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Date	Release	Changed by	Description
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		Management	
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		Management	
2017-12-08	1.3.0	AUTOSAR Release	Updated according to Release 1.3.0
		Management	
2017-10-27	1.2.0	AUTOSAR Release	Updated according to Release 1.2.0
		Management	
2017-03-31	1.1.0	AUTOSAR Release	Updated according to Release 1.1.0
		Management	
2016-11-30	1.0.0	AUTOSAR Release	Initial release
		Management	



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### 1 Introduction

## 1.1 Scope of this document

This document provides an overview of the complement of AUTOSAR specifications of the AUTOSAR standard "Foundation" comprising the initial Release 1.5.0 and its latest Revision.

#### 1.2 AUTOSAR standards

#### 1.2.1 Introduction

AUTOSAR addresses with its standards a wide range of use cases in automotive software development. These use cases have different requirements and lead to different technical solutions.

Packaging its deliverables into different "standards"

- eases the access to AUTOSAR solutions for users
- allows AUTOSAR to scale with market needs

#### 1.2.2 Definition

An AUTOSAR standard is a consistent set of AUTOSAR deliverables, which are released at the same time. AUTOSAR deliverables can, but are not limited to be of the following kinds:

- textual explanations
- textual specifications
- test specification
- source code
- other formal or semi-formal textual formats (e.g. ARXML, UML models, XML Schemata)

Each AUTOSAR Standard has its own release schedule. At the time of release, AUTOSAR ensures that the dependencies are fulfilled when a standard depends on another.

#### 1.2.3 Overview on AUTOSAR's standards

AUTOSAR delivers the following standards:

Cluster / Standard	Abbreviation
Classic Platform	СР
Adaptive Platform	AP
Foundation	FO



#### 1.2.3.1 Foundation

The purpose of the Foundation standard is to enforce interoperability between the AUTOSAR platforms.

Foundation contains common requirements and technical specifications (e.g. protocols) shared between the AUTOSAR platforms.

#### 1.2.3.2 Classic Platform

The Classic Platform is AUTOSAR's solution for embedded systems with hard real-time and safety constraints.

#### 1.2.3.3 Adaptive Platform

The Adaptive Platform is AUTOSAR's solution for high-performance computing ECUs to build safety-related systems for use cases such as highly automated and autonomous driving.

#### 1.2.4 Dependencies between Standards

Each release of Classic and Adaptive Platform relies on a dedicated version of Foundation. The specific dependency is documented in the release overview of the respective standard.

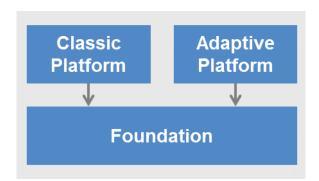


Figure 1: Dependencies of AUTOSAR Standards

# 1.2.5 Overview of AUTOSAR schema versions and corresponding valid AUTOSAR releases

Schema Version	Classic Platform Release	Adaptive Platform Release
AUTOSAR_00042	R 4.3.0	17-03
AUTOSAR_00043	R 4.3.0	17-10
AUTOSAR_00044	R 4.3.1	17-10
AUTOSAR_00045	R 4.3.1	18-03
AUTOSAR_00046	R 4.4.0	18-10



## 1.3 Content of chapters

This document is structured as follows:

- Chapter 2 provides a list of documentation references.
- Chapter 3 contains the overview of specifications comprising the AUTOSAR Foundation Release 1.5.0 in its latest Revision. This chapter is structured according to the clusters being in use in AUTOSAR Foundation Release 1.5.0.
- Chapter 4 provides a summary of changes e.g. in case a document has been migrated from another standard like the Classic Platform.
- Chapter 5 contains remarks about known technical deficiencies.
- Chapter 6 contains the detailed revision history of all released specifications.
- Chapter 7.1 provides a set of definitions aimed to increase the understanding of the content of this document and the AUTOSAR Foundation Release 1.5.0.



# 2 Related documentation

- 1) AUTOSAR specifications in general
- 2) Glossary



# 3 Specification overview

The published specifications are divided into the following clusters:

- Release Documentation
- General
- Diagnostics
- Methodology and Templates
- Communication Management
- Health Monitoring
- Protocols

The assignment of the specifications to those clusters is shown below.

Long Name	File Name	Life cycle changes	Draft Specification
Release Documentation		Changes	Specification
Foundation Release	AUTOSAR_TR_FoundationRel		
Overview	easeOverview		
AUTOSAR Foundation	AUTOSAR_TR_FoundationSpe		
Specification Hashes	cificationHashes		
<b>Communication Management</b>			
Requirements on	AUTOSAR_RS_NetworkManag	Initial	
AUTOSAR Network	ement	release	
Management			
Requirements on E2E	AUTOSAR_RS_E2E		
Requirements on Log and	AUTOSAR_RS_LogAndTrace		
Trace			
Requirements	AUTOSAR_RS_FoundationDeb	Initial	
Requirements on Tracing	ugTraceProfile	release	
and Timing-Analysis			
support of AUTOSAR			
Components			
Diagnostics			
Requirements on	AUTOSAR_SRS_Diagnostics		
Diagnostics			
Methodology and Templates			
Requirements on	AUTOSAR_RS_Methodology		
Methodology			
Health Monitoring			
Requirements on Health	AUTOSAR_RS_HealthMonitori		Х
Monitoring	ng		
Specification of Health	AUTOSAR_SWS_HealthMonito		X
Monitoring	ring		
General			



Long Name	File Name	Life cycle changes	Draft Specification
Explanation of Foundation	AUTOSAR_EXP_FoundationDi	changes	Specification
Diagram Source			
Glossary	AUTOSAR_TR_Glossary		
Main Requirements	AUTOSAR_RS_Main		
Project Objectives	AUTOSAR_RS_ProjectObjectives		
Protocols	100		
E2E Protocol Specification	AUTOSAR PRS E2EProtocol		
Log and Trace Protocol Specification	AUTOSAR_PRS_LogAndTrace Protocol		
Requirements on SOME/IP	AUTOSAR_RS_SOMEIPProtoc		
Protocol	ol		
Requirements on SOME/IP	AUTOSAR_RS_SOMEIPServic		
Service Discovery Protocol	eDiscoveryProtocol		
Requirements on Time	AUTOSAR_RS_TimeSync	Initial	
Synchronization		release	
SOME/IP Protocol	AUTOSAR_PRS_SOMEIPProt		
Specification	ocol		
SOME/IP Service	AUTOSAR_PRS_SOMEIPServi		
Discovery Protocol	ceDiscoveryProtocol		
Specification			
Specification of the	AUTOSAR_PRS_NetworkMana	Initial	
AUTOSAR Network	gementProtocol	release	
Management Protocol			
Time Synchronization	AUTOSAR_PRS_TimeSyncPro	Initial	
Protocol Specification	tocol	release	
E2E Protocol Specification	AUTOSAR_PRS_E2EProtocol		
Log and Trace Protocol	AUTOSAR_PRS_LogAndTrace		
Specification	Protocol		
Requirements on SOME/IP	AUTOSAR_RS_SOMEIPProtoc		
Protocol	ol		
Requirements on SOME/IP	AUTOSAR_RS_SOMEIPServic		
Service Discovery Protocol	eDiscoveryProtocol		
Requirements on Time	AUTOSAR_RS_TimeSync		
Synchronization	_		
SOME/IP Protocol	AUTOSAR_PRS_SOMEIPProt		
Specification	ocol		



## 4 Summary of changes

This chapter contains a summary of changes which were implemented. This can have the following sources:

- Regular maintenance of document
- Documents have been migrated from the Classic Platform or Adaptive Platform to the Foundation
- New documents have been created and are first time released
- Documents went through a major rework

#### 4.1 Release 1.5.0

The purpose of the Foundation standard is to enforce interoperability between the AUTOSAR platforms and therefore contains common requirements and technical specifications (e.g. protocols) shared between the AUTOSAR platforms.

With the current release, this goal has been pursued once more. Especially in the technical fields of end-to-end communication protection, network management and time synchronization via communication busses progress has been made towards harmonization between Classic and Adaptive Platform.

#### 4.1.1 Concepts

#### 4.1.1.1 Introduced Concepts

The following concepts in 4.1.1.1.1 have been introduced.

# 4.1.1.1 Extended Serialization for Data Structures in SOME/IP with tag/length/value encoding (TLV)

The concept TLV is released as draft and will be validated in 2019.

The concept adds support for improved forward and backward compatibility during evolution of interfaces on SOME/IP protocol-level. Moreover, the concept integrates support for optional struct members on protocol-level and application-level (RTE and ara::com).

#### 4.1.1.1.2 AUTOSARRunTimeInterface

The concept "AUTOSARRunTimeInterface" is released as draft and will be validated in 2019.

The concept "ARTI" defines an interface between build tools and debugging/tracing tools to the AUTOSAR standard. It defines standardized hooks that AUTOSAR components shall contain and also defines a model to export information about the internal representation of the components to ease debugging and tracing.



#### 4.1.1.1.3 SecurityExtensions

The concept adds important security controls to the AUTOSAR framework which support the efficient implementation of secure automotive systems.

The extensions include secure logging, vehicle key and certificate management, authentic time and diagnostic policy management.

#### 4.1.2 Specifications

#### 4.1.2.1 New Specifications

- Requirements on Time Synchroinzation (UID 906, RS)
- Time Synchronization Protocol Specification (UID 897, PRS)
- Requirements on Network Management (UID 927, RS)
- Specification of the AUTOSAR Network Management Protocol (UID 928, PRS)
- Requirements on Debugging, Tracing and Profiling support of AUTOSAR Components (UID 915, RS)

#### 4.1.2.2 Migrated Specifications

With this release, the following specifications were moved from Adaptive Platform to the Foundation standard:

 Requirements on Adaptive Network Management (UID 898, RS), merged with the new document Requirements on Network Management (UID 927, RS)

With this release, the following specifications were moved from Classic Platform to the Foundation standard:

 Requirements on Synchronized Time-Base Manager (UID 420, SRS), merged with the new document Requirements on Time Synchronization (UID 906, RS)

#### 4.1.2.3 Obsolete Specifications

The following specification is set to status "obsolete" in this release:

none

#### 4.1.2.4 Draft Specification

The status of the following specifications are set to "draft" in this release:

- Requirements on Health Monitoring (UID 878, RS)
- Specification of Health Monitoring (UID 850, SWS)

#### 4.1.3 Release Documentation

There were no major changes regarding the Release Documentation.



#### 5 Remarks to known technical deficiencies

The technical deficiencies per specification are – if applicable – mentioned inside the respective specification in a chapter called "Known Limitations" which is located after the table of contents.

There are the following technical deficiencies to be mentioned which are not related to a specific specification:

none

## 5.1 Known technical deficiencies per document

- E2E Protocol Specification (UID 849, PRS): E2E communication protection is limited to periodic or semi-periodic data communication paradigm, where the receiver (subscriber) has an expectancy on the regular reception of data and in case of communication loss/timeout or error, performs an error handling. Data communication is called sender/receiver in Classic Platform, and it is called event communication in Adaptive Platform.
  Note that the word event is a bit confusing as a periodic communication is required. This means, a protection of client-server (methods) as well as non-periodic data communication (e.g. transmission only on occurrence of a specific event) are not supported by E2E communication protection.
- Requirements on Health Monitoring (UID 878, RS) is set back to status "draft" and Specification of Health Monitoring (UID 850, SWS) is set to status "draft" with the initial release. Both specifications currently only describe the Adaptive Platform part and are therefore treated like Adaptive Platform specifications which are not handled with the AUTOSAR Change Management Process for Foundation. A clear separation between the documents in all three standards, Classic Platform, Adaptive Platform and Foundation is foreseen in the upcoming releases AP R19-10, CP R4.5.0 and FO R1.6.0.



# 6 Revision history

### 6.1 Release 1.5.0

Revision 0 of Release 1.5.0 has been released on the 31<sup>st</sup> of October 2018. The following deliverables had major changes.

Name	Specification history entry
E2E Protocol Specification	<ul> <li>Migrated all functional specifications from Classic Platform's SWS E2ELibrary into Foundation's E2E Protocol Specification</li> <li>Moved all figures and tables out of specifications and added references to them</li> <li>Fixed duplicate/missing figures in profiles 2 (Calculate DeltaCounter), 5 (Read CRC), 6 (Read Counter) and 11 (Read DataIDNibble).</li> <li>Added protocol examples for each profile</li> </ul>
Glossary	Extended abbreviations  Added terms:  AUTOSAR Run-Time Interface  Bus Mirroring  Cluster  Executable Entity Cluster  Execution Order Constraint  Execution Time  LIN Bus Idle  Log and Trace  Logical Execution Time  Mappable Element  Security Event  Synchronization Points  Timed Communication
	<ul> <li>Changed OSEK references</li> <li>Incorporated concepts as draft:         <ul> <li>AUTOSAR Run-Time Interface</li> <li>MCAL Multicore Distribution</li> <li>Transport Layer Security</li> </ul> </li> </ul>
Log And Trace	LT Command SyncTimeStamp added
Protocol Specification	Editorial changes
Main Requirements	<ul> <li>Restructuring of RS_Main by splitting into functional and non-functional requirements, separating Platform Level candidates</li> <li>New requirements from concepts TLS (Draft), Bus Mirroring, ARTI (Draft)</li> <li>Improvement of requirements for topics like Security and Communication</li> </ul>
Network Management Protocol Specification	Initial release
Project Objectives	Editorial changes



Name	Specification history entry	
Requirements on	New requirements for CP and AP	
Diagnostic	Structural optimization of document	
Requirements on	Initial release	
Debugging,		
Tracing and Profiling		
support of		
AUTOSAR		
Components		
Requirements on E2E	Editorial changes	
Requirements on	Document from Release 1.4.0 released again	
Health Monitoring		
Requirements on Log	Requirement to provide Logging Information added	
and Trace	Editorial changes	
Requirements on	<ul> <li>scope of some requirements extended (from CP to CP+AP)</li> </ul>	
Methodology		
Requirements on	Initial release	
Network Management		
Requirements on	No content changes	
SOME/IP Protocol		
Requirements on	Editorial changes	
SOME/IP Service		
Discovery Protocol		
Requirements on	Initial release	
Time		
Synchronization		
SOME/IP Protocol	Backward-incompatibility statement removed	
Specification	Some statements improved	
SOME/IP Service	Clarify load balancing option usage	
Discovery Protocol	Contradicting requirements improved	
Specification	Redundant requirements removed	
Specification of Health	Document from Release 1.4.0 released again	
Monitoring		
Time Synchronization	Initial release	
Protocol		
Specification		



# 7 Appendix

#### 7.1 Definitions

As far as not explained in this chapter, a collection of AUTOSAR definitions is provided in 2).

#### 7.1.1 Release number

AUTOSAR applies a two-digit numbering scheme Rx.y to identify Releases. Its primary purpose is to identify a Release as a major (upgrade, can contain non-backward-compatible extensions) or as minor (update, backward compatible extensions) Release. Referring to previous Releases (e.g. R2.0), incrementing the first digit "x" does identify a Release as major, whereas incrementing "y" will mark a Release as only minor by nature.

#### 7.1.2 Revision number

The Revision Number was first time introduced with Release 2.1 and extends the Release Numbering scheme as explained in section 7.1.1. Combined with the Release Number, the Revision Number shall:

- 1) Precisely identify the actual content (set of specifications) of a given Release.
- 2) As depicted in every specification, precisely identify a given specification (with its unique name and three-digit version ID) as being part of the Release.

Item 1) addresses the fact that the set of specifications comprising a Release (in the meaning of a baseline) is rarely established once at a certain point in time ("Big Bang"), but rather evolves and/or varies over a certain timeframe. The maximum duration, which is limited by the timeframe, a Release is declared as "valid" by the AUTOSAR Partnership (see section 7.1.3).

Hence with Item 1), a major prerequisite will be put in place to enable the Standard Maintenance as planned by the AUTOSAR Partnership. In general, the primary objective is to avoid the provision of an additional – previously not planned – Release in case only one or a few specifications were to be modified as part of the Standard Maintenance. Conversely, without the application of a Revision Number, if the AUTOSAR partnership wants to avoid the provision of (an) additional intermediate Release(s), one would have to defer the introduction of any changes until the next planned Release – even in case of changes urgently needed by the applicants of the AUTOSAR Standard.

Item 2) is complementary to Item 1) in that for every specification a unique identifier is provided upon which Revision a) a specification was either 1<sup>st</sup> time added to/removed from a Release or b) a specification was modified as being part of one and the same Release, as long the latter is valid and therefore subject to Standard Maintenance.



Hence with item 2), the combination of Release and Revision Number in a specification can be interpreted either as a) "specification was  $(1^{st}$  time) added to the Release x.y Rev n" or b) as "specification was modified as part of Release x.y Rev m", with m > n.

Conversely, the Revision number will only change for specifications subject to addition or modification of a valid Release (baseline). After their 1<sup>st</sup> time addition to the Release (baseline), it will not change for specifications which are not modified.

In the light of the above provided background, as an additional remark, the Revision Number will only be applied for each specification's Release version, i.e. it will not be applied to working versions.

#### 7.1.3 Release life cycle of a major release

Each major release goes through four consecutive steps within its lifecycle:

- 1. Development: Between start of life cycle and the initial release (e.g. R4.0.1)
- 2. Evolution: Following the initial release with zero, one or several minor releases and/or revisions (e.g. R4.0.2, R4.1.1)
- 3. Maintenance: No new contents is added to a major release but only maintenance of the existing content with zero, one or several revisions (e.g. R3.2.2) is provided
- 4. Issue Notice: No more revisions but zero, one or several issue notices, i.e. updates of the list of known issues until end of life cycle.

#### 7.1.4 Specification item and requirement life cycle states

The life cycle state of a specification item is found after the specification item ID surrounded by curly brackets. The states are:

- **Valid**: This indicates that the related entity is a valid part of the document. This is the default.
- **Draft:** This indicates that the related entity is newly introduced but still experimental. This information is published but is subject to change without backward compatibility guarantee.
- **Obsolete:** This indicates that the related entity is obsolete and will be removed in the next release.

If there is no life cycle state information stated then the state is Valid.

The life cycle state of a requirement is found in the attribute "type". The states are the same as the specification item states.



## 7.1.5 History information in AUTOSAR

The following diagram shows where which changes are documented.

		Information at release / revision
Scope / abstractio	n	Release only: Changes on AUTOSAR by concepts (lists also affected docs)
Specification (all docs)	Release Overview	Release and revision: Chapter "Summary of changes":  • Maintenance work  • e.g. Service interfaces  • Known deficiencies  • Major changes (high impact) Chapter 7:  • A subset of external histories of documents shall be given: that would be major changes but not the standard entries
Document	Document external history	Release only: Changes / "influence" on document by concepts Major changes Guidance for DocOwner: Please: state major changes with high impact (e.g. high BWC or usage) or put a standard entry: "minor corrections / clarifications/editorial changes; For details please refer to the ChangeDocumentation"
Requirement	ChangeDocumentation	Changes on RfC granularity
	Number of entries	