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2014-10-31	4.2.1	AUTOSAR Release Management	 New API and configuration containers to support EcuM Fixed for Multi Core Addition of new container for defining mode values: BswMCompuScaleModeValue New Action BswMFrSMAllSlots for invoking FrSM_AllSlots New requirements for: Action list execution (SWS_BswM_00223) and Deadline Monitoring (SWS_BswM_00224,00225)
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2013-03-15	4.1.1	AUTOSAR Administration	 Extended to support Pretended Networking mode handling Extended to support Heavy Duty Vehicles and J1939
2011-12-22	4.0.3	AUTOSAR Administration	 Support of Mode Machine Instances assigned to the SchM Include of user defined header files Possibility to provide an initial value for a BswMModeRequestPort
2009-12-18	4.0.1	AUTOSAR Administration	 Include file BswMUserCallout.h added. This user defined header file contains declarations of the call out functions. Requirement that the BswM module shall perform inter module version checks added Information added for each configurable action which API to call Functions BswM_TriggerSlaveRTEStop and BswM_TriggerStartUpPhase2 added to control the start and stop of the RTE on slave cores
2010-02-02	3.1.4	AUTOSAR Administration	Initial release



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1 Introduction and functional overview

This specification specifies the functionality, API and the configuration of the AUTOSAR Basic Software module BSW Mode Manager (BswM).

The BSW Mode Manager is the module that implements the part of the Vehicle Mode Management and Application Mode Management concept that resides in the BSW. Its responsibility is to arbitrate mode requests from application layer SW-Cs or other BSW modules based on simple rules, and perform actions based on the arbitration result.



2 Acronyms and abbreviations

Abbreviation / Acronym	Description
BSW	Basic Software
BswM	BSW Mode Manager
BSWMD	Basic Software Module Description
CDD	Complex Driver
Dem	Diagnostic Event Manager
Det	Default Error Tracer
ECU	Electronic Control Unit
RTE	Real Time Environment
SWC / SW-C	Software Component
SWCD	Software Component Description

Table 2.1: Table of acronyms and abbreviations



3 Related documentation

3.1 Input documents & related standards and norms

- [1] General Specification of Basic Software Modules AUTOSAR_SWS_BSWGeneral
- [2] Guide to Mode Management AUTOSAR_EXP_ModeManagementGuide
- [3] General Requirements on Basic Software Modules AUTOSAR_SRS_BSWGeneral
- [4] Requirements on Mode Management AUTOSAR_SRS_ModeManagement
- [5] Specification of Basic Software Mode Manager AUTOSAR SWS BSWModeManager
- [6] Specification of RTE Software AUTOSAR SWS RTE

3.2 Related specification

AUTOSAR provides a General Specification on Basic Software modules (see [1]), which is also valid for BSW Mode Manager.

Thus, the specification [1] shall be considered as additional and required specification for BSW Mode Manager.

Information regarding the configuration and usage of the BSW Mode Manager is found in the auxillary document: Guide to Mode Management [2]



4 Constraints and assumptions

4.1 Limitations

Maximum one instance of the BSW Mode Manager may be used within a partition.

4.2 Applicability to car domains

The BSW Mode Manager is applicable to all car domains.



5 Dependencies to other modules

The BSW Mode Manager has interfaces to many of the BSW Modules in the AUTOSAR architecture. The majority of these interfaces are however optional and are used based on the needs of each ECU.

The dependencies listed in this chapter are intended to give an overview of some possible interactions between the BswM and other modules. The interactions and modules listed herein should not be considered an exhaustive list of all possibilities.

5.1 RTE

The BswM receives mode requests from the SW-Cs via the RTE. Mode Switch Notifications are also propagated to the SW-Cs via the RTE.

5.2 EcuM - Flex

EcuM Flex can indicate the state of its wakeup sources to BswM. When ECU Mode Handling is used, BswM can set the state of EcuM - Flex and receives status of certain modes based on the RUN Request Protocol.

5.3 ComM

Mode Switch Indications originating from the ComM go through the BswM for further propagation to the SW-Cs.

The BswM can request communication modes at the ComM by means of ComMUsers.

5.4 COM

The handling of I-PDU Groups in COM is performed by the BswM. As a part of I-PDU group start/stop, it is possible to have the included signal values reset to their corresponding initialization values.

BswM handles the enabling and disabling of deadline monitoring of signals in COM.

BswM can also trigger transmission of an I-PDU.

5.5 PduR

The BswM can enable and disable routing groups of I-PDUs in the PDU router.



5.6 CanSM

Mode Switch Indications originating from the CanSM go through the BswM for further propagation to the SW-Cs.

5.7 LinSM

BswM coordinates switching of LIN Schedule Tables in the LinSM with starting and stopping of the corresponding I-PDU groups in COM.

Mode Switch Indications originating from the LinSM go through the BswM for further propagation to the SW-Cs.

5.8 LinTp

The LIN Transport Protocol that is a part of LinIf requests modes from BswM to make sure that the correct LIN Schedule Table is active during LinTp operation.

5.9 FrSM

Mode Switch Indications originating from the FrSM go through the BswM for further propagation to the SW-Cs.

The usage of "Single Slot Mode" on FlexRay is controlled by the FrSM by request of BswM. The send capability of the FlexRay stack can be controlled by the BswM via FrSM by calling the API FrSM_SetEcuPassive.

5.10 **EthSM**

Mode Switch Indications originating from the EthSM go through the BswM for further propagation to the SW-Cs.

5.11 DCM

The DCM performs mode requests to the BswM based on the diagnostic requests it receives.

Example: DCM can request "Disable Normal Communication". During this mode BswM will turn off the corresponding I-PDU groups and NM PDUs.



5.12 J1939Dcm

The J1939Dcm reports communication state changes to the BswM for further propagation to the SW-Cs. BswM changes states of J1939Dcm via J1939Dcm_SetState.

5.13 J1939Nm

The J1939Nm provides a state indication via BswM_J1939Nm_StateChangeNotification.

5.14 J1939Rm

BswM changes states of J1939Rm via J1939Rm_SetState.

5.15 NM Interface

BswM will use the Nm_EnableCommunication and Nm_DisableCommunication to control the NM communication based on the current mode.

Example: In "Disable Normal Communication" mode, the BswM needs to disable NM communication on the corresponding NM channel.

The Nm uses BswM_Nm_CarWakeUpIndication to indicate a CarWakeup.

5.16 NvM

The NvM module reports the state of its blocks to the BswM via "integration code" registered as NvM callbacks. BswM has actions causing the NvM to read and write all blocks during startup and shutdown.

5.17 OS

The features of OS that are required by BswM, are implementation specific.

5.18 Sd

The BswM receives status indications from Sd via several exported APIs (see chapter 8.3 for examples). These status indications from Sd can be configured as BswMModeRequestSources.



5.19 File structure

The BswM may use interfaces in AUTOSAR BSW modules that are not explicitly defined within this specification.



6 Requirements Tracing

The following tables reference the requirements specified in [3] and [4] and links to the fulfillment of these. Please note that if column "Satisfied by" is empty for a specific requirement this means that this requirement is not fulfilled by this document.

Requirement	Description	Satisfied by	
[SRS_BSW_00003]	All software modules shall provide version and identification information	[SWS_BswM_00003]	
[SRS_BSW_00101]	The Basic Software Module shall be able to initialize variables and hardware in a separate initialization function	[SWS_BswM_00002] [SWS_BswM_00043] [SWS_BswM_00044] [SWS_BswM_00261]	
[SRS_BSW_00167]	All AUTOSAR Basic Software Modules shall provide configuration rules and constraints to enable plausibility checks	[SWS_BswM_00240] [SWS_BswM_00242] [SWS_BswM_00243] [SWS_BswM_00256] [SWS_BswM_CONSTR_00001] [SWS_BswM_CONSTR_00002]	
[SRS_BSW_00170]	The AUTOSAR SW Components shall provide information about their dependency from faults, signal qualities, driver demands	[SWS_BswM_NA_09999]	
[SRS_BSW_00301]	All AUTOSAR Basic Software Modules shall only import the necessary information	[SWS_BswM_00001] [SWS_BswM_00237] [SWS_BswM_00279]	
[SRS_BSW_00305]	Data types naming convention	[SWS_BswM_00041]	
[SRS_BSW_00323]	All AUTOSAR Basic Software Modules shall check passed API parameters for validity	[SWS_BswM_00045] [SWS_BswM_00089] [SWS_BswM_00090] [SWS_BswM_00091] [SWS_BswM_00093] [SWS_BswM_00095] [SWS_BswM_00097] [SWS_BswM_00099] [SWS_BswM_00101] [SWS_BswM_00103] [SWS_BswM_00110] [SWS_BswM_00113] [SWS_BswM_00133] [SWS_BswM_00150] [SWS_BswM_00154] [SWS_BswM_00206] [SWS_BswM_00209] [SWS_BswM_00212] [SWS_BswM_00228] [SWS_BswM_00229] [SWS_BswM_00268]	
[SRS_BSW_00336]	Basic SW module shall be able to shutdown	[SWS_BswM_00119] [SWS_BswM_00120] [SWS_BswM_NA_09999]	
[SRS_BSW_00339]	Reporting of production relevant error status	[SWS_BswM_NA_09999]	
[SRS_BSW_00344]	BSW Modules shall support link-time configuration	[SWS_BswM_00002]	
[SRS_BSW_00358]	The return type of init() functions implemented by AUTOSAR Basic Software Modules shall be void	[SWS_BswM_00002]	
[SRS_BSW_00384]	The Basic Software Module specifications shall specify at least in the description which other modules they require	[SWS_BswM_00007] [SWS_BswM_00008]	
[SRS_BSW_00385]	List possible error notifications	[SWS_BswM_00230]	
[SRS_BSW_00399]	Parameter-sets shall be located in a separate segment and shall be loaded after the code	[SWS_BswM_NA_09999]	
[SRS_BSW_00400]	Parameter shall be selected from multiple sets of parameters after code has been loaded and started	[SWS_BswM_NA_09999]	
[SRS_BSW_00404]	BSW Modules shall support post-build configuration	[SWS_BswM_00002] [SWS_BswM_00042] [SWS_BswM_00213]	





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Requirement		Satisfied by
[SRS_BSW_00405]	BSW Modules shall support multiple	
	configuration sets	[SWS_BswM_00002] [SWS_BswM_NA_09999]
[SRS_BSW_00406]	A static status variable denoting if a BSW module is initialized shall be initialized with value 0 before any APIs of the BSW module is called	[SWS_BswM_00077] [SWS_BswM_00078] [SWS_BswM_00079] [SWS_BswM_00080] [SWS_BswM_00081] [SWS_BswM_00082] [SWS_BswM_00083] [SWS_BswM_00084] [SWS_BswM_00086] [SWS_BswM_00109] [SWS_BswM_00112] [SWS_BswM_00149] [SWS_BswM_00153] [SWS_BswM_00159] [SWS_BswM_00205] [SWS_BswM_00208] [SWS_BswM_00211] [SWS_BswM_00227] [SWS_BswM_00266] [SWS_BswM_00267]
[SRS_BSW_00407]	Each BSW module shall provide a function to read out the version information of a dedicated module implementation	[SWS_BswM_00003]
[SRS_BSW_00409]	All production code error ID symbols are defined by the Dem module and shall be retrieved by the other BSW modules from Dem configuration	[SWS_BswM_NA_09999]
[SRS_BSW_00414]	Init functions shall have a pointer to a configuration structure as single parameter	[SWS_BswM_00002]
[SRS_BSW_00425]	The BSW module description template shall provide means to model the defined trigger conditions of schedulable objects	[SWS_BswM_00053]
[SRS_BSW_00441]	Naming convention for type, macro and function	[SWS_BswM_00213] [SWS_BswM_00214] [SWS_BswM_00216]
[SRS_BSW_00452]	Classification of runtime errors	[SWS_BswM_00238] [SWS_BswM_00239]
[SRS_BSW_00467]	The init / deinit services shall only be called by BswM or EcuM	[SWS_BswM_00118]
[SRS_ModeMgm 09116]	Requesting and releasing the RUN state shall be provided	[SWS_BswM_91004]
[SRS_ModeMgm 09174]	The BSW Mode Manager [5] shall support the 'disable normal Communication'	[SWS_BswM_00038]
[SRS_ModeMgm 09175]	A configurable Set of Mode dependent enabled and concomitant disabled IPDU groups shall be supported	[SWS_BswM_00038]
[SRS_ModeMgm 09177]	The rules of the mode arbitration shall be pre-compile and post-build configurable	[SWS_BswM_00010] [SWS_BswM_00012] [SWS_BswM_00015] [SWS_BswM_00016] [SWS_BswM_00062] [SWS_BswM_00067] [SWS_BswM_00223] [SWS_BswM_00252] [SWS_BswM_00253] [SWS_BswM_00256]
[SRS_ModeMgm 09178]	The lists of mode transition specific actions shall be pre-compile and post-build configurable	[SWS_BswM_00017] [SWS_BswM_00018] [SWS_BswM_00019] [SWS_BswM_00037] [SWS_BswM_00054] [SWS_BswM_00055] [SWS_BswM_00062] [SWS_BswM_00067] [SWS_BswM_00147] [SWS_BswM_00223] [SWS_BswM_00271] [SWS_BswM_00272] [SWS_BswM_CONSTR_00001]
[SRS_ModeMgm 09179]	The BSW Mode Manager [5] shall provide an Interface to allow Mode Requests of SW-C's	[SWS_BswM_00046] [SWS_BswM_00064] [SWS_BswM_00201] [SWS_BswM_00203] [SWS_BswM_00236]



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Requirement	Description	Satisfied by
[SRS_ModeMgm 09180]	The BSW Mode Manager [5] shall evaluate the current mode requests	[SWS_BswM_00009] [SWS_BswM_00011] [SWS_BswM_00013] [SWS_BswM_00014] [SWS_BswM_00023] [SWS_BswM_00035] [SWS_BswM_00059] [SWS_BswM_00060] [SWS_BswM_00061] [SWS_BswM_00064] [SWS_BswM_00066] [SWS_BswM_00068] [SWS_BswM_00069] [SWS_BswM_00075] [SWS_BswM_00115] [SWS_BswM_00116] [SWS_BswM_00117] [SWS_BswM_00189] [SWS_BswM_00200] [SWS_BswM_00203] [SWS_BswM_00220] [SWS_BswM_00241] [SWS_BswM_00244] [SWS_BswM_00245] [SWS_BswM_00246] [SWS_BswM_00247] [SWS_BswM_00248] [SWS_BswM_00252] [SWS_BswM_00253] [SWS_BswM_00254] [SWS_BswM_00255] [SWS_BswM_00262] [SWS_BswM_00258] [SWS_BswM_00262] [SWS_BswM_00263] [SWS_BswM_00264] [SWS_BswM_00266] [SWS_BswM_00266]
[SRS_ModeMgm 09182]	The BSW Mode Manager [5] shall propagate a performed mode change to all local SW-Cs	[SWS_BswM_00038] [SWS_BswM_00202] [SWS_BswM_00259]
[SRS_ModeMgm 09183]	Configurable Mode Activation initiated Reset of Signals to Initial Values shall be supported	[SWS_BswM_00251]
[SRS_ModeMgm 09184]	The mode manager shall be able to use a COM interface to activate, respectively deactivate, I-PDU groups	[SWS_BswM_00038]
[SRS_ModeMgm 09228]	The BSW Mode Manager [5] shall provide an Interface to allow Mode Requests of BSW Modules	[SWS_BswM_00046] [SWS_BswM_00047] [SWS_BswM_00048] [SWS_BswM_00049] [SWS_BswM_00050] [SWS_BswM_00051] [SWS_BswM_00052] [SWS_BswM_00058] [SWS_BswM_00064] [SWS_BswM_00104] [SWS_BswM_00131] [SWS_BswM_00148] [SWS_BswM_00152] [SWS_BswM_00156] [SWS_BswM_00158] [SWS_BswM_00165] [SWS_BswM_00193] [SWS_BswM_00194] [SWS_BswM_00203] [SWS_BswM_00204] [SWS_BswM_00207] [SWS_BswM_00210] [SWS_BswM_00217] [SWS_BswM_00216] [SWS_BswM_00217] [SWS_BswM_00235] [SWS_BswM_00249] [SWS_BswM_00250] [SWS_BswM_00283] [SWS_BswM_91001] [SWS_BswM_91003] [SWS_BswM_91004]
[SRS_ModeMgm 09229]	The mode manager shall be able to make generic, configured callouts of void functions to other BSW modules	[SWS_BswM_00039] [SWS_BswM_00040]
[SRS_ModeMgm 09230]	All actions shall only be performed on mode change	[SWS_BswM_00011] [SWS_BswM_00023] [SWS_BswM_00066] [SWS_BswM_00260]
[SRS_ModeMgm 09240]	ComM shall notify BswM of any PNC communication state change	[SWS_BswM_00148]

Table 6.1: RequirementsTracing



7 Functional specification

This chapter specifies the functional behavior of the BSW Mode Manager. The operation of the BSW Mode Manager basic functionality can be described as two different tasks: Mode Arbitration and Mode Control.

The Mode Arbitration part initiates mode switches resulting from rule-based arbitration of mode requests and mode indications received from SW-Cs or other BSW modules.

The Mode Control part performs the mode switches by execution of action lists containing mode switch operations of other BSW modules.

The BswM should be seen as a mode management framework module in which behavior is completely defined by its configuration.

There may be different ways of implementing the BswM, such as generation of the complete BswM based on the configuration, or as a rule interpreter that parses an encoded configuration at run time.

However, this specification does not intend to specify any implementation details of the BSW Mode Manager. Hence, any examples stated in this document describing design details should be treated as explanatory text and not as requirements.

7.1 Mode Arbitration

The Mode Arbitration performed by the BswM is simple and rule-based. The rules used for mode arbitration are specified in the configuration of the BSW Mode Manager module.

The rules are composed of trivial Boolean expressions and the mode arbitration is thus expected to have a low runtime impact.

In order to know what action lists to execute, the BswM is required to detect changes in mode arbitration results from previous rule evaluation. How this is done, and the memory needed to store results, is implementation specific and not described in this document.

7.1.1 Arbitration Rules

A rule is a logical expression that is composed of a set of mode request conditions. The rules are evaluated when the input mode requests and mode indications are changed, or during the execution of the BswM main function. The result of the evaluation (True or False) is used to decide about execution of the corresponding mode control Action List.



7.1.2 Mode Conditions and Logical Expressions.

The logical expression that comprises a mode arbitration rule can use different operators such as AND, OR, XOR, NOT and NAND. Each term in the expression corresponds to a mode request condition. If the mode condition references a <code>BswMModeRequest-Port</code>, the condition will verify if a requested or indicated mode is EQUAL or NOT_EQUAL to a certain mode. If the condition references a <code>BswMEventRequestPort</code>, the condition will verify if the request port is SET or CLEAR. <code>BswMEventRequest-Port</code> events requests differ from mode requests in that the requester sends no requested mode/value to the <code>BswM</code> and as such, there is no mode condition for the <code>BswM</code> to evaluate. Rather, there is only the reception of the event for the <code>BswM</code> to evaluate. When the requester sends/calls the event, then the <code>BswMEventRequestPort</code> will be in a SET state. The <code>BswM</code> can then later place the <code>BswMEventRequestPort</code> into a CLEAR state by executing a <code>BswMClearEventRequest</code> action. An example rule with two conditions is shown in Figure 7.1. The rules and the set of available logical operations are defined as a part of the ECU configuration described in chapter 10.2.



Figure 7.1: Pseudocode representation of an example rule with two conditions.



[SWS_BswM_00252] [When a BswMModeCondition has BswMConditionType = BSWM EVENT IS SET and references a BswMEventRequestPort:

- if the BswMEventRequestPort is in a SET state, then the BswMModeCondition shall evaluate to TRUE
- if the BswMEventRequestPort is in a CLEAR state, then the BswMModeCondition shall evaluate to FALSE

(SRS ModeMgm 09180, SRS ModeMgm 09177)

[SWS_BswM_00253] [When a BswMModeCondition has BswMConditionType = BSWM EVENT_IS_CLEARED and references a BswMEventRequestPort:

- if the BswMEventRequestPort is in a SET state, then the BswMModeCondition shall evaluate to FALSE
- if the BswMEventRequestPort is in a CLEAR state, then the BswMModeCondition shall evaluate to TRUE

(SRS ModeMgm 09180, SRS ModeMgm 09177)

[SWS_BswM_00254] [When the BswM receives an event on a configured BswMEven-tRequestPort (e.g. BswM_ComM_InitiateReset is called by the ComM), the BswMEventRequestPort shall be placed in a SET state. | (SRS_ModeMgm_09180)

[SWS_BswM_00255] [When a BswMClearEventRequest action is executed on a BswMEventRequestPort, the BswMEventRequestPort shall be placed in a CLEAR state. | (SRS_ModeMgm_09180)

7.1.3 Requirements of Mode Arbitration

As mentioned above, the BswM accepts mode requests and mode indications as input for the mode arbitration. Mode requests normally originate from the application SW-Cs but may also originate from other BSW modules such as the DCM. Mode indications are always issued by other BSW modules, such as the different bus specific State Managers and the EcuM. In this document, the generic term mode arbitration request corresponds either to a mode indication or to a mode request.

[SWS_BswM_00009] [The BswM shall perform mode arbitration based on incoming mode requests.] (SRS ModeMgm 09180)

[SWS_BswM_00035] [The BswM shall perform mode arbitration based on incoming mode indications.] (SRS_ModeMgm_09180)

[SWS_BswM_00278] [The BswM shall perform mode arbitration based on event requests as well as the clearing of event requests.]

Note: All mode arbitration requests (requests and indications) are handled in the same way by the BswM. They are configured by selection of the corresponding mode condition type in the BswMModeRequestSource configuration container.



[SWS_BswM_00010] [The BswM shall perform mode arbitration using configured rules.] (SRS_ModeMgm_09177)

[SWS_BswM_00012] The mode arbitration rules shall be configurable using the module configuration parameters. | (SRS_ModeMgm_09177)

[SWS_BswM_00117] [BswM is not allowed to use results of previous arbitration rule evaluations as input for the logical expressions. | (SRS_ModeMgm_09180)

Note: Requirement [SWS_BswM_00117] exists to prohibit using the results of rule evaluations as the input to other rule evaluations. It is largely satisfied by the existing structure of the BswM Configuration containers, because the configurable inputs for logical expressions excludes the results of previous rule evaluations.

[SWS_BswM_00147] The action(s) invoked as a result of evaluating a BswM arbitration rule may be called only in the context of an action list. (SRS ModeMgm 09178)

[SWS_BswM_00189] [The BswM shall perform mode arbitration based on incoming mode switch notifications.] (SRS_ModeMgm_09180)

7.1.3.1 Immediate and Deferred Operation

There are two different ways to schedule the processing of the mode arbitration. It is either done immediately within the context of a mode request/indication, or deferred (cyclically) to the main function of the BswM.

An 'immediate' request is executed in the context of the caller. It is the responsibility of the system integrator to ensure that execution of the action list does not jeopardize system performance or consistency.

Especially, if the caller runs (or may run) in interrupt context, the restrictions concerning usage of system functions in interrupt context apply.

The difference between immediate and deferred operation is shown in the sequence diagrams in section 9.1 and 9.2.

[SWS_BswM_00061] \[A \text{ mode arbitration rule may contain any combination of immediate and deferred mode arbitration requests. \[(SRS \text{ ModeMgm 09180}) \]

[SWS_BswM_00013] [It shall be possible to configure the BswM to execute the mode arbitration immediately upon a mode arbitration request. This is configured by setting the BswMRequestProcessing configuration parameter (within the BswMModeRequestPort container) to BSWM_IMMEDIATE.] (SRS_ModeMgm_09180)

[SWS_BswM_00059] [Only the mode arbitration rules that use a specific immediate mode condition shall be evaluated by the BswM within the context of that specific mode request/indication.] (SRS_ModeMgm_09180)



[SWS_BswM_00014] [It shall (also) be possible to defer the mode arbitration until the execution of the main function of the BswM. This is configured by setting the BswM-RequestProcessing configuration parameter (within the BswMModeRequestPort container) to BSWM_DEFERRED. | (SRS_ModeMgm_09180)

[SWS_BswM_00257] [It shall be possible to configure the BswM to execute the mode arbitration immediately when an event is set. This is configured by setting the BswMEventRequestProcessing configuration parameter (within the BswMEventRequestPort container) to BSWM_IMMEDIATE.|(SRS_ModeMgm_09180)

[SWS_BswM_00258] [It shall (also) be possible to defer the mode arbitration until the execution of the main function of the BswM. This is configured by setting the BswMEventRequestProcessing configuration parameter (within the BswMEventRequestPort container) to BSWM DEFERRED. | (SRS ModeMgm 09180)

[SWS_BswM_00060] [All rules that use at least one deferred mode condition shall be evaluated during every execution of the main function of BswM.] (SRS_ModeMgm_-09180)

[SWS_BswM_00068] [BswM shall postpone mode arbitration requests received during the processing of its main function until it is finished. Any such postponed IM-MEDIATE requests shall be processed directly before the BswM main function exits. Any such postponed DEFERRED requests shall be processed in the next subsequent BswM main function. | (SRS_ModeMgm_09180)

[SWS_BswM_00069] [BswM shall postpone mode arbitration requests received during the processing of an IMMEDIATE request until it is finished. Any such postponed IMMEDIATE requests shall be processed directly after the processing of the original IMMEDIATE request. Any such postponed DEFERRED requests shall be processed in the next subsequent BswM main function. | (SRS_ModeMgm_09180)

The BswM implementation can choose to use protection mechanisms (e.g. Exclusive Area) in order to guarantee that the execution of actions or of the BswM main function does not get interrupted by any other task (for example a higher-priority task).

Terminology clarification for port "updating": Any mode request port has an associated value\state. Updating a port would mean changing its value\state.

[SWS_BswM_00281] [BswM shall update the value of an IMMEDIATE mode request port directly before the arbitration actually takes place and not when the mode request port is triggered.]

[SWS_BswM_00282] [BswM shall update the value of a DEFERRED mode request port when the mode request port is triggered.] ()



7.1.4 Arbitration Behavior after Initialization

The behavior of the mode arbitration of BswM after initialization is controlled by the configuration container <code>BswMModeInitValue</code>. This parameter may be configured once for each <code>BswMModeRequestPort</code> in the configuration.

[SWS_BswM_00064] [If the container <code>BswMModeInitValue</code> does not exist or the ModeRequest does not already have an initial value, the BswM shall treat the corresponding mode condition as undefined and not use it for mode arbitration until the corresponding mode arbitration request has been updated for the first time.] (SRS_-ModeMgm_09179, SRS_ModeMgm_09228, SRS_ModeMgm_09180)

[SWS_BswM_00241] [BswM shall only arbitrate rules that do not contain any undefined mode conditions within its logical expressions. | (SRS_ModeMgm_09180)

The initial value of each <code>BswMModeRequestPort</code> after initialization may be controlled by the configuration container <code>BswMModeInitValue</code>.

[SWS_BswM_00203] [In case BswMModeInitValue is defined the BswM shall initialize the corresponding BswMModeRequestSource with either the BswMBswModeInitValue or the BswMCompuScaleModeValue while the BswM is initialized. The BswM shall reject configurations which contain both a BswMBswModeInitValue and a BswMCompuScaleModeValue for a single BswMModeInitValue. This initialization value shall be used for the arbitration rule until the corresponding mode arbitration request has been updated e.g. each call of BswM_RequestMode shall update the GenericRequest mode.] (SRS_ModeMgm_09179, SRS_ModeMgm_09228, SRS_ModeMgm_09180)

Note: the Rte and SchM modes always have an intial value (see [SRS_Rte_00116])

[SWS_BswM_00251] [Upon initialization of the BswM, all BswMEventRequestPorts shall be initialized to a CLEAR state.] (SRS_ModeMgm_09183)

7.2 Mode Control

The Mode Control part of BswM performs all required actions based on the results of the mode arbitration. This is done using Action Lists. An Action List is an ordered list of actions that the BswM executes when triggered by the Mode Arbitration.

The actions in an Action List can be of three types:

- 1. Calls to other BSW modules or the RTE. A set of pre-defined actions are listed in 7.2.4.
- 2. Links to other action lists to be included in the execution.
- 3. Mode arbitration rules. These rules will be evaluated when the corresponding action list is executed. In this way, a hierarchy of rules is obtained.



The BswM is not required to store or react on any BSW module specific return values on its performed actions. Due to this, the different state managers in the BSW indicate their current state to the BswM to be used as input for the mode arbitration.

However, if an error (E_NOT_OK) is returned, the BswM can issue a Det Runtime Error and/or cancel the currently executing action list.

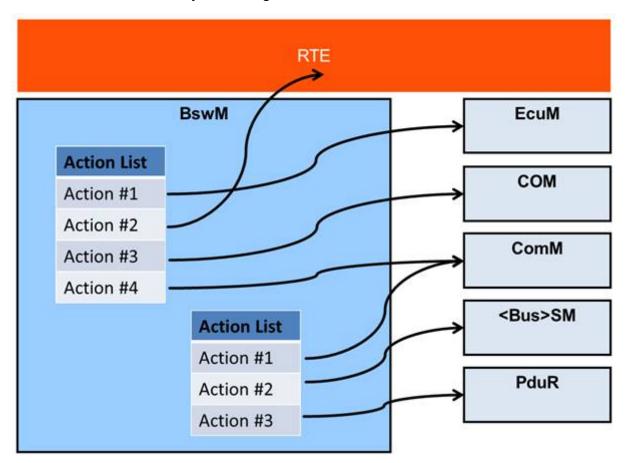


Figure 7.2: Example showing two action lists

As shown in Figure 7.2, the BswM may contain multiple Action Lists, and a single Action List can hold multiple actions. To reduce the overall number of action lists, it shall be possible to cascade them. An element of an action list can either be a concrete action or a reference to another action list, or as stated above, a rule to be executed by the mode arbitration. There shall be a flag connected to every action list entry that states its type (action/reference/rule). There shall be no difference between the way a list with concrete actions and the way a list with references or even a mixed list, is activated.

7.2.1 Mode Processing Cycle

Figure 7.3 shows the minimal processing cycle for a Mode Request:

1. The Mode Requester SW-C requests mode A through its Sender Port. The RTE distributes the request and the BswM receives it through its Receiver Port.



- 2. The BswM evaluates its rules either as a result of a received mode arbitration request, or cyclically during the execution of the BswM main function.
- 3. The corresponding Action List is executed according to the selected execution method (see section "Triggered and Conditional action lists").
- 4. When executing the Action List, the BswM may issue one or several calls to the RTE Switch API [6] as actions to inform the affected SW-Cs about the arbitration result. Any SW-C, especially the mode requester can register to receive the mode switch indications.

Note that the mode requester can only receive the mode switch indications from the local BswM; this is true also for requests that originate from a different ECU that is made by a local proxy SW-C.



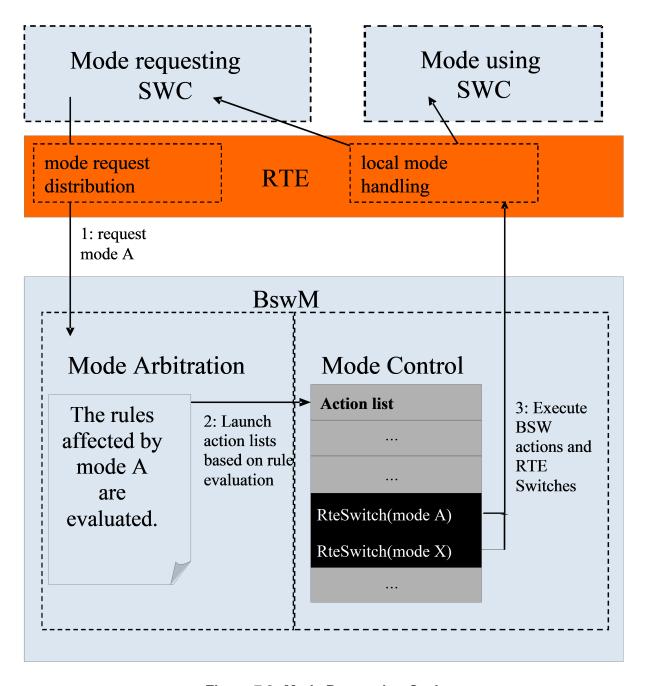


Figure 7.3: Mode Processing Cycle

7.2.2 Requirements on Mode Control

[SWS_BswM_00016] [The BswM shall perform mode control by means of action lists that are executed as a result of rule evaluation in the mode arbitration.] (SRS_-ModeMgm_09177)

[SWS_BswM_00015] For each rule of the mode arbitration, BswM shall be able to execute different action lists based on if the rule evaluates to True or False. *(SRS_-ModeMgm_09177)*



[SWS_BswM_00017] An action list comprises a set of actions that BswM shall execute in an ordered manner. (SRS_ModeMgm_09178)

[SWS_BswM_00018] An action list may contain links to other action lists that BswM shall include in the execution. (SRS ModeMgm 09178)

[SWS_BswM_00019] An action list may also include links to mode arbitration rules that BswM shall evaluate within the scope of the execution of the current action list. (SRS_ModeMam_09178)

[SWS_BswM_00067] If a rule is included in an action list as specified in [SWS_BswM_00019], any action list execution resulting from that evaluation shall be executed by BswM before it continues to execute the original action list.] (SRS_-ModeMgm_09177, SRS_ModeMgm_09178)

[SWS_BswM_00037] [If cascaded action lists are used (i.e. using references to other rules or action lists) the action list structure may contain up to seven (7) hierarchic levels.

Note: The purpose of this limit is to make testing of BswM implementations and generator tools possible. The limit must be checked by the generator tool. (SRS_ModeMgm_-09178)

[SWS_BswM_00062] [Action lists associated with rules evaluated in the context of the mode arbitration request shall be executed by BswM immediately when triggered by the mode arbitration, and not be deferred to the main function execution.

Rationale: This allows very short latencies on mode requests when necessary. (SRS_-ModeMgm_09177, SRS_ModeMgm_09178)

[SWS_BswM_00223] [If a top-level action list is triggered by multiple rules during mode arbitration, this shall result in a single trigger to execute the action list during mode control. | (SRS_ModeMgm_09177, SRS_ModeMgm_09178)

A top-level action list is an action list which is directly executed by a top-level rule (i.e. a rule which is not nested within an action list), and which is not nested within another action list. [SWS_BswM_00223] only applies to top-level action lists. [SWS_BswM_00223] does not apply to nested rules and nested action lists, since their order within the parent action list is user-defined and should be respected.

[SWS_BswM_00275] [If more than one top-level Action List is to be executed during Mode Control, the order of execution shall start with the highest BswMActionListPriority and continue to the lowest. In cases where BswMActionListPriority are the same, the order of execution is arbitrary.]

[SWS_BswM_00276] [The BswMActionListPriority shall be ignored for action lists which are not top-level action lists.] ()

[SWS_BswM_00277] [An Action List with no BswMActionListPriority shall be interpreted as having a BswMActionListPriority equal to 0.]()



[SWS_BswM_CONSTR_00001] [The BswM shall reject configurations where a BswMActionList contains BswMActionListItems with same-valued BswMActionListItemIndexes.] (SRS ModeMgm 09178, SRS BSW 00167)

[SWS_BswM_00260] [When executing a BswMActionList: the BswM shall start with the BswMActionListItem that has the lowest-valued BswMActionListItemmIndex. Subsequent BswMActionListItems shall be executed in increasing order of their BswMActionListItemIndex.] (SRS ModeMgm 09230)

Within an action list, the configured <code>BswMActionListItemIndexes</code> do not necessarily need to be contiguous or zero-based. The BswM will start execution of the action list item with the lowest index, and continue to the one with the highest. If the indexes have "gaps" (i.e. are not contiguous), these gaps will simply be ignored.

Because the action list is an ordered list, it is not allowed to configure BswMAction—ListItemIndexes of the same value within the context of an action list.

7.2.3 Triggered and Conditional action lists

There are two ways that an action list may be executed based on evaluation of rules. Either it is executed every time the rule is evaluated with the corresponding result, or only when the evaluation result has changed from the previous evaluation. The execution method for an action list is configured using the <code>BswMActionListExecution</code> parameter (within the <code>BswMActionList</code> container).

However, for a nested action list which is not directly referenced by rules, the <code>BswMAc-tionListExecution</code> parameter (e.g. <code>BSWM_CONDITION</code> or <code>BSWM_TRIGGER</code>) has no meaning, and will have no effect on the way that the nested action list is executed. Such a nested action list (i.e. not directly referenced by rules) is accordingly executed whenever its parent action list is executed.

[SWS_BswM_00011] [If a True action list is configured for triggered execution, the BswM shall only execute it when the evaluation of the corresponding rule changes from False to True. | (SRS_ModeMgm_09180, SRS_ModeMgm_09230)

[SWS_BswM_00023] [If a False action list is configured for triggered execution the BswM shall only execute it when the evaluation of the corresponding rule changes from True to False. | (SRS_ModeMgm_09180, SRS_ModeMgm_09230)

[SWS_BswM_00115] [If a True action list is configured for conditional execution, the BswM shall execute it every time the corresponding rule is evaluated to True.] (SRS_-ModeMgm_09180)

[SWS_BswM_00116] [If a False action list is configured for conditional execution, the BswM shall execute it every time the corresponding rule is evaluated to False.] (SRS_-ModeMgm_09180)



[SWS_BswM_00055] [The BswM shall abort the execution of an action list if an action returns E_NOT_OK and the corresponding <code>BswMAbortOnFail</code> configuration parameter is set to "true".|(SRS_ModeMgm_09178)

7.2.4 Available Actions

The set of actions that are available to use in an action list is predefined. The reason for this is to ease ECU configuration and generation of BswM configuration code.

[SWS_BswM_00038] [BswM shall be able to execute the predefined actions defined by configuration container BswMAvailableActions.] (SRS_ModeMgm_09175, SRS_ModeMgm_09174, SRS_ModeMgm_09182, SRS_ModeMgm_09184)

[SWS_BswM_00039] [The BswM shall be able to call any function in the AUTOSAR BSW even though it is not among the standardized actions defined in BswMAvailableActions.] (SRS ModeMgm 09229)

[SWS_BswM_00040] The BswM shall be able to call user defined functions. (SRS_-ModeMgm 09229)

[SWS_BswM_00054] [The parameters of the user defined functions, and their values, shall be defined at ECU configuration time using the BswMUserCallout configuration container. | (SRS_ModeMgm_09178)

7.2.5 Behavior of Mode Control after Initialization

The behavior of the Mode Control after initialization of the BswM is configured by the BswMRuleInitState parameter (within the BswMRule container). It defines the "previous evaluation result" to be used when deciding on what action list to execute after the first evaluation of a rule after initialization. The configuration parameter BswMActionListExecution (within the BswMActionList container) also affects the action list execution after initialization.

[SWS BswM 00066] [

BswMRuleInitState	BswMActionListExecution	Rule evaluated to true	Rule evaluated to false
BSWM_UNDEFINED	BSWM_TRIGGER	Execute "true" action list	Execute "false" action list
BSWM_TRUE	BSWM_TRIGGER	Do nothing	Execute "false" action list
BSWM_FALSE	BSWM_TRIGGER	Execute "true" action list	Do nothing
BSWM_UNDEFINED	BSWM_CONDITION	Execute "true" action list	Execute "false" action list
BSWM_TRUE	BSWM_CONDITION	Execute "true" action list	Execute "false" action list
BSWM_FALSE	BSWM_CONDITION	Execute "true" action list	Execute "false" action list

Table 7.1: The BswM shall act according to what is stated in this table when a rule is evaluated for the first time after initialization. Note: The "true" and "false" action lists are optional for each rule.

(SRS ModeMgm 09180, SRS ModeMgm 09230)



7.3 Waiting Functionality

Sometimes it is necessary to delay specific actions or wait for further mode controls. For this reason a Timer handling was added to the BswM.

A Timer consists always of a <code>BswMTimer</code> as <code>BswMModeRequestSource</code> and corresponding actions (see <code>BswMTimerControl</code>) controlling this <code>BswMTimer</code> i.e. the timer can only be controlled in the context of the action <code>BswMTimerControl</code> -> <code>BswMModeRequestSource/BswMTimer</code>. The value of the <code>BswMTimer</code> (e.g. <code>BSWM_TIMER_STOPPED</code>, <code>BSWM_TIMER_STARTED</code>, <code>BSWM_TIMER_EXPIRED</code>) can be evaluated by other rules configured in the <code>BswM</code>, in order to trigger action lists. There is no external interface to control or manipulate the timer.

[SWS_BswM_00261] [Each BswMTimer shall be stopped (BSWM_TIMER_ STOPPED) during initialization. | (SRS_BSW_00101)

[SWS_BswM_00262] [The action BswMTimerAction BSWM_TIMER_START shall reload the referenced BswMTimer (via BswMTimerRef) with the corresponding timer value (refer BswMTimerValue) and change the mode of the timer to BSWM_TIMER_STARTED.](SRS_ModeMgm_09180)

Note: The timer can only reload by the BswMTimerAction action (no automatic reload possible).

[SWS_BswM_00263] [Each BswMTimer in mode BSWM_TIMER_STARTED shall decrement the timer during the BswM_MainFunction (by the cycle time of the BswM_MainFunction).] (SRS_ModeMgm_09180)

Note: The BswMTimer resolution is a multiple of the BswM_MainFunction cycle. Also, the accuracy of the BswMTimer depends on the accuracy of the BswM_Main-Function.

[SWS_BswM_00264] [In case a BswMTimer which is in mode BSWM_TIMER_ STARTED expires, its mode shall be changed to BSWM_TIMER_EXPIRED, and then the BswMTimer mode shall be arbitrated in the same BswM_MainFunction cycle.] (SRS_ModeMgm_09180)

[SWS_BswM_00265] [The action BswMTimerAction BSWM_TIMER_STOP shall stop the referenced BswMTimer (via BswMTimerRef) immediately and change its' mode to BSWM_TIMER_STOPPED.](SRS_ModeMgm_09180)

[SWS_BswM_00220] [The BswMRequestProcessing (e.g. IMMEDIATE, DEFERRED) configuration associated with a BswMTimer shall be ignored by the BswM. The BswM shall treat the processing of a BswMTimer always as DEFERRED; the BswMTimer is arbitrated during the BswM main function.] (SRS_ModeMgm_09180)

Note: A <code>BswMTimer</code> in mode <code>BSWM_TIMER_EXPIRED</code> will not automatically be set to <code>BSWM_TIMER_STOPPED</code> by the <code>BswMTimer</code> from <code>BSWM_TIMER_EXPIRED</code> into another mode. If there is no action configured to transition the <code>BswMTimer</code> out of



mode BSWM_TIMER_EXPIRED, then the <code>BswMTimer</code> will continue to be arbitrated as <code>BSWM_TIMER_EXPIRED</code> in the following BswM main function cycles.

7.4 Multi Partition Support

For multiple BswM instances, each BswM instance will generate its own separate service component description based on its own config set. The integrator will need to allocate these separate service components to the corresponding partition.

BswM is present in each partition with a partition specific configuration (separate instance of BswMConfig per partition). The contained action lists are executed partition locally.

7.5 Error classification

Section 7.2 "Error Handling" of the document "General Specification of Basic Software Modules" describes the error handling of the Basic Software in detail. Above all, it constitutes a classification scheme consisting of five error types which may occur in BSW modules.

Based on this foundation, the following section specifies particular errors arranged in the respective subsections below

7.5.1 Development Errors

[SWS BswM 00230] [

Type of error	Related error code	Error value
A service was called prior to initialization	BSWM_E_UNINIT	0x01
A null pointer was passed as an argument	BSWM_E_NULL_POINTER	0x02
A parameter was invalid (unspecific)	BSWM_E_PARAM_INVALID	0x03
A requesting user was out of range	BSWM_E_REQ_USER_OUT_OF_RANGE	0x04
A requested mode was out of range	BSWM_E_REQ_MODE_OUT_OF_RANGE	0x05
The provided configuration is inconsistent	BSWM_E_PARAM_CONFIG	0x06
A parameter pointer was invalid	BSWM_E_PARAM_POINTER	0x07
Invalid configuration set selection	BSWM_E_INIT_FAILED	0x08

(SRS BSW 00385)



7.5.2 Runtime Errors

[SWS BswM 00238] [

Type of error	Related error code	Error value
An action returned E_NOT_OK	BSWM_E_ACTION_FAILED	0x800xFF (as configured in BswMReportFail RuntimeErrorld)

(SRS BSW 00452)

[SWS_BswM_00239] [If BswMReportFailRuntimeErrorId is configured for a BswMActionListItem, then the BswM shall report a BSWM_E_ACTION_FAILED Runtime Error to Det if the action returns E_NOT_OK. The Errorld reported in the BSWM_E_ACTION_FAILED Runtime Error is given by the value configured in BswM-ReportFailRuntimeErrorId.|(SRS_BSW_00452)

Since the calling context of the action depends on the configuration (e.g. DEFERRED or IMMEDIATE), the Apild reported in the BSWM_E_ACTION_FAILED Runtime Error is not defined in this specification and may be implementation specific.

The BSWM_E_ACTION_FAILED Runtime Error represents a range of Errorld values. The range of values is restricted to the values given in the table for Runtime Error Types.

[SWS_BswM_00240] [The BswM shall reject configurations where a BswMRe-portFailRuntimeErrorId does not lie within the range of values given for BSWM E ACTION FAILED in the Runtime Error Types table. | (SRS BSW 00167)

7.5.3 Transient Faults

There are no transient faults.

7.5.4 Production Errors

There are no production errors.

7.5.5 Extended Production Errors

There are no extended production errors.



7.6 BswM Interfaces and Ports

This chapter specifies the AUTOSAR Interfaces and Ports that are provided by the Basic Software Mode Manager. Note that ports on both sides of the RTE are required: The SW-C description of the Basic Software Mode Manager services will define the ports below the RTE. Each AUTOSAR SW-C, which uses the services, must contain service ports in its own SW-C description. These ports are typed with the same interfaces and have to be connected to the ports of the Basic Software Mode Manager, so that the RTE can generate the appropriate IDs and the required symbols.

SW-Cs request modes from the BSW Mode Manager. To that end, they provide a Sender Port that has a special Sender/Receiver Interface (Mode Request Interface) with one data element. The corresponding Receiver Port at the BSW Mode Manager is described in Chapter 7.6.1. The data element's type has the same values as the Mode Declarations in the Mode Declaration Group of the corresponding mode (since the ImplementationDataType of the data element is mapped to the ModeDeclaration Group).

The same SW-C that requests a mode may also be a mode user because it may also need to know the arbitration result of the BSW Mode Manager. The SW-C has a Mode Switch Port, which is a R-Port with a Mode Switch Interface with one data element. This data element's type is then the Mode Declaration Group itself. In addition, other SW-Cs that do not request modes, but depend on them, have such a Mode Switch Port. See Chapter 7.6.3 for a detailed description of the interface to mode users. Note that the BSW Mode Manager also needs a Mode Switch R-Port if it needs to know the current mode in addition to the requested one in its decisions.

Mode Notifications are dispatched by the RTE when a Mode Manager switches the corresponding mode. To do that, the BSW Mode Manager has a Provided type Mode Switch Port that the SW-Cs can connect to. See Chapter 7.6.2 for a detailed description of Mode Switch Ports.

In the context of the requesting SW-C, a Mode Request Port (Sender/Receiver) is defined. The configuration of BSW Mode Manager references this port definition. Let us assume that the SW-C defines an Application Mode AppModeType, a corresponding AppModeRequestType and an AppModeTypeMap that maps the two types to each other:

```
ModeDeclarationGroup AppModeType {
      { APP_MODE_A, APP_MODE_B, APP_MODE_C }
      initialMode = APP_MODE_A;
};

ImplementationDataType AppModeRequestType {
    lowerLimit = 0;
      upperLimit = 2;
};
```



```
ModeRequestTypeMap AppModeTypeMap {
    modeGroup = AppModeType;
    implementationDataType = AppModeRequestType;
};
```

In the context of the SW-C, two Interfaces are defined: the <code>AppModeRequestInterface</code> of Sender/Receiver type where the SW-C is sender, and the <code>AppModeInterface</code> of Mode Switch type where the SW-C can have P-Ports and R-Ports depending upon the usage:

Figure 7.4 shows how the ports of the application SW-Cs connect to the service ports of the BSW Mode Manager. The Application Mode Manager SW-C has a Mode Request Port and a Mode Switch R-port (named modeNotificationPort to distinguish it from the Mode Switch P-ports). The first port is to request changes in its application mode, the latter to receive notifications when the BswM has performed the mode change. The Mode Request Port of the Application Mode Manager (modeRequest Port0) connects to the corresponding Mode Request Port of the BSW Mode Manager. Since this is normal Sender/Receiver communication, the Application Mode Manager may connect to multiple BSW Mode Managers even on remote ECUs.

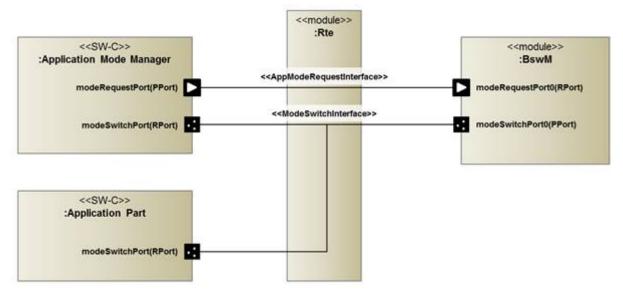


Figure 7.4: Connections between Application Mode Manager, Application Parts and the BSW Mode Manager

In order to switch the application mode, the BSW Mode Manager has a Mode Switch Port (modeSwitchPort_{Name}) that is implemented by the local RTE.

When the RTE performs the mode switch, it informs all connected entities (BSW Modules or SW-Cs) that are connected via Mode Switch R-Ports to the providing port. The following example presents the Application Mode Manager, the other mode-dependent Application Part and the BSW Mode Manager itself (Note that it's named modeNoti-ficationPort_{Name} but the port type is Mode Switch Port). All of these connections are also local.



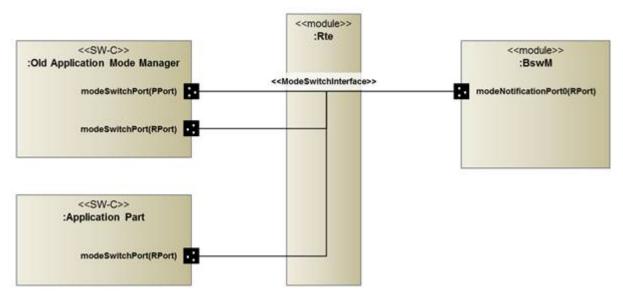


Figure 7.5: Connections between SW-C based Application Mode Manager, Application Parts and the BSW Mode Manager

Figure 7.5 shows that SW-C based Application Mode Managers (as used in AUTOSAR R3.1 and earlier) switch the application mode directly and do not request it from the BSW Mode Manager. Therefore, they directly connect a Mode Switch Port to the local RTE. This implies that the application mode needs to be local to that ECU and that no arbitration in the BSW Mode Manager is possible. Nevertheless, the BSW Mode Manager may use the current application mode as an input for its rules because it can have a Mode Switch R-Port (named modeNotificationPort0 in the figure) for this application mode.

Note: To configure the BswM, knowledge of what mode request ports and ECU resources are needed/available for a specific ECU is needed. Therefore, the SW-C description of the BswM can only be completed during ECU configuration time.

From now on, all following interface definitions are interpreted to be in:

ARPackage AUTOSAR_BswM/BswModuleDescription

Note that the pseudocode presented in this chapter is not exact, but provides a hint of how the corresponding model elements need to be defined.

7.6.1 Mode Request Ports

The BSW Mode Manager must declare a Receiver Port with the interface defined in the context of the SW-C:

RequirePort AppModeRequestInterface modeRequestPort_{ArbName}_{ReqName};

To read the currently requested mode, the BSW Mode Manager implementation must call:



Rte_Read_modeRequestPort_{ArbName}_{ReqName}_requestedMode(&
<variable>);

7.6.2 Mode Switch Ports

As with Mode Requests, the BSW Mode Manager only references the mode switch interfaces defined in the context of the corresponding SW-C Description in its Provide Ports for mode switches. For the above example the declaration for a mode switch is:

```
ProvidePort AppModeInterface modeSwitchPort_{ModConName}
_{SwitchName};
```

The configuration parameter <code>BswMModeSwitchInterfaceRef</code> references this Mode Switch interface.

To switch the currently active mode, the BSW Mode Manager implementation must insert one of the following calls into its actions list:

```
Rte_Switch_modeSwitchPort_{ModConName}_{SwitchName}_currentMode
( <new_mode> );
SchM_Switch_modeSwitchPort_{ModConName}_{SwitchName}_current
Mode( <new_mode> );
```

7.6.3 Notifications of Mode Switches

In addition to mode requests, the currently active modes can also be used as inputs to mode arbitration. For Application and Vehicle Modes, the BSW Mode Manager needs to register as a mode user. It then receives notifications about changed modes via a Mode Switch Port. For the above example the declaration for a mode notification is:

Note: In order to make it easier to distinguish between a RequirePort and ProvidePort of the ModeSwitchPort type, the RequirePorts are named mode notification port for the following example.

```
RequirePort AppModeInterface modeNotificationPort_{Arb
Name}_{ModeName};
```

To read the currently active mode, the BSW Mode Manager implementation must call one of the following functions:

```
Rte_Mode_modeNotificationPort_{ArbName}_{ModeName}_currentMode(
&<variable> );
SchM_Mode_modeNotificationPort_{ArbName}_{ModeName}_currentMode
( &<variable> );
```

In case the enhanced Rte_Mode or SchM_Mode is configured, the BSW Mode Manager implementation must call one of the following functions:



```
Rte_Mode_modeNotificationPort_{ArbName}_{ModeName}_currentMode(
&<variable>, &<previousmode>, &<nextmode>);

SchM_Mode_modeNotificationPort_{ArbName}_{ModeName}_currentMode
( &<variable>, &<previosmode>, &<nextmode>);
```

7.6.4 Component Type and Internal Behavior

The BSW Mode Manager is a Service Component that serves Mode Requests local to the ECU. The ServiceComponentType for the BSW Mode Manager declares all of the above-mentioned ports, and some Internal Behavior.

```
ServiceComponentType BswM {
    ...
    InternalBehavior {
        ...
    };
};
```

The internal behavior depends on the parameter <code>BswMRequestProcessing</code> for the corresponding Mode Request Port. For <code>BSWM_DEFERRED</code>, the RTE must not perform any special actions, as the <code>BSWM</code> Mode Manager reads the request cyclically in its <code>BswM_MainFunction</code>. By contrast, for <code>BSWM_IMMEDIATE</code> the RTE must trigger mode arbitration immediately. Therefore, the BSW Mode Manager needs to register a trigger function that triggers mode arbitration. For the above example, an immediate processing of the mode request would need the following declaration in the Internal Behavior of the BSW Mode Manager:

```
RunnableEntity ModeArbitrationRunnable {
    symbol = <mode_arbitration_function>;
    canBeInvokedConcurrently = TRUE;
};

DataReceiveEvent AppModeRequestEvent {
    port = modeRequestPort0;
    dataElement = requestedMode;
    startOnEvent = ModeArbitrationRunnable;
};
```

Note: To deal with Mode Requests that originate from other ECUs, another kind of service component is needed. On the VFB level it looks like one global Service Component, but actually it is instantiated as one Service Component that resides above the RTE for each ECU. To support that, the SW-C Template offers the ServiceProxy ComponentType instead of the normal ServiceComponentType.



The specification of the Mode Management Service Proxy Component is not described within this document since it is user specific.

7.7 Ethernet switch port group switching

The current version of the SWS BswM supports Ethernet switch port group switching. Based on the current requested PNC, BswM maps the PNC request to a configured Eth IfSwitchPortGroup and calls EthIf_SwitchPortGroupRequestMode. The BswM is indicated by the EthIf, if the accumulated link state has changed. The accumulated link state could be used to inform an application. This could be used to cover error scenarios where the requested and the current accumulated link state of EthIfSwitch PortGroups are contradicting and error handling needs to be initiated.

The AUTOSAR_EXP_ModemanagementGuide document contains guidelines for the BswM configuration regarding Ethernet switch port group switching.



8 API specification

8.1 Imported types

[SWS_BswM_00237] [The BSW Mode Manager shall use only the imported types which are listed in SWS_BswM_00001.] (SRS_BSW_00301)

[SWS_BswM_00001]

Module	Header File	Imported Type
CanSM	CanSM.h	CanSM_BswMCurrentStateType
Com	Com.h	Com_lpduGroupIdType
ComM	ComM.h	ComM_InitStatusType
	ComM.h	ComM_PncModeType
	Rte_ComM_Type.h	ComM_InhibitionStatusType
	Rte_ComM_Type.h	ComM_ModeType
	Rte_ComM_Type.h	ComM_UserHandleType
ComStack_Types	ComStack_Types.h	NetworkHandleType
	ComStack_Types.h	PNCHandleType
	ComStack_Types.h	PduldType
Dcm	Dcm.h	Dcm_CommunicationModeType
EcuM	EcuM.h	EcuM_RunStatusType
	EcuM.h	EcuM_StateType
	EcuM.h	EcuM_WakeupSourceType
	EcuM.h	EcuM_WakeupStatusType
	Rte_EcuM_Type.h	EcuM_UserType
Eth	Eth_GeneralTypes.h	Eth_ModeType
Ethlf	Ethlf.h	Ethlf_SwitchPortGroupIdxType
EthSM	EthSM.h	EthSM_NetworkModeStateType
EthTrcv	Eth_GeneralTypes.h	EthTrcv_LinkStateType
FrSm	FrSm.h	FrSM_BswM_StateType
IdsM	ldsM_Filters_Types.h	IdsM_Filters_BlockStateType
J1939Dcm	J1939Dcm.h	J1939Dcm_StateType
J1939Rm	J1939Rm.h	J1939Rm_StateType
LinIf	Linlf.h	LinIf_SchHandleType
	Linlf.h	LinTp_Mode
LinSM	LinSM.h	LinSM_ModeType
McOs	Os.h	CoreldType
Nm	NmStack_types.h	Nm_StateType
NvM	NvM.h	NvM_MultiBlockRequestType
	Rte_NvM_Type.h	NvM_BlockIdType
	Rte_NvM_Type.h	NvM_RequestResultType
Os	Os.h	IdleModeType
	Os.h	StatusType
Sd	Sd.h	Sd_ClientServiceCurrentStateType





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Module	Header File	Imported Type
	Sd.h	Sd_ConsumedEventGroupCurrentStateType
	Sd.h	Sd_EventHandlerCurrentStateType
	Sd.h	Sd_ServiceGroupIdType
SoAd	SoAd.h	SoAd_SoConIdType
	SoAd.h	SoAd_SoConModeType
Std	Std_Types.h	Std_ReturnType
	Std_Types.h	Std_VersionInfoType

(SRS_BSW_00301)

8.2 Type definitions

[SWS_BswM_00041] [The following Data Types shall be used for the functions defined in this specification.] (SRS_BSW_00305)

8.2.1 BswM_ConfigType

[SWS_BswM_00213] [

Name	BswM_ConfigType	
Kind	Structure	
Elements	-	
	Туре	_
	Comment	The contents of this structure depends on the configuration variant.
Description	This structure contains all post-build configurable parameters of the BSW Mode Manager. A pointer to this structure is passed to the BSW Mode Manager initialization function for configuration.	
Available via	BswM.h	

(SRS_BSW_00404, SRS_BSW_00441)

[SWS_BswM_00042] [The structure <code>BswM_ConfigType</code> shall contain all post-build configurable parameters of the BSW Mode Manager. The exact content of this structure depends on the selected configuration variant | (SRS_BSW_00404)



8.2.2 BswM_ModeType

[SWS_BswM_00214] [

Name	BswM_ModeType		
Kind	Туре		
Derived from	uint16		
Range	0-65535	_	_
Description	This type identifies the modes that can be requested by BswM Users.		
Available via	BswM.h		

(SRS_ModeMgm_09228, SRS_BSW_00441)

8.2.3 BswM_UserType

[SWS_BswM_00216] [

Name	BswM_UserType		
Kind	Туре		
Derived from	uint16		
Range	0-65535	_	_
Description	This type identifies a BswM User that makes mode requests to the BswM.		
Available via	BswM.h		

(SRS_ModeMgm_09228, SRS_BSW_00441)

8.3 Function definitions

8.3.1 BswM_BswMPartitionRestarted

[SWS_BswM_00193] [

Service Name	BswM_BswMPartitionRestarted	
Syntax	void BswM_BswMPartitionRestarted (
	void)	
Service ID [hex]	0x1e	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	None	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called by Restart Task if the partition containing the BswM has been restarted.	
Available via	BswM.h	

∫(SRS_ModeMgm_09228)



8.3.2 BswM CanSM CurrentState

[SWS_BswM_00049] [

Service Name	BswM_CanSM_CurrentStat	е
Syntax	void BswM_CanSM_CurrentState (NetworkHandleType Network, CanSM_BswMCurrentStateType CurrentState)	
Service ID [hex]	0x05	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	Network The CAN channel that the indicated state corresponds to.	
	CurrentState	The current state of the CAN channel.
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called by CanSM to indicate its current state.	
Available via	BswM_CanSM.h	

(SRS_ModeMgm_09228)

[SWS_BswM_00080] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the state indication and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.|(SRS_BSW_00406)

[SWS_BswM_00095] [If the <code>BswMDevErrorDetect</code> switch is enabled, the parameter CurrentState shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the state indication and report the error to the Default Error Tracer with the value <code>BSWM_E_REQ_MODE_OUT_OF_RANGE.]</code> (SRS_BSW_00323)

8.3.3 BswM_ComM_CurrentMode

[SWS_BswM_00047] [

Service Name	BswM_ComM_CurrentMode	
Syntax	<pre>void BswM_ComM_CurrentMode (NetworkHandleType Network, ComM_ModeType RequestedMode)</pre>	
Service ID [hex]	0x0e	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	Network	The ComM communication channel that the indicated state corresponds to.
	RequestedMode	The current state of the ComM communication channel
Parameters (inout)	None	





Parameters (out)	None
Return value	None
Description	Function called by ComM to indicate the current communication mode of a ComM channel.
Available via	BswM_ComM.h

\(\((SRS_ModeMgm_09228 \)

[SWS_BswM_00078] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM E UNINIT. | (SRS BSW 00406)

[SWS_BswM_00091] [If the BswMDevErrorDetect switch is enabled, the parameter RequestedMode shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value BSWM E REQ MODE OUT OF RANGE.|(SRS_BSW_00323)

8.3.4 BswM_ComM_CurrentPNCMode

[SWS BswM 00148] [

Service Name	BswM_ComM_CurrentPN	BswM_ComM_CurrentPNCMode	
Syntax	<pre>void BswM_ComM_CurrentPNCMode (PNCHandleType PNC, ComM_PncModeType CurrentPncMode)</pre>		
Service ID [hex]	0x15		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	PNC The handle of the PNC for which the current state is reported.		
	CurrentPncMode	The current mode of the PNC.	
Parameters (inout)	None	None	
Parameters (out)	None		
Return value	None		
Description	Function is called by ComM to indicate the current mode of the PNC.		
Available via	BswM_ComM.h		

(SRS ModeMgm 09228, SRS ModeMgm 09240)

[SWS_BswM_00149] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.] (SRS_BSW_00406)

[SWS_BswM_00150] [If the BswMDevErrorDetect switch is enabled, the parameter CurrentPncMode shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value BSWM E REQ MODE OUT OF RANGE.|(SRS_BSW_00323)



8.3.5 BswM ComM InitiateReset

[SWS_BswM_00217] [

Service Name	BswM_ComM_InitiateReset
Syntax	<pre>void BswM_ComM_InitiateReset (void)</pre>
Service ID [hex]	0x22
Sync/Async	Synchronous
Reentrancy	Non Reentrant
Parameters (in)	None
Parameters (inout)	None
Parameters (out)	None
Return value	None
Description	Function is called by ComM to signal a shutdown.
Available via	BswM_ComM.h

(SRS_ModeMgm_09228)

8.3.6 BswM_Dcm_ApplicationUpdated

[SWS BswM 00158] [

Service Name	BswM_Dcm_ApplicationUpdated		
Syntax	<pre>void BswM_Dcm_ApplicationUpdated (void)</pre>		
Service ID [hex]	0x14		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	None		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	This function is called by the DCM in order to report an updated application.		
Available via	BswM_Dcm.h		

(SRS_ModeMgm_09228)

[SWS_BswM_00159] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM E UNINIT. | (SRS BSW 00406)



8.3.7 BswM Dcm CommunicationMode CurrentState

[SWS_BswM_00048] [

Service Name	BswM_Dcm_CommunicationMode_CurrentState	
Syntax	<pre>void BswM_Dcm_CommunicationMode_CurrentState (NetworkHandleType Network, Dcm_CommunicationModeType RequestedMode)</pre>	
Service ID [hex]	0x06	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	Network	The communication channel that the diagnostic mode corresponds to.
	RequestedMode The requested diagnostic communication mode.	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called by DCM to inform the BswM about the current state of the communication mode.	
Available via	BswM_Dcm.h	

(SRS ModeMgm 09228)

The behavior of this function shall be configured using the configuration container <code>BswMDcmComModeRequest</code>, wherein the configuration parameter <code>BswMDcmComM-ChannelRef</code> correlates to the argument Network of this function.

[SWS_BswM_00079] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM E UNINIT. | (SRS BSW 00406)

[SWS_BswM_00093] [If the <code>BswMDevErrorDetect</code> switch is enabled, the parameter RequestedMode shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value <code>BSWM_E_REQ_MODE_OUT_OF_RANGE.|(SRS_BSW_00323)</code>

CDD Implementation Hint: All AUTOSAR BSW modules that may trigger transmission of PDUs provide an API to enable/disable it. To e.g. disable the whole communication in a corresponding diagnostic request, it makes sense if CDD modules (which use communication protocols) provides such an API as well. These functions may be called in the configured action list which is linked to this function.



8.3.8 BswM Deinit

[SWS BswM 00119]

Service Name	BswM_Deinit	
Syntax	void BswM_Deinit (
Service ID [hex]	0x04	
Sync/Async	Synchronous	
Reentrancy	Non Reentrant	
Parameters (in)	None	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Deinitializes the BSW Mode Manager.	
Available via	BswM.h	

(SRS_BSW_00336)

[SWS_BswM_00120] [After a call of <code>BswM_Deinit</code> no mode processing shall be performed by BswM even if any mode requests are made or the BswM main function is called.] (SRS_BSW_00336)

8.3.9 BswM EcuM CurrentState

[SWS_BswM_91003] [

Service Name	BswM_EcuM_CurrentState	
Syntax	<pre>void BswM_EcuM_CurrentState (EcuM_StateType CurrentState)</pre>	
Service ID [hex]	0x28	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	CurrentState The requested ECU Operation Mode	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called EcuM to indicate the current ECU Operation Mode.	
Available via	BswM_EcuM.h	

|(SRS_ModeMgm_09228)

[SWS_BswM_00084] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.] (SRS_BSW_00406)



[SWS_BswM_00103] [If the BswMDevErrorDetect switch is enabled, the parameter CurrentState shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.|(SRS_BSW_00323)

8.3.10 BswM EcuM CurrentWakeup

[SWS BswM 00131] [

Service Name	BswM_EcuM_CurrentWakeup		
Syntax	<pre>void BswM_EcuM_CurrentWakeup (EcuM_WakeupSourceType source, EcuM_WakeupStatusType state)</pre>		
Service ID [hex]	0x10		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	source Wakeup source(s) that changed state.		
	state The new state of the wakeup source(s)		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	Function called by EcuM to indicate the current state of a wakeup source.		
Available via	BswM_EcuM.h	BswM_EcuM.h	

|(SRS_ModeMgm_09228)

[SWS_BswM_00132] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT. | (SRS_BSW_00406)

[SWS_BswM_00133] [If the BswMDevErrorDetect switch is enabled, the parameter state shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.] (SRS_BSW_00323)

8.3.11 BswM EcuM RequestedState

[SWS_BswM_91004] [

Service Name	BswM_EcuM_RequestedState	
Syntax	<pre>void BswM_EcuM_RequestedState (EcuM_StateType State, EcuM_RunStatusType CurrentState)</pre>	





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Service ID [hex]	0x29	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	State The requested state by EcuM	
	CurrentState	Result of the Run Request Protocol
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called by EcuM notify about current Status of the Run Request Protocol.	
Available via	BswM_EcuM.h	

(SRS ModeMgm 09116, SRS ModeMgm 09228)

[SWS_BswM_00227] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT. | (SRS_BSW_00406)

[SWS_BswM_00228] [If the BswMDevErrorDetect switch is enabled, the parameter State shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.|(SRS_BSW_00323)

[SWS_BswM_00229] [If the <code>BswMDevErrorDetect</code> switch is enabled, the parameter CurrentStatus shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value <code>BSWM_E_REQ_MODE_OUT_OF_RANGE.|(SRS_BSW_00323)</code>

8.3.12 BswM_EthIf_PortGroupLinkStateChg

[SWS BswM 91001] [

Service Name	BswM_EthIf_PortGroupLinkStateChg	
Syntax	<pre>void BswM_EthIf_PortGroupLinkStateChg (EthIf_SwitchPortGroupIdxType PortGroupIdx, EthTrcv_LinkStateType PortGroupState)</pre>	
Service ID [hex]	0x26	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	PortGroupIdx The port group index in the context of the Ethernet Interface	
	PortGroupState	The state of the port group. State is derived from the physical link of the Ethernet Transceiver: ETHTRCV_LINK_STATE_DOWN == Port group has link down. ETHTRCV_LINK_STATE_ACTIVE == Port group has link up.
Parameters (inout)	None	
Parameters (out)	None	





Return value	None	
Description	Function called by EthIf to indicate the link state change of a certain Ethernet switch port group.	
Available via	BswM_Ethlf.h	

|(SRS_ModeMgm_09228)

[SWS_BswM_00267] [If the BswMDevErrorDetect switch is enabled, the BswM_-EthIf_PortGroupLinkStateChg routine shall check if the BSW Mode Manager is initialized. In case the BswM is not initialized, the BswM shall ignore the mode request and report to the Default Error Tracer with the error code BSWM_E_UNINIT.] (SRS_-BSW_00406)

[SWS_BswM_00268] [If the BswMDevErrorDetect switch is enabled, the BswM_-EthIf_PortGroupLinkStateChg parameters shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.] (SRS_BSW_00323)

8.3.13 BswM EthSM CurrentState

[SWS_BswM_00050] [

Service Name	BswM_EthSM_CurrentState		
Syntax	<pre>void BswM_EthSM_CurrentState (NetworkHandleType Network, EthSM_NetworkModeStateType CurrentState)</pre>		
Service ID [hex]	0x0d	0x0d	
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	Network The Ethernet channel that the indicated state corresponds to.		
	CurrentState The current state of the Ethernet channel.		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	Function called by EthSM to indicate its current state.		
Available via	BswM_EthSM.h	BswM_EthSM.h	

(SRS_ModeMgm_09228)

[SWS_BswM_00081] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the state indication and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.|(SRS_BSW_00406)

[SWS_BswM_00097] [If the BswMDevErrorDetect switch is enabled, the parameter CurrentState shall be checked for being in the allowed range. In case of an error, the



BswM shall ignore the state indication and report the error to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.|(SRS_BSW_00323)

8.3.14 BswM_FrSM_CurrentState

[SWS_BswM_00051] [

Service Name	BswM_FrSM_CurrentState		
Syntax	<pre>void BswM_FrSM_CurrentState (NetworkHandleType Network, FrSM_BswM_StateType CurrentState)</pre>		
Service ID [hex]	0x0c		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	Network The FlexRay cluster that the indicated state corresponds to.		
	CurrentState The corrent state of the FlexRay cluster.		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	Function called by FrSM to	Function called by FrSM to indicate its current state.	
Available via	BswM_FrSM.h		

(SRS ModeMgm 09228)

[SWS_BswM_00082] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the state indication and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.] (SRS_BSW_00406)

[SWS_BswM_00099] [If the <code>BswMDevErrorDetect</code> switch is enabled, the parameter CurrentState shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the state indication and report the error to the Default Error Tracer with the value <code>BSWM_E_REQ_MODE_OUT_OF_RANGE.|(SRS_BSW_00323)</code>

8.3.15 BswM_GetVersionInfo

[SWS BswM 00003] [

Service Name	BswM_GetVersionInfo
Syntax	void BswM_GetVersionInfo (Std_VersionInfoType* VersionInfo)
Service ID [hex]	0x01
Sync/Async	Synchronous
Reentrancy	Reentrant





Parameters (in)	None	
Parameters (inout)	None	
Parameters (out)	VersionInfo Pointer to where to store the version information of the module.	
Return value	None	
Description	Returns the version information of this module.	
Available via	BswM.h	

(SRS BSW 00407, SRS BSW 00003)

8.3.16 BswM Init

[SWS BswM 00002]

Service Name	BswM_Init		
Syntax	<pre>void BswM_Init (const BswM_ConfigType * ConfigPtr)</pre>		
Service ID [hex]	0x00		
Sync/Async	Synchronous	Synchronous	
Reentrancy	Conditionally Reentrant		
Parameters (in)	ConfigPtr	Pointer to post-build configuration data	
Parameters (inout)	None	None	
Parameters (out)	None		
Return value	None		
Description	Initializes the BSW Mode Manager.		
Available via	BswM.h		

](SRS_BSW_00344, SRS_BSW_00404, SRS_BSW_00405, SRS_BSW_00101, SRS_BSW_00358, SRS_BSW_00414)

The Reentrancy for the <code>BswM_Init</code> API is set to "Conditionally reentrant" for support of implementations where the BswM is instantiated in multiple partitions (e.g. in single core systems using multiple BSW partitions OR in multi-core systems.

[SWS_BswM_00043] This routine initializes the BSW Mode Manager. After execution of this routine the BSW Mode Manager is ready to arbitrate incoming mode requests. (SRS_BSW_00101)

[SWS_BswM_00044] [This routine shall initialize all module global variables of the BSW Mode Manager. | (SRS_BSW_00101)

[SWS_BswM_00118] [BswM_Init shall only require the OS and the SchM to be initialized before it can be called. | (SRS_BSW_00467)

[SWS_BswM_00045] [If the BswMDevErrorDetect switch is enabled, the contents of the given configuration set shall be checked for being within the allowed boundaries. If an error is detected the initialization of the BSW Mode Manager shall not be executed and the error shall be reported to the Default Error Tracer with the value BSWM_E_PARAM_CONFIG.|(SRS_BSW_00323)



8.3.17 BswM_J1939DcmBroadcastStatus

[SWS BswM 00165]

Service Name	BswM_J1939DcmBroadcastStatus	
Syntax	void BswM_J1939DcmBroadcastStatus (uint16 NetworkMask)	
Service ID [hex]	0x1b	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	NetworkMask	Mask containing one bit for each available network. The bit position within this mask corresponds to the ComMChannel.Com MChannelId for the communication channel (so ComMChannelID 0 is represented by bit 0). The meaning for each bit is: 1: Network enabled, 0: Network disabled. Note: only the first 16 communication channel IDs can be supported by this API.
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	This API tells the BswM the desired communication status of the available networks. The status will typically be activated via COM I-PDU group switches.	
Available via	BswM_J1939Dcm.h	

](SRS_ModeMgm_09228)

[SWS_BswM_00249] [The BswM_J1939DcmBroadcastStatus parameter NetworkMask is a bitmask where the bit position corresponds to the ComMChannel. ComMChannelId which is referenced by the BswMJ1939DcmBroadcastStatus. BswMJ1939DcmChannelRef parameter. For rule processing, the BswM shall use the value in NetworkMask of the bit (0 or 1) which lies in the position configured by the referenced ComMChannel.ComMChannelId.](SRS_ModeMgm_09228)

8.3.18 BswM_J1939Nm_StateChangeNotification

[SWS BswM 00194] [

Service Name	BswM_J1939Nm_StateChangeNotification	
Syntax	void BswM_J1939Nm_StateChangeNotification (NetworkHandleType Network, uint8 Node, Nm_StateType NmState)	
Service ID [hex]	0x18	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	Network	Identification of the J1939 channel
	Node	Identification of the J1939 node
	NmState	Current (new) state of the J1939 node
Parameters (inout)	None	





Parameters (out)	None
Return value	None
Description	Notification of current J1939Nm state after state changes.
Available via	BswM_J1939Nm.h

∫(SRS_ModeMgm_09228)

8.3.19 BswM_LinSM_CurrentSchedule

[SWS_BswM_00058] [

Service Name	BswM_LinSM_CurrentSche	dule	
Syntax	<pre>void BswM_LinSM_CurrentSchedule (NetworkHandleType Network, LinIf_SchHandleType CurrentSchedule)</pre>		
Service ID [hex]	0x0a		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	Network	The LIN channel that the schedule table switch have occurred on.	
	CurrentSchedule	The currently active schedule table of the LIN channel.	
Parameters (inout)	None		
Parameters (out)	None	None	
Return value	None		
Description	Function called by LinSM to indicate the currently active schedule table for a specific LIN channel.		
Available via	BswM_LinSM.h		

(SRS_ModeMgm_09228)

[SWS_BswM_00086] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error the BswM shall ignore the schedule indication and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.] (SRS_BSW_00406)

8.3.20 BswM LinSM CurrentState

[SWS_BswM_00052] [

Service Name	BswM_LinSM_CurrentState
Syntax	<pre>void BswM_LinSM_CurrentState (NetworkHandleType Network, LinSM_ModeType CurrentState)</pre>
Service ID [hex]	0x09
Sync/Async	Synchronous





Reentrancy	Reentrant	
Parameters (in)	Network	The LIN channel that the indicated state corresponds to.
	CurrentState	The current state of the LIN channel.
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called by LinSM to indicate its current state.	
Available via	BswM_LinSM.h	

|(SRS_ModeMgm_09228)

[SWS_BswM_00083] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the state indication and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.] (SRS_BSW_00406)

[SWS_BswM_00101] [If the BswMDevErrorDetect switch is enabled, the parameter CurrentState shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the state indication and report the error to the Default Error Tracer with the value BSWM E REQ MODE OUT OF RANGE.|(SRS_BSW_00323)

8.3.21 BswM_LinTp_RequestMode

[SWS_BswM_00156] [

Service Name	BswM_LinTp_RequestMod	BswM_LinTp_RequestMode	
Syntax	NetworkHandleType	void BswM_LinTp_RequestMode (NetworkHandleType Network, LinTp_Mode LinTpRequestedMode)	
Service ID [hex]	0x0b		
Sync/Async	Synchronous	Synchronous	
Reentrancy	Reentrant	Reentrant	
Parameters (in)	Network	Network The LIN channel that the LinTp mode request relates to.	
	LinTpRequestedMode	The requested LIN TP mode.	
Parameters (inout)	None	None	
Parameters (out)	None	None	
Return value	None		
Description		Function called by LinTP to request a mode for the corresponding LIN channel. The LinTp_ Mode correlates to the LIN schedule table that should be used.	
Available via	BswM_LinTp.h		

(SRS ModeMgm 09228)

[SWS_BswM_00112] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM E UNINIT. | (SRS BSW 00406)



[SWS_BswM_00113] [If the <code>BswMDevErrorDetect</code> switch is enabled, the parameter LinTpRequestedMode shall be checked for being in the allowed range. In case of an error the BswM shall ignore the mode request and report the error, to the Default Error Tracer with the value <code>BSWM_E_REQ_MODE_OUT_OF_RANGE.]</code> (SRS_BSW_-00323)

8.3.22 BswM Nm CarWakeUpIndication

[SWS BswM 00235] [

Service Name	BswM_Nm_CarWakeUpIndication		
Syntax	void BswM_Nm_CarWakeUpIndication (NetworkHandleType Network)		
Service ID [hex]	0x24		
Sync/Async	Synchronous	Synchronous	
Reentrancy	Reentrant	Reentrant	
Parameters (in)	Network Identification of the Nm-Channel		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	Function called by Nm to in-	Function called by Nm to indicate a CarWakeup.	
Available via	BswM_Nm.h		

(SRS_ModeMgm_09228)

8.3.23 BswM Nm StateChangeNotification

[SWS BswM 91002]

Service Name	BswM_Nm_StateChangeNo	BswM_Nm_StateChangeNotification	
Syntax	<pre>void BswM_Nm_StateChangeNotification (NetworkHandleType Network, Nm_StateType currentState)</pre>		
Service ID [hex]	0x27		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	Network Identification of the Nm-channel		
	currentState	Current (new) state of the Nm-channel	
Parameters (inout)	None	None	
Parameters (out)	None		
Return value	None		
Description	Notification of current Nm state after state changes.		
Available via	BswM_Nm.h		

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8.3.24 BswM NvM CurrentBlockMode

[SWS BswM 00104]

Service Name	BswM_NvM_CurrentBlockM	lode
Syntax	<pre>void BswM_NvM_CurrentBlockMode (NvM_BlockIdType Block, NvM_RequestResultType CurrentBlockMode)</pre>	
Service ID [hex]	0x16	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	Block The Block that the new NvM Mode corresponds to.	
	CurrentBlockMode	The current block mode of the NvM block.
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called by NvM to indicate the current block mode of an NvM block.	
Available via	BswM_NvM.h	

|(SRS_ModeMgm_09228)

[SWS_BswM_00109] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the block mode indication and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.] (SRS_BSW_00406)

[SWS_BswM_00110] [If the BswMDevErrorDetect switch is enabled, the parameter CurrentBlockMode shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the block mode indication and report the error to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.] (SRS_BSW_-00323)

8.3.25 BswM_NvM_CurrentJobMode

[SWS BswM 00152]

Service Name	BswM_NvM_CurrentJobMode		
Syntax	void BswM_NvM_CurrentJobMode (NvM_MultiBlockRequestType MultiBlockRequest, NvM_RequestResultType CurrentJobMode)		
Service ID [hex]	0x17		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	MultiBlockRequest Indicates which multi block service this callback refers to.		
	CurrentJobMode	Current state of the multi block job indicated by parameter Multi BlockRequest	





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Parameters (inout)	None
Parameters (out)	None
Return value	None
Description	Function called by NvM to inform the BswM about the current state of a multi block job.
Available via	BswM_NvM.h

(SRS ModeMgm 09228)

[SWS_BswM_00153] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the job mode indication and report the error to the Default Error Tracer with the error code BSWM E UNINIT.|(SRS BSW 00406)

[SWS_BswM_00154] [If the BswMDevErrorDetect switch is enabled, the parameter MultiBlockRequest shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the job mode indication and report the error to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.] (SRS_BSW_-00323)

8.3.26 BswM_RequestMode

[SWS BswM 00046] [

Service Name	BswM_RequestMode	
Syntax	<pre>void BswM_RequestMode (BswM_UserType requesting_user, BswM_ModeType requested_mode)</pre>	
Service ID [hex]	0x02	
Sync/Async	Synchronous	
Reentrancy	Reentrant	
Parameters (in)	requesting_user The user that requests the mode	
	requested_mode The requested mode.	
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Generic function call to request modes. This function shall only be used by other BSW modules that does not have a specific mode request interface.	
Available via	BswM.h	

(SRS_ModeMgm_09179, SRS_ModeMgm_09228)

[SWS_BswM_00077] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM E UNINIT. | (SRS BSW 00406)

[SWS_BswM_00089] [If the BswMDevErrorDetect switch is enabled, the parameter requested_mode shall be checked for being in the allowed range. In case of an error,



the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value BSWM_E_REQ_MODE_OUT_OF_RANGE.|(SRS_BSW_00323)

[SWS_BswM_00090] [If the BswMDevErrorDetect switch is enabled, the parameter requesting_user shall be checked for being in the allowed range. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the value BSWM E REQ USER OUT OF RANGE.|(SRS_BSW_00323)

8.3.27 BswM_Sd_ClientServiceCurrentState

[SWS BswM 00204] [

Service Name	BswM_Sd_ClientServiceCu	BswM_Sd_ClientServiceCurrentState	
Syntax	<pre>void BswM_Sd_ClientServiceCurrentState (uint16 SdClientServiceHandleId, Sd_ClientServiceCurrentStateType CurrentClientState)</pre>		
Service ID [hex]	0x1f		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	SdClientServiceHandleId HandleId to identify the ClientService		
	CurrentClientState Current state of the ClientService		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	Function called by Service Discovery to indicate current state of the Client Service (available/down).		
Available via	BswM_Sd.h		

(SRS ModeMgm 09228)

[SWS_BswM_00205] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM E UNINIT. | (SRS_BSW_00406)

[SWS_BswM_00206] [If the BswMDevErrorDetect switch is enabled, the parameter CurrentClientState shall be checked for being in the allowed range. In case of an error the BswM shall ignore the mode request and report the error, to the Default Error Tracer with the value BSWM E REQ MODE OUT OF RANGE. (SRS BSW 00323)



8.3.28 BswM Sd ConsumedEventGroupCurrentState

[SWS BswM 00207]

Service Name	BswM_Sd_ConsumedEven	BswM_Sd_ConsumedEventGroupCurrentState	
Syntax	uint16 SdConsumedE	<pre>void BswM_Sd_ConsumedEventGroupCurrentState (uint16 SdConsumedEventGroupHandleId, Sd_ConsumedEventGroupCurrentStateType ConsumedEventGroupState)</pre>	
Service ID [hex]	0x21		
Sync/Async	Synchronous	Synchronous	
Reentrancy	Reentrant	Reentrant	
Parameters (in)	SdConsumedEventGroup Handleld	Handleld to identify the Consumed Eventgroup	
	ConsumedEventGroup State	Status of the Consumed Eventgroup	
Parameters (inout)	None	None	
Parameters (out)	None	None	
Return value	None	None	
Description	Function called by Service (available/down).	Function called by Service Discovery to indicate current status of the Consumed Eventgroup (available/down).	
Available via	BswM_Sd.h		

(SRS_ModeMgm_09228)

[SWS_BswM_00208] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM E UNINIT. | (SRS BSW 00406)

[SWS_BswM_00209] [If the <code>BswMDevErrorDetect</code> switch is enabled, the parameter ConsumedEventGroupState shall be checked for being in the allowed range. In case of an error the BswM shall ignore the mode request and report the error, to the Default Error Tracer with the value <code>BSWM_E_REQ_MODE_OUT_OF_RANGE.]</code> (SRS_BSW_-00323)

8.3.29 BswM_Sd_EventHandlerCurrentState

[SWS BswM 00210] [

Service Name	BswM_Sd_EventHandlerCurrentState		
Syntax	<pre>void BswM_Sd_EventHandlerCurrentState (uint16 SdEventHandlerHandleId, Sd_EventHandlerCurrentStateType EventHandlerStatus)</pre>		
Service ID [hex]	0x20		
Sync/Async	Synchronous		
Reentrancy	Reentrant		
Parameters (in)	SdEventHandlerHandleld Handleld to identify the EventHandler		





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	EventHandlerStatus	Status of the EventHandler
Parameters (inout)	None	
Parameters (out)	None	
Return value	None	
Description	Function called by Service Discovery to indicate current status of the EventHandler (requested/released).	
Available via	BswM_Sd.h	

(SRS_ModeMgm_09228)

[SWS_BswM_00211] [If the BswMDevErrorDetect switch is enabled, the routine shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the mode request and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT.|(SRS_BSW_00406)

[SWS_BswM_00212] [If the BswMDevErrorDetect switch is enabled, the parameter EventHandlerStatus shall be checked for being in the allowed range. In case of an error the BswM shall ignore the mode request and report the error, to the Default Error Tracer with the value BSWM E REQ MODE OUT OF RANGE. | (SRS_BSW_00323)

8.3.30 BswM_SoAd_SoConModeChg

[SWS_BswM_91005] [

Service Name	BswM_SoAd_SoConModeChg		
Syntax	<pre>void BswM_SoAd_SoConModeChg (SoAd_SoConIdType SoConId, SoAd_SoConModeType State)</pre>		
Service ID [hex]	0x2a		
Sync/Async	Synchronous		
Reentrancy	Reentrant for different SoConlds. Non reentrant for the same SoConld.		
Parameters (in)	SoConId The socket connection index.		
	State The state of the SoAd socket connection.		
Parameters (inout)	None		
Parameters (out)	None		
Return value	None		
Description	Function called by SoAd to	Function called by SoAd to notify state changes of a socket connection.	
Available via	BswM_SoAd.h		

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8.4 Call-back notifications

There are no call-back notifications in the BswM.



8.5 Scheduled functions

These functions are directly called by Basic Software Scheduler. The following functions shall have no return value and no parameter. All functions shall be non-reentrant.

8.5.1 BswM MainFunction

[SWS BswM 00053] [

Service Name	BswM_MainFunction
Syntax	void BswM_MainFunction (void)
Service ID [hex]	0x03
Description	Main function of the BswM
Available via	SchM_BswM.h

(SRS_BSW_00425)

[SWS_BswM_00075] [The BswM_MainFunction shall perform evaluation of all rules that uses at least one mode request with configuration parameter BswMRequestProcessing set to BSWM_DEFERRED as input. | (SRS_ModeMgm_09180)

8.6 Expected Interfaces

In this chapter all external interfaces required from other modules are listed.

8.6.1 Mandatory Interfaces

This chapter defines all interfaces that are required to fulfill the core functionality of the module.

[SWS_BswM_00007] [

API Function	Header File	Description
There are no mandatory interfaces.		

(SRS BSW 00384)

8.6.2 Optional Interfaces

According to [SWS_BswM_00039], the BswM can call any function in the AUTOSAR BSW. The following table contains a list of specific functions which may be useful in implementing BswM functionality.



[SWS_BswM_00008]

API Function	Header File	Description
Com_DisableReceptionDM	Com.h	Disables the reception deadline monitoring for the I-PDUs within the given I-PDU group.
Com_EnableReceptionDM	Com.h	Enables the reception deadline monitoring for the I-PDUs within the given I-PDU group.
Com_lpduGroupStart	Com.h	Starts a preconfigured I-PDU group. For example, cyclic I-PDUs will be sent out cyclically after the call of Com_IpduGroupStart(). If Initialize is true all I-PDUs of the I-PDU group shall be (re-)initialized before the I-PDU group is started. That is they shall behave like after a start-up of COM, for example the old_value of the filter objects and shadow buffers of signal groups have to be (re-)initialized.
Com_lpduGroupStop	Com.h	Stops a preconfigured I-PDU group. For example, cyclic I-PDUs will be stopped after the call of Com_IpduGroupStop().
Com_SwitchIpduTxMode	Com.h	The service Com_SwitchIpduTxMode sets the transmission mode of the I-PDU referenced by Pdu Id to Mode. In case the transmission mode changes, the new mode shall immediately be effective (see SWS_Com_00239). In case the requested transmission mode was already active for this I-PDU, the call will have no effect.
ComM_GetCurrentComMode	ComM.h	Function to query the current Communication Mode. ComM shall use the corresponding interfaces of the Bus State Managers to get the current Communication Mode of the network. (Call to Bus State Manager API: <bus>SM _GetCurrentCom Mode())</bus>
ComM_GetInhibitionStatus	ComM.h	Returns the inhibition status of a ComM channel.
ComM_GetMaxComMode	ComM.h	Function to query the maximum allowed Communication Mode of the corresponding user.
ComM_GetRequestedComMode	ComM.h	Function to query the currently requested Communication Mode of the corresponding user.
ComM_GetStatus	ComM.h	Returns the initialization status of the AUTOSAR Communication Manager. After a call to ComM_De Init() ComM should have status COMM_UNINIT, and a new call to ComM_Init needed to make sure Com M restart internal state machines to defailt values.
ComM_GetVersionInfo	ComM.h	This function returns the version information of this module
ComM_LimitChannelToNoComMode	ComM.h	Changes the inhibition status for the channel for changing from COMM_NO_COMMUNICATION to a higher Communication Mode. (See also ComM_LimitECUToNoComMode, same functionality but for all channels)
ComM_LimitECUToNoComMode	ComM.h	Changes the inhibition status for the ECU (=all channels) for changing from COMM_NO_COMMUNICATION to a higher Communication Mode. (See also ComM_LimitChannelToNoCom Mode, same functionality but for a specific channels)
ComM_PreventWakeUp	ComM.h	Changes the inhibition status COMM_NO_WAKEUP for the corresponding channel.
ComM_ReadInhibitCounter	ComM.h	This function returns the amount of rejected COMM_FULL_COMMUNICATION user requests.





API Function	Header File	Description
ComM_RequestComMode	ComM.h	Requesting of a Communication Mode by a user.
		Note:
		The following modes are no vaild user requests, since they are used as internal modes:
		- COMM_SILENT_COMMUNICATION (this mode is used for synchronization at shutdown)
		- COMM_FULL_COMMUNICATION_WITH_ WAKEUP_REQUEST (this mode is used internally within the ComM channel statemachine to trigger the lower layers to request a wakeup on the network if the used hardware support such a feature. (e.g. Ethernet hardware which is compatible with OA TC10).
		The following modes are valid user requests:
		- COMM_NO_COMMUNICATION
		- COMM_FULL_COMMUNICATION. The communication request could also be released due to a ComM communication inhibition
ComM_ResetInhibitCounter	ComM.h	This function resets the Inhibited COMM_FULL_COMMUNICATION request Counter.
ComM_SetECUGroupClassification	ComM.h	Changes the ECU Group Classification status (see chapter 10.2.2)
Controlldle	Os.h	This API allows the caller to select the idle mode action which is performed during idle time of the OS (e.g. if no Task/ISR is active). It can be used to implement energy savings. The real idle modes are hardware dependent and not standardized. The default idle mode on each core is IDLE_NO_HALT.
Det_ReportError	Det.h	Service to report development errors.
EcuM_AL_DriverInitBswM_ <x></x>	EcuM.h	This callback shall provide BSW module initializations to be called by the BSW Mode Manager.
EcuM_GoDownHaltPoll	EcuM.h	Instructs the ECU State Manager module to go into a sleep mode, Reset or OFF depending on the previously selected shutdown target.
EcuM_SetState	EcuM.h	Function called by BswM to notify about State Switch.
EthIf_StartAllPorts	Ethlf.h	Request to set all configured and affected EthSwt Ports to ETH_MODE_ACTIVE
EthIf_SwitchPortGroupRequestMode	Ethlf.h	Request a mode for the EthlfSwtPortGroup. The call shall be forwarded to EthSwt by calling EthSwt_Set SwitchPortMode for all EthSwtPorts referenced by the port group.
FrSm_AllSlots	FrSm.h	This API function can be used to leave the KeySlot OnlyMode.
FrSm_SetEcuPassive	FrSm.h	This API function can be used to set all FlexRay clusters of the ECU to a receive only mode.
ldsM_BswM_StateChanged	ldsM_Cbk.h	This callback function is invoked by the BswM to indicate ECU state changes.
J1939Dcm_SetState	J1939Dcm.h	Changes the communication state of J1939Dcm to offline or online.
J1939Rm_SetState	J1939Rm.h	Changes the communication state of J1939Rm to offline (only Request for AC supported) or online.





API Function	Header File	Description
LinSM_ScheduleRequest	LinSM.h	The upper layer requests a schedule table to be changed on one LIN network.
Nm_DisableCommunication	Nm.h	Disables the NM PDU transmission ability. For that purpose <bus>Nm_DisableCommunication shall be called in case NmBusType is not set to NM_BUSNM_LOCALNM (e.g. CanNm_Disable Communication function is called if channel is configured as CAN).</bus>
Nm_EnableCommunication	Nm.h	Enables the NM PDU transmission ability. For that purpose <bus>Nm_EnableCommunication shall be called in case NmBusType is not set to NM_BUSNM_LOCALNM. (e.g. CanNm_Enable Communication function is called if channel is configured as CAN).</bus>
Sd_ServiceGroupStart	Sd.h	Starts a preconfigured SdServiceGroup. For example, OfferService entries will be sent out after the call of Sd_ServiceGroupStart() for all Server Servives of a SdServiceGroup, which are not requested yet.
Sd_ServiceGroupStop	Sd.h	Stops a preconfigured SdServiceGroup. For example, StopOfferService entries will be sent out after the call of Sd_ServiceGroupStop() for all ServerServices of a SdServiceGroup, which are not requested by another SdServiceGroup.

∫(SRS_BSW_00384)

8.7 Service Interfaces

8.7.1 Scope of this Chapter

This chapter defines the AUTOSAR Interfaces of the Basic Software Mode Manager Service (BswM). The definitions in this section are interpreted to be in ARPackage AUTOSAR/Services/BswM.

8.7.2 Ports

8.7.2.1 BswM_modeNotificationPort

[SWS_BswM_00200] [

Name	modeNotificationPort_{ArbName}_{ModeName}
Kind	RequiredPort
Interface-Ref	{ecuc(BswM/BswMConfig/BswMArbitration/BswMModeRequestPort/BswMModeRequestSource/BswMSwcModeNotification.BswMSwcModeNotificationModeDeclarationGroupPrototype Ref)}.parent
Description	-





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Variation	ArbName = {ecuc(BswM/BswMConfig/BswMArbitration.SHORT-NAME)}
	ModeName = {ecuc(BswM/BswMConfig/BswMArbitration/BswMModeRequestPort/BswMMode
	RequestSource/BswMSwcModeNotification.SHORT-NAME)}

(SRS_ModeMgm_09180)

[SWS_BswM_00266] [If the BswMDevErrorDetect switch is enabled, BswM_modeNotificationPort shall check if the BSW Mode Manager is initialized. In case of an error, the BswM shall ignore the notification and report the error to the Default Error Tracer with the error code BSWM_E_UNINIT|(SRS_BSW_00406)

8.7.2.2 BswM_modeRequestPort

[SWS_BswM_00201] [

Name	modeRequestPort_{ArbName}_{ReqName}
Kind	RequiredPort
Interface-Ref	{ecuc(BswM/BswMConfig/BswMArbitration/BswMModeRequestPort.BswMModeRequest Source.BswMSwcModeRequest.BswMSwcModeRequestVariableDataPrototypeRef)}.parent
Description	_
Variation	ArbName = {ecuc(BswM/BswMConfig/BswMArbitration.SHORT-NAME)} ReqName = {ecuc(BswM/BswMConfig/BswMArbitration/BswMModeRequestPort.SHORT-NAME)}

(SRS_ModeMgm_09179)

8.7.2.3 BswM modeSwitchPort

[SWS BswM 00202] [

Name	modeSwitchPort_{ModConName}_{SwitchName}
Kind	ProvidedPort
Interface-Ref	{ecuc(BswM/BswMConfig/BswMModeControl/BswMSwitchPort.BswMModeSwitchInterfaceRef)}
Description	-
Variation	{ecuc(BswM/BswMConfig/BswMModeControl/BswMSwitchPort.BswMModeSwitchInterfaceRef} != NULL ModConName = {ecuc(BswM/BswMConfig/BswMModeControl.SHORT-NAME)} SwitchName = {ecuc(BswM/BswMConfig/BswMModeControl/BswMSwitchPort.SHORT-NAME)}

(SRS_ModeMgm_09182)

8.8 API to Request Port Mappings

[SWS_BswM_00283] [

API	Request Port	API / Config-parameter pairs
BswM_BswMPartitionRestarted	BswMPartitionRestarted	-



API	Request Port	API / Config-parameter pairs
BswM_CanSM_CurrentState	BswMCanSMIndication	Network / BswMCanSMChan- nelRef
BswM_ComM_CurrentMode	BswMComMIndication	Network / BswMComMChannel- Ref
BswM_ComM_CurrentPNCMode BswM_ComM_InitiateReset	BswMComMPncRequest BswMComMInitiateReset	PNC / BswMComMPncRef
BswM_Dcm_ApplicationUpdated	BswMDcmApplicationUpdated Indication	-
BswM_Dcm_Communication- Mode_CurrentState	BswMDcmComModeRequest	Network / BswMDcmComM ChannelRef
BswM_EcuM_CurrentState	BswMEcuMIndication	-
BswM_EcuM_CurrentWakeup	BswMEcuMWakeupSource	source / BswMEcuMWakeupSr-cRef
BswM_EcuM_RequestedState	BswMEcuMRUNRequestIndication	State / BswMEcuMRUNRequest ProtocolPort
BswM_EthIf_PortGroupLink StateChg	BswMEthIfPortGroupLinkState- Chg	PortGroupIdx / BswMEthIf SwitchPortGroupRef
BswM_EthSM_CurrentState	BswMEthSMIndication	Network / BswMEthSMChannel- Ref
BswM_FrSM_CurrentState	BswMFrSMIndication	Network / BswMFrSMChannel- Ref
BswM_J1939DcmBroadcast Status	BswMJ1939DcmBroadcast Status	NetworkMask / BswMJ1939 DcmChannelRef
BswM_J1939Nm_StateChange Notification	BswMJ1939NmIndication	Network / BswMJ1939NmChan- nelRef, Node / BswMJ1939Nm NodeRef
BswM_LinSM_CurrentSchedule	BswMLinScheduleIndication	Network / BswMLinSMChannel Ref
BswM_LinSM_CurrentState	BswMLinSMIndication	Network / BswMLinSMChannel Ref
BswM_LinTp_RequestMode	BswMLinTpModeRequest	Network / BswMLinTpChannel Ref
BswM_Nm_CarWakeUpIndication	BswMNmCarWakeUpIndication	-
BswM_Nm_StateChangeNotification	BswMNmStateChangeNotification	Network / BswMNmChannelRef
BswM_NvM_CurrentBlockMode	BswMNvMRequest	Block / BswMNvMBlockRef
BswM_NvM_CurrentJobMode	BswMNvMJobModeIndication	MultiBlockRequest / BswMNvm Service
BswM_RequestMode	BswMGenericRequest	requesting_user / BswMMode RequesterId
BswM_Sd_ClientServiceCurrentState	BswMSdClientServiceCurrent State	SdClientServiceHandleId / BswMSdClientMethodsRef
BswM_Sd_ConsumedEvent GroupCurrentState	BswMSdConsumedEventGroup CurrentState	SdConsumedEventGroupHan- dleId / BswMSdConsumedEvent GroupRef
BswM_Sd_EventHandlerCur- rentState	BswMSdEventHandlerCurrent State	SdEventHandlerHandleId / BswMSdEventHandlerRef

Table 8.1: API to Request Port Mappings: This table describes which request port shall be triggered when an API is called. In addition, it describes which configuration parameter(s) correspond to which API parameter(s)



](SRS_ModeMgm_09228)



9 Sequence diagrams

9.1 Deferred operation of BswM

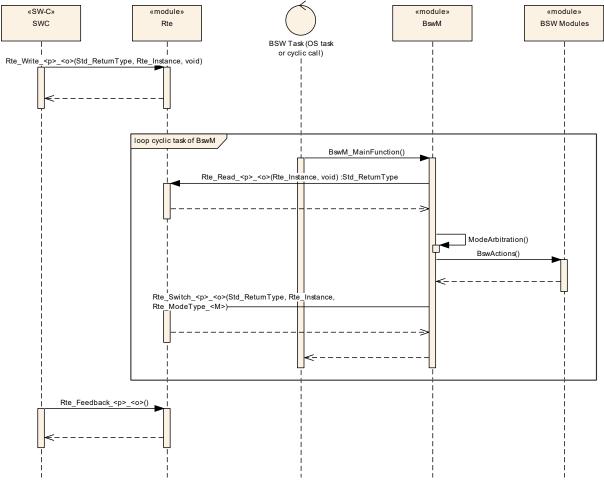


Figure 9.1: Deferred operation of BswM



9.2 Immediate operation of BswM

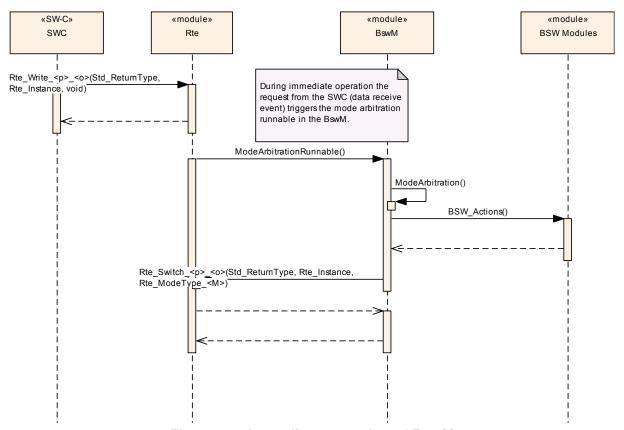


Figure 9.2: Immediate operation of BswM



10 Configuration specification

In general, this chapter defines configuration parameters and their clustering into containers. In order to support the specification Chapter 10.1 describes fundamentals. It also specifies a template (table) you shall use for the parameter specification. We intend to leave Chapter 10.1 in the specification to guarantee comprehension.

Chapter 10.2 specifies the structure (containers) and the parameters of the module BSW Mode Manager.

Chapter 10.3 specifies published information of the module BSW Mode Manager.

10.1 How to read this chapter

For details refer to the chapter 10.1 "Introduction to configuration specification" in SWS BSWGeneral.

10.2 Containers and configuration parameters

The following chapters summarize all configuration parameters. The detailed meanings of the parameters describe Chapter 7 and Chapter 8.

Note for implementers: For some <code>BswMModeRequestSources</code> and <code>BswMAvail-ableActions</code>, a naming convention is used to map certain configuration parameter enumeration values with the underlying function parameter value used in the implementation. In this naming convention, the configuration parameter enumeration label is the same as the mapped function parameter enumeration label, but prefixed with "BSWM_". For example: the <code>BswMEthlfSwitchPortGroupRequestMode</code> value <code>BSWM_ETH_MODE_ACTIVE</code> corresponds to the value of <code>ETH_MODE_ACTIVE</code> of the respective type.

10.2.1 BswM

SWS Item	[ECUC_BswM_01063]	
Module Name	BswM	
Description	Configuration of the BswM (Basic SW Mode Manager) module.	
Post-Build Variant Support	true	
Supported Config Variants	VARIANT-LINK-TIME, VARIANT-POST-BUILD, VARIANT-PRE-COMPILE	



Included Containers				
Container Name	Multiplicity	Scope / Dependency		
BswMConfig	1*	This container contains the configuration parameters and sub containers of the AUTOSAR BswM module. This container exists once per partition.		
BswMGeneral	1	General configuration parameters of the Basic SW Mode Manager.		

10.2.2 BswMConfig

SWS Item	[ECUC_BswM_00895]
Container Name	BswMConfig
Parent Container	BswM
Description	This container contains the configuration parameters and sub containers of the AUTOSAR BswM module. This container exists once per partition.
Configuration Parameters	

SWS Item	[ECUC_BswM_00984]			
Parameter Name	BswMPartitionRef			
Parent Container	BswMConfig			
Description	This references the partition the Bs	wM shall	run inside.	
Multiplicity	01			
Туре	Reference to EcucPartition			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration Class	Pre-compile time X All Variants			
	Link time –			
	Post-build time	Post-build time –		
Value Configuration Class	Pre-compile time X All Variants			
	Link time –			
	Post-build time –			
Scope / Dependency	scope: local		·	

Included Containers				
Container Name	Multiplicity	Scope / Dependency		
BswMArbitration	1	This container includes all configuration sub-containers and parameters related to the mode arbitration functionality of the BswM.		
BswMDataTypeMappingSets	01	Collection of references to DataTypeMappingSet.		
BswMModeControl	1	This container includes all configuration sub-containers and parameters related to the mode control functionality of the BswM.		



10.2.3 BswMArbitration

SWS Item	[ECUC_BswM_00801]
Container Name	BswMArbitration
Parent Container	BswMConfig
Description	This container includes all configuration sub-containers and parameters related to the mode arbitration functionality of the BswM.
Configuration Parameters	

Included Containers				
Container Name	Multiplicity	Scope / Dependency		
BswMEventRequestPort	0*	Each instance of this container defines an event which can be sent to the BswM. Basic Software Modules may send these events to the BswM by calling the corresponding BswM C-API (for example: BswM_ComM_InitiateReset()).		
BswMLogicalExpression	0*	This container describes the logical expressions that can be used for the mode arbitration. The logical expressions are built of a set of arguments and a logical operator. Each argument can either be a mode condition or a sub-expression to allow definition of more complex logical expressions. There may be an unlimited number of arguments in each logical expression. Note that the order of evaluation of the expressions is not defined.		
BswMModeCondition	0*	This container describes the BswM mode conditions that can be used either by itself to form a rule or as a part of a logical expression.		
BswMModeRequestPort	0*	Each instance of this container defines a mode request interfat that is used to requests or indicate modes from/to the BswM. These interfaces are implemented as ports or as ordinary C-functions based upon if the request is made by an SW-C or BSW module. There are different types of mode requests: 1. Mode requests from the SW-C:s 2. Mode Requests from other BSW modules such as the DCM. 3. State/mode indications from the RTE or other BSW modules such as the bus specific State Managers.		
		Note that the BswM treats all request and indications in the exact same way.		
BswMRule	0*	Each instance of this container describes a BswM arbitration rule. The rule either consists of a simple mode condition or a more complex logical expression. This container also references the action lists that shall be invoked when the rule is evaluated to True or False.		

10.2.4 BswMLogicalExpression

SWS Item	[ECUC_BswM_00808]	
Container Name	BswMLogicalExpression	
Parent Container	BswMArbitration	
Description	This container describes the logical expressions that can be used for the mode arbitration. The logical expressions are built of a set of arguments and a logical operator. Each argument can either be a mode condition or a sub-expression to allow definition of more complex logical expressions. There may be an unlimited number of arguments in each logical expression. Note that the order of evaluation of the expressions is not defined.	





Post-Build Variant Multiplicity	false			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE, VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Link time	_		
	Post-build time	_		
Configuration Parameters				

SWS Item	[ECUC_BswM_00814]			
Parameter Name	BswMLogicalOperator			
Parent Container	BswMLogicalExpression			
Description	This parameter specifies the logical operator to be used in the logical expression. If the logical operator is set to something other than BSWM_NOT, and the expression only consists of a single condition, then this parameter will have no effect.			
Multiplicity	01			
Туре	EcucEnumerationParamDef			
Range	BSWM_AND	-		
	BSWM_NAND	-		
	BSWM_NOT	-		
	BSWM_OR			
	BSWM_XOR	M_XOR –		
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration Class	Pre-compile time	Χ	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time –			
Value Configuration Class	Pre-compile time	X VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00820]			
Parameter Name	BswMArgumentRef	BswMArgumentRef		
Parent Container	BswMLogicalExpression			
Description	This is a choice reference either to a	a mode co	ondition or a sub-expression.	
	In case the BswMLogicalExpression.BswMLogicalOperator equals BSWM_NAND only two operands are supported. In case the BswMLogicalExpression.BswMLogical Operator equals BSWM_NOT only one operand is supported.			
Multiplicity	1*			
Туре	Choice reference to [BswMLogicalExpression, BswMModeCondition]			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time –			
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE	





	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

No Included Containers

[SWS_BswM_00242] [The BswM shall reject configurations where a BswMLogical-Expression has a BswMLogicalOperator equal to BSWM_NAND and its number of BswMArgumentRefs is not two. | (SRS_BSW_00167)

[SWS_BswM_00243] [The BswM shall reject configurations where a BswMLogical-Expression has a BswMLogicalOperator equal to BSWM_NOT and its number of BswMArgumentRefs is not one.] (SRS_BSW_00167)

[SWS_BswM_00244] The BswM shall implement BSWM_XOR to evaluate to TRUE if an odd number of its arguments is TRUE, and evaluate to FALSE if an even number of its arguments is TRUE. (SRS ModeMgm 09180)

[SWS_BswM_00245] The BswM shall implement BSWM_AND to evaluate to TRUE if all of its arguments are TRUE, and evaluate to FALSE if at least one of its arguments is FALSE.] (SRS_ModeMgm_09180)

[SWS_BswM_00246] The BswM shall implement BSWM_NAND to evaluate to FALSE if all of its arguments are TRUE, and evaluate to TRUE if at least one of its arguments is FALSE. (SRS_ModeMgm_09180)

[SWS_BswM_00247] The BswM shall implement BSWM_OR to evaluate to FALSE if all of its arguments are FALSE, and evaluate to TRUE if at least one of its arguments is TRUE. (SRS_ModeMam_09180)

[SWS_BswM_00248] The BswM shall implement BSWM_NOT to evaluate to FALSE if its argument is TRUE, and evaluate to TRUE if its argument is FALSE. (SRS_-ModeMgm_09180)

10.2.5 BswMModeCondition

SWS Item	[ECUC_BswM_00807]		
Container Name	BswMModeCondition	BswMModeCondition	
Parent Container	BswMArbitration		
Description	This container describes the BswM mode conditions that can be used either by itself to form a rule or as a part of a logical expression.		
Post-Build Variant Multiplicity	false		
Multiplicity Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE, VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Link time	_	





	Post-build time	_	
Configuration Parameters			

SWS Item	[ECUC_BswM_00815]			
Parameter Name	BswMConditionType			
Parent Container	BswMModeCondition	BswMModeCondition		
Description	This parameter specifies what kind of comparison that is made for the evaluation of the mode condition.			
	For BSWM_EQUALS and BSWM_EQUALS_NOT, the BswMModeRequestPort port referenced by BswMConditionMode is compared with the value configured in Bsw MConditionValue for equality or not-equality.			
			/ENT_IS_CLEARED, the BswMEvent ionMode is checked for being set or	
Multiplicity	1	1		
Туре	EcucEnumerationParamDef			
Range	BSWM_EQUALS	_		
	BSWM_EQUALS_NOT	-		
	BSWM_EVENT_IS_CLEARED	_		
	BSWM_EVENT_IS_SET	_		
Post-Build Variant Value	false	•		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local	·		

SWS Item	[ECUC_BswM_00821]	[ECUC_BswM_00821]		
Parameter Name	BswMConditionMode	BswMConditionMode		
Parent Container	BswMModeCondition			
Description	This parameter references eit	ner a mode re	quest port or an event request port.	
Multiplicity	1	1		
Туре	Choice reference to [BswMEx	Choice reference to [BswMEventRequestPort, BswMModeRequestPort]		
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
BswMConditionValue	01	This container holds the parameters and references necessary to identify the mode type and the value that the mode request is compared to.

[SWS_BswM_00256] Configuration constraint for mode request comparisons and event request checking [The BswM shall reject configurations where BswM_ConditionType BSWM_EQUALS or BSWM_EQUALS_NOT are configured in conjunction with a BswMEventRequestPort port referenced by the BswMConditionType tionMode. The BswM shall reject configurations where BswMConditionType



BSWM_EVENT_IS_SET or BSWM_EVENT_IS_CLEARED are configured in conjunction with a BswMModeRequestPort port referenced by the BswMConditionMode.] (SRS_BSW_00167, SRS_ModeMgm_09177)

10.2.6 BswMConditionValue

SWS Item	[ECUC_BswM_00816]
Choice Container Name	BswMConditionValue
Parent Container	BswMModeCondition
Description	This container holds the parameters and references necessary to identify the mode type and the value that the mode request is compared to.

Container Choices		
Container Name	Multiplicity	Scope / Dependency
BswMBswMode	01	This container defines the value of a mode in the BSW.
BswMCompuScaleModeValue	01	This container contains parameters used to define a mode value.
BswMModeDeclaration	01	When the mode corresponds to a mode request or mode indication interface the mode is defined by a mode declaration. The mode declarations are defined in the SW-C Template and hence a foreign reference to the corresponding Mode Declaration is used.

10.2.7 BswMBswMode

SWS Item	[ECUC_BswM_00869]
Container Name	BswMBswMode
Parent Container	BswMConditionValue
Description	This container defines the value of a mode in the BSW.
Configuration Parameters	

SWS Item	[ECUC_BswM_00866]		
Parameter Name	BswMBswRequestedMode		
Parent Container	BswMBswMode		
Description		This parameter contains the symbolic name (as a string) of a certain mode/state that can be requested/indicated by the BSW modules.	
Multiplicity	1		
Туре	EcucStringParamDef		
Default value	_		
Regular Expression	-		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	Х	All Variants
	Link time	_	
	Post-build time	_	
Value Configuration Class	Pre-compile time	Х	All Variants





	Link time	-	
	Post-build time	-	
Scope / Dependency	scope: local		

No Included Containers	

10.2.8 BswMModeDeclaration

SWS Item	[ECUC_BswM_00868]
Container Name	BswMModeDeclaration
Parent Container	BswMConditionValue
Description	When the mode corresponds to a mode request or mode indication interface the mode is defined by a mode declaration. The mode declarations are defined in the SW-C Template and hence a foreign reference to the corresponding Mode Declaration is used.
Configuration Parameters	

SWS Item	[ECUC_BswM_00864]		
Parameter Name	BswMModeValueRef		
Parent Container	BswMModeDeclaration		
Description	This is a foreign reference to the Mode Declaration used for the mode requests corresponding to this condition.		
Multiplicity	1		
Туре	Foreign reference to MODE-DECLARATION		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

		1
No Included Containers		1
NO Included Containers		1

10.2.9 BswMEventRequestPort

SWS Item	[ECUC_BswM_01052]
Container Name	BswMEventRequestPort
Parent Container	BswMArbitration
Description	Each instance of this container defines an event which can be sent to the BswM. Basic Software Modules may send these events to the BswM by calling the corresponding BswM C-API (for example: BswM_ComM_InitiateReset()).
Post-Build Variant Multiplicity	false





Multiplicity Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE, VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Link time	_	
	Post-build time	_	
Configuration Parameters			

SWS Item	[ECUC_BswM_01056]			
Parameter Name	BswMEventRequestProcessing	BswMEventRequestProcessing		
Parent Container	BswMEventRequestPort			
Description	This parameter defines if the processing of the mode arbitration shall be done immediately when an event request is received or if it shall be deferred to the processing of the main function of BswM.			
Multiplicity	1	1		
Туре	EcucEnumerationParamDef			
Range	BSWM_DEFERRED	-		
	BSWM_IMMEDIATE	-		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local		_	

Included Containers			
Container Name	Multiplicity	Scope / Dependency	
BswMEventRequestSource	1	This choice container specifies the source of the event request. The sender of the event can be another BSW Module, such as ComM.	

10.2.10 BswMModeRequestPort

SWS Item	[ECUC_BswM_00805]		
Container Name	BswMModeRequestPort		
Parent Container	BswMArbitration		
Description	Each instance of this container defines a mode request interface that is used to requests or indicate modes from/to the BswM. These interfaces are implemented as ports or as ordinary C-functions based upon if the request is made by an SW-C or a BSW module. There are different types of mode requests: 1. Mode requests from the SW-C:s 2. Mode Requests from other BSW modules such as the DCM. 3. State/mode indications from the RTE or other BSW modules such as the bus specific State Managers. Note that the BswM treats all request and indications in the exact same way.		
Post-Build Variant Multiplicity	false		
Multiplicity Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE, VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Link time	_	





	Post-build time	_	
Configuration Parameters			

SWS Item	[ECUC_BswM_00822]		
Parameter Name	BswMRequestProcessing		
Parent Container	BswMModeRequestPort		
Description	This parameter defines if the processing of the mode arbitration shall be done immediately when a mode request is received or if it shall be deferred to the processing of the main function of BswM.		
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	BSWM_DEFERRED	-	
	BSWM_IMMEDIATE -		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local	·	

Included Containers				
Container Name	Multiplicity	Scope / Dependency		
BswMModelnitValue	01	This container defines the initial mode value that is used by Bsw M for the corresponding mode request after initialization. The initial mode value is defined by configuring either BswMBsw ModelnitValue or BswMCompuScaleModeValue. This container is optional.		
BswMModeRequestSource	1	This choice container specifies the source of the mode request or state/mode indication. The requester of a mode can be both SW-C:s and other BSW Modules, such as the bus specific State Managers.		

10.2.11 BswMModelnitValue

SWS Item	[ECUC_BswM_00928]
Container Name	BswMModeInitValue
Parent Container	BswMModeRequestPort
Description	This container defines the initial mode value that is used by BswM for the corresponding mode request after initialization. The initial mode value is defined by configuring either BswMBswModeInitValue or BswMCompuScaleModeValue. This container is optional.
Configuration Parameters	

SWS Item	[ECUC_BswM_00932]
Parameter Name	BswMBswModeInitValue
Parent Container	BswMModeInitValue
Description	This parameter defines the initial mode value that is used by BswM for the corresponding mode request after initialization.
Multiplicity	01





Туре	EcucStringParamDef		
Default value	_		
Regular Expression	_		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	Х	All Variants
	Link time	_	
	Post-build time	_	
Value Configuration Class	Pre-compile time	Х	All Variants
	Link time	_	
	Post-build time	_	
Scope / Dependency	scope: local		

Included Containers		
Container Name	Multiplicity	Scope / Dependency
BswMCompuScaleModeValue	01	This container contains parameters used to define a mode value.

10.2.12 BswMCompuScaleModeValue

SWS Item	[ECUC_BswM_01039]
Container Name	BswMCompuScaleModeValue
Parent Container	BswMConditionValue, BswMModeInitValue
Description	This container contains parameters used to define a mode value.
Configuration Parameters	

SWS Item	[ECUC_BswM_01041]			
Parameter Name	BswMCompuConstText	BswMCompuConstText		
Parent Container	BswMCompuScaleModeValu	е		
Description	The value of this parameter shall match the VT member of a CompuConst defined within the referenced CompuMethod (BswMCompuMethodRef). The interval value of the corresponding CompuScale shall be used as the mode request value.			
Multiplicity	1	1		
Туре	EcucStringParamDef	EcucStringParamDef		
Default value	-			
Regular Expression	-			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time	-		
	Post-build time –			
Scope / Dependency	scope: local	·		

SWS Item	[ECUC_BswM_01040]
Parameter Name	BswMCompuMethodRef
Parent Container	BswMCompuScaleModeValue





Description	This is a foreign reference to the CompuMethod used for mode requests.		
Multiplicity	1		
Туре	Foreign reference to COMPU-METHOD		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X All Variants		
	Link time	-	
	Post-build time	_	
Scope / Dependency	scope: local		

No Included Containers

[SWS_BswM_CONSTR_00002] [The value of CompuMethod.category referenced by the foreign reference of BswMCompuMethodRef shall be TEXTTABLE.] (SRS_BSW_-00167)

10.2.13 BswMEventRequestSource

SWS Item	[ECUC_BswM_01053]
Choice Container Name	BswMEventRequestSource
Parent Container	BswMEventRequestPort
Description	This choice container specifies the source of the event request. The sender of the event can be another BSW Module, such as ComM.

Container Choices		
Container Name	Multiplicity	Scope / Dependency
BswMComMInitiateReset	01	This is an indication from the ComM to signal a shutdown.
BswMDcmApplicationUpdated Indication	01	This is a request to update application data from the DCM. This container does not contain any parameters since there are no further configuration needed for this type of request.
BswMModeSwitchErrorEvent	01	This is a notification that an error occurred because the partition containing mode users of the referenced PPort was restarted by the RTE. Because the Mode Machine Instance holding the current mode can reside on that terminated partition, the Mode Manager has to be informed about the loss of this partition.
BswMNmCarWakeUpIndication	01	This is an indication of a CarWakeup from the Nm.
BswMPartitionRestarted	01	This is a notification that an error occured because the partition containing the BswM was restarted by the RTE. The Mode Users may lie in another (still running) partition. So the BswM has to be informed that the start of its partition is no normal startup but a restart of a single partition. This information can be used inside the Rules. This notification has to be used by the Restart Task of the particular partition.
BswMSwitchAckNotification	01	This is a notification that a mode transition has been completed.



10.2.14 BswMModeRequestSource

SWS Item	[ECUC_BswM_00856]
Choice Container Name	BswMModeRequestSource
Parent Container	BswMModeRequestPort
Description	This choice container specifies the source of the mode request or state/mode indication. The requester of a mode can be both SW-C:s and other BSW Modules, such as the bus specific State Managers.

Container Choices		
Container Name	Multiplicity	Scope / Dependency
BswMBswModeNotification	01	This is a mode request source emanating from another BSW Module.
BswMCanSMIndication	01	This is an indication of the current state of the CAN State Manager.
BswMComMIndication	01	This is an indication of the current communication mode of a channel in the Communication Manager.
BswMComMPncRequest	01	This is a request of the current communication mode of a Partial Network Cluster in the Communication Manager.
BswMDcmComModeRequest	01	The source of the mode request is the Diagnostic Communication Manager.
BswMEcuMIndication	01	This is a notification of the current operation mode of the ECU State Manager. This container does not contain any parameters since there are no further configuration needed for this type of request.
BswMEcuMRUNRequestIndication	01	This is an indication of the current State of the RUN Request Protocol.
BswMEcuMWakeupSource	01	This is a notification of the current state of an ECU State Manager wakeup source.
BswMEthIfPortGroupLinkStateChg	01	This is an indication from the Ethlf if the link state of a Ethernet interface switch port group has changed.
BswMEthSMIndication	01	This is an indication of the current state of the Ethernet State Manager.
BswMFrSMIndication	01	This is an indication of the current state of the FlexRay State Manager.
BswMGenericRequest	01	This mode request originates from a requester that is not among the list of standardized mode requesters (i.e. the different resource managers).
BswMJ1939DcmBroadcastStatus	01	This is a notification of the desired broadcast status per network, triggered via DM13.
BswMJ1939NmIndication	01	This is an indication of the current state of the J1939 network management module.
BswMLinSMIndication	01	This is an indication of the current state of the LIN State Manager.
BswMLinScheduleIndication	01	This is an indication of the currently active LIN Schedule Table for a specific LIN Interface.
BswMLinTpModeRequest	01	This is a LinTp mode request from the LinIf. This port corresponds to a call of the BswM_LinTp_RequestMode API.
BswMNmStateChangeNotification	01	This is a notification from the Nm module that its state has changed.
BswMNvMJobModeIndication	01	Indicates the current status of the multiblock job. The job is identified via BswMNvmService. Possible values for this indication are the possible values of NvM_RequestResultType.





Container Choices		
Container Name	Multiplicity	Scope / Dependency
BswMNvMRequest	01	Via this Mode Request Source the NvM indicates the current status of the specified block. Possible Values are: NvM_Request ResultType NVM_REQ_OK NVM_REQ_NOT_OK NVM_REQ_PENDING NVM_REQ_INTEGRITY_FAILED NVM_REQ_BLOCK_SKIPPED NVM_REQ_NV_INVALIDATED NVM_REQ_CANCELED NVM_REQ_REDUNDANCY_FAILED NVM_REQ_RESTORED_FROM_ROM
BswMSdClientServiceCurrentState	01	Used by Service Discovery module to indicate current state of the Client Service (available/down).
BswMSdConsumedEventGroup CurrentState	01	Used by Service Discovery to indicate current status of the Event Handler (requested/released).
BswMSdEventHandlerCurrentState	01	Used by Service Discovery to indicate current status of the Event Handler (requested/released).
BswMSoAdSoConModeChg	01	This is an indication of the current state of the SoAd.
BswMSwcModeNotification	01	This is a mode switch notification associated with a RTE switch interface.
BswMSwcModeRequest	01	The source of the mode request is a SW Component.
BswMTimer	01	This is a timer which can be used for time dependent rules. This mode request port can be in one of three modes (depending on the state of the timer):
		 BSWM_TIMER_STOPPED (intial) (The timer has been stopped by an action)
		BSWM_TIMER_STARTED (The timer has been started by an action)
		BSWM_TIMER_EXPIRED (The timer has expired)

10.2.15 BswMBswModeNotification

SWS Item	[ECUC_BswM_00926]
Container Name	BswMBswModeNotification
Parent Container	BswMModeRequestSource
Description	This is a mode request source emanating from another BSW Module.
Configuration Parameters	

SWS Item	[ECUC_BswM_00927]			
Parameter Name	BswMBswModeDeclarationGroup	BswMBswModeDeclarationGroupPrototypeRef		
Parent Container	BswMBswModeNotification			
Description	This is a foreign reference to the M	This is a foreign reference to the Mode Declaration Group Prototype.		
Multiplicity	1	1		
Туре	Foreign reference to MODE-DECLARATION-GROUP-PROTOTYPE			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local	-		

No Included Contain	iers
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10.2.16 BswMCanSMIndication

SWS Item	[ECUC_BswM_00857]
Container Name	BswMCanSMIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the current state of the CAN State Manager.
Configuration Parameters	

SWS Item	[ECUC_BswM_00870]			
Parameter Name	BswMCanSMChannelRef	BswMCanSMChannelRef		
Parent Container	BswMCanSMIndication			
Description	This is a reference to the CAN cha	This is a reference to the CAN channel handle that the mode request corresponds to.		
Multiplicity	1	1		
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	-		
Scope / Dependency	scope: local			

No Included Containers	

10.2.17 BswMComMIndication

SWS Item	[ECUC_BswM_00880]
Container Name	BswMComMIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the current communication mode of a channel in the Communication Manager.
Configuration Parameters	

SWS Item	[ECUC_BswM_00883]			
Parameter Name	BswMComMChannelRef	BswMComMChannelRef		
Parent Container	BswMComMIndication			
Description	This is a reference to the Communication Manager channel handle that the indication corresponds to.			
Multiplicity	1			
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	-		
Scope / Dependency	scope: local			

No Included Containers



10.2.18 BswMComMInitiateReset

SWS Item	[ECUC_BswM_01014]
Container Name	BswMComMInitiateReset
Parent Container	BswMEventRequestSource
Description	This is an indication from the ComM to signal a shutdown.
Configuration Parameters	

No Included Containers

10.2.19 BswMComMPncRequest

SWS Item	[ECUC_BswM_00922]
Container Name	BswMComMPncRequest
Parent Container	BswMModeRequestSource
Description	This is a request of the current communication mode of a Partial Network Cluster in the Communication Manager.
Configuration Parameters	

SWS Item	[ECUC_BswM_00924]			
Parameter Name	BswMComMPncRef	BswMComMPncRef		
Parent Container	BswMComMPncRequest			
Description		This is a reference to the Communication Manager PNC handle of the Partial Network Cluster that the request corresponds to.		
Multiplicity	1	1		
Туре	Symbolic name reference to ComMPnc			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.20 BswMDcmApplicationUpdatedIndication

SWS Item	[ECUC_BswM_00925]
Container Name	BswMDcmApplicationUpdatedIndication
Parent Container	BswMEventRequestSource
Description	This is a request to update application data from the DCM. This container does not contain any parameters since there are no further configuration needed for this type of request.
Configuration Parameters	



No Included Containers

10.2.21 BswMDcmComModeRequest

SWS Item	[ECUC_BswM_00863]
Container Name	BswMDcmComModeRequest
Parent Container	BswMModeRequestSource
Description	The source of the mode request is the Diagnostic Communication Manager.
Configuration Parameters	

SWS Item	[ECUC_BswM_00969]			
Parameter Name	BswMDcmComMChannelRef			
Parent Container	BswMDcmComModeRequest			
Description	This is a reference from DcmModeRequest to the ComM channel that the indication corresponds to.			
Multiplicity	1			
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.22 BswMEcuMIndication

SWS Item	[ECUC_BswM_01085]
Container Name	BswMEcuMIndication
Parent Container	BswMModeRequestSource
Description	This is a notification of the current operation mode of the ECU State Manager. This container does not contain any parameters since there are no further configuration needed for this type of request.
Configuration Parameters	

No Included Containers



10.2.23 BswMEcuMRUNRequestIndication

SWS Item	[ECUC_BswM_01086]
Container Name	BswMEcuMRUNRequestIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the current State of the RUN Request Protocol.
Configuration Parameters	

SWS Item	[ECUC_BswM_01087]			
Parameter Name	BswMEcuMRUNRequestProtocolPo	BswMEcuMRUNRequestProtocolPort		
Parent Container	BswMEcuMRUNRequestIndication			
Description	Identifies the EcuM State which is re	elated to	the mode request.	
Multiplicity	1	1		
Туре	EcucEnumerationParamDef			
Range	BSWM_ECUM_STATE_POST_ RUN	Port for POST_RUN State of EcuM.		
	BSWM_ECUM_STATE_RUN	Port for RUN State of EcuM.		
Post-Build Variant Value	false	_		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local		_	

No Included Containers

10.2.24 BswMEcuMWakeupSource

SWS Item	[ECUC_BswM_00904]
Container Name	BswMEcuMWakeupSource
Parent Container	BswMModeRequestSource
Description	This is a notification of the current state of an ECU State Manager wakeup source.
Configuration Parameters	

SWS Item	[ECUC_BswM_00905]		
Parameter Name	BswMEcuMWakeupSrcRef		
Parent Container	BswMEcuMWakeupSource		
Description	This is a reference to the ECU State Manager Wakeup Source that the indication corresponds to.		
Multiplicity	1		
Туре	Symbolic name reference to EcuMWakeupSource		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	





Scope / Dependency	scope: local
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No Included Containers

10.2.25 BswMEthIfPortGroupLinkStateChg

SWS Item	[ECUC_BswM_01066]
Container Name	BswMEthIfPortGroupLinkStateChg
Parent Container	BswMModeRequestSource
Description	This is an indication from the Ethlf if the link state of a Ethernet interface switch port group has changed.
Configuration Parameters	

SWS Item	[ECUC_BswM_01067]			
Parameter Name	BswMEthIfSwitchPortGroupRef	BswMEthIfSwitchPortGroupRef		
Parent Container	BswMEthIfPortGroupLinkStateChg			
Description	This is a reference to the Ethernet I corresponds to.	This is a reference to the Ethernet Interface Switch Port Group that the indication corresponds to.		
Multiplicity	1			
Туре	Symbolic name reference to EthIfSwitchPortGroup			
Post-Build Variant Value	true			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.26 BswMEthSMIndication

SWS Item	[ECUC_BswM_00860]
Container Name	BswMEthSMIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the current state of the Ethernet State Manager.
Configuration Parameters	

SWS Item	[ECUC_BswM_00873]
Parameter Name	BswMEthSMChannelRef
Parent Container	BswMEthSMIndication
Description	This is a reference to the Ethernet channel handle that the mode request corresponds to.





Multiplicity	1			
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

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10.2.27 BswMFrSMIndication

SWS Item	[ECUC_BswM_00858]
Container Name	BswMFrSMIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the current state of the FlexRay State Manager.
Configuration Parameters	

SWS Item	[ECUC_BswM_00872]			
Parameter Name	BswMFrSMChannelRef			
Parent Container	BswMFrSMIndication			
Description	This is a reference to the FlexRay	This is a reference to the FlexRay Cluster handle that the mode request corresponds to.		
Multiplicity	1	1		
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No	Included Containers		

10.2.28 BswMGenericRequest

SWS Item	[ECUC_BswM_00861]
Container Name	BswMGenericRequest
Parent Container	BswMModeRequestSource
Description	This mode request originates from a requester that is not among the list of standardized mode requesters (i.e. the different resource managers).
Configuration Parameters	



SWS Item	[ECUC_BswM_00874]			
Parameter Name	BswMModeRequesterId			
Parent Container	BswMGenericRequest			
Description	This parameters identifies the difference	ent users	of the generic mode request interface.	
Multiplicity	1	1		
Туре	EcucIntegerParamDef (Symbolic Name generated for this parameter)			
Range	0 65535			
Default value	-	-		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	All Variants	
	Link time	_		
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.29 BswMJ1939DcmBroadcastStatus

SWS Item	[ECUC_BswM_00985]
Container Name	BswMJ1939DcmBroadcastStatus
Parent Container	BswMModeRequestSource
Description	This is a notification of the desired broadcast status per network, triggered via DM13.
Configuration Parameters	

SWS Item	[ECUC_BswM_00988]			
Parameter Name	BswMJ1939DcmChannelRef			
Parent Container	BswMJ1939DcmBroadcastStatus			
Description	Reference to the communication ch	annel wh	ich is affected by this mode request.	
Multiplicity	1	1		
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

[SWS_BswM_00250] [Since NetworkMask (in the BswM_-J1939DcmBroadcastStatus API) is 16 bits wide, the BswM shall reject configurations where the ComMChannel.ComMChannelId referenced by a BswMJ1939DcmBroadcastStatus.BswMJ1939DcmChannelRef parameter is greater than 15.] (SRS_ModeMgm_09228)



10.2.30 BswMJ1939NmIndication

SWS Item	[ECUC_BswM_00966]
Container Name	BswMJ1939NmIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the current state of the J1939 network management module.
Configuration Parameters	

SWS Item	[ECUC_BswM_00967]			
Parameter Name	BswMJ1939NmChannelRef			
Parent Container	BswMJ1939NmIndication			
Description	This is a reference to the J1939Nn to.	This is a reference to the J1939Nm channel handle that the mode request corresponds to.		
Multiplicity	1	1		
Туре	Symbolic name reference to ComM	Symbolic name reference to ComMChannel		
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00997]		
Parameter Name	BswMJ1939NmNodeRef		
Parent Container	BswMJ1939NmIndication		
Description	This is a reference to the node that	the mode	e request corresponds to.
Multiplicity	1		
Туре	Symbolic name reference to J1939NmNode		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	-	
Scope / Dependency	scope: local		

No Included Containers	

10.2.31 BswMLinSMIndication

SWS Item	[ECUC_BswM_00859]
Container Name	BswMLinSMIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the current state of the LIN State Manager.
Configuration Parameters	



SWS Item	[ECUC_BswM_00871]			
Parameter Name	BswMLinSMChannelRef	BswMLinSMChannelRef		
Parent Container	BswMLinSMIndication			
Description	This is a reference to the LIN channel handle that the mode request corresponds to.			
Multiplicity	1			
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	-		
Scope / Dependency	scope: local			

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10.2.32 BswMLinScheduleIndication

SWS Item	[ECUC_BswM_00885]
Container Name	BswMLinScheduleIndication
Parent Container	BswMModeRequestSource
Description	This is an indication of the currently active LIN Schedule Table for a specific LIN Interface.
Configuration Parameters	

SWS Item	[ECUC_BswM_00886]			
Parameter Name	BswMLinScheduleRef	BswMLinScheduleRef		
Parent Container	BswMLinScheduleIndication	BswMLinScheduleIndication		
Description	This is a reference to the LIN Schedule Table handle that the mode request corresponds to.			
Multiplicity	1	1		
Туре	Symbolic name reference to I	Symbolic name reference to LinSMSchedule		
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01028]		
Parameter Name	BswMLinSMChannelRef		
Parent Container	BswMLinScheduleIndication		
Description	This is a reference to the LIN channel handle that the mode request corresponds to.		
Multiplicity	1		
Туре	Symbolic name reference to ComMChannel		
Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME





	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

10.2.33 BswMLinTpModeRequest

SWS Item	[ECUC_BswM_00914]
Container Name	BswMLinTpModeRequest
Parent Container	BswMModeRequestSource
Description	This is a LinTp mode request from the LinIf. This port corresponds to a call of the Bsw M_LinTp_RequestMode API.
Configuration Parameters	

SWS Item	[ECUC_BswM_00915]		
Parameter Name	BswMLinTpChannelRef		
Parent Container	BswMLinTpModeRequest		
Description	This is a reference to the LIN Interface Channel that the mode request corresponds to.		
Multiplicity	1		
Туре	Symbolic name reference to ComMChannel		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local	•	

ded Containers

10.2.34 BswMModeSwitchErrorEvent

SWS Item	[ECUC_BswM_00990]
Container Name	BswMModeSwitchErrorEvent
Parent Container	BswMEventRequestSource
Description	This is a notification that an error occurred because the partition containing mode users of the referenced PPort was restarted by the RTE. Because the Mode Machine Instance holding the current mode can reside on that terminated partition, the Mode Manager has to be informed about the loss of this partition.
Configuration Parameters	

SWS Item	[ECUC_BswM_01030]
Parameter Name	BswMRteSwitchPortRef
Parent Container	BswMModeSwitchErrorEvent





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Description	This is a reference to the BswMSwitchPort.			
Multiplicity	1			
Туре	Reference to BswMSwitchPort			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers

[SWS_BswM_00259] [BswMModeSwitchErrorEvent specifies a SwcMode-ManagerErrorEvent, which the BswM shall create in its SWCD. The ModeDeclarationGroupPrototype which is referenced by the SwcModeManager-ErrorEvent.modeGroup shall correspond to the one used by the ModeSwitchInterface which is referenced by the BswMSwitchPort that is configured by the BswMRteSwitchPortRef in BswMModeSwitchErrorEvent. The BswM shall create an associated runnable which will arbitrate the SwcModeManagerErrorEvent.] (SRS_ModeMgm_09182)

10.2.35 BswMNmCarWakeUpIndication

SWS Item	[ECUC_BswM_01075]
Container Name	BswMNmCarWakeUpIndication
Parent Container	BswMEventRequestSource
Description	This is an indication of a CarWakeup from the Nm.
Configuration Parameters	

SWS Item	[ECUC_BswM_01049]			
Parameter Name	BswMNmChannelRef			
Parent Container	BswMNmCarWakeUpIndication			
Description	This is a reference to the channel h	andle tha	t the indication corresponds to.	
Multiplicity	1			
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers



10.2.36 BswMNmStateChangeNotification

SWS Item	[ECUC_BswM_01081]
Container Name	BswMNmStateChangeNotification
Parent Container	BswMModeRequestSource
Description	This is a notification from the Nm module that its state has changed.
Configuration Parameters	

SWS Item	[ECUC_BswM_01082]			
Parameter Name	BswMNmChannelRef			
Parent Container	BswMNmStateChangeNotification			
Description	This is a reference to the channel h	andle tha	t this notification corresponds to.	
Multiplicity	1	1		
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Co	ntainers				
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10.2.37 BswMNvMJobModeIndication

SWS Item	[ECUC_BswM_00956]
Container Name	BswMNvMJobModeIndication
Parent Container	BswMModeRequestSource
Description	Indicates the current status of the multiblock job. The job is identified via BswMNvm Service. Possible values for this indication are the possible values of NvM_Request ResultType.
Configuration Parameters	

SWS Item	[ECUC_BswM_00957]		
Parameter Name	BswMNvmService		
Parent Container	BswMNvMJobModeIndication		
Description	Identifies the Nvm job which is relat	ted to the mode request.	
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	NvmCancelWriteAll	corresponds to multi block service NvM_Cancel WriteAll	
	NvmFirstInitAll	corresponds to multi block service NvM_FirstInit All	
	NvmReadAll corresponds to multi block service NvM_Rea		
	NvmValidateAll	corresponds to multi block service NvM_Validate All	





	NvmWriteAll	corresp	corresponds to multi block service NvM_WriteAll	
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers	
NO Included Containers	

10.2.38 BswMNvMRequest

SWS Item	[ECUC_BswM_00890]
Container Name	BswMNvMRequest
Parent Container	BswMModeRequestSource
Description	Via this Mode Request Source the NvM indicates the current status of the specified block. Possible Values are: NvM_RequestResultType NVM_REQ_OK NVM_REQ_NOT_OK NVM_REQ_PENDING NVM_REQ_INTEGRITY_FAILED NVM_REQ_BLOCK_SKIPPED NVM_REQ_NV_INVALIDATED NVM_REQ_CANCELED NVM_REQ_REDUNDANCY_FAILED NVM_REQ_RESTORED_FROM_ROM
Configuration Parameters	

SWS Item	[ECUC_BswM_00891]			
Parameter Name	BswMNvMBlockRef	BswMNvMBlockRef		
Parent Container	BswMNvMRequest			
Description	This is a reference to the NvM Bl	This is a reference to the NvM Block Descriptor that the request corresponds to.		
Multiplicity	1	1		
Туре	Symbolic name reference to NvMBlockDescriptor			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers	
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10.2.39 BswMPartitionRestarted

SWS Item	[ECUC_BswM_00989]
Container Name	BswMPartitionRestarted
Parent Container	BswMEventRequestSource





Description	This is a notification that an error occured because the partition containing the BswM was restarted by the RTE. The Mode Users may lie in another (still running) partition. So the BswM has to be informed that the start of its partition is no normal startup but a restart of a single partition. This information can be used inside the Rules. This notification has to be used by the Restart Task of the particular partition.
Configuration Parameters	

No Included Containers

10.2.40 BswMSdClientServiceCurrentState

SWS Item	[ECUC_BswM_01011]
Container Name	BswMSdClientServiceCurrentState
Parent Container	BswMModeRequestSource
Description	Used by Service Discovery module to indicate current state of the Client Service (available/down).
Configuration Parameters	

SWS Item	[ECUC_BswM_01009]			
Parameter Name	BswMSdClientMethodsRef	BswMSdClientMethodsRef		
Parent Container	BswMSdClientServiceCurrentStat	e		
Description	This is a reference to a client serv	This is a reference to a client service in the Sd module.		
Multiplicity	1	1		
Туре	Symbolic name reference to SdCl	Symbolic name reference to SdClientService		
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers

10.2.41 BswMSdConsumedEventGroupCurrentState

SWS Item	[ECUC_BswM_01012]
Container Name	BswMSdConsumedEventGroupCurrentState
Parent Container	BswMModeRequestSource
Description	Used by Service Discovery to indicate current status of the EventHandler (requested/released).
Configuration Parameters	



SWS Item	[ECUC_BswM_01010]			
Parameter Name	BswMSdConsumedEventGroupRef			
Parent Container	BswMSdConsumedEventGroupCuri	rentState		
Description	This is a reference to an eventGroup that is defined within a client service in the Sd module.			
Multiplicity	1			
Туре	Symbolic name reference to SdConsumedEventGroup			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers	
No included containers	

10.2.42 BswMSdEventHandlerCurrentState

SWS Item	[ECUC_BswM_01013]
Container Name	BswMSdEventHandlerCurrentState
Parent Container	BswMModeRequestSource
Description	Used by Service Discovery to indicate current status of the EventHandler (requested/released).
Configuration Parameters	

SWS Item	[ECUC_BswM_01008]	[ECUC_BswM_01008]			
Parameter Name	BswMSdEventHandlerRef				
Parent Container	BswMSdEventHandlerCurrer	ntState			
Description	This is a reference to an eve module.	This is a reference to an event handler that is defined within a server service in the Sd module.			
Multiplicity	1	1			
Туре	Symbolic name reference to	Symbolic name reference to SdEventHandler			
Post-Build Variant Value	false	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD				
	Post-build time –				
Scope / Dependency	scope: local				

No Included Containers



10.2.43 BswMSoAdSoConModeChg

SWS Item	[ECUC_BswM_01091]
Container Name	BswMSoAdSoConModeChg
Parent Container	BswMModeRequestSource
Description	This is an indication of the current state of the SoAd.
Post-Build Variant Multiplicity	false
Configuration Parameters	

SWS Item	[ECUC_BswM_01092]			
Parameter Name	BswMSoAdSocketIdRef	BswMSoAdSocketIdRef		
Parent Container	BswMSoAdSoConModeChg			
Description	This is a reference to the SoAd soc	ket ID ha	ndle that the mode request corresponds to.	
Multiplicity	1	1		
Туре	Symbolic name reference to SoAdSocketConnection			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers

10.2.44 BswMSwcModeNotification

SWS Item	[ECUC_BswM_00892]
Container Name	BswMSwcModeNotification
Parent Container	BswMModeRequestSource
Description	This is a mode switch notification associated with a RTE switch interface.
Configuration Parameters	

SWS Item	[ECUC_BswM_00893]			
Parameter Name	BswMSwcModeNotificationModeDeclarationGroupPrototypeRef			
Parent Container	BswMSwcModeNotification			
Description	This is a foreign reference to the	This is a foreign reference to the ModeDeclarationGroupPrototype.		
Multiplicity	1			
Туре	Foreign reference to MODE-DECLARATION-GROUP-PROTOTYPE			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers



10.2.45 BswMSwcModeRequest

SWS Item	[ECUC_BswM_00862]
Container Name	BswMSwcModeRequest
Parent Container	BswMModeRequestSource
Description	The source of the mode request is a SW Component.
Configuration Parameters	

SWS Item	[ECUC_BswM_01046]			
Parameter Name	BswMSwcModeRequestVarial	BswMSwcModeRequestVariableDataPrototypeRef		
Parent Container	BswMSwcModeRequest			
Description	This is a reference to the Varia	This is a reference to the VariableDataPrototype.		
Multiplicity	1			
Туре	Foreign reference to VARIABLE-DATA-PROTOTYPE			
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local			

No Included Containers

[SWS_BswM_00236] [The BswM shall only accept configurations where the VariableDataPrototype, which is referenced by a BswMSwcModeRequest, belongs to a SenderReceiverInterface. | (SRS_ModeMgm_09179)

10.2.46 BswMSwitchAckNotification

SWS Item	[ECUC_BswM_01083]
Container Name	BswMSwitchAckNotification
Parent Container	BswMEventRequestSource
Description	This is a notification that a mode transition has been completed.
Configuration Parameters	

SWS Item	[ECUC_BswM_01084]			
Parameter Name	BswMSwitchPortRef	BswMSwitchPortRef		
Parent Container	BswMSwitchAckNotification			
Description	References the switch port which w	References the switch port which will receive the notification.		
Multiplicity	1			
Туре	Reference to BswMSwitchPort			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time	Post-build time –		





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Scope / Dependency	scope: local
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No Included Containers

[SWS_BswM_00284] [For BswMSwitchAckNotification, if the referenced BswM-SwitchPort is configured with BswMModeSwitchInterfaceRef without a BswM-SchMModeDeclarationGroupRef: This specifies a ModeSwitchedAckEvent, which the BswM shall create in its SWCD. The BswM shall create an associated runnable; the C definition of this runnable/schedulable entity shall arbitrate the ModeSwitchedAckEvent. | ()

[SWS_BswM_00285] [For BswMSwitchAckNotification, if the referenced BswM-SwitchPort is configured with BswMSchMModeDeclarationGroupRef: This specifies a BswModeSwitchedAckEvent, which the BswM shall create in its BSWMD. The BswM shall create an associated runnable; the C definition of this runnable/schedulable entity shall arbitrate the BswModeSwitchedAckEvent. | ()

10.2.47 BswMTimer

SWS Item	[ECUC_BswM_01058]	
Container Name	BswMTimer	
Parent Container	BswMModeRequestSource	
Description	This is a timer which can be used for time dependent rules. This mode request port can be in one of three modes (depending on the state of the timer):	
	BSWM_TIMER_STOPPED (intial) (The timer has been stopped by an action)	
	BSWM_TIMER_STARTED (The timer has been started by an action)	
	BSWM_TIMER_EXPIRED (The timer has expired)	
Configuration Parameters		

No Included Containers

10.2.48 BswMRule

SWS Item	[ECUC_BswM_00806]			
Container Name	BswMRule			
Parent Container	BswMArbitration			
Description	Each instance of this container describes a BswM arbitration rule. The rule either consists of a simple mode condition or a more complex logical expression. This container also references the action lists that shall be invoked when the rule is evaluated to True or False.			
Post-Build Variant Multiplicity	true			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME	







	Post-build time	Х	VARIANT-POST-BUILD
Configuration Parameters			

SWS Item	[ECUC_BswM_00935]			
Parameter Name	BswMNestedExecutionOnly	BswMNestedExecutionOnly		
Parent Container	BswMRule			
Description	This parameter defines for its Subordinate rule;	This parameter defines for its related Rule if the Rule is an Independent rule or a Subordinate rule;		
	·	false: an Independent rule, i.e. to be evaluated each time applicable (both as standalone Rule driven by its own BswMModeRequestSource and when referenced by another Rule).		
	true: a Subordinated rule, to bor more Action Lists.	true: a Subordinated rule, to be evaluated ONLY as a result of being referenced in one or more Action Lists.		
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00888]			
Parameter Name	BswMRuleInitState			
Parent Container	BswMRule			
Description	This parameter is a part of the reset/initialization behavior of BswM. Action lists are executed when the result of a rule evaluation have changed since the last evaluation. This parameter defines the "previous evaluation result" of a rule to be used after initialization of the BswM.			
		If this parameter is set to BSWM_UNDEFINED, the evaluation result is always treated as changed at the first evaluation of the rule after initialization.		
	If this parameter is set to BSWM_T the rule is evaluated to false.	If this parameter is set to BSWM_TRUE, the evaluation result is treated as changed if the rule is evaluated to false.		
	If this parameter is set to BSWM_FALSE, the evaluation result is treated as changed if the rule is evaluated to true.			
Multiplicity	1	1		
Туре	EcucEnumerationParamDef			
Range	BSWM_FALSE -			
	BSWM_TRUE	_		
	BSWM_UNDEFINED -			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time –			
Scope / Dependency	scope: local			



SWS Item	[ECUC_BswM_00819]			
Parameter Name	BswMRuleExpressionRef			
Parent Container	BswMRule	BswMRule		
Description	This is a reference to the logical expression that is evaluated for each rule.			
Multiplicity	1			
Туре	Reference to BswMLogicalExpression			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00818]			
Parameter Name	BswMRuleFalseActionList			
Parent Container	BswMRule			
Description	This is a reference to the action list that shall be executed when the rule is evaluated to False			
Multiplicity	01	01		
Туре	Reference to BswMActionList			
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time	X	VARIANT-POST-BUILD	
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00817]		
Parameter Name	BswMRuleTrueActionList		
Parent Container	BswMRule		
Description	This is a reference to the action list that shall be executed when the rule is evaluated to True		
Multiplicity	01		
Туре	Reference to BswMActionList		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

No Included Containers



10.2.49 BswMDataTypeMappingSets

SWS Item	[ECUC_BswM_00936]
Container Name	BswMDataTypeMappingSets
Parent Container	BswMConfig
Description	Collection of references to DataTypeMappingSet.
Configuration Parameters	

SWS Item	[ECUC_BswM_00937]			
Parameter Name	BswMDataTypeMappingSetRef			
Parent Container	BswMDataTypeMappingSets			
Description	Reference to DataTypeMappingS	et.		
Multiplicity	1*			
Туре	Foreign reference to DATA-TYPE	Foreign reference to DATA-TYPE-MAPPING-SET		
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.50 BswMModeControl

SWS Item	[ECUC_BswM_00802]
Container Name	BswMModeControl
Parent Container	BswMConfig
Description	This container includes all configuration sub-containers and parameters related to the mode control functionality of the BswM.
Configuration Parameters	

Included Containers		
Container Name	Multiplicity	Scope / Dependency
BswMAction	0*	Each container of this type defines an action. These actions can be part of one or several action lists.
BswMActionList	0*	Each instance of this container defines an action list that is invoked based on the BswM Rules. An action list contains a list of numbered action items to be processed. An action list can also include other action lists.





Included Containers		
Container Name	Multiplicity	Scope / Dependency
BswMRteModeRequestPort	0*	This container defines a mode request port which the BswM may utilize to send a mode request to a SW-C which is acting as a mode-manager. If this container is referenced by a BswMRte ModeRequest, the BswM shall create a corresponding PPort in its service description.
BswMSwitchPort	0*	Represents an output mode-switch port to be generated by the BswM. If BswMModeSwitchInterfaceRef is configured then a PPortPrototype is generated in the SWCD. If BswMSchMMode DeclarationGroupRef is configured then a ModeDeclaration GroupPrototype is generated in the ProvidedModeGroups of the BSWMD. If both BswMModeSwitchInterfaceRef and BswMSch MModeDeclarationGroupRef are configured then an SwcBsw SynchronizedModeGroupPrototype is also generated in the BSWMD (see Chapter 6.11 of the BSW Module Description Template SWS and EXP ModemanagementGuide)

10.2.51 BswMAction

SWS Item	[ECUC_BswM_00810]			
Container Name	BswMAction			
Parent Container	BswMModeControl	BswMModeControl		
Description	Each container of this type defines an action. These actions can be part of one or several action lists.			
Post-Build Variant Multiplicity	false			
Multiplicity Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE, VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Link time	_		
	Post-build time –			
Configuration Parameters				

Included Containers		
Container Name	Multiplicity	Scope / Dependency
BswMAvailableActions	1	Choice container including the available actions to be used in the action lists.

10.2.52 BswMAvailableActions

SWS Item	[ECUC_BswM_00826]	
Choice Container Name	BswMAvailableActions	
Parent Container	BswMAction	
Description	Choice container including the available actions to be used in the action lists.	





Container Choices		10 /0 /	
Container Name	Multiplicity	Scope / Dependency	
BswMClearEventRequest	01	This container contains a reference to a BswMEventRequestPor which will be cleared (i.e. set to CLEAR state) when this action is executed.	
BswMComMAllowCom	01	This container includes all parameters for the action to allow or to block communication for a ComM Channel. ComM_CommunicationAllowed is called when this action is configured.	
BswMComMModeLimitation	01	This container includes all parameters related to a limitation of communication mode for a ComM Channel. ComM_Limit ChannelToNoComMode is called when this action is configured.	
BswMComMModeSwitch	01	This container includes all parameters related to a switch of communication mode for a ComM User. ComM_RequestCom Mode is called when this action is configured.	
BswMCoreHaltMode	01	This container includes all parameters related to a switch of the activation state of core Halt.	
BswMDeadlineMonitoringControl	01	This container includes all parameters related to enabling and disabling of deadline monitoring for one or several PDUs in COM.	
BswMEcuMDriverInitListBswM	01	This container defines the action to trigger an EcuM driver initialization list.	
BswMEcuMGoDownHaltPoll	01	This container defines the action to trigger the EcuM_GoDown HaltPoll from BswM.	
BswMEcuMSelectShutdownTarget	01	This container defines the shutdown target.	
BswMEcuMStateSwitch	01	This container defines the action to switch a State of the ECU State Manager.	
BswMEthIfStartAllPorts	01	This container defines the action to call EthIf_StartAllPorts from BswM and thus to start all affected EthSwtPorts.	
BswMEthIfSwitchPortGroup RequestMode	01	This container includes all parameters related to requesting a mode for the EthIfSwtPortGroup.	
		The EthIf_SwitchPortGroupRequestMode API is called when this action is executed.	
BswMFrSMAllSlots	01	This container includes all parameter(s) for the action to requ an exit from Flexray KeySlotOnlyMode. FrSM_AllSlots is calle when this action is executed.	
BswMldsMBlockStateChange Request	01	This container defines the action to switch a BlockState of the IdsM.	
		Tags: atp.Status=draft	
BswMJ1939DcmStateSwitch	01	This container includes all parameters related to a switch of the J1939 Diagnostic Communication Managers network state for a J1939 node. J1939Dcm_SetState is called when this action is configured.	
BswMJ1939RmStateSwitch	01	This container includes all parameters related to a switch of the J1939 Request Managers network state for a J1939 node. J1939Rm_SetState is called when this action is configured.	
BswMLinScheduleSwitch	01	This container includes all parameters related to a switch of LIN schedule table. LinSM_ScheduleRequest is called when this action is configured.	
		The configuration for the "network" parameter can be accessed via the reference LinSMComMNetworkHandleRef contained in the parent container LinSMChannel of the container referenced by BswMLinScheduleRef.	
BswMNMControl	01	This container includes all parameters related to enabling and disabling of Network Management communication. Disabling of NM communication can be requested by DCM. Nm_Enable Communication or Nm_DisableCommunication is called when this action is configured.	





Container Choices				
Container Name	Multiplicity	Scope / Dependency		
BswMPduGroupSwitch	01	This container includes references to the PDU groups that shall be enabled and disabled.		
BswMPduRouterControl	01	This container includes all parameters related to enabling and disabling of routing of Routing Path Groups in the PDU Router. PduR_EnableRouting or PduR_DisableRouting is called when this action is configured.		
BswMRteModeRequest	01	This container defines a mode request that the BswM may send to a SW-C which is acting as a mode-manager. RTE_Write is called when this action is configured.		
BswMRteStart	01	This container defines the action to call the Rte_Start from Bsw M.		
BswMRteStop	01	This container defines the action to call the Rte_Stop from Bsw M.		
BswMRteSwitch	01	This container defines a mode switch indication that the BswM provides to the SW-C that need to be notified about the mode switch. RTE_Switch is called when this action is configured.		
BswMSchMSwitch	01	This container defines a mode switch indication that the BswM provides to the SW-C that need to be notified about the mode switch. SchM_Switch is called when this action is configured.		
BswMSdClientServiceMode Request	01	This container includes all parameters related to the selection an client service of Sd. Sd_ClientServiceSetState is called what this action is configured.		
BswMSdConsumedEventGroup ModeRequest	01	This container includes all parameters related to the selection a consumed EventGroup of Sd. Sd_ConsumedEventGroupSet State is called when this action is configured.		
BswMSdServerServiceMode Request	01	This container includes all parameters related to the selection of a server service of Sd. Sd_ServerServiceSetState is called when this action is configured.		
BswMSdServiceGroupSwitch	01	This container includes references to the SdServiceGroups that shall be enabled and disabled.		
BswMSwitchIPduMode	01	This container includes all parameters related to the selection of the transmission mode an I-PDU to be sent by COM. Com_SwitchIpduTxMode is called when this action is configured.		
BswMTimerControl	01	This container includes all parameters for the action to start or t stop a timer.		
BswMTriggerlPduSend	01	This container includes all parameters related to the triggering of an I-PDU to be sent by COM. Com_TriggerIPDUSend is called when this action is configured.		
BswMUserCallout	01	This container includes all details needed for a user defined function call.		

10.2.53 BswMClearEventRequest

SWS Item	[ECUC_BswM_01054]
Container Name	BswMClearEventRequest
Parent Container	BswMAvailableActions
Description	This container contains a reference to a BswMEventRequestPort which will be cleared (i.e. set to CLEAR state) when this action is executed.
Configuration Parameters	



SWS Item	[ECUC_BswM_01055]			
Parameter Name	BswMClearEventRequestPort	Ref		
Parent Container	BswMClearEventRequest			
Description	This parameter references the	BswMEvent	RequestPort which will be cleared.	
Multiplicity	1	1		
Туре	Reference to BswMEventRequestPort			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

Nο	Inc	ludec	l Conta	iners

10.2.54 BswMComMAllowCom

SWS Item	[ECUC_BswM_00909]
Container Name	BswMComMAllowCom
Parent Container	BswMAvailableActions
Description	This container includes all parameters for the action to allow or to block communication for a ComM Channel. ComM_CommunicationAllowed is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00918]			
Parameter Name	BswMComAllowed			
Parent Container	BswMComMAllowCom			
Description	The parameter BswMComMAllowChannelRef refers to a channel which will allow or block communication using the function ComM_CommunicationAllowed(). This parameter corresponds to the parameter "Allowed" of the function ComM_			
	CommunicationAllowed().	CommunicationAllowed().		
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value	-			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00912]
Parameter Name	BswMComMAllowChannelRef
Parent Container	BswMComMAllowCom





Description	This is a reference to the Coblocked.	This is a reference to the ComM Channel for which communication shall be allowed or blocked.		
	This reference corresponds CommunicationAllowed().	This reference corresponds to the parameter "Channel" of the function ComM_CommunicationAllowed().		
Multiplicity	1	1		
Туре	Symbolic name reference to	Symbolic name reference to ComMChannel		
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.55 BswMComMModeLimitation

SWS Item	[ECUC_BswM_00908]
Container Name	BswMComMModeLimitation
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to a limitation of communication mode for a ComM Channel. ComM_LimitChannelToNoComMode is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00910]		
Parameter Name	BswMComMLimitMode		
Parent Container	BswMComMModeLimitation		
Description	The function ComM_LimitChannelToNoComMode() takes in this boolean parameter to limit the channel's com mode to no-com mode. This parameter corresponds to the parameter "Status" of the function ComM_Limit ChannelToNoComMode.		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value	-		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time –		
Scope / Dependency	scope: local	-	

SWS Item	[ECUC_BswM_00911]
Parameter Name	BswMComMLimitChannelRef
Parent Container	BswMComMModeLimitation





Description	This is a reference to the ComM channel for which the communication mode should be limited.		
	This reference corresponds to the parameter "Channel" of the function ComM_Limit ChannelToNoComMode.		
Multiplicity	1		
Туре	Symbolic name reference to ComMChannel		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

No Included Containers

10.2.56 BswMComMModeSwitch

SWS Item	[ECUC_BswM_00831]
Container Name	BswMComMModeSwitch
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to a switch of communication mode for a ComM User. ComM_RequestComMode is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00840]			
Parameter Name	BswMComMRequestedMode			
Parent Container	BswMComMModeSwitch			
Description	This parameter specifies if the requ	This parameter specifies if the requested communication mode.		
	This parameter corresponds to the parameter "ComMode" of the function ComM_ RequestComMode.			
Multiplicity	1			
Туре	EcucEnumerationParamDef			
Range	BSWM_COMM_FULL_ COMMUNICATION	-		
	BSWM_COMM_NO_ COMMUNICATION	-		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00841]
Parameter Name	BswMComMUserRef
Parent Container	BswMComMModeSwitch





Description	This is a reference to the ComM User that is associated to the Communication channel for which the communication mode should be requested. This reference corresponds to the parameter "User" of the function ComM_Request ComMode.		
Multiplicity	1		
Туре	Symbolic name reference to ComMUser		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

No Included Containers

10.2.57 BswMCoreHaltMode

SWS Item	[ECUC_BswM_00970]
Container Name	BswMCoreHaltMode
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to a switch of the activation state of core Halt.
Configuration Parameters	

SWS Item	[ECUC_BswM_00972]		
Parameter Name	BswMCoreHaltActivationState		
Parent Container	BswMCoreHaltMode		
Description	Different possibilities are offered depending on the OS implementation and the CPU HW. The HALT modes addressed by this parameter are defined as names (strings) in the OS implementation. Different implementation may implement different HALT modes and subsequently different names.		
Multiplicity	1		
Туре	EcucStringParamDef		
Default value	_		
Regular Expression	-		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	Х	All Variants
	Link time	-	
	Post-build time	_	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00971]
Parameter Name	BswMTargetCoreRef
Parent Container	BswMCoreHaltMode
Description	This is a reference to the core on which the Core Halt process must be influenced.
Multiplicity	1





Туре	Reference to EcucCoreDefinition		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local	-	

No Included Containers	

10.2.58 BswMDeadlineMonitoringControl

SWS Item	[ECUC_BswM_00830]
Container Name	BswMDeadlineMonitoringControl
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to enabling and disabling of deadline monitoring for one or several PDUs in COM.
Configuration Parameters	

SWS Item	[ECUC_BswM_00852]		
Parameter Name	BswMDisabledDMPduGroupRef		
Parent Container	BswMDeadlineMonitoringControl		
Description	This is a reference to a PDU Group for which the Deadline Monitoring should be disabled. This reference corresponds to the parameter "IpduGroupId" of the function Com_DisableReceptionDM.		
Multiplicity	0*		
Туре	Symbolic name reference to ComlPduGroup		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME		
	Post-build time X VARIANT-POST-BUILD		
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00851]
Parameter Name	BswMEnabledDMPduGroupRef
Parent Container	BswMDeadlineMonitoringControl
Description	This is a reference to a PDU Group for which the Deadline Monitoring should be enabled. This reference corresponds to the parameter "IpduGroupId" of the function Com_EnableReceptionDM.
Multiplicity	0*
Туре	Symbolic name reference to ComlPduGroup





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Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

No Included Containers

[SWS_BswM_CONSTR_00003] [The BswM shall reject configurations where a BswMDeadlineMonitoringControl container has a BswMDisabledDMPduGroupRef and a BswMEnabledDMPduGroupRef which reference the same PDU Group.|()

[SWS_BswM_00274] [When a BswMDeadlineMonitoringControl action is executed, the BswM shall call Com_EnableReceptionDM for each BswMEnabledDMP-duGroupRef, and call Com_DisableReceptionDM for each BswMDisabledDMP-duGroupRef. The ordering of these calls to Com is undefined.]

Note: If a strict ordering of the calls to <code>Com_EnableReceptionDM</code>, or <code>Com_DisableReceptionDM</code> is required, then this can be achieved by configuring individual actions (<code>BswMDeadlineMonitoringControl</code>, each with just a single <code>BswM*PduGroupRef</code>) within an ordered action list.

10.2.59 BswMEcuMDriverInitListBswM

SWS Item	[ECUC_BswM_01064]
Container Name	BswMEcuMDriverInitListBswM
Parent Container	BswMAvailableActions
Description	This container defines the action to trigger an EcuM driver initialization list.
Configuration Parameters	

SWS Item	[ECUC_BswM_01065]		
Parameter Name	BswMEcuMDriverInitListBswMRef		
Parent Container	BswMEcuMDriverInitListBswM		
Description	This is a reference to the EcuM EcuMDriverInitListBswM container which represents the driver init list to be triggered.		
Multiplicity	1		
Туре	Reference to EcuMDriverInitListBswM		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		





	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	-	
Scope / Dependency	scope: local		

No Included Containers	

The EcuM (flex) can be configured with driver initialization lists (EcuMDriverInitListB-swM) which may then be called by the BswM.

[SWS_BswM_00269] [When a BswMEcuMDriverInitListBswM action is executed, the BswM shall call the EcuM_AL_DriverInitBswM_<EcuMDriverInitListB-swM.shortName>(void) function which is provided by the EcuM.] (SRS_-ModeMgm_09180)

10.2.60 BswMEcuMGoDownHaltPoll

SWS Item	[ECUC_BswM_00963]
Container Name	BswMEcuMGoDownHaltPoll
Parent Container	BswMAvailableActions
Description	This container defines the action to trigger the EcuM_GoDownHaltPoll from BswM.
Configuration Parameters	

SWS Item	[ECUC_BswM_00964]			
Parameter Name	BswMEcuMUserldRef			
Parent Container	BswMEcuMGoDownHaltPoll			
Description	This is a reference to a EcuM Userl	d.		
Multiplicity	1	1		
Туре	Symbolic name reference to EcuMFlexUserConfig			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers



10.2.61 BswMEcuMSelectShutdownTarget

SWS Item	[ECUC_BswM_00961]
Container Name	BswMEcuMSelectShutdownTarget
Parent Container	BswMAvailableActions
Description	This container defines the shutdown target.
Configuration Parameters	

SWS Item	[ECUC_BswM_00993]		
Parameter Name	BswMEcuMShutdownTarget		
Parent Container	BswMEcuMSelectShutdownTarget		
Description	This parameter contains the shutdo	wn target	that the BswM selects at the EcuM.
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	BSWM_ECUM_SHUTDOWN TARGET_OFF		
	BSWM_ECUM_SHUTDOWN_ TARGET_RESET	In case the configuration parameter BswMEcu MShutdownTarget is set to BSWM_ECUM_ SHUTDOWN_TARGET_RESET the configuration parameter BswMEcuMResetMode Ref shall exist and contain a valid reference to a EcuM reset mode.	
	BSWM_ECUM_SHUTDOWN_ TARGET_SLEEP	In case the configuration parameter BswMEcu MShutdownTarget is set to BSWM_ECUM_ SHUTDOWN_TARGET_SLEEP the configuration parameter BswMEcuMSleepModeRef shall exist and contain a valid reference to a EcuM sleep mode.	
Post-Build Variant Value	false	•	
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00994]			
Parameter Name	BswMEcuMResetModeRef			
Parent Container	BswMEcuMSelectShutdownTarget			
Description	This is a reference to a reset mode) .		
Multiplicity	01			
Туре	Symbolic name reference to EcuMResetMode			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time –			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		





Scope / Dependency

SWS Item	[ECUC_BswM_00962]			
Parameter Name	BswMEcuMSleepModeRef			
Parent Container	BswMEcuMSelectShutdownTarg	jet		
Description	This is a reference to a sleep mo	ode.		
Multiplicity	01	01		
Туре	Symbolic name reference to EcuMSleepMode			
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.62 BswMEcuMStateSwitch

SWS Item	[ECUC_BswM_01045]
Container Name	BswMEcuMStateSwitch
Parent Container	BswMAvailableActions
Description	This container defines the action to switch a State of the ECU State Manager.
Configuration Parameters	

SWS Item	[ECUC_BswM_01044]			
Parameter Name	BswMEcuMState			
Parent Container	BswMEcuMStateSwitch	BswMEcuMStateSwitch		
Description	This parameter corresponds to the parameter "State" of the function EcuM_ SetState ().			
Multiplicity	1			
Туре	EcucEnumerationParamDef			
Range	BSWM_ECUM_STATE_POST_ RUN	-		
	BSWM_ECUM_STATE_RUN	_		
	BSWM_ECUM_STATE_ SHUTDOWN	-		
	BSWM_ECUM_STATE_SLEEP	-		
	BSWM_ECUM_STATE_ STARTUP	-		
Post-Build Variant Value	false			





Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local	-	

10.2.63 BswMEthIfStartAllPorts

SWS Item	[ECUC_BswM_01088]
Container Name	BswMEthIfStartAllPorts
Parent Container	BswMAvailableActions
Description	This container defines the action to call EthIf_StartAllPorts from BswM and thus to start all affected EthSwtPorts.
Configuration Parameters	

No Included Containers	
No Included Containers	

[SWS_BswM_00286] [If the action <code>BswMEthIfStartAllPorts</code> is configured, the function <code>EthIf_StartAllPorts</code> (void) shall be called by the BswM when the action is executed.]()

10.2.64 BswMEthIfSwitchPortGroupRequestMode

SWS Item	[ECUC_BswM_01068]
Container Name	BswMEthIfSwitchPortGroupRequestMode
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to requesting a mode for the EthlfSwt PortGroup.
	The EthIf_SwitchPortGroupRequestMode API is called when this action is executed.
Configuration Parameters	

SWS Item	[ECUC_BswM_01070]				
Parameter Name	BswMEthTrcvMode	BswMEthTrcvMode			
Parent Container	BswMEthIfSwitchPortGroupRequestMode				
Description	This parameter contains the mode which will be requested.				
Multiplicity	1				
Туре	EcucEnumerationParamDef				
Range	BSWM_ETH_MODE_ACTIVE enable the port group				
	BSWM_ETH_MODE_ACTIVE_ WITH_WAKEUP_REQUEST	Enable the port group and request to trigger a wake-up on the network.			
	BSWM_ETH_MODE_DOWN	disable the port group			





Post-Build Variant Value	true		
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD		
	Post-build time	_	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_01069]				
Parameter Name	BswMEthIfSwitchPortGroupRef	BswMEthIfSwitchPortGroupRef			
Parent Container	BswMEthIfSwitchPortGroupRequestMode				
Description	This is a reference to the Ethernet Interface Switch Port Group which will receive the request.				
Multiplicity	1				
Туре	Symbolic name reference to EthIfSwitchPortGroup				
Post-Build Variant Value	true				
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE				
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD				
	Post-build time –				
Scope / Dependency	scope: local				

Nο	Incl	uded	Conta	iners

10.2.65 BswMFrSMAllSlots

SWS Item	[ECUC_BswM_01037]
Container Name	BswMFrSMAllSlots
Parent Container	BswMAvailableActions
Description	This container includes all parameter(s) for the action to request an exit from Flexray KeySlotOnlyMode. FrSM_AllSlots is called when this action is executed.
Configuration Parameters	

SWS Item	[ECUC_BswM_01038]			
Parameter Name	BswMFrSMAllSlotsNetworkH	HandleRef		
Parent Container	BswMFrSMAllSlots			
Description	This references the FlexRay cluster. The reference corresponds to the parameter "NetworkHandle" of the function FrSM_AllSlots.			
Multiplicity	1			
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers



10.2.66 BswMJ1939DcmStateSwitch

SWS Item	[ECUC_BswM_01032]
Container Name	BswMJ1939DcmStateSwitch
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to a switch of the J1939 Diagnostic Communication Managers network state for a J1939 node. J1939Dcm_SetState is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_01035]	[ECUC_BswM_01035]		
Parameter Name	BswMJ1939DcmRequestedState)		
Parent Container	BswMJ1939DcmStateSwitch			
Description	·	This parameter describes the communication state of the J1939 Diagnostic Communication Manager and corresponds to the parameter "newState" of the function J1939Dcm_SetState.		
Multiplicity	1	1		
Туре	EcucEnumerationParamDef	EcucEnumerationParamDef		
Range	BSWM_J1939DCM_STATE_ OFFLINE	-		
	BSWM_J1939DCM_STATE_ ONLINE	E		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	-		
Scope / Dependency	scope: local	•		

SWS Item	[ECUC_BswM_01033]	[ECUC_BswM_01033]		
Parameter Name	BswMJ1939DcmChannelRef			
Parent Container	BswMJ1939DcmStateSwitch			
Description	This reference points to the unique channel defined by the ComMChannel and provides access to the unique channel index value in ComMChannelld.			
	This reference corresponds to the parameter "channel" of the function J1939Dcm_Set State.			
Multiplicity	1			
Туре	Symbolic name reference to Com	Symbolic name reference to ComMChannel		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01034]
Parameter Name	BswMJ1939DcmNodeRef
Parent Container	BswMJ1939DcmStateSwitch
Description	This reference points to a J1939NmNode and provides access to the unique J1939Nm Nodeld. This reference corresponds to the parameter "node" of the function J1939Dcm_SetState.





Multiplicity	1		
Туре	Symbolic name reference to J1939NmNode		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

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No	Inc	uded	Cor	ntainers

10.2.67 BswMJ1939RmStateSwitch

SWS Item	[ECUC_BswM_00998]
Container Name	BswMJ1939RmStateSwitch
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to a switch of the J1939 Request Managers network state for a J1939 node. J1939Rm_SetState is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_01002]				
Parameter Name	BswMJ1939RmRequestedState	BswMJ1939RmRequestedState			
Parent Container	BswMJ1939RmStateSwitch				
Description	This parameter describes the communication state of the J1939 Request Manager and corresponds to the parameter "new state" of the function J1939Rm_SetState.				
Multiplicity	1				
Туре	EcucEnumerationParamDef				
Range	BSWM_J1939RM_STATE_ OFFLINE	_			
	BSWM_J1939RM_STATE_ ONLINE	_			
Post-Build Variant Value	false				
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD		
	Post-build time	_			
Scope / Dependency	scope: local				

SWS Item	[ECUC_BswM_01000]
Parameter Name	BswMJ1939RmChannelRef
Parent Container	BswMJ1939RmStateSwitch
Description This reference points to the unique channel defined by the ComMCha provides access to the unique channel index value in ComMChannello	
	This reference corresponds to the parameter "channel" of the function J1939Rm_Set State.
Multiplicity	1





Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01001]			
Parameter Name	BswMJ1939RmNodeRef			
Parent Container	BswMJ1939RmStateSwitch			
Description	This reference points to a J1939NmNode and provides access to the unique J1939Nm Nodeld.			
	State.	This reference corresponds to the parameter "node" of the function J1939Rm_Set State.		
Multiplicity	1	1		
Туре	Symbolic name reference to J1939I	Symbolic name reference to J1939NmNode		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers

10.2.68 BswMLinScheduleSwitch

SWS Item	[ECUC_BswM_00827]
Container Name	BswMLinScheduleSwitch
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to a switch of LIN schedule table. Lin SM_ScheduleRequest is called when this action is configured.
	The configuration for the "network" parameter can be accessed via the reference Lin SMComMNetworkHandleRef contained in the parent container LinSMChannel of the container referenced by BswMLinScheduleRef.
Configuration Parameters	

SWS Item	[ECUC_BswM_00842]		
Parameter Name	BswMLinScheduleRef		
Parent Container	BswMLinScheduleSwitch		
Description	This is a reference to the LIN schedule table that the LIN SM shall change to.		
	This reference corresponds to the parameter "schedule" of the function LinSM_ ScheduleRequest.		
Multiplicity	1		
Туре	Symbolic name reference to LinSMSchedule		





Post-Build Variant Value	true			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

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10.2.69 BswMNMControl

SWS Item	[ECUC_BswM_00837]
Container Name	BswMNMControl
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to enabling and disabling of Network Management communication. Disabling of NM communication can be requested by DCM. Nm_EnableCommunication or Nm_DisableCommunication is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00838]				
Parameter Name	BswMNMAction				
Parent Container	BswMNMControl				
Description	This parameter specifies if the communication of the corresponding NM channel should be enabled or disabled.				
Multiplicity	1	1			
Туре	EcucEnumerationParamDef				
Range	BSWM_NM_DISABLE	-			
	BSWM_NM_ENABLE	-			
Post-Build Variant Value	false				
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD		
	Post-build time	_			
Scope / Dependency	scope: local				

SWS Item	[ECUC_BswM_00999]			
Parameter Name	BswMComMNetworkHandleRef			
Parent Container	BswMNMControl			
Description	This reference points to the unique channel defined by the ComMChannel and provides access to the unique channel index value in ComMChannelld. This reference corresponds to the parameter "NetworkHandle" of the function Nm_EnableCommunication and Nm_DisableCommunication.			
Multiplicity	1			
Туре	Symbolic name reference to ComMChannel			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			





	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

No Included Containers	
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10.2.70 BswMPduGroupSwitch

SWS Item	[ECUC_BswM_00828]
Container Name	BswMPduGroupSwitch
Parent Container	BswMAvailableActions
Description	This container includes references to the PDU groups that shall be enabled and disabled.
Configuration Parameters	

SWS Item	[ECUC_BswM_00913]		
Parameter Name	BswMPduGroupSwitchReinit		
Parent Container	BswMPduGroupSwitch		
Description	This parameter defines if the data of the I-PDU, the shadow buffers of included signal groups, etc. are reinitialized when a PDU Group is started. This parameter corresponds to the parameter "initialize" of the function Com_IpduGroupStart.		
Multiplicity	01		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00850]			
Parameter Name	BswMDisabledPduGroupRef	BswMDisabledPduGroupRef		
Parent Container	BswMPduGroupSwitch			
Description	This is a reference to a PDU Group that should be disabled. This reference corresponds to the parameter "lpduGroupId" of the function Com_lpduGroupStop.			
Multiplicity	0*			
Туре	Symbolic name reference to ComlPduGroup			
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME	





	Post-build time	Х	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00849]			
Parameter Name	BswMEnabledPduGroupRef			
Parent Container	BswMPduGroupSwitch	BswMPduGroupSwitch		
Description	This is a reference to a PDU Group that should be enabled. This reference corresponds to the parameter "IpduGroupId" of the function Com_IpduGroupStart.			
Multiplicity	0*			
Туре	Symbolic name reference to ComlPduGroup			
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

No Included Containers

[SWS_BswM_CONSTR_00004] [The BswM shall reject configurations where a BswMPduGroupSwitch container has a BswMDisabledPduGroupRef and a BswMEnabledPduGroupRef which reference the same PDU Group.]()

[SWS_BswM_00273] [When a BswMPduGroupSwitch action is executed, the BswM shall call Com_IpduGroupStart for each BswMEnabledPduGroupRef, and call Com_IpduGroupStop for each BswMDisabledPduGroupRef. The ordering of these calls to Com is undefined.]

Note: If a strict ordering of the calls to <code>Com_IpduGroupStart</code>, or <code>Com_IpduGroup-Stop</code> is required, then this can be achieved by configuring individual actions (<code>BswM-PduGroupSwitch</code>, each with just a single <code>BswM*PduGroupRef</code>) within an ordered action list.

10.2.71 BswMPduRouterControl

SWS Item	[ECUC_BswM_00853]
Container Name	BswMPduRouterControl
Parent Container	BswMAvailableActions





Description	This container includes all parameters related to enabling and disabling of routing of Routing Path Groups in the PDU Router. PduR_EnableRouting or PduR_Disable Routing is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00854]			
Parameter Name	BswMPduRouterAction	BswMPduRouterAction		
Parent Container	BswMPduRouterControl			
Description	This parameter specifies if the rout disabled.	This parameter specifies if the routing of the corresponding PDU should be enabled or disabled.		
Multiplicity	1	1		
Туре	EcucEnumerationParamDef			
Range	BSWM_PDUR_DISABLE	-		
	BSWM_PDUR_ENABLE	_		
Post-Build Variant Value	true	•		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01036]		
Parameter Name	BswMPduRouterDisableInitBuffer		
Parent Container	BswMPduRouterControl		
Description	When BswPduRouterAction is set to BSWM_PDUR_DISABLE and this parameter is set to true, then the call to PduR_DisableRouting will be invoked with parameter "initialize" set to true, otherwise false.		
Multiplicity	01		
Туре	EcucBooleanParamDef		
Default value	-		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	X	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00855]
Parameter Name	BswMPduRoutingPathGroupRef
Parent Container	BswMPduRouterControl
Description	This is a reference to the PDU Routing Path Group for which the routing in the PDU Router should be enabled or disabled.
	This reference corresponds to the parameter "id" of the function PduR_EnableRouting and PduR_DisableRouting.
Multiplicity	1*
Туре	Symbolic name reference to PduRRoutingPathGroup
Post-Build Variant Multiplicity	true





Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

No Included Containers

10.2.72 BswMRteModeRequest

SWS Item	[ECUC_BswM_01021]
Container Name	BswMRteModeRequest
Parent Container	BswMAvailableActions
Description	This container defines a mode request that the BswM may send to a SW-C which is acting as a mode-manager. RTE_Write is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_01024]		
Parameter Name	BswMRequestedModeRef		
Parent Container	BswMRteModeRequest		
Description	This is a foreign reference to the Mo	ode Decla	aration used for the mode request
Multiplicity	1	1	
Туре	Foreign reference to MODE-DECLARATION		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		·

SWS Item	[ECUC_BswM_01023]		
Parameter Name	BswMRteModeRequestPortRef	BswMRteModeRequestPortRef	
Parent Container	BswMRteModeRequest		
Description	This is a reference to a BswMRtel	ModeReq	uestPort.
Multiplicity	1	1	
Туре	Reference to BswMRteModeRequestPort		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local	·	

No Included Containers



10.2.73 BswMRteStart

SWS Item	[ECUC_BswM_01073]
Container Name	BswMRteStart
Parent Container	BswMAvailableActions
Description	This container defines the action to start the Rte from BswM.
Configuration Parameters	

No Included Containers

[SWS_BswM_00271] [If the action BswMRteStart is configured, the function Rte_-Start (void) shall be called by the BswM when the action is executed.] (SRS_-ModeMgm_09178)

10.2.74 BswMRteStop

SWS Item	[ECUC_BswM_01074]	
Container Name	BswMRteStop	
Parent Container	BswMAvailableActions	
Description	This container defines the action to stop the Rte from BswM	
Configuration Parameters		

No Included Containers

[SWS_BswM_00272] [If the action <code>BswMRteStop</code> is configured, the function <code>Rte_-Stop(void)</code> shall be called by the BswM when the action is executed.] (SRS_-ModeMgm_09178)

10.2.75 BswMRteSwitch

SWS Item	[ECUC_BswM_00803]
Container Name	BswMRteSwitch
Parent Container	BswMAvailableActions
Description	This container defines a mode switch indication that the BswM provides to the SW-C that need to be notified about the mode switch. RTE_Switch is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00952]
Parameter Name	BswMRteSwitchPortRef
Parent Container	BswMRteSwitch
Description	This is a reference to the BswMSwitchPort.
Multiplicity	1

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Туре	Reference to BswMSwitchPort		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00896]		
Parameter Name	BswMSwitchedMode		
Parent Container	BswMRteSwitch		
Description	This parameter contains the integer value that corresponds to a certain mode in a Mode Declaration Group.		
Multiplicity	1		
Туре	Foreign reference to MODE-DECLARATION		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

No Included	Containers	

10.2.76 BswMSchMSwitch

SWS Item	[ECUC_BswM_00899]
Container Name	BswMSchMSwitch
Parent Container	BswMAvailableActions
Description	This container defines a mode switch indication that the BswM provides to the SW-C that need to be notified about the mode switch. SchM_Switch is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00901]			
Parameter Name	BswMSchMSwitchedMode			
Parent Container	BswMSchMSwitch			
Description	This parameter contains the integer value that corresponds to a certain mode in a Mode Declaration Group.			
Multiplicity	1			
Туре	Foreign reference to MODE-DECLARATION			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time –			
Scope / Dependency	scope: local			



SWS Item	[ECUC_BswM_01080]			
Parameter Name	BswMSchMSwitchPortRef			
Parent Container	BswMSchMSwitch			
Description	This is a reference to the BswMS	witchPort.		
Multiplicity	1	1		
Туре	Reference to BswMSwitchPort			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No Included Containers

10.2.77 BswMSdClientServiceModeRequest

SWS Item	[ECUC_BswM_00974]
Container Name	BswMSdClientServiceModeRequest
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to the selection of an client service of Sd. Sd_ClientServiceSetState is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_01016]		
Parameter Name	BswMSdClientServiceState		
Parent Container	BswMSdClientServiceModeReques	t	
Description	This parameter specifies if the corresponding client service shall be released or requested.		
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	BSWM_SD_CLIENT_SERVICE_ RELEASED	Client service shall be released	
	BSWM_SD_CLIENT_SERVICE_ REQUESTED	Client service shall be requested	
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	-	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_01009]	
Parameter Name	BswMSdClientMethodsRef	
Parent Container	BswMSdClientServiceModeRequest	
Description	This is a reference to a client service in the Sd module.	





Multiplicity	1			
Туре	Symbolic name reference to SdClientService			
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

No	Inc	lud	ed	Con	tai	iners
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10.2.78 BswMSdConsumedEventGroupModeRequest

SWS Item	[ECUC_BswM_01004]
Container Name	BswMSdConsumedEventGroupModeRequest
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to the selection of a consumed Event Group of Sd. Sd_ConsumedEventGroupSetState is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_01017]				
Parameter Name	BswMSdConsumedEventGroupSta	BswMSdConsumedEventGroupState			
Parent Container	BswMSdConsumedEventGroupMo	deReque	st		
Description	This parameter specifies if the corr or requested.	This parameter specifies if the corresponding consumed event group shall be released or requested.			
Multiplicity	1				
Туре	EcucEnumerationParamDef				
Range	BSWM_SD_CONSUMED_ EVENTGROUP_RELEASED	Event group shall be released.			
	BSWM_SD_CONSUMED_ EVENTGROUP_REQUESTED	Event group shall be requested.			
Post-Build Variant Value	false	•			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD		
	Post-build time	_			
Scope / Dependency	scope: local	-			

SWS Item	[ECUC_BswM_01010]
Parameter Name	BswMSdConsumedEventGroupRef
Parent Container	BswMSdConsumedEventGroupModeRequest
Description	This is a reference to an eventGroup that is defined within a client service in the Sd module.
Multiplicity	1
Туре	Symbolic name reference to SdConsumedEventGroup





Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	-	
Scope / Dependency	scope: local		

No Included Containers

10.2.79 BswMSdServerServiceModeRequest

SWS Item	[ECUC_BswM_01005]
Container Name	BswMSdServerServiceModeRequest
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to the selection of a server service of Sd. Sd_ServerServiceSetState is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_01015]		
Parameter Name	BswMSdServerServiceState		
Parent Container	BswMSdServerServiceModeReques	st	
Description	This parameter specifies if the corre	sponding	server service shall be down or available.
Multiplicity	1		
Туре	EcucEnumerationParamDef		
Range	BSWM_SD_SERVER_SERVICE_ AVAILABLE	Server service shall be available.	
	BSWM_SD_SERVER_SERVICE_ DOWN	Server	service shall be down.
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	_	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_01007]			
Parameter Name	BswMSdServerMethodsRef			
Parent Container	BswMSdServerServiceModeReque	st		
Description	This is a reference to a server servi	ce in the	Sd module.	
Multiplicity	1	1		
Туре	Symbolic name reference to SdServerService			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		





Scope / Dependency	scope: local
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No Included Containers

10.2.80 BswMSdServiceGroupSwitch

SWS Item	[ECUC_BswM_01077]
Container Name	BswMSdServiceGroupSwitch
Parent Container	BswMAvailableActions
Description	This container includes references to the SdServiceGroups that shall be enabled and disabled.
Configuration Parameters	

SWS Item	[ECUC_BswM_01078]		
Parameter Name	BswMDisabledSdServiceGroupRef		
Parent Container	BswMSdServiceGroupSwitch		
Description	This is a reference to a SdServiceGroup that should be disabled. This reference corresponds to the parameter "ServiceGroupId" of the function Sd_ServiceGroupStop.		
Multiplicity	0*		
Туре	Symbolic name reference to SdServiceGroup		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_01079]			
Parameter Name	BswMEnabledSdServiceGroupRef	BswMEnabledSdServiceGroupRef		
Parent Container	BswMSdServiceGroupSwitch			
Description	This is a reference to a SdServiceGroup that should be enabled. This reference corresponds to the parameter "ServiceGroupId" of the function Sd_ServiceGroupStart.			
Multiplicity	0*	0*		
Туре	Symbolic name reference to SdServiceGroup			
Post-Build Variant Multiplicity	true			
Post-Build Variant Value	true			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	X	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	





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Scope / Dependency	scope: local
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No Included Containers

[SWS_BswM_CONSTR_00005] [The BswM shall reject configurations where a BswMSdServiceGroupSwitch container has a BswMDisabledSdServiceGroupRef and a BswMEnabledSdServiceGroupRef which reference the same Sd-ServiceGroup.]

[SWS_BswM_00280] [When a BswMSdServiceGroupSwitch action is executed, the BswM shall call Sd_ServiceGroupStart for each BswMEnabledSdServiceGroupRef, and call Sd_ServiceGroupStop for each BswMDisabledSdServiceGroupRef. The ordering of these calls to Sd is undefined.

Note: If a strict ordering of the calls to Sd_ServiceGroupStart or Sd_ServiceGroupStop is required, then this can be achieved by configuring individual actions (BswMSdServiceGroupSwitch, each with just a single BswM*ServiceGroupRef) within an ordered action list. | ()

10.2.81 BswMSwitchIPduMode

SWS Item	[ECUC_BswM_00958]
Container Name	BswMSwitchIPduMode
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to the selection of the transmission mode an I-PDU to be sent by COM. Com_SwitchIpduTxMode is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00960]	[ECUC_BswM_00960]		
Parameter Name	BswMSwitchIPduModeValue			
Parent Container	BswMSwitchIPduMode			
Description	This parameter defines which tra	nsmission	mode shall be selected during this call.	
	This parameter corresponds to the TxMode.	This parameter corresponds to the parameter "Mode" of the function Com_Switchlpdu TxMode.		
Multiplicity	1			
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value	-	-		
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME	
	Post-build time	Х	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			



SWS Item	[ECUC_BswM_00959]	[ECUC_BswM_00959]		
Parameter Name	BswMSwitchIPduModeRef			
Parent Container	BswMSwitchIPduMode			
Description	This is a reference to an I-PD	U for which th	e transmission mode shall be set.	
	This reference corresponds to TxMode.	This reference corresponds to the parameter "Pduld" of the function Com_Switchlpdu TxMode.		
Multiplicity	1	1		
Туре	Symbolic name reference to ComIPdu			
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME	
	Post-build time	X	VARIANT-POST-BUILD	
Scope / Dependency	scope: local			

No I	ncl	luded	Containers	
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10.2.82 BswMTimerControl

SWS Item	[ECUC_BswM_01059]
Container Name	BswMTimerControl
Parent Container	BswMAvailableActions
Description	This container includes all parameters for the action to start or to stop a timer.
Configuration Parameters	

SWS Item	[ECUC_BswM_01060]			
Parameter Name	BswMTimerAction			
Parent Container	BswMTimerControl			
Description	Specify the action for the timer. The	timer ca	n be started or stopped.	
Multiplicity	1	1		
Туре	EcucEnumerationParamDef			
Range	BSWM_TIMER_START	_		
	BSWM_TIMER_STOP	_		
Default value	BSWM_TIMER_START			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01061]
Parameter Name	BswMTimerValue
Parent Container	BswMTimerControl
Description	Specify the timer value (in seconds) that is used when the timer is started.
Multiplicity	01





Туре	EcucFloatParamDef		
Range]0 INF[
Default value	_		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time	-	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_01062]			
Parameter Name	BswMTimerRef	BswMTimerRef		
Parent Container	BswMTimerControl			
Description	Specify the Timer for which the	Specify the Timer for which the timer action shall be executed.		
Multiplicity	1	1		
Туре	Reference to BswMTimer	Reference to BswMTimer		
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	-		
Scope / Dependency	scope: local			

No Included Containers

10.2.83 BswMTriggerlPduSend

SWS Item	[ECUC_BswM_00906]
Container Name	BswMTriggerIPduSend
Parent Container	BswMAvailableActions
Description	This container includes all parameters related to the triggering of an I-PDU to be sent by COM. Com_TriggerIPDUSend is called when this action is configured.
Configuration Parameters	

SWS Item	[ECUC_BswM_00907]		
Parameter Name	BswMTriggeredIPduRef		
Parent Container	BswMTriggerIPduSend		
Description	This is a reference to an I-PDU that should be triggered for transmission. This reference corresponds to the parameter "Pduld" of the function Com_Trigger IPDUSend.		
Multiplicity	1*		
Туре	Symbolic name reference to ComlPdu		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	Χ	VARIANT-PRE-COMPILE





	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE
	Link time	Х	VARIANT-LINK-TIME
	Post-build time	Х	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

No Included Containers	
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10.2.84 BswMUserCallout

SWS Item	[ECUC_BswM_00834]
Container Name	BswMUserCallout
Parent Container	BswMAvailableActions
Description	This container includes all details needed for a user defined function call.
Configuration Parameters	

SWS Item	[ECUC_BswM_00843]	[ECUC_BswM_00843]	
Parameter Name	BswMUserCalloutFunction		
Parent Container	BswMUserCallout		
Description	This parameter specifies the complete function call including all parameters. The parameters are specified during configuration time, and cannot be changed during run time. Any return values passed by the callout will be ignored.		
	Example usage can be: Actions to initialize other BSW modules Action to call NvM_ReadAll() Action to call NvM_WriteAll()		
Multiplicity	1	1	
Туре	EcucStringParamDef		
Default value	-		
Regular Expression	-		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	-	
	Post-build time	_	
Scope / Dependency	scope: local		

No Included Containers	

10.2.85 BswMActionList

SWS Item	[ECUC_BswM_00809]
Container Name	BswMActionList
Parent Container	BswMModeControl







Description	Each instance of this container defines an action list that is invoked based on the BswM Rules. An action list contains a list of numbered action items to be processed. An action list can also include other action lists.		
Post-Build Variant Multiplicity	true		
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME		
	Post-build time X VARIANT-POST-BUILD		
Configuration Parameters			

SWS Item	[ECUC_BswM_00894]				
Parameter Name	BswMActionListExecution	BswMActionListExecution			
Parent Container	BswMActionList				
Description	rule is evaluated or only when the r	This parameter controls if the corresponding action list shall be executed every time the rule is evaluated or only when the result of the evaluation changes. This parameter does not have an effect when this action list is executed within another action list.			
Multiplicity	1	1			
Туре	EcucEnumerationParamDef				
Range	BSWM_CONDITION	CONDITION Action list shall be executed every time the rule is evaluated.			
	BSWM_TRIGGER	Action list shall be executed every time the result of the evaluation changes.			
Post-Build Variant Value	false	•			
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD		
	Post-build time	_			
Scope / Dependency	scope: local				

SWS Item	[ECUC_BswM_01076]			
Parameter Name	BswMActionListPriority	BswMActionListPriority		
Parent Container	BswMActionList			
Description	This controls the order of execution, in the case when multiple action lists are executed during a single mode control cycle. Highest priority action list will be executed first. Zero (0) is lowest priority, and 255 is highest priority.			
Multiplicity	01			
Туре	EcucIntegerParamDef			
Range	0 255			
Default value	0			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time	Х	VARIANT-LINK-TIME, VARIANT-POST-BUILD	
	Post-build time	_		
Scope / Dependency	scope: local			

Included Containers		
Container Name	Multiplicity	Scope / Dependency
BswMActionListItem	1*	This container defines an item in an action list.



10.2.86 BswMActionListItem

SWS Item	[ECUC_BswM_00823]			
Container Name	BswMActionListItem	BswMActionListItem		
Parent Container	BswMActionList			
Description	This container defines an item in an	action lis	st.	
Post-Build Variant Multiplicity	true			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Configuration Parameters				

SWS Item	[ECUC_BswM_00902]	[ECUC_BswM_00902]		
Parameter Name	BswMAbortOnFail			
Parent Container	BswMActionListItem			
Description	action returns E_NOT_OK. N	This parameter defines if the execution of the action list shall be aborted if this specific action returns E_NOT_OK. Note that this is only applicable for actions that have E_NOT_OK as a possible return value.		
Multiplicity	1	1		
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value	false	false		
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00824]			
Parameter Name	BswMActionListItemIndex	BswMActionListItemIndex		
Parent Container	BswMActionListItem			
Description	This parameter defines the index of the action in the action list. It is used define in which order the actions shall be performed.			
Multiplicity	1			
Туре	EcucIntegerParamDef			
Range	0 255	0 255		
Default value	-			
Post-Build Variant Value	true			
Value Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE			
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01050]
Parameter Name	BswMReportFailRuntimeErrorld
Parent Container	BswMActionListItem
Description	If this parameter is configured, and this specific action returns E_NOT_OK, the BswM will report a Det Runtime Error. The Errorld reported in the Runtime Error is given by the value configured in this parameter.
Multiplicity	01





Туре	EcucIntegerParamDef		
Range	128 255		
Default value	128		
Post-Build Variant Multiplicity	true		
Post-Build Variant Value	true		
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE
	Link time	X	VARIANT-LINK-TIME
	Post-build time	X	VARIANT-POST-BUILD
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00825]			
Parameter Name	BswMActionListItemRef			
Parent Container	BswMActionListItem			
Description	The action item can either be an at rule.	The action item can either be an atomic action or a reference to another action list or rule.		
Multiplicity	1	1		
Туре	Choice reference to [BswMAction, BswMActionList, BswMRule]			
Post-Build Variant Value	true	true		
Value Configuration Class	Pre-compile time	Pre-compile time X VARIANT-PRE-COMPILE		
	Link time X VARIANT-LINK-TIME			
	Post-build time X VARIANT-POST-BUILD			
Scope / Dependency	scope: local			

No Included Containers

10.2.87 BswMRteModeRequestPort

SWS Item	[ECUC_BswM_01022]			
Container Name	BswMRteModeRequestPort	BswMRteModeRequestPort		
Parent Container	BswMModeControl			
Description	This container defines a mode request port which the BswM may utilize to send a mode request to a SW-C which is acting as a mode-manager. If this container is referenced by a BswMRteModeRequest, the BswM shall create a corresponding PPort in its service description.			
Post-Build Variant Multiplicity	false			
Multiplicity Configuration Class	Pre-compile time X VARIANT-PRE-COMPILE, VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Link time –			
	Post-build time –			
Configuration Parameters				



SWS Item	[ECUC_BswM_01025]			
Parameter Name	BswMRteModeRequestPortInterfaceRef			
Parent Container	BswMRteModeRequestPort			
Description	This is an instance reference to the	variable (data prototype used for the mode request.	
Multiplicity	01	01		
Туре	Instance reference to VARIABLE-DATA-PROTOTYPE context: SW-COMPONENT-PROTOTYPE*PORT-PROTOTYPE			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time –			
	Post-build time –			
Scope / Dependency	scope: local			
	dependency: BswMRteModeRequestVariableDataPrototypeSRRef == NULL			

SWS Item	[ECUC_BswM_01057]			
Parameter Name	BswMRteModeRequestVariableDataPrototypeSRRef			
Parent Container	BswMRteModeRequestPort	BswMRteModeRequestPort		
Description	This is a foreign reference to a Varia	ableDataF	Prototype used for the mode request.	
Multiplicity	01			
Туре	Foreign reference to VARIABLE-DATA-PROTOTYPE			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time –			
	Post-build time –			
Scope / Dependency	scope: local			
	dependency: BswMRteModeRequestPortInterfaceRef == NULL			

No Included Containers

10.2.88 BswMSwitchPort

SWS Item	[ECUC_BswM_00950]		
Container Name	BswMSwitchPort		
Parent Container	BswMModeControl		
Description	Represents an output mode-switch port to be generated by the BswM. If BswMMode SwitchInterfaceRef is configured then a PPortPrototype is generated in the SWCD. If BswMSchMModeDeclarationGroupRef is configured then a ModeDeclarationGroup Prototype is generated in the ProvidedModeGroups of the BSWMD. If both BswMMode SwitchInterfaceRef and BswMSchMModeDeclarationGroupRef are configured then an SwcBswSynchronizedModeGroupPrototype is also generated in the BSWMD (see Chapter 6.11 of the BSW Module Description Template SWS and EXP ModemanagementGuide)		
Post-Build Variant Multiplicity	false		
Multiplicity Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE, VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Link time	-	





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	Post-build time	_	
Configuration Parameters			

SWS Item	[ECUC_BswM_00951]			
Parameter Name	BswMModeSwitchInterfaceRef	BswMModeSwitchInterfaceRef		
Parent Container	BswMSwitchPort			
Description	Reference to the ModeSwitchInterface from which the BswM will generate a PPort Prototype.			
Multiplicity	01			
Туре	Foreign reference to MODE-SWITCH-INTERFACE			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE	
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01031]			
Parameter Name	BswMSchMModeDeclarationGroup	BswMSchMModeDeclarationGroupRef		
Parent Container	BswMSwitchPort			
Description	Reference to the ModeDeclarationGroup from which the BswM will generate a Mode DeclarationGroupPrototype.			
Multiplicity	01			
Туре	Foreign reference to MODE-DECLARATION-GROUP			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Scope / Dependency	scope: local			

No Included Containers

[SWS_BswM_CONSTR_00006] [If the BswMSwitchPort is referred by any BswM-RteSwitch actions or BswMModeSwitchErrorEvents then BswMModeSwitchInterfaceRef shall be configured. If the BswMSwitchPort is referred by any BswM-SchMSwitch actions then BswMSchMModeDeclarationGroupRef shall be configured. At least one of the contained references shall be configured.]()

10.2.89 BswMGeneral

SWS Item	[ECUC_BswM_00800]
Container Name	BswMGeneral
Parent Container	BswM
Description	General configuration parameters of the Basic SW Mode Manager.
Configuration Parameters	



SWS Item	[ECUC_BswM_00938]			
Parameter Name	BswMCanSMEnabled			
Parent Container	BswMGeneral			
Description	enable/disable CanSM module relat	ed Bswl	A API: true: Enabled false: Disabled	
Multiplicity	1	1		
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time –			
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00939]			
Parameter Name	BswMComMEnabled	BswMComMEnabled		
Parent Container	BswMGeneral			
Description	enable/disable ComM module relate	ed BswM	API: true: Enabled false: Disabled	
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time –			
	Post-build time –			
Scope / Dependency	scope: local		_	

SWS Item	[ECUC_BswM_00940]			
Parameter Name	BswMDcmEnabled	BswMDcmEnabled		
Parent Container	BswMGeneral			
Description	enable/disable Dcm module related	BswM AF	PI: true: Enabled false: Disabled	
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time –			
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00811]	
Parameter Name	BswMDevErrorDetect	
Parent Container	BswMGeneral	
Description	Switches the development error detection and notification on or off.	
	true: detection and notification is enabled.	
	false: detection and notification is disabled.	
Multiplicity	1	
Туре	EcucBooleanParamDef	







Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X All Variants		
	Link time	_	
	Post-build time	_	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00941]		
Parameter Name	BswMEcuMEnabled		
Parent Container	BswMGeneral		
Description	enable/disable EcuM module related BswM API: true: Enabled false: Disabled		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time X All Variants		
	Link time –		
	Post-build time –		
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_01072]	[ECUC_BswM_01072]		
Parameter Name	BswMEthIfEnabled	BswMEthIfEnabled		
Parent Container	BswMGeneral			
Description	enable/disable Ethlf module	related BswM	API: true: Enabled false: Disabled	
Multiplicity	1	1		
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value	false	false		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Pre-compile time X All Variants		
	Link time	_		
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00942]		
Parameter Name	BswMEthSMEnabled		
Parent Container	BswMGeneral		
Description	enable/disable EthSM module relate	ed BswN	A API: true: Enabled false: Disabled
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time –		
	Post-build time –		
Scope / Dependency	scope: local		



SWS Item	[ECUC_BswM_00943]		
Parameter Name	BswMFrSMEnabled		
Parent Container	BswMGeneral		
Description	enable/disable FrSM module related BswM API: true: Enabled false: Disabled		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	-	
	Post-build time	_	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00949]			
Parameter Name	BswMGenericRequestEnabled			
Parent Container	BswMGeneral			
Description	enable/disable Generic Request rela	enable/disable Generic Request related BswM API: true: Enabled false: Disabled		
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	Х	All Variants	
	Link time –			
	Post-build time –			
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00987]			
Parameter Name	BswMJ1939DcmEnabled	BswMJ1939DcmEnabled		
Parent Container	BswMGeneral	BswMGeneral		
Description	Enable/disable J1939Dcm n	nodule related l	BswM API: true: Enabled false: Disabled	
Multiplicity	1	1		
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value	false	false		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	All Variants	
	Link time –			
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_00965]
Parameter Name	BswMJ1939NmEnabled
Parent Container	BswMGeneral
Description	Enable/disable J1939Nm module related BswM API. true: Enabled false: Disabled
Multiplicity	1
Туре	EcucBooleanParamDef
Default value	false
Post-Build Variant Value	false







Value Configuration Class	Pre-compile time	Х	All Variants
	Link time	-	
	Post-build time	-	
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_00944]			
Parameter Name	BswMLinSMEnabled	BswMLinSMEnabled		
Parent Container	BswMGeneral			
Description	enable/disable LinSM module relat	enable/disable LinSM module related BswM API: true: Enabled false: Disabled		
Multiplicity	1	1		
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value	false	false		
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	All Variants	
	Link time	_		
	Post-build time	_		
Scope / Dependency	scope: local	-		

SWS Item	[ECUC_BswM_00945]			
Parameter Name	BswMLinTPEnabled			
Parent Container	BswMGeneral	BswMGeneral		
Description	enable/disable LinTP module relate	enable/disable LinTP module related BswM API: true: Enabled false: Disabled		
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time X All Variants			
	Link time	-		
	Post-build time	_		
Scope / Dependency	scope: local		_	

SWS Item	[ECUC_BswM_00813]			
Parameter Name	BswMMainFunctionPeriod			
Parent Container	BswMGeneral			
Description	The cycle time of the periodic main	function o	of BswM. Defined in seconds .	
Multiplicity	01			
Туре	EcucFloatParamDef	EcucFloatParamDef		
Range]0 INF[
Default value	_	-		
Post-Build Variant Multiplicity	false			
Post-Build Variant Value	false			
Multiplicity Configuration Class	Pre-compile time	X	VARIANT-PRE-COMPILE	
	Link time X VARIANT-LINK-TIME, VARIANT-POST-BUILD			
	Post-build time –			
Value Configuration Class	Pre-compile time	Х	VARIANT-PRE-COMPILE	





	Link time	X	VARIANT-LINK-TIME, VARIANT-POST-BUILD
	Post-build time		
Scope / Dependency	scope: local		

SWS Item	[ECUC_BswM_01071]			
Parameter Name	BswMNmEnabled	BswMNmEnabled		
Parent Container	BswMGeneral	BswMGeneral		
Description	enable/disable Nm module related BswM API: true: Enabled false: Disabled			
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	All Variants	
	Link time	_		
	Post-build time	_		
Scope / Dependency	scope: local	•		

SWS Item	[ECUC_BswM_00946]			
Parameter Name	BswMNvMEnabled	BswMNvMEnabled		
Parent Container	BswMGeneral			
Description	enable/disable NvM module related BswM API: true: Enabled false: Disabled			
Multiplicity	1			
Туре	EcucBooleanParamDef			
Default value	false			
Post-Build Variant Value	false			
Value Configuration Class	Pre-compile time	X	All Variants	
	Link time	_		
	Post-build time	_		
Scope / Dependency	scope: local			

SWS Item	[ECUC_BswM_01047]			
Parameter Name	BswMSdEnabled	BswMSdEnabled		
Parent Container	BswMGeneral	BswMGeneral		
Description	enable/disable Sd module related BswM API. true: Enabled false: Disabled			
Multiplicity	1	1		
Туре	EcucBooleanParamDef	EcucBooleanParamDef		
Default value	false	false		
Post-Build Variant Value	false	false		
Value Configuration Class	Pre-compile time	X	All Variants	
	Link time	_		
	Post-build time	_		
Scope / Dependency	scope: local	•		

SWS Item	[ECUC_BswM_00812]
Parameter Name	BswMVersionInfoApi
Parent Container	BswMGeneral





Description	Switches the possibility to read the version information with the service BswM_Get VersionInfo(). true: Enabled false: Disabled		
Multiplicity	1		
Туре	EcucBooleanParamDef		
Default value	false		
Post-Build Variant Value	false		
Value Configuration Class	Pre-compile time	X	All Variants
	Link time	[-	
	Post-build time	_	
Scope / Dependency	scope: local		

Included Containers				
Container Name	Multiplicity	Scope / Dependency		
BswMUserIncludeFiles	01	Collection of header file names which shall be included by the BswM.		

[SWS_BswM_00279] [The availability of private header files (e.g. BswM_ComM.h) between the BswM and other basic software modules depend on the configuration parameters (BswM<BSWModule>Enabled). If the configuration parameter is set to false, then no private header shall be provided by BswM for that BSWModule.] (SRS_-BSW_00301)

10.2.90 BswMUserIncludeFiles

SWS Item	[ECUC_BswM_00954]
Container Name	BswMUserIncludeFiles
Parent Container	BswMGeneral
Description	Collection of header file names which shall be included by the BswM.
Configuration Parameters	

SWS Item	[ECUC_BswM_00955]		
Parameter Name	BswMUserIncludeFile		
Parent Container	BswMUserIncludeFiles		
Description	Header file name which shall be included by the BswM. The value of this parameter shall be used as h-char-sequence or q-char-sequence according to ISO C99. The parameter value shall not represent a path.		
Multiplicity	1*		
Туре	EcucStringParamDef		
Default value	-		
Regular Expression	-		
Post-Build Variant Multiplicity	false		
Post-Build Variant Value	false		
Multiplicity Configuration Class	Pre-compile time	Х	All Variants
	Link time	_	
	Post-build time	_	_
Value Configuration Class	Pre-compile time	Х	All Variants





	Link time	ı	
	Post-build time	ı	
Scope / Dependency	scope: local		

		_
		4
N.	Included Containers	4
	included Containers	4

10.3 Published Information

For details refer to the chapter 10.3 "Published Information" in SWS_BSWGeneral.



A Not applicable requirements

[SWS_BswM_NA_09999] [These requirements are not applicable to this specification.] (SRS_BSW_00405, SRS_BSW_00170, SRS_BSW_00399, SRS_BSW_00400, SRS_BSW_00336, SRS_BSW_00339, SRS_BSW_00409)