel Busy Ratio(CBR)	
<b>Available via</b>		

]()

[SWS\_EthIf\_00551]{DRAFT} [The function `EthIf_GetChanCV2xPC5TxParams` shall forward the call to function `Cv2x_GetChanTxParams` of the respective Cellular V2X Driver.]()

[SWS\_EthIf\_00552]{DRAFT} [The function `EthIf_GetChanCV2xPC5TxParams` shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableCV2xApi`.]()

[SWS\_EthIf\_00553]{DRAFT} [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00554]{DRAFT} [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00555]{DRAFT} [If development error detection is enabled: the function shall check the parameter `ChannelId` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_PARAM.` ]()

[SWS\_EthIf\_00556]{DRAFT} [If development error detection is enabled: the function shall check the parameter `ParamIds` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER.` ]()

[SWS\_EthIf\_00557]{DRAFT} [If development error detection is enabled: the function shall check the parameter `ParamValues` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER.` ]()

### 8.3.83 EthIf\_SwitchMacSecUpdateSecY

[SWS\_EthIf\_91219]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecUpdateSecY (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchMacSecUpdateSecY (     const EthSwt_MgmtInfoType* MgmtInfoPtr,     const Mka_MacSecConfigType* MACsecCfgPtr,     uint64 TxSci )</pre>	
<b>Service ID [hex]</b>	0x6d	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	MACsecCfgPtr	Pointer to the structure to configure a MACsec Entity (SecY)
	TxSci	Secure Channel Identifier for the MACsec's Transmission Secure channel
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	<p>Requests the Ethernet Switch to update the SecY/PAC of the the provided port with the provided parameters. A Transmission Secure Channel with the provided SCI shall be configured during the first call. A pointer to a MACsec Basic Parameters Configuration file shall be provided to create the Secure Channel.</p> <p><b>Tags:</b> atp.Status=DRAFT</p>	
<b>Available via</b>	EthIf.h	

]()

### 8.3.84 EthIf\_MacSecUpdateSecY

[SWS\_EthIf\_91215]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecUpdateSecY (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_MacSecUpdateSecY (     uint8 CtrlIdx,     const Mka_MacSecConfigType* MACsecCfgPtr,     uint64 TxSci )</pre>	
<b>Service ID [hex]</b>	0x88	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	MACsecCfgPtr	Pointer to the structure to configure a MACsec Entity (SecY)
	TxSci	Secure Channel Identifier for the MACsec's Transmission Secure channel
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver to update the SecY/PAC of the PHY with the provided parameters. A Transmission Secure Channel with the provided SCI shall be configured during the first call. A pointer to a MACsec Basic Parameters Configuration file shall be provided to create the Secure Channel. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.85 EthIf\_SwitchMacSecUpdateSecYNotification

[SWS\_EthIf\_91217]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecUpdateSecYNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_SwitchMacSecUpdateSecYNotification (     const EthSwt_MgmtInfoType* MgmtInfoPtr )</pre>	
<b>Service ID [hex]</b>	0x6b	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	





<b>Description</b>	Callback to notify that Ehtlf_SwitchMacSecUpdateSecY finished. <b>Tags:</b> atp.Status=DRAFT
<b>Available via</b>	Ethlf.h

]()

### 8.3.86 Ethlf\_MacSecUpdateSecYNotification

[SWS\_Ethlf\_91218]{DRAFT} [

<b>Service Name</b>	Ethlf_MacSecUpdateSecYNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_MacSecUpdateSecYNotification (     uint8 CtrlIdx )</pre>	
<b>Service ID [hex]</b>	0x6c	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Callback to notify that Ehtlf_SwitchMacSecUpdateSecY finished. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	Ethlf.h	

]()

### 8.3.87 Ethlf\_SwitchMacSecInitRxSc

[SWS\_Ethlf\_91220]{DRAFT} [

<b>Service Name</b>	Ethlf_SwitchMacSecInitRxSc (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchMacSecInitRxSc (     const EthSwt_MgmtInfoType* MgmtInfoPtr,     uint64 Sci )</pre>	
<b>Service ID [hex]</b>	0x6e	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of Ethlf, PortIdx in context of EthSwt.
	Sci	Secure Channel Identifier for the MACsec's Reception Secure channel
<b>Parameters (inout)</b>	None	





<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests the Ethernet Switch Driver to configure a Reception Secure Channel for the given Secure Channel Identifier. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.88 EthIf\_MacSecInitRxSc

[SWS\_EthIf\_91211]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecInitRxSc (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecInitRxSc ( uint8 CtrlIdx, uint64 Sci )	
<b>Service ID [hex]</b>	0x87	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	Sci	Secure Channel Identifier for the MACsec's Reception Secure channel
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to configure a Reception Secure Channel for the given Secure Channel Identifier. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.89 EthIf\_SwitchMacSecResetRxSc

[SWS\_EthIf\_91221]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecResetRxSc (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchMacSecResetRxSc ( const EthSwt_MgmtInfoType* MgmtInfoPtr, uint64 Sci )	
<b>Service ID [hex]</b>	0x6f	







<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	Sci	Secure Channel Identifier for the MACsec's Reception Secure channel
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests the Ethernet Switch Driver to reset to default the MACsec values of the Reception Secure Channel for the given Secure Channel Identifier. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.90 EthIf\_MacSecResetRxSc

[SWS\_EthIf\_91213]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecResetRxSc (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecResetRxSc ( uint8 CtrlIdx, uint64 Sci )	
<b>Service ID [hex]</b>	0x86	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	Sci	Secure Channel Identifier for the MACsec's Reception Secure channel
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to reset to default the MACsec values of the Reception Secure Channel for the given Secure Channel Identifier. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.91 EthIf\_SwitchMacSecAddTxSa

[SWS\_EthIf\_91222]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecAddTxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchMacSecAddTxSa (     const EthSwt_MgmtInfoType* MgmtInfoPtr,     uint8 An,     uint64 NextPn,     uint32 Ssci,     const Mka_SakKeyPtrType* KeysPtr,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x70	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	An	Association Number to use in the MACsec's transmission secure association
	NextPn	Next accepted Packet Number in the MACsec's transmission secure association
	Ssci	Short Secure Channel Identifier used in the MACsec's transmission secure association
	KeysPtr	Pointer to the SAKs Key (and needed Key information) to use in the MACsec's transmission secure association
	Active	Boolean to enable/disable the MACsec's transmission secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests the Ethernet Switch Driver to create a Transmission Secure Association in the provided port. The Short Secure Channel Identifier is included to support XPN configurations. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.92 EthIf\_MacSecAddTxSa

[SWS\_EthIf\_91206]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecAddTxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_MacSecAddTxSa (     uint8 CtrlIdx,     uint8 An,     uint64 NextPn,     uint32 Ssci,     const Mka_SakKeyPtrType* KeysPtr,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x85	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	An	Association Number to use in the MACsec's transmission secure association
	NextPn	Next accepted Packet Number in the MACsec's transmission secure association
	Ssci	Short Secure Channel Identifier used in the MACsec's transmission secure association
	KeysPtr	Pointer to the SAKs Key (and needed Key information) to use in the MACsec's transmission secure association
	Active	Boolean to enable/disable the MACsec's transmission secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	<p>Requests the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to create a Transmission Secure Association in the Transceiver. The Short Secure Channel Identifier is included to support XPN configurations.</p> <p><b>Tags:</b> atp.Status=DRAFT</p>	
<b>Available via</b>	EthIf.h	

]()

### 8.3.93 EthIf\_SwitchMacSecAddTxSaNotification

[SWS\_EthIf\_91223]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecAddTxSaNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_SwitchMacSecAddTxSaNotification (     const EthSwt_MgmtInfoType* MgmtInfoPtr )</pre>	
<b>Service ID [hex]</b>	0x71	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	





<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwT.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Callback to notify that EthIf_SwitchMacSecAddTxSa finished. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.94 EthIf\_MacSecAddTxSaNotification

[SWS\_EthIf\_91224]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecAddTxSaNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_MacSecAddTxSaNotification (     uint8 CtrlIdx )</pre>	
<b>Service ID [hex]</b>	0x72	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Callback to notify that EthIf_MacSecAddTxSa finished. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.95 EthIf\_SwitchMacSecUpdateTxSa

[SWS\_EthIf\_91225]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecUpdateTxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchMacSecUpdateTxSa (     const EthSwT_MgmtInfoType* MgmtInfoPtr,     uint8 An,     uint64 NextPn,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x73	





<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwT.
	An	Association Number to use in the MACsec's transmission secure association
	NextPn	Next accepted Packet Number in the MACsec's transmission secure association
	Active	Boolean to enable/disable the MACsec's transmission secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests the Ethernet Switch Driver to update the Transmission Secure Association with the given Packet Number. The Active parameter is included to change the specified AN status. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.96 EthIf\_MacSecUpdateTxSa

[SWS\_EthIf\_91216]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecUpdateTxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_MacSecUpdateTxSa (     uint8 CtrlIdx,     uint8 An,     uint64 NextPn,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x84	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	An	Association Number to use in the MACsec's transmission secure association
	NextPn	Next accepted Packet Number in the MACsec's transmission secure association
	Active	Boolean to enable/disable the MACsec's transmission secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted





<b>Description</b>	Requests the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to update the Transmission Secure Association with the given Packet Number. The Active parameter is included to change the specified AN status. <b>Tags:</b> atp.Status=DRAFT
<b>Available via</b>	EthIf.h

]()

### 8.3.97 EthIf\_SwitchMacSecDeleteTxSa

[SWS\_EthIf\_91226]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecDeleteTxSa (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchMacSecDeleteTxSa ( const EthSwt_MgmtInfoType* MgmtInfoPtr, uint8 An )	
<b>Service ID [hex]</b>	0x74	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	An	Association Number to use in the MACsec's transmission secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Switch Driver to remove the Transmission Secure Association identified by the provided Association Number. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.98 EthIf\_MacSecDeleteTxSa

[SWS\_EthIf\_91208]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecDeleteTxSa (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecDeleteTxSa ( uint8 CtrlIdx, uint8 An )	
<b>Service ID [hex]</b>	0x16	
<b>Sync/Async</b>	Synchronous	





<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	An	Association Number to use in the MACsec's transmission secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to remove the Transmission Secure Association identified by the provided Association Number. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.99 EthIf\_SwitchMacSecAddRxSa

[SWS\_EthIf\_91227]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecAddRxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchMacSecAddRxSa (     const EthSwt_MgmtInfoType* MgmtInfoPtr,     uint8 An,     uint64 LowestPn,     uint32 Ssci,     const Mka_SakKeyPtrType* KeysPtr,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x75	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	An	Association Number to use in the MACsec's reception secure association
	LowestPn	Lowest accepted Packet Number in the MACsec's reception secure association
	Ssci	Short Secure Channel Identifier used in the MACsec's reception secure association
	KeysPtr	Pointer to the SAKs Key (and needed Key information) to use in the MACsec's reception secure association
	Active	Boolean to enable/disable the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted



△

<b>Description</b>	Request the Ethernet Switch Driver to create a Reception Secure Association in the provided Port. The Short Secure Channel Identifier is included to support XPN configurations. <b>Tags:</b> atp.Status=DRAFT
<b>Available via</b>	EthIf.h

]()

### 8.3.100 EthIf\_MacSecAddRxSa

[SWS\_EthIf\_91205]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecAddRxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_MacSecAddRxSa (     uint8 CtrlIdx,     uint8 An,     uint64 LowestPn,     uint32 Ssci,     const Mka_SakKeyPtrType* KeysPtr,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x83	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	An	Association Number to use in the MACsec's reception secure association
	LowestPn	Lowest accepted Packet Number in the MACsec's reception secure association
	Ssci	Short Secure Channel Identifier used in the MACsec's reception secure association
	KeysPtr	Pointer to the SAKs Key (and needed Key information) to use in the MACsec's reception secure association
	Active	Boolean to enable/disable the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to create a Reception Secure Association in the Transceiver. The Short Secure Channel Identifier is included to support XPN configurations. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()



### 8.3.101 EthIf\_SwitchMacSecAddRxSaNotification

[SWS\_EthIf\_91228]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecAddRxSaNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_SwitchMacSecAddRxSaNotification (     const EthSwt_MgmtInfoType* MgmtInfoPtr )</pre>	
<b>Service ID [hex]</b>	0x76	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Callback to notify that EthIf_SwitchMacSecAddRxSa finished. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.102 EthIf\_MacSecAddRxSaNotification

[SWS\_EthIf\_91229]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecAddRxSaNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_MacSecAddRxSaNotification (     uint8 CtrlIdx )</pre>	
<b>Service ID [hex]</b>	0x77	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Callback to notify that EthIf_MacSecAddRxSa finished. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.103 EthIf\_SwitchMacSecUpdateRxSa

[SWS\_EthIf\_91230]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecUpdateRxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchMacSecUpdateRxSa (     const EthSwt_MgmtInfoType* MgmtInfoPtr,     uint8 An,     uint64 LowestPn,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x78	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	An	Association Number to use in the MACsec's reception secure association
	LowestPn	Lowest accepted Packet Number in the MACsec's reception secure association
	Active	Boolean to enable/disable the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Switch Driver to update the Reception Secure Association with the given Packet Number. The Active parameter is included to change the specified AN status. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.104 EthIf\_MacSecUpdateRxSa

[SWS\_EthIf\_91214]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecUpdateRxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_MacSecUpdateRxSa (     uint8 CtrlIdx,     uint8 An,     uint64 LowestPn,     boolean Active )</pre>	
<b>Service ID [hex]</b>	0x82	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface





	An	Association Number to use in the MACsec's reception secure association
	LowestPn	Lowest accepted Packet Number in the MACsec's reception secure association
	Active	Boolean to enable/disable the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to update the Reception Secure Association with the given Packet Number. The Active parameter is included to change the specified AN status. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

}]()

### 8.3.105 EthIf\_SwitchMacSecDeleteRxSa

[SWS\_EthIf\_91231]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecDeleteRxSa (DRAFT)	
<b>Syntax</b>	<pre>Std_ReturnType EthIf_SwitchMacSecDeleteRxSa (     const EthSwt_MgmtInfoType* MgmtInfoPtr,     uint8 An )</pre>	
<b>Service ID [hex]</b>	0x79	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	An	Association Number to use in the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Switch Driver to remove the Reception Secure Association identified by the provided Association Number. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

}]()

### 8.3.106 EthIf\_MacSecDeleteRxSa

[SWS\_EthIf\_91207]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecDeleteRxSa (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecDeleteRxSa ( uint8 CtrlIdx, uint8 An )	
<b>Service ID [hex]</b>	0x81	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	An	Association Number to use in the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to remove the Reception Secure Association identified by the provided Association Number. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.107 EthIf\_SwitchMacSecGetTxSaNextPn

[SWS\_EthIf\_91232]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecGetTxSaNextPn (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchMacSecGetTxSaNextPn ( const EthSwt_MgmtInfoType* MgmtInfoPtr, uint8 An, uint64* NextPnPtr )	
<b>Service ID [hex]</b>	0x7a	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	An	Association Number to use in the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	NextPnPtr	Pointer to the Next Packet Number read out from the MACsec Entity (SecY)
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted





<b>Description</b>	Request the Ethernet Switch Driver to return the Packet Number that is used for the next packet in the given Transmission Secure Association. <b>Tags:</b> atp.Status=DRAFT
<b>Available via</b>	EthIf.h

]()

### 8.3.108 EthIf\_MacSecGetTxSaNextPn

[SWS\_EthIf\_91210]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecGetTxSaNextPn (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecGetTxSaNextPn ( uint8 CtrlIdx, uint8 An, uint64* NextPnPtr )	
<b>Service ID [hex]</b>	0x90	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	An	Association Number to use in the MACsec's reception secure association
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	NextPnPtr	Pointer to the Next Packet Number read out from the MACsec Entity (SecY)
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to return the Packet Number that is used for the next packet in the given Transmission Secure Association. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.109 EthIf\_SwitchMacSecGetMacSecStats

[SWS\_EthIf\_91233]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecGetMacSecStats (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchMacSecGetMacSecStats ( const EthSwt_MgmtInfoType* MgmtInfoPtr )	
<b>Service ID [hex]</b>	0x7b	
<b>Sync/Async</b>	Asynchronous	





<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwT.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet switch Driver to provide MACsec statistics. The result is returned through EthIf_SwitchMacSecGetMacSecStatsNotification. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.110 EthIf\_MacSecGetMacSecStats

[SWS\_EthIf\_91209]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecGetMacSecStats (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecGetMacSecStats ( uint8 CtrlIdx )	
<b>Service ID [hex]</b>	0x89	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Request the Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver to provide MACsec statistics. The result is returned through EthIf_MacSecGetMacSecStatsNotification <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.111 EthIf\_SwitchMacSecGetMacSecStatsNotification

[SWS\_EthIf\_91234]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecGetMacSecStatsNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_SwitchMacSecGetMacSecStatsNotification (     const EthSwt_MgmtInfoType* MgmtInfoPtr,     const Mka_Stats_SecYType* MacSecStatsPtr )</pre>	
<b>Service ID [hex]</b>	0x7c	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	MacSecStatsPtr	Pointer to a structure including the MACsec statistics of an MKA participant
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Callback to notify that EthIf_SwitchMacSecGetMacSecStats finished and provide the requested statistics. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.112 EthIf\_MacSecGetMacSecStatsNotification

[SWS\_EthIf\_91235]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecGetMacSecStatsNotification (DRAFT)	
<b>Syntax</b>	<pre>void EthIf_MacSecGetMacSecStatsNotification (     uint8 CtrlIdx,     const Mka_Stats_SecYType* MacSecStatsPtr )</pre>	
<b>Service ID [hex]</b>	0x7d	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	MacSecStatsPtr	Pointer to a structure including the MACsec statistics of an MKA participant
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Callback to notify that EthIf_MacSecGetMacSecStats finished and provide the requested statistics. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.113 EthIf\_SwitchMacSecOperational

[SWS\_EthIf\_91236]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecOperational (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchMacSecOperational ( const EthSwt_MgmtInfoType* MgmtInfoPtr, boolean MacSecOperational )	
<b>Service ID [hex]</b>	0x7e	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	MacSecOperational	Boolean to notify if MACsec is operational
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	To inform EthIf that MacSec is operational and that EthSM can be notified. (Switch case) <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.114 EthIf\_MacSecOperational

[SWS\_EthIf\_91212]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecOperational (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecOperational ( uint8 CtrlIdx, boolean MacSecOperational )	
<b>Service ID [hex]</b>	0x1c	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	MacSecOperational	Boolean to notify if MACsec is operational
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	To inform EthIf that MacSec is operational and that EthSM can be informed. (Ethernet Interface (MACsec per SW) or the Ethernet Transceiver Driver) <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()



### 8.3.115 EthIf\_SwitchMacSecSetControlledPortEnabled

[SWS\_EthIf\_91237]{DRAFT} [

<b>Service Name</b>	EthIf_SwitchMacSecSetControlledPortEnabled (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_SwitchMacSecSetControlledPortEnabled ( const EthSwt_MgmtInfoType* MgmtInfoPtr, boolean ControlledPortEnabled )	
<b>Service ID [hex]</b>	0x7f	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different MgmtInfoPtr, Non reentrant for the same MgmtInfoPtr	
<b>Parameters (in)</b>	MgmtInfoPtr	Pointer to the management information within the context of an Ethernet Switch Driver. SwitchIdx in context of EthIf, PortIdx in context of EthSwt.
	ControlledPortEnabled	Boolean to activate the Controlled Port of the PAE
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests to set the Controlled Port enabled parameter of a PAE. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

### 8.3.116 EthIf\_MacSecSetControlledPortEnabled

[SWS\_EthIf\_91238]{DRAFT} [

<b>Service Name</b>	EthIf_MacSecSetControlledPortEnabled (DRAFT)	
<b>Syntax</b>	Std_ReturnType EthIf_MacSecSetControlledPortEnabled ( uint8 CtrlIdx, boolean ControlledPortEnabled )	
<b>Service ID [hex]</b>	0x80	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant for different CtrlIdx, Non reentrant for the same CtrlIdx	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	ControlledPortEnabled	Boolean to activate the Controlled Port of the PAE
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	Std_ReturnType	E_OK: The request has been accepted E_NOT_OK: The request has not been accepted
<b>Description</b>	Requests to set the Controlled Port enabled parameter of a PAE. <b>Tags:</b> atp.Status=DRAFT	
<b>Available via</b>	EthIf.h	

]()

## 8.4 Callback notifications

This is a list of functions provided for other modules.

### 8.4.1 EthIf\_RxIndication

[SWS\_EthIf\_00085] [

<b>Service Name</b>	EthIf_RxIndication	
<b>Syntax</b>	<pre>void EthIf_RxIndication (     uint8 CtrlIdx,     Eth_FrameType FrameType,     boolean IsBroadcast,     const uint8* PhysAddrPtr,     const Eth_DataType* DataPtr,     uint16 LenByte )</pre>	
<b>Service ID [hex]</b>	0x10	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the physical Ethernet controller within the context of the Ethernet Interface
	FrameType	Frame type of received Ethernet frame
	IsBroadcast	parameter to indicate a broadcast frame
	PhysAddrPtr	Pointer to Physical source address (MAC address in network byte order) of received Ethernet frame
	DataPtr	Pointer to payload of received Ethernet frame.
	LenByte	Length (bytes) of the payload in received frame.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Handles a received frame received by the indexed controller	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00086] [If development error detection is enabled: the function shall check that the service `EthIf_Init` was previously called. If the check fails, the function shall raise the development error `ETHIF_E_UNINIT`.]()

[SWS\_EthIf\_00087] [If development error detection is enabled: the function shall check the parameter `CtrlIdx` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_INV_CTRL_IDX`.]()

[SWS\_EthIf\_00088] [If development error detection is enabled: the function shall check the parameter `DataPtr` for being valid. If the check fails, the function shall raise the development error `ETHIF_E_PARAM_POINTER`.]()

[SWS\_EthIf\_00151] [The Ethernet Driver shall indicate broadcast message with the parameter `IsBroadcast` to the Ethernet Interface.]()

**[SWS\_EthIf\_00145]** [If the VLAN is not active the Ethernet Interface shall increment the corresponding measurement data and filter the message.]()

## 8.4.2 EthIf\_TxConfirmation

**[SWS\_EthIf\_00091]** [

<b>Service Name</b>	EthIf_TxConfirmation	
<b>Syntax</b>	<pre>void EthIf_TxConfirmation (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx,     Std_ReturnType Result )</pre>	
<b>Service ID [hex]</b>	0x11	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	CtrlIdx	Index of the physical Ethernet controller within the context of the Ethernet Interface
	BufIdx	Index of the transmitted buffer
	Result	E_OK: The transmission was successful, E_NOT_OK: The transmission failed.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Confirms frame transmission by the indexed controller	
<b>Available via</b>	EthIf.h	

]()

**[SWS\_EthIf\_00255]** [[EthIf\\_TxConfirmation](#) shall pass the Result received within [EthIf\\_TxConfirmation](#) to the configured upper layer via `<UL>_TxConfirmation`.]()

**[SWS\_EthIf\_00092]** [If development error detection is enabled: the function shall check that the service [EthIf\\_Init](#) was previously called. If the check fails, the function shall raise the development error [ETHIF\\_E\\_UNINIT](#).]()

**[SWS\_EthIf\_00093]** [If development error detection is enabled: the function shall check the parameter [CtrlIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_CTRL\\_IDX](#).]()

**[SWS\_EthIf\_00094]** [If development error detection is enabled: the function shall check the parameter [BufIdx](#) for being valid. If the check fails, the function shall raise the development error [ETHIF\\_E\\_INV\\_PARAM](#).]()

### 8.4.3 EthIf\_CtrlModeIndication

[SWS\_EthIf\_00231] [

<b>Service Name</b>	EthIf_CtrlModeIndication	
<b>Syntax</b>	<pre>void EthIf_CtrlModeIndication (     uint8 CtrlIdx,     Eth_ModeType CtrlMode )</pre>	
<b>Service ID [hex]</b>	0x0e	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant for the same CtrlIdx, reentrant for different	
<b>Parameters (in)</b>	CtrlIdx	Index of the physical Ethernet controller within the context of the Ethernet Interface
	CtrlMode	Notified Ethernet controller mode
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Called asynchronously when mode has been read out. Triggered by previous <EthDrv>_Set ControllerMode call. Can directly be called within the trigger functions.	
<b>Available via</b>	EthIf.h	

]()

[SWS\_EthIf\_00252] [The function shall call EthSM\_CtrlModeIndication.]()

### 8.4.4 EthIf\_TrvcModeIndication

[SWS\_EthIf\_00232] [

<b>Service Name</b>	EthIf_TrvcModeIndication	
<b>Syntax</b>	<pre>void EthIf_TrvcModeIndication (     uint8 TrcvIdx,     Eth_ModeType TrcvMode )</pre>	
<b>Service ID [hex]</b>	0x0f	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Non Reentrant for the same CtrlIdx, reentrant for different	
<b>Parameters (in)</b>	TrcvIdx	Index of the Ethernet transceiver within the context of the Ethernet Interface
	TrcvMode	Notified Ethernet transceiver mode
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Called asynchronously when a mode change has been read out. If the function is triggered by previous call of EthTrcv_SetTransceiverMode it can directly be called within the trigger function.	
<b>Available via</b>	EthIf.h	

]()

### 8.4.5 EthIf\_SwitchPortModeIndication

[SWS\_EthIf\_91055] [

<b>Service Name</b>	EthIf_SwitchPortModeIndication	
<b>Syntax</b>	<pre>void EthIf_SwitchPortModeIndication (     uint8 SwitchIdx,     uint8 SwitchPortIdx,     Eth_ModeType PortMode )</pre>	
<b>Service ID [hex]</b>	0x46	
<b>Sync/Async</b>	Asynchronous	
<b>Reentrancy</b>	Non Reentrant	
<b>Parameters (in)</b>	SwitchIdx	Index of the switch within the context of the Ethernet Switch Driver
	SwitchPortIdx	Index of the port at the addressed switch.
	PortMode	Notified Ethernet Switch port mode.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	<p>The EthIf shall determine the expected notifications based on the EthSwtPort configuration. In case the EthSwtPort references an EthTrcv the EthIf expects a notification from the EthTrcv via API EthIf_TrvcModeIndication(). Otherwise the EthIf expects a notification from the EthSwt via API EthIf_SwitchPortModeIndication()</p>	
<b>Available via</b>	EthIf.h	

]()

### 8.4.6 EthIf\_SleepIndication

[SWS\_EthIf\_91006]{DRAFT} [

<b>Service Name</b>	EthIf_SleepIndication (draft)	
<b>Syntax</b>	<pre>void EthIf_SleepIndication (     uint8 TrcvIdx )</pre>	
<b>Service ID [hex]</b>	0x68	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Reentrant	
<b>Parameters (in)</b>	TrcvIdx	Index of the Ethernet transceiver within the context of the Ethernet Interface
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	<p>This API is called by the corresponding EthTrcv, if a sleep indication was detected on the network. This could be used e.g. for Ethernet hardware which is compliant to the OA TC10. In this case the Ethernet hardware (PHY) detect an Sleep.Indication which was triggered by a Sleep.Request of the connected link partner.</p> <p><b>Tags:</b> atp.Status=draft</p>	
<b>Available via</b>	EthIf.h	

] ([SRS\\_Eth\\_00156](#))

[SWS\_EthIf\_00497]{DRAFT} [The function shall call `EthSM_SleepIndication` with the corresponding `EthIfCtrl`.] ([SRS\\_Eth\\_00156](#))

## 8.5 Scheduled functions

These functions are directly called by Basic Software Scheduler. The following functions shall have no return value and no parameter. All functions shall be non reentrant.

### 8.5.1 EthIf\_MainFunctionRx

[SWS\_EthIf\_00097] [

<b>Service Name</b>	EthIf_MainFunctionRx
<b>Syntax</b>	<pre>void EthIf_MainFunctionRx (     void )</pre>
<b>Service ID [hex]</b>	0x20
<b>Description</b>	The function checks for new received frames and issues reception indications in polling mode.
<b>Available via</b>	SchM_EthIf.h

]()

[SWS\_EthIf\_00099] [The receive frame check shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableRxInterrupt`.]()

### 8.5.2 EthIf\_MainFunctionRx\_<PriorityProcessing ShortName>

[SWS\_EthIf\_91051] [

<b>Service Name</b>	EthIf_MainFunctionRx_<PriorityProcessing ShortName>
<b>Syntax</b>	<pre>void EthIf_MainFunctionRx_&lt;PriorityProcessing ShortName&gt; (     void )</pre>
<b>Service ID [hex]</b>	0x42
<b>Description</b>	The function checks for new received frames at the related Ethernet controller or CanXL controller and reception queue by calling <code>&lt;EthDrv&gt;_Receive()</code> with the respective <code>FifIdx</code> . <code>EthIf_MainFunctionRx</code> shall receive frames from all FIFOs that are not assigned for processing via <code>EthIfPhysCtrlRxMainFunctionPriorityProcessing</code> .
<b>Available via</b>	EthIf_SchM.h

]()

### 8.5.3 EthIf\_MainFunctionTx

[SWS\_EthIf\_00113] [

<b>Service Name</b>	EthIf_MainFunctionTx
<b>Syntax</b>	void EthIf_MainFunctionTx ( void )
<b>Service ID [hex]</b>	0x21
<b>Description</b>	The function issues transmission confirmations in polling mode. It checks also for transceiver state changes.
<b>Available via</b>	SchM_EthIf.h

]()

[SWS\_EthIf\_00100] [The transmission confirmation check shall be pre compile time configurable On/Off by the configuration parameter: `EthIfEnableTxInterrupt`.]()

[SWS\_EthIf\_00101] [The frequency of polling the transceiver state change shall be configurable by the configuration parameter: `EthIfTrcvLinkStateChgMain-Reload`.]()

### 8.5.4 EthIf\_MainFunctionState

[SWS\_EthIf\_91104] [

<b>Service Name</b>	EthIf_MainFunctionState
<b>Syntax</b>	void EthIf_MainFunctionState ( void )
<b>Service ID [hex]</b>	0x05
<b>Sync/Async</b>	Asynchronous
<b>Reentrancy</b>	Non Reentrant
<b>Parameters (in)</b>	None
<b>Parameters (inout)</b>	None
<b>Parameters (out)</b>	None
<b>Return value</b>	None
<b>Description</b>	The function is polling different communication hardware (Ethernet transceiver, Ethernet switch ports) related information, e.g. link state, signal quality.
<b>Available via</b>	EthIf_SchM.h

]()

[SWS\_EthIf\_00407] [The function `EthIf_MainFunctionState` shall poll Ethernet communication hardware related information with the period of `EthIfMainFunction-StatePeriod`.]()

[SWS\_EthIf\_00408] [For each Ethernet switch port where a link state `ETHTRCV_LINK_STATE_ACTIVE` is yielded and references an Ethernet Transceiver the function shall poll the signal quality by calling `EthSwt_GetPortSignalQuality`.]()

**[SWS\_EthIf\_00409]** [For each Ethernet transceiver where a link state of `ETHTRCV_LINK_STATE_ACTIVE` is yielded the function shall poll the signal quality by calling `EthTrcv_GetPhySignalQuality.()`]

**[SWS\_EthIf\_00410]** [The obtained signal quality value shall be stored as type of `EthIf_SignalQualityResultType`. The value shall always be stored as `ActualSignalQuality`. If the obtained signal quality is higher than the stored highest signal quality (`HighestSignalQuality`), then `HighestSignalQuality` shall be updated with the obtained signal quality. If the obtained signal quality is lower than the lowest signal quality (`LowestSignalQuality`), then `LowestSignalQuality` shall be updated with the obtained signal quality.]

**[SWS\_EthIf\_00498]** [EthIf shall check its maintained Ethernet hardware (Ethernet switch port, Ethernet transceiver), if the Ethernet hardware has reached the requested mode and requested link state under the following conditions:

- the timer to switch off the `EthSwTPort` (see `EthIfSwitchOffPortTimeDelay`) is not running AND
- the timer to keep the `EthSwTPort` in `ETH_MODE_ACTIVE` (see `EthIfPortStartupActiveTime`) is not running and the `EthSwTPort` has not been requested with `ETH_MODE_ACTIVE`

If EthIf detects that the requested mode and / or requested link state has not reached, EthIf shall re-trigger the requested mode and link state, respectively.]

Note:

1. This shall ensure to re-trigger a wake-up on the network, if e.g. OA TC10 compliant hardware is used (see [5, OPEN Sleep/Wake-up Specification for Automotive Ethernet]).
2. Additionally, the check shall not try to re-establish a requested mode if the timer to switch off the `EthSwTPort` (requested via `EthIfSwitchOffPortTimeDelay`) or the timer to keep the `EthSwTPort` active (requested via `EthIfPortStartupActiveTime`) is running. Switching-off of the Ethernet hardware in an Ethernet switched network after `EthIfSwitchOffPortTimeDelay` expires, lead to a situation that an Ethernet switch port and the connected Ethernet hardware (PHY) of the link partner are not synchronized. Thus, first the connected PHY will be switched off and after `EthIfSwitchOffPortTimeDelay` the Ethernet switch port. This is acceptable since the network management has already confirmed to go to sleep. For example, if using OA TC10 compliant Ethernet hardware, the ECU which is connected to the Ethernet switch trigger a `Sleep.Request` on the network and bring the connected Ethernet switch ports and its own Ethernet hardware to sleep mode, due to the specified OA TC10 synchronized shutdown of the Ethernet hardware. Thus, the ECU that maintain the Ethernet switch may detect a link down on the affected Ethernet switch port, which should be ignored by the EthIf, if the switch-off of the Ethernet switch port was already triggered but not forwarded to the Ethernet switch.



**[SWS\_EthIf\_00499]{DRAFT}** [For EthIfTransceiver where the referenced EthTrcv is acting as a passive communication slave (EthTrcvActAsSlavePassiveEnabled set to TRUE), EthIf shall check for unexpected link down. If an unexpected link down (link state is requested with ETHTRCV\_LINK\_STATE\_ACTIVE, but current link state is ETHTRCV\_LINK\_STATE\_DOWN) lasts as long as specified in EthIfQualifiedUnexpectedLinkDownTime, EthIf shall trigger to release the affected communication channel by calling EthSM\_SleepIndication. If an unexpected link down was detected, the EthSM shall immediately be indicated via EthSM\_TrcvLinkStateChg without considering EthIfQualifiedUnexpectedLinkDownTime.](SRS\_Eth\_00156)

Note: [SWS\_EthIf\_00499] should grant that a communication channel that act as an passive communication channel will shutdown even though the communication master could not transmit a sleep over the network (e.g. hardware failure, unexpected shutdown of the ECU that act as communication master, a.s.o).

## 8.6 Expected interfaces

In this chapter all interfaces required from other modules are listed.

### 8.6.1 Mandatory interfaces

Note: This section defines all interfaces, which are required to fulfill the core functionality of the module.

### 8.6.2 Optional interfaces

This section defines all interfaces, which are required to fulfill an optional functionality of the module.

**[SWS\_EthIf\_00103]** [

API Function	Header File	Description
BswM_EthIf_PortGroupLinkStateChg	BswM_EthIf.h	Function called by EthIf to indicate the link state change of a certain Ethernet switch port group.
CanXL_GetControllerMode	CanXL.h	Obtains the communication state of the indexed controller
CanXL_GetPhysAddr	CanXL.h	Obtains the physical source address used by the indexed controller
CanXL_ProvideTxBuffer	CanXL.h	Provides access to a transmit buffer of the queue related to the specified priority
CanXL_Receive	CanXL.h	Receive a frame from the related queue.
CanXL_SetControllerMode	CanXL.h	Enables / Disables Rx/Tx communication of the indexed controller





<b>API Function</b>	<b>Header File</b>	<b>Description</b>
CanXL_Transmit	CanXL.h	Triggers transmission of a previously filled transmit buffer
CanXL_TxConfirmation	CanXL.h	Triggers frame transmission confirmation
CanXLTrcv_GetLinkState	CanXLTrcv.h	Obtains the link state of the indexed transceiver
CanXLTrcv_GetTransceiverMode	CanXLTrcv.h	Obtains the state of the indexed transceiver
CanXLTrcv_SetTransceiverMode	CanXLTrcv.h	Enables / disables the indexed transceiver
CV2x_GetBufCV2xPC5RxParams (draft)	CV2x.h	Read out values related to a received packet. For example, this could be CBR to one single packet. This API is valid only within the context of CV2x_Receive <b>Tags:</b> atp.Status=draft
CV2x_GetBufCV2xPC5TxParams (draft)	CV2x.h	Read out values related to the receive direction for a transmitted packet. For example, this could be transaction ID to one single packet. This API is valid only within the context of CV2x_TxConfirmation <b>Tags:</b> atp.Status=draft
CV2x_GetChanCV2xPC5TxParams (draft)	CV2x.h	Read values related to the receive direction of the channel. For example, this could be a Channel Busy Ratio (CBR) <b>Tags:</b> atp.Status=draft
CV2x_SetBufCV2xPC5TxParams (draft)	CV2x.h	Set values related to the transmit direction for a specific buffer (packet to be sent). For example, this can be PPPP belonging to one single packet. <b>Tags:</b> atp.Status=draft
Eth_GetControllerMode	Eth.h	Obtains the communication state of the indexed controller
Eth_GetPhysAddr	Eth.h	Obtains the physical source address used by the indexed controller
Eth_ProvideTxBuffer	Eth.h	Provides access to a transmit buffer of the queue related to the specified priority
Eth_ReadMii	Eth.h	Reads a transceiver register
Eth_Receive	Eth.h	Receive a frame from the related queue.
Eth_SetControllerMode	Eth.h	Enables / Disables Rx/Tx communication of the indexed controller
Eth_Transmit	Eth.h	Triggers transmission of a previously filled transmit buffer
Eth_TxConfirmation	Eth.h	Triggers frame transmission confirmation
Eth_WriteMii	Eth.h	Configures a transceiver register or triggers a function offered by the receiver
EthSM_CtrlModelIndication	EthSM.h	Called when mode has been read out. Either triggered by previous EthIf_GetControllerMode or by EthIf_SetControllerMode call. Can directly be called within the trigger functions.





API Function	Header File	Description
EthSM_SleepIndication (draft)	EthSM.h	This API is called by the EthIf and indicate that a sleep indication was detected on the network. This API is only called if the ECU is acting as a passive communication slave on the corresponding communication channel (the referenced EthTrcv of the affected EthIfTransceiver has set EthTrcvActAs SlavePassiveEnabled to TRUE). This could be used e.g. for Ethernet hardware which is compliant to the OA TC10. In this case the Ethernet hardware detect an Sleep.Indication which was triggered by a Sleep.Request of the connected link partner. <b>Tags:</b> atp.Status=draft
EthSM_TrvcLinkStateChg	EthSM.h	This service is called by the Ethernet Interface to report a transceiver link state change.
EthSwt_PortEnableTimeStamp	EthSwt.h	Activates egress time stamping on a dedicated message object on a dedicated port of a Switch if EthSwtPortTimeStampSupport is set to TRUE for this port. The selective activation of dedicated message objects for time stamping reduces the number of notification calls only to the required calls. Some HW does store once the egress time stamp marker and some HW needs it always before transmission. There will be no disabled functionality, due to the fact, that the message type is always "time stamped" by network design.
EthSwt_SetMgmtInfo	EthSwt.h	Extends the Ethernet frame prepared previously by EthSwt_EthTxPrepareFrame() with the management information to achieve transmission only on specific ports.
EthTrcv_GetBaudRate	EthTrcv.h	Obtains the baud rate of the indexed transceiver
EthTrcv_GetDuplexMode	EthTrcv.h	Obtains the duplex mode of the indexed transceiver
EthTrcv_GetLinkState	EthTrcv.h	Obtains the link state of the indexed transceiver
EthTrcv_GetTransceiverMode	EthTrcv.h	Obtains the state of the indexed transceiver
EthTrcv_SetTransceiverMode	EthTrcv.h	Enables / disables the indexed transceiver
EthTrcv_StartAutoNegotiation	EthTrcv.h	Restarts the negotiation of the transmission parameters used by the indexed transceiver
IdsM_SetSecurityEvent	IdsM.h	This API is the application interface to report security events to the IdsM.
IdsM_SetSecurityEventWithContext Data	IdsM.h	This API is the application interface to report security events with context data to the IdsM.
WEth_GetBufWRxParams	WEth.h	Read out values related to the receive direction for a received packet. For example, this could be RSSI or Channel belonging to one single packet. This API is valid only within the context of WEth_Receive
WEth_GetBufWTxParams	WEth.h	Read out values related to the transmit direction for a transmitted packet. For example, this could be transaction ID belonging to one single packet. This API is valid only within the context of WEth_Tx Confirmation.
WEth_SetBufWTxParams	WEth.h	Set values related to the transmit direction for a specific buffer (packet to be sent). For example, this can be the desired transmit power or the channel belonging to one single packet.
WEthTrcv_GetChanRxParams	WEthTrcv.h	Read values related to the receive direction of the transceiver. For example, this could be a Channel Busy Ratio (CBR) or the average Channel Idle Time (CIT).





API Function	Header File	Description
WEthTrcv_SetChanRxParams	WEthTrcv.h	Set values related to the receive direction of a transceiver's wireless channel. For example, this could be a channel parameter like the frequency.
WEthTrcv_SetChanTxParams	WEthTrcv.h	Set values related to the transmit direction of a transceiver's wireless channel. For example, this could be the bitrate of a channel.
WEthTrcv_SetRadioParams	WEthTrcv.h	Set values related to a transceiver's wireless radio. For example, this could be the selection of the radio settings (channel, ...).

]()

### 8.6.3 Configurable interfaces

In this section, all interfaces are listed where the target function could be configured. The target function is usually a callback function. The names of this kind of interfaces are not fixed because they are configurable.

[SWS\_EthIf\_00104] [

<b>Service Name</b>	<User>_RxIndication	
<b>Syntax</b>	<pre>void &lt;User&gt;_RxIndication (     uint8 CtrlIdx,     Eth_FrameType FrameType,     boolean IsBroadcast,     const uint8* PhysAddrPtr,     const uint8* DataPtr,     uint16 LenByte )</pre>	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Dont care	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	FrameType	frame type of received Ethernet frame
	IsBroadcast	parameter to indicate a broadcast frame
	PhysAddrPtr	pointer to Physical source address (MAC address in network byte order) of received Ethernet frame
	DataPtr	Pointer to payload of the received Ethernet frame (i.e. Ethernet header is not provided).
	LenByte	Length of received data.
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Indicates the reception of an Ethernet frame	
<b>Available via</b>	configurable	

]()

[SWS\_EthIf\_00105] [The callback function shall be configurable by the configuration parameter: EthIfRxIndicationFunction.]()

[SWS\_EthIf\_00106] [

<b>Service Name</b>	<UL>_TxConfirmation	
<b>Syntax</b>	<pre>void &lt;UL&gt;_TxConfirmation (     uint8 CtrlIdx,     Eth_BufIdxType BufIdx,     Std_ReturnType Result )</pre>	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Dont care	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	BufIdx	Index of the buffer resource
	Result	–
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Confirms the transmission of an Ethernet frame	
<b>Available via</b>	configurable	

]()

[SWS\_EthIf\_00107] [The callback function shall be configurable by the configuration parameter: `EthIfTxConfirmationFunction.`]()

[SWS\_EthIf\_00108] [

<b>Service Name</b>	<User>_TrcvLinkStateChg	
<b>Syntax</b>	<pre>void &lt;User&gt;_TrcvLinkStateChg (     uint8 CtrlIdx,     EthTrcv_LinkStateType TrcvLinkState )</pre>	
<b>Sync/Async</b>	Synchronous	
<b>Reentrancy</b>	Don't care	
<b>Parameters (in)</b>	CtrlIdx	Index of the Ethernet controller within the context of the Ethernet Interface
	TrcvLinkState	ETHTRCV_LINK_STATE_DOWN transceiver link is down ETHTRCV_LINK_STATE_ACTIVE transceiver link is up
<b>Parameters (inout)</b>	None	
<b>Parameters (out)</b>	None	
<b>Return value</b>	None	
<b>Description</b>	Indicates the change of a transceiver state	
<b>Available via</b>	configurable	

]()

[SWS\_EthIf\_00109] [The callback function shall be configurable by the configuration parameter: `EthIfTrcvLinkStateChgFunction.`]()

[SWS\_EthIf\_00229] [EthIfControllers not referring to an Ethernet Transceiver, i.e. no valid `EthIfEthTrcvRef` or `EthIfCanXLTrcvRef` is configured, shall act as if the transceiver was present and the transceiver status was `ETHTRCV_LINK_STATE_ACTIVE.`]()

**[SWS\_EthIf\_00230]** [Upon change of link state `<User>_TrcvLinkStateChg` shall be invoked for every affected EthIfController.] ()

Terms and definitions:

**Reentrant** interface is reentrant

**Don't care** reentrancy of interface not relevant for this module (in general it is in this case not reentrant).

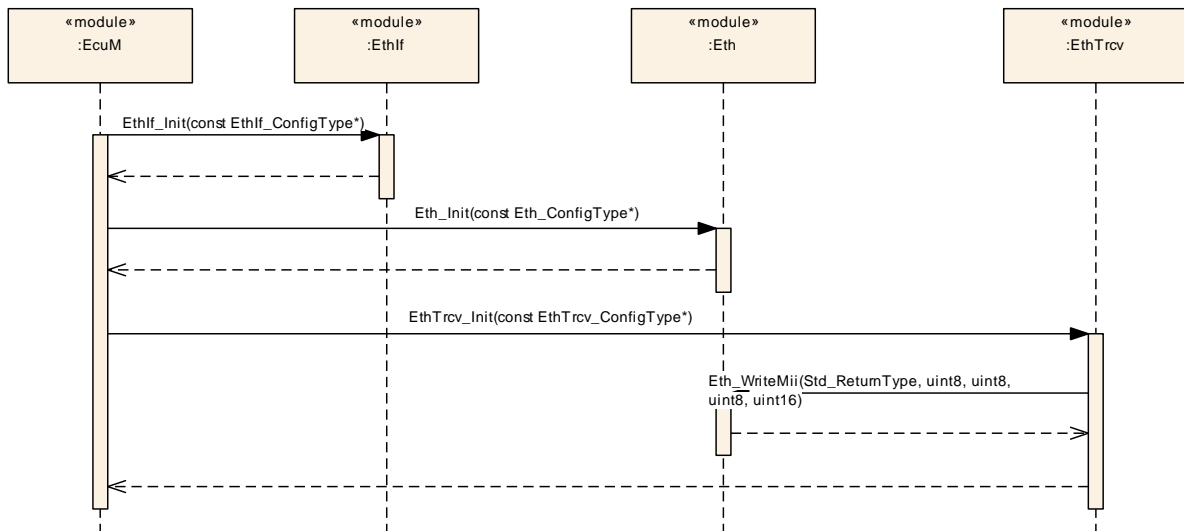
## 9 Sequence diagrams

The sequence diagrams show the basic operations carried out during operation. They show the interaction of the Ethernet Interface with upper layer BSW module and the underlying Ethernet Controller Driver.

Please note that the sequence diagrams are an extension for illustrational purposes to ease understanding of the specification.

### 9.1 Initialization

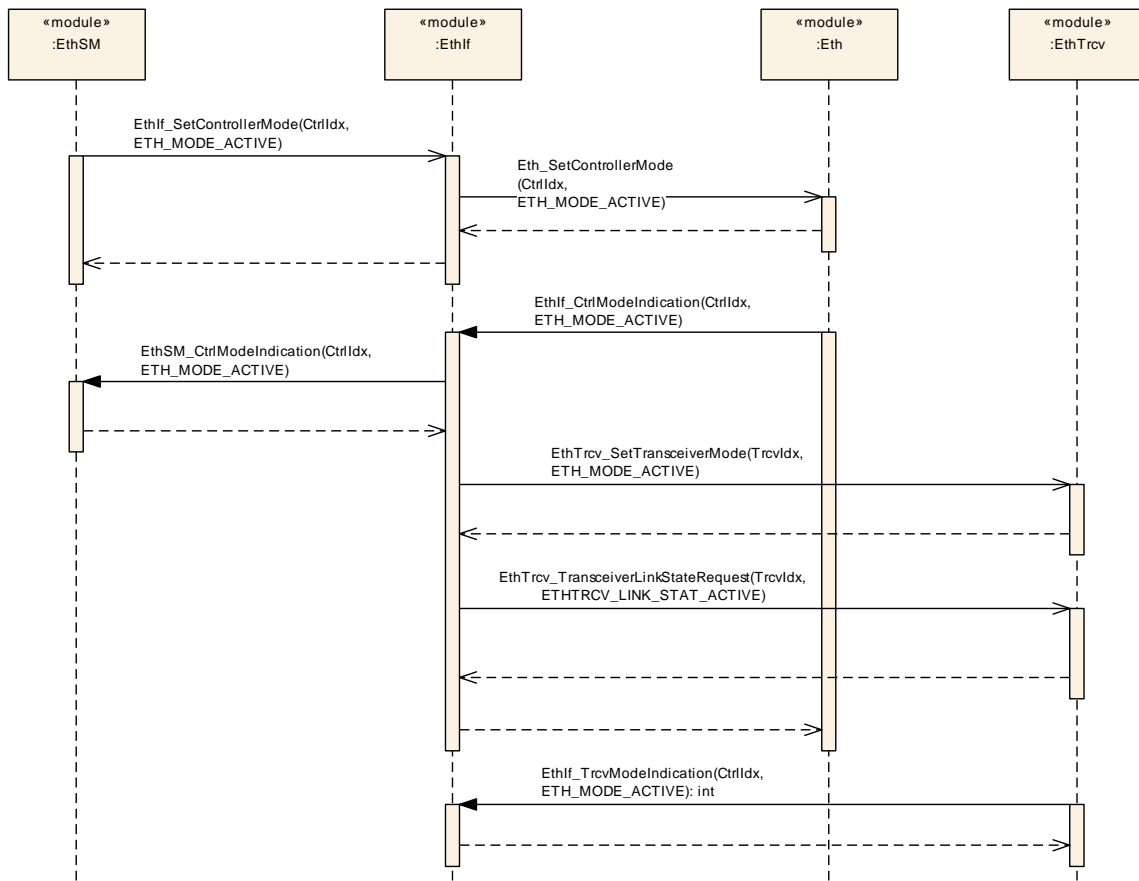
Name: EthIf\_Initialization  
Package: EthIf  
Version: 1.0  
Author: fix0ec2



**Figure 9.1: Initialization**

## 9.2 Communication Initialization

Name: EthIf\_CommunicationInitialization  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2

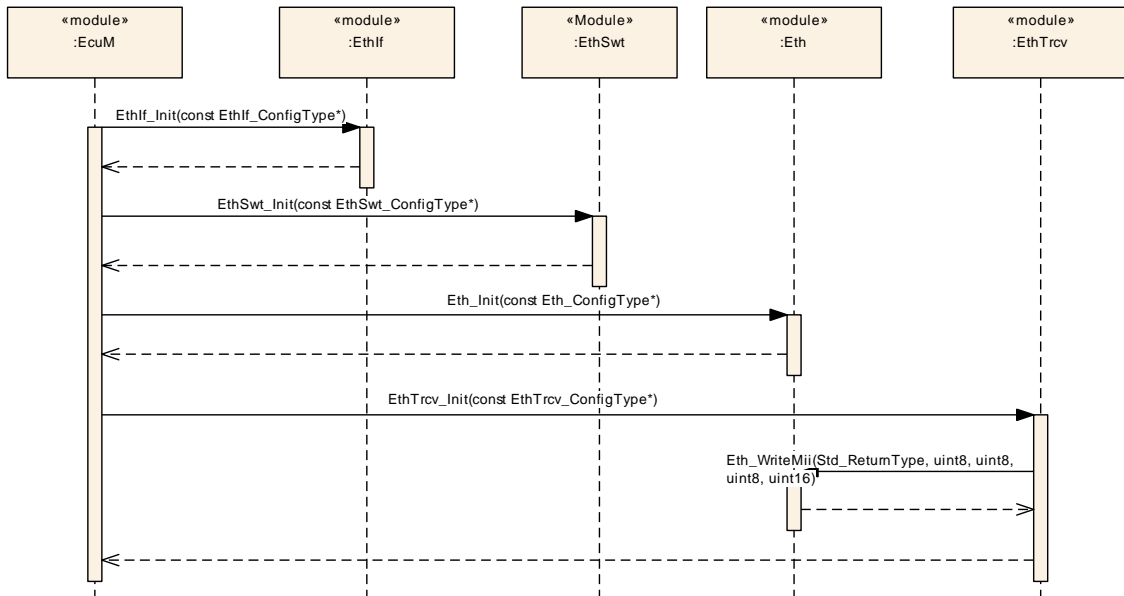


**Figure 9.2: Communication Initialization**



### 9.3 Switch Initialization

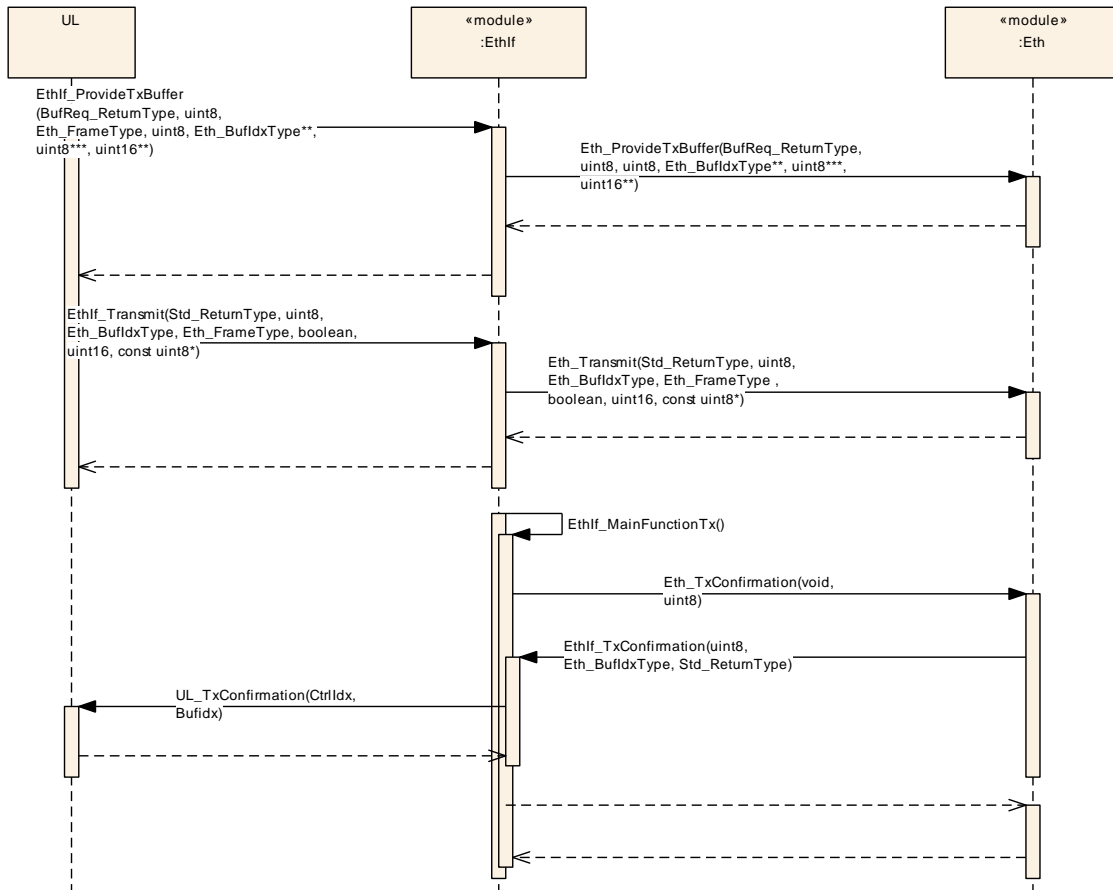
Name: EthIf\_SwitchInitialization  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2



**Figure 9.3: Switch Initialization**

### 9.4 Data Transmission

Name: EthIf\_DataTransmission  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2



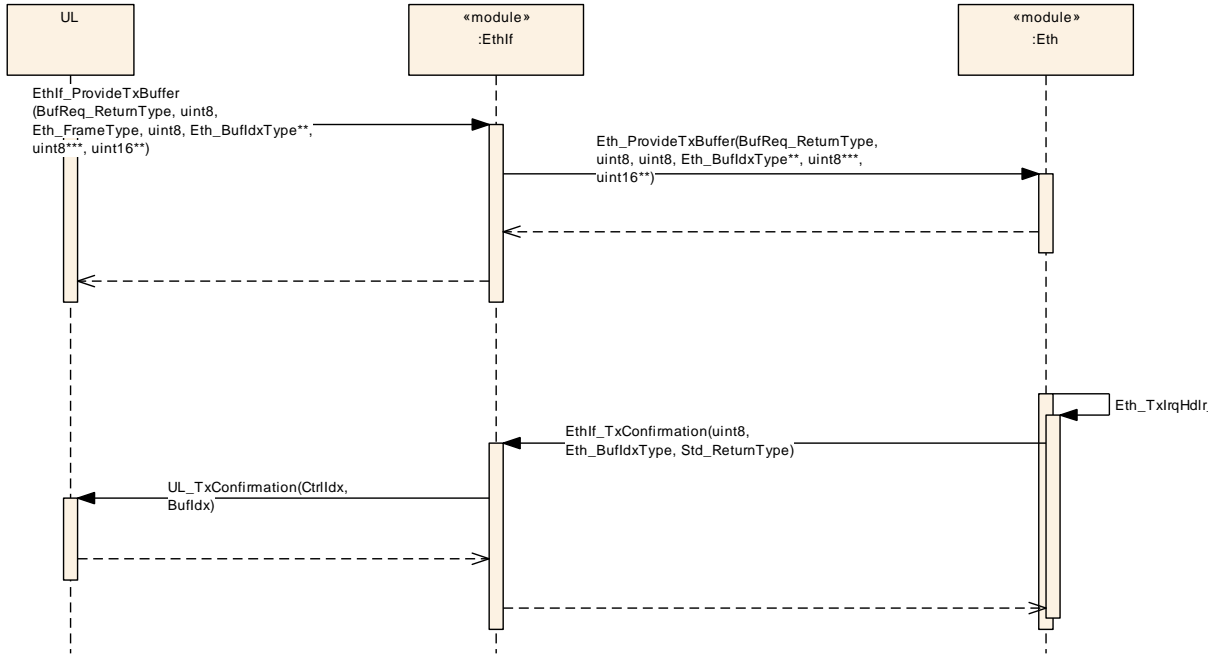
**Figure 9.4: Frame Transmission in Polling Mode**

**[SWS\_EthIf\_00115]** [In each call of `EthIf_MainFunctionTx` the component shall call `<EthDrv>_TxConfirmation` for all Ethernet Controller Drivers.

Note: The Ethernet Interface expects that each Ethernet Controller Driver issues confirmations for all transmitted frames using the call-back function `EthIf_TxConfirmation`.]()

**[SWS\_EthIf\_00125]** [`EthIf_TxConfirmation` shall forward the confirmation to the registered call-back functions `<User>_TxConfirmation`.]()

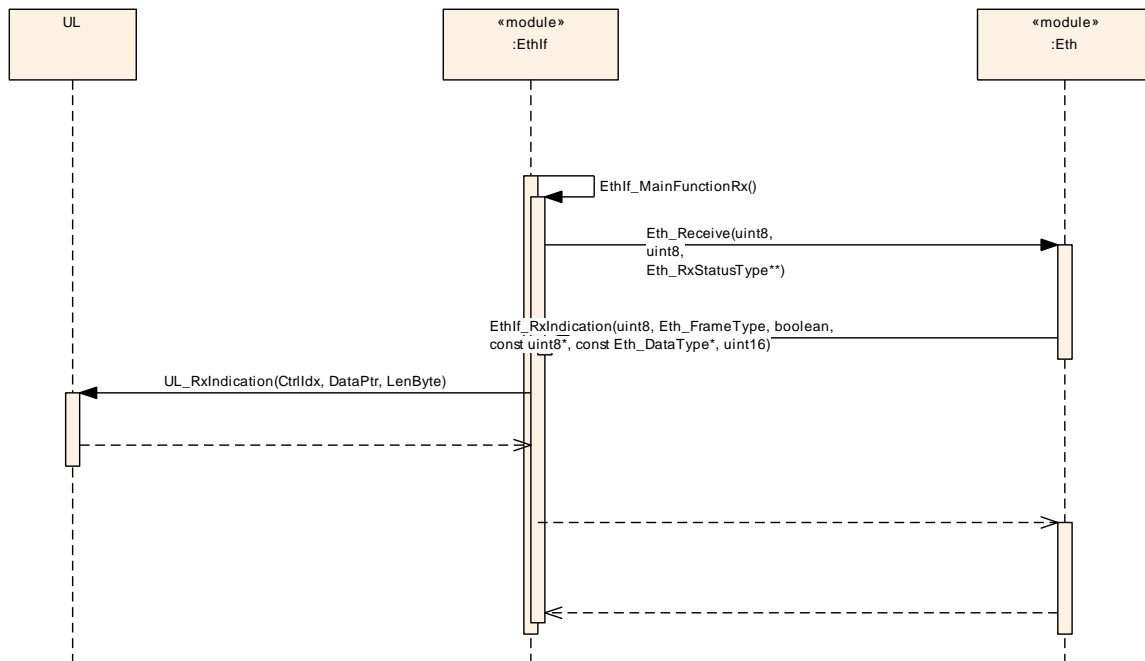
Name: EthIf\_TransmissionInterrupt  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2



**Figure 9.5: Frame Transmission in Interrupt Mode**

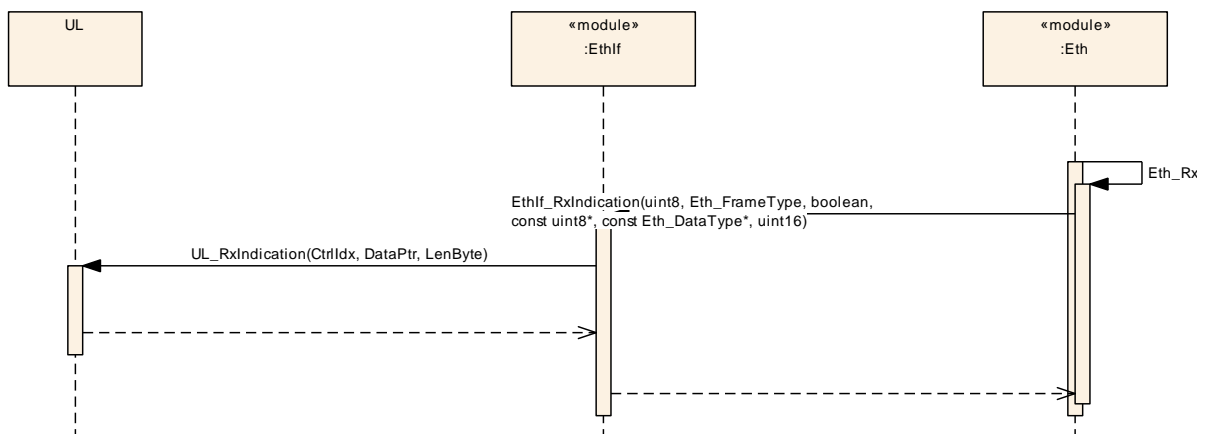
## 9.5 Data Reception

Name: EthIf\_DataReception  
Package: EthIf  
Version: 1.0  
Author: fix0ec2



**Figure 9.6: Frame Reception in Polling Mode**

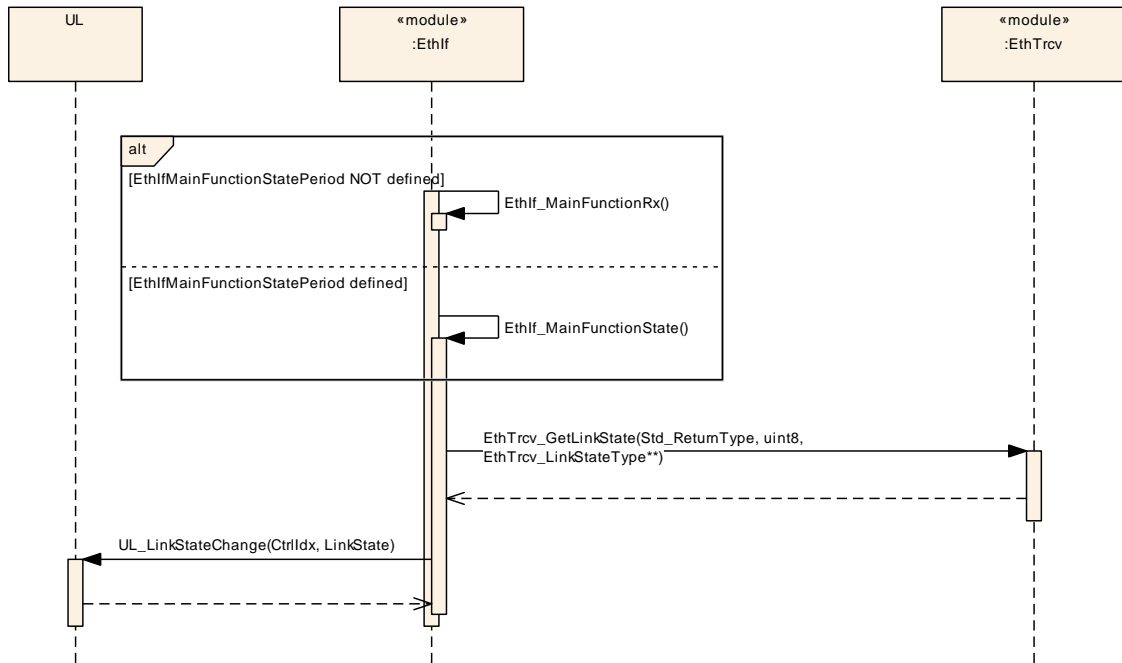
Name: EthIf\_ReceptionInterrupt  
Package: EthIf  
Version: 1.0  
Author: fix0ec2



**Figure 9.7: Frame Reception in Interrupt Mode**

## 9.6 Link State Change

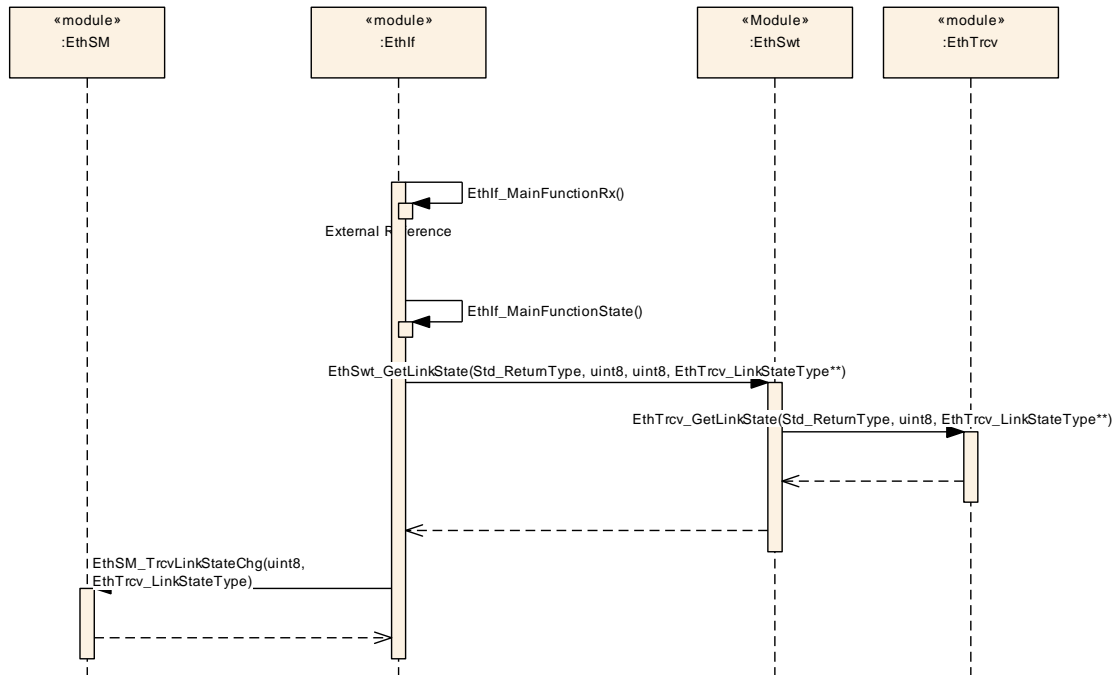
Name: EthIf\_LinkStateChange  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2



**Figure 9.8: Link State Change**

## 9.7 Link State Change without Port Groups

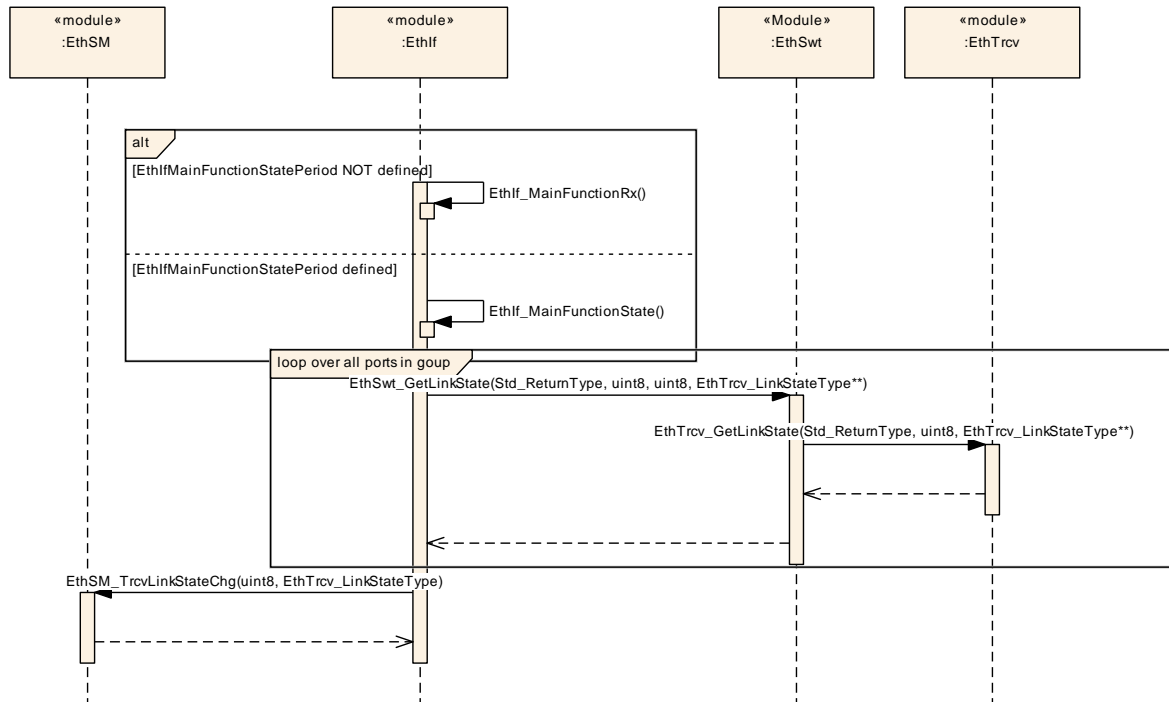
Name: EthIf\_EthSwt\_LinkStateChange\_NoPortGroup  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2



**Figure 9.9: Link State Change without Port Groups**

## 9.8 Link State Change with Port Groups

Name: EthIf\_EthSwt\_LinkStateChangePortGroupControl  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2



**Figure 9.10: Link State Change with Port Groups**

## 9.9 Link State Change with Port Groups and Partial Network Cluster

Name: EthIf\_EthSwt\_LinkStateChangePortGroupPNC  
 Package: EthIf  
 Version: 1.0  
 Author: fix0ec2

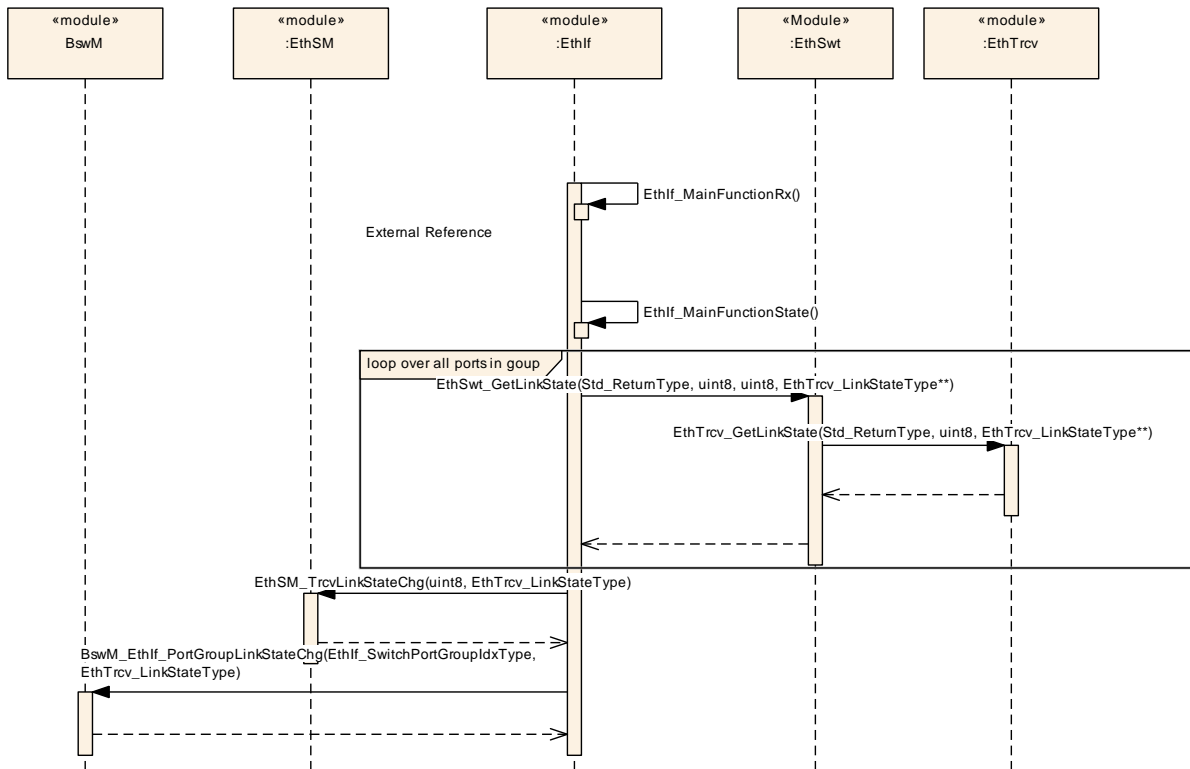
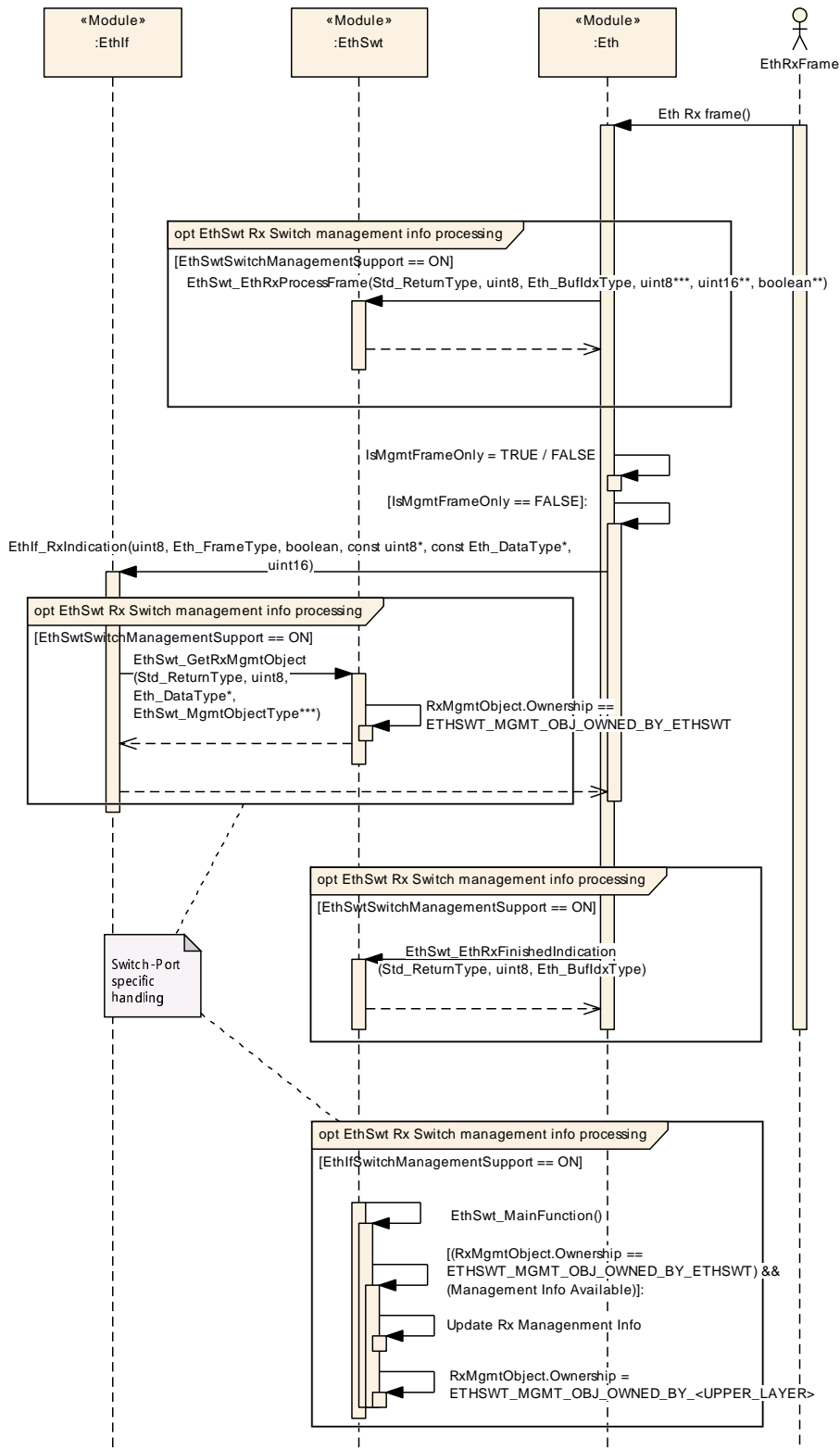


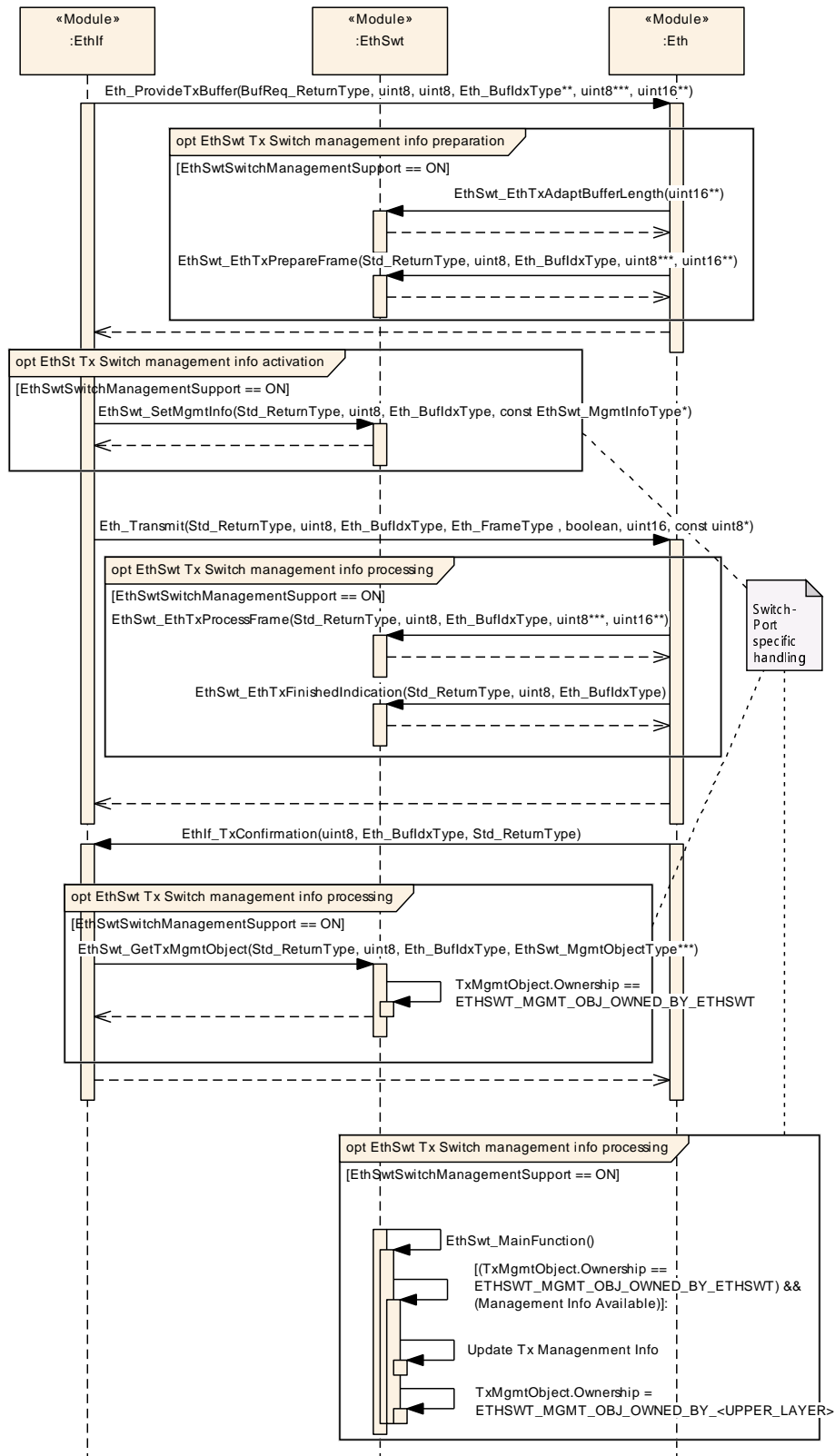
Figure 9.11: and Partial Network Cluster



### 9.10 Switch Management support



**Figure 9.12: Switch Management support for transmission**



**Figure 9.13: Switch Management support for reception**

## 10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification Chapter 10.1 describes fundamentals. It also specifies a template (table) you shall use for the parameter specification. We intend to leave Chapter 10.1 in the specification to guarantee comprehension.

Chapter 10.2 specifies the structure (containers) and the parameters of the module Ethernet Interface.

Chapter 10.3 specifies published information of the module Ethernet Interface.

### 10.1 How to read this chapter

For details refer to the chapter 10.1 “Introduction to configuration specification” in SWS\_BSWGeneral [6].

### 10.2 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapter 7 and Chapter 8.

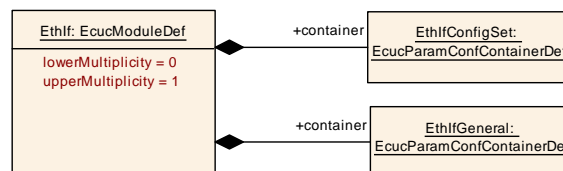
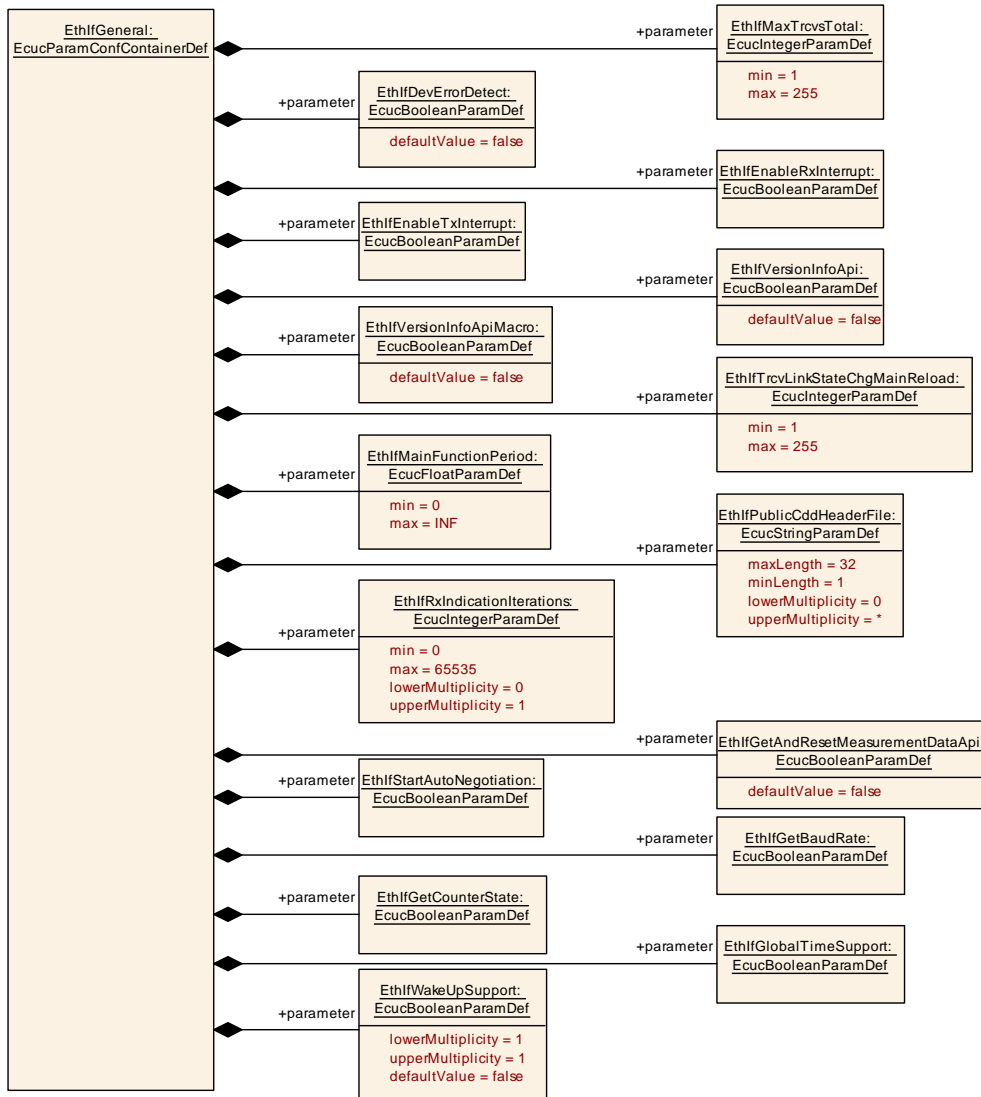
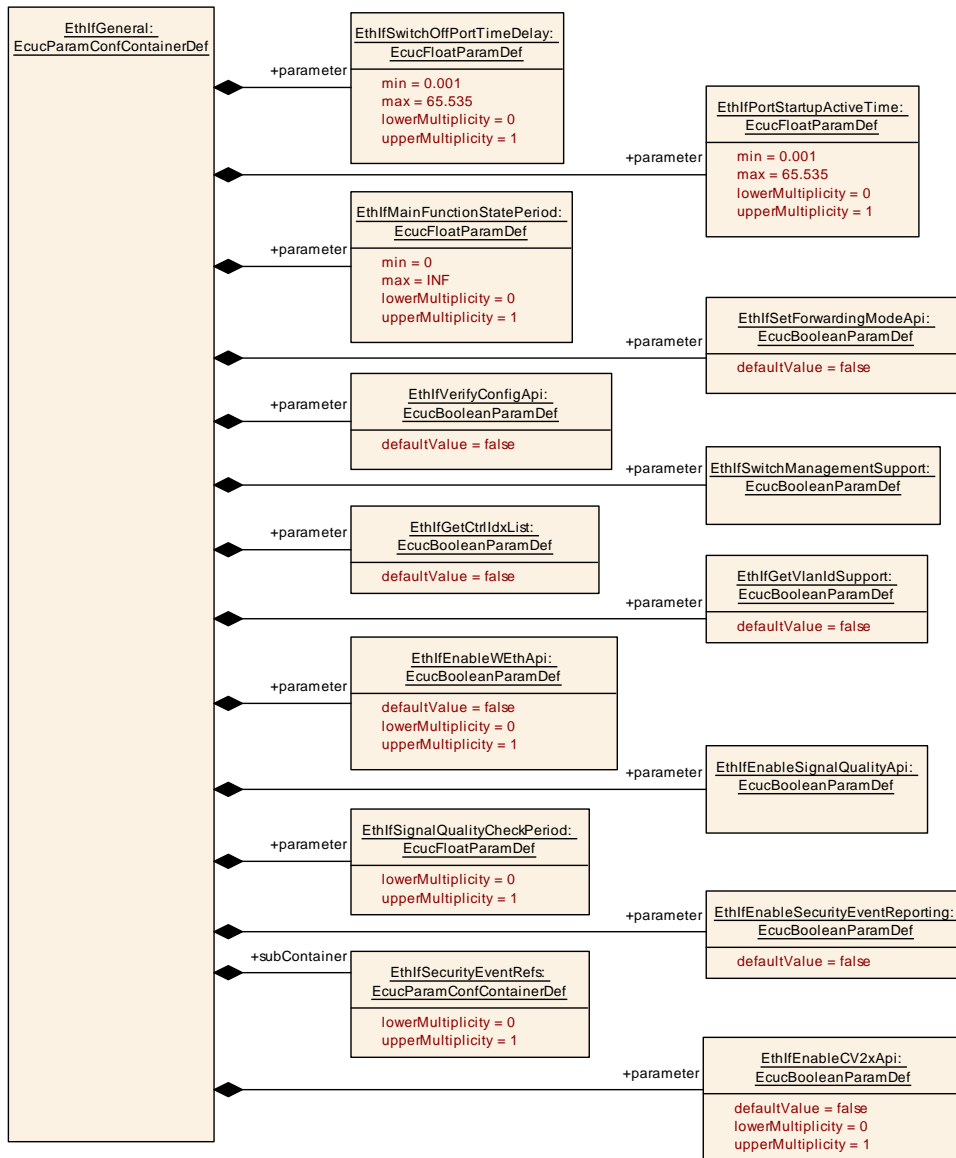


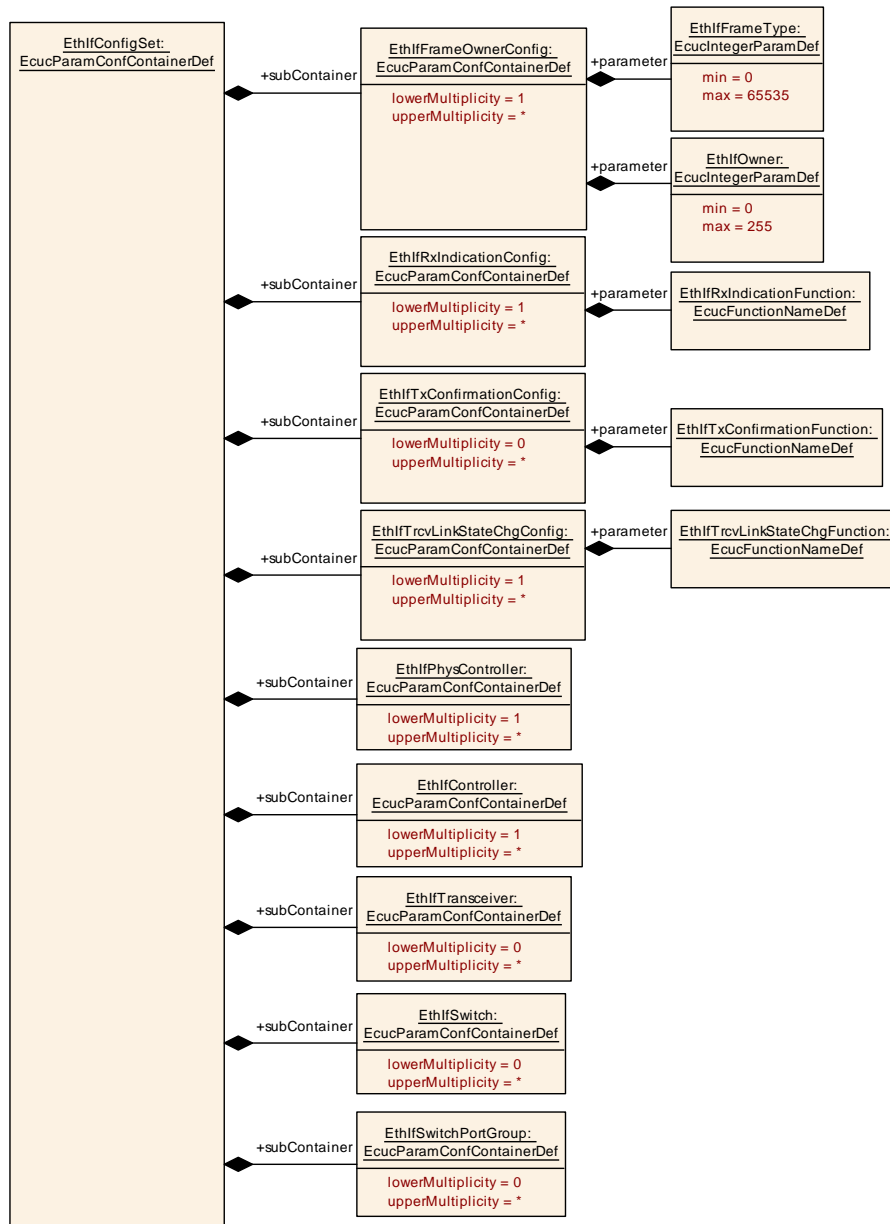
Figure 10.1: Ethernet Interface



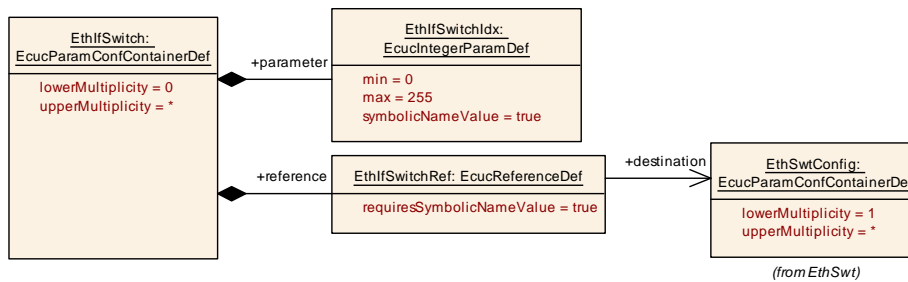
**Figure 10.2: Ethernet Interface general configuration structure**



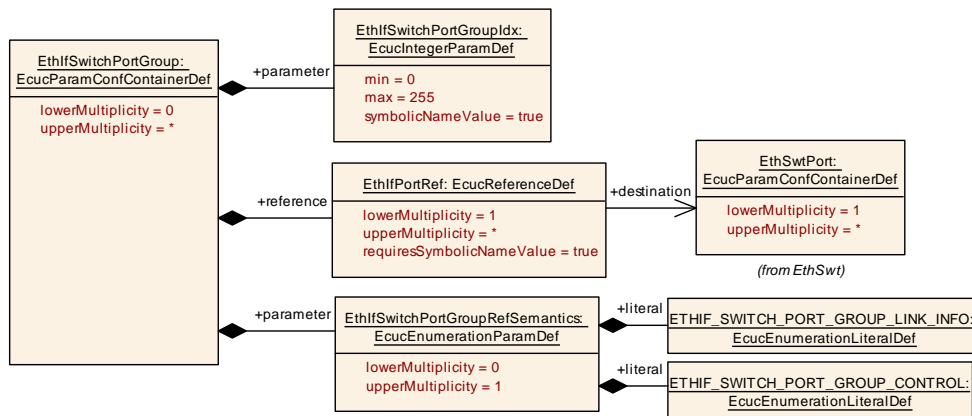
**Figure 10.3: Ethernet Interface general configuration structure (continued)**



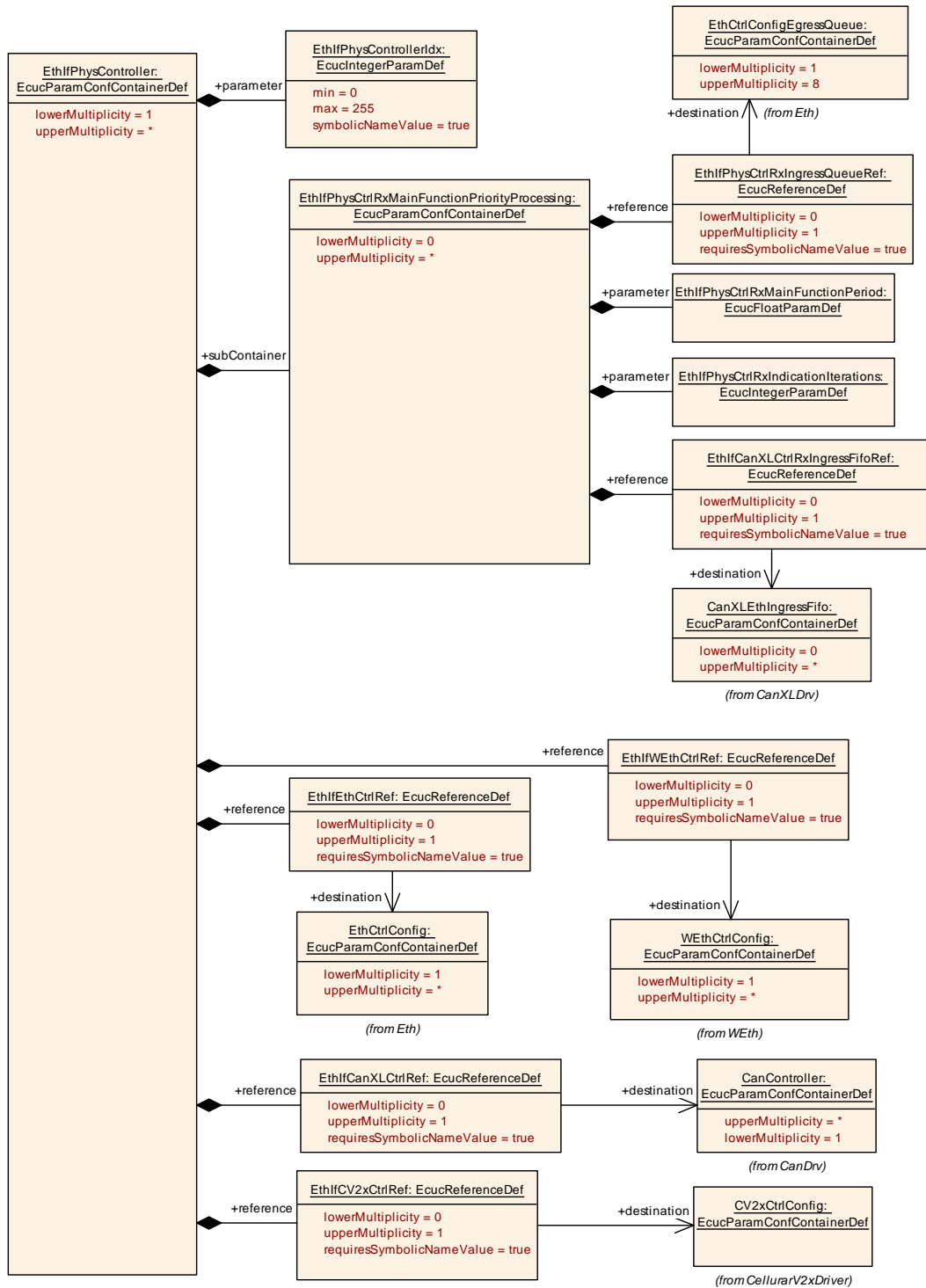
**Figure 10.4: Ethernet Interface interface configuration structure**



**Figure 10.5: Ethernet Interface Switch configuration structure**

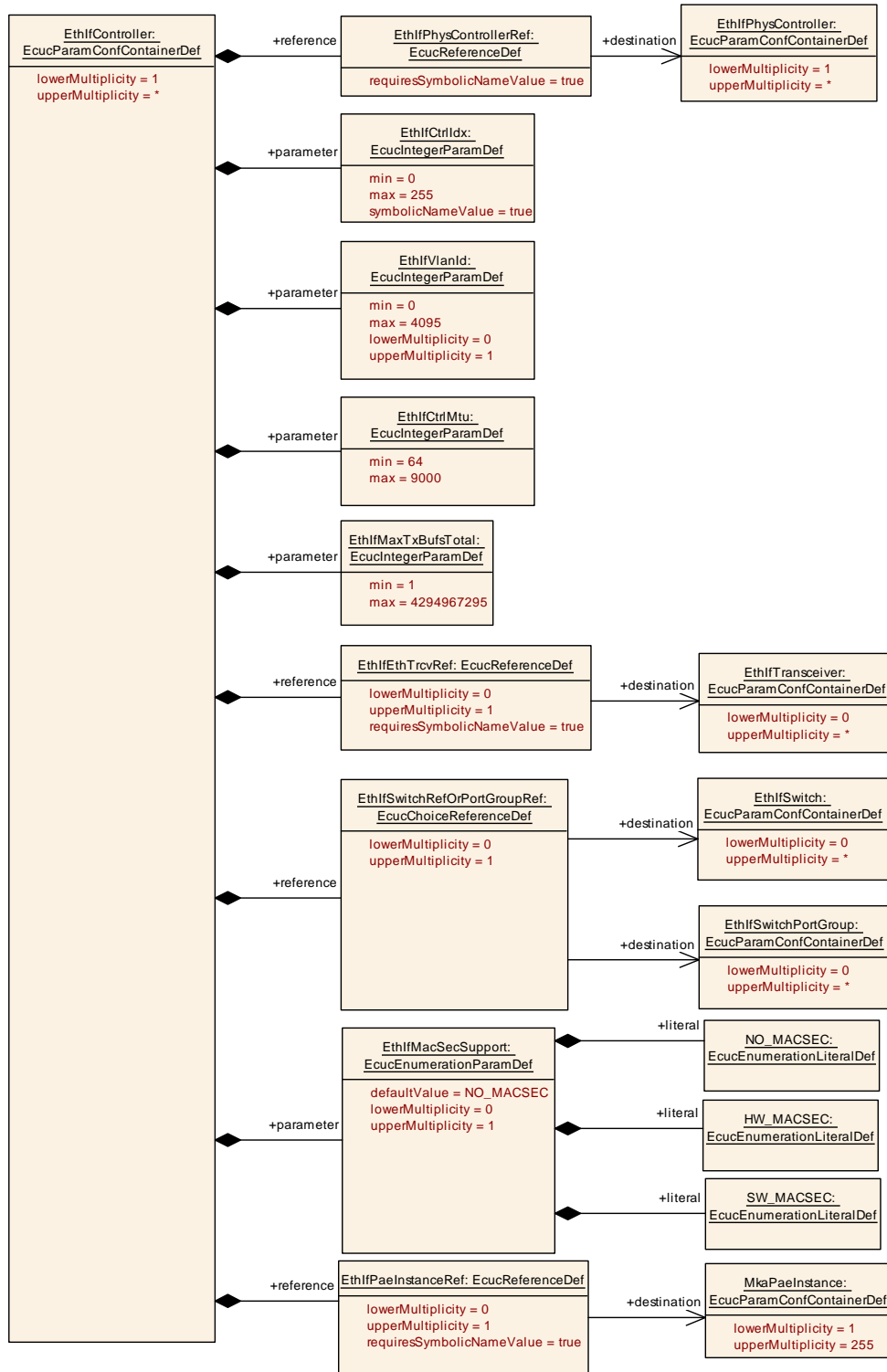


**Figure 10.6: Ethernet Interface SwitchPortGroup configuration structure**

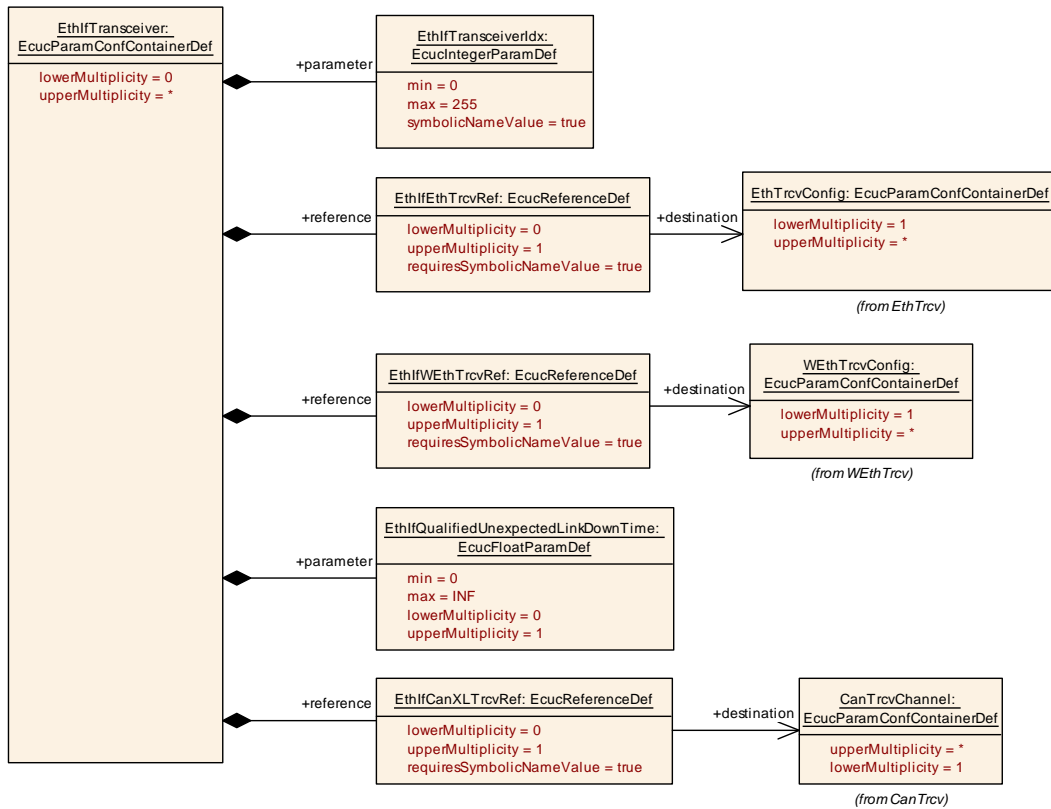


**Figure 10.7: Ethernet Interface physical controller configuration structure**

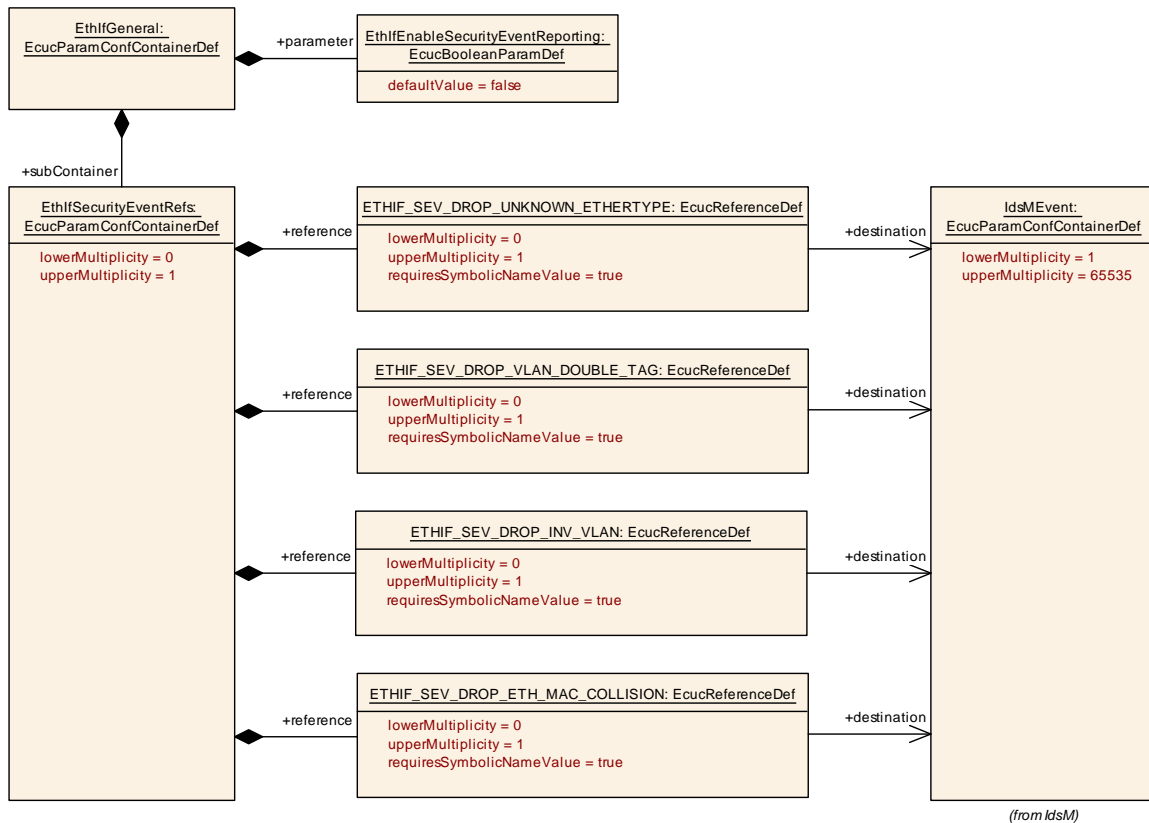




**Figure 10.8: Ethernet Interface controller configuration structure**



**Figure 10.9: Ethernet Interface transceiver configuration structure**



**Figure 10.10: Ethernet security event ref**

### 10.2.1 Ethlf

<b>SWS Item</b>	[ECUC_Ethlf_00049]
<b>Module Name</b>	Ethlf
<b>Description</b>	Configuration of the Ethlf (Ethernet Interface) module.
<b>Post-Build Variant Support</b>	true
<b>Supported Config Variants</b>	VARIANT-LINK-TIME, VARIANT-POST-BUILD, VARIANT-PRE-COMPILE

Included Containers		
Container Name	Multiplicity	Scope / Dependency
<a href="#">EthlfConfigSet</a>	1	Collecting container for all parameters with post-build configuration classes.
<a href="#">EthlfGeneral</a>	1	This container contains the general configuration parameters of the Ethernet Interface.

### 10.2.2 EthlfGeneral

<b>SWS Item</b>	[ECUC_Ethlf_00001]
<b>Container Name</b>	EthlfGeneral
<b>Parent Container</b>	<a href="#">Ethlf</a>
<b>Description</b>	This container contains the general configuration parameters of the Ethernet Interface.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	[ECUC_Ethlf_00004]		
<b>Parameter Name</b>	EthlfDevErrorDetect		
<b>Parent Container</b>	<a href="#">EthlfGeneral</a>		
<b>Description</b>	Switches the development error detection and notification on or off. <ul style="list-style-type: none"> <li>• true: detection and notification is enabled.</li> <li>• false: detection and notification is disabled.</li> </ul>		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_Ethlf_00091]
<b>Parameter Name</b>	EthlfEnableCV2xApi
<b>Parent Container</b>	<a href="#">EthlfGeneral</a>
<b>Description</b>	Enables / Disables API's for CV2x <b>Tags:</b> atp.Status=draft
<b>Multiplicity</b>	0..1
<b>Type</b>	EcucBooleanParamDef





<b>Default value</b>	false		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00005]		
<b>Parameter Name</b>	EthIfEnableRxInterrupt		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables receive interrupt.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00079]		
<b>Parameter Name</b>	EthIfEnableSecurityEventReporting		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Switches the reporting of security events to the IdsM: - true: reporting is enabled. - false: reporting is disabled. <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	[ECUC_EthIf_00076]		
<b>Parameter Name</b>	EthIfEnableSignalQualityApi		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enable/disable the APIs read and clear the signal quality.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		





<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00006]		
<b>Parameter Name</b>	EthIfEnableTxInterrupt		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables the transmit interrupt.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00075]		
<b>Parameter Name</b>	EthIfEnableWEthApi		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables API's for WEth / WEthTrcv		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00072]		
<b>Parameter Name</b>	EthIfGetAndResetMeasurementDataApi		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables the Get and Reset Measurement Data API		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00034]</b>		
<b>Parameter Name</b>	EthIfGetBaudRate		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables GetBaudRate API.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00035]</b>		
<b>Parameter Name</b>	EthIfGetCounterState		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables GetCounterState API.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00070]</b>		
<b>Parameter Name</b>	EthIfGetCtrlIdxList		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables GetCtrlIdxList API.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00071]</b>		
<b>Parameter Name</b>	EthIfGetVlanIdSupport		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables GetVlanId API.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		





<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_Ethlf_00039]</b>		
<b>Parameter Name</b>	EthlfGlobalTimeSupport		
<b>Parent Container</b>	<a href="#">EthlfGeneral</a>		
<b>Description</b>	Enables/Disables the Global Time APIs used amongst others by Global Time Synchronization over Ethernet.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_Ethlf_00023]</b>		
<b>Parameter Name</b>	EthlfMainFunctionPeriod		
<b>Parent Container</b>	<a href="#">EthlfGeneral</a>		
<b>Description</b>	Specifies the period of main function Ethlf_MainFunctionRx and Ethlf_MainFunctionTx in seconds. Ethernet Interface does not require this information but the BSW scheduler.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucFloatParamDef		
<b>Range</b>	]0 .. INF[		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_Ethlf_00056]</b>		
<b>Parameter Name</b>	EthlfMainFunctionStatePeriod		
<b>Parent Container</b>	<a href="#">EthlfGeneral</a>		
<b>Description</b>	Specifies the period of main function Ethlf_MainFunctionState in seconds. Ethernet Interface does not require this information but the BSW scheduler.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucFloatParamDef		
<b>Range</b>	]0 .. INF[		
<b>Default value</b>	–		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	





<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local dependency: If parameter is defined, then EthIf_MainFunctionState shall be generated.		

<b>SWS Item</b>	<b>[ECUC_EthIf_00003]</b>		
<b>Parameter Name</b>	EthIfMaxTrcvsTotal		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Limits the total number of transceivers.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	1 .. 255		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00055]</b>		
<b>Parameter Name</b>	EthIfPortStartupActiveTime		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Denote the time delay after the mode "ETH_MODE_ACTIVE" of all EthIfSwitchPorts are requested via EthIf_StartAllPorts.  This is only used for ports in EthIfSwtPortGroups which are not referenced by any EthIf Controller.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucFloatParamDef		
<b>Range</b>	[0.001 .. 65.535]		
<b>Default value</b>	–		
<b>Post-Build Variant Multiplicity</b>	true		
<b>Post-Build Variant Value</b>	true		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00024]</b>		
<b>Parameter Name</b>	EthIfPublicCddHeaderFile		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Defines header files for callback functions which shall be included in case of CDDs. Range of characters is 1.. 32.		
<b>Multiplicity</b>	0..*		







<b>Type</b>	EcucStringParamDef		
<b>Default value</b>	-		
<b>Length</b>	1-32		
<b>Regular Expression</b>	-		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	[ECUC_EthIf_00030]		
<b>Parameter Name</b>	EthIfRxIndicationIterations		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Maximum number of Ethernet frames per Ethernet controller polled from the Ethernet driver within EthIf_MainFunctionRx.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	0 .. 65535		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00062]		
<b>Parameter Name</b>	EthIfSetForwardingModeApi		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables /disables EthIf_SetForwardingMode API.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00077]		
<b>Parameter Name</b>	EthIfSignalQualityCheckPeriod		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		





<b>Description</b>	Specifies the period in units of seconds in which the signal quality is polled in the context of EthIf_MainFunctionState. The value shall be an integral multiple of EthIfMainFunctionStatePeriod.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucFloatParamDef		
<b>Range</b>	[-INF .. INF]		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local dependency: If this parameter is defined, the EthIf_MainFunctionState shall be generated and parameter EthIfEnableSignalQualityApi shall be set to TRUE.		

<b>SWS Item</b>	<b>[ECUC_EthIf_00033]</b>		
<b>Parameter Name</b>	EthIfStartAutoNegotiation		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables StartAutoNegotiation API.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00064]</b>		
<b>Parameter Name</b>	EthIfSwitchManagementSupport		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables/Disables the Switch management APIs to support a Switch-port specific communication attribute access.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00054]</b>		
<b>Parameter Name</b>	EthIfSwitchOffPortTimeDelay		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		





<b>Description</b>	Denote the time delay after the mode "ETH_MODE_DOWN" of a EthIfSwitchPortGroup will be executed.  This is only used for EthIfSwitPortGroups which are not referenced by any EthIf Controller.  The time delay shall be greater than the UdpNm timings, because UdpNm shall finish its shutdown handling. (Repeat Message State, Prepare Bus-Sleep state, Bus-Sleep state).		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucFloatParamDef		
<b>Range</b>	[0.001 .. 65.535]		
<b>Default value</b>	-		
<b>Post-Build Variant Multiplicity</b>	true		
<b>Post-Build Variant Value</b>	true		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local  dependency: EthIfSwitchOffPortTimeDelay > (UdpNmTimeoutTime + UdpNmWaitBus SleepTime)		

<b>SWS Item</b>	[ECUC_EthIf_00009]		
<b>Parameter Name</b>	EthIfTrcvLinkStateChgMainReload		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Specifies the frequency of transceiver link state change checks in each period of main function EthIf_MainFunctionTx.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	1 .. 255		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00063]		
<b>Parameter Name</b>	EthIfVerifyConfigApi		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables /disables EthIf_VerifyConfig API.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	





	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00007]</b>		
<b>Parameter Name</b>	EthIfVersionInfoApi		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables version info API		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00008]</b>		
<b>Parameter Name</b>	EthIfVersionInfoApiMacro		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Enables / Disables version info API macro implementation.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00040]</b>		
<b>Parameter Name</b>	EthIfWakeUpSupport		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Configures if wake-up handling is supported or not: TRUE: wake-up handling is supported FALSE: wake-up handling is not supported  This configuration parameter also enables particular other the API at Pre-Compile-Time, e.g. EthIf_CheckWakeup.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucBooleanParamDef		
<b>Default value</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
<a href="#">EthIfSecurityEventRefs</a>	0..1	<p>Container for the references to IdsMEvent elements representing the security events that the EthIf module shall report to the IdsM in case the corresponding security related event occurs (and if EthIfEnableSecurityEventReporting is set to "true"). The standardized security events in this container can be extended by vendor-specific security events.</p> <p><b>Tags:</b> atp.Status=draft</p>

### 10.2.3 EthIfConfigSet

SWS Item	[ECUC_EthIf_00010]
Container Name	EthIfConfigSet
Parent Container	<a href="#">EthIf</a>
Description	Collecting container for all parameters with post-build configuration classes.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
<a href="#">EthIfController</a>	1..*	This container contains the configuration of EthIfController.
<a href="#">EthIfFrameOwnerConfig</a>	1..*	Configuration of Ethernet frame owner
<a href="#">EthIfPhysController</a>	1..*	<p>This container contains the configuration of EthIfPhysController.</p> <p>The usage of EthIfEthCtrlRef, EthIfCanXLCtrlRef, and EthIfWEthCtrlRef and EthIfCV2xCtrlRef is exclusive OR.</p>
<a href="#">EthIfRxIndicationConfig</a>	1..*	Configuration of receive callback functions.
<a href="#">EthIfSwitch</a>	0..*	This container contains the configuration of EthIfSwitches.
<a href="#">EthIfSwitchPortGroup</a>	0..*	<p>This container contains the configuration of EthIfSwitchPort Groups.</p> <p>If EthIfSwitchPortGroups are controlled by PNC one EthIfSwitchPortGroup per PNC shall exist.</p> <p>The host port shall be part of all EthIfSwitchPortGroups.</p> <p>The up link port of a master switch and the up link port of the slave switch shall be part of all EthIfSwitchPortGroups that contain EthSwtPorts belonging to the slave switch.</p>
<a href="#">EthIfTransceiver</a>	0..*	<p>This container contains the configuration of EthIfTransceiver.</p> <p>The usage of EthIfEthTrcvRef, EthIfCanXLTrcvRef, and EthIfWEthTrcvRef is exclusive OR.</p>
<a href="#">EthIfTrcvLinkStateChgConfig</a>	1..*	Specifies link state change callback function
<a href="#">EthIfTxConfirmationConfig</a>	0..*	Configuration of transmit indication callback functions.

## 10.2.4 EthIfController

<b>SWS Item</b>	[ECUC_EthIf_00025]
<b>Container Name</b>	EthIfController
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	This container contains the configuration of EthIfController.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	[ECUC_EthIf_00026]		
<b>Parameter Name</b>	EthIfCtrlIdx		
<b>Parent Container</b>	<a href="#">EthIfController</a>		
<b>Description</b>	This parameter provides a zero-based consecutive index of the Ethernet Communication Controllers. Upper layer BSW modules and the EthIf itself use this index to identify a Ethernet CC.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	0 .. 255		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	[ECUC_EthIf_00032]		
<b>Parameter Name</b>	EthIfCtrlMtu		
<b>Parent Container</b>	<a href="#">EthIfController</a>		
<b>Description</b>	Specifies the maximum transmission unit (MTU) of the EthIfCtrl in [bytes]. Note: In case a VLAN tag is used for the EthIfCtrl, the frame length of the Ethernet frame will increase by 4 bytes.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	64 .. 9000		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU dependency: 1) EthIfVlanId. 2) [Draft] If EthIfController.EthIfMacSecSupport is set to HW_MACSEC or SW_MACSEC then the Mtu will need a proper adaption of the MTU size (MTU size has to be decreased by 24 bytes to avoid packets with a greater size than 1500).		

<b>SWS Item</b>	[ECUC_EthIf_00089]
<b>Parameter Name</b>	EthIfMacSecSupport
<b>Parent Container</b>	<a href="#">EthIfController</a>





<b>Description</b>	MACsec support of the ethernet interface controller. <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucEnumerationParamDef		
<b>Range</b>	HW_MACSEC	–	<b>Tags:</b> atp.Status=draft
	NO_MACSEC	–	<b>Tags:</b> atp.Status=draft
	SW_MACSEC	–	<b>Tags:</b> atp.Status=draft
<b>Default value</b>	<a href="#">NO_MACSEC</a>		
<b>Post-Build Variant Multiplicity</b>	true		
<b>Post-Build Variant Value</b>	true		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00002]</b>		
<b>Parameter Name</b>	EthIfMaxTxBufsTotal		
<b>Parent Container</b>	<a href="#">EthIfController</a>		
<b>Description</b>	Limits the total number of transmit buffers.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	1 .. 4294967295		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00029]</b>		
<b>Parameter Name</b>	EthIfVlanId		
<b>Parent Container</b>	<a href="#">EthIfController</a>		
<b>Description</b>	A virtual-LAN is identified by this attribute according to IEEE 802.1Q.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	0 .. 4095		
<b>Default value</b>	–		
<b>Post-Build Variant Multiplicity</b>	true		
<b>Post-Build Variant Value</b>	true		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE





Value Configuration Class	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: ECU		

SWS Item	[ECUC_EthIf_00028]		
Parameter Name	EthIfEthTrcvRef		
Parent Container	<a href="#">EthIfController</a>		
Description	Reference to an Ethernet transceiver, which is handled by the Ethernet Interface.		
Multiplicity	0..1		
Type	Symbolic name reference to <a href="#">EthIfTransceiver</a>		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: ECU		

SWS Item	[ECUC_EthIf_00090]		
Parameter Name	EthIfPaeInstanceRef		
Parent Container	<a href="#">EthIfController</a>		
Description	Reference to MkaPaeInstance <b>Tags:</b> atp.Status=draft		
Multiplicity	0..1		
Type	Symbolic name reference to MkaPaeInstance		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	[ECUC_EthIf_00027]		
Parameter Name	EthIfPhysControllerRef		
Parent Container	<a href="#">EthIfController</a>		
Description	Reference to a physical Ethernet controller, which is handled by the Ethernet Interface.		
Multiplicity	1		
Type	Symbolic name reference to <a href="#">EthIfPhysController</a>		







<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00048]</b>		
<b>Parameter Name</b>	EthIfSwitchRefOrPortGroupRef		
<b>Parent Container</b>	<a href="#">EthIfController</a>		
<b>Description</b>	<p>The choice reference allows to configure that the EthIfController either references an EthIfSwitch or an EthIfSwitchPortGroup.</p> <p>In case EthIfSwitchPortGroups are controlled by the BswM (e.g. according particular PNC requests), then EthIfSwitchPortGroupRefSemantics shall have the value ETHIF_SWITCH_PORT_GROUP_LINK_INFO. In case EthIfSwitchPortGroups are controlled by the EthIfController, then EthIfSwitchPortGroupRefSemantics shall have the value ETHIF_SWITCH_PORT_GROUP_CONTROL.</p>		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Choice reference to [ <a href="#">EthIfSwitch</a> , <a href="#">EthIfSwitchPortGroup</a> ]		
<b>Post-Build Variant Multiplicity</b>	true		
<b>Post-Build Variant Value</b>	true		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	<p>scope: local</p> <p>dependency: * The configuration of EthIfSwitchRefOrPortGroupRef shall only be valid, if this EthIfController has no EthIfEthTrcvRef configured. * If EthIfSwitchPortGroups are configured, then all EthIfController which refer to the same EthIfPhysController shall reference an EthIfSwitchPortGroup. * If EthIfSwitchPortGroups are configured, then also EthIfSwitches shall be configured according to the corresponding EthSwIfConfig. Those EthIfSwitches shall not be referenced by any EthIfController. (Please note: the EthIfSwitches are used to provide the according EthIfSwitchIdx in the context of EthIf module, which abstracts the underlying switch hardware and is needed in several APIs, e.g. EthSwIf_GetSwitchPortWakeupReason).</p>		

<b>No Included Containers</b>
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### 10.2.5 EthIfFrameOwnerConfig

<b>SWS Item</b>	<b>[ECUC_EthIf_00011]</b>
<b>Container Name</b>	EthIfFrameOwnerConfig
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	Configuration of Ethernet frame owner
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>[ECUC_EthIf_00012]</b>		
<b>Parameter Name</b>	EthIfFrameType		
<b>Parent Container</b>	<a href="#">EthIfFrameOwnerConfig</a>		
<b>Description</b>	Selects the Ethernet frame type.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	0 .. 65535		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00013]</b>		
<b>Parameter Name</b>	EthIfOwner		
<b>Parent Container</b>	<a href="#">EthIfFrameOwnerConfig</a>		
<b>Description</b>	Selects the owner of an Ethernet frame type. The owner is a zero based index into the callback function configuration 'EthIfRxIndicationConfig'. I.e. an Ethernet frame of type IPv4 (0x800) at index 0 will call the first callback function configured in 'EthIfRxIndicationConfig'.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	0 .. 255		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>No Included Containers</b>
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## 10.2.6 EthIfPhysController

<b>SWS Item</b>	<b>[ECUC_EthIf_00045]</b>
<b>Container Name</b>	EthIfPhysController
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	This container contains the configuration of EthIfPhysController. The usage of EthIfEthCtrlRef, EthIfCanXLCtrlRef, and EthIfWEthCtrlRef and EthIfCV2xCtrlRef is exclusive OR.
<b>Post-Build Variant Multiplicity</b>	false
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>[ECUC_EthIf_00046]</b>		
<b>Parameter Name</b>	EthIfPhysControllerIdx		
<b>Parent Container</b>	<a href="#">EthIfPhysController</a>		
<b>Description</b>	This parameter provides a zero-based consecutive index of the physical Ethernet controllers. Upper layer BSW modules and the Ethernet Interface itself use this index to identify a physical Ethernet controller.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	0 .. 255		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00085]</b>		
<b>Parameter Name</b>	EthIfCanXLCtrlRef		
<b>Parent Container</b>	<a href="#">EthIfPhysController</a>		
<b>Description</b>	Reference to a physical CAN XL controller which is handled by a specific CAN XL driver.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to CanController		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: ECU dependency: The referenced CanController has to contain a CanXLController.		

<b>SWS Item</b>	<b>[ECUC_EthIf_00093]</b>		
<b>Parameter Name</b>	EthIfCV2xCtrlRef		
<b>Parent Container</b>	<a href="#">EthIfPhysController</a>		
<b>Description</b>	Reference to physical Cellular V2X controller, which is handled by a specific Cellular V2X controller driver <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to CV2xCtrlConfig		
<b>Post-Build Variant Multiplicity</b>	true		
<b>Post-Build Variant Value</b>	true		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE





	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00047]</b>		
<b>Parameter Name</b>	EthIfEthCtrlRef		
<b>Parent Container</b>	<a href="#">EthIfPhysController</a>		
<b>Description</b>	Reference to a physical Ethernet controller, which is handled by a specific Ethernet controller driver.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to EthCtrlConfig		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00073]</b>		
<b>Parameter Name</b>	EthIfWEthCtrlRef		
<b>Parent Container</b>	<a href="#">EthIfPhysController</a>		
<b>Description</b>	Reference to a physical Wireless Ethernet controller, which is handled by a specific Wireless Ethernet controller driver.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to WEthCtrlConfig		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU		

<b>Included Containers</b>		
<b>Container Name</b>	<b>Multiplicity</b>	<b>Scope / Dependency</b>
<a href="#">EthIfPhysCtrlRxMainFunctionPriorityProcessing</a>	0..*	Configuration of ingress FIFO based main function processing.

**[SWS\_EthIf\_CONSTR\_00001]** [The `EthIfPhysController` and `EthIfTransceiver` shall always refer to the same bus type: If `EthIfPhysController` refers to an `EthIfEthCtrlRef`, `EthIfTransceiver` shall refer to a `EthIfEthTrcvRef`. If `EthIfPhysController` refers to an `EthIfWEthCtrlRef`, `EthIfTransceiver` shall refer to a `EthIfWEthTrcvRef`. If `EthIfPhysController` refers to an `EthIfCanXLCtrlRef`, `EthIfTransceiver` shall refer to a `EthIfCanXLTrcvRef`.]()

## 10.2.7 EthIfPhysCtrlRxMainFunctionPriorityProcessing

<b>SWS Item</b>	[ECUC_EthIf_00050]		
<b>Container Name</b>	EthIfPhysCtrlRxMainFunctionPriorityProcessing		
<b>Parent Container</b>	<a href="#">EthIfPhysController</a>		
<b>Description</b>	Configuration of ingress FIFO based main function processing.		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Configuration Parameters</b>			

<b>SWS Item</b>	[ECUC_EthIf_00052]		
<b>Parameter Name</b>	EthIfPhysCtrlRxIndicationIterations		
<b>Parent Container</b>	<a href="#">EthIfPhysCtrlRxMainFunctionPriorityProcessing</a>		
<b>Description</b>	Max number of Ethernet frames polled per main function invocation.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef		
<b>Range</b>	0 .. 18446744073709551615		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00051]		
<b>Parameter Name</b>	EthIfPhysCtrlRxMainFunctionPeriod		
<b>Parent Container</b>	<a href="#">EthIfPhysCtrlRxMainFunctionPriorityProcessing</a>		
<b>Description</b>	Specifies the period of main function in seconds.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucFloatParamDef		
<b>Range</b>	[-INF .. INF]		
<b>Default value</b>	–		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	[ECUC_EthIf_00087]		
<b>Parameter Name</b>	EthIfCanXLCtrlRxIngressFifoRef		
<b>Parent Container</b>	<a href="#">EthIfPhysCtrlRxMainFunctionPriorityProcessing</a>		
<b>Description</b>	Reference to the reception FIFO.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to CanXLEthIngressFifo		





<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local dependency: Mutually exclusive with EthIfPhysCtrlRxIngressQueueRef. One of the two parameters is required.		

<b>SWS Item</b>	<b>[ECUC_EthIf_00053]</b> (Obsolete)		
<b>Parameter Name</b>	EthIfPhysCtrlRxIngressFifoRef		
<b>Parent Container</b>	<a href="#">EthIfPhysCtrlRxMainFunctionPriorityProcessing</a>		
<b>Description</b>	Reference to the reception FIFO. <b>Tags:</b> atp.Status=obsolete		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to EthCtrlConfigIngressFifo		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local dependency: Mutually exclusive with EthIfCanXLCtrlRxIngressFifoRef. One of the two parameters is required.		

<b>SWS Item</b>	<b>[ECUC_EthIf_00088]</b>		
<b>Parameter Name</b>	EthIfPhysCtrlRxIngressQueueRef		
<b>Parent Container</b>	<a href="#">EthIfPhysCtrlRxMainFunctionPriorityProcessing</a>		
<b>Description</b>	Reference to the reception Queue. <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to EthCtrlConfigEgressQueue		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	





<b>Scope / Dependency</b>	scope: local dependency: Mutually exclusive with EthIfCanXLCtrlRxIngressFifoRef. One of the two parameters is required.
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<b>No Included Containers</b>
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## 10.2.8 EthIfRxIndicationConfig

<b>SWS Item</b>	[ECUC_EthIf_00014]
<b>Container Name</b>	EthIfRxIndicationConfig
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	Configuration of receive callback functions.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	[ECUC_EthIf_00015]		
<b>Parameter Name</b>	EthIfRxIndicationFunction		
<b>Parent Container</b>	<a href="#">EthIfRxIndicationConfig</a>		
<b>Description</b>	Specifies receive indication callback function.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucFunctionNameDef		
<b>Default value</b>	–		
<b>Regular Expression</b>	–		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>No Included Containers</b>
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## 10.2.9 EthIfSwitch

<b>SWS Item</b>	[ECUC_EthIf_00036]
<b>Container Name</b>	EthIfSwitch
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	This container contains the configuration of EthIfSwitches.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	[ECUC_EthIf_00037]
<b>Parameter Name</b>	EthIfSwitchIdx
<b>Parent Container</b>	<a href="#">EthIfSwitch</a>





<b>Description</b>	This parameter provides a zero-based consecutive index of the Ethernet Interface Switches. Upper layer BSW modules and the EthIf itself use this index to identify a Ethernet Switch.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	0 .. 255		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00038]</b>		
<b>Parameter Name</b>	EthIfSwitchRef		
<b>Parent Container</b>	<a href="#">EthIfSwitch</a>		
<b>Description</b>	Reference to a Ethernet Switch, which is handled by a specific Ethernet Switch driver.		
<b>Multiplicity</b>	1		
<b>Type</b>	Symbolic name reference to EthSwTConfig		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU		

<b>No Included Containers</b>
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## 10.2.10 EthIfSwitchPortGroup

<b>SWS Item</b>	<b>[ECUC_EthIf_00057]</b>
<b>Container Name</b>	EthIfSwitchPortGroup
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	<p>This container contains the configuration of EthIfSwitchPortGroups.</p> <p>If EthIfSwitchPortGroups are controlled by PNC one EthIfSwitchPortGroup per PNC shall exist.</p> <p>The host port shall be part of all EthIfSwitchPortGroups.</p> <p>The up link port of a master switch and the up link port of the slave switch shall be part of all EthIfSwitchPortGroups that contain EthSwTPorts belonging to the slave switch.</p>
<b>Configuration Parameters</b>	

<b>SWS Item</b>	<b>[ECUC_EthIf_00058]</b>
<b>Parameter Name</b>	EthIfSwitchPortGroupIdx
<b>Parent Container</b>	<a href="#">EthIfSwitchPortGroup</a>







<b>Description</b>	This parameter provides a zero-based consecutive index of the Ethernet Switch Port Groups. Upper layer BSW modules and the EthIf itself use this index to identify an Ethernet Switch Port Group.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	0 .. 255		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00059]</b>		
<b>Parameter Name</b>	EthIfSwitchPortGroupRefSemantics		
<b>Parent Container</b>	<a href="#">EthIfSwitchPortGroup</a>		
<b>Description</b>	Defines how the EthIfSwitchRefOrPortGroupRef referring to a EthIfSwitchPortGroup shall be interpreted.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucEnumerationParamDef		
<b>Range</b>	ETHIF_SWITCH_PORT_GROUP_CONTROL	Used in case all ports in this group are controlled by the EthIf Controller.	
	ETHIF_SWITCH_PORT_GROUP_LINK_INFO	Used in case all ports in this group are controlled by EthIf_SwitchPortGroupRequestMode.	
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local dependency: only valid if a EthIfSwitchRefOrPortGroupRef refers to the EthIfSwitchPortGroup.		

<b>SWS Item</b>	<b>[ECUC_EthIf_00060]</b>		
<b>Parameter Name</b>	EthIfPortRef		
<b>Parent Container</b>	<a href="#">EthIfSwitchPortGroup</a>		
<b>Description</b>	Reference to an Ethernet Switch Port.		
<b>Multiplicity</b>	1..*		
<b>Type</b>	Symbolic name reference to EthSwtPort		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>No Included Containers</b>
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### 10.2.11 EthIfTransceiver

<b>SWS Item</b>	[ECUC_EthIf_00042]
<b>Container Name</b>	EthIfTransceiver
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	This container contains the configuration of EthIfTransceiver. The usage of EthIfEthTrcvRef, EthIfCanXLTrcvRef, and EthIfWEthTrcvRef is exclusive OR.
<b>Post-Build Variant Multiplicity</b>	false
<b>Configuration Parameters</b>	

<b>SWS Item</b>	[ECUC_EthIf_00078]		
<b>Parameter Name</b>	EthIfQualifiedUnexpectedLinkDownTime		
<b>Parent Container</b>	<a href="#">EthIfTransceiver</a>		
<b>Description</b>	Specifies the time in seconds an unexpected link down is qualified. This parameter is only used for those Ethernet channels where the ECU act as a passive communication slave (referenced EthTrcv set EthTrcvActAsSlavePassiveEnabled = TRUE). The value shall be a multiple integral of EthIf_MainFunctionState.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	EcucFloatParamDef		
<b>Range</b>	]0 .. INF[		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU dependency: 1.) If this parameter is set, EthIf_MainFunctionState has to be available 2.) Only applicable if the referenced EthTrcv has set EthTrcvActAsSlavePassive Enabled to TRUE.		

<b>SWS Item</b>	[ECUC_EthIf_00043]		
<b>Parameter Name</b>	EthIfTransceiverIdx		
<b>Parent Container</b>	<a href="#">EthIfTransceiver</a>		
<b>Description</b>	This parameter provides a zero-based consecutive index of the Ethernet transceivers. Upper layer BSW modules and the Ethernet Interface itself use this index to identify an Ethernet transceiver.		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucIntegerParamDef (Symbolic Name generated for this parameter)		
<b>Range</b>	0 .. 255		
<b>Default value</b>	-		
<b>Post-Build Variant Value</b>	false		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	-	
	<b>Post-build time</b>	-	
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00086]</b>		
<b>Parameter Name</b>	EthIfCanXLTrcvRef		
<b>Parent Container</b>	<a href="#">EthIfTransceiver</a>		
<b>Description</b>	Reference to a CAN XL transceiver, which is handled by a specific CAN XL transceiver driver.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to CanTrcvChannel		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: ECU dependency: The referenced CanTrcvChannel has to contain a CanTrcvXLChannel.		

<b>SWS Item</b>	<b>[ECUC_EthIf_00044]</b>		
<b>Parameter Name</b>	EthIfEthTrcvRef		
<b>Parent Container</b>	<a href="#">EthIfTransceiver</a>		
<b>Description</b>	Reference to an Ethernet transceiver, which is handled by a specific Ethernet transceiver driver.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to EthTrcvConfig		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU		

<b>SWS Item</b>	<b>[ECUC_EthIf_00074]</b>		
<b>Parameter Name</b>	EthIfWEthTrcvRef		
<b>Parent Container</b>	<a href="#">EthIfTransceiver</a>		
<b>Description</b>	Reference to an Wireless Ethernet transceiver, which is handled by a specific Wireless Ethernet transceiver driver.		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to WEthTrcvConfig		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: ECU		

**No Included Containers**

### 10.2.12 EthIfTrcvLinkStateChgConfig

<b>SWS Item</b>	[ECUC_EthIf_00018]
<b>Container Name</b>	EthIfTrcvLinkStateChgConfig
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	Specifies link state change callback function
<b>Configuration Parameters</b>	

<b>SWS Item</b>	[ECUC_EthIf_00019]		
<b>Parameter Name</b>	EthIfTrcvLinkStateChgFunction		
<b>Parent Container</b>	<a href="#">EthIfTrcvLinkStateChgConfig</a>		
<b>Description</b>	Specifies link state change callback function		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucFunctionNameDef		
<b>Default value</b>	-		
<b>Regular Expression</b>	-		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD
<b>Scope / Dependency</b>	scope: local		

<b>No Included Containers</b>
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### 10.2.13 EthIfTxConfirmationConfig

<b>SWS Item</b>	[ECUC_EthIf_00016]
<b>Container Name</b>	EthIfTxConfirmationConfig
<b>Parent Container</b>	<a href="#">EthIfConfigSet</a>
<b>Description</b>	Configuration of transmit indication callback functions.
<b>Configuration Parameters</b>	

<b>SWS Item</b>	[ECUC_EthIf_00017]		
<b>Parameter Name</b>	EthIfTxConfirmationFunction		
<b>Parent Container</b>	<a href="#">EthIfTxConfirmationConfig</a>		
<b>Description</b>	Specifies transmit indication callback function		
<b>Multiplicity</b>	1		
<b>Type</b>	EcucFunctionNameDef		
<b>Default value</b>	-		
<b>Regular Expression</b>	-		
<b>Post-Build Variant Value</b>	true		
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	VARIANT-PRE-COMPILE
	<b>Link time</b>	X	VARIANT-LINK-TIME
	<b>Post-build time</b>	X	VARIANT-POST-BUILD





<b>Scope / Dependency</b>	scope: local
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<b>No Included Containers</b>
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## 10.2.14 EthIfSecurityEventRefs

<b>SWS Item</b>	<b>[ECUC_EthIf_00080]</b>		
<b>Container Name</b>	EthIfSecurityEventRefs		
<b>Parent Container</b>	<a href="#">EthIfGeneral</a>		
<b>Description</b>	Container for the references to IdsMEvent elements representing the security events that the EthIf module shall report to the IdsM in case the corresponding security related event occurs (and if EthIfEnableSecurityEventReporting is set to "true"). The standardized security events in this container can be extended by vendor-specific security events. <b>Tags:</b> atp.Status=draft		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Configuration Parameters</b>			

<b>SWS Item</b>	<b>[ECUC_EthIf_00084]</b>		
<b>Parameter Name</b>	ETHIF_SEV_DROP_ETH_MAC_COLLISION		
<b>Parent Container</b>	<a href="#">EthIfSecurityEventRefs</a>		
<b>Description</b>	An Ethernet datagram was dropped because local MAC was same as source MAC in an incoming frame. <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to IdsMEvent		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00083]</b>		
<b>Parameter Name</b>	ETHIF_SEV_DROP_INV_VLAN		
<b>Parent Container</b>	<a href="#">EthIfSecurityEventRefs</a>		
<b>Description</b>	An Ethernet datagram was dropped due to an invalid CrtIdx/VLAN. <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	0..1		





<b>Type</b>	Symbolic name reference to IdsMEvent		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00081]</b>		
<b>Parameter Name</b>	ETHIF_SEV_DROP_UNKNOWN_ETHERTYPE		
<b>Parent Container</b>	<a href="#">EthIfSecurityEventRefs</a>		
<b>Description</b>	An Ethernet datagram was dropped due to an unknown Ethertype. <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to IdsMEvent		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>SWS Item</b>	<b>[ECUC_EthIf_00082]</b>		
<b>Parameter Name</b>	ETHIF_SEV_DROP_VLAN_DOUBLE_TAG		
<b>Parent Container</b>	<a href="#">EthIfSecurityEventRefs</a>		
<b>Description</b>	An Ethernet datagram was dropped due to double VLAN tag. <b>Tags:</b> atp.Status=draft		
<b>Multiplicity</b>	0..1		
<b>Type</b>	Symbolic name reference to IdsMEvent		
<b>Post-Build Variant Multiplicity</b>	false		
<b>Post-Build Variant Value</b>	false		
<b>Multiplicity Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Value Configuration Class</b>	<b>Pre-compile time</b>	X	All Variants
	<b>Link time</b>	–	
	<b>Post-build time</b>	–	
<b>Scope / Dependency</b>	scope: local		

<b>No Included Containers</b>
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### **10.3 Published Information**

For details refer to the chapter 10.3 “Published Information” in SWS\_BSWGeneral [6].

## A Not applicable requirements

**[SWS\_EthIf\_00999]** [These requirements are not applicable to this specification.]  
([SRS\\_BSW\\_00170](#))