

	Adaptive Platform Release	
	Overview	
Document Owner	AUTOSAR	
Document Responsibility	AUTOSAR	
Document Identification No	782	

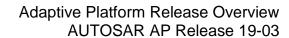
Document Status	Final
Part of AUTOSAR Standard	Adaptive Platform
Part of Standard Release	19-03
Release Life Cycle Status	R19-03 is in Development, R19-03 supersedes R18-10

	Document Change History		
Date	Date Release Changed by Change Description		
2019-03-29	19-03		Updated according to R19-03
		Management	
2018-10-31	18-10	AUTOSAR Release	Initial release
		Management	



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1 Introduction

1.1 Scope of this document

This document provides an overview on the AUTOSAR standard Adaptive Platform Release 19-03.

1.2 Dependencies to other standards

This release of the Adaptive Platform depends on the standard Foundation in Release 1.5.1, which

- defines protocols implemented by Adaptive Platform and
- contains the project objectives and the common requirements from which the features of the Adaptive Platform are derived.

These dependencies are refined in the trace information of the requirements in the respective specifications.

1.3 Content of chapters

This document is structured as follows:

- Chapter 2 provides an introduction to the Adaptive Platform and its standardization approach.
- Chapter 3 provides a list of documentation references.
- Chapter 4 contains the overview of specifications comprising the Release 19-03. This chapter is structured according to the clusters of AUTOSAR Release 19-03.
- Chapter 5 provides a summary of changes since the previous release of the Adaptive Platform.
- Chapter 6 contains remarks about known technical deficiencies.
- Chapter 7 contains the detailed release history of all released specifications.
- Chapter 8 provides a set of definitions aimed to increase the understanding of the content of this document and the Release 19-03.



2 Introduction to the Adaptive Platform

The AUTOSAR Adaptive Platform is the standardized platform for microprocessorbased ECUs supporting use cases like highly automated driving as well as high speed on-board and off-board communication.

The Adaptive Platform differs in a number of aspects from the standardization approach of the Classic Platform:

- Release strategy
- Parallel validation of specification via software implementation
- Specification of functional clusters instead of modules

2.1 Release strategy

The Adaptive Platform will be in lifecycle state "Development" according to AUTOSAR's lifecycle model for its standards (see figures 1 and 2) until it will reach a certain maturity level. Until November 2019, AUTOSAR will release a new version of the Adaptive Platform in a 6-month cycle. The lifecycle state "Development" implies that users of the Adaptive Platform have no guarantee on backward compatibility. Consequently, all requirements have the lifecycle status *draft*.

The release R19-03 is considered to be a stabilization release.

Thus the focus of the release is on stabilization of the existing features from R18-10 and not on additional features.

According to the release scheme of AUTOSAR the release R19-03 is a Revision.

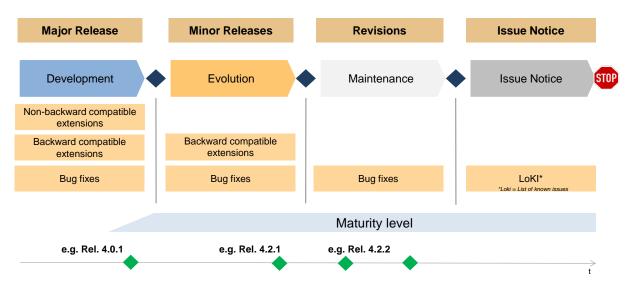


Figure 1: Lifecycle model of AUTOSAR standards and its application to Classic Platform



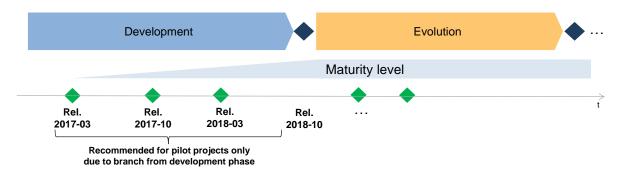


Figure 2: Application of AUTOSAR lifecycle to Adaptive Platform (Release numbers only exemplary)

Apart from the regular specifications that have been elaborated in intensive expert discussion, according to current planning, the releases may comprise draft specifications to indicate the intended scope and direction of discussion to the AUTOSAR development community.

The following must be considered for the draft specifications:

- 1. Minimal or less quality measures are being applied during development
- No indication of quality / stability due to a lack of discussions between the AUTOSAR partners

2.2 Parallel validation of specification via implementation

The Adaptive Platform is partially validated through an AUTOSAR-internal implementation: the Adaptive Platform Demonstrator. This Demonstrator is available to all the partners and can provide further details to understand the underlying concepts of the Adaptive Platform. The Demonstrator provides an implementation example based on the specification rather than a reference implementation. All further development based on the Demonstrator will become the responsibility of the respective partner. For legal constraints see the dedicated paragraphs in the Development Agreement.

For the current releases, the Demonstrator software implementation has undergone only informal reviews with no strict quality assurance. AUTOSAR is increasing the quality assurance significantly to ensure the maintainability and extensibility of the Demonstrator software implementation.

The Demonstrator comes with traceability up to the specifications and explanatory documents or the so-called Functional Cluster Design specifications. Additionally AUTOSAR develops System Tests to test the demonstrator implementation against the AUTOSAR requirements. These tests are also part of the release.



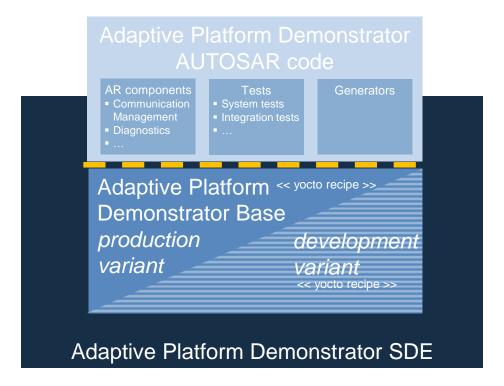


Figure 3: Overview of the AUTOSAR Adaptive Platform Demonstrator

2.3 Specification depth

Based on the development history of the Classic Platform, AUTOSAR has decided to specify functional clusters instead of a specific software architecture to provide the implementers with options to find efficient solutions for the standardized features.



3 Related documentation

[1] AUTOSAR Specifications in general

[2] Glossary



4 Specification overview

4.1 Release 18-10

The published specifications are divided into the following clusters:

- Release Documentation
- General
- Methodology and Manifests
- Adaptive Foundation
- Adaptive Services

All specifications contain requirements which are identified by special braces:

[= Beginning of the requirement content

| = End of the requirement content

In addition, all XML files and schemas are considered as requirements.

The assignment of specifications to clusters is shown below.

Long Name	File Name	Life cycle	Draft
· ·		changes	Specification
Release Documentation			
Adaptive Platform Release	AUTOSAR_TR_Adaptive		
Overview	PlatformReleaseOverview		
AUTOSAR Adaptive Platform	AUTOSAR_TR_Adaptive		
Specification Hashes	PlatformSpecificationHashes		
Adaptive Foundation			
Explanation of ara::com API	AUTOSAR_EXP_ARACom API		
Explanation of IPsec	AUTOSAR_EXP_IPsecImpl	Initial release	
Implementation Guidelines	ementationGuidelines		
Requirement on Time	AUTOSAR_RS_TimeSynch		
Synchronization for	ronization		
Adaptive Platform			
Requirements on	AUTOSAR_RS_Communic		
Communication	ationManagement		
Management	_		
Requirements on	AUTOSAR_RS_Cryptograp		
Cryptography	hy		
Requirements on Execution	AUTOSAR_RS_Execution		
Management	Management		
Requirements on Identity	AUTOSAR_RS_IdentityAnd		
and Access Management	AccessManagement		
Requirements on Operating	AUTOSAR_RS_OperatingS		
System Interface	ystemInterface		
Requirements on	AUTOSAR_RS_Persistenc		
Persistency			
Requirements on Platform	AUTOSAR_RS_PlatformHe		
Health Management for	althManagement		



Long Name	File Name	Life cycle	Draft
Long Name	i ne Name	changes	Specification
Adaptive Platform		onangoo	opoomoation .
Requirements on Security	AUTOSAR_RS_SecurityMa		
Management for Adaptive	nagement		
Platform			
Specification of	AUTOSAR_SWS_Commun		
Communication	icationManagement		
Management	3.00		
Specification of	AUTOSAR_SWS_Cryptogr		X
Cryptography for Adaptive	aphy		
Platform			
Specification of Execution	AUTOSAR_SWS_Executio		
Management	nManagement		
Specification of Identity and	AUTOSAR_SWS_IdentityA		
Access Management	ndAccessManagement		
Specification of Log and	AUTOSAR SWS LogAndT		
Trace	race		
Specification of Operating	AUTOSAR_SWS_Operatin		
System Interface	gSystemInterface		
Specification of Persistency	AUTOSAR_SWS_Persisten		
	су		
Specification of Platform	AUTOSAR_SWS_Platform		
Health Management for	HealthManagement		
Adaptive Platform			
Specification of RESTful	AUTOSAR_SWS_REST		
communication			
Specification of Time	AUTOSAR_SWS_TimeSyn		
Synchronization for	chronization		
Adaptive Platform			
Adaptive Services			
Explanation of Sensor	AUTOSAR_EXP_SensorInt	Initial release	
Interfaces	erfaces		
Requirements of State	AUTOSAR_RS_StateMana	Initial release	
Management	gement		
Requirements on Update	AUTOSAR_RS_UpdateAnd		
and Configuration	ConfigManagement		
Management			
Specification for Network	AUTOSAR_SWS_Network		
Management	Management		
Specification of Diagnostics	AUTOSAR_SWS_Diagnostics		
Specification of State	AUTOSAR_SWS_StateMa	Initial release	
Management	nagement		
Specification of Update and	AUTOSAR_SWS_UpdateA		
Configuration Management	ndConfigManagement		
Methodology and Manifests			
Meta Model	AUTOSAR_MMOD_MetaM		



Long Name	File Name	Life cycle	Draft
		changes	Specification
	odel		
Meta Model-generated XML	AUTOSAR_MMOD_XMLSc		
Schema	hema		
Methodology for Adaptive	AUTOSAR_TR_AdaptiveM		
Platform	ethodology		
Requirements on Manifest	AUTOSAR_RS_ManifestSp		
Specification	ecification		
Specification of Manifest	AUTOSAR_TPS_ManifestS		
	pecification		
Specification of Platform	AUTOSAR_SWS_Adaptive		
Types for Adaptive Platform	PlatformTypes		
Supplementary material of	AUTOSAR_TR_XMLSche		
the AUTOSAR XML	maSupplement		
Schema			
Collection of blueprints for	AUTOSAR_MOD_Adaptive	Initial release	
AUTOSAR Adaptive	PlatformGeneralBlueprints		
Platform models			
General			
Design guidelines for using	AUTOSAR_EXP_ParallelPr		
parallel processing	ocessingGuidelines		
technologies on Adaptive			
Platform	ALITOOAD EVD DIGITOOD		
Explanation of Adaptive	AUTOSAR_EXP_PlatformD		
Platform Design	esign		
Explanation of Safety	AUTOSAR_EXP_SafetyOv		
Overview	erview		
Functional Cluster	AUTOSAR_TR_Functional		
Shortnames Congrel Deguirements	ClusterShortnames		
General Requirements	AUTOSAR_RS_General		
specific to Adaptive Platform			
	AUTOSAR SWS General		
General Specification of Adaptive Platform	AUTOSAR_SWS_General		
Guidelines for the use of	AUTOSAR_RS_CPP14Gui		
the C++14 language in	delines		
critical and safety-related			
systems			
Guidelines for using	AUTOSAR EXP Adaptive	Initial release	
Adaptive Platform	PlatformInterfacesGuideline	minai ititast	
interfaces			
Specification of Core Types	S AUTOSAR_SWS_CoreTyp		
for Adaptive Platform	es		
System Tests of Adaptive	AUTOSAR_TR_AdaptivePl		
Platform			
ı ialiviiii	atformSystemTests		



The published specifications are divided into the following clusters:

- Release Documentation
- Adaptive Foundation
- Adaptive Services
- Methodology and Templates
- Methodology and Manifests
- General

The assignment of specifications to clusters is shown below.

Long Name	File Name	Life cycle changes	Draft Specification
Release Documentation			
Adaptive Platform Release Overview	AUTOSAR_TR_AdaptivePlatform ReleaseOverview		
AUTOSAR Adaptive Platform Specification Hashes	AUTOSAR_TR_AdaptivePlatform SpecificationHashes		
Adaptive Foundation			
Explanation of ara::com API	AUTOSAR_EXP_ARAComAPI		
Explanation of IPsec Implementation Guidelines	AUTOSAR_EXP_IPsec ImplementationGuidelines		
Requirement on Time Synchronization for Adaptive Platform	AUTOSAR_RS_Time Synchronization		
Requirements on	AUTOSAR_RS_Communication		
Communication Management	Management		
Requirements on	AUTOSAR_RS_Cryptography		
Cryptography			
Requirements on Execution Management	AUTOSAR_RS_Execution Management		
Requirements on Identity and	AUTOSAR_RS_IdentityAnd		
Access Management	AccessManagement		
Requirements on Operating System Interface	AUTOSAR_RS_OperatingSystem Interface		
Requirements on Persistency	AUTOSAR_RS_Persistency		
Requirements on Platform Health Management for Adaptive Platform	AUTOSAR_RS_PlatformHealth Management		
Requirements on Security Management for Adaptive Platform	AUTOSAR_RS_SecurityManageme nt		
Specification of	AUTOSAR_SWS_Communication		
Communication Management	Management		
Specification of Cryptography for Adaptive Platform	AUTOSAR_SWS_Cryptography		Х



Law w Name	E'l. N	1.16.	D (1
Long Name	File Name	Life	Draft
		cycle	Specification
		changes	
Specification of Execution	AUTOSAR_SWS_Execution		
Management	Management		
Specification of Identity and	AUTOSAR_SWS_IdentityAnd		
Access Management	AccessManagement		
Specification of Log and Trace	AUTOSAR_SWS_LogAndTrace		
Specification of Operating	AUTOSAR_SWS_OperatingSystem		
System Interface	Interface		
Specification of Persistency	AUTOSAR_SWS_Persistency		
Specification of Platform	AUTOSAR_SWS_Platform		
Health Management for	Health		
Adaptive Platform	Management		
Specification of RESTful	AUTOSAR_SWS_REST		
communication			
Specification of Time	AUTOSAR_SWS_Time		
Synchronization for Adaptive	Synchronization		
Platform			
Adaptive Services			
Explanation of Sensor	AUTOSAR_EXP_SensorInterfaces		
Interfaces			
Requirements of State	AUTOSAR_RS_StateManagement		
Management			
Requirements on Update and	AUTOSAR_RS_UpdateAndConfig		
Configuration Management	Management		
Specification for Network	AUTOSAR_SWS_Network		
Management	Management		
Specification of Diagnostics	AUTOSAR_SWS_Diagnostics		
Specification of State	AUTOSAR_SWS_State		
Management	Management		
Specification of Update and	AUTOSAR_SWS_UpdateAnd		
Configuration Management	ConfigManagement		
Methodology and Templates			
Meta Model	AUTOSAR_MMOD_MetaModel		
Meta Model-generated XML	AUTOSAR_MMOD_XMLSchema		
Schema			
Supplementary material of the	AUTOSAR_TR_XMLSchema		
AUTOSAR XML Schema	Supplement		
Methodology and Manifests	ALITOOAD MOD Aday the District	ı	
Collection of blueprints for	AUTOSAR_MOD_AdaptivePlatform		
AUTOSAR Adaptive Platform	GeneralBlueprints		
models	ALITOOAD TD Adambarda da la		
Methodology for Adaptive	AUTOSAR_TR_AdaptiveMethodolo		
Platform	gy		
Requirements on Manifest	AUTOSAR_RS_ManifestSpecificati		
Specification	on		
Specification of Manifest	AUTOSAR_TPS_ManifestSpecificat		
0 10 10 10	ion		
Specification of Platform	AUTOSAR_SWS_AdaptivePlatform		
Types for Adaptive Platform	Types		



Long Name	File Name	Life cycle changes	Draft Specification
General			
Design guidelines for using parallel processing technologies on Adaptive Platform	AUTOSAR_EXP_ParallelProcessin gGuidelines		
Explanation of Adaptive Platform Design	AUTOSAR_EXP_PlatformDesign		
Explanation of Safety Overview	AUTOSAR_EXP_SafetyOverview		
Functional Cluster	AUTOSAR_TR_FunctionalCluster		
Shortnames	Shortnames		
General Requirements specific to Adaptive Platform	AUTOSAR_RS_General		
General Specification of Adaptive Platform	AUTOSAR_SWS_General		
Guidelines for the use of the C++14 language in critical and safety-related systems	AUTOSAR_RS_CPP14Guidelines	obsolete	
Guidelines for using Adaptive Platform interfaces	AUTOSAR_EXP_AdaptivePlatform InterfacesGuidelines		
Specification of Core Types for Adaptive Platform	AUTOSAR_SWS_CoreTypes		
System Tests of Adaptive Platform	AUTOSAR_TR_AdaptivePlatform SystemTests		

All specifications contain requirements which are identified by special braces:

- [= Beginning of the requirement content
- | = End of the requirement content

In addition, all XML files and schemas are considered as requirements.



5 Summary of changes

This chapter contains a summary of changes which were implemented since the previous release.

- Regular maintenance of document.
- New Documents have been created and are released for the first time.
- Documents went through a major rework.

5.1 Release 18-10

In AUTOSAR R18-10 the Adaptive Platform has been elaborated further to harmonize with the Classic Platform.

Additionally the System Tests have been reworked to test the Adaptive Platform Demonstrator against the Requirements Specifications of the AUTOSAR Adaptive Platform.

Further improvements have been applied to all the specifications that are part of R18-10.

5.1.1 Concepts

The following concepts in 5.1.1.1 - 5.1.1.2 have been introduced.

5.1.1.1 Formal Model Query and Blueprint Derivation Mechanisms

The concept "Formal Model Query and Blueprint Derivation Mechanisms" is released as draft and will be validated in 2019.

The concept completes the extension of AUTOSAR Classic (CP) and Adaptive platforms (AP) with the AUTOSAR Model Query Language (ARMQL). This new language enables a highly efficient collaboration of AUTOSAR user due to resolving variation points in CP and AP by the same mechanism. It is published in textual form, not bound to a specific tool and significant better understandable as the existing Formula Language.

5.1.1.2 Extended Serialization for Data Structures in SOME/IP with tag/length/value encoding (TLV)

The concept TLV is released as draft and will be validated in 2019.

The concept adds support for improved forward and backward compatibility during evolution of interfaces on SOME/IP protocol-level. Moreover, the concept integrates support for optional struct members on protocol-level and application-level (RTE and ara::com).



5.1.2 Specifications

5.1.2.1 New Specifications

The following documents and templates were added to the R18-10:

- Specification of State Management (UID 908, SWS)
- Requirements of State Management (UID 909, RS)
- Explanation of Sensor Interfaces (UID 913, EXP)
- Guidelines for using Adaptive Platform interfaces (UID 929, EXP)
- Explanation of IPsec Implementation Guidelines (UID 930, EXP)
- Collection of blueprints for AUTOSAR Adaptive Platform models (UID 931, MOD)

5.1.2.2 Migrated Specifications

With this release, the following specifications were moved from Adaptive Platform to the Foundation standard:

 Requirements on Adaptive Network Management (UID 898, RS), merged with the new document Requirements on Network Management (UID 927, RS)

5.1.2.3 Obsolete Specifications

The following specification is set to status "obsolete" in this release:

· No specifications were set to "obsolete".

5.1.2.4 Cancelled Specifications

The following specification is canceled in this release:

No specifications were canceled.

5.1.3 Release Documentation

There were no major changes regarding the Release Documentation.



Additionally the System Tests have been reworked to test the Adaptive Platform Demonstrator against the Requirements Specifications of the AUTOSAR Adaptive Platform.

For the "Specification of Cryptography for Adaptive Platform" the prefix for specification items has changed from "SWS_CRYPTO_XXXXX" to "SWS_CRYPT_XXXXX" due to an overlap with the Classic Platform "Specification of Crypto Driver".

Further improvements have been applied to all the specifications that are part of R19-03.

5.2.1 Concepts

No Concepts have been introduced with AP R19-03.

5.2.2 Specifications

5.2.2.1 New Specifications

No new specifications have been introduced with AP R19-03.

5.2.2.2 Migrated Specifications

No specifications have been migrated with AP R19-03.

5.2.2.3 Obsolete Specifications

The following specification is set to status "obsolete" in this release:

 Guidelines for the use of the C++14 language in critical and safety-related systems (UID 839, RS). The work has been handed over to MISRA and the document will no longer be maintained by AUTOSAR.

5.2.2.4 Cancelled Specifications

No specifications were canceled.

5.2.3 Release Documentation

There were no major changes regarding the Release Documentation.



6 Remarks to known technical deficiencies

The technical deficiencies per specification are – if applicable – mentioned inside the respective specification in a chapter called "Known Limitations".

There are the following technical deficiencies which are not related to a particular specification: None

6.1 Release 18-10

6.1.1 Known technical deficiencies per document

Document Long	Known Limitations
Name Methodology for Adaptive Platform Specification of	The following sections are still under discussion: • Section 2.4.5 (Set up an initial Machine), • Section 2.4.6 (Create Software Packages) • Section 2.4.7 (Management and provision of Software Packages) • Local Buffer Overruns: Currently it is not specified what
Communication Management	 Local Burier Overruits. Currently it is not specified what happens if local buffers are full because the application accesses data slower than they are received over the network. The Signal to Service mapping in this specification does not contain behavior specification. The E2E communication protection works only for events which are polled and which are transmitted at least once per fault tolerant time interval. This means, it requires: Periodic invocation of the method Update in a polling mode Periodic or mixed-periodic invocation of the method Send In case Update or Send are not invoked periodically, then some communication failure modes are not detected (loss, delay and possibly also repetition). In this case, if E2E is used, then additional measures need to be taken at application level to address those non-detected failure modes. The values of some E2E parameters are defined by the standard and shall not be changed. Optional method arguments: The Specification does not support the existence of optional method arguments Some limitations apply for optional arguments introduced with the TLV serialization



Document Long Name	Known Limitations
Specification of Core Types for Adaptive Platform	 The specification of some data types (Array, Map, Optional, String, StringView, Variant) mentions "supporting constructs", but lacks a precise scope definition of this term. The specification of some data types (Map, Vector, String) is lacking a comprehensive definition of memory allocation behavior; it currently only describes it as "implementation-defined". Chapter 7 ("Functional Specification") describes some behavior informally that should rather be given as specification items.
Specification of Cryptography for Adaptive Platform	 The entire Crypto API is provisional and likely to be fully revised in the upcoming releases. The content was not updated for the current release.
Specification of Diagnostics	 It is probable that shared_ptr will change in an upcoming release.
Specification of Execution Management	 Support for Resource Limitation is not complete Support for Fault Tolerance (reacting to, and coping with errors in EM itself) is not complete Support for establishment of a Trusted Platform ([RS_EM_00014]) is not specified
Specification of Identity and Access Management	 The topic of providing identity information of Adaptive Applications to PEPs is still under discussion. Requirements and specification details regarding Application ID / Application Instance ID and providing application identity in general may be affected by this discussion and may change accordingly. There is no API specification available yet
Specification of Manifest	 The AUTOSAR SWS REST defines a low-level API for REST-based communication. The content of section 11, on the other hand, applies for the configuration of a not-yet standardized API on top of the ara::rest API.
Specification of Network Management	 Only supports UdpNM at the moment Does not allow node detection - Repeat Message State requests but handles incoming requests Cannot be configured as master network coordinator Does not support coordinated shutdown using information from CBV Does not support passive mode or passive startup Mapping of logical networks to BitVector positions (in the message) not available in the manifest New: User data cannot be accessed from applications in a standardized way – the service interface was moved as NM now interacts with SM instead of applications. User data has to be clarified for next release.



Document Long Name	Known Limitations
Specification of Operating System Interface	 There is currently no (sufficient) API providing periodic time-based processing to fulfill [RS_OSI_00102]. Authorized access to APIs is not supported [RS_OSI_00205, RS_OSI_00208].
Specification of Persistency	 The interpretation of deployment related information in the AUTOSAR model is not yet covered in detail in this specification. In addition, the concept of a roll-back after an update is not yet supported. The configuration of encryption for Persistency is not defined in Specification of Manifest.
Specification of Platform Health Management for Adaptive Platform	 Daisy chaining (i.e. forwarding Supervision Status, Checkpoint or Health channel information to an entity external to PHM or another PHM instance) is currently not supported in this document release. Platform Health Management configuration related to Supervision Modes is not fully supported in this document release. An API to inform Supervised Entities about the Supervision states is available only in polling mode. No API using notification mode is available in this release. Interface with the Diagnostic Manager is not specified in this release.
Specification of RESTful communication	 The interfaces are only specified to the point to make semantics clear The error handling for RESTful communication is currently limited due to the fact that errors are not reported in the context of a request transmission
Specification of State Management	 Section 7.3 on Component States are partially discussed and not finished yet. The RequestRestart and Communication Control for Diagnostic reasons is a proposal only and subject to change.
Specification of Time Synchronization for Adaptive Platform	 The Time Synchronization module is bound to Adaptive Platform Systems. For the TS, it is necessary that at least there is one TBR in the system, otherwise no functionality can be provided to the Adaptive Applications API design is not fully compliant to Adaptive Platform Design Rules which request the usage of UpperCamelCase.



Document Long Name	Known Limitations
System Tests of Adaptive Platform	 Test cases may not cover whole RS as specified against test cases Test setup figure may not exactly reflect the test configuration Test cases may not be fully covered by corresponding system test implementations System test cases are just examples, since there could be many ways to define and implement use case scenarios DIAG does not have any RS traceability, as it is intended to reuse WP-T results LT does not have any RS traceability. Traceability will be added in next release

6.2.1 Known technical deficiencies per document

Document Long Name	Known Limitations
Specification of Time Synchronization for Adaptive Platform	 The Time Synchronization (TS) module is bound to Adaptive Platform Systems For the TS, it is necessary that there is at least one Time Base Resource (TBR) in the system, otherwise no functionality can be provided to the Adaptive Applications (i.e. the Adaptive Applications would not get any handle for TBR). API design is not fully compliant to Adaptive Platform Design Rules which requests the usage of UpperCamelCase. The current concept on TimeSync is not in line with the port prototype approach. The topic on InstanceSpecifier is not yet finalized. Further changes to be expected in R19-11.
Specification of Identity and Access Management	 A detailed API will be added in a future release. For other Functional Clusters, implementation on Policy Enforcement Points are envisaged for the next release (R19-11). Currently limited to ara::com



Document Long	Known Limitations
Document Long Name Specification of Diagnostics	Chapter 7 Functional specification is not reworked for the experimentally introduced diagnostic interfaces of chapter 8.5 C++ Diagnostic API Interfaces OBD ISO 15031 and WWH OBD ISO 27145 is not supported by the DM. Software Cluster/Diagnostic Server instances are supported by DM interfaces but are not specified in detail. DoIP edge node is not supported by the DM. The following UDS services are not implemented by the DM: 0 0x23 ReadMemoryByAddress 0 0x24 ReadScalingDataByIdentifier 0 0x2C DynamicallyDefineDataIdentifier 0 0x2C DynamicallyDefineDataIdentifier 0 0x38 RequestFileTransfer 0 0x38 NequestFileTransfer 0 0x38 AccessTimingParameter 0 0x84 SecuredDataTransmission 0 0x87 LinkControl Sub-functions of UDS services are implemented according to ISO 14229-1 unless explicitly stated. The UDS mirror event memory is not supported by the DM. As a result of this, the DM does not support the UDS service. 0 0x19 with subfunction 0x0F (reportMirrorMemoryDTCByStatusMask) 0 0x19 with subfunction 0x10 (reportNirrorMemoryDTCByStatusAsk) 0 0x19 with subfunction 0x11 (reportNumberOfMirrorMemoryDTCByStatus-Mask) The OBDWWH OBD is not supported by the DM. As a result of this, the DM does not support the UDS service. 0 0x19 with subfunction 0x01 (reportNumberOfMirrorMemoryDTCByStatus-Mask) The OBDWWH OBD is not supported by the DM. As a result of this, the DM does not support the UDS service. 0 0x19 with subfunction 0x05 (reportDTCStoredDataByRecordNumber) 0 0x19 with subfunction 0x12 (reportNumberOfEmissionsOBDDTCByStatus-Mask) 0 0x19 with subfunction 0x13 (reportEmissionsOBDDTCByStatus-Mask)
	 (reportWWHOBDDTCWithPermanentStatus) Event Memory: Variant handling at runtime for events/DTCs is not supported. Event Memory: Details for combined events are not specified. Event Memory: Event displacement is not supported. The DM
	 stores for each DTC related data. Event Memory: Interface to read the number of event memory entries is not supported.



Document Long Name	Known Limitations
	 Event Memory: Internal configuration parameters and DM values as extended data are not supported. Persistent Storage of failed attempts to change security level: After each increment of the attempt counter, it shall be persisted to survive accidental or intended resets. Here the option to select the persistent storage is mandatory in Adaptive Autosar.
Specification of Cryptography for Adaptive Platform	The current version of this document is missing some functionality that is available in the AUTOSAR Classic Platform: • Secure Counter: There is currently no API available to access secure counter primitives that an implementation may provide.
	 The following functional domains and descriptions are still missing in the current version of Crypto API specification: Asynchronous interfaces: Currently there is only a synchronous API specification and asynchronous behavior (if required) should be implemented on the consumer application level. It can be done via utilization of dedicated execution threads for long-time operations. X.509 certificates support: Crypto API doesn't provide complete specification of the X.509 certificates management on the client (ECU) side yet. Current version of Crypto API specifies only minimal subset of interfaces responsible for basic X.509 functionality and related on utilization of cryptographic algorithms. Current API supports extraction and parsing of only basic attributes of X.509 certificates and certification requests. An extension of the API specification by additional interfaces dedicated for complete support of X.509 extensions is planned for the next release of this specification. Note: Generally current specification of the X.509 Provider API is preliminary and subject for extensions and changes. Memory management: In the current version of the specification Crypto Provider supports the safety-aligned memory management concept suitable for real-time applications. Up to the next release this concept will be extended for X.509 Provider too. Application of any memory management mechanisms specific for support of asynchronous calls (like std::future) is in scope a developer responsibility.



Document Long Name	Known Limitations
	 Formats of cryptographic objects: Current version of Crypto API has minimal support of well-known cryptographic formats encoding/decoding: support of only DER and PEM encoding for X.509 certificates and certificate signing requests is required from any implementation of Crypto API. For other cryptographic objects an implementation can support only "raw" formats. Following extension of the Crypto API by unified interfaces for encoding/decoding of complex objects to standard formats is planned for the next release of this specification. Key slots modeling: Now Crypto API defines some structures that should be produced as a result of the key slots modeling process. But the whole concept of the key slots modeling is not finished yet. Therefore Key Storage API can be updated slightly for next release in order to extend support of the ara::core::InstanceSpecifier type as one of mechanisms for the Logical Key Slot identification. Functional specification: Detailed functional specification (chapter 7) is not available yet and will be elaborated for next Autosar AP release. Depth of inheritance: The performance of the inheritance tree design applied for the Crypto Provider interfaces is still subject to further investigation. Therefore a redesign of APIs defined in namespace ara::crypto::cryp may be executed for next Autosar release, in order to achieve a very limited inheritance depth (or completely "flattened" API design).
Requirements on Execution Management	 The following requirements are described within this document but not otherwise considered in this release: [RS_EM_00050] – System-wide coordination [RS_EM_00051] – External trigger conditions [RS_EM_00011] – Identification of Processes [RS_EM_00014] – Trusted Platform. The functionality described above is subject to modification and will be considered for inclusion in a future release of this document.
Requirements on Operating System Interface	The following requirements are described within this document but not otherwise considered in this release: [RS_OSI_00204] [RS_OSI_00208] The functionality described above is subject to modification and will be considered for inclusion in a future release of this document.



Document Long Name	Known Limitations
Specification of Communication Management	The current version of this document is missing some functionality which is not standardized and specified within the SWS Communication Management document but described in Explanation of ara::com API [1] and implemented in the demonstrator code: Local Buffer Overruns: Currently it is not specified what happens if local buffers are full because the application accesses data slower than they are received over the network. The Signal to Service mapping in this specification does not contain behavior specification. The E2E communication protection works only for events which are polled and which are transmitted at least once per fault tolerant time interval. This means, it requires: Periodic invocation of the method GetNewSamples (see [SWS_CM_0701]) in a polling mode Periodic or mixed-periodic invocation of the method Send (see [SWS_CM_00162] and [SWS_CM_90437]) In case GetNewSamples or Send are not invoked periodically, then some communication failure modes are not detected (loss, delay and possibly also repetition). In this case, if E2E is used, then additional measures need to be taken at application level to address those non-detected failure modes. The values of the following E2E parameters are defined by the standard and shall not be changed. See E2E Protocol Specification. dataldMode counterOffset crcOffset dataldNibbleOffset offset EndToEndTransformationComSpecProps are not supported. The following limitations regarding optionality introduced with the Tag-Length-Value serialization principle described in SOME/IP Protocol Specification and Specification of Manifest apply: Optional method arguments: The Specification does not
	 Optional method arguments: The Specification does not support the existence of optional method arguments.



Document Long Name	Known Limitations
Specification of Execution Management	 The following functionality is mentioned within this document but is not fully specified in this release: Section 7.7 Resource Limitation and Section 7.8 Fault Tolerance – these sections have been expanded in this release but are not complete. In particular the contents will be expanded with more properties and formal requirements in the next release. The following functionality is not specified in this release: Support of a Trusted Platform ([RS_EM_00014]). Section 6.1 details requirements from Execution Management Requirement Specification [1] that are not elaborated within this specification. The presence of these requirements in this document ensures that the requirement tracing is complete and also provides an indication of how Execution Management will evolve in future releases of the AUTOSAR Adaptive Platform. The functionality described above is subject to modification and will be considered for inclusion in a future release of this document.
Specification of Log and Trace	The provided Logging framework API is designed to be independent from the underlying Logging back-end implementation and as such doesn't impose limitations.
Specification of Operating System Interface	 The following functionality is mentioned within this document but is not fully specified in this release: The currently known limitations are the requirements in Requirements on Operating System Interface which are listed within Appendix A. There is currently no sufficient API providing periodic time-based processing to fulfill [RS_OSI_00102]. This will be defined in a future release.
Specification of Persistency	The configuration of encryption for Persistency is not defined in Specification of Manifest.
Specification of Platform Health Management for Adaptive Platform	 [SWS_PHM_00110] Daisy chaining (i.e. forwarding Supervision Status, Checkpoint or Health channel information to an entity external to PHM or another PHM instance) is currently not supported in this document release. (RS_PHM_00108, RS_PHM_00109) [SWS_PHM_00111] Platform Health Management configuration related to Supervision Modes is not fully supported in this document release. (RS_PHM_00104, RS_HM_09253) [SWS_PHM_00112] An API to inform Supervised Entities about the Supervision states is available only in polling mode. No API using notification mode is available in this release. (RS_HM_09237) Interface with the Diagnostic Manager is not specified in this release.



Document Long Name	Known Limitations
Specification of RESTful communication	The interfaces are only specified to the point to make semantics clear. To be precise this document does not yet fully specify the qualification C++ functions noexcept, overloading of functions to provide move semantics for optimization purposes nor does it claim to be const-correct. Move semantics in particular are specified where required for semantic correctness only. Also only HTTP network binding aspects of the AUTOSAR meta model are currently supported by the SWS_REST. No modeling of the Rest-ServiceInterface internal structure is possible with the current SWS_REST. The error handling for RESTful communication is currently limited due to the fact that errors are not reported in the context of a request transmission.
Specification of Network Management	 The Adaptive Network Management currently only supports UdpNM. The Adaptive Network Management does not allow node detection (Repeat Message State) but only handles incoming requests. The Adaptive Network Management cannot be configured as the master network coordinator. The Adaptive Network Management does not support coordinated shutdown using the information in CBV. The Adaptive Network Management does not support passive mode and passive startup. Passive start-up would mean that a node has started (i.e. goes to Normal mode), but the network has been woken up by another node. Modeling part for mapping the logical networks to the BitVector positions as defined in chapter 7.3 is not available in the manifest. Update and access of User Data was removed as the service interface to Applications has been removed. State Management will control the network request/release and it must be clarified if user data changes/indications shall be done via State
Specification of State Management	 Management or directly by applications. The following functionality is mentioned within this document but is not (fully) specified in this release: Section 7.2 This document will show the basic principles of the intended functionality of State Management. To enable State Management to be portable, in future versions of this document standardized fields and values shall be introduced. Section 7.3 Communication Control for Diagnostic reasons this is not yet discussed with Adaptive Diagnostics. Section 7.3 RequestRestart for Diagnostic reasons this is discussed with Adaptive Diagnostics, but some interface details are not yet finalized.



Document Long	Known Limitations
Specification of Update and Configuration Management	 UCM is not responsible to initiate the update process. UCM realizes a service interface to achieve this operation. The user of this service interface is responsible to verify that the vehicle is in a safe state before executing a software update procedure on demand. It is also in the responsibility of the user to communicate with other AUTOSAR Adaptive Platforms or AUTOSAR Classic Platforms within the vehicle. Therefore management of software dependencies between different physical or virtual ECU software platforms is currently out of UCM's scope but will be managed by the UCM Master which will be introduced in the next release. The UCM receives a locally available software package for processing. The software package is usually downloaded from the OEM backend. The download of the software packages has to be done by another application, i.e. UCM does not manage the connection to the OEM backend. Prior to triggering their processing, the software packages have to be transferred to UCM by using the provided ara::com interface. The UCM update process is designed to cover updates on use case with single AUTOSAR Adaptive Platform. UCM can update Adaptive Applications, the AUTOSAR Adaptive Platform itself, including all functional clusters and the underlying OS. Distinction between different types of updates, such as safety critical updates vs infotainment updates, isn't addressed in this release. Currently such distinction shall be included into vendor specific meta-data. The UCM is not responsible for enforcing authentication and access control to the provided interfaces. The document currently does not provide any mechanism for the confidentiality protection as well as measures against denial of service attacks. The assumption is that the platform preserves the
Specification of Core Types for Adaptive Platform	 integrity of parameters exchanged between UCM and its user. The specification of Promise misses the specializations for void> and <t&> that std::promise defines.</t&> The specification lacks comparison operators for class ErrorCode. The specification of class Result uses an insufficient conditional noexcept classifier that does not consider the properties of the <e> type.</e> The specification of some data types (Array, Map, Optional, String, StringView, Variant) mentions "supporting constructs", but lacks a precise scope definition of this term. The specification of some data types (Map, Vector, String) is lacking a comprehensive definition of memory allocation behavior; it currently only describes it as "implementation-defined". Chapter 7 ("Functional Specification") describes some behavior informally that should rather be given as specification items.



Document Long Name	Known Limitations
System Tests of Adaptive Platform	 Test cases may not cover whole RS specifications as specified against test cases Test setup figure may not exactly reflect the test configuration Test cases may not be fully covered by corresponding system test implementations System test cases are just examples, since there could be many ways to define and implement use case scenarios DIAG does not have any RS traceability, as it is intended to reuse WP-T results LT does not have any RS traceability. Traceability will be added in next release In the E2E test case, the common parts of the E2E profiles are checked
Specification of Manifest	The AUTOSAR SWS REST defines a low-level API for REST-based communication. The content of section 11, on the other hand, applies for the configuration of a not-yet standardized API on top of the ara::rest API.
Methodology for Adaptive Platform	The sections related to the deployment of Software Packages, i.e., Section 2.4.5 (Set up an initial Machine), Section 2.4.6 (Create Software Packages) and Section 2.4.7 (Management and provision of Software Packages), are still under discussion.



7 Release history

7.1 Release 18-10

Release R18-10 was originally released on the 31st of October 2018.

Name	Specification history entry
Design guidelines for using parallel processing technologies on Adaptive Platform	Minor changes
Explanation of Adaptive Platform Design	Changes to reflect the latest SWS contents
Explanation of ara::com API	 Added InstanceIdentifier and InstanceSpecifier explanation Restructured chapter structure Adapt FindService signatures Added sample code for event usage Restructured chapter structure Proxy and skeleton instances are not copyable Changed certain data types to ara::core namespace. Adapted to new error handling based on ara::core::ErrorCode
Explanation of Automated Driving Interfaces	Initial release
Explanation of Ipsec Implementation Guidelines	Initial release
Explanation of Safety Overview	 Restructuring of document inspired by ISO 26262 Rework chapters 1-5 Add functional safety requirements table
Functional Cluster Shortnames	Renaming of Identity and Access Management, Operating System Interface, Update and Configuration Management
General Requirements specific to Adaptive Platform	 More details to clause 1 Scope of document given Former chapter 4.3 on Design requirements putted below chapter 4.2 Non-functional requirements Following requirements have been revised: [RS_AP_00111], [RS_AP_00113], [RS_AP_00114], [RS_AP_00115], [RS_AP_00122], [RS_AP_00120], [RS_AP_00121], [RS_AP_00124], [RS_AP_00125] Following requirements have been deleted: [RS_AP_00117], [RS_AP_00118] Following requirements have been added: [RS_AP_00127], [RS_AP_00128], [RS_AP_00129], [RS_AP_00130],
General Specification of	[RS_AP_00131], [RS_AP_00132], [RS_AP_00134] • SWS AP 00003 removed since there is no demand in
Adaptive Platform	RS_AP_00003 which requires it anymore
Guidelines for the use of the C++14 language in critical and safety-related systems	 Added traceability for ISO 26262 (B.6) New rules resulting from continued analysis of the C++ Core Guideline Finished addressing MISRA review comments of the 2017-03 release Improvements of already existing rules, more details in the
	Changelog (D.3) • Marked the specification as obsolete



Name	Specification history entry
Guidelines for using Adaptive Platform interfaces	Initial release
Methodology for Adaptive Platform	 Renamed Application Manifest to Execution Manifest Moved references from spec.item body to foot notes Editorial changes
Requirement on Time Synchronization for Adaptive Platform	Minor changes and bugfixesEditorial changes
Requirements of State Management	Initial release
Requirements on Communication Management	Minor changes and bugfixes
Requirements on Cryptography	Removed: [RS_CRYPTO_02303] and [RS_CRYPTO_02402]Updated: [RS_CRYPTO_02006]
Requirements on Execution Management	 Removed: RS_EM_00003, RS_EM_00004, RS_EM_00110 and RS_EM_00111. Added: [RS_EM_00014]
Requirements on Identity and Access Management	 Functional Description of Capabilities Functional Description of Access Control for Inter-Platform Communication Requirement for Superset Manifests
Requirements on Manifest Specification	Minor corrections / clarifications / editorial changes; For details please refer to the ChangeDocumentation in AUTOSAR_RS_ManifestSpecification
Requirements on Operating System Interface	 Removed: RS_OSI_00102 and RS_OSI_00105 Added: [RS_OSI_00207], [RS_OSI_00208].
Requirements on Persistency	 Restructured document Added resource handling Added UCM related requirements
Requirements on Platform Health Management for Adaptive Platform	minor corrections / clarifications / editorial changes
Requirements on Security Management for Adaptive Platform	Chapter 2.3 'Protected Runtime Environment' revised
Requirements on Update and Configuration Management	 Requirements on Operating System updates Requirement on Security Requirement on History
Specification of Communication Management	 Introduced Adaptive Core types Introduced exception-less API Refined DDS network binding Minor changes and bugfixes



Name	Specification history entry
Specification of Core	Add chapter 2 with acronyms
Types for Adaptive	 Add chapter 2 with acronyms Add chapter 4 with limitations of the current specifications
Platform	
	Add chapter 5 with dependencies to other modules
	Add chapter 7 Add classes as a second of the control of the
	Add classes representing the approach to error handling to
	chapter 8
	Adapt classes Future and Promise to the error handling
	approach
	 Add global functions for initialization and shutdown of the framework
	 Add class InstanceSpecifier to chapter 8
	Add more types and functions from the C++ standard
Specification of	
Cryptography for Adaptive	No changes
Platform	
Specification of	Diagnostic Protocol replaced by Diagnostic Conversations
Diagnostics	ResponseOnEvent, CommunicationControl, EcuReset added
3	Chapter 7 overall rework and updates
	 Chapter 7 overall rework and updates Chapter 8 split into chapter 8 (C++ API) and chapter 9 (Service
	Interfaces)
Specification of Execution	Refinement of Deterministic Execution
Management	Updated Process lifecycle to clarify
3	Process and Execution States
	Updated Application Recovery Actions
Specification of Identity	Reworked functional specification
and	Removed API specification for general rework
Access Management	Tremoved Att appealment for general rewark
Specification of Log and	Changed initialization APIs
Trace	Improved references
	Log file definition
Specification of Manifest	Finish introduction of CppImplementationDataType
•	Support for optional elements in structures
	Rework configuration of adaptive platform modules
Specification of Network	Updated interaction with State Management
Management	 Removed APIs and Services (interaction is done via SM)
	Temporary removed user data access to applications
Specification of Operating	Add Resource Control
System Interface	 Added Shared object support
Specification of	Introduction of ara::core types and switch to exceptionless API
Persistency	Rework of redundancy approach
- -	Support for resource limitation
	Improvements and harmonization of KeyValueStorage and
	FileProxy API
Specification of Platform	Described the interfaces with functional clusters execution
Health Management for	management and state management
Adaptive Platform	•
Specification of Platform	Rework to CppImplementationDataTypes
Types for Adaptive	
Platform	
Specification of RESTful	 Updated APIs to use ara::core types
communication	Minor editorial fixes
Specification of State	Initial release
Management	



Name	Specification history entry
Specification of Time Synchronization for Adaptive Platform	Minor changes and bugfixesEditorial changes
Specification of Update and Configuration Management	 Updated interaction other functional clusters like PER and EMO/SM Introduction of vehicle package distribution
System Tests of Adaptive Platform	 Added RS traceability for test cases Added ISO 9646 framework and mapping on system test architecture Added more test cases for CM, REST, EMO, and UCM

Release R19-03 was originally released on the 29th of March 2019.

Name	Specification history entry
Adaptive Platform	Updated according to R19-03
Release Overview	, , , , , , , , , , , , , , , , , , ,
Design guidelines for	Minor changes
using parallel	
processing technologies	
on Adaptive Platform	
Explanation of Adaptive	Changes to reflect the latest SWS contents. Chapter 17.4 C++
Platform Design	coding guidelines deleted.
Explanation of ara::com	Changed explanation of Event reception due to new ara::com
API	API
Explanation of IPsec	No changes
Implementation	
Guidelines	
Explanation of Safety	No content changes
Overview	minor layout changes
Explanation of Sensor	No content changes
Interfaces	
Functional Cluster	No content changes
Shortnames	
General Requirements	No content changes
specific to Adaptive	
Platform	
General Specification of	No content changes
Adaptive Platform	
Guidelines for the use of	Added the obsolete statement
the C++14 language in	
critical and safety-	
related systems	
Guidelines for using	Clause 4 revised to reflect the updated design on State
Adaptive Platform	Management
interfaces	
Methodology for	No content changes
Adaptive Platform	



Name	Specification history entry
Requirement on Time Synchronization for Adaptive Platform	No content changes
Requirements of State Management	Updated requirements due to reworked intended design
Requirements on Communication Management	No content changes
Requirements on Cryptography	 Editorial changes and rephrasing Improved requirements description and rationale (Updated: [RS_CRYPTO_02001] [RS_CRYPTO_02002] [RS_CRYPTO_02003] [RS_CRYPTO_02004] [RS_CRYPTO_02005] [RS_CRYPTO_02007] [RS_CRYPTO_02009] [RS_CRYPTO_02109] [RS_CRYPTO_02116] [RS_CRYPTO_02202] [RS_CRYPTO_02206])
Requirements on Execution Management	Updated: RS_EM_00008 and RS_EM_00010
Requirements on Identity and Access Management	Introduction of Grant concept
Requirements on Manifest Specification	editorial changes
Requirements on Operating System Interface	Added: use case for [RS_OSI_00201] and [RS_OSI_00202]
Requirements on Persistency	 Updated introduction Information on wear leveling Finalization was removed
Requirements on Platform Health Management for Adaptive Platform	removed references to RS_Main_00330
Requirements on Security Management for Adaptive Platform	Unnecessary requirement [RS SEC 05006] removed
Requirements on Update and Configuration Management	 Spelling fixes Minor explanation improvements
Specification for Network Management	 Introduced Service Interface for interaction via SM Introduced possibility to group PNCs/Channels/VLANs



Name	Specification history entry
Specification of	Predictable Resource Allocation for Samples
Communication	Usage of Future::Get/Wait with an unreliable transport
	Removed exceptions on reception of malformed messages
Management	Changes to Identity and Access Management to incorporate
	Grant design
	Minor changes and bugfixes
Specification of Core	 Add specification of the template specialization Result<void, e=""></void,>
Types for Adaptive	Add specification of the template specialization result void, L
Platform	
	Discretil and five of Courts ADI is necessary to be access or access to a signal
Specification of	Direct" prefix of Crypto API is removed, because now it is single All burse found after PAR 02 are fixed.
Cryptography for	All bugs found after R18-03 are fixed
Adaptive Platform	Crypto API is converted for usage of basic ara::core types
	Crypto API is converted for support of the "Exception-less"
Charification of	approach
Specification of	Document quality improvement and fixing bugs Introduced ara::diag interfaces in draft state
Diagnostics	Introduced ara::diag interfaces in draft state
Specification of	Refinement of State Management semantics
Execution Management	Document structure modified to reflect current template
Specification of Identity	Reworked chapter 7 to incorporate new concept of Grants
and Access	 Incorporation of several bug tickets
Management	
Specification of Log and	 Changed APIs (Logstream, Logmanager, Logging)
Trace	 Refactoring and editorial changes
Specification of Manifest	Introduction of Diagnostic Port Interfaces
	 Overhaul of Software Cluster and introduction of Software
	Package
	 Support for Identity and Access Management
	 Network Management Configuration
Specification of	 Clarified that PSE51 following POSIX-1003.1-2003 is the
Operating System	currently-targeted version.
Interface	 Minor changes in tracing, clean up
Charification of	Improved naming of alcohool/mathoda/functions
Specification of	Improved naming of classes/methods/functions Powerland installation/undeta
Persistency	Reworked installation/updateSupport for parallel execution in multiple threads
	· · · · · · · · · · · · · · · · · · ·
Specification of Platform	Cleaned up usage of ara::core concepts Modified the ADI for Supervised Entity and Health Channel The Country of the Channel The
	 Modified the API for Supervised Entity and Health Channel Modified the interface with the Execution Manager
Health Management for	• Modified the interface with the Execution Manager
Adaptive Platform	minor corrections / clarifications / aditorial changes
Specification of Platform	 minor corrections / clarifications / editorial changes
Types for Adaptive	
Platform	No control di conce
Specification of RESTful	No content changes
communication	
Specification of State	Removed components
Management	RequestState and ReleaseRequest are now deprecated
	State Managements internal states can now be influenced by
	"Trigger" and are distributed by "Notifier" fields
Consideration of Time	Eupational description detected from setual ADI
Specification of Time	Functional description detached from actual API Improved resource discovery
Synchronization for	Improved resource discovery
Adaptive Platform	



Name	Specification history entry
Specification of Update	Updating Package Management state machine
and Configuration	New requirements for robustness against reset
Management	Improving specification item atomicity
	Fixing errors in chapter Service Interfaces
Supplementary material of the AUTOSAR XML Schema	Updated according to R19-03
System Tests of	Changed format for RS traceability items
Adaptive Platform	Added new section and test cases for Time Synchronization
-	 Added more test cases for CM, EMO, and DIAG



8 Appendix

8.1 Definitions

8.1.1 Release number

AUTOSAR applies a four-digit numbering scheme Ryy-mm to identify releases.

yy = yearmm = month

8.1.2 Specification item and requirement life cycle states

The life cycle state of a specification item is found after the specification item ID surrounded by curly brackets. The states are:

- Valid: This indicates that the related entity is a valid part of the document.
- **Draft:** This indicates that the related entity is newly introduced but still experimental. This information is published but is subject to change without backward compatibility guarantee. This is the default for Adaptive Platform.
- **Obsolete:** This indicates that the related entity is obsolete and will be removed in the next release.

If there is no life cycle state information stated then the state is Draft.

Requirements: The requirement attribute "type" indicates the life cycle state of the requirement. The states are the same as the specification item states.