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	Communication Stack Types	
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	Document Change History		
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Document Change History			
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Table of Contents

1	Introduction and functional overview	6
2	Acronyms and abbreviations	7
3	Related documentation 3.1 Input documents 3.2 Related standards and norms 3.3 Related specification	8 8
4	Constraints and assumptions4.1 Limitations4.2 Applicability to car domains4.3 Applicability to safety related environments	. 10 . 10
5	Software Architecture5.1 Dependencies to other modules	
6	Requirements traceability	.12
7	Functional specification	. 16 . 16 . 16 . 16 . 16 . 16
8	API specification. 8.1 Type definitions. 8.1.1 PduldType 8.1.2 PduLengthType 8.1.3 PduInfoType 8.1.4 PNCHandleType 8.1.5 TPParameterType 8.1.6 BufReq_ReturnType 8.1.7 TpDataStateType 8.1.8 RetryInfoType 8.1.9 NetworkHandleType 8.2 Function definitions	. 17 . 18 . 19 . 20 . 20 . 21 . 21
9	Sequence diagrams	
	Configuration specification	. 25
11	Not applicable requirements	



1 Introduction and functional overview

This document specifies the AUTOSAR communication stack type header file. It contains all types that are used across several modules of the communication stack of the basic software and all types of all basic software modules that are platform and compiler independent.

It is strongly recommended that those communication stack type files are unique within the AUTOSAR community to guarantee unique types and to avoid type changes when changing from supplier A to B.



2 Acronyms and abbreviations

Acronyms and abbreviations that have a local scope are not contained in the

AUTOSAR glossary. These must appear in a local glossary.

Acronym:	Description:	
API	Application Programming Interface	
DCM	Diagnostic Communication Manager	
I-PDU	Interaction Layer PDU. In AUTOSAR the Interaction Layer is	
	equivalent to the Communication Services Layer.	
L-PDU	Data Link Layer PDU. In AUTOSAR the Data Link Layer is	
	equivalent to the Communication Hardware Abstraction and	
	Microcontroller Abstraction Layer.	
N-PDU	Network Layer PDU. In AUTOSAR the Network Layer is equivalent	
	to the Transport Protocol.	
OSEK/VDX	In May 1993 OSEK has been founded as a joint project in the	
	German automotive industry aiming at an industry standard for an	
	open-ended architecture for distributed control units in vehicles.	
	OSEK is an abbreviation for the German term "Offene Systeme und	
	deren Schnittstellen für die Elektronik im Kraftfahrzeug" (English:	
	Open Systems and the Corresponding Interfaces for Automotive	
	Electronics). Initial project partners were BMW, Bosch,	
	DaimlerChrysler, Opel, Siemens, VW and the IIIT of the University of	
	Karlsruhe as co-ordinator. The French car manufacturers PSA and	
	Renault joined OSEK in 1994 introducing their VDX-approach	
	(Vehicle Distributed eXecutive) which is a similar project within the	
	French automotive industry. At the first workshop on October 1995	
	the OSEK/VDX group presented the results of the harmonised	
	specification between OSEK and VDX. After the 2nd international	
	OSEK/VDX Workshop in October 1997 the 2nd versions of the	
5511	specifications were published.	
PDU	Protocol Data Unit	
SDU	Service Data Unit - Payload of PDU	
TP	Transport Protocol	

Abbreviation:	Description:
Com	Communication
EcuC	ECU Configuration
e.g.	[lat.] exempli gratia = [eng.] for example
i.e.	[lat.] it est = [eng.] that is



3 Related documentation

3.1 Input documents

- [1] [GeneralSRS] General Requirements on Basic Software Modules AUTOSAR_SRS_BSWGeneral.pdf
- [2] [SRSSPAL] General Requirements on SPAL AUTOSAR SRS SPALGeneral.pdf
- [3] [StdTypes] Specification of Standard Types AUTOSAR SWS Std Types.pdf
- [4] [PltfTypes] Specification of Platform Types AUTOSAR_SWS_Platform_Types.pdf
- [5] [CompTypes] Specification of Compiler Abstraction AUTOSAR_SWS_CompilerAbstraction.pdf
- [6] [CANTP] Specification of CAN Transport Layer AUTOSAR_SWS_CANTransportLayer.pdf
- [7] [FlexRayTP] Specification of FlexRay Transport Layer AUTOSAR_SWS_FlexRayTransportLayer.pdf
- [8] [CANTRCV] Specification of CAN Transceiver Driver AUTOSAR_SWS_CANTransceiverDriver.pdf
- [9] [FRTRCV] Specification of FlexRay Transceiver Driver AUTOSAR_SWS_FlexRayTransceiverDriver.pdf
- [10] [BSMDT]Basic Software Module Description Template, AUTOSAR_TPS_BSWModuleDescriptionTemplate.pdf
- [11] [BSWModule]List of Basic Software Modules AUTOSAR TR BSWModuleList
- [12] [BSWGeneral]General Specification of Basic Software Modules AUTOSAR_SWS_BSWGeneral.pdf

3.2 Related standards and norms

[CProgLang] ISO/IEC 9899:1990 Programming Language – C [ISONM] ISO/IEC 15765-2; 2003 Diagnostics on Controller Area Networks (CAN) – Network layer services



3.3 Related specification

AUTOSAR provides a General Specification on Basic Software modules (→ chapter 3.1) (SWS BSW General), which is also valid for Communication Stack Types.

Thus, the specification SWS BSW General shall be considered as additional and required specification for Communication Stack Types.



4 Constraints and assumptions

4.1 Limitations

No limitations.

4.2 Applicability to car domains

No limitations.

4.3 Applicability to safety related environments

No restrictions, because the subject of this specification is a header file specifying types. It does not include or implement any functionality.



5 Software Architecture

5.1 Dependencies to other modules

The communication stack type header file defines communication types based on the platform types [PltfTypes] (Platform_Types.h) and Compiler (Compiler.h) header file [CompTypes]. To prevent multiple includes of header files, the communication stack header file includes the standard types header file [StdTypes] which already includes both other files.



6 Requirements traceability

Requirement	Description	Satisfied by
SRS_BSW_00006	The source code of software modules above the µC Abstraction Layer (MCAL) shall not be processor and compiler dependent.	SWS_Comtype_NA_3
SRS_BSW_00007	All Basic SW Modules written in C language shall conform to the MISRA C 2012 Standard.	SWS_Comtype_NA_3
SRS_BSW_00009	All Basic SW Modules shall be documented according to a common standard.	SWS_Comtype_NA_3
SRS_BSW_00010	The memory consumption of all Basic SW Modules shall be documented for a defined configuration for all supported platforms.	SWS_Comtype_NA_3
SRS_BSW_00158	-	SWS_Comtype_NA_0
SRS_BSW_00159	All modules of the AUTOSAR Basic Software shall support a tool based configuration	SWS_Comtype_NA_0
SRS_BSW_00160	Configuration files of AUTOSAR Basic SW module shall be readable for human beings	SWS_Comtype_NA_0
SRS_BSW_00167	All AUTOSAR Basic Software Modules shall provide configuration rules and constraints to enable plausibility checks	SWS_Comtype_NA_0
SRS_BSW_00168	SW components shall be tested by a function defined in a common API in the Basis-SW	SWS_Comtype_NA_1
SRS_BSW_00170	The AUTOSAR SW Components shall provide information about their dependency from faults, signal qualities, driver demands	SWS_Comtype_NA_1
SRS_BSW_00171	Optional functionality of a Basic-SW component that is not required in the ECU shall be configurable at pre-compile-time	SWS_Comtype_NA_0
SRS_BSW_00300	All AUTOSAR Basic Software Modules shall be identified by an unambiguous name	SWS_Comtype_NA_3
SRS_BSW_00301	All AUTOSAR Basic Software Modules shall only import the necessary information	SWS_Comtype_NA_3
SRS_BSW_00302	All AUTOSAR Basic Software Modules shall only export information needed by other modules	SWS_Comtype_NA_3
SRS_BSW_00304	All AUTOSAR Basic Software Modules shall use the following data types instead of native C data types	SWS_Comtype_NA_3
SRS_BSW_00306	AUTOSAR Basic Software Modules shall be compiler and platform independent	SWS_Comtype_NA_3
SRS_BSW_00307	Global variables naming convention	SWS_Comtype_NA_3
SRS_BSW_00308	AUTOSAR Basic Software Modules shall not define global data in their header files, but in the C file	SWS_Comtype_NA_3
SRS_BSW_00309	All AUTOSAR Basic Software Modules shall indicate all global data with read-only purposes by explicitly assigning the const keyword	SWS_Comtype_NA_3





CDC DCM 00340	API naming convention	SIMS Compus NIA 2
	API naming convention	SWS_Comtype_NA_3
SRS_BSW_00312	Shared code shall be reentrant	SWS_Comtype_NA_3
SRS_BSW_00321	The version numbers of AUTOSAR Basic Software Modules shall be enumerated according specific rules	SWS_Comtype_NA_3
SRS_BSW_00323	All AUTOSAR Basic Software Modules shall check passed API parameters for validity	SWS_Comtype_NA_3
SRS_BSW_00327	Error values naming convention	SWS_Comtype_NA_5
SRS_BSW_00328	All AUTOSAR Basic Software Modules shall avoid the duplication of code	SWS_Comtype_NA_3
SRS_BSW_00330	It shall be allowed to use macros instead of functions where source code is used and runtime is critical	SWS_Comtype_NA_3
SRS_BSW_00331	All Basic Software Modules shall strictly separate error and status information	SWS_Comtype_NA_3
SRS_BSW_00333	For each callback function it shall be specified if it is called from interrupt context or not	SWS_Comtype_NA_3
SRS_BSW_00334	All Basic Software Modules shall provide an XML file that contains the meta data	SWS_Comtype_NA_3
SRS_BSW_00335	Status values naming convention	SWS_Comtype_NA_3
SRS_BSW_00336	Basic SW module shall be able to shutdown	SWS_Comtype_NA_4
SRS_BSW_00337	Classification of development errors	SWS_Comtype_NA_5
SRS_BSW_00339	Reporting of production relevant error status	SWS_Comtype_NA_5
SRS_BSW_00341	Module documentation shall contains all needed informations	SWS_Comtype_NA_3
SRS_BSW_00342	It shall be possible to create an AUTOSAR ECU out of modules provided as source code and modules provided as object code, even mixed	SWS_Comtype_NA_0
SRS_BSW_00343	The unit of time for specification and configuration of Basic SW modules shall be preferably in physical time unit	SWS_Comtype_NA_0
SRS_BSW_00344	BSW Modules shall support link-time configuration	SWS_Comtype_NA_0
SRS_BSW_00345	BSW Modules shall support pre-compile configuration	SWS_Comtype_NA_0
SRS_BSW_00346	All AUTOSAR Basic Software Modules shall provide at least a basic set of module files	SWS_Comtype_NA_0
SRS_BSW_00348	All AUTOSAR standard types and constants shall be placed and organized in a standard type header file	SWS_Comtype_NA_3
SRS_BSW_00350	All AUTOSAR Basic Software Modules shall allow the enabling/disabling of detection and reporting of development errors.	SWS_Comtype_NA_5
SRS_BSW_00353	All integer type definitions of target and compiler specific scope shall be placed and organized in a single type header	SWS_Comtype_NA_3
SRS_BSW_00357	For success/failure of an API call a standard return type shall be defined	SWS_Comtype_NA_3
SRS_BSW_00358	The return type of init() functions implemented by AUTOSAR Basic Software Modules shall be void	SWS_Comtype_NA_3
SRS_BSW_00359	All AUTOSAR Basic Software Modules callback functions shall avoid return types other than void if possible	SWS_Comtype_NA_3
	The return type of init() functions implemented by AUTOSAR Basic Software Modules shall be void All AUTOSAR Basic Software Modules callback functions shall avoid return types other than void if possible	





SRS_BSW_00360	AUTOSAR Basic Software Modules callback functions are allowed to have parameters	SWS_Comtype_NA_3
SRS_BSW_00369	All AUTOSAR Basic Software Modules shall not return specific development error codes via the API	SWS_Comtype_NA_5
SRS_BSW_00371	The passing of function pointers as API parameter is forbidden for all AUTOSAR Basic Software Modules	SWS_Comtype_NA_3
SRS_BSW_00373	The main processing function of each AUTOSAR Basic Software Module shall be named according the defined convention	SWS_Comtype_NA_3
SRS_BSW_00374	All Basic Software Modules shall provide a readable module vendor identification	SWS_Comtype_NA_3
SRS_BSW_00377	A Basic Software Module can return a module specific types	SWS_Comtype_NA_3
SRS_BSW_00378	AUTOSAR shall provide a boolean type	SWS_Comtype_NA_3
SRS_BSW_00379	All software modules shall provide a module identifier in the header file and in the module XML description file.	SWS_Comtype_NA_3
SRS_BSW_00380	Configuration parameters being stored in memory shall be placed into separate c-files	SWS_Comtype_NA_0
SRS_BSW_00381	-	SWS_Comtype_NA_0
SRS_BSW_00383	The Basic Software Module specifications shall specify which other configuration files from other modules they use at least in the description	SWS_Comtype_NA_0
SRS_BSW_00385	List possible error notifications	SWS_Comtype_NA_5
SRS_BSW_00386	The BSW shall specify the configuration for detecting an error	SWS_Comtype_NA_5
SRS_BSW_00388	Containers shall be used to group configuration parameters that are defined for the same object	SWS_Comtype_NA_0
SRS_BSW_00389	Containers shall have names	SWS_Comtype_NA_0
SRS_BSW_00390	Parameter content shall be unique within the module	SWS_Comtype_NA_0
SRS_BSW_00392	Parameters shall have a type	SWS_Comtype_NA_0
SRS_BSW_00393	Parameters shall have a range	SWS_Comtype_NA_0
SRS_BSW_00394	The Basic Software Module specifications shall specify the scope of the configuration parameters	SWS_Comtype_NA_0
SRS_BSW_00395	The Basic Software Module specifications shall list all configuration parameter dependencies	SWS_Comtype_NA_0
SRS_BSW_00396	The Basic Software Module specifications shall specify the supported configuration classes for changing values and multiplicities for each parameter/container	SWS_Comtype_NA_0
SRS_BSW_00397	The configuration parameters in pre-compile time are fixed before compilation starts	SWS_Comtype_NA_0
SRS_BSW_00398	The link-time configuration is achieved on object code basis in the stage after compiling and before linking	SWS_Comtype_NA_0
SRS_BSW_00399	Parameter-sets shall be located in a separate segment and shall be loaded after the code	SWS_Comtype_NA_0
SRS_BSW_00400	Parameter shall be selected from multiple sets of parameters after code has been loaded and started	SWS_Comtype_NA_0



Specification of Communication Stack Types AUTOSAR CP R20-11

SRS_BSW_00401	Documentation of multiple instances of configuration parameters shall be available	SWS_Comtype_NA_0
SRS_BSW_00404	BSW Modules shall support post-build configuration	SWS_Comtype_NA_0
SRS_BSW_00405	BSW Modules shall support multiple configuration sets	SWS_Comtype_NA_0
SRS_BSW_00407	Each BSW module shall provide a function to read out the version information of a dedicated module implementation	SWS_Comtype_NA_3
SRS_BSW_00408	All AUTOSAR Basic Software Modules configuration parameters shall be named according to a specific naming rule	SWS_Comtype_NA_0
SRS_BSW_00409	All production code error ID symbols are defined by the Dem module and shall be retrieved by the other BSW modules from Dem configuration	SWS_Comtype_NA_5
SRS_BSW_00411	All AUTOSAR Basic Software Modules shall apply a naming rule for enabling/disabling the existence of the API	SWS_Comtype_NA_3
SRS_BSW_00412	-	SWS_Comtype_NA_0
SRS_BSW_00414	Init functions shall have a pointer to a configuration structure as single parameter	SWS_Comtype_NA_3
SRS_BSW_00415	Interfaces which are provided exclusively for one module shall be separated into a dedicated header file	SWS_Comtype_NA_3
SRS_BSW_00417	Software which is not part of the SW-C shall report error events only after the DEM is fully operational.	SWS_Comtype_NA_5
SRS_BSW_00422	Pre-de-bouncing of error status information is done within the DEM	SWS_Comtype_NA_5
SRS_BSW_00423	BSW modules with AUTOSAR interfaces shall be describable with the means of the SW-C Template	SWS_Comtype_NA_1
SRS_BSW_00432	Modules should have separate main processing functions for read/receive and write/transmit data path	SWS_Comtype_NA_3
SRS_BSW_00433	Main processing functions are only allowed to be called from task bodies provided by the BSW Scheduler	SWS_Comtype_NA_3



7 Functional specification

7.1 General issues

[SWS_Comtype_00004] [It is not allowed to add any project or supplier specific extension to this file. Any extension invalidates the AUTOSAR conformity.] ()

[SWS_Comtype_00015] [Because many of the communication stack type are depending on the appropriate ECU, this file shall be generated dependent on the specific ECU configuration for each ECU independently.] ()

[SWS_Comtype_00030] [The value of PduIdType and PduLengthType shall be derived from the 'PduIdTypeEnum' and 'PduLengthTypeEnum' of the EcuCPduCollection container respectively.] ()

7.2 Error classification

7.2.1 Development Errors

There are no development errors.

7.2.2 Runtime Errors

There are no runtime errors.

7.2.3 Transient Faults

There are no transient faults.

7.2.4 Production Errors

There are no production errors.

7.2.5 Extended Production Errors

There are no extended production errors.



8 API specification

8.1 Type definitions

8.1.1 PduldType

[SWS_COMTYPE_00005][

[OWO_OOM	SWITTE_00003]			
Name	PduldType			
Kind	Туре			
	Basetype	Variation		
Derived from	uint16	The size of this global type depends on the maximum number of PDUs used within one software module.		
	uint8	The size of this global type depends on the maximum number of PDUs used within one software module.		
Range	0 <pdu Idmax></pdu 	Zero-based integer number The size of this global type depends on the maximum number of PDUs used within one software module. This parameter shall be generated by the generator tool depending on the value configured in EcuC virtual layer. This parameter shall be generated in ComStack_Cfg.h file Example: If no software module deals with more PDUs that 256, this type can be set to uint8. If at least one software module handles more than 256 PDUs, this type must globally be set to uint16.		
Description	This type is used within the entire AUTOSAR Com Stack except for bus drivers.			
Available via	ComStack_Types.h			

()

[SWS_Comtype_00006] Variables of this type serve as a unique identifier of a PDU within a software module or a set thereof, and also for interaction of two software modules where the PduId of the corresponding target module is being used for referencing.

]()

[SWS_Comtype_00007] In order to be able to perform table-indexing within a software module, variables of this type shall be zero-based and consecutive. There might be several ranges of Pdulds in a module, one for each type of operation performed within that module (e.g. sending and receiving).

]()

[SWS_Comtype_00014] Pduldmax, the maximum number of a Pduld range, is the



number -1 of PDUs dealt with in the corresponding type of operation within that module.

]()

8.1.2 PduLengthType

[SWS_COMTYPE_00008][

	[3VV3_CONTTPE_00000]				
Name	PduLengthType				
Kind	Туре				
	Basetype	Variation			
Derived	uint16	The size of this global type depends on the maximum length of PDUs to be sent by an ECU.			
from	uint32	The size of this global type depends on the maximum length of PDUs to be sent by an ECU.			
	uint8	The size of this global type depends on the maximum length of PDUs to be sent by an ECU.			
Range	0 <pdu Lengthmax></pdu 	Zero-based integer number The size of this global type depends on the maximum length of PDUs to be sent by an ECU. This parameter shall be generated by the generator tool depending on the value configured in EcuC virtual layer. This parameter shall be generated in ComStack_Cfg.h file Example: If no segmentation is used the length depends on the maximum payload size of a frame of the underlying communication system (for FlexRay maximum size is 255, therefore uint8). If segmentation is used it depends on the maximum length of a segmented N-PDU (in general uint16 is used)			
Description	This type shall be used within the entire AUTOSAR Com Stack of an ECU except for bus drivers.				
Available via	ComStack_Types.h				

]()

[SWS_Comtype_00010] Variables of this type serve as length information of a PDU. The length information is provided in number of bytes.

]()

 $[SWS_Comtype_00017] \Gamma \ \, \text{PduLengthmax}, \ \, \text{the maximum length of a Pdu, is the length of the largest (possibly segmented) PDU to be sent by the ECU.}$

]()



8.1.3 PduInfoType

[SWS_COMTYPE_00011][

Name	PduInfoType				
Kind	Structure				
	SduDataPtr	•			
	Туре	uint8*			
	Comment	Pointer to the SDU (i.e. payload data) of the PDU. The type of this pointer depends on the memory model being used at compile time.			
	MetaDataPtr				
Flamonto	Туре	uint8*			
Elements	Comment	Pointer to the meta data (e.g. CAN ID, socket ID, diagnostic addresses) of the PDU, consisting of a sequence of meta data items. The length and type of the meta data items is statically configured for each PDU. Meta data items with more than 8 bits use platform byte order.			
	SduLength				
	Туре	PduLengthType			
	Comment	Length of the SDU in bytes.			
Description	Variables of this type shall be used to store the basic information about a PDU of any type, namely a pointer variable pointing to its SDU (payload), a pointer to Meta Data of the PDU, and the corresponding length of the SDU in bytes.				
Available via	ComStack_Types.h				

]()

8.1.4 PNCHandleType

[SWS_COMTYPE_00036][

Name	PNCHandleType		
Kind	Туре		
Derived from	uint8		
Description Used to store the identifier of a partial network cluster.			
Available via ComStack_Types.h			

]()



8.1.5 TPParameterType

[SWS_COMTYPE_00031][

[6116_66111					
Name	TPParameterType				
Kind	Enumeratio	Enumeration			
	TP_ STMIN	0x00	Separation Time		
Range	TP_BS	0x01	Block Size		
	TP_BC	0x02	The Band width control parameter used in FlexRay transport protocol module.		
Description	Specify the parameter to which the value has to be changed (BS or STmin).				
Available via	ComStack_Types.h				

]()

8.1.6 BufReq_ReturnType

[SWS_COMTYPE_00012][

Name	BufReq_ReturnType			
Kind	Enumeration			
	BUFREQ_OK	0x00	Buffer request accomplished successful. This status shall have the value 0.	
Pango	BUFREQ_E_ NOT_OK	0x01	Buffer request not successful. Buffer cannot be accessed. This status shall have the value 1.	
Range	BUFREQ_E_ BUSY	0x02	Temporarily no buffer available. It's up the requester to retry request for a certain time. This status shall have the value 2.	
	BUFREQ_E_ OVFL	0x03	No Buffer of the required length can be provided. This status shall have the value 3.	
Description	Variables of this type shall be used to store the result of a buffer request.			
Available via	ComStack_Types.h			

]()

8.1.7 TpDataStateType

[SWS COMTYPE 00027]

Nan	ne	TpDataStateType			

Kind	Enumeration			
	TP_DATACONF	0x00	TP_DATACONF indicates that all data, that have been copied so far, are confirmed and can be removed from the TP buffer. Data copied by this API call are excluded and will be confirmed later.	
Range	TP_ DATARETRY	0x01	TP_DATARETRY indicates that this API call shall copyalready copied data in order to recover from an error. In this case TxTpDataCnt specifies the offset of the first byte to be copied by the API call.	
	TP_ CONFPENDING	0x02	TP_CONFPENDING indicates that the previously copied data must remain in the TP.	
Description	Variables of this type shall be used to store the state of TP buffer.			
Available via	ComStack_Types.h			

]()

8.1.8 RetryInfoType

ISWS COMTYPE 000371

TOMO_COM						
Name	RetryInfoType					
Kind	Structure	Structure				
	TpDataState					
	Туре	TpDataStateType				
	Comment	The enum type to be used to store the state of Tp buffer.				
Elements	TxTpDataCnt					
	Туре	PduLengthType				
	Comment	Offset from the current position which identifies the number of bytes to be retransmitted.				
Description	Variables of this type shall be used to store the information about Tp buffer handling.					
Available via	ComStack_Types.h					

]()

8.1.9 NetworkHandleType

[SWS COMTYPE 00038]

<u> </u>	=
Name	NetworkHandleType



Specification of Communication Stack Types AUTOSAR CP R20-11

Kind	Туре				
Derived from	uint8				
Range	0255	0255 Zero-based integer number			
Description	Variables of the type NetworkHandleType shall be used to store the identifier of a communication channel.				
Variation					
Available via	ComStack_Types.h				

]()



8.2 Function definitions

Not applicable.



9 Sequence diagrams

Not applicable.



10 Configuration specification

10.1 Published parameters

For details refer to the chapter 10.3 "Published Information" in "SWS_BSWGeneral" [12].



11 Not applicable requirements

[SWS_Comtype_NA_0] | This specification item references requirements that are not applicable, because ComStack_Types neither has configurable parameters nor has reference to configuration parameters from other modules. | (SRS_BSW_00344, SRS_BSW_00404, SRS_BSW_00405, SRS_BSW_00345, SRS_BSW_00159, SRS_BSW_00167, SRS_BSW_00171, SRS_BSW_00380, SRS_BSW_00381, SRS_BSW_00412, SRS_BSW_00383, SRS_BSW_00388, SRS_BSW_00389, SRS_BSW_00390, SRS_BSW_00392, SRS_BSW_00393, SRS_BSW_00394, SRS_BSW_00395, SRS_BSW_00396, SRS_BSW_00397, SRS_BSW_00398, SRS_BSW_00399, SRS_BSW_00400, SRS_BSW_00342, SRS_BSW_00343, SRS_BSW_00160, SRS_BSW_00408, SRS_BSW_00346, SRS_BSW_00158, SRS_BSW_00401)

[SWS_Comtype_NA_1] This specification item references requirements that are not applicable, because ComStack_Types has no interdepencies to SW Components. (SRS_BSW_00170, SRS_BSW_00168, SRS_BSW_00423)

[SWS_Comtype_NA_2] 「This specification item references requirements that are not applicable, because ComStack_Types does not implement any interrupts, is not a driver or MCAL abstraction layer or has any direct access to OS.」
(SRS_BSW_00375, SRS_BSW_00101, SRS_BSW_00406, SRS_BSW_00416, SRS_BSW_00424, SRS_BSW_00425, SRS_BSW_00426, SRS_BSW_00427, SRS_BSW_00428, SRS_BSW_00429, SRS_BSW_00161, SRS_BSW_00162, SRS_BSW_00005, SRS_BSW_00164, SRS_BSW_00325, SRS_BSW_00413, SRS_BSW_00347, SRS_BSW_00314, SRS_BSW_00410, SRS_BSW_00314, SRS_BSW_00361, SRS_BSW_00172,)

[SWS_Comtype_NA_3] This specification item references requirements that are not applicable, because ComStack_Types does not implement any version check information, main function. APIs, standard types, \(\)

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(SRS_BSW_00323, SRS_BSW_00415, SRS_BSW_00007, SRS_BSW_00300, SRS_BSW_00307, SRS_BSW_00310, SRS_BSW_00373, SRS_BSW_00335, SRS_BSW_00411, SRS_BSW_00348, SRS_BSW_00353, SRS_BSW_00301, SRS_BSW_00302, SRS_BSW_00328, SRS_BSW_00312, SRS_BSW_00006, SRS_BSW_00357, SRS_BSW_00377, SRS_BSW_00304, SRS_BSW_00378, SRS_BSW_00306, SRS_BSW_00308, SRS_BSW_00309, SRS_BSW_00371, SRS_BSW_00358, SRS_BSW_00407, SRS_BSW_00432, SRS_BSW_00433, SRS_BSW_00414, SRS_BSW_00359, SRS_BSW_00360, SRS_BSW_00330, SRS_BSW_00331, SRS_BSW_00009, SRS_BSW_00010, SRS_BSW_00333, SRS_BSW_00374, SRS_BSW_00379, SRS_BSW_00321, SRS_BSW_00341, SRS_BSW_00334)
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[SWS_Comtype_NA_4] This specification item references requirements that are not applicable, because ComStack_Types does not have any shutdown functionality. (SRS_BSW_00336)

[SWS_Comtype_NA_5] This specification item references requirements that are not applicable, because ComStack_Types does not implement development errors and production errors. (SRS_BSW_00337, SRS_BSW_00369, SRS_BSW_00339, SRS_BSW_00422, SRS_BSW_00417, SRS_BSW_00409, SRS_BSW_00385, SRS_BSW_00386, SRS_BSW_00327, SRS_BSW_00350)